# **Soheil Habibian**

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# RESEARCH INTERESTS

Robot learning • human-robot collaboration • artificial intelligence • robotics.

#### **EDUCATION**

## Virginia Polytechnic Institute and State University (Virginia Tech), Blacksburg, VA 2020–Present

Ph.D. Candidate, Mechanical Engineering

Dissertation: Exploring Communication-Driven Robot Learning for Human-Robot Collaboration

Relevant Coursework: Advanced Machine Learning, Deep Learning Specialization (DeepLearning.AI), Reinforcement Learning, Human-Robot Interaction, Robotics Kinematics and Mathematical Foundation (PennX).

### **Bucknell University**, Lewisburg, PA

2017-2020

M.Sc., Mechanical Engineering

Thesis: Analysis and Control of Fiber-Reinforced Elastomeric Enclosures

## Qazvin Azad University, Qazvin, Iran

2009-2015

B.S., Mechanical Engineering

Honors Thesis: Design and Implementation of a Tele-operative Response Robot

# SOFTWARE SKILLS

Python, PyTorch, TensorFlow, PyBullet, git, Robot Operating System (ROS), SPSS, MATLAB/Simulink, SolidWorks, ABAQUS, MasterCam, LabVIEW, LATEX, Linux

# RESEARCH EXPERIENCE

## Graduate Research Assistant, Virginia Tech, Blacksburg, VA

Dec 2020-Present

Collaborative Robotics Lab

- Created a communicative supervised learning framework to help novice robot users enhance robot teaching via imitation learning.
- Implemented a representation learning approach using recurrent neural networks to enable collaborative robots to robustly influence new human partners.
- Developed a Bayesian-based optimization approach to encourage human participation in robot teams by incorporating fairness and legibility into subtask allocations.
- Developed an active preference-based learning algorithm for efficient and transparent robot learning.

## **Reserach Intern**, Honda Research Institue, San Jose, CA

Jan 2023-May 2023

**Human Factors and Ergonomics Group** 

- Developed an experimental framework to understand and predict factors that influence human cognitive states for human-automation interactions in hybrid mobility environments.
- Created and validated tools to optimize system performance based on predicted human states.

## **Graduate Research Assistant**, Bucknell University, Lewisburg, PA

Aug 2017–Jan 2020

Integrated Design Manufacturing Robotics Lab

- Developed a dynamic lumped-parameter model and a finite element model to study the practicability of a fiber-reinforced soft robotic actuator for use in robotic arms.
- Developed a controller-based trajectory following algorithm for the soft actuator.
- Conducted workspace analysis for a module of multiple soft actuators using FEA.

## Undergraduate Researcher, Qazvin Azad University, Qazvin, Iran

Nov 2011-Jul 2017

Advanced Mobile Robotics Lab

- Managed projects and led an engineering team of 10+ to design and develop mobile response robots for real-life rescue missions.
- Designed and implemented a compact 7-DoF robot arm for dexterous mobile manipulation.

- Designed and implemented a tele-operative response robot for hazardous environments.
- Developed a lightweight throwable two-wheeled robot for reconnaissance missions.

# JOURNAL PUBLICATIONS

- A. A. Valdivia, **S. Habibian**, C. A. Mendenhall, F. Fuentes, R. Shailly, D. P. Losey, and L. H. Blumenschein, "Wrapping Haptic Displays Around Robot Arms to Communicate Learning," *IEEE Transactions on Haptics*, vol. 16, no. 1, pp. 57-72, 2023.
- **S. Habibian**, A. Jonnavittula, D. P. Losey, "Here's What I've Learned: Asking Questions that Reveal Reward Learning," *ACM Transactions on Human-Robot Interaction*, vol. 11, no. 4, pp. 1-28, 2022.
- **S. Habibian**, D. P. Losey, "Encouraging Human Interaction with Robot Teams: Legible and Fair Subtask Allocations," *IEEE Robotics and Automation Letters*, vol. 7, no. 3, pp. 6685-6692, 2022.
- M. Dadvar, **S. Habibian**, "Contemporary Research Trends in Response Robotics," *Robomech*, vol. 9, no. 9, 2022.
- **S. Habibian**, B. B. Wheatley, S. Bae, J. Shin, K. W. Buffinton, "Evaluation of Two Complementary Modeling Approaches for Fiber-Reinforced Soft Actuators," *Robomech*, vol. 9, no. 12, 2022.
- **S. Habibian**, M. Dadvar, et al., "Design and Implementation of a Maxi-Sized Rescue Robot (Karo) for Rescue Missions," *Robomech*, vol. 8, no. 1, 2021.

## REFEREED CONFERENCE PROCEEDINGS

- S. Parekh, **S. Habibian**, "RILI: Robustly Influencing Latent Intent," in *Proceedings of IEEE/RSJ International Conference on Intelligent Robots and Systems*, Kyoto, Japan, 23-27 October, 2022.
- K. W. Buffinton, B. B. Wheatley, **S. Habibian**, J. Shin, B. H. Cenci, and A. E. Christy, "Investigating the Mechanics of Human-Centered Soft Robotic Actuators with Finite Element Analysis," in *Proceedings of IEEE International Conference on Soft Robotics*, New Haven, CT, 15 May 15 July, 2020.

## **THESIS**

**S. Habibian**, "Analysis and Control of Fiber-Reinforced Elastomeric Enclosures (FREEs)," *Master's thesis submitted to the Department of Mechanical Engineering - Bucknell University*, 2019.

# CONFERENCE & WORKSHOP PRESENTATIONS

"Encouraging Human Interaction with Robot Teams: Legible and Fair Subtask Allocations," *IEEE International Conference on Robotics and Automation*, London, United Kingdom, 29 May - 2 June, 2023.

"Leveraging Roles in Robot Teams to Encourage Human Participation," *Southeast Controls Conference*, Blacksburg, VA, 29-30 November, 2021.

"Finite Element Analysis of Fiber Reinforced Elastomeric Enclosures," *Toyota Research Institute Workshop*, Ann Arbor, MI, 16-17 January , 2019.

# HONORS & AWARDS

| • <b>Full Scholarship</b> , Bucknell University Full-tuition scholarship with stipend to incoming master's students.                    | 2017–2019 |
|---|-----------|
| <ul> <li>Summer Research Fellowship, Bucknell University</li> <li>A merit-based award to the top graduate research proposal.</li> </ul> | 2018      |
| <ul> <li>3rd Place Award, Rescue Robot League, RoboCup Competition, Japan</li> </ul>  | 2017      |
| <ul> <li>2nd Place, Rescue Robot League, RoboCup Competition, Germany</li> </ul>  | 2016      |
| ■ Best-in-Class Exploration, Rescue Robot League, RoboCup Competition, Germany  | 2016      |
| ■ 1st Place, Rescue Robot League, RoboCup Competition, China  | 2015      |
| <ul> <li>2nd Place, Rescue Robot League, RoboCup Competition, Brazil</li> </ul>   | 2014      |
| ■ Best-in-Class Mobility, Rescue Robot League, RoboCup Competition, Brazil  | 2014      |
| ■ 1st Place, Rescue Robot League, RoboCup Competition, Mexico   | 2012      |

## Technical Committee Member, IranOpen RoboCup Competitions 2015-2017 **PROFESSIONAL AFFILIATIONS** Co-organized competitions for objective performance evaluations of rescue robot teams. & ACTIVITIES **Engineering Director**, Advanced Mobile Robotics Lab 2014-2017 Organized projects and supervised trainee students to design and implement mobile robots. Reviewer • IEEE International Conference on Intelligent Robots and Systems (IROS) IEEE RAS International Conference on Soft Robotics (RoboSoft) International Conference on Robotics and Automation (ICRA) International Conference on Human-Robot Interaction (HRI) International Journal of Advanced Robotic Systems Journal of Intelligent & Robotic Systems Robotics and Automation Systems Journal of Field Robotics Robomech Journal **TEACHING** Teaching Assistant, Virginia Tech, Blacksburg, VA Fall 2020 - Spring 2021 **EXPERIENCE** Mechanical Design Lab Teaching Assistant, Bucknell University, Lewisburg, VA Fall 2017 - Spring 2019 Mechanical Design Manufacturing Processes