# Week\_7\_Second\_Modeling-Copy1

October 22, 2024

```
[1]: # Standard Libraries
     import io
     import numpy as np
     import pandas as pd
     import matplotlib.pyplot as plt
     # Deep Learning and PyTorch
     import torch
     import torch.nn as nn
     import torch.nn.functional as F
     import torch.optim as optim
     from torch.utils.data import Dataset, DataLoader
     from torchvision import models
     # Image Processing
     from PIL import Image
     from torchvision import transforms, models
     # File Handling
     import h5py
     # Metrics and Evaluation
     from sklearn.metrics import classification_report, roc_auc_score, roc_curve, auc
     # Progress Visualization
     from tqdm import tqdm
```

## 0.1 Create Custom Dataset

```
[2]: class MultiInputDataset(Dataset):
    def __init__(self, hdf5_file, csv_file, transform=None):
        # Open the HDF5 file with error handling
        try:
            self.hdf5_file = h5py.File(hdf5_file, 'r') # Read-only mode
        except Exception as e:
            raise IOError(f"Could not open HDF5 file: {hdf5_file}. Error: {e}")

# Read the CSV file containing image labels and additional features
```

```
try:
          self.labels_df = pd.read_csv(csv_file)
      except Exception as e:
          raise IOError(f"Could not read CSV file: {csv_file}. Error: {e}")
       # Ensure that all image IDs from the CSV are present in the HDF5 file
      self.image_ids = self.labels_df['isic_id'].values
      for image_id in self.image_ids:
          if str(image id) not in self.hdf5 file.keys():
              raise ValueError(f"Image id {image_id} not found in HDF5 file.")
       # Store any transformations to be applied to the images
      self.transform = transform
  def len (self):
      # Return the total number of samples in the dataset
      return len(self.labels_df)
  def __getitem__(self, idx):
       # Get the image ID from the CSV file based on index
      image_id = str(self.labels_df.iloc[idx]['isic_id'])
      # Load the image data from the HDF5 file
      image_bytes = self.hdf5_file[image_id][()]
      # Convert the image bytes to a PIL Image
      image = Image.open(io.BytesIO(image_bytes))
      # Apply any specified transformations to the image
      if self.transform:
          image = self.transform(image)
       # Retrieve the label
      label = torch.tensor(self.labels_df.iloc[idx]['target'], dtype=torch.
→long) # Adjust dtype if needed
       # Retrieve other features, excluding 'isic_id' and 'target'
      other_variables = self.labels_df.iloc[idx].drop(['isic_id', 'target']).
⇔values.astype(float)
       # Convert other variables (metadata) to a tensor
      metadata_tensor = torch.tensor(other_variables, dtype=torch.float32)
      # Return the image, metadata, and label
      return image, metadata_tensor, label
```

#### 0.2 Train DataLoader

```
[4]: # Initialize the dataset

train_dataset = MultiInputDataset(hdf5_file='../data/raw/train_images.hdf5',u

csv_file='../data/processed/processed-train-metadata1.csv',u

transform=normal_transform)

val_dataset = MultiInputDataset(hdf5_file='../data/raw/validation_image.hdf5',u

csv_file='../data/processed/processed-validation-metadata1.csv',u

transform=normal_transform)

# Create a DataLoader

train_dataloader = DataLoader(train_dataset, batch_size=64, shuffle=True)

val_dataloader = DataLoader(val_dataset, batch_size=64, shuffle=True)
```

```
[5]: device = "cuda" if torch.cuda.is_available() else "cpu"
```

## 0.3 Model Building

```
[6]: import torch
import torch.nn as nn
import torch.nn.functional as F
from torchvision import models

class CustomImageFeatureResNet(nn.Module):
    def __init__(self, feature_input_size, pretrained=True):
        super(CustomImageFeatureResNet, self).__init__()
```

```
# Load a pretrained ResNet model for image feature extraction (ResNet184
⇔in this case)
      resnet = models.resnet18(pretrained=pretrained) # Change to resnet50, ___
⇔resnet101 as needed
      self.resnet = nn.Sequential(*list(resnet.children())[:-1]) # Remove_
→ the final classification layer
      # The output of ResNet18's last conv layer is 512-dimensional (for
\neg ResNet50, it would be 2048)
      self.fc_image = nn.Linear(resnet.fc.in_features, 512) # Adjust if_
using ResNet50 → using ResNet50
      # Fully connected layer for metadata (feature data)
      self.fc_metadata = nn.Linear(feature_input_size, 128)
      # Dropout layer to prevent overfitting
      self.dropout = nn.Dropout(0.5) # 50% dropout
      # Final fully connected layer for binary classification (combined image
→+ feature input)
      self.fc_combined = nn.Linear(512 + 128, 1) # For binary classification
  def forward(self, image, metadata):
      # Forward pass for the image through the ResNet (without the final
⇔classification layer)
      x = self.resnet(image) # ResNet feature extraction
      x = x.view(x.size(0), -1) # Flatten the ResNet output
      image_features = F.relu(self.fc_image(x))
      # Process metadata (feature data)
      metadata_features = F.relu(self.fc_metadata(metadata))
      # Ensure the batch sizes are consistent
      assert image features.shape[0] == metadata features.shape[0], \
          f"Batch sizes do not match! Image batch size: {image_features.
⇒shape[0]}, Metadata batch size: {metadata features.shape[0]}"
       # Concatenate image features and metadata features
      combined_features = torch.cat((image_features, metadata_features),__
\rightarrowdim=1)
      # Dropout and final classification layer
      combined_features = self.dropout(combined_features)
      output = self.fc_combined(combined_features)
      # If you're using BCELoss, uncomment the next line to apply sigmoid
```

```
output = torch.sigmoid(output)
return output
```

## 0.4 Model Training

```
[7]: # Function to compute partial AUC-above-TPR
     def score(solution: np.array, submission: np.array, min_tpr: float = 0.80) ->__
      ⊶float:
         Compute the partial AUC by focusing on a specific range of true positive \sqcup
      \hookrightarrow rates (TPR).
         Args:
             solution (np.array): Ground truth binary labels.
             submission (np.array): Model predictions.
             min_tpr (float): Minimum true positive rate to calculate partial AUC.
         Returns:
             float: The calculated partial AUC.
         Raises:
             ValueError: If the min_tpr is not within a valid range.
         # Rescale the target to handle sklearn limitations and flip the predictions
         v_gt = abs(solution - 1)
         v_pred = -1.0 * submission
         max_fpr = abs(1 - min_tpr)
         # Compute ROC curve using sklearn
         fpr, tpr, _ = roc_curve(v_gt, v_pred)
         if max_fpr is None or max_fpr == 1:
             return auc(fpr, tpr)
         if max fpr <= 0 or max fpr > 1:
             raise ValueError(f"Expected min_tpr in range [0, 1), got: {min_tpr}")
         # Interpolate for partial AUC
         stop = np.searchsorted(fpr, max_fpr, "right")
         x_interp = [fpr[stop - 1], fpr[stop]]
         y_interp = [tpr[stop - 1], tpr[stop]]
         tpr = np.append(tpr[:stop], np.interp(max_fpr, x_interp, y_interp))
         fpr = np.append(fpr[:stop], max_fpr)
         partial_auc = auc(fpr, tpr)
         return partial_auc
```

```
# Training and validation loop function
def train_and_validate(
    model: nn.Module,
    train_dataloader: torch.utils.data.DataLoader,
    val_dataloader: torch.utils.data.DataLoader,
    criterion: nn.Module,
    optimizer: torch.optim.Optimizer,
    epochs: int,
    device: torch.device,
    early_stopping_patience: int = 5,
    min tpr: float = 0.80
) -> nn.Module:
    Train and validate a PyTorch model with early stopping, AUROC, partial AUC, __
 \hookrightarrow and error handling.
    Args:
        model (nn.Module): The model to be trained and validated.
        train dataloader (torch.utils.data.DataLoader): Dataloader for training
 \hookrightarrow data.
        val\_dataloader (torch.utils.data.DataLoader): Dataloader for validation \sqcup
 \hookrightarrow data.
        criterion (nn.Module): Loss function.
        optimizer (torch.optim.Optimizer): Optimizer to update the model.
        epochs (int): Number of training epochs.
        device (torch.device): The device (CPU or GPU) to use.
        early_stopping_patience (int): Early stopping patience.
        min\_tpr (float): The minimum true positive rate for calculating partial_
 \hookrightarrow AUC.
    Returns:
        nn. Module: The trained model.
    # Initialize tracking variables
    best val loss = float('inf')
    best epoch = 0
    train_losses = []
    val losses = []
    train_accuracies = []
    val_accuracies = []
    early_stopping_counter = 0
    # Start the training and validation loop
    for epoch in range(epochs):
        print(f'Epoch {epoch + 1}/{epochs}')
        # Training phase
```

```
model.train()
      running_train_loss = 0.0
      correct_train = 0
      total_train = 0
      all_train_labels = []
      all_train_probs = []
      progress_bar = tqdm(train_dataloader, desc=f'Training Epoch {epoch +_\pu
→1}')
      try:
           # Loop through the training batches
          for i, (image, metadata, labels) in enumerate(progress_bar):
               image, metadata, labels = image.to(device), metadata.
→to(device), labels.float().to(device)
               labels = labels.unsqueeze(1) # Adjust labels to have the right
⇒shape for binary classification
               optimizer.zero_grad()
               # Forward pass
               probs = model(image, metadata)
               if probs.shape != labels.shape:
                   raise ValueError(f"Shape mismatch: Predictions shape {probs.
⇒shape} does not match labels shape {labels.shape}")
               # Calculate loss and backpropagate
               loss = criterion(probs, labels)
               loss.backward()
               optimizer.step()
               # Update running loss
               running_train_loss += loss.item()
               # Store labels and predictions for accuracy calculations
               all_train_labels.extend(labels.cpu().detach().numpy())
               all_train_probs.extend(probs.cpu().detach().numpy())
               # Calculate binary predictions for training accuracy
               predicted_train = (probs >= 0.5).float()
               total_train += labels.size(0)
               correct_train += (predicted_train == labels).sum().item()
               # Update progress bar
               progress_bar.set_postfix(train_loss=running_train_loss / (i +__
→1))
```

```
# Calculate training accuracy and loss
           train_accuracy = 100 * correct_train / total_train
           train_losses.append(running_train_loss / len(train_dataloader))
           train_accuracies.append(train_accuracy)
       except ValueError as ve:
           print(f"Error during training loop: {ve}")
           break
       # Validation phase
      model.eval()
      running_val_loss = 0.0
      correct = 0
      total = 0
      all_labels = []
      all_probs = []
      progress_bar = tqdm(val_dataloader, desc=f'Validating Epoch {epoch +u
→1}')
      with torch.no_grad():
          try:
               # Loop through the validation batches
               for i, (images, metadata, labels) in enumerate(progress_bar):
                   images, metadata, labels = images.to(device), metadata.
→to(device), labels.float().to(device)
                   labels = labels.unsqueeze(1)
                   probs = model(images, metadata)
                   loss = criterion(probs, labels)
                   running_val_loss += loss.item()
                   all_labels.extend(labels.cpu().detach().numpy())
                   all_probs.extend(probs.cpu().detach().numpy())
                   # Calculate binary predictions for validation accuracy
                   predicted = (probs >= 0.5).float()
                   total += labels.size(0)
                   correct += (predicted == labels).sum().item()
                   progress_bar.set_postfix(val_loss=running_val_loss / (i +__
→1))
               val_accuracy = 100 * correct / total
               val_loss = running_val_loss / len(val_dataloader)
```

```
val_accuracies.append(val_accuracy)
              val_losses.append(val_loss)
              # Calculate AUROC
              try:
                  valid_auroc = roc_auc_score(all_labels, all_probs)
              except ValueError as ve:
                  print(f"AUROC Calculation Error: {ve}")
                  valid_auroc = 0.0
              # Calculate partial AUC-above-TPR
              try:
                  partial_auroc = score(np.array(all_labels), np.
→array(all_probs), min_tpr=min_tpr)
              except ValueError as ve:
                  print(f"Partial AUC Calculation Error: {ve}")
                  partial_auroc = 0.0
              print(f'Epoch [{epoch + 1}/{epochs}], Train Loss:
f'Val Accuracy: {val_accuracy:.2f}%, Val AUROC:__

√{valid_auroc:.4f}, Partial AUROC: {partial_auroc:.4f}')

              # Early stopping based on validation loss
              if val_loss < best_val_loss:</pre>
                  best_val_loss = val_loss
                  best_epoch = epoch + 1
                  early_stopping_counter = 0
                  torch.save(model.state_dict(), 'best_model.pth')
              else:
                  early_stopping_counter += 1
              if early_stopping_counter >= early_stopping_patience:
                  print(f"Early stopping triggered at epoch {epoch + 1}")
                  break
          except Exception as e:
              print(f"Error during validation loop: {e}")
              break
  print(f"Best Epoch: {best_epoch}, Best Validation Loss: {best_val_loss:.

4f}")

  print('Training Complete')
  # Plot training and validation loss
  plt.figure(figsize=(10, 5))
  plt.plot(train_losses, label='Train Loss')
```

```
plt.plot(val_losses, label='Validation Loss')
  plt.xlabel('Epochs')
  plt.ylabel('Loss')
  plt.title('Training and Validation Loss')
  plt.legend()
  plt.show()
  # Plot training and validation accuracy
  plt.figure(figsize=(10, 5))
  plt.plot(train_accuracies, label='Train Accuracy')
  plt.plot(val_accuracies, label='Validation Accuracy')
  plt.xlabel('Epochs')
  plt.ylabel('Accuracy (%)')
  plt.title('Training and Validation Accuracy')
  plt.legend()
  plt.show()
  # Generate classification report
  try:
      print("Classification Report:")
      print(classification_report(all_labels, (np.array(all_probs) >= 0.5).

→astype(int), target_names=['Class 0', 'Class 1']))
  except Exception as e:
      print(f"Error generating classification report: {e}")
  return model
```

### 0.5 Model 1

```
/home/jupyter-sohka/.local/lib/python3.10/site-
packages/torchvision/models/_utils.py:208: UserWarning: The parameter
'pretrained' is deprecated since 0.13 and may be removed in the future, please
use 'weights' instead.
   warnings.warn(
/home/jupyter-sohka/.local/lib/python3.10/site-
packages/torchvision/models/_utils.py:223: UserWarning: Arguments other than a
weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed
```

```
in the future. The current behavior is equivalent to passing
    `weights=ResNet18_Weights.IMAGENET1K_V1`. You can also use
    `weights=ResNet18_Weights.DEFAULT` to get the most up-to-date weights.
      warnings.warn(msg)
[9]: train_and_validate(model1,train_dataloader, val_dataloader, criterion,_
     ⇔optimizer, epochs, device )
    Epoch 1/20
    Training Epoch 1: 100% | 33/33 [05:20<00:00, 9.70s/it,
    train_loss=0.487]
    Validating Epoch 1: 100% | 24/24 [01:10<00:00, 2.93s/it,
    val_loss=0.359]
```

Epoch [1/20], Train Loss: 0.4871, Val Loss: 0.3585, Val Accuracy: 85.57%, Val AUROC: 0.7102, Partial AUROC: 0.0499 Epoch 2/20 Training Epoch 2: 100% | 33/33 [05:13<00:00, 9.50s/it, train\_loss=0.37] Validating Epoch 2: 100% | 24/24 [01:09<00:00, 2.88s/it, val\_loss=0.458] Epoch [2/20], Train Loss: 0.3699, Val Loss: 0.4577, Val Accuracy: 82.21%, Val AUROC: 0.8521, Partial AUROC: 0.1003 Epoch 3/20 Training Epoch 3: 100% | 33/33 [05:16<00:00, 9.58s/it, train loss=0.31] Validating Epoch 3: 100% | 24/24 [01:09<00:00, 2.88s/it, val loss=0.288] Epoch [3/20], Train Loss: 0.3105, Val Loss: 0.2877, Val Accuracy: 83.22%, Val AUROC: 0.8656, Partial AUROC: 0.1226 Epoch 4/20 Training Epoch 4: 100% | 33/33 [05:07<00:00, 9.30s/it, train\_loss=0.248] Validating Epoch 4: 100% | 24/24 [01:11<00:00, 2.97s/it, val\_loss=0.301] Epoch [4/20], Train Loss: 0.2482, Val Loss: 0.3012, Val Accuracy: 87.18%, Val AUROC: 0.8861, Partial AUROC: 0.1248 Epoch 5/20 Training Epoch 5: 100% | 33/33 [05:04<00:00, 9.24s/it, train loss=0.18] Validating Epoch 5: 100% | 24/24 [01:06<00:00, 2.77s/it, val\_loss=0.25] Epoch [5/20], Train Loss: 0.1802, Val Loss: 0.2495, Val Accuracy: 90.27%, Val

AUROC: 0.8954, Partial AUROC: 0.1271

Epoch 6/20 Training Epoch 6: 100% | 33/33 [05:06<00:00, 9.28s/it, train loss=0.152] Validating Epoch 6: 100% | 24/24 [01:06<00:00, 2.77s/it, val loss=0.206] Epoch [6/20], Train Loss: 0.1522, Val Loss: 0.2059, Val Accuracy: 94.23%, Val AUROC: 0.7653, Partial AUROC: 0.0532 Epoch 7/20 Training Epoch 7: 100% | 33/33 [05:02<00:00, 9.16s/it, train\_loss=0.145] Validating Epoch 7: 100% | 24/24 [01:07<00:00, 2.79s/it, val\_loss=1.37] Epoch [7/20], Train Loss: 0.1453, Val Loss: 1.3696, Val Accuracy: 67.38%, Val AUROC: 0.8349, Partial AUROC: 0.1053 Epoch 8/20 Training Epoch 8: 100% | 33/33 [05:04<00:00, 9.23s/it, train\_loss=0.125] Validating Epoch 8: 100% | 24/24 [01:14<00:00, 3.10s/it, val\_loss=0.193] Epoch [8/20], Train Loss: 0.1246, Val Loss: 0.1926, Val Accuracy: 93.15%, Val AUROC: 0.8817, Partial AUROC: 0.1245 Epoch 9/20 Training Epoch 9: 100% | 33/33 [05:04<00:00, 9.21s/it, train\_loss=0.0645] Validating Epoch 9: 100% | 24/24 [01:12<00:00, 3.00s/it, val\_loss=0.146] Epoch [9/20], Train Loss: 0.0645, Val Loss: 0.1464, Val Accuracy: 96.51%, Val AUROC: 0.8796, Partial AUROC: 0.1200 Epoch 10/20 Training Epoch 10: 100% | 33/33 [04:57<00:00, 9.02s/it, train loss=0.039] Validating Epoch 10: 100% | 24/24 [01:08<00:00, 2.87s/it, val loss=0.183] Epoch [10/20], Train Loss: 0.0390, Val Loss: 0.1834, Val Accuracy: 95.03%, Val AUROC: 0.8746, Partial AUROC: 0.1210 Epoch 11/20 Training Epoch 11: 100% | 33/33 [05:08<00:00, 9.34s/it, train\_loss=0.031] Validating Epoch 11: 100% | 24/24 [01:14<00:00, 3.10s/it,

Epoch [11/20], Train Loss: 0.0310, Val Loss: 0.2539, Val Accuracy: 92.55%, Val AUROC: 0.8574, Partial AUROC: 0.1095

val\_loss=0.254]

#### Epoch 12/20

Training Epoch 12: 100% | 33/33 [05:08<00:00, 9.36s/it, train\_loss=0.0615]
Validating Epoch 12: 100% | 24/24 [01:11<00:00, 2.98s/it, val\_loss=0.189]

Epoch [12/20], Train Loss: 0.0615, Val Loss: 0.1888, Val Accuracy: 94.03%, Val AUROC: 0.8672, Partial AUROC: 0.1175

Epoch 13/20

Training Epoch 13: 100% | 33/33 [04:57<00:00, 9.03s/it, train\_loss=0.0328]

Validating Epoch 13: 100% | 24/24 [01:07<00:00, 2.80s/it, val\_loss=0.244]

Epoch [13/20], Train Loss: 0.0328, Val Loss: 0.2440, Val Accuracy: 93.76%, Val AUROC: 0.8565, Partial AUROC: 0.1048

Epoch 14/20

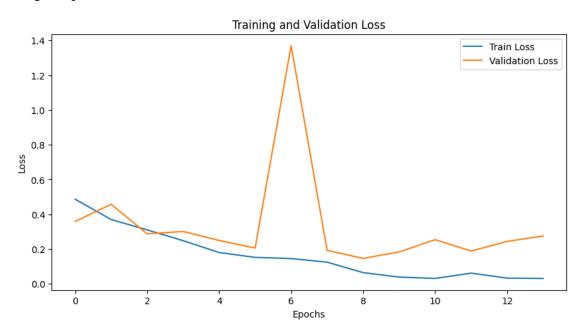
Training Epoch 14: 100% | 33/33 [05:06<00:00, 9.27s/it, train\_loss=0.0311]
Validating Epoch 14: 100% | 24/24 [01:08<00:00, 2.86s/it]

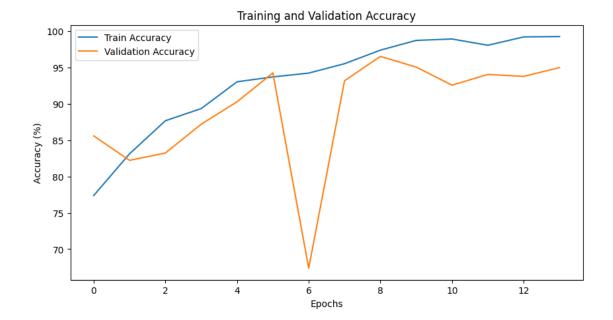
Validating Epoch 14: 100% | 24/24 [01:08<00:00, 2.86s/it, val\_loss=0.275]

Epoch [14/20], Train Loss: 0.0311, Val Loss: 0.2752, Val Accuracy: 94.97%, Val AUROC: 0.8445, Partial AUROC: 0.1057 Early stopping triggered at epoch 14

Best Epoch: 9, Best Validation Loss: 0.1464

Training Complete





## Classification Report:

	precision	recall	f1-score	support
Class 0	0.97	0.98	0.97	1431
Class 1	0.35	0.31	0.32	59
accuracy			0.95	1490
macro avg	0.66	0.64	0.65	1490
weighted avg	0.95	0.95	0.95	1490

## [9]: CustomImageFeatureResNet(

(resnet): Sequential(

- (0): Conv2d(3, 64, kernel\_size=(7, 7), stride=(2, 2), padding=(3, 3),
- (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)
  - (2): ReLU(inplace=True)
- (3): MaxPool2d(kernel\_size=3, stride=2, padding=1, dilation=1, ceil\_mode=False)
  - (4): Sequential(
    - (0): BasicBlock(

(conv1): Conv2d(64, 64, kernel\_size=(3, 3), stride=(1, 1), padding=(1,

1), bias=False)

(bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,

track\_running\_stats=True)

(relu): ReLU(inplace=True)

```
(conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      )
      (1): BasicBlock(
        (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
     )
    )
    (5): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(64, 128, kernel_size=(3, 3), stride=(2, 2), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (downsample): Sequential(
          (0): Conv2d(64, 128, kernel_size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        )
      )
      (1): BasicBlock(
        (conv1): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      )
    )
    (6): Sequential(
```

```
(0): BasicBlock(
        (conv1): Conv2d(128, 256, kernel size=(3, 3), stride=(2, 2), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (downsample): Sequential(
          (0): Conv2d(128, 256, kernel_size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        )
      )
      (1): BasicBlock(
        (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    )
    (7): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(256, 512, kernel_size=(3, 3), stride=(2, 2), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (downsample): Sequential(
          (0): Conv2d(256, 512, kernel_size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        )
      )
      (1): BasicBlock(
        (conv1): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
```

```
1), bias=False)
              (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
              (relu): ReLU(inplace=True)
              (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
              (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
          )
          (8): AdaptiveAvgPool2d(output size=(1, 1))
        (fc_image): Linear(in_features=512, out_features=512, bias=True)
        (fc_metadata): Linear(in_features=9, out_features=128, bias=True)
        (dropout): Dropout(p=0.5, inplace=False)
        (fc_combined): Linear(in_features=640, out_features=1, bias=True)
      )
     0.6 Model 2
[10]: model2 = CustomImageFeatureResNet(feature_input_size=9) # Assuming 9 features_
       ⇔for metadata
      model2.to(device)
      # Initialize optimizer
      optimizer = optim.SGD(model2.parameters(), lr=0.001)
      # Define the loss function with the class weights
      criterion = nn.BCELoss() # Binary classification loss
      # Set the number of epochs
      epochs = 20
     /home/jupyter-sohka/.local/lib/python3.10/site-
     packages/torchvision/models/_utils.py:208: UserWarning: The parameter
     'pretrained' is deprecated since 0.13 and may be removed in the future, please
     use 'weights' instead.
       warnings.warn(
     /home/jupyter-sohka/.local/lib/python3.10/site-
     packages/torchvision/models/_utils.py:223: UserWarning: Arguments other than a
     weight enum or 'None' for 'weights' are deprecated since 0.13 and may be removed
     in the future. The current behavior is equivalent to passing
     `weights=ResNet18_Weights.IMAGENET1K_V1`. You can also use
     `weights=ResNet18_Weights.DEFAULT` to get the most up-to-date weights.
       warnings.warn(msg)
[11]: train_and_validate(model2, train_dataloader, val_dataloader, criterion, __
       ⇔optimizer, epochs, device )
```

Epoch 1/20

```
Training Epoch 1: 100% | 33/33 [05:10<00:00, 9.41s/it,
train_loss=0.649]
Validating Epoch 1: 100% | 24/24 [01:07<00:00, 2.80s/it,
val_loss=0.484]
Epoch [1/20], Train Loss: 0.6494, Val Loss: 0.4835, Val Accuracy: 96.04%, Val
AUROC: 0.5763, Partial AUROC: 0.0208
Epoch 2/20
Training Epoch 2: 100% | 33/33 [05:09<00:00, 9.37s/it,
train_loss=0.637]
Validating Epoch 2: 100% | 24/24 [01:08<00:00, 2.86s/it,
val_loss=0.44]
Epoch [2/20], Train Loss: 0.6371, Val Loss: 0.4399, Val Accuracy: 96.04%, Val
AUROC: 0.5812, Partial AUROC: 0.0224
Epoch 3/20
Training Epoch 3: 100% | 33/33 [05:13<00:00, 9.51s/it,
train_loss=0.632]
Validating Epoch 3: 100% | 24/24 [01:09<00:00, 2.88s/it,
val loss=0.427]
Epoch [3/20], Train Loss: 0.6323, Val Loss: 0.4268, Val Accuracy: 96.04%, Val
AUROC: 0.6200, Partial AUROC: 0.0318
Epoch 4/20
Training Epoch 4: 100% | 33/33 [05:12<00:00, 9.46s/it,
train_loss=0.622]
Validating Epoch 4: 100% | 24/24 [01:09<00:00, 2.88s/it,
val_loss=0.421]
Epoch [4/20], Train Loss: 0.6218, Val Loss: 0.4208, Val Accuracy: 96.04%, Val
AUROC: 0.6634, Partial AUROC: 0.0398
Epoch 5/20
Training Epoch 5: 100% | 33/33 [05:13<00:00, 9.49s/it,
train loss=0.613]
Validating Epoch 5: 100% | 24/24 [01:09<00:00, 2.88s/it,
val loss=0.429]
Epoch [5/20], Train Loss: 0.6126, Val Loss: 0.4288, Val Accuracy: 96.04%, Val
AUROC: 0.6879, Partial AUROC: 0.0439
Epoch 6/20
Training Epoch 6: 100% | 33/33 [05:01<00:00, 9.13s/it,
train_loss=0.606]
Validating Epoch 6: 100% | 24/24 [01:07<00:00, 2.81s/it,
val loss=0.42
Epoch [6/20], Train Loss: 0.6055, Val Loss: 0.4201, Val Accuracy: 96.04%, Val
AUROC: 0.7171, Partial AUROC: 0.0529
```

Epoch 7/20

```
Training Epoch 7: 100% | 33/33 [04:58<00:00, 9.05s/it,
train_loss=0.599]
Validating Epoch 7: 100% | 24/24 [01:07<00:00, 2.79s/it,
val loss=0.407]
Epoch [7/20], Train Loss: 0.5989, Val Loss: 0.4068, Val Accuracy: 96.04%, Val
AUROC: 0.7272, Partial AUROC: 0.0528
Epoch 8/20
Training Epoch 8: 100% | 33/33 [05:12<00:00, 9.48s/it,
train_loss=0.591]
Validating Epoch 8: 100% | 24/24 [01:08<00:00, 2.86s/it,
val_loss=0.407
Epoch [8/20], Train Loss: 0.5911, Val Loss: 0.4073, Val Accuracy: 96.04%, Val
AUROC: 0.7430, Partial AUROC: 0.0560
Epoch 9/20
Training Epoch 9: 100% | 33/33 [05:07<00:00, 9.32s/it,
train_loss=0.587]
Validating Epoch 9: 100% | 24/24 [01:10<00:00, 2.95s/it,
val loss=0.405]
Epoch [9/20], Train Loss: 0.5865, Val Loss: 0.4047, Val Accuracy: 95.97%, Val
AUROC: 0.7575, Partial AUROC: 0.0573
Epoch 10/20
Training Epoch 10: 100% | 33/33 [05:11<00:00, 9.43s/it,
train_loss=0.577]
Validating Epoch 10: 100% | 24/24 [01:08<00:00, 2.87s/it,
val_loss=0.399]
Epoch [10/20], Train Loss: 0.5770, Val Loss: 0.3985, Val Accuracy: 95.97%, Val
AUROC: 0.7674, Partial AUROC: 0.0635
Epoch 11/20
Training Epoch 11: 100% | 33/33 [05:11<00:00, 9.44s/it,
train loss=0.567]
Validating Epoch 11: 100% | 24/24 [01:08<00:00, 2.87s/it,
val loss=0.404]
Epoch [11/20], Train Loss: 0.5675, Val Loss: 0.4040, Val Accuracy: 96.04%, Val
AUROC: 0.7689, Partial AUROC: 0.0615
Epoch 12/20
Training Epoch 12: 100% | 33/33 [05:08<00:00, 9.35s/it,
train_loss=0.563]
Validating Epoch 12: 100% | 24/24 [01:11<00:00, 2.97s/it,
val loss=0.389]
Epoch [12/20], Train Loss: 0.5634, Val Loss: 0.3887, Val Accuracy: 95.91%, Val
AUROC: 0.7855, Partial AUROC: 0.0679
```

Epoch 13/20

```
Training Epoch 13: 100% | 33/33 [05:00<00:00, 9.10s/it,
train_loss=0.559]
Validating Epoch 13: 100% | 24/24 [01:09<00:00, 2.90s/it,
val_loss=0.381]
Epoch [13/20], Train Loss: 0.5594, Val Loss: 0.3807, Val Accuracy: 95.91%, Val
AUROC: 0.7903, Partial AUROC: 0.0692
Epoch 14/20
Training Epoch 14: 100% | 33/33 [05:09<00:00, 9.37s/it,
train_loss=0.551]
Validating Epoch 14: 100% | 24/24 [01:09<00:00, 2.89s/it,
val_loss=0.381]
Epoch [14/20], Train Loss: 0.5513, Val Loss: 0.3811, Val Accuracy: 95.91%, Val
AUROC: 0.7868, Partial AUROC: 0.0667
Epoch 15/20
Training Epoch 15: 100% | 33/33 [05:08<00:00, 9.35s/it,
train_loss=0.542]
Validating Epoch 15: 100% | 24/24 [01:08<00:00, 2.86s/it,
val loss=0.379]
Epoch [15/20], Train Loss: 0.5425, Val Loss: 0.3791, Val Accuracy: 95.91%, Val
AUROC: 0.7936, Partial AUROC: 0.0692
Epoch 16/20
Training Epoch 16: 100% | 33/33 [05:04<00:00, 9.23s/it,
train_loss=0.535]
Validating Epoch 16: 100% | 24/24 [01:08<00:00, 2.85s/it,
val_loss=0.37]
Epoch [16/20], Train Loss: 0.5355, Val Loss: 0.3700, Val Accuracy: 95.77%, Val
AUROC: 0.8040, Partial AUROC: 0.0754
Epoch 17/20
Training Epoch 17: 100% | 33/33 [05:03<00:00, 9.18s/it,
train loss=0.523]
Validating Epoch 17: 100% | 24/24 [01:11<00:00, 2.98s/it,
val loss=0.365]
Epoch [17/20], Train Loss: 0.5230, Val Loss: 0.3650, Val Accuracy: 95.91%, Val
AUROC: 0.8042, Partial AUROC: 0.0754
Epoch 18/20
Training Epoch 18: 100% | 33/33 [05:03<00:00, 9.20s/it,
train_loss=0.514]
Validating Epoch 18: 100% | 24/24 [01:08<00:00, 2.86s/it,
val loss=0.375]
Epoch [18/20], Train Loss: 0.5138, Val Loss: 0.3750, Val Accuracy: 94.77%, Val
AUROC: 0.8019, Partial AUROC: 0.0730
```

Epoch 19/20

Training Epoch 19: 100% | 33/33 [05:02<00:00, 9.16s/it,

train\_loss=0.518]

Validating Epoch 19: 100% | 24/24 [01:08<00:00, 2.87s/it,

val\_loss=0.354]

Epoch [19/20], Train Loss: 0.5178, Val Loss: 0.3542, Val Accuracy: 94.90%, Val

AUROC: 0.8084, Partial AUROC: 0.0757

Epoch 20/20

Training Epoch 20: 100% | 33/33 [04:59<00:00, 9.08s/it,

train\_loss=0.501]

Validating Epoch 20: 100% | 24/24 [01:07<00:00, 2.80s/it,

val\_loss=0.352]

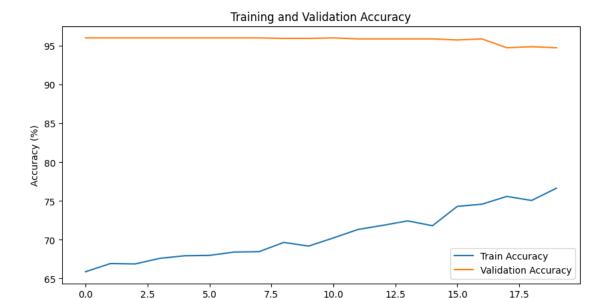
Epoch [20/20], Train Loss: 0.5011, Val Loss: 0.3516, Val Accuracy: 94.77%, Val

AUROC: 0.8129, Partial AUROC: 0.0767

Best Epoch: 20, Best Validation Loss: 0.3516

Training Complete





Epochs

## Classification Report:

	precision	recall	f1-score	support
Class 0	0.97	0.98	0.97	1431
Class 1	0.31	0.27	0.29	59
accuracy			0.95	1490
macro avg	0.64	0.62	0.63	1490
weighted avg	0.94	0.95	0.95	1490

## [11]: CustomImageFeatureResNet(

(resnet): Sequential(

- (0): Conv2d(3, 64, kernel\_size=(7, 7), stride=(2, 2), padding=(3, 3), bias=False)
- (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)
  - (2): ReLU(inplace=True)
- (3): MaxPool2d(kernel\_size=3, stride=2, padding=1, dilation=1, ceil mode=False)
  - (4): Sequential(
    - (0): BasicBlock(

(conv1): Conv2d(64, 64, kernel\_size=(3, 3), stride=(1, 1), padding=(1,

1), bias=False)

(bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,

track\_running\_stats=True)

(relu): ReLU(inplace=True)

```
(conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      )
      (1): BasicBlock(
        (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
     )
    )
    (5): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(64, 128, kernel_size=(3, 3), stride=(2, 2), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (downsample): Sequential(
          (0): Conv2d(64, 128, kernel_size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        )
      )
      (1): BasicBlock(
        (conv1): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      )
    )
    (6): Sequential(
```

```
(0): BasicBlock(
        (conv1): Conv2d(128, 256, kernel size=(3, 3), stride=(2, 2), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (downsample): Sequential(
          (0): Conv2d(128, 256, kernel_size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        )
      )
      (1): BasicBlock(
        (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    )
    (7): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(256, 512, kernel_size=(3, 3), stride=(2, 2), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (downsample): Sequential(
          (0): Conv2d(256, 512, kernel_size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        )
      )
      (1): BasicBlock(
        (conv1): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
```

```
1), bias=False)
              (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
              (relu): ReLU(inplace=True)
              (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
              (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
          )
          (8): AdaptiveAvgPool2d(output size=(1, 1))
        (fc_image): Linear(in_features=512, out_features=512, bias=True)
        (fc_metadata): Linear(in_features=9, out_features=128, bias=True)
        (dropout): Dropout(p=0.5, inplace=False)
        (fc_combined): Linear(in_features=640, out_features=1, bias=True)
      )
     0.7 Model 3
[12]: model3 = CustomImageFeatureResNet(feature_input_size=9) # Assuming 9 features_
       ⇔for metadata
      model3.to(device)
      # Initialize optimizer
      optimizer = optim.SGD(model3.parameters(), lr=0.0001,weight_decay=1e-4)
      # Define the loss function with the class weights
      criterion = nn.BCELoss() # Binary classification loss
      # Set the number of epochs
      epochs = 20
      batch_size = 32
     /home/jupyter-sohka/.local/lib/python3.10/site-
     packages/torchvision/models/_utils.py:208: UserWarning: The parameter
     'pretrained' is deprecated since 0.13 and may be removed in the future, please
     use 'weights' instead.
       warnings.warn(
     /home/jupyter-sohka/.local/lib/python3.10/site-
     packages/torchvision/models/_utils.py:223: UserWarning: Arguments other than a
     weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed
     in the future. The current behavior is equivalent to passing
     `weights=ResNet18_Weights.IMAGENET1K_V1`. You can also use
     `weights=ResNet18_Weights.DEFAULT` to get the most up-to-date weights.
       warnings.warn(msg)
[13]: train_dataloader = DataLoader(train_dataset, batch_size=batch_size,_u
       ⇒shuffle=True)
      val_dataloader = DataLoader(val_dataset, batch_size=batch_size, shuffle=True)
```

```
[14]: train_and_validate(model3,train_dataloader, val_dataloader, criterion,_
      →optimizer, epochs, device )
     Epoch 1/20
     Training Epoch 1: 100% | 66/66 [04:39<00:00, 4.23s/it,
     train_loss=0.7]
     Validating Epoch 1: 100% | 47/47 [01:06<00:00, 1.42s/it,
     val_loss=0.659]
     Epoch [1/20], Train Loss: 0.6999, Val Loss: 0.6592, Val Accuracy: 77.05%, Val
     AUROC: 0.3767, Partial AUROC: 0.0063
     Epoch 2/20
     Training Epoch 2: 100% | 66/66 [04:35<00:00, 4.18s/it,
     train_loss=0.685]
     Validating Epoch 2: 100% | 47/47 [01:07<00:00, 1.44s/it,
     val_loss=0.62]
     Epoch [2/20], Train Loss: 0.6847, Val Loss: 0.6203, Val Accuracy: 92.28%, Val
     AUROC: 0.3632, Partial AUROC: 0.0067
     Epoch 3/20
     Training Epoch 3: 100% | 66/66 [04:42<00:00, 4.28s/it,
     train_loss=0.674]
     Validating Epoch 3: 100% | 47/47 [01:07<00:00, 1.43s/it,
     val_loss=0.586]
     Epoch [3/20], Train Loss: 0.6740, Val Loss: 0.5864, Val Accuracy: 95.57%, Val
     AUROC: 0.3735, Partial AUROC: 0.0074
     Epoch 4/20
     Training Epoch 4: 100% | 66/66 [04:47<00:00, 4.36s/it,
     train loss=0.667]
     Validating Epoch 4: 100% | 47/47 [01:06<00:00, 1.42s/it,
     val_loss=0.558]
     Epoch [4/20], Train Loss: 0.6675, Val Loss: 0.5584, Val Accuracy: 96.04%, Val
     AUROC: 0.3819, Partial AUROC: 0.0084
     Epoch 5/20
     Training Epoch 5: 100% | 66/66 [04:45<00:00, 4.32s/it,
     train_loss=0.663]
     Validating Epoch 5: 100% | 47/47 [01:06<00:00, 1.42s/it,
     val_loss=0.541]
     Epoch [5/20], Train Loss: 0.6630, Val Loss: 0.5414, Val Accuracy: 96.04%, Val
     AUROC: 0.3721, Partial AUROC: 0.0083
     Epoch 6/20
     Training Epoch 6: 100% | 66/66 [04:37<00:00, 4.21s/it,
```

train\_loss=0.65]

```
Validating Epoch 6: 100% | 47/47 [01:07<00:00, 1.44s/it,
val_loss=0.521]
Epoch [6/20], Train Loss: 0.6500, Val Loss: 0.5210, Val Accuracy: 96.04%, Val
AUROC: 0.3960, Partial AUROC: 0.0105
Epoch 7/20
Training Epoch 7: 100% | 66/66 [04:34<00:00, 4.16s/it,
train loss=0.652]
Validating Epoch 7: 100% | 47/47 [01:05<00:00, 1.39s/it,
val loss=0.506]
Epoch [7/20], Train Loss: 0.6518, Val Loss: 0.5059, Val Accuracy: 96.04%, Val
AUROC: 0.4008, Partial AUROC: 0.0120
Epoch 8/20
Training Epoch 8: 100% | 66/66 [04:38<00:00, 4.22s/it,
train_loss=0.645]
Validating Epoch 8: 100% | 47/47 [01:05<00:00, 1.39s/it,
val_loss=0.496
Epoch [8/20], Train Loss: 0.6452, Val Loss: 0.4963, Val Accuracy: 96.04%, Val
AUROC: 0.4022, Partial AUROC: 0.0107
Epoch 9/20
Training Epoch 9: 100% | 66/66 [04:33<00:00, 4.14s/it,
train_loss=0.645]
Validating Epoch 9: 100% | 47/47 [01:07<00:00, 1.43s/it,
val_loss=0.483]
Epoch [9/20], Train Loss: 0.6446, Val Loss: 0.4831, Val Accuracy: 96.04%, Val
AUROC: 0.4151, Partial AUROC: 0.0131
Epoch 10/20
Training Epoch 10: 100% | 66/66 [04:34<00:00, 4.17s/it,
train_loss=0.636]
Validating Epoch 10: 100% | 47/47 [01:04<00:00, 1.38s/it,
val_loss=0.477]
Epoch [10/20], Train Loss: 0.6357, Val Loss: 0.4769, Val Accuracy: 96.04%, Val
AUROC: 0.4274, Partial AUROC: 0.0137
Epoch 11/20
Training Epoch 11: 100% | 66/66 [04:40<00:00, 4.25s/it,
train loss=0.634]
Validating Epoch 11: 100% | 47/47 [01:06<00:00, 1.42s/it,
val_loss=0.47]
Epoch [11/20], Train Loss: 0.6341, Val Loss: 0.4700, Val Accuracy: 96.04%, Val
AUROC: 0.4331, Partial AUROC: 0.0140
Epoch 12/20
Training Epoch 12: 100% | 66/66 [04:41<00:00, 4.26s/it,
```

train\_loss=0.639]

```
Validating Epoch 12: 100% | 47/47 [01:07<00:00, 1.44s/it,
val_loss=0.465]
Epoch [12/20], Train Loss: 0.6386, Val Loss: 0.4655, Val Accuracy: 96.04%, Val
AUROC: 0.4561, Partial AUROC: 0.0164
Epoch 13/20
Training Epoch 13: 100% | 66/66 [04:45<00:00, 4.32s/it,
train loss=0.638]
Validating Epoch 13: 100% | 47/47 [01:07<00:00, 1.43s/it,
val loss=0.46]
Epoch [13/20], Train Loss: 0.6376, Val Loss: 0.4599, Val Accuracy: 96.04%, Val
AUROC: 0.4592, Partial AUROC: 0.0170
Epoch 14/20
Training Epoch 14: 100% | 66/66 [04:44<00:00, 4.30s/it,
train_loss=0.633]
Validating Epoch 14: 100% | 47/47 [01:07<00:00, 1.43s/it,
val_loss=0.454]
Epoch [14/20], Train Loss: 0.6331, Val Loss: 0.4540, Val Accuracy: 96.04%, Val
AUROC: 0.4620, Partial AUROC: 0.0180
Epoch 15/20
Training Epoch 15: 100% | 66/66 [04:44<00:00, 4.30s/it,
train loss=0.632]
Validating Epoch 15: 100% | 47/47 [01:07<00:00, 1.44s/it,
val_loss=0.452]
Epoch [15/20], Train Loss: 0.6315, Val Loss: 0.4521, Val Accuracy: 96.04%, Val
AUROC: 0.4847, Partial AUROC: 0.0194
Epoch 16/20
Training Epoch 16: 100% | 66/66 [04:44<00:00, 4.31s/it,
train_loss=0.63]
Validating Epoch 16: 100% | 47/47 [01:07<00:00, 1.43s/it,
val_loss=0.447
Epoch [16/20], Train Loss: 0.6296, Val Loss: 0.4473, Val Accuracy: 96.04%, Val
AUROC: 0.4830, Partial AUROC: 0.0192
Epoch 17/20
Training Epoch 17: 100% | 66/66 [04:42<00:00, 4.29s/it,
train loss=0.633]
Validating Epoch 17: 100% | 47/47 [01:07<00:00, 1.43s/it,
val_loss=0.444
Epoch [17/20], Train Loss: 0.6327, Val Loss: 0.4435, Val Accuracy: 96.04%, Val
AUROC: 0.4997, Partial AUROC: 0.0210
Epoch 18/20
Training Epoch 18: 100% | 66/66 [04:45<00:00, 4.32s/it,
```

train\_loss=0.629]

Validating Epoch 18: 100% | 47/47 [01:07<00:00, 1.43s/it, val\_loss=0.443]

Epoch [18/20], Train Loss: 0.6285, Val Loss: 0.4429, Val Accuracy: 96.04%, Val

AUROC: 0.5151, Partial AUROC: 0.0219

Epoch 19/20

Training Epoch 19: 100% | 66/66 [04:41<00:00, 4.27s/it,

train loss=0.625]

Validating Epoch 19: 100% | 47/47 [01:06<00:00, 1.42s/it,

val\_loss=0.442]

Epoch [19/20], Train Loss: 0.6254, Val Loss: 0.4423, Val Accuracy: 96.04%, Val

AUROC: 0.5279, Partial AUROC: 0.0251

Epoch 20/20

Training Epoch 20: 100% | 66/66 [04:42<00:00, 4.29s/it,

train\_loss=0.619]

Validating Epoch 20: 100% | 47/47 [01:06<00:00, 1.42s/it,

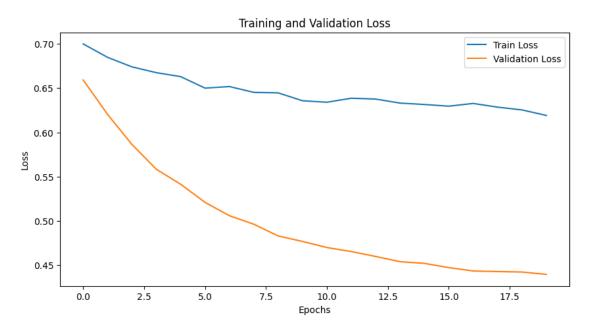
val\_loss=0.44]

Epoch [20/20], Train Loss: 0.6192, Val Loss: 0.4397, Val Accuracy: 96.04%, Val

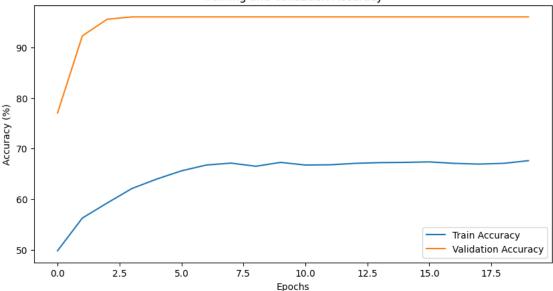
AUROC: 0.5377, Partial AUROC: 0.0247

Best Epoch: 20, Best Validation Loss: 0.4397

Training Complete



Training and Validation Accuracy



#### Classification Report:

	precision	recall	f1-score	support
Class 0	0.96	1.00	0.98	1431
Class 1	0.00	0.00	0.00	59
accuracy			0.96	1490
macro avg	0.48	0.50	0.49	1490
weighted avg	0.92	0.96	0.94	1490

/opt/tljh/user/lib/python3.10/site-

packages/sklearn/metrics/\_classification.py:1531: UndefinedMetricWarning: Precision is ill-defined and being set to 0.0 in labels with no predicted samples. Use `zero\_division` parameter to control this behavior.

\_warn\_prf(average, modifier, f"{metric.capitalize()} is", len(result))
/opt/tljh/user/lib/python3.10/site-

packages/sklearn/metrics/\_classification.py:1531: UndefinedMetricWarning: Precision is ill-defined and being set to 0.0 in labels with no predicted samples. Use `zero\_division` parameter to control this behavior.

\_warn\_prf(average, modifier, f"{metric.capitalize()} is", len(result))
/opt/tljh/user/lib/python3.10/site-

packages/sklearn/metrics/\_classification.py:1531: UndefinedMetricWarning: Precision is ill-defined and being set to 0.0 in labels with no predicted samples. Use `zero\_division` parameter to control this behavior.

\_warn\_prf(average, modifier, f"{metric.capitalize()} is", len(result))

```
[14]: CustomImageFeatureResNet(
        (resnet): Sequential(
          (0): Conv2d(3, 64, kernel size=(7, 7), stride=(2, 2), padding=(3, 3),
      bias=False)
          (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track running stats=True)
          (2): ReLU(inplace=True)
          (3): MaxPool2d(kernel_size=3, stride=2, padding=1, dilation=1,
      ceil mode=False)
          (4): Sequential(
            (0): BasicBlock(
              (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
              (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
              (relu): ReLU(inplace=True)
              (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
              (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track running stats=True)
            (1): BasicBlock(
              (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
              (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
              (relu): ReLU(inplace=True)
              (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
              (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
            )
          )
          (5): Sequential(
            (0): BasicBlock(
              (conv1): Conv2d(64, 128, kernel size=(3, 3), stride=(2, 2), padding=(1,
      1), bias=False)
              (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
              (relu): ReLU(inplace=True)
              (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1,
      1), bias=False)
              (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
      track_running_stats=True)
              (downsample): Sequential(
                (0): Conv2d(64, 128, kernel_size=(1, 1), stride=(2, 2), bias=False)
                (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
```

```
track_running_stats=True)
      )
      (1): BasicBlock(
        (conv1): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      )
    )
    (6): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(128, 256, kernel_size=(3, 3), stride=(2, 2), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (downsample): Sequential(
          (0): Conv2d(128, 256, kernel_size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        )
      )
      (1): BasicBlock(
        (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1,
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      )
    )
    (7): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(256, 512, kernel_size=(3, 3), stride=(2, 2), padding=(1,
```

```
1), bias=False)
             (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
             (relu): ReLU(inplace=True)
             (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
     1), bias=False)
             (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
             (downsample): Sequential(
               (0): Conv2d(256, 512, kernel_size=(1, 1), stride=(2, 2), bias=False)
               (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
             )
           )
           (1): BasicBlock(
             (conv1): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
     1), bias=False)
             (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track_running_stats=True)
             (relu): ReLU(inplace=True)
             (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
     1), bias=False)
             (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
     track running stats=True)
           )
         )
         (8): AdaptiveAvgPool2d(output_size=(1, 1))
      )
       (fc_image): Linear(in_features=512, out_features=512, bias=True)
       (fc_metadata): Linear(in_features=9, out_features=128, bias=True)
       (dropout): Dropout(p=0.5, inplace=False)
       (fc_combined): Linear(in_features=640, out_features=1, bias=True)
     )
[]:
[]:
```