

view\_frames Result

Recorded at time: 408.137

odom

Broadcaster: /gazebo\_odom  
Average rate: 20.215 Hz  
Most recent transform: 408.124 ( 0.013 sec old)  
Buffer length: 4.650 sec

base\_footprint

Broadcaster: /robot\_0/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 408.137 sec old)  
Buffer length: 0.000 sec

base\_link

Broadcaster: /robot\_0/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 408.137 sec old)  
Buffer length: 0.000 sec

hokuyo\_front\_link

Broadcaster: /robot\_0/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 408.137 sec old)  
Buffer length: 0.000 sec

hokuyo\_rear\_link

robot\_2\_odom

Broadcaster: /gazebo  
Average rate: 10.121 Hz  
Most recent transform: 408.038 ( 0.099 sec old)  
Buffer length: 4.545 sec

robot\_2\_obstacle

robot\_1\_odom

Broadcaster: /gazebo  
Average rate: 10.119 Hz  
Most recent transform: 408.049 ( 0.088 sec old)  
Buffer length: 4.546 sec

robot\_1\_obstacle

robot\_0deprecated\_odom

Broadcaster: /gazebo  
Average rate: 10.121 Hz  
Most recent transform: 408.054 ( 0.083 sec old)  
Buffer length: 4.545 sec

robot\_0platform

Broadcaster: /robot\_0/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 408.137 sec old)  
Buffer length: 0.000 sec

imu\_link