EE 511: Spring 2018 Simulation Methods for Stochastic Systems Project #5: Optimization & Sampling via MCMC

[MCMC for Sampling]

```
nsamples=1000;
delta=0.5;
pd1 = \emptyset(x) betapdf(x,1,8);
pd2 = @(x)betapdf(x,9,1);
pdf = @(x)(0.6*pd1(x) + 0.4*pd2(x));
start=0;
proppdf = @(x,y) normpdf(y-x,0,1);
proprnd = @(x) x + rand*2*delta - delta;
tic;
smpl =
mhsample(start,nsamples,'pdf',pdf,'proppdf',proppdf',proprnd',proprnd);
t=toc;
xxhat = cumsum(smpl.^2)./(1:nsamples)';
figure;
plot(1:nsamples,xxhat)
figure;
h = histfit(smpl,50);
h(1).FaceColor = [.8 .8 1];
```

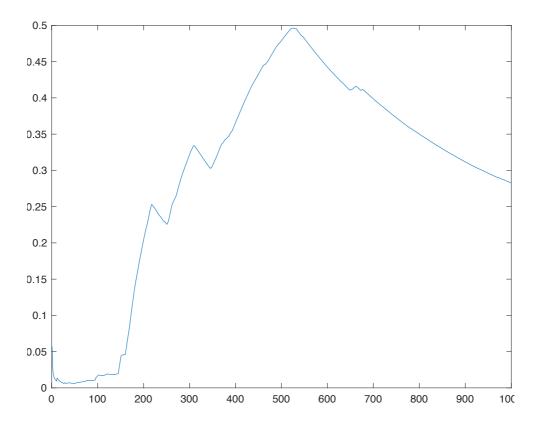


Figure 1: MH Algo sample path gausian start from 0

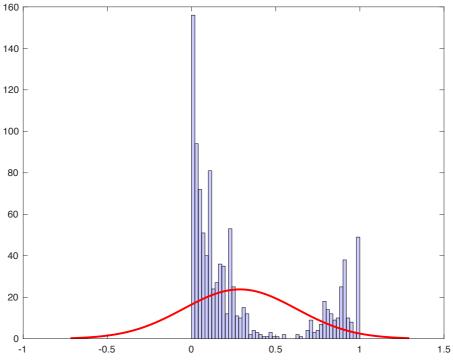
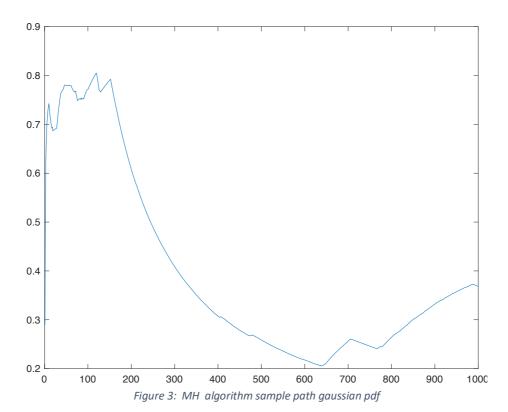


Figure 2: MH algorithm histogram start from 0



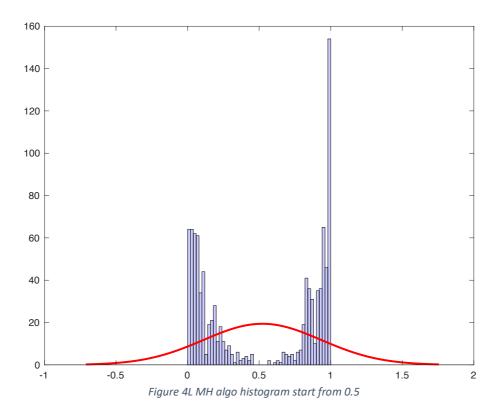


Figure 5: MH algorithm for uniformpdf (-.5,+.5)

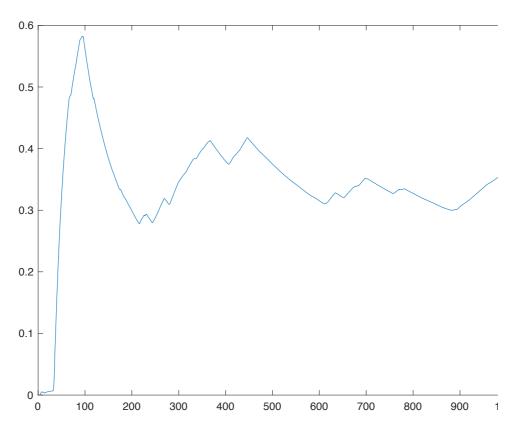
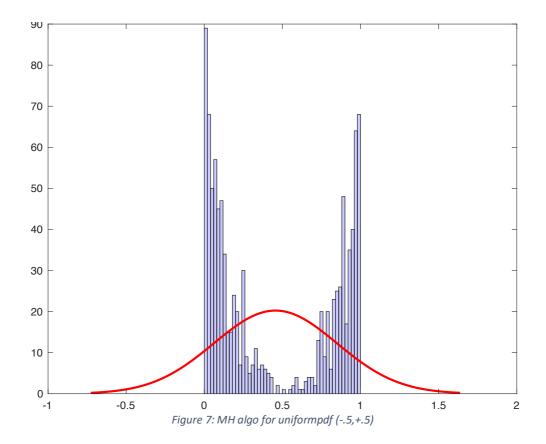


Figure 6: MH algorithm sample path uniform pdf



Discussion:

Above code uses Metropolis-Hastings algorithm to generate samples from mixture of Beta distributions. Metropolis-Hastings algorithm simulates samples from a probability distribution. It makes use of the full joint density function and proposal distributions for each variable user interested in.

The main loop of the algorithm consists of generating a proposal sample from the proposal distribution. Then we check the probability of acceptance of this sample by computing the acceptance function. Acceptance function is crucial in the sense of it forces the sampling method to visit higher probability areas under full density. The proposal distribution might be symmetric or asymmetric. If the proposal distribution is symmetric, this procedure is known as 'Random-walk MH algorithm'. In my case, I used symmetric proposal pdf (Gaussian) as my proposal pdf.

I run the algorithm with two different starting points. One starting from 0 and the other starting from 0.5. We can easily see that starting from zero gave more samples that are accepted around zero. But when we start from 0.5 we don't get too many samples for that region this is because the original distribution is less dense within that region. We can say that the algorithm converges to it's equilibrium distribution more rapidly if we start from a initially denser point. For starting from 0.5 it took 3.861320 seconds for it to converge, whereas starting from 0 took 3.308173.

In terms of change in variances, it took 5.235680 seconds to converge for the algorithm with Gaussian pdf and variance=100. Whereas it took 2.738232 seconds for same pdf with variance=1. If the problems get more complicated and samples are increased, the differences between these computation times are also going to get increased.

[MCMC for Optimization]

i.

```
[X,Y] = meshgrid(-500:0.5:500,-500:0.5:500);
Z= (418.9829*2-(X.*sin(sqrt(abs(X)))+Y.*sin(sqrt(abs(Y)))));
C = X.*Y;
surf(X,Y,Z,C)
figure
contour(X,Y,Z)
```

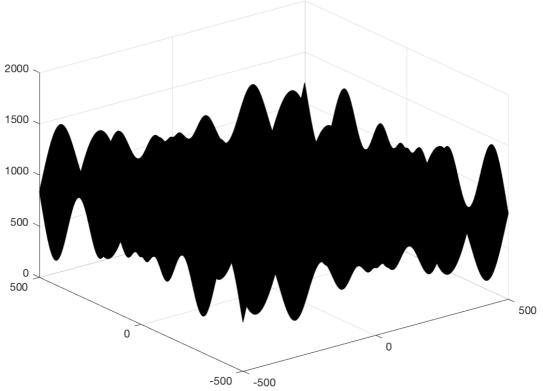
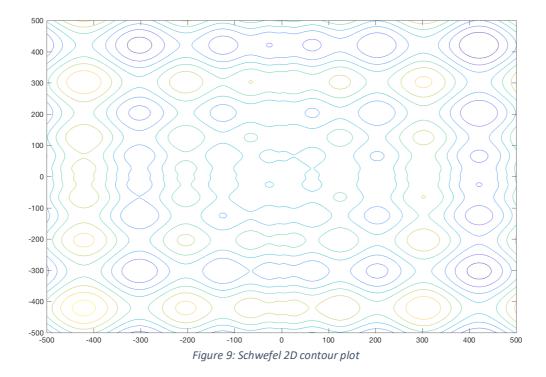


Figure 8: Surface plot of 2D Schwefel

Above the surface plot is generated. Even though I tried to implement colormap, somehow, I could not able to show it. But, it is clear that the surface is very bumpy and it has lots of local maxima, minima such that classical optimization methods would take much longer to converge to a global optimal solution. That is why we implement MCMC method.



Contour plot generated above also gives an idea about level surfaces of the 2-D Schwefel function.

```
ii.
%-----$ function implementation function implementation function implementation function func
function [minimum, fval] = anneal(loss, parent, options)
def = struct(...
                               'CoolSched',@(T) (log(T)),...
                               'Generator', @(x) (-500 + (500-(-500)).*rand(1,2)),...
                               'InitTemp',1,...
                              'MaxConsRej',1000,...
'MaxSuccess',20,...
                               'MaxTries',300,...
                               'StopTemp',1e-8,...
                              'StopVal',-Inf,...
                              'Verbosity',1);
% Check input
if ~nargin %user wants default options, give it and stop
              minimum = def;
               return
elseif nargin<2 %user gave only objective function, throw error</pre>
               error('MATLAB:anneal:noParent','You need to input a first guess.');
elseif nargin<3 %user gave no options structure, use default
              options=def;
else %user gave all input, check if options structure is complete
               if ~isstruct(options)
                             error('MATLAB:anneal:badOptions',...
    'Input argument ''options'' is not a structure')
               end
```

```
fs = {'CoolSched', 'Generator', 'InitTemp', 'MaxConsRej',...
        'MaxSuccess', 'MaxTries', 'StopTemp', 'StopVal', 'Verbosity'};
    for nm=1:length(fs)
        if ~isfield(options,fs{nm}), options.(fs{nm}) = def.(fs{nm}); end
    end
end
% main settings
newsol = options.Generator;
                                 % neighborhood space function
Tinit = options.InitTemp;
                                 % initial temp
                                % stopping temp
minT = options.StopTemp;
cool = options.CoolSched;
                                 % annealing schedule
minF = options.StopVal;
max consec rejections = options.MaxConsRej;
max try = options.MaxTries;
max success = options.MaxSuccess;
report = options. Verbosity;
k = 1;
                                  % boltzmann constant
% counters etc
itry = 0;
success = 0;
finished = 0;
consec = 0;
T = Tinit;
initenergy = loss(parent);
oldenergy = initenergy;
total = 0;
if report==2, fprintf(1,'\n T = %7.5f, loss = %10.5f\n', T, oldenergy); end
while ~finished
    itry = itry+1; % just an iteration counter
    current = parent;
    % % Stop / decrement T criteria
    if itry >= max_try || success >= max_success
        if T < minT || consec >= max_consec_rejections
            finished = 1;
            total = total + itry;
            break;
        else
            T = cool(T); % decrease T according to cooling schedule
            if report==2 % output
                fprintf(1, T = %7.5f, loss = %10.5f \ T, oldenergy);
            end
            total = total + itry;
            itry = 1;
            success = 1;
        end
    end
    newparam = newsol(current);
    newenergy = loss(newparam);
    if (newenergy < minF),</pre>
        parent = newparam;
        oldenergy = newenergy;
        break
    end
    if (oldenergy-newenergy > 1e-6)
        parent = newparam;
```

```
oldenergy = newenergy;
        success = success+1;
       consec = 0;
    else
        if (rand < exp( (oldenergy-newenergy)/(k*T) ))</pre>
           parent = newparam;
            oldenergy = newenergy;
           success = success+1;
        else
            consec = consec+1;
       end
    end
end
minimum = parent;
fval = oldenergy;
if report
    fprintf(1, '\n Initial temperature: \t%g\n', T
fprintf(1, ' Final temperature: \t%g\n', T);
                                           \t%g\n', Tinit);
    fprintf(1, ' Consecutive rejections: \t%i\n', consec);
fprintf(1, ' Number of function calls:\t%i\n', total);
    fprintf(1, 'Total final loss:
                                          \t%g\n', fval);
end
%-----$ function implementation%-----$
%-----$
camel = @(x,y)(418.9829*2-(x*sin(sqrt(abs(x)))+y*sin(sqrt(abs(y)))));
loss = @(p)camel(p(1),p(2));
[mini, fvali] = anneal(loss,[0,0]);
%-----$ function-----$
mini =
 420.7000, 429.4613
fvali =
  9.1068
iii.
```

To change the cooling schedule, we modify the default cooling function of the anneal.m as exponential, polynomial, and logarithmic respectively. For each cooling function we change the initial temperature as [20,50,100,1000] from the same function. To impement different cooling functions, the reference website is used to generate relevant cooling schedules.

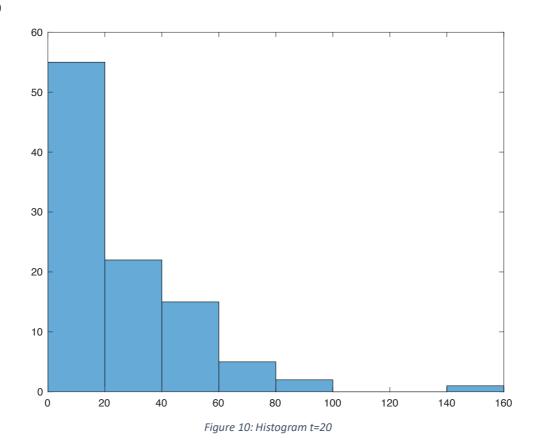
Exponential Cooling Function: T*(0.8)^(itry) %% itry is the iteration number

This cooling function is proposed by Kirkpatrick, Gelatt and Vecchi (1983) for the exponential cooling schedule.

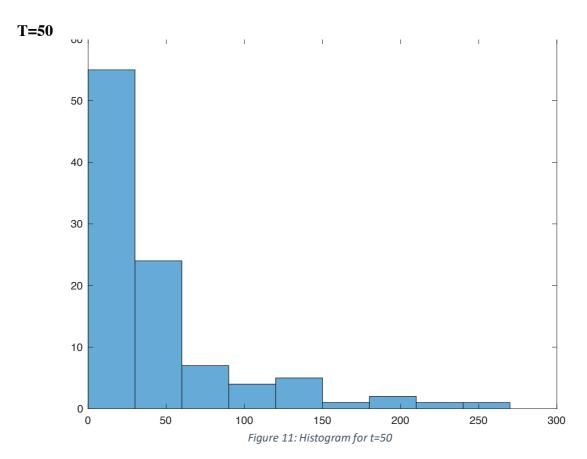
```
camel = @(x,y)(418.9829*2-(x*sin(sqrt(abs(x)))+y*sin(sqrt(abs(y)))));
loss = @(p)camel(p(1),p(2));
minn=zeros(100,2);
fval=zeros(100,1);
for k=1:1:100
[mini, fvali] = anneal(loss,[0,0]);
minn(k,1)=mini(1);
minn(k,2)=min(2);
fval(k)=fvali;
end

[m,I]=min(fval);
min_pair(1)=minn(I,1);
min_pair(2)=minn(I,2);
histogram(fval);
```

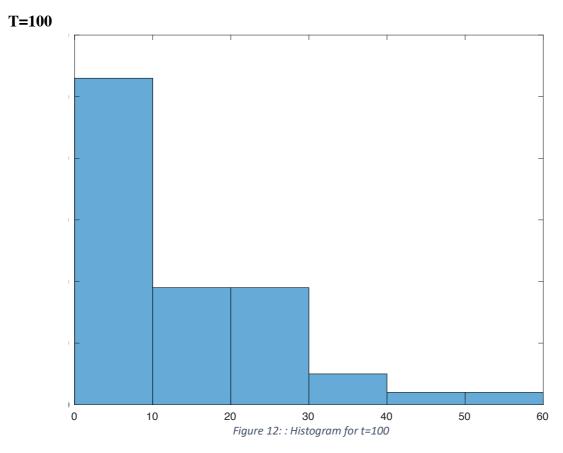
T=20



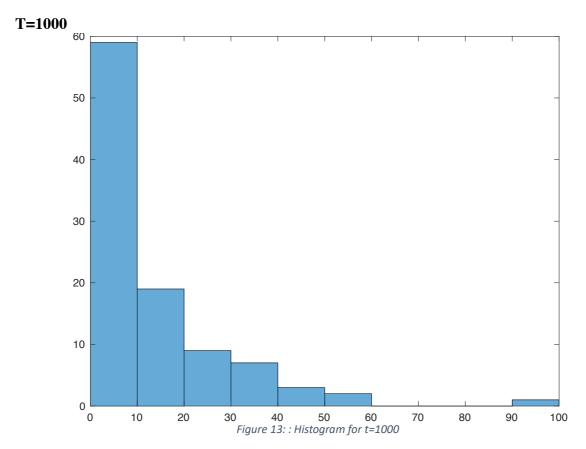
m = 0.0711 min_pair = 421.2102, 421.6791



m =3.0711 min_pair =419.6273 425.7147

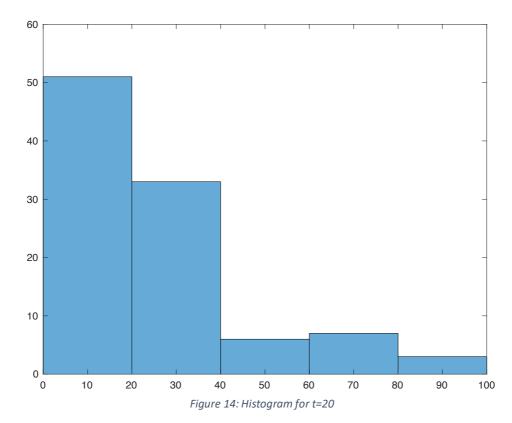


m = 0.0019 min_pair = 420.9553 421.0898



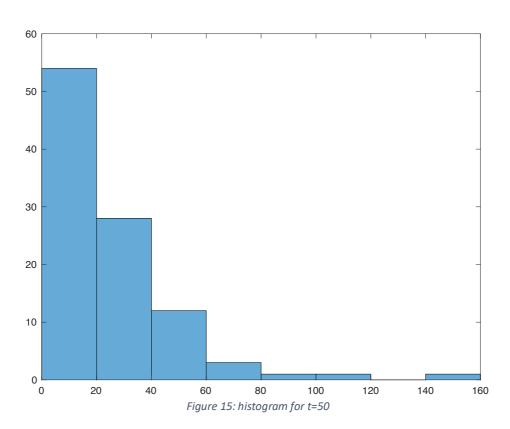
m = 0.0247min_pair = 421.3862 420.8242

Polynomial Cooling Function: (T/(1+(0.5*itry))) T=20



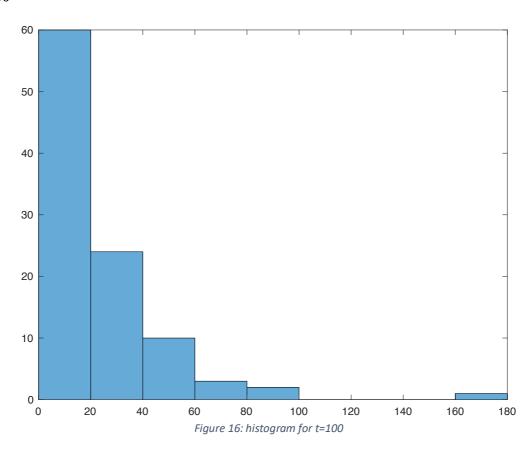
m = 0.0188 min_pair=420.6103, 421.1117

T=50



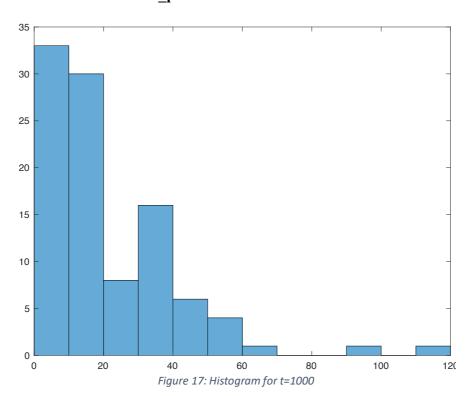
m =0.0110 min_pair =421.1581 421.1940

T=100



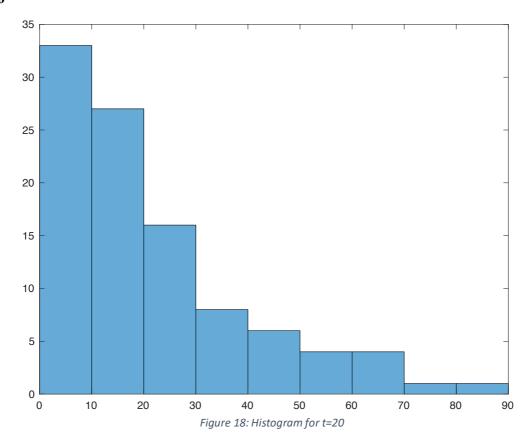
m =0.4770 min_pair = 421.6044 419.1305

T=1000

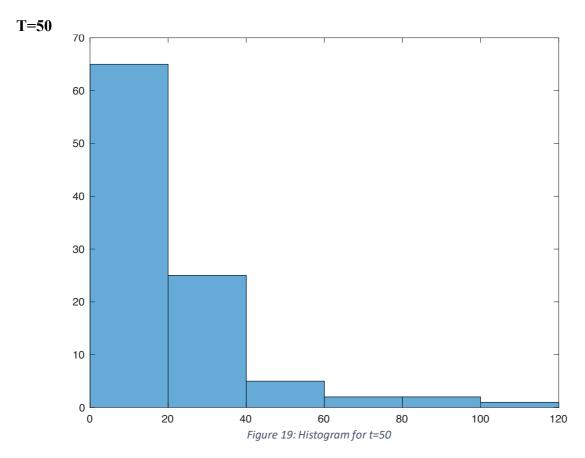


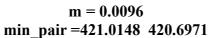
m =0.4909 min_pair = 422.4599 422.2591

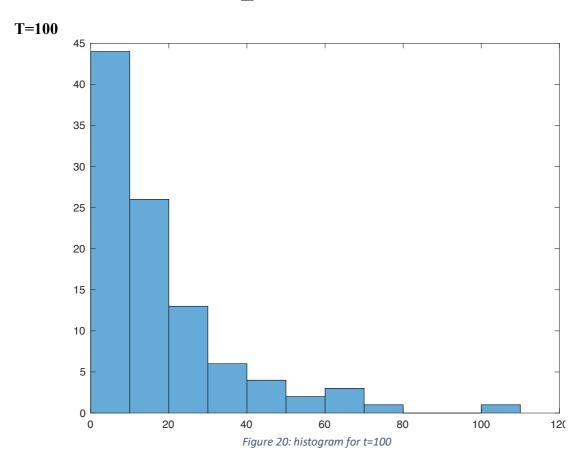
Logarithmic Cooling Function: $(5/(\log(1+T)))$ T=20



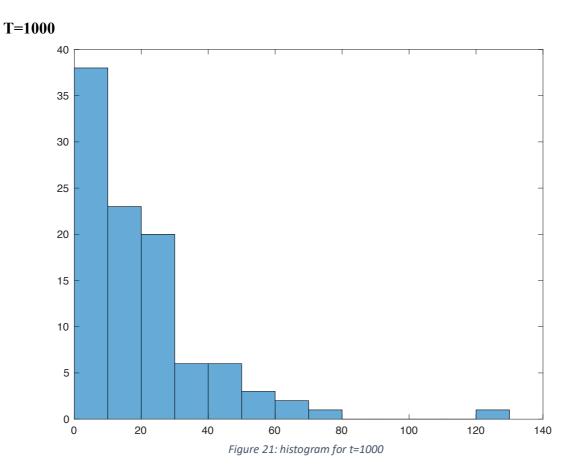
m = 0.3245min_pair = 421.8492 419.6283







m = 0.1115min_pair = 420.0286 420.9830



m = 0.0730min_pair = 421.5877 420.5273

iv.

Looking at the histograms and the minimum values achieved by the algorithms, the minimum value achieved was m = 0.0019 with x and y pairs as 420.9553 421.0898 using exponential cooling schedule with initial T=100. The solution pairs on top of the contour is shown below.

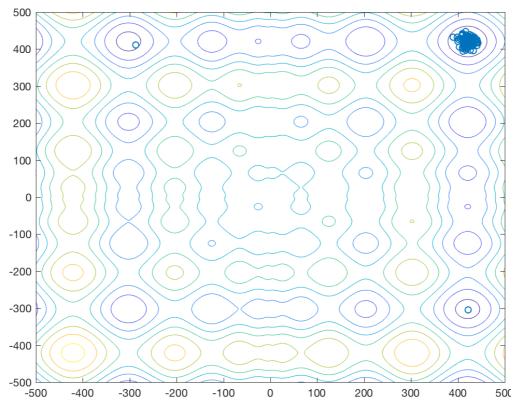


Figure 22: Contour plot with the pairs

[Optimal Paths]

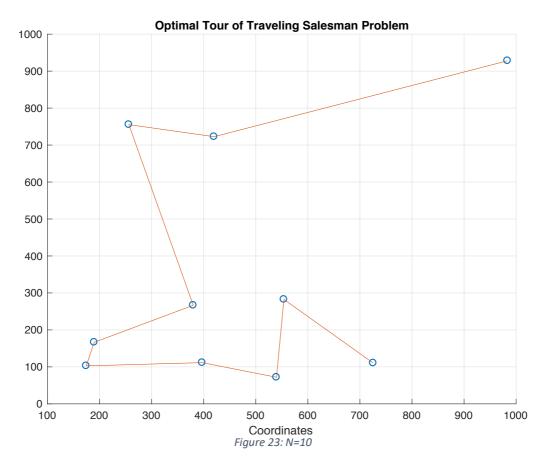
```
function simulatedAnnealingTSP(no cities, temperature start,
cooling factor)
cities mat = unifrnd(0, 1000, no cities, 2);
% matrix of city coordinates
distance_mat = squareform(pdist(cities_mat));
% matrix of intercity distances
temperature = temperature start;
% process temperature variable
distance_prev = Inf;
% set initial tour distance to infinity
counter = 0;
% iteration counter variable
random tour = randperm(no cities);
% create initial tour as a random combination of cities
%% simulated annealing process as long as temperature is positive
while temperature > 1
    % below code randomly swaps to cities in the tour. This it the
    % most efficient stochastic method of simulating all possible tours.
```

```
tour position1 = round(unifrnd(1, no cities));
    tour position2 = round(unifrnd(1, no cities));
    % randomly select two tour positions from current random tour
    swap_city1 = random_tour(tour_position1);
    swap_city2 = random_tour(tour_position2);
    % extract the cities at these random positions
    random_tour(tour_position1) = swap_city2;
    random tour(tour position2) = swap city1;
    % swap the cities
    tour distance = 0;
    % reinitialize the tour distance for each iteration
    % calculate the sum of intercity distance along the current random
    % route
    for i = 1 : no_cities - 1
        tour distance = tour distance + distance mat(random tour(i),
random tour(\overline{i} + 1);
    difference = tour_distance - distance_prev;
    % calculate the differnece between current random tour and previous
    % random tour
    % calculate the acceptance probability of the computed tour distance
    % according to exp(-difference/temperature) > rand(0, 1). If either
    % condition below holds true, set the distance as current optimal, and
    % tour as current optimal tour.
    if(difference < 0 | exp(-difference / temperature) > rand(0, 1))
        distance prev = tour distance;
        optimal_tour = random_tour;
    end
    counter = counter + 1;
    % counter variable to track iterations
    temperature vec(counter, :) = temperature;
    % vector tracks annealing temperature at each iteration
    temperature = temperature * (1 - cooling_factor);
    % cool the process by discounting temperatuee by cooling factor
    optim distance(counter, :) = distance prev;
    calc distance(counter, :) = tour distance;
    % vectors to store the current optimal distance as well as currently
    % computed distance
end
%% Plot of results
plot(1: 1: counter, temperature_vec, '-', 'Linewidth', 2);
xlabel('Number of Steps');
ylabel('Temperature');
title('Decay of Annealing Temperature');
% plot of annealing temperature vs iterations
figure;
```

```
plot(1: 1: counter, optim_distance, '-', 'Linewidth', 2); hold on;
plot(1: 1: counter, calc_distance, '-', 'Linewidth', 2);
legend;
xlabel('Number of Steps');
ylabel('Distance');
title('Simulated Annealing of Traveling Salesman Problem');
% Plot of calculated distance and currently optimal distance vs.
% iterations

figure;
scatter(cities_mat(1: no_cities, 1), cities_mat(1: no_cities, 2), 'o');
hold on;
plot(cities_mat(optimal_tour, 1), cities_mat(optimal_tour, 2), '-'); grid on;
xlabel('Coordinates');
ylabel('Coordinates');
title('Optimal Tour of Traveling Salesman Problem');
% plot of city coordinates and optimal route
```

Set of random tours evaluated at each iteration, evaluated distance is compared to the previous tour distance. If the distance is less it is assumed optimal, but since we are using simulated annealing procedure if the distance is more it is not disregarded. It is held off with a certain probability. I am using exponential cooling schedule since it performed best for the MCMC for Optimization problem.



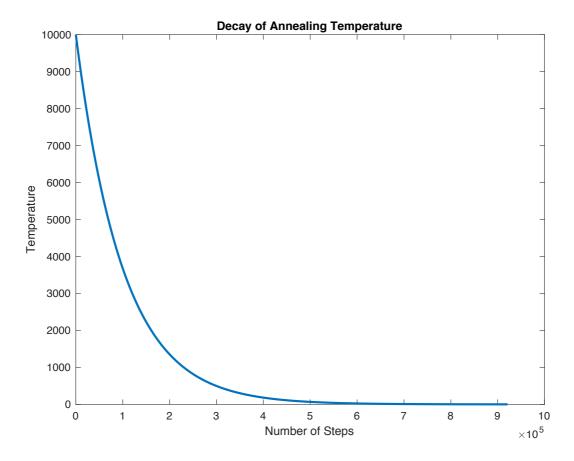
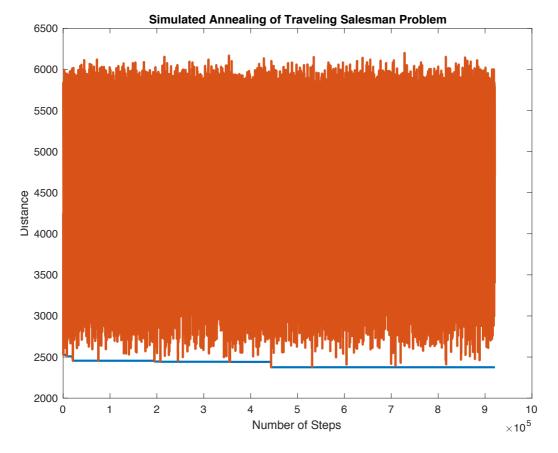


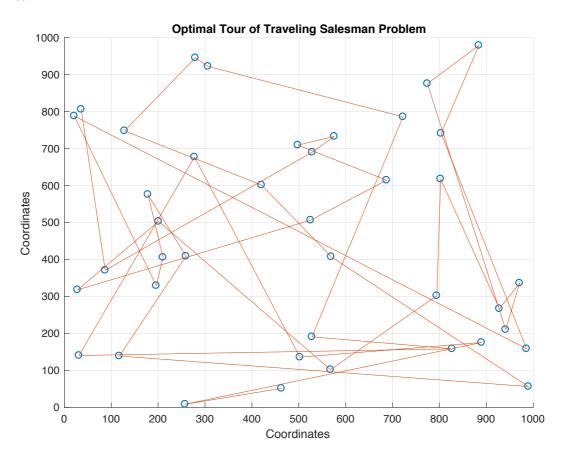
Figure 24: temperature decay for N=10

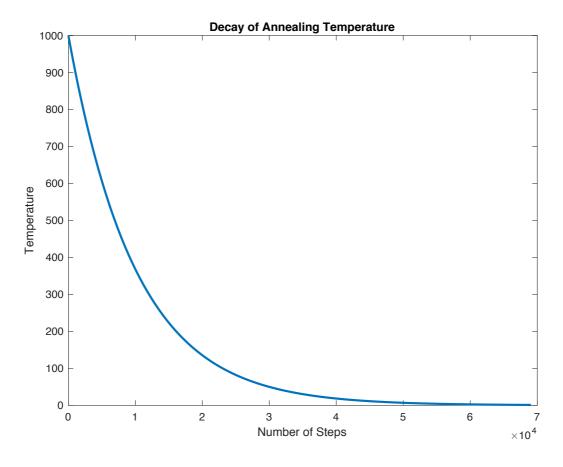


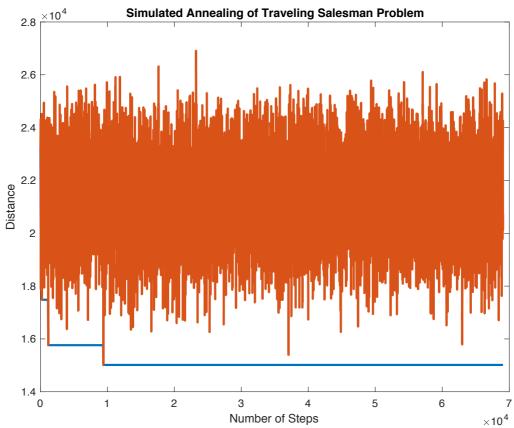
When I choose N=10, Initial Temperature as 10000 and decay rate as 0.00001 with exponential cooling schedule. For N=40, 400, 1000 the elapsed time for the computation of the algorithm is given below.

Elapsed time is 11.784691 seconds. N=10 >> annealingtest Elapsed time is 11.872613 seconds. N=40 >> annealingtest Elapsed time is 21.178397 seconds. N=400 >> annealingtest Elapsed time is 32.370761 seconds N=1000

It is clearly seen that the number of cities increases the computation time significantly. The optimal tour, Decay of the temperature and the calculated distances are plotted below for N=40.







References:

- (1) Taylan Cemgil's lecture slides on Monte Carlo Methods (http://www.cmpe.boun.edu.tr/courses/cmpe58n/fall2009/)
- (2) http://what-when-how.com/artificial-intelligence/a-comparison-of-cooling-schedules-for-simulated-annealing-artificial-intelligence/
- (3) <a href="https://de.mathworks.com/matlabcentral/mlc-downloads/downloads/submissions/10548/versions/1/previews/anneal.m/index.html?access_key="https://de.mathworks.com/matlabcentral/mlc-downloads/downloads/submissions/10548/versions/1/previews/anneal.m/index.html?access_key="https://de.mathworks.com/matlabcentral/mlc-downloads/downloads/submissions/10548/versions/1/previews/anneal.m/index.html?access_key="https://de.mathworks.com/matlabcentral/mlc-downloads/downloads/submissions/10548/versions/1/previews/anneal.m/index.html?access_key="https://de.mathworks.com/matlabcentral/mlc-downloads/submissions/10548/versions/1/previews/anneal.m/index.html?access_key="https://de.mathworks.com/matlabcentral/mlc-downloads/submissions/10548/versions/1/previews/anneal.m/index.html?access_key="https://de.mathworks.com/matlabcentral/mlc-downloads/submissions/10548/versions/1/previews/anneal.m/index.html?access_key="https://de.mathworks.com/matlabcentral/mlc-downloads/submissions/10548/versions/1/previews/anneal.m/index.html?access_key="https://de.mathworks.com/matlabcentral/mlc-downloads/submissions/10548/versions/submissions/submi
- (4) https://github.com/kufer/Traveling-Salesman-Problem-by-Simulated-AnnealingTSP.m