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### Problem 1

#### Solution

$$a = \sum_{i=1}^{10} k_i$$

## Problem 2

Listing 1: demo

- 根據文獻 [1]
- 根據文獻 [2]
- 根據文獻 [3]

# Problem 3

# Problem 4

## References

- [1] E. C. Chen, I. Morgan, U. Jayarathne, B. Ma, and T. M. Peters, "Hand–eye calibration using a target registration error model," *Healthcare Technology Letters*, vol. 4, no. 5, pp. 157–162, 2017.
- [2] P. Features, "A Simple Robotic Eye-In-Hand Camera Positioning Parallelogram Features," 2018.
- [3] R. Szeliski, "Computer Vision: Algorithms and Applications," *Computer*, vol. 5, p. 832, 2010.