



Master thesis

**Design and Development of a Compact Dynamic Nuclear
Polarization System for Medical Applications**

Study programme: N0714A150003 – Mechatronics

Author: **Bc. Michal Sojka**

Supervisor: Ing. Ekaterina Vedel

Consultant: Mgr. Michael Pešek, Ph.D.

Liberec 2026

This page has to be replaced
by original of an assignment.

Declaration

I hereby certify, I, myself, have written my master thesis as an original and primary work using the literature listed below and consulting it with my thesis supervisor and my thesis counsellor.

I acknowledge that my master thesis is fully governed by Act No. 121/2000 Coll., the Copyright Act, in particular Article 60 – School Work.

I acknowledge that the Technical University of Liberec does not infringe my copyrights by using my master thesis for internal purposes of the Technical University of Liberec.

I am aware of my obligation to inform the Technical University of Liberec on having used or granted license to use the results of my master thesis; in such a case the Technical University of Liberec may require reimbursement of the costs incurred for creating the result up to their actual amount.

At the same time, I honestly declare that the text of the printed version of my master thesis is identical with the text of the electronic version uploaded into the IS STAG.

I acknowledge that the Technical University of Liberec will make my master thesis public in accordance with paragraph 47b of Act No. 111/1998 Coll., on Higher Education Institutions and on Amendment to Other Acts (the Higher Education Act), as amended.

I am aware of the consequences which under the Higher Education Act result from a breach of this declaration.

24. 2. 2026

Bc. Michal Sojka

Design and Development of a Compact Dynamic Nuclear Polarization System for Medical Applications

Abstrakt

Design and Development of a Compact Dynamic Nuclear Polarization System for Medical Applications

Abstract

Magnetic Resonance Imaging (MRI) is one of the most powerful non-invasive diagnostic tools in modern medicine, yet its sensitivity remains limited by the inherently low nuclear spin polarization achievable at thermal equilibrium. Dynamic Nuclear Polarization (DNP) offers a promising method to overcome this limitation by transferring the high polarization of electron spins to nearby nuclei under low temperature and high magnetic field conditions.

This thesis presents the **design and development of a compact Dynamic Nuclear Polarization (DNP) system for medical applications**, with the goal of enabling enhanced magnetic resonance imaging sensitivity in biomedical and diagnostic research. The project focuses on the *engineering and mechatronic aspects* of the DNP system, integrating cryogenic, electromagnetic, and microwave components into a compact, modular prototype suitable for use with existing MRI or NMR infrastructure.

The work includes the **design and simulation of a 2.5 T superconducting solenoid**, ensuring high field homogeneity for efficient polarization transfer, and the **mechanical and electromagnetic design of a microwave chamber** optimized for uniform power distribution at approximately 70 GHz. A special emphasis is placed on **cryogenic integration**, achieving operational temperatures near 1 K using a liquid helium cooling system and on the **mechanical and vacuum interfaces** necessary for operation in a medical or laboratory environment.

Additionally, the thesis explores the **automation and control of the DNP setup**, including temperature monitoring, and microwave power delivery. The final prototype aims to demonstrate a scalable and cost-effective approach to nuclear hyperpolarization, opening the way for enhanced MRI studies with hyperpolarized stable and radioactive tracers (e.g., ^{13}C , ^{15}N , ^{19}F , or ^{18}F).

Acknowledgements

Contents

List of abbreviations	20
1 Introduction	21
1.1 Motivation and Problem Statement	21
1.2 Project Background	21
1.3 Reader Guidance	22
1.4 Objectives and Scope	23
1.5 Target Requirements and Design Specifications	24
1.6 Thesis Structure	25
2 Theoretical and Technological Background	26
2.1 Magnetic Resonance Imaging Sensitivity and Polarization	26
2.1.1 Intuitive Picture of Net Magnetization (Beer Analogy)	27
2.1.2 Thermal Equilibrium Polarization	27
2.1.3 Spin-Lattice Relaxation and Time Constraints	28
2.2 Principles of Dynamic Nuclear Polarization	29
2.2.1 DNP Mechanisms Relevant for Solid Samples	30
2.2.2 Microwave Irradiation at Cryogenic Temperature	30
2.2.3 Polarization Build-Up and Expected Enhancement	31
2.3 System-Level Requirements for a Compact DNP Setup	32
2.3.1 Magnetic Field Strength and Homogeneity Requirements	32
2.3.2 Cryogenic Temperature Requirements	33
2.3.3 Microwave Frequency and Power Requirements	33
3 System Requirements and Design Constraints	35
3.1 Use Case and Operational Scenarios	35
3.2 Geometrical and Integration Constraints	36
3.2.1 Insert Envelope and Interfaces	37
3.2.2 Compatibility With Dewar/Cryostat Infrastructure	37
3.3 Functional Requirements	38

3.3.1	Sample Handling and Target Region	38
3.3.2	Vacuum and Helium-Tightness Requirements	39
3.3.3	Safety and Operational Limits	39
3.4	Verification Strategy	40
4	Superconducting Magnet Design	41
4.1	Design Rationale and Target Specifications	41
4.2	Solenoid Geometry and Winding Concept	41
4.2.1	Coil Geometry Definition	41
4.2.2	Conductor Selection and Current Density Constraints	41
4.3	Magnetic Field Simulation and Homogeneity Evaluation	41
4.3.1	Simulation Setup and Assumptions	41
4.3.2	Homogeneity Metrics and Evaluation Volume	41
4.3.3	Results and Sensitivity to Tolerances	41
4.4	Mechanical and Cryogenic Considerations	41
4.4.1	Forces, Supports, and Quench Considerations	41
4.4.2	Integration With Cryostat and Current Leads	41
5	Microwave Chamber Development	42
5.1	Functional Role and Design Targets	42
5.2	RF Architecture and Interfaces	42
5.2.1	Waveguide Interface and Transitions	42
5.2.2	Coupling Strategy and Mode Considerations	42
5.3	Mechanical Design and CAD Implementation	42
5.3.1	Key Dimensions, Tolerances, and Materials	42
5.3.2	Manufacturability and Assembly Constraints	42
5.4	Electromagnetic Simulation and Power Distribution	42
5.4.1	Simulation Setup, Boundary Conditions, and Meshing	42
5.4.2	Field Uniformity Metrics in Sample Region	42
5.4.3	Losses, Heating, and Material Selection Impact	42
6	Cryogenic, Vacuum, and Mechanical Integration	43
6.1	Cryogenic Concept and Temperature Stages	43
6.1.1	Heat Loads and Thermal Budget	43
6.1.2	Thermal Anchoring and Wiring/Feedthrough Strategy	43
6.2	Vacuum Interfaces and Sealing Strategy	43
6.2.1	Helium-Tightness and Leak Testing Approach	43
6.2.2	Materials, Surface Treatment, and Cleanliness	43

6.3	Mechanical Support, Alignment, and Assembly Procedure	43
6.3.1	Tolerance Stack-Up and Alignment Features	43
6.3.2	Serviceability and Modular Replacement	43
7	Automation and Control System	44
7.1	Control Objectives and System Architecture	44
7.2	Instrumentation: Sensors and Readout	44
7.2.1	Temperature Monitoring	44
7.2.2	Pressure/Vacuum Monitoring	44
7.2.3	Microwave Source Monitoring and Interlocks	44
7.3	Actuation and Interfaces	44
7.3.1	Heaters and Power Drivers	44
7.3.2	Valves, Pumps, and Pneumatic/Electrical Interfaces	44
7.4	Software Concept and Operational States	44
7.4.1	State Machine and Safety Interlocks	44
7.4.2	Data Logging and Traceability	44
8	Prototype Implementation and Verification	45
8.1	Prototype Build and Assembly Summary	45
8.2	Subsystem Tests	45
8.2.1	Magnetic Field Mapping and Homogeneity Verification	45
8.2.2	Microwave Line and Cavity Characterization	45
8.2.3	Cryogenic Cooldown Tests and Thermal Performance	45
8.2.4	Vacuum and Leak Tests	45
8.3	System-Level Integration Tests	45
8.3.1	End-to-End Operational Procedure (Dry Run)	45
8.3.2	Failure Modes Observed and Mitigations	45
9	Results and Performance Evaluation	46
9.1	Achieved Specifications Versus Requirements	46
9.2	Discussion of Key Engineering Trade-Offs	46
9.3	Limitations of the Current Prototype	46
10	Discussion and Future Work	47
10.1	Lessons Learned During Development	47
10.2	Recommended Design Improvements	47
10.2.1	Magnet and Homogeneity Improvements	47
10.2.2	Microwave Uniformity and Loss Reduction	47
10.2.3	Cryogenic Robustness and Operational Simplification	47

10.2.4	Automation, Safety, and User Workflow Enhancements	47
10.3	Path Toward Experimental Polarization Demonstration	47
11	Conclusion	48
11.1	Summary of Contributions	48
11.2	Outlook	48

List of abbreviations

DNP	Dynamic Nuclear Polarization
MRI	Magnetic Resonance Imaging
CERN	Conseil Européen pour la Recherche Nucléairee
NMR	Nuclear Magnetic Resonance
ISOLDE	Isotope Separator On Line DEvice
LHe	Liquid-Helium

1 Introduction

This chapter introduces the motivation for a compact Dynamic Nuclear Polarization (DNP) system and outlines the scope of the work performed at CERN (Conseil Européen pour la Recherche Nucléaire, *European Council for Nuclear Research*). Additionally, it provides the project’s high-level context, summarizes the thesis objectives, and explains the document’s structure.

1.1 Motivation and Problem Statement

Magnetic Resonance Imaging (MRI) is a non-invasive diagnostic technique whose sensitivity is fundamentally limited by the low thermal equilibrium polarization of nuclear spins. Dynamic nuclear polarization is a well-established approach to increasing nuclear polarization by transferring polarization from electron spins under microwave irradiation at cryogenic temperatures. This enables a significantly enhanced signal-to-noise ratio in downstream Nuclear Magnetic Resonance (NMR) and MRI experiments. The practical adoption of DNP-enhanced workflows is strongly influenced by system complexity, physical footprint and operational robustness. In particular, compact implementations must satisfy stringent requirements regarding magnetic field quality, cryogenic performance, microwave delivery and mechanical/vacuum integration while remaining serviceable and safe for routine operation.

1.2 Project Background

The work presented in this thesis was carried out at CERN (Conseil Européen pour la Recherche Nucléaire, *European Council for Nuclear Research*) in the context of a funded development activity aiming to enable novel tracers for Nuclear Magnetic Resonance and Magnetic Resonance Imaging by using dynamic nuclear polarization in a compact, low-cost, and versatile setup [TODO:Kowalska2023MABudget]. The project builds on CERN know-how originating from polarised target technology, cryogenic engineering, and superconducting magnet development, and

targets an instrument concept that can be deployed with a small superconducting solenoid and a cryogenic insert compatible with commercially available liquid-helium (LHe) dewars commonly present in NMR/MRI laboratories [TODO:Kowalska2023MABudget].

From a system perspective, the intended operational principle follows the established dissolution-DNP workflow: a sample containing a radical is polarized in the solid state at cryogenic temperature under microwave irradiation, subsequently rapidly heated and dissolved, and then transferred for downstream measurement or imaging. The central engineering challenge addressed in this thesis is the realization of such functionality under strict geometric and integration constraints, requiring robust interfaces between the superconducting magnet, the microwave delivery chain and cavity, the cryogenic and vacuum subsystem, and the mechanical structure enabling repeatable assembly and serviceability.

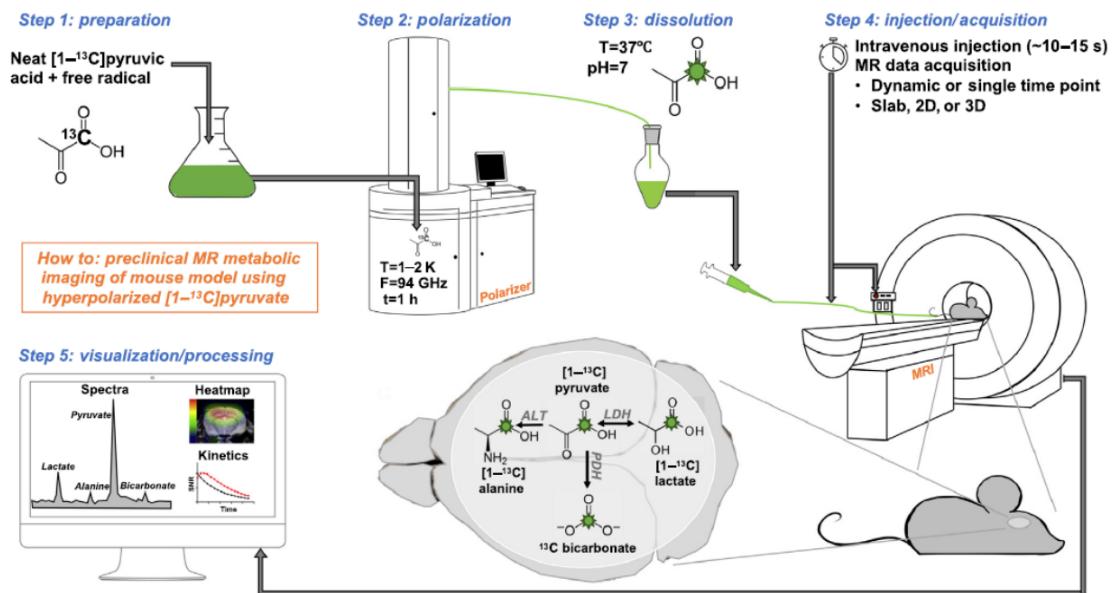


Figure 1.1: Conceptual dissolution-DNP workflow illustrating the main operational steps: sample preparation, polarization at cryogenic temperature under microwave irradiation, rapid dissolution, and transfer for downstream acquisition and processing. Adapted from [TODO:Kowalska2023MABudget].

1.3 Reader Guidance

Although the overall purpose of the developed system is closely connected to experimental physics and magnetic resonance methods, this thesis is written primarily from an engineering perspective. Only the physical phenomena relevant to Dynamic

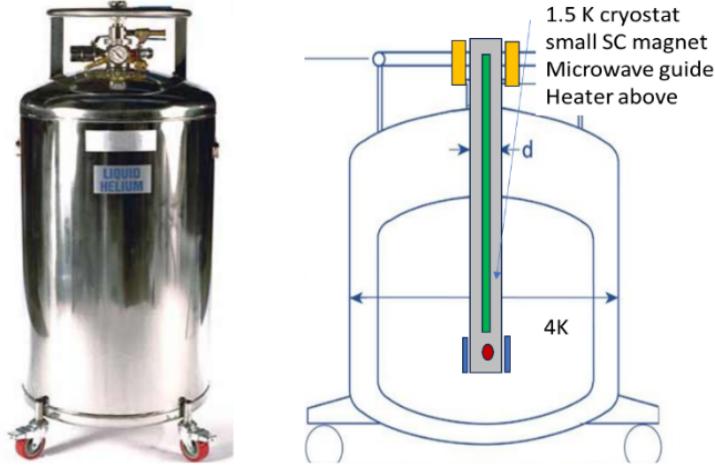


Figure 1.2: Conceptual integration of a compact DNP insert into a commercial LHe dewar, showing the main building blocks relevant for engineering integration: cryogenic insert, small superconducting magnet, microwave guide, and a heating stage for rapid sample melting/dissolution. Adapted from [TODO:Kowalska2023MABudget].

Nuclear Polarization and low-temperature operation are introduced at a level necessary to motivate the design requirements and to support engineering decisions. The main emphasis is placed on system integration, interfaces, mechanical and cryogenic constraints, microwave delivery, verification methodology, and practical implementation aspects.

The author's contributions to the project focus on early-stage engineering development rather than detailed theoretical or experimental physics analyses. Consequently, the discussion intentionally avoids deeper derivations and specialized physics interpretations beyond what is necessary for a technically consistent description of the system and its constraints.

1.4 Objectives and Scope

The main objective of this thesis is to design and validate core subsystems of a compact DNP setup under CERN integration constraints. The work is structured into the following specific goals:

1. Define system-level requirements and interfaces based on the intended operational scenario and physical constraints.
2. Develop the superconducting magnet concept and evaluate magnetic field homogeneity in the target sample region.

3. Design the microwave chamber and interfaces for microwave delivery, including manufacturability and integration aspects.
4. Address cryogenic, vacuum, and mechanical integration constraints, including sealing and thermal anchoring considerations.
5. Propose an automation and control concept suitable for safe operation and traceable measurements.
6. Plan and execute subsystem-level verification activities where feasible within the project timeframe.

1.5 Target Requirements and Design Specifications

The project targets a compact, modular DNP insert compatible with commercial liquid-helium (LHe) dewars, with key specifications driven by the operational needs of solid-state polarization at cryogenic temperature under microwave irradiation, followed by rapid melting/dissolution and transfer to downstream measurement. The primary engineering requirements used throughout this thesis are summarized in Table 1.1.

Table 1.1: Target requirements and design specifications for the compact DNP insert as defined at project level. Values are taken from the project MA Budget submission form.

Subsystem / Parameter	Target Requirement
Cryogenics: Base temperature	$\sim 1.5 \text{ K}$
Cryogenics: Sample loading temperature	$< 100 \text{ K}$
Magnet: Field strength	$> 1 \text{ T}$
Magnet: Candidate operating points	$2.5 \text{ T} @ 70 \text{ GHz}$
Magnet: Homogeneity	around 100 ppm
Microwaves: Frequency range	$> 30 \text{ GHz}$
Microwaves: Output power	$> 1 \text{ W}$
Microwave cavity: Field distribution	Microwave power distribution over sample
Dissolution / heating stage	Melt/liquify sample in a few seconds
Pumping system (for 1.5 K)	Pumping group enabling evaporative cooling
Integration: Host infrastructure	Fit into commercial LHe dewar

The thesis chapters that follow translate these top-level targets into subsystem-level design requirements and verification criteria. In particular, the magnet design is evaluated against the field strength and homogeneity targets, the microwave chamber is developed to support the required frequency/power delivery and field

distribution in the sample region, and the cryogenic/vacuum-mechanical integration is constrained by the temperature target and the host dewar compatibility requirement.

1.6 Thesis Structure

The remainder of this thesis is organized as follows. Chapter 2 summarizes the theoretical and technological background required to justify the key design requirements. Chapter 3 formulates the system requirements and integration constraints. The magnet and microwave chamber developments are presented in Chapter 4 and Chapter 5, respectively. Cryogenic, vacuum, and mechanical integration topics are covered in Chapter 6, followed by the automation and control concept in Chapter 7. Verification activities and achieved results are summarized in Chapter 8 and Chapter 9. Finally, Chapter 10 discusses limitations and future work, and Chapter 11 concludes the thesis.

2 Theoretical and Technological Background

This chapter summarizes the theoretical and technological background required to motivate the key design choices for a compact dynamic nuclear polarization system. The focus is placed on the minimum set of concepts needed to translate the intended application into engineering requirements, namely the sensitivity limitations of magnetic resonance imaging and nuclear magnetic resonance, the principle of polarization enhancement via DNP under microwave irradiation at cryogenic temperature, and the resulting constraints on magnetic field quality, temperature, and microwave delivery. The presented material intentionally remains at a conceptual level and serves as a basis for the requirement definition in Chapter 3 and for the subsequent subsystem development and verification chapters.

2.1 Magnetic Resonance Imaging Sensitivity and Polarization

Magnetic resonance methods are based on detecting the macroscopic magnetization of a very large number of nuclear spins. Each nucleus carrying a magnetic moment can be viewed as a microscopic “compass needle” with a preferred interaction with an applied static magnetic field B_0 . In practice, the signal measured in Nuclear Magnetic Resonance (NMR) and Magnetic Resonance Imaging (MRI) is proportional to the net (vector-summed) magnetization of the sample, and therefore proportional to how strongly the spin ensemble is biased to align with B_0 . This bias is quantified by the nuclear spin polarization and it is the fundamental reason why magnetic resonance methods are inherently sensitivity-limited under normal thermal equilibrium conditions [TODO:MRI_NMR_sensitivity_ref].

From an engineering standpoint, this section provides the minimum intuition required to understand why the system requirements in later chapters are dominated by three parameters: magnetic field strength and homogeneity, temperature,

and time. Field strength and temperature set the achievable thermal equilibrium polarization, while time enters through relaxation processes that continuously drive the system back toward equilibrium.

2.1.1 Intuitive Picture of Net Magnetization (Beer Analogy)

A useful mental model is to separate the problem into two levels: (i) what individual spins do, and (ii) what the large ensemble looks like when averaged. Without an external magnetic field, spins are oriented randomly due to thermal motion, so their contributions cancel and the ensemble magnetization is approximately zero. When a static field B_0 is applied, only discrete orientations (energy states) are allowed for a spin- $\frac{1}{2}$ nucleus, and the ensemble develops a small population imbalance: slightly more spins occupy the lower-energy state aligned with the field than the higher-energy state opposed to the field. This imbalance produces a non-zero net magnetization along B_0 , which is the starting point of all NMR/MRI measurements [TODO:spin_physics_intro_ref].

A (mildly unfair) engineering analogy is to imagine the spins as a crowd after work with “random objectives” (no field): the crowd’s average direction is zero because everyone walks somewhere else. Applying B_0 is like placing two clearly marked exits on the wall: “ α ” (lower-energy, easier door) and “ β ” (higher-energy, slightly harder door). At room temperature, most people still move randomly, but there is a tiny statistical preference for the easier door. The result is not that the crowd suddenly becomes perfectly organised; rather, you get a very small net bias. In magnetic resonance, that small bias is exactly the valuable part — and also the reason why the signal is weak unless additional polarization methods such as Dynamic Nuclear Polarization (DNP) are used [TODO:DNP_intro_ref].

2.1.2 Thermal Equilibrium Polarization

For a spin- $\frac{1}{2}$ nucleus in a static magnetic field B_0 , the thermal equilibrium polarization P_{th} can be expressed as [TODO:spin_temperature_ref]:

$$P_{\text{th}} = \tanh\left(\frac{\gamma\hbar B_0}{2k_B T}\right), \quad (2.1)$$

where γ is the gyromagnetic ratio of the nucleus in $\text{rad s}^{-1} \text{T}^{-1}$, \hbar is the reduced Planck constant in J s , k_B is the Boltzmann constant in J K^{-1} , and T is the absolute temperature in K. For typical operating conditions, the argument of the hyperbolic

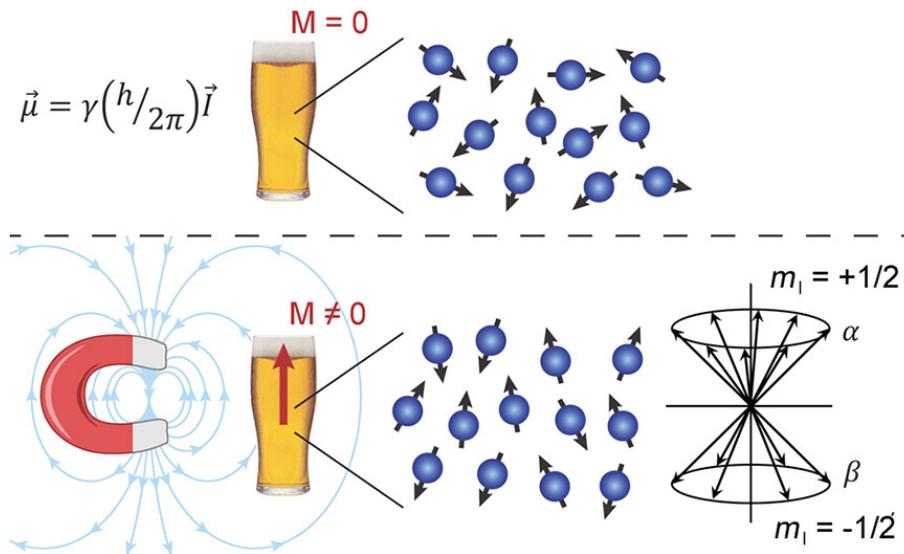


Figure 2.1: Illustration of the net magnetization concept. Without an external field, spin orientations are random and the ensemble magnetization is approximately zero ($M = 0$). In an applied static field B_0 , the allowed spin states split into a lower-energy α state and a higher-energy β state for a spin- $\frac{1}{2}$ nucleus, leading to a small population imbalance and a non-zero net magnetization ($M \neq 0$). Adapted from [TODO:<https://pubs.acs.org/doi/10.1021/acs.chemrev.2c00534>].

tangent is small and the polarization is approximately linear:

$$P_{\text{th}} \approx \frac{\gamma \hbar B_0}{2k_B T} \quad \text{for} \quad \frac{\gamma \hbar B_0}{2k_B T} \ll 1. \quad (2.2)$$

Equations 2.1–2.2 capture the scaling that is directly relevant for system engineering: increasing B_0 and decreasing T increases the available polarization and therefore the available signal. In a compact system, however, magnet dimensions, cryogenic complexity, and integration interfaces limit how far B_0 and T can be pushed in practice. DNP addresses this limitation by transferring polarization from electron spins to nuclear spins under microwave irradiation, effectively creating a much larger nuclear polarization than thermal equilibrium would provide at the same B_0 and T [TODO:DNP_fundamentals_ref].

2.1.3 Spin-Lattice Relaxation and Time Constraints

Spin-lattice relaxation describes the tendency of the nuclear spin system to return toward thermal equilibrium by exchanging energy with its environment. The characteristic time constant is the longitudinal relaxation time T_1 , which governs the evolution of the longitudinal magnetization M_z toward its equilibrium value M_0

[TODO:relaxation_ref]:

$$M_z(t) = M_0 + (M_z(0) - M_0) \exp\left(-\frac{t}{T_1}\right), \quad (2.3)$$

where t is time in s. In practical terms, T_1 sets the “expiration time” of any enhanced polarization once the sample conditions change. This is particularly relevant for dissolution-DNP workflows, where the sample is rapidly heated and transferred: while the engineering system is moving the sample from the polarizer to downstream acquisition, nature is continuously moving the polarization back toward thermal equilibrium [TODO:dissolution_dnp_workflow_ref].

For system engineering, this implies that time-dependent losses must be managed by design. Heating/dissolution should be fast and repeatable, transfer dead volumes and flow impedance should be minimized, and operational procedures should be designed to reduce unnecessary delays. In addition, the temperature profile and magnetic field environment along the sample path influence relaxation, and therefore must be treated as part of the integrated design rather than as isolated subsystem details [TODO:hyperpolarized_transfer_constraints_ref].

2.2 Principles of Dynamic Nuclear Polarization

Dynamic Nuclear Polarization (DNP) is a technique that increases nuclear spin polarization by transferring polarization from electron spins to nuclear spins. The engineering relevance of DNP follows directly from the polarization scaling introduced in section 2.1: because the electron gyromagnetic ratio is much larger than the nuclear gyromagnetic ratio, electron spins can reach a substantially higher thermal equilibrium polarization under the same magnetic field and temperature. DNP uses microwave irradiation to drive transitions that couple the electron and nuclear spin systems, thereby enabling nuclear polarization levels far above the thermal equilibrium value [TODO:DNP_fundamentals_ref].

In practical solid-state implementations, DNP requires (i) a paramagnetic agent providing unpaired electrons (typically a radical), (ii) a cryogenic environment to maximize electron polarization and reduce relaxation losses, (iii) a magnetic field defining the resonance frequencies, and (iv) a microwave delivery system that provides sufficient and stable power at the required frequency. The following subsections summarize the underlying mechanisms at a conceptual level and translate them into engineering constraints that influence the design choices presented in later chapters.

2.2.1 DNP Mechanisms Relevant for Solid Samples

Several microscopic mechanisms can enable polarization transfer from electrons to nuclei in solids. The detailed regime depends on the electron spin resonance linewidth, the nuclear Larmor frequency, the type and concentration of the radical, and the operating field and temperature [TODO:DNP_mechanisms_review]. For the purposes of this thesis, it is sufficient to distinguish the following commonly referenced mechanisms:

- **Solid Effect:** polarization transfer is driven by microwave irradiation at frequencies offset from the electron resonance by approximately the nuclear Larmor frequency. Conceptually, this corresponds to “forbidden” transitions in which electron and nuclear spins flip in a correlated manner. It is typically associated with relatively narrow electron resonance lines [TODO:solid_effect_ref].
- **Cross Effect:** the transfer involves two coupled electron spins and one nuclear spin. The mechanism becomes efficient when the difference between the resonance frequencies of two electrons matches the nuclear Larmor frequency. In many practical high-field DNP systems with suitable radicals, the cross effect is often the dominant pathway [TODO:cross_effect_ref].
- **Thermal Mixing:** in systems with high electron spin concentration and broad electron resonance, the electron spin ensemble can be treated as an effective “spin reservoir” with a spin temperature, enabling polarization exchange with nuclei. This mechanism is often discussed for certain radicals and conditions where strong electron-electron interactions are present [TODO:thermal_mixing_ref].

From an engineering perspective, the important point is that these mechanisms impose requirements on microwave frequency stability and tuning capability, magnetic field stability and homogeneity in the sample region, and on the achievable microwave magnetic field distribution inside the cavity. The thesis therefore does not attempt to select or optimize a radical chemistry; instead, it focuses on the hardware infrastructure that allows relevant operating conditions to be reached and controlled repeatably.

2.2.2 Microwave Irradiation at Cryogenic Temperature

Microwave irradiation is the actuator that enables DNP: it drives electron spin transitions at (or near) the electron Larmor frequency. For a magnetic field B_0 , the

Larmor angular frequency ω of a spin species is given by [TODO:larmor_ref]:

$$\omega = \gamma B_0, \quad (2.4)$$

where γ is the gyromagnetic ratio in $\text{rad s}^{-1} \text{T}^{-1}$. Using the corresponding frequency $f = \omega/(2\pi)$, this relationship directly links the selected magnet operating field to the required microwave frequency range for electron spin resonance. Consequently, early system-level decisions (e.g., selecting a 2.5 T vs. 3.35 T operating point) propagate into concrete engineering requirements on microwave sources, waveguides, vacuum feedthroughs, and cavity geometry [TODO:Kowalska2023MABudget].

Cryogenic temperature is essential for two reasons. First, it increases electron polarization, providing a stronger “polarization source” for transfer to nuclei. Second, it generally improves polarization retention by reducing relaxation rates, which is critical because DNP build-up is not instantaneous. For implementation, this means the microwave chain must remain functional and stable under cryogenic and vacuum boundary conditions, and the cavity region must be designed to distribute microwave power efficiently at the sample location while managing losses and undesired heating in nearby components [TODO:cryogenic_microwave_design_ref].

2.2.3 Polarization Build-Up and Expected Enhancement

Under constant DNP conditions (fixed B_0 , temperature, radical system, and microwave irradiation), the nuclear polarization typically approaches a steady-state value over time. A common engineering-level model is an exponential build-up [TODO:dnp_buildup_model_ref]:

$$P(t) = P_\infty \left(1 - \exp\left(-\frac{t}{T_b}\right) \right), \quad (2.5)$$

where $P(t)$ is the nuclear polarization at time t , P_∞ is the steady-state polarization under the applied DNP conditions, and T_b is an effective build-up time constant.

For the system design described in this thesis, Equation 2.5 provides the key practical implication: achieving a useful polarization requires maintaining stable operating conditions for a non-negligible time, and therefore the cryogenic and microwave subsystems must be designed for reliable steady-state operation. In addition, the achievable enhancement in downstream NMR/MRI depends not only on P_∞ but also on how much polarization is retained during subsequent steps such as rapid heating/dissolution and transfer, which motivates a strong emphasis on minimizing thermal and timing overheads in the integrated system design

[TODO:dissolution_dnp_workflow_ref].

2.3 System-Level Requirements for a Compact DNP Setup

The concepts introduced in section 2.1 and section 2.2 translate into a small set of system-level requirements that dominate the engineering design of a compact Dynamic Nuclear Polarization (DNP) setup. In particular, the achievable polarization and the practical usability of the system are constrained by (i) the static magnetic field strength and its homogeneity in the sample region, (ii) the attainable cryogenic temperature and thermal stability, and (iii) the ability to deliver sufficient microwave power at the required frequency with a suitable field distribution in the cavity. These targets drive the subsystem designs presented in later chapters and are summarized in Table ?? [TODO:Kowalska2023MABudget].

Table 2.1: Key target values used as baseline specifications for the compact DNP setup. Values are taken from the project definition [TODO:Kowalska2023MABudget].

Parameter	Target Value	Notes
Selected operating point	2.5 T @ 70 GHz	Baseline chosen for this thesis (reason discussed later)
Base temperature	$\sim 1.5 \text{ K}$	Flow-type ^4He cryostat with evaporative cooling.
Sample loading temperature	$< 100 \text{ K}$	Or below the freezing point of the sample formulation
Microwave output power	$> 1 \text{ W}$	Output power requirement for efficient irradiation.

In addition to the target values listed in Table 2.1, several qualitative requirements strongly influence the engineering design. These include a magnetic field strength exceeding 1 T with a homogeneity on the order of 100 ppm in the sample region, a microwave frequency capability above 30 GHz consistent with the selected operating point, and a microwave cavity design that provides an even microwave field distribution over the sample volume [TODO:Kowalska2023MABudget]. Finally, the dissolution/heating stage is expected to enable melting/dissolution within a few seconds, which introduces time-critical constraints on thermal actuation and operational procedures.

2.3.1 Magnetic Field Strength and Homogeneity Requirements

The static magnetic field B_0 determines both the baseline thermal polarization (Equation 2.1) and the electron resonance condition that sets the microwave frequency requirement (Equation 2.4). At project level, the magnetic field strength

is required to exceed 1 T, with candidate operating points of 2.5 T and 3.35 T discussed in the initial system concept [TODO:Kowalska2023MABudget]. For the work presented in this thesis, the 2.5 T operating point is selected as the baseline, corresponding to a 70 GHz microwave chain. The detailed rationale and practical considerations behind this selection are discussed later in the thesis (including equipment availability and integration aspects).

Beyond field strength, the field quality in the sample region is a primary performance driver. A homogeneity on the order of 100 ppm is targeted [TODO:Kowalska2023MABudget]. From an engineering perspective, this requirement translates into constraints on coil geometry, winding tolerances, mechanical alignment, and assembly repeatability. In compact solenoid geometries, end effects and tolerance stack-up can dominate the achievable homogeneity, motivating simulation-based evaluation and tolerance sensitivity analyses in the magnet development chapter.

2.3.2 Cryogenic Temperature Requirements

DNP performance benefits from cryogenic operation because electron polarization increases with decreasing temperature and relaxation losses can be reduced. The project targets a base temperature of approximately 1.5 K, implemented using a flow-type ^4He cryostat with evaporative cooling [TODO:Kowalska2023MABudget]. In addition, the sample loading procedure must maintain the sample below 100 K (or below the freezing point of the specific sample formulation) [TODO:Kowalska2023MABudget]. These targets impose system-level constraints on the thermal design, including heat-load control, thermal anchoring of wiring and microwave components, and helium-tight sealing of interfaces that separate vacuum and helium spaces.

For a compact insert intended for deployment in commercial liquid-helium (LHe) dewars, the cryogenic concept also constrains the mechanical layout and serviceability. Components placed near the cold region must be selected and designed for cryogenic compatibility, while maintaining interfaces that enable assembly, alignment, and leak testing under realistic laboratory conditions.

2.3.3 Microwave Frequency and Power Requirements

Microwave irradiation is required to drive the electron spin transitions that enable polarization transfer. The project definition specifies a microwave system operating above 30 GHz with an output power exceeding 1 W

[TODO:Kowalska2023MABudget]. With the selected 2.5 T operating point, the baseline microwave frequency for this thesis is 70 GHz. Delivering this power into a cryogenic cavity is an engineering challenge because waveguide and feedthrough losses, impedance mismatches, and mechanical tolerances can significantly affect the power delivered to the sample region.

In addition to power and frequency, the microwave cavity must provide a sufficiently even microwave field distribution over the sample volume [TODO:Kowalska2023MABudget]. This requirement impacts the cavity geometry, coupling strategy, and alignment features. Since microwave losses can introduce undesired heating, the microwave design must also account for loss budgeting and thermal management, particularly in the vicinity of the 1.5 K stage.

3 System Requirements and Design Constraints

This chapter translates the system-level targets introduced in Chapter 2 into concrete engineering requirements and practical design constraints. The compact Dynamic Nuclear Polarization (DNP) setup is treated as an integrated system composed of a superconducting magnet, a microwave delivery chain and cavity, a cryogenic insert compatible with a commercial liquid-helium (LHe) dewar, and supporting vacuum, mechanical, and control subsystems. The purpose of this chapter is to define the operational scenarios, identify the geometrical and interface limitations, specify functional requirements that guide the design work, and describe the verification approach used throughout the thesis [TODO:Kowalska2023MABudget].

3.1 Use Case and Operational Scenarios

The intended use case is the generation of a hyperpolarized sample using dissolution-DNP principles, with the compact insert operating inside a commercial LHe dewar. From an engineering perspective, the process can be represented as an end-to-end operational workflow with clearly defined states and time-critical transitions. A representative operational sequence is outlined below [TODO:dissolution_dnp_workflow_ref]:

1. **Preparation:** A sample containing a suitable paramagnetic agent is prepared and loaded into the sample holder. The system is assembled and checked for mechanical integrity and required connections (microwave, sensors, pumping lines).
2. **Cooldown and Stabilisation:** The insert is cooled down to a base temperature of approximately 1.5 K. The vacuum and pumping configuration is established to enable evaporative cooling, and the thermal stability of the cold stage is verified.

3. **Polarisation Phase:** The superconducting magnet is energised to the selected operating point of 2.5 T. Microwave irradiation at 70 GHz with an output power exceeding 1 W is applied to the cavity region. The sample remains in the target region for a sufficient build-up duration.
4. **Rapid Heating/Dissolution:** A heater stage is activated to melt/liquify the sample within a few seconds. The process must be repeatable and should minimise unnecessary thermal load to the surrounding cryogenic stages.
5. **Transfer and Downstream Use:** The sample is transferred for downstream measurement or imaging. The transfer path and procedure should be designed to minimise polarization loss and to support repeatable operation.
6. **Reset or Shutdown:** Depending on the use case, the system returns to a standby state, prepares for a subsequent run, or is warmed up and disassembled for maintenance.

In addition to the nominal sequence above, the system must support non-nominal operational scenarios relevant for safe and maintainable laboratory operation:

- **Standby / Hold:** Maintaining cryogenic temperature without applying microwaves, for preparation or scheduling reasons.
- **Maintenance Mode:** Warm state access to the sample region and cavity for cleaning, replacement, or mechanical adjustments.
- **Emergency Stop:** Immediate microwave shutdown and controlled transition to a safe state (including heater cutoff and safe magnet ramping strategy).

3.2 Geometrical and Integration Constraints

The compact DNP setup is designed as an insert intended to be deployed in existing laboratory infrastructure rather than requiring a dedicated cryostat. As a consequence, the dominant constraints are defined by the geometry and interfaces of commercial LHe dewars, by the practicalities of installation/removal, and by the routing of microwave, pumping, and instrumentation lines. These constraints strongly influence subsystem design choices, especially the mechanical stack-up between the magnet, microwave cavity, and sample region [TODO:Kowalska2023MABudget].

3.2.1 Insert Envelope and Interfaces

The insert envelope is limited by the available dewar neck diameter and the permissible overall insert length. The design must therefore meet a strict outer diameter constraint while accommodating internal components such as the magnet bore, microwave guide, thermal shields, wiring, and the sample handling mechanism. The envelope and interface requirements are summarised as follows:

- **Outer envelope:** **TODO: insert maximum outer diameter and usable length based on the target dewar specification.**
- **Top interface:** A top plate/flange providing mechanical support, alignment references, and routing of services (pumping, electrical, microwave).
- **Service routing:** Dedicated paths for the microwave guide (waveguide), instrumentation wiring (temperature/pressure sensors), and heater power lines, with provisions for strain relief and repeatable assembly.
- **Alignment:** Defined alignment features to position the sample region relative to the magnet centre and the microwave cavity with controlled tolerances.

Wherever possible, the mechanical design should support modular replacement of subsystems (e.g., cavity parts, sample holder, feedthrough components) to simplify iteration and maintenance. Interface definitions are treated as first-class design inputs and are referenced throughout the mechanical and subsystem chapters.

3.2.2 Compatibility With Dewar/Cryostat Infrastructure

A key project requirement is compatibility with commercial LHe dewars commonly available in NMR/MRI laboratories [**TODO:Kowalska2023MABudget**]. The design is therefore constrained by what such infrastructure can realistically provide and what must be integrated into the insert itself. The following compatibility aspects are considered:

- **Cryogenic environment:** The insert must operate in a liquid-helium environment and support evaporative cooling to reach $\sim 1.5\text{ K}$, which implies suitable pumping connections and helium-tight interfaces.
- **Installation and handling:** The insert should be installable and removable without specialised equipment beyond common laboratory tools. Handling constraints include weight distribution, clearance above the dewar, and safe routing of external lines.

- **Pumping infrastructure:** Evaporative cooling requires a pumping group; the system design must define compatible pumping line dimensions and connection standards [TODO:Kowalska2023MABudget].
- **Laboratory integration:** The microwave source, control electronics, and safety interlocks must integrate with a typical laboratory environment (cable lengths, access, and shielding).

3.3 Functional Requirements

Functional requirements describe what the system must achieve during operation, independent of a specific mechanical implementation. In this thesis, functional requirements are expressed in a way that supports verification by analysis, simulation, or measurement. Where exact numeric acceptance criteria are not fixed at the time of writing, they are stated as design intents with a planned verification method and a **TODO** placeholder for the final threshold.

3.3.1 Sample Handling and Target Region

The sample handling concept must provide repeatable placement of the sample into the defined target region inside the magnet and microwave cavity. This target region is the volume for which the field homogeneity and microwave field distribution requirements apply. The functional requirements include:

- **Repeatable positioning:** The sample position must be repeatable to within **TODO: insert positioning tolerance** in order to ensure comparable operating conditions between runs.
- **Thermal control:** The sample must reach and remain at the base temperature stage during polarisation, with a controlled loading procedure below 100 K (or below the freezing point of the sample formulation) [TODO:Kowalska2023MABudget].
- **Workflow readiness:** The design must allow rapid transition between polarisation and heating/dissolution, including electrical and thermal interfaces to the heater stage.
- **Serviceability:** The sample holder should be removable and inspectable, supporting cleaning and replacement without disassembling the full insert where possible.

3.3.2 Vacuum and Helium-Tightness Requirements

Stable operation near 1.5 K requires controlled separation of helium spaces and vacuum spaces, as well as robust sealing of interfaces that experience thermal cycling. Helium leaks can compromise cooling performance and introduce operational risks, while air ingress can lead to ice formation and degradation of thermal interfaces. The following functional requirements are therefore defined:

- **Helium-tight interfaces:** Interfaces separating helium and vacuum (or helium and ambient) must meet helium leak-tightness requirements suitable for cryogenic operation. **TODO: insert leak rate acceptance criterion and test method.**
- **Vacuum integrity:** Vacuum regions must reach the required pressure range for thermal insulation and cryogenic stability. **TODO: insert pressure target (order-of-magnitude) and measurement approach.**
- **Thermal cycling robustness:** Seals and joints must remain functional across repeated cool-down and warm-up cycles. Materials and seal types must be compatible with cryogenic temperatures and differential thermal contraction.

3.3.3 Safety and Operational Limits

The system combines cryogenics, superconducting magnets, microwave power, heaters, and vacuum infrastructure. Even at prototype stage, safe operation requires explicit limits and interlocks. The safety-related functional requirements considered in this thesis include:

- **Microwave safety:** Microwave generation must be enabled only when the waveguide chain is properly connected and shielding is in place. An interlock concept should be defined to avoid unintended irradiation.
- **Thermal safety:** Heater operation must be limited to prevent damage to nearby cryogenic components. Temperature monitoring and cutoff thresholds are required. **TODO: define maximum heater power and temperature cutoffs.**
- **Magnet safety:** Magnet energisation must follow a controlled ramp procedure. Quench considerations, mechanical forces, and stored energy management are addressed at design level. **TODO: define current limits and ramp rate constraints.**

- **Cryogenic and pressure safety:** Interfaces and lines must be protected against overpressure by appropriate relief/venting strategies. **TODO: define relief concept and pressure thresholds.**

3.4 Verification Strategy

Verification is structured as a combination of simulation-based evaluation, inspection, and subsystem-level tests, selected to match the project maturity and the scope of this thesis. The strategy follows a requirement-to-method mapping: each requirement is assigned a verification method (analysis/simulation, inspection, or measurement) and a reference to where the evidence is presented in later chapters. Table 3.1 provides a compact overview.

Table 3.1: Mapping of key requirements to verification methods and thesis locations. Where verification is not completed within the thesis timeframe, the planned method is stated as a **TODO**.

Requirement	Verification Method	Evidence in
2.5 T operating point, field quality	Simulation / analysis	Chapter 4
Field homogeneity (~ 100 ppm)	Simulation; mapping test (TODO)	Chapter 4
~ 1.5 K cryogenic operation	Thermal design + cooldown test (TODO)	Chapter 6
70 GHz, > 1 W microwave delivery	RF analysis + bench test (TODO)	Chapter 5
Helium-tightness / vacuum integrity	Leak test and pumping test (TODO)	Chapter 6
Safety interlocks and operational limits	Review + functional testing (TODO)	Chapter 7

4 Superconducting Magnet Design

4.1 Design Rationale and Target Specifications

4.2 Solenoid Geometry and Winding Concept

4.2.1 Coil Geometry Definition

4.2.2 Conductor Selection and Current Density Constraints

4.3 Magnetic Field Simulation and Homogeneity Evaluation

4.3.1 Simulation Setup and Assumptions

4.3.2 Homogeneity Metrics and Evaluation Volume

4.3.3 Results and Sensitivity to Tolerances

4.4 Mechanical and Cryogenic Considerations

4.4.1 Forces, Supports, and Quench Considerations

4.4.2 Integration With Cryostat and Current Leads

5 Microwave Chamber Development

5.1 Functional Role and Design Targets

5.2 RF Architecture and Interfaces

5.2.1 Waveguide Interface and Transitions

5.2.2 Coupling Strategy and Mode Considerations

5.3 Mechanical Design and CAD Implementation

5.3.1 Key Dimensions, Tolerances, and Materials

5.3.2 Manufacturability and Assembly Constraints

5.4 Electromagnetic Simulation and Power Distribution

5.4.1 Simulation Setup, Boundary Conditions, and Meshing

5.4.2 Field Uniformity Metrics in Sample Region

5.4.3 Losses, Heating, and Material Selection Impact

6 Cryogenic, Vacuum, and Mechanical Integration

6.1 Cryogenic Concept and Temperature Stages

6.1.1 Heat Loads and Thermal Budget

6.1.2 Thermal Anchoring and Wiring/Feedthrough Strategy

6.2 Vacuum Interfaces and Sealing Strategy

6.2.1 Helium-Tightness and Leak Testing Approach

6.2.2 Materials, Surface Treatment, and Cleanliness

6.3 Mechanical Support, Alignment, and Assembly Procedure

6.3.1 Tolerance Stack-Up and Alignment Features

6.3.2 Serviceability and Modular Replacement

7 Automation and Control System

7.1 Control Objectives and System Architecture

7.2 Instrumentation: Sensors and Readout

7.2.1 Temperature Monitoring

7.2.2 Pressure/Vacuum Monitoring

7.2.3 Microwave Source Monitoring and Interlocks

7.3 Actuation and Interfaces

7.3.1 Heaters and Power Drivers

7.3.2 Valves, Pumps, and Pneumatic/Electrical Interfaces

7.4 Software Concept and Operational States

7.4.1 State Machine and Safety Interlocks

7.4.2 Data Logging and Traceability

8 Prototype Implementation and Verification

8.1 Prototype Build and Assembly Summary

8.2 Subsystem Tests

8.2.1 Magnetic Field Mapping and Homogeneity Verification

8.2.2 Microwave Line and Cavity Characterization

8.2.3 Cryogenic Cooldown Tests and Thermal Performance

8.2.4 Vacuum and Leak Tests

8.3 System-Level Integration Tests

8.3.1 End-to-End Operational Procedure (Dry Run)

8.3.2 Failure Modes Observed and Mitigations

9 Results and Performance Evaluation

9.1 Achieved Specifications Versus Requirements

9.2 Discussion of Key Engineering Trade-Offs

9.3 Limitations of the Current Prototype

10 Discussion and Future Work

10.1 Lessons Learned During Development

10.2 Recommended Design Improvements

10.2.1 Magnet and Homogeneity Improvements

10.2.2 Microwave Uniformity and Loss Reduction

10.2.3 Cryogenic Robustness and Operational Simplification

10.2.4 Automation, Safety, and User Workflow Enhancements

10.3 Path Toward Experimental Polarization Demonstration

11 Conclusion

11.1 Summary of Contributions

11.2 Outlook

List of Figures

1.1	Conceptual Dissolution-DNP Workflow	22
1.2	Compact Insert Concept For LHe Dewar	23
2.1	Net Magnetization With and Without a Static Field	28

List of Tables

1.1	Target Requirements for the Compact DNP Insert	24
2.1	Key Target Values for the Compact DNP Setup	32
3.1	Verification Strategy Mapping	40

Listings