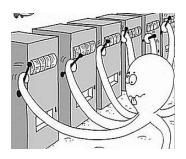
#### Model-based Interval Estimation for MDP

Alexander L. Strehl, Micheal L. Littman Journal of Computer and System Science - Elsevier IF: 1.497

### Background

- Exploration or exploitation? k-armed bandit problem
- Probability Approximately Correct (PAC)
- Confidence Intervals
- Model-based Interval Estimation (MBIE)

#### k-armed bandit



- $\blacktriangleright$  k arms, one choice at a time, a payoff, drawn from an unknown distribution with mean  $\mu_i$  and variance
- **optimal long term**: always select the arm with highest known mean.

$$\operatorname{argmax}_{i}\{\mu_{i}\}$$

► Any problems?

#### k-armed bandit

- You don't get the chance to explore other machines
- Or, you don't get the chance to exploit what it was learned
- You just waste money to learn!
- ► Solution: Interval Estimation (IE)

#### Interval Estimation

In each trial, construct confidence interval for the mean of the payoff distribution for each arm

$$[\hat{\mu}_i - \epsilon_i, \hat{\mu}_i + \epsilon_i]$$

- ► If the confidence interval is loose, the mean payoff may not be near optimal, we need to gain more information
- $\blacktriangleright$  What is missing?  $\epsilon$
- Model-based Interval Estimation (MBIE) is based on PAC optimality.

#### What is PAC?

- Probability Approximately Correct
- First developed for supervised learning classification problems
- ► Set of observations instances *X*
- ► Set of hypothesis *H* 
  - class of linear functions
  - class of polynomials
  - class of radial basis functions
- Set of concepts C
- ► Training set  $\{(x_i, y_i)\}_i^m = \{(x_i, c(x_i))\}_i^m$

$$y = c(x), \quad c \in C$$

$$\hat{y} = h(x), \quad h \in H$$

What is the probability that a classifier (with  $\epsilon$  chance of misclassification), classifies correctly (Err is test error)

$$Pr(Err > \epsilon) < |H|e^{\epsilon m}$$

$$|H|e^{-\epsilon m} < \delta \to m \ge 1/\epsilon (\ln|H| + \ln(1/\delta))$$

<sup>&</sup>lt;sup>0</sup>Watch this! It's good!

#### **MBIE**

- Definitions
  - ightharpoonup occupancy count n(s,a)
  - ightharpoonup next-state count n(s, a, s')
  - model size limit m
- Reward Confidence Interval
  - immediate reward from taking action a from state s: r[1], r[2], ... r[n(s,a)]
  - empirical mean reward

$$\hat{R}(s,a) = \frac{1}{n(s,a)} \sum_{i=1}^{n(s,a)} r[i]$$

confidence interval

$$CI(R) = (\hat{R}(s, a) - \epsilon_{n(s, a)}^{R}, \hat{R}(s, a) + \epsilon_{n(s, a)}^{R})$$
 
$$\epsilon_{n(s, a)}^{R} = \sqrt{\frac{2/\delta_r}{2.n(s, a)}}$$

## How PAC is applied to MDPs?

**▶** ???

#### **MBIE**

Transition Confidence Interval

$$\hat{T}(s'|s,a) = \frac{n(s,a,s')}{n(s,a)}$$

$$\epsilon_{n(s,a)}^T = \sqrt{\frac{2(\ln(2^{|S|}) - 2) - \ln(\delta_T)}{m}}$$

• from Hoeffiding bounds, with probability at least  $1-\delta$ , R and T are in the confidence interval

#### **MBIE**

Value iteration with confidence interval:

$$Q'(s,a) = \max_{\tilde{R}(s,a) \in CI(R)} \tilde{R}(s,a) + \max_{\tilde{T}(s,a) \in CI(T)} \gamma \sum_{s'} \tilde{T}(s'|s,a) \max_{a'} Q(s',a') \quad (1)$$

MBIE-EB solves

$$Q'(s,a) = \tilde{R}(s,a) + \gamma \sum_{s'} \tilde{T}(s'|s,a) \max_{a'} \tilde{Q}(s',a') + \frac{\beta}{\sqrt{n(s,a)}}$$
(2)

<sup>0</sup>item page 5, difference between MBIE and MBIE-EB

# Thank You!