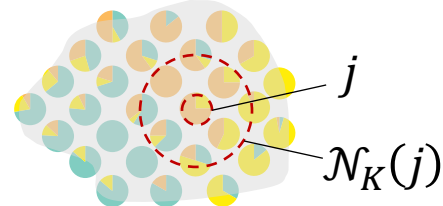


## Uncertainty quantification

spatially variability  $v_j$



$$\lambda_j = \frac{1}{K} \sum_{j \in \mathcal{N}_K(j)} d(z_i, z_j)$$

calibration score

$$v_j = \frac{|z_j - \hat{z}_j|}{\lambda_j}$$

