

Statistical prediction of hand-load carrying strategy and load level from wearable inertial sensor data

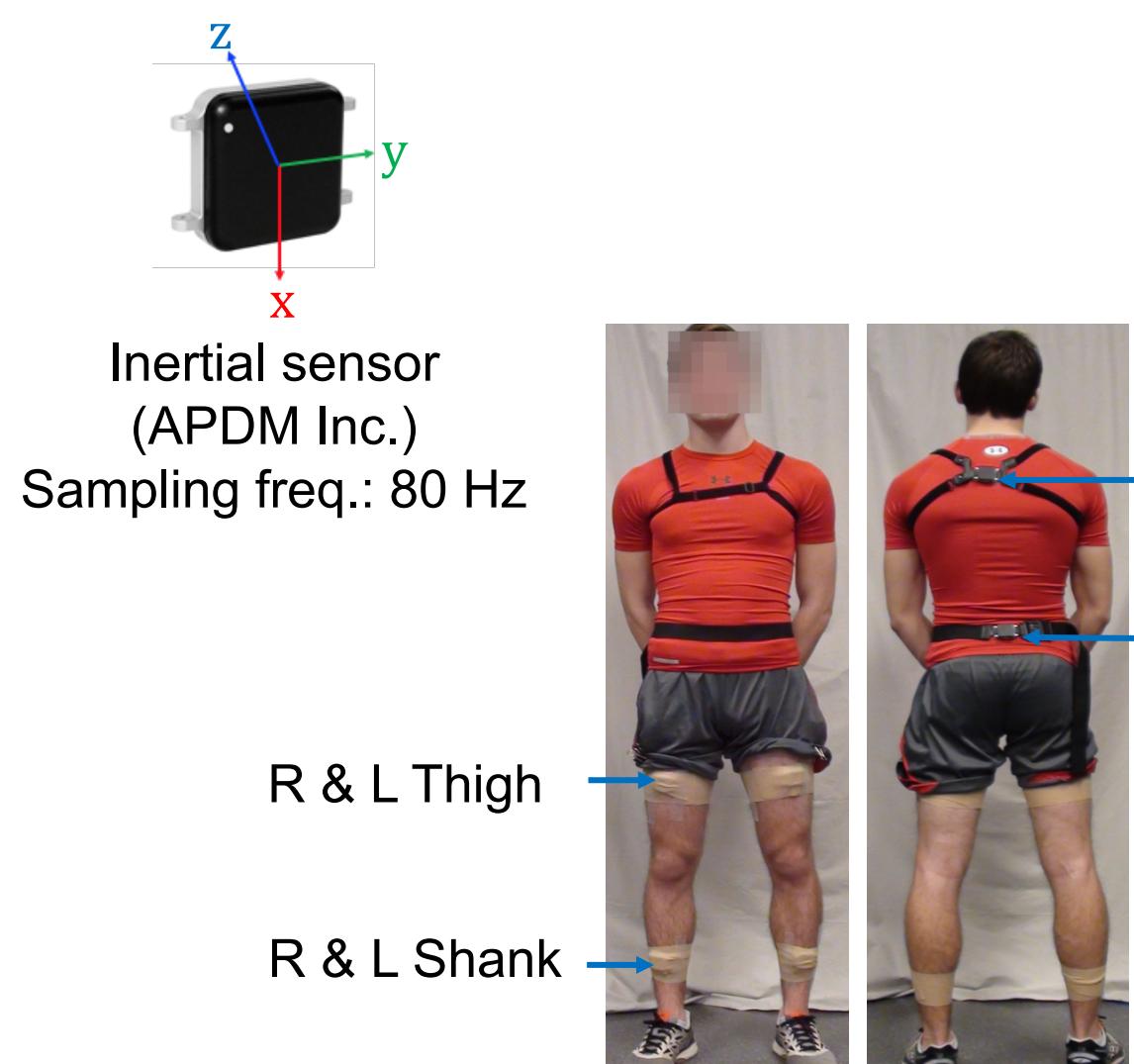
Sol Lim, Clive D'Souza, Ph.D.
Department of Industrial and Operations Engineering, University of Michigan, Ann Arbor, MI

Objective

To develop and validate a statistical prediction algorithm that uses body-worn inertial sensor data for classifying load carrying strategy and load-level in workers.

Methods

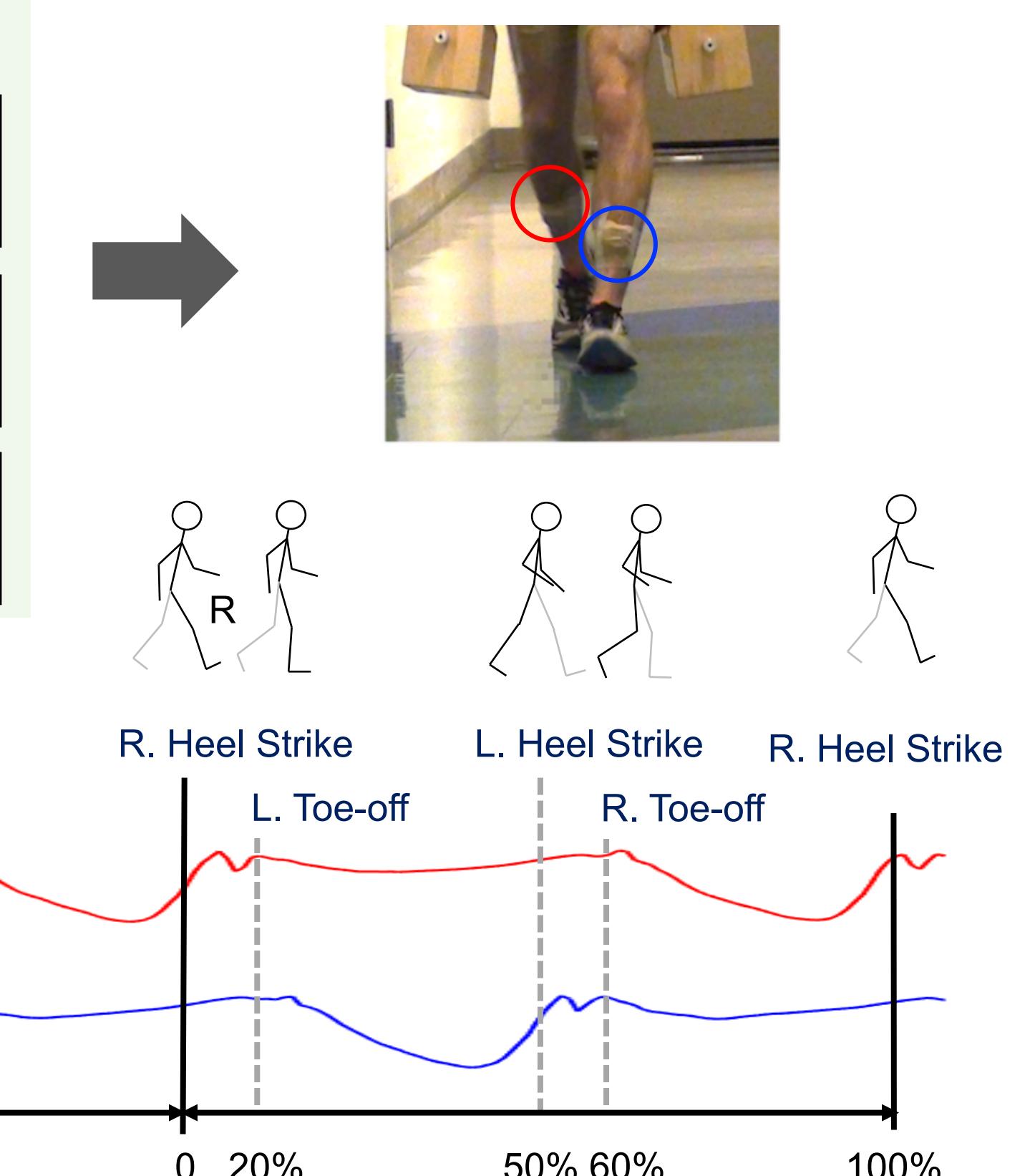
1 Instrumentation



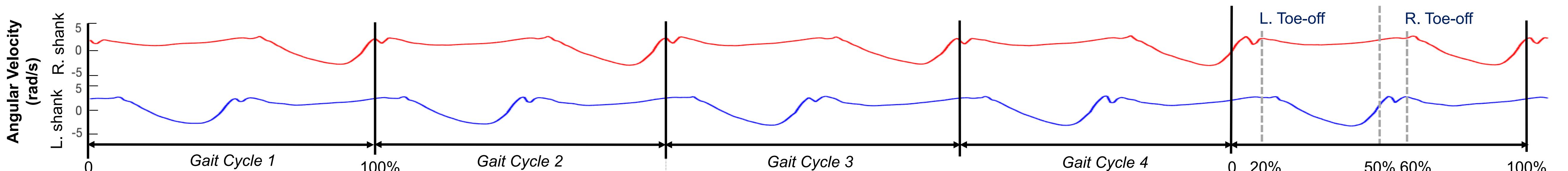
2 Collected data from 10 right-handed males in simulated carrying tasks



3 Algorithmically detect gait events from inertial sensor data [2]



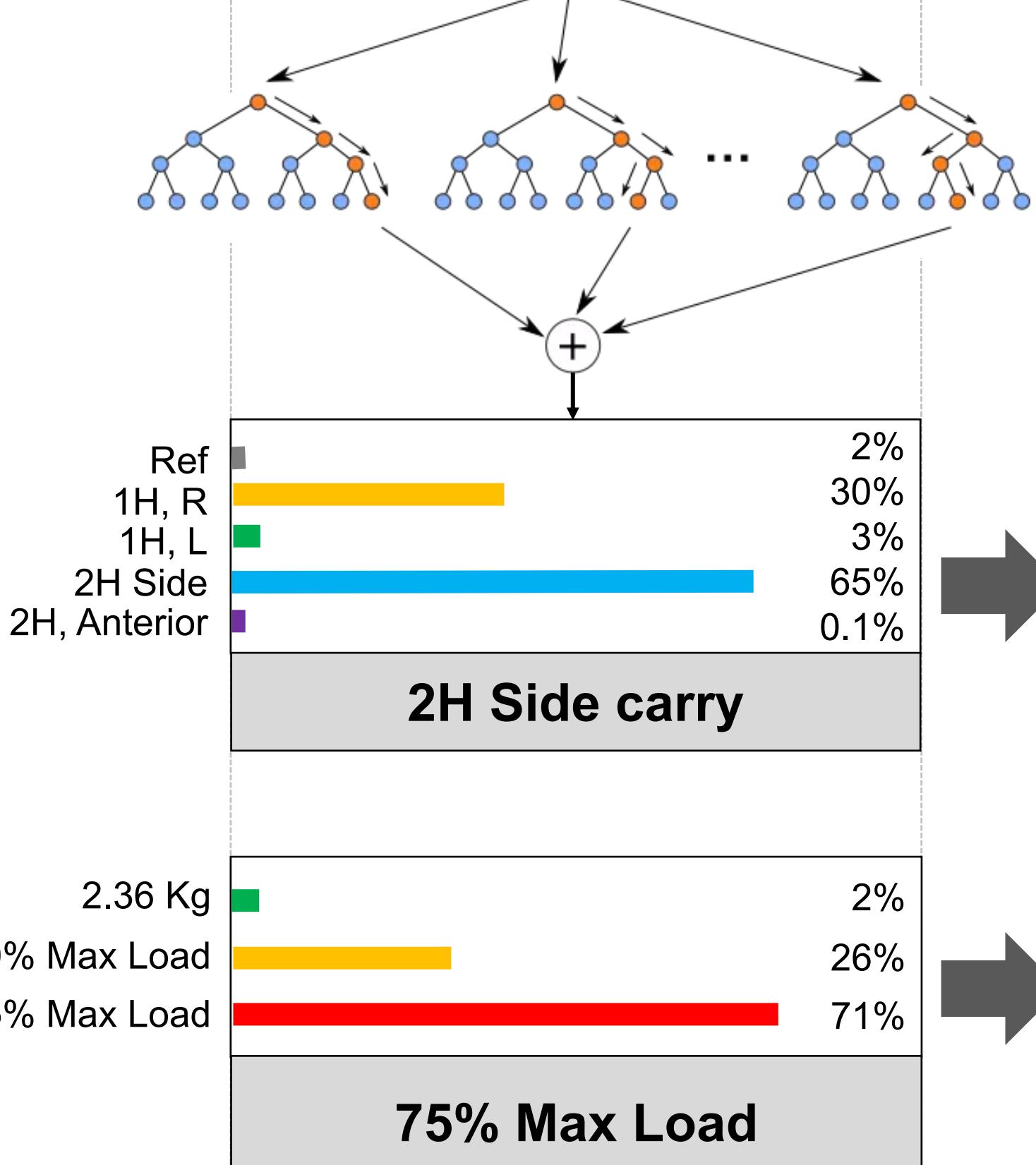
Sample gait trajectory



4 Compute predictor variables =

24 Gait parameters for each cycle

5 Implemented Random Forest [3]



6 Predict Carrying Strategy [stage 1]

Model Performance

Based on 10-fold holdout cross-validation repeated 20 times

Table 1. Accuracy of predicting strategy (95.0%)

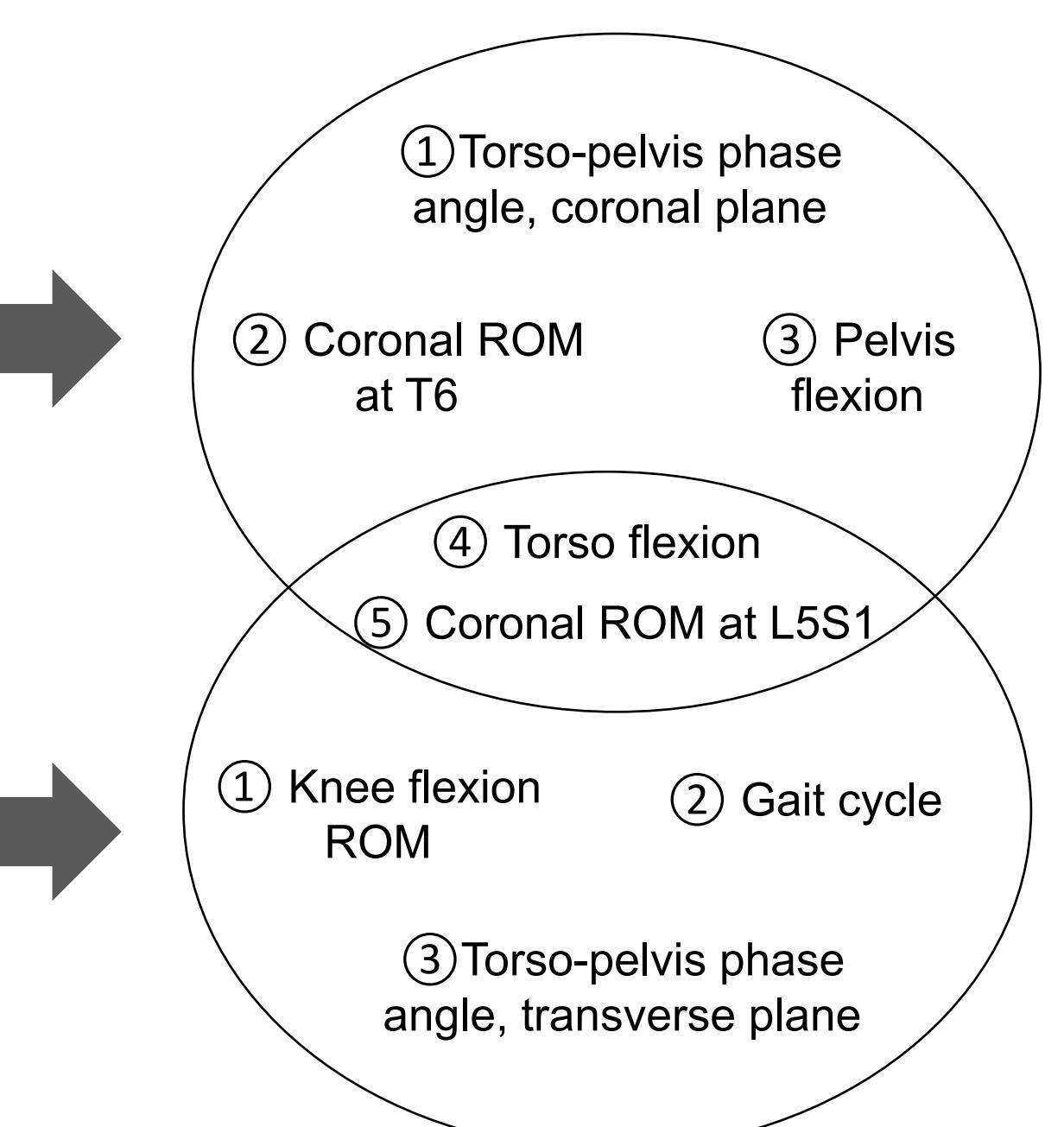
Predicted strategy	Actual strategy				
	Ref	1H, R	1H, L	2H side	2H Ant
Ref	38	0	0	0	0
1H, R	4	109	1	2	0
1H, L	0	3	67	3	4
2H side	1	1	1	88	3
2H Ant	1	0	0	0	152

Table 2. Accuracy of predicting load within 2H side carry (95.7%)

Predicted load level	Actual strategy		
	2.36 kg	50% Max	75% Max
2.36 kg	22	1	0
50% Max	0	21	0
75% Max	0	2	24

Model Interpretation

Top 5 important variables for carrying strategy (top) & loads (bottom)



Conclusions

- A two-stage random forest algorithm correctly classified the carrying strategy and load level in 389 out of 478 (81.3%) gait cycles
- Wearable sensor data combined with statistical prediction demonstrate strong potential for measuring workers exposures to physically demanding tasks over time.
- Our goal is to develop low-cost personalized tools for assessing physical workload and injury risk in workers engaged in physical labor.

References

- [1] Liberty Mutual Inc. (2017). 2017 Liberty Mutual Workplace Safety Index. *Annual Report of Scientific Activity*. Hopkinton, MA.
- [2] Aminian, K., Najafi, B., Büla, C., Leyvraz, P.-F., & Robert, P. (2002). Spatio-temporal parameters of gait measured by an ambulatory system using miniature gyroscopes. *Journal of Biomechanics*, 35(5), 689-699.
- [3] Breiman, L., Friedman, J. H., Olshen, R. A., & Stone, C. J. (1984). Classification and regression trees. Wadsworth & Brooks. Monterey, CA.

This study was supported by NIDILRR (Grant # 90IF-0094-01-00).