

# SOHEIL HABIBIAN

Curriculum Vitae

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## Research Interests

Robot learning, human-robot teams, and artificial intelligence.

## Education

May 2024 **Virginia Polytechnic Institute and State University**  
(expected) Ph.D. Student, Mechanical Engineering

January **Bucknell University**  
2020 M.Sc. Mechanical Engineering  
Thesis: “Analysis and Control of Fiber-Reinforced Elastomeric Enclosures (FREEs)”

June 2015 **Qazvin Azad University (QIAU)\***  
B.Sc. Mechanical Engineering  
Honors Thesis: “Design and Implementation of a Tele-operative Response Robot”

\* QIAU organizes the International IranOpen RoboCup competition and has established the Mechatronics Research Laboratory (MRL) as one of the outstanding independent robotics research centers in Iran.

## Research Experience

2020- **Collaborative Robotics Lab, Virginia Tech**  
Present Advisor: Dylan P. Losey

- Implemented a representation learning approach using recurrent neural networks to enable robots robustly influence humans
- Developed an optimization framework using Bayesian inference for encouraging human interaction with robot teams
- Developed an active preference-based learning algorithm for transparent robot teaching

2017- **Integrated Design Manufacturing Robotics Lab, Bucknell University**  
2020 Advisor: Keith W. Buffinton

- Developed a dynamic lumped-parameter model and a finite element model to study the practicability of a fiber-reinforced soft robotic actuator for use in robotic arms
- Developed a controller-based trajectory following algorithm for the soft actuator
- Conducted workspace analysis for a module of multiple soft actuators using FEA

2011-2017 **Advanced Mobile Robotics Lab, Qazvin Azad University**  
Advisor: Prof. Farshid Najafi

- Managed projects and led an engineering team of 10+ to design and develop mobile response robots for real-life rescue missions.
- Designed and implemented a compact 7-DoF robot arm for dexterous mobile manipulation
- Designed and implemented a tele-operative response robot for hazardous environments
- Development a lightweight throwable two-wheeled robot for reconnaissance missions

## **Publications**

### **Papers**

- S. Habibian**, D. P. Losey, "Encouraging Human Interaction with Robot Teams: Legible and Fair Subtask Allocations," *IEEE Robotics and Automation Letters*, 2022.
- S. Parekh, **S. Habibian**, D. P. Losey, "RILI: Robustly influencing latent intent," *arXiv preprint arXiv:2203.12705*, 2022.
- S. Habibian**, A. Jonnavittula, D. P. Losey, "Here's What I've Learned: Asking Questions that Reveal Reward Learning," *ACM Transactions on Human-Robot Interaction*, 2022.
- M. Dadvar, **S. Habibian**, "Contemporary Research Trends in Response Robotics," *ROBOMECH Journal*, 2022.
- S. Habibian**, B. B. Wheatley, S. Bae, J. Shin, K. W. Buffinton, "Evaluation of Two Complementary Modeling Approaches for Fiber-Reinforced Soft Actuators," *ROBOMECH Journal*, 2022.
- S. Habibian**, M. Dadvar, "Design and Implementation of a Maxi-Sized Rescue Robot (Karo) for Rescue Missions," *ROBOMECH Journal*, 2021.
- K.W. Buffinton, B. B. Wheatley, **S. Habibian**, J. Shin, Brielle H. Cenci, and A. E. Christy, "Investigating the Mechanics of Human-Centered Soft Robotic Actuators with Finite Element Analysis," *IEEE International Conference on Soft Robotics (RobotSoft)*, 2020.
- F. Najafi, M. Dadvar, **S. Habibian**, et al., "Team Description Papers of Rescue Robots," *In Proceedings of the International Symposium of RoboCup*, 2018.

### **Poster**

- S. Habibian**, A.E. Christy, K.W. Buffinton, B.B. Wheatley, "Finite Element Analysis of Fiber Reinforced Elastomeric Enclosures (FREEs)," *3rd Toyota Research Institute Workshop*, 2019.

### **Thesis**

- S. Habibian**, "Analysis and Control of Fiber-Reinforced Elastomeric Enclosures (FREEs)," *Master's thesis submitted to the Department of Mechanical Engineering - Bucknell University*, 2019.

## **Awards and Fellowships**

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|--------|---|
| 2017-9 | Granted <b>Full Scholarship</b> , M.Sc. Mechanical Engineering, Bucknell University.                        |
| 2018   | Granted <b>Graduate Summer Research Fellowship</b> , Graduate Studies, Bucknell University.                 |
| 2018   | <b>2<sup>nd</sup> Place</b> & Best-in-Class Dexterity, Rescue Robot League, RoboCup Competition, Canada.    |
| 2017   | <b>3<sup>rd</sup> Place</b> , Rescue Robot League, RoboCup Competition, Japan.                              |
| 2013-7 | <b>1st Places</b> , Rescue Robot League, IranOpen Competitions.   |
| 2013-7 | Best-In-Class Mobility, Autonomy, Dexterity, Rescue Robot League, IranOpen Competitions.                    |
| 2016   | <b>2<sup>nd</sup> Place</b> & Best-in-Class Exploration, Rescue Robot League, RoboCup Competition, Germany. |
| 2015   | <b>1st Place</b> , Rescue Robot League, RoboCup Competition, China.   |
| 2011-5 | Awarded <b>Partial Scholarship</b> , B.Sc. Mechanical Engineering, Qazvin Azad University.                  |
| 2014   | <b>2<sup>nd</sup> Place</b> and Best-in-Class Mobility, Rescue Robot League, RoboCup Competition, Brazil.   |
| 2012   | <b>1st Place</b> , Rescue Robot League, World RoboCup Competition, Mexico.                                  |

## **Professional Services**

- 2020 - 2021     **Committee Member, ASTM Subcommittee E54.09**  
Established terminologies for standard test methods and guides for evaluating response robots
- 2015-2017     **Technical Committee Member, IranOpen RoboCup Competitions**  
Co-organized competitions for objective performance evaluations of rescue robot teams
- 2014-2017     **Group Leader, Advanced Mobile Robotics Lab**  
Organized projects and supervised trainee students to design and implement mobile robots

### **Reviewer**

- ROBOMECH Journal
- Journal of Field Robotics
- Journal of Intelligent & Robotic Systems
- International Journal of Advanced Robotic Systems
- IEEE RAS International Conference on Soft Robotics (RoboSoft)
- IEEE International Conference on Intelligent Robots and Systems (IROS)

## **Industrial Training Courses**

- 2012             Introduction to Hydraulics-H511, FESTO Co., Iran, October 7th -10th.
- 2012             Modern Industrial Pneumatics-PN111, FESTO Co., Iran, October 21st-24th.
- 2010             Lathe Machine Operation, Vocational Training Organization, Iran, December 5th.

## **Skills**

Python, PyTorch, PyBullet, ROS, MATLAB, SolidWorks, ABAQUS, MasterCam, LabVIEW, LaTeX

## **Teaching Experience**

- Fall 2020,         **Mechanical Engineering Dept., Virginia Tech**  
Spring 2021     Graduate Student Instructor, Mechanical Design Lab
- Fall 2017,         **Mechanical Engineering Dept., Bucknell University**  
Spring 2019     Graduate Student Instructor, Mechanical Design  
Graduate Student Instructor, Manufacturing Processes  
Graduate Student Instructor, Renewable Energy Conversion

## **Campus Involvements**

- 2019             **Engineering Camp Counselor**, Summer Engineering Camp Program, Bucknell University
- 2018             **International Orientation Assistant**, International Student Orientation, Bucknell University
- 2018             **Journal Organizing Project Assistant**, Bertrand Library, Bucknell University