



University of Central Florida

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UCF Locals

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Contest (1)

template.cpp	11 lines
<pre>#include <bits/stdc++.h> using namespace std; #define rep(i, a, b) for (ll i = a; i < (ll)(b); ++i) #define all(x) (x).begin(), (x).end() #define sz(x) (ll) x.size() typedef long long ll; typedef vector<ll> vll; int main() { cin.tie(0)->sync_with_stdio(0); cin.exceptions(cin.failbit); }</pre>	
.bashrc	3 lines
<pre>alias c='g++ -Wall -Wconversion -Wfatal-errors -g -std=c++17 \ -fsanitize=undefined,address' xmodmap -e 'clear lock' -e 'keycode 66=less greater' #caps =◇</pre>	
.vimrc	6 lines
<pre>set cin aw ai is ts=4 sw=4 tm=50 nu noeb bg=dark ru cul sy on im jk <esc> im kj <esc> no ; : " Select region and then type :Hash to hash your selection. " Useful for verifying that there aren't mistypes. ca Hash w !cpp -dD -P -fpreprocessed \ tr -d '[:space:]' \ \ md5sum \ cut -c-6</pre>	
hash.sh	5 lines
<pre># Hashes a file, ignoring all whitespace and comments. Use for # verifying that code was correctly typed. # Use chmod +x hash.sh # Then ./hash.sh < ./fileName cpp -dD -P -fpreprocessed tr -d '[:space:]' md5sum cut -c-6</pre>	
troubleshoot.txt	48 lines
<pre>Pre-submit: Write a few test cases INCLUDE MAX CASES. Is memory fine? Overflow? Correct file? Wrong answer: Print your solution + Print debug Clearing all structures between test cases? Can your code handle the whole input range? Read the problem statement again. Do you handle all corner cases correctly? Have you understood the problem correctly? Uninitialized variables? Overflows? Confusing N and M, i and j, etc.? Are you sure your algorithm works? Any very special cases? Do you know how the STL functions you use work? Add some assertions, maybe resubmit. Create some testcases Go through the algorithm for a simple case. Go through this list again. Explain your algorithm to a teammate. Ask the teammate to look at your code. Go for a small walk, e.g. to the toilet. Is your output format correct? (whitespace) You/Teammate rewrite solution from the start</pre>	

Runtime error:

- Have you tested all corner cases locally?
- Any uninitialized variables?
- Are you reading or writing outside of range?
- Consider increasing the size of your vectors
- Any assertions that might fail?
- Any possible division by 0? (mod 0 for example)
- Any possible infinite recursion?
- Invalidated pointers or iterators?
- Are you using too much memory?

Time limit exceeded:

- Do you have any possible infinite loops?
- What is the complexity of your algorithm?
- Are you copying a lot of unnecessary data?
- How big is the input and output?
- Avoid vector, map. (use arrays/unordered_map)
- What do your teammates think about your algorithm?

Memory limit exceeded:

- Max amount of memory your code should need?
- Clearing all data structures between test cases?

Mathematics (2)

2.1 Equations

$$ax^2+bx+c=0\Rightarrow x=\frac{-b\pm\sqrt{b^2-4ac}}{2a}$$

The extremum is given by $x=-b/2a$.

$$\begin{array}{lcl} ax+by=e & \Rightarrow & x=\frac{ed-bf}{ad-bc} \\ cx+dy=f & & y=\frac{af-ec}{ad-bc} \end{array}$$

In general, given an equation $Ax=b$, the solution to a variable x_i is given by

$$x_i=\frac{\det A'_i}{\det A}$$

where A'_i is A with the i 'th column replaced by b .

2.2 Recurrences

If $a_n=c_1a_{n-1}+\cdots+c_ka_{n-k}$, and r_1,\dots,r_k are distinct roots of $x^k-c_1x^{k-1}-\cdots-c_k$, there are d_1,\dots,d_k s.t.

$$a_n=d_1r_1^n+\cdots+d_kr_k^n.$$

Non-distinct roots r become polynomial factors, e.g.

$$a_n=(d_1n+d_2)r^n.$$

2.3 Trigonometry

$$\sin(v+w)=\sin v\cos w+\cos v\sin w$$

$$\cos(v+w)=\cos v\cos w-\sin v\sin w$$

$$\tan(v+w)=\frac{\tan v+\tan w}{1-\tan v\tan w}$$

$$\sin v+\sin w=2\sin\frac{v+w}{2}\cos\frac{v-w}{2}$$

$$\cos v+\cos w=2\cos\frac{v+w}{2}\cos\frac{v-w}{2}$$

$$(V+W)\tan(v-w)/2=(V-W)\tan(v+w)/2$$

where V,W are lengths of sides opposite angles v,w .

$$a\cos x+b\sin x=r\cos(x-\phi)$$

$$a\sin x+b\cos x=r\sin(x+\phi)$$

where $r=\sqrt{a^2+b^2},\phi=\text{atan2}(b,a)$.

2.4 Geometry

2.4.1 Triangles

Side lengths: a,b,c

Semiperimeter: $p=\frac{a+b+c}{2}$

Area: $A=\sqrt{p(p-a)(p-b)(p-c)}$

Circumradius: $R=\frac{abc}{4A}$

Inradius: $r=\frac{A}{p}$

Length of median (divides triangle into two equal-area triangles):

$$m_a=\tfrac{1}{2}\sqrt{2b^2+2c^2-a^2}$$

Length of bisector (divides angles in two):

$$s_a=\sqrt{bc\left[1-\left(\frac{a}{b+c}\right)^2\right]}$$

Law of sines: $\frac{\sin\alpha}{a}=\frac{\sin\beta}{b}=\frac{\sin\gamma}{c}=\frac{1}{2R}$

Law of cosines: $a^2=b^2+c^2-2bc\cos\alpha$

Law of tangents: $\frac{a+b}{a-b}=\frac{\tan\frac{\alpha+\beta}{2}}{\tan\frac{\alpha-\beta}{2}}$

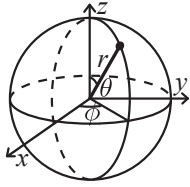
2.4.2 Quadrilaterals

With side lengths a,b,c,d , diagonals e,f , diagonals angle θ , area A and magic flux $F=b^2+d^2-a^2-c^2$:

$$4A=2ef\cdot\sin\theta=F\tan\theta=\sqrt{4e^2f^2-F^2}$$

For cyclic quadrilaterals the sum of opposite angles is 180° , $ef=ac+bd$, and $A=\sqrt{(p-a)(p-b)(p-c)(p-d)}$.

2.4.3 Spherical coordinates



$$\begin{aligned}x &= r \sin \theta \cos \phi & r &= \sqrt{x^2 + y^2 + z^2} \\y &= r \sin \theta \sin \phi & \theta &= \arccos(z / \sqrt{x^2 + y^2 + z^2}) \\z &= r \cos \theta & \phi &= \operatorname{atan2}(y, x)\end{aligned}$$

2.5 Derivatives/Integrals

$$\begin{aligned}\frac{d}{dx} \arcsin x &= \frac{1}{\sqrt{1-x^2}} & \frac{d}{dx} \arccos x &= -\frac{1}{\sqrt{1-x^2}} \\ \frac{d}{dx} \tan x &= 1 + \tan^2 x & \frac{d}{dx} \arctan x &= \frac{1}{1+x^2} \\ \int \tan ax &= -\frac{\ln |\cos ax|}{a} & \int x \sin ax &= \frac{\sin ax - ax \cos ax}{a^2} \\ \int e^{-x^2} &= \frac{\sqrt{\pi}}{2} \operatorname{erf}(x) & \int x e^{ax} dx &= \frac{e^{ax}}{a^2} (ax - 1)\end{aligned}$$

Integration by parts:

$$\int_a^b f(x)g(x)dx = [F(x)g(x)]_a^b - \int_a^b F(x)g'(x)dx$$

2.6 Sums

$$c^a + c^{a+1} + \dots + c^b = \frac{c^{b+1} - c^a}{c - 1}, c \neq 1$$

$$\begin{aligned}1 + 2 + 3 + \dots + n &= \frac{n(n+1)}{2} \\ 1^2 + 2^2 + 3^2 + \dots + n^2 &= \frac{n(2n+1)(n+1)}{6} \\ 1^3 + 2^3 + 3^3 + \dots + n^3 &= \frac{n^2(n+1)^2}{4} \\ 1^4 + 2^4 + 3^4 + \dots + n^4 &= \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}\end{aligned}$$

2.7 Series

$$\begin{aligned}e^x &= 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots, (-\infty < x < \infty) \\ \ln(1+x) &= x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots, (-1 < x \leq 1) \\ \sqrt{1+x} &= 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{2x^3}{32} - \frac{5x^4}{128} + \dots, (-1 \leq x \leq 1)\end{aligned}$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots, (-\infty < x < \infty)$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots, (-\infty < x < \infty)$$

2.8 Probability theory

Let X be a discrete random variable with probability $p_X(x)$ of assuming the value x . It will then have an expected value (mean) $\mu = \mathbb{E}(X) = \sum_x x p_X(x)$ and variance $\sigma^2 = V(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \sum_x (x - \mathbb{E}(X))^2 p_X(x)$ where σ is the standard deviation. If X is instead continuous it will have a probability density function $f_X(x)$ and the sums above will instead be integrals with $p_X(x)$ replaced by $f_X(x)$.

Expectation is linear:

$$\mathbb{E}(aX + bY) = a\mathbb{E}(X) + b\mathbb{E}(Y)$$

For independent X and Y ,

$$V(aX + bY) = a^2 V(X) + b^2 V(Y).$$

2.8.1 Discrete distributions

Binomial distribution

The number of successes in n independent yes/no experiments, each which yields success with probability p is $\operatorname{Bin}(n, p)$, $n = 1, 2, \dots$, $0 \leq p \leq 1$.

$$p(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

$$\mu = np, \sigma^2 = np(1-p)$$

$\operatorname{Bin}(n, p)$ is approximately $\operatorname{Po}(np)$ for small p .

First success distribution

The number of trials needed to get the first success in independent yes/no experiments, each which yields success with probability p is $\operatorname{Fs}(p)$, $0 \leq p \leq 1$.

$$p(k) = p(1-p)^{k-1}, k = 1, 2, \dots$$

$$\mu = \frac{1}{p}, \sigma^2 = \frac{1-p}{p^2}$$

Poisson distribution

The number of events occurring in a fixed period of time t if these events occur with a known average rate κ and independently of the time since the last event is $\operatorname{Po}(\lambda)$, $\lambda = t\kappa$.

$$p(k) = e^{-\lambda} \frac{\lambda^k}{k!}, k = 0, 1, 2, \dots$$

$$\mu = \lambda, \sigma^2 = \lambda$$

2.8.2 Continuous distributions

Uniform distribution

If the probability density function is constant between a and b and 0 elsewhere it is $\operatorname{U}(a, b)$, $a < b$.

$$f(x) = \begin{cases} \frac{1}{b-a} & a < x < b \\ 0 & \text{otherwise} \end{cases}$$

$$\mu = \frac{a+b}{2}, \sigma^2 = \frac{(b-a)^2}{12}$$

Exponential distribution

The time between events in a Poisson process is $\operatorname{Exp}(\lambda)$, $\lambda > 0$.

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & x < 0 \end{cases}$$

$$\mu = \frac{1}{\lambda}, \sigma^2 = \frac{1}{\lambda^2}$$

Normal distribution

Most real random values with mean μ and variance σ^2 are well described by $\mathcal{N}(\mu, \sigma^2)$, $\sigma > 0$.

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

If $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$ and $X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$ then

$$aX_1 + bX_2 + c \sim \mathcal{N}(\mu_1 + \mu_2 + c, a^2\sigma_1^2 + b^2\sigma_2^2)$$

2.9 Markov chains

A *Markov chain* is a discrete random process with the property that the next state depends only on the current state. Let X_1, X_2, \dots be a sequence of random variables generated by the Markov process. Then there is a transition matrix $\mathbf{P} = (p_{ij})$, with $p_{ij} = \Pr(X_n = i | X_{n-1} = j)$, and $\mathbf{p}^{(n)} = \mathbf{P}^n \mathbf{p}^{(0)}$ is the probability distribution for X_n (i.e., $p_i^{(n)} = \Pr(X_n = i)$), where $\mathbf{p}^{(0)}$ is the initial distribution.

π is a stationary distribution if $\pi = \pi \mathbf{P}$. If the Markov chain is *irreducible* (it is possible to get to any state from any state), then $\pi_i = \frac{1}{\mathbb{E}(T_i)}$ where $\mathbb{E}(T_i)$ is the expected time between two visits in state i . π_j / π_i is the expected number of visits in state j between two visits in state i .

For a connected, undirected and non-bipartite graph, where the transition probability is uniform among all neighbors, π_i is proportional to node i 's degree.

A Markov chain is *ergodic* if the asymptotic distribution is independent of the initial distribution. A finite Markov chain is ergodic iff it is irreducible and *aperiodic* (i.e., the gcd of cycle lengths is 1). $\lim_{k \rightarrow \infty} \mathbf{P}^k = \mathbf{1}\pi$.

A Markov chain is an A-chain if the states can be partitioned into two sets **A** and **G**, such that all states in **A** are absorbing ($p_{ii} = 1$), and all states in **G** leads to an absorbing state in **A**. The probability for absorption in state $i \in \mathbf{A}$, when the initial state is j , is $a_{ij} = p_{ij} + \sum_{k \in \mathbf{G}} a_{ik} p_{kj}$. The expected time until absorption, when the initial state is i , is $t_i = 1 + \sum_{k \in \mathbf{G}} p_{ki} t_k$.

Data structures (3)

Note: if there are no updates, consider merges

BitVector.h

Description: Given vector of bits, counts number of 0's in [0, r). Use with WaveletTree.h by using modifications in comments in that file and replacing bv[h][x] with bv[h].cnt0(x)
Time: $\mathcal{O}(1)$ time

```
struct BitVector {
    vector<pair<ll, int>> b;
    BitVector(vector<bool> a): b(sz(a) / 64 + 1) {
        rep(i, 0, sz(a))
            b[i >> 6].first |= ll(a[i]) << (i & 63);
        rep(i, 0, sz(b)-1)
            b[i + 1].second = __builtin_popcountll(b[i].first)
                + b[i].second;
    }
    int cnt0(int r) {
        auto [x, y] = b[r >> 6];
        return r - y
            - __builtin_popcountll(x & ((1ULL << (r & 63)) - 1));
    }
};
```

OrderStatisticTree.h

Description: A set (not multiset!) with support for finding the n'th element, and finding the index of an element. To get a map, change null_type.
Time: $\mathcal{O}(\log N)$

```
#include <bits/extc++.h>
using namespace __gnu_pbds;

template<class T>
using Tree = tree<T, null_type, less<T>, rb_tree_tag,
    tree_order_statistics_node_update>;

void example() {
    Tree<int> t, t2; t.insert(8);
    auto it = t.insert(10).first;
    assert(it == t.lower_bound(9));
    assert(t.order_of_key(10) == 1);
    assert(t.order_of_key(11) == 2);
    assert(*t.find_by_order(0) == 8);
    t.join(t2); // assuming T< T2 or T> T2, merge t2 into t
}
```

HashMap.h

Description: Hash map with mostly the same API as unordered_map, but ~3x faster. Uses 1.5x memory. Initial capacity must be a power of 2 (if provided).

```
#include <bits/extc++.h>
// To use most bits rather than just the lowest ones:
struct chash { // large odd number for C
    const uint64_t C = ll(4e18 * acos(0)) | 71;
    ll operator()(ll x) const { return __builtin_bswap64(x*C); }
```

```
};
__gnu_pbds::gp_hash_table<ll,int,chash> h({}, {}, {}, {}, {1<<16});
```

KactlSegmentTree.h

Description: Zero-indexed max-tree. Bounds are inclusive to the left and exclusive to the right. Can be changed by modifying T, f and unit.
Time: $\mathcal{O}(\log N)$

```
1905ff, 19 lines
struct Tree {
    typedef ll T;
    static constexpr T unit = LLONG_MIN;
    T f(T a, T b) { return max(a, b); }
    vector<T> s; ll n;
    Tree(ll n = 0, T def = unit) : s(2*n, def), n(n) {}
    void update(ll pos, T val) {
        for (s[pos += n] = val; pos /= 2;)
            s[pos] = f(s[pos * 2], s[pos * 2 + 1]);
    }
    T query(ll b, ll e) {
        T ra = unit, rb = unit;
        for (b += n, e += n; b < e; b /= 2, e /= 2) {
            if (b % 2) ra = f(ra, s[b++]);
            if (e % 2) rb = f(s[--e], rb);
        }
        return f(ra, rb);
    }
};
```

LazySegmentTree.h

Description: Segment tree with ability to add or set values of large intervals, and compute max of intervals. Can be changed to other things. Use with a bump allocator for better performance, and SmallPtr or implicit indices to save memory.
Usage: Node* tr = new Node(v, 0, sz(v));
Time: $\mathcal{O}(\log N)$.

```
c97658, 50 lines
const int inf = 1e9;
struct Node {
    Node *l = 0, *r = 0;
    int lo, hi, mset = inf, madd = 0, val = -inf;
    Node(int lo,int hi):lo(lo),hi(hi){} // Large interval of -inf
    Node(vll& v, int lo, int hi) : lo(lo), hi(hi) {
        if (lo + 1 < hi) {
            int mid = lo + (hi - lo)/2;
            l = new Node(v, lo, mid); r = new Node(v, mid, hi);
            val = max(l->val, r->val);
        }
        else val = v[lo];
    }
    int query(int L, int R) {
        if (R <= lo || hi <= L) return -inf;
        if (L <= lo && hi <= R) return val;
        push();
        return max(l->query(L, R), r->query(L, R));
    }
    void set(int L, int R, int x) {
        if (R <= lo || hi <= L) return;
        if (L <= lo && hi <= R) mset = val = x, madd = 0;
        else {
            push(), l->set(L, R, x), r->set(L, R, x);
            val = max(l->val, r->val);
        }
    }
    void add(int L, int R, int x) {
        if (R <= lo || hi <= L) return;
        if (L <= lo && hi <= R) {
            if (mset != inf) mset += x;
            else madd += x;
            val += x;
        }
```

```
    }
    else {
        push(), l->add(L, R, x), r->add(L, R, x);
        val = max(l->val, r->val);
    }
}
void push() {
    if (!l) {
        int mid = lo + (hi - lo)/2;
        l = new Node(lo, mid); r = new Node(mid, hi);
    }
    if (mset != inf)
        l->set(lo,hi,mset), r->set(lo,hi,mset), mset = inf;
    else if (madd)
        l->add(lo,hi,madd), r->add(lo,hi,madd), madd = 0;
}
};
```

NodeBasedSegmentTree.h

Description: Simple node based segment tree for quick typing on more unique problems

```
76c3ea, 23 lines
struct node {
    pll val = {inf, inf};
    ll lo, hi, mid;
    node *left = nullptr, *right = nullptr;
    node (ll l, ll h) : lo(l), hi(h) {
        mid = (lo + hi) / 2;
        if (lo + 1 == hi) return;
        left = new node(lo, mid);
        right = new node(mid, hi);
    }
    void merge() { val = min(left->val, right->val); }
    void set(ll i, ll x) {
        if (lo + 1 == hi) { val = {x, i}; return; }
        if (i < mid) left->set(i, x);
        else right->set(i, x);
        merge();
    }
    pll query(ll l, ll r) {
        if (r <= lo || l >= hi) return {inf,inf};
        if (lo >= l && hi <= r) return val;
        return min(left->query(l, r), right->query(l, r));
    }
};
```

DynamicSegmentTree.h

Description: Segment Tree that only create nodes for used values. Consider using offline value compression before using a DST

```
248be1, 27 lines
struct Node {
    ll lo, hi;
    ll val = 0;
    Node *left = nullptr, *right = nullptr;
    Node(ll lo, ll hi) : lo(lo), hi(hi) {}
    void extend() {
        if (!left && lo + 1 < hi) {
            ll t = (lo + hi) / 2;
            left = new Node(lo, t);
            right = new Node(t, hi);
        }
    }
    void add(ll k, ll x) {
        extend();
        val += x;
        if (left) {
            if (k < left->hi) left->add(k, x);
            else right->add(k, x);
        }
    }
```

```
    }
    ll get_sum(ll lq, ll rq) {
        if (lq <= lo && hi <= rq) return val;
        if (max(lo, lq) >= min(hi, rq)) return 0;
        extend();
        return left->get_sum(lq, rq) + right->get_sum(lq, rq);
    }
};
```

SegmentTree.h

Description: General Segment Tree with functionality for common problems.

Usage: set(i, v, 0, 0, SIZE)

```
typedef struct Tree {
    ll size;
    vll vals;
    ll NEUTRAL_ELEMENT = 0;
    ll f(ll a, ll b) { return a + b; }
    void init(ll n) {
        size = 1;
        while (size < n) size *= 2;
        vals.assign(2 * size, 0LL);
    }
    void build(vll &a, ll x, ll lx, ll rx) {
        if (lx + 1 == rx) {
            if (lx < (ll)a.size()) vals[x] = a[lx];
            return;
        }
        ll m = (lx + rx) / 2;
        build(a, 2 * x + 1, lx, m);
        build(a, 2 * x + 2, m, rx);
        vals[x] = f(vals[2 * x + 1], vals[2 * x + 2]);
    }
    void set(ll i, ll v, ll x, ll lx, ll rx) {
        if (lx + 1 == rx) {
            vals[x] = v;
            return;
        }
        ll m = (lx + rx) / 2;
        if (i < m) set(i, v, 2 * x + 1, lx, m);
        else set(i, v, 2 * x + 2, m, rx);
        vals[x] = f(vals[2 * x + 1], vals[2 * x + 2]);
    }
    ll calc(ll l, ll r, ll x, ll lx, ll rx) {
        if (lx >= r || l >= rx) return NEUTRAL_ELEMENT;
        if (lx >= l && rx <= r) return vals[x];
        ll m = (lx + rx) / 2;
        ll s1 = calc(l, r, 2 * x + 1, lx, m);
        ll s2 = calc(l, r, 2 * x + 2, m, rx);
        return f(s1, s2);
    }
    ll findKth(ll k, ll x, ll lx, ll rx) {
        if (lx + 1 == rx) return lx;
        ll m = (lx + rx) / 2;
        ll s1 = vals[2*x + 1];
        if (k < s1) return findKth(k, 2*x + 1, lx, m);
        else return findKth(k-s1, 2*x + 2, m, rx);
    }
    ll first_above(ll v, ll l, ll x, ll lx, ll rx) {
        if (vals[x] < v) return -1;
        if (rx <= l) return -1;
        if (rx - lx == 1) return lx;
        ll m = (lx + rx) / 2;
        ll res = first_above(v, l, 2*x + 1, lx, m);
        if (res == -1) res = first_above(v, l, 2*x + 2, m, rx);
        return res;
    }
} Tree;
```

PST.h

Description: Persistent segment tree with laziness

Time: $\mathcal{O}(\log N)$ per query, $\mathcal{O}((n + q) \log n)$ memory

```
struct PST {
    PST *l = 0, *r = 0;
    int lo, hi;
    ll val = 0, lzadd = 0;
    PST(vl& v, int lo, int hi) : lo(lo), hi(hi) {
        if (lo + 1 < hi) {
            int mid = lo + (hi - lo)/2;
            l = new PST(v, lo, mid); r = new PST(v, mid, hi);
            val = l->val + r->val;
        }
        else val = v[lo];
    }
    ll query(int L, int R) {
        if (R <= lo || hi <= L) return 0; // idempotent
        if (L <= lo && hi <= R) return val;
        push();
        return l->query(L, R) + r->query(L, R);
    }
    PST* add(int L, int R, ll v) {
        if (R <= lo || hi <= L) return this;
        PST *n = new PST(*this);
        if (L <= lo && hi <= R) {
            n->val += v * (hi - lo);
            n->lzadd += v;
        } else {
            n->push();
            n->l = n->l->add(L, R, v);
            n->r = n->r->add(L, R, v);
            n->val = n->l->val + n->r->val;
        }
        return n;
    }
    void push() {
        if (lzadd == 0) return;
        l = l->add(lo, hi, lzadd);
        r = r->add(lo, hi, lzadd);
        lzadd = 0;
    }
};
```

SqrtDecomp.h

Description: decomposes (l, r) range into pair of (list of fully covered blocks, list of partially covered blocks)

Time: $\mathcal{O}(B + (r - l)/B)$

```
template<int B>
pair<vi, vector<array<int, 3>>> decomp(int l, int r) {
    if (l/B == (r-1)/B) return {{}, {{l/B, l, r}}};
    vi full;
    vector<array<int, 3>> subs;
    if (l%B != 0) {
        subs.push_back({l/B, l, (l/B+1)*B});
        l = subs.back()[2];
    }
    if (r%B != 0) {
        subs.push_back({r/B, r/B*B, r});
        r = subs.back()[1];
    }
    rep(i, l/B, r/B) full.push_back(i);
    return {full, subs};
}
```

LiChao.h

Description: Creates a segment tree style data structure that supports adding a function to the set and query the min value at a given x. For any two added functions, they must intersect at most once. If queries can be floating point, consider line container instead.

Time: Both operations are $\mathcal{O}(\log N)$.

```
struct line {
    ll m, b;
    line(ll m = 0, ll b = LLONG_MAX) : m(m), b(b) {}
    ll operator() (ll x) { return m * x + b; }
};

struct node {
    int lo, md, hi;
    line f;
    node *left, *right;
    node(int L, int R) : lo(L), md((L+R)>>1), hi(R) {
        if (lo == hi) return;
        left = new node(lo, md);
        right = new node(md+1, hi);
    }
    void update(line g) {
        if (g(md) < f(md)) swap(f, g);
        if (lo == hi) return;
        if (f(lo) <= g(lo) && f(hi) <= g(hi)) return;
        if (f(lo) > g(lo)) left->update(g);
        else right->update(g);
    }
    ll query(ll x) {
        if (lo == hi) return f(x);
        return min(f(x), (x <= md ? left : right)->query(x));
    }
};
```

UnionFindRollback.h

Description: Disjoint-set data structure with undo. If undo is not needed, skip st, time() and rollback().

Usage: int t = uf.time(); ...; uf.rollback(t);

Time: $\mathcal{O}(\log(N))$

```
struct RollbackUF {
    vll e; vector<pll> st;
    RollbackUF(int n) : e(n, -1) {}
    int size(int x) { return -e[find(x)]; }
    int find(int x) { return e[x] < 0 ? x : find(e[x]); }
    int time() { return sz(st); }
    void rollback(int t) {
        for (int i = time(); i --> t;)
            e[st[i].first] = st[i].second;
        st.resize(t);
    }
    bool join(int a, int b) {
        a = find(a), b = find(b);
        if (a == b) return false;
        if (e[a] > e[b]) swap(a, b);
        st.push_back({a, e[a]});
        st.push_back({b, e[b]});
        e[a] += e[b]; e[b] = a;
        return true;
    }
};
```

SubMatrix.h

Description: Calculate submatrix sums quickly, given upper-left and lower-right corners (half-open).

Usage: SubMatrix<int> m(matrix);

m.sum(0, 0, 2, 2); // top left 4 elements

Time: $\mathcal{O}(N^2 + Q)$

<pre>template<class T> struct SubMatrix { vector<vector<T>>> p; SubMatrix(vector<vector<T>>& v) { int R = sz(v), C = sz(v[0]); p.assign(R+1, vector<T>(C+1)); rep(r,0,R) rep(c,0,C) p[r+1][c+1] = v[r][c] + p[r][c+1] + p[r+1][c] - p[r][c]; } T sum(int u, int l, int d, int r) { return p[d][r] - p[d][l] - p[u][r] + p[u][l]; } };</pre>	
--	--

Matrix.h

Description: Basic operations on square matrices.

Usage: Matrix<int, 3> A;
A.d = {{{{1,2,3}}, {{4,5,6}}, {{7,8,9}}}}};
array<int, 3> vec = {1,2,3};
vec = (A^N) * vec;

6ab5db, 26 lines

<pre>template<class T, int N> struct Matrix { typedef Matrix M; array<array<T, N>, N> d{}; M operator*(const M& m) const { M a; rep(i,0,N) rep(j,0,N) rep(k,0,N) a.d[i][j] += d[i][k]*m.d[k][j]; return a; } array<T, N> operator*(const array<T, N>& vec) const { array<T, N> ret{}; rep(i,0,N) rep(j,0,N) ret[i] += d[i][j] * vec[j]; return ret; } M operator^(ll p) const { assert(p >= 0); M a, b(*this); rep(i,0,N) a.d[i][i] = 1; while (p) { if (p&1) a = a*b; b = b*b; p >>= 1; } return a; } };</pre>	
--	--

LineContainer.h

Description: Container where you can add lines of the form $kx+m$, and query maximum values at points x . Useful for dynamic programming (“convex hull trick”).

Time: $\mathcal{O}(\log N)$

8ec1c7, 30 lines

<pre>struct Line { mutable ll k, m, p; bool operator<(const Line& o) const { return k < o.k; } bool operator<(ll x) const { return p < x; } }; struct LineContainer : multiset<Line, less<>> { // (for doubles, use inf = 1/.0, div(a,b) = a/b) static const ll inf = LLONG_MAX; ll div(ll a, ll b) { // floored division return a / b - ((a ^ b) < 0 && a % b); } bool isect(iterator x, iterator y) { if (y == end()) return x->p = inf, 0; if (x->k == y->k) x->p = x->m > y->m ? inf : -inf; else x->p = div(y->m - x->m, x->k - y->k);</pre>	
---	--

<pre> return x->p >= y->p; } void add(ll k, ll m) { auto z = insert({k, m, 0}), y = z++, x = y; while (isect(y, z)) z = erase(z); if (x != begin() && isect(--x, y)) isect(x, y = erase(y)); while ((y = x) != begin() && (--x)->p >= y->p) isect(x, erase(y)); } ll query(ll x) { assert(!empty()); auto l = *lower_bound(x); return l.k * x + l.m; } };</pre>	
--	--

Treap.h

Description: A short self-balancing tree. It acts as a sequential container with log-time splits/joins, and is easy to augment with additional data.

Time: $\mathcal{O}(\log N)$

1754b4, 53 lines

<pre>struct Node { Node *l = 0, *r = 0; int val, y, c = 1; Node(int val) : val(val), y(rand()) {} void recalc(); }; int cnt(Node* n) { return n ? n->c : 0; } void Node::recalc() { c = cnt(l) + cnt(r) + 1; } template<class F> void each(Node* n, F f) { if (n) { each(n->l, f); f(n->val); each(n->r, f); } } pair<Node*, Node*> split(Node* n, int k) { if (!n) return {}; if (cnt(n->l) >= k) { // "n->val >= k" for lower_bound(k) auto [L,R] = split(n->l, k); n->l = R; n->recalc(); return {L, n}; } else { auto [L,R] = split(n->r, k - cnt(n->l) - 1); // and just "k" n->r = L; n->recalc(); return {n, R}; } }</pre>	
---	--

<pre>Node* merge(Node* l, Node* r) { if (!l) return r; if (!r) return l; if (l->y > r->y) { l->r = merge(l->r, r); return l->recalc(), l; } else { r->l = merge(l, r->l); return r->recalc(), r; } } Node* ins(Node* t, Node* n, int pos) { auto [l,r] = split(t, pos); return merge(merge(l, n), r); } // Example application: move the range [l, r) to index k void move(Node*& t, int l, int r, int k) {</pre>	
--	--

<pre>Node *a, *b, *c; tie(a,b) = split(t, l); tie(b,c) = split(b, r - l); if (k <= l) t = merge(ins(a, b, k), c); else t = merge(a, ins(c, b, k - r)); }</pre>	
---	--

FenwickTree.h

Description: Computes partial sums $a[0] + a[1] + \dots + a[\text{pos} - 1]$, and updates single elements $a[i]$, taking the difference between the old and new value.

Time: Both operations are $\mathcal{O}(\log N)$.

be8dea, 22 lines

<pre>struct FT { vll s; FT(int n) : s(n) {} void update(int pos, ll dif) { // a[pos] += dif for (; pos < sz(s); pos = pos + 1) s[pos] += dif; } ll query(int pos) { // sum of values in [0, pos) ll res = 0; for (; pos > 0; pos &= pos - 1) res += s[pos-1]; return res; } int lower_bound(ll sum) { // min pos st sum of [0, pos] >= sum // Returns n if no sum is >= sum, or -1 if empty sum is. if (sum <= 0) return -1; int pos = 0; for (int pw = 1 << 25; pw; pw >>= 1) { if (pos + pw <= sz(s) && s[pos + pw-1] < sum) pos += pw, sum -= s[pos-1]; } return pos; } };</pre>	
---	--

FenwickTree2d.h

Description: Computes sums $a[i,j]$ for all $i < I, j < J$, and increases single elements $a[i,j]$. Requires that the elements to be updated are known in advance (call `fakeUpdate()` before `init()`).

Time: $\mathcal{O}(\log^2 N)$. (Use persistent segment trees for $\mathcal{O}(\log N)$.)

"FenwickTree.h" c31cc5, 22 lines

<pre>struct FT2 { vector<vll> ys; vector<FT> ft; FT2(int limx) : ys(limx) {} void fakeUpdate(int x, int y) { for (; x < sz(ys); x = x + 1) ys[x].push_back(y); } void init() { for (vll& v : ys) sort(all(v)), ft.emplace_back(sz(v)); } int ind(int x, int y) { return (int)(lower_bound(all(ys[x]), y) - ys[x].begin()); } void update(int x, int y, ll dif) { for (; x < sz(ys); x = x + 1) ft[x].update(ind(x, y), dif); } ll query(int x, int y) { ll sum = 0; for (; x; x &= x - 1) sum += ft[x-1].query(ind(x-1, y)); return sum; } };</pre>	
---	--

RMQ.h

Description: Range Minimum Queries on an array. Returns $\min(V[a], V[a + 1], \dots V[b - 1])$ in constant time.

Usage: RMQ rmq(values);

rmq.query(inclusive, exclusive);

Time: $\mathcal{O}(|V| \log |V| + Q)$

510c32, 16 lines

```
template<class T>
struct RMQ {
    vector<vector<T>>> jmp;
    RMQ(const vector<T>& V) : jmp(1, V) {
        for (int pw = 1, k = 1; pw * 2 <= sz(V); pw *= 2, ++k) {
            jmp.emplace_back(sz(V) - pw * 2 + 1);
            rep(j, 0, sz(jmp[k]))
                jmp[k][j] = min(jmp[k - 1][j], jmp[k - 1][j + pw]);
        }
    }
    T query(int a, int b) {
        assert(a < b); // or return inf if a == b
        int dep = 31 - __builtin_clz(b - a);
        return min(jmp[dep][a], jmp[dep][b - (1 << dep)]);
    }
};
```

MoQueries.h

Description: Answer interval or tree path queries by finding an approximate TSP through the queries, and moving from one query to the next by adding/removing points at the ends. If values are on tree edges, change step to add/remove the edge (a, c) and remove the initial add call (but keep in).

Time: $\mathcal{O}(N\sqrt{Q})$

a12ef4, 49 lines

```
void add(int ind, int end) { ... } // add a[ind] (end = 0 or 1)
void del(int ind, int end) { ... } // remove a[ind]
int calc() { ... } // compute current answer
```

```
vi mo(vector<pii> Q) {
    int L = 0, R = 0, blk = 350; // ~N/sqrt(Q)
    vi s(sz(Q)), res = s;
    #define K(x) pii(x.first/blk, x.second ^ -(x.first/blk & 1))
    iota(all(s), 0);
    sort(all(s), [&](int s, int t){ return K(Q[s]) < K(Q[t]); });
    for (int qi : s) {
        pii q = Q[qi];
        while (L > q.first) add(--L, 0);
        while (R < q.second) add(R++, 1);
        while (L < q.first) del(L++, 0);
        while (R > q.second) del(--R, 1);
        res[qi] = calc();
    }
    return res;
}
```

```
vi moTree(vector<array<int, 2>> Q, vector<vi>& ed, int root=0) {
    int N = sz(ed), pos[2] = {}, blk = 350; // ~N/sqrt(Q)
    vi s(sz(Q)), res = s, I(N), L(N), R(N), in(N), par(N);
    add(0, 0), in[0] = 1;
    auto dfs = [&](int x, int p, int dep, auto& f) -> void {
        par[x] = p;
        L[x] = N;
        if (dep) I[x] = N++;
        for (int y : ed[x]) if (y != p) f(y, x, !dep, f);
        if (!dep) I[x] = N++;
        R[x] = N;
    };
    dfs(root, -1, 0, dfs);
    #define K(x) pii(I[x[0]] / blk, I[x[1]] ^ -(I[x[0]] / blk & 1))
    iota(all(s), 0);
    sort(all(s), [&](int s, int t){ return K(Q[s]) < K(Q[t]); });
    for (int qi : s) rep(end, 0, 2) {
        int &a = pos[end], b = Q[qi][end], i = 0;
```

```
#define step(c) { if (in[c]) { del(a, end); in[a] = 0; } \
                  else { add(c, end); in[c] = 1; } a = c; } \
while (!(L[b] <= L[a] && R[a] <= R[b]))
    I[i++] = b, b = par[b];
while (a != b) step(par[a]);
while (i-->) step(I[i]);
if (end) res[qi] = calc();
}
return res;
}
```

PQUpdate.h

Description: T: value/update type. DS: Stores T. Same semantics as std::priority_queue.

Time: $\mathcal{O}(U \log N)$.

35a7d2, 36 lines

```
template<class T, class DS, class Compare = less<T>>
struct PQUpdate {
    DS inner;
    multimap<T, int, Compare> rev_upd;
    using iter = decltype(rev_upd)::iterator;
    vector<iter> st;
    PQUpdate(DS inner, Compare comp={}) :
        inner(inner), rev_upd(comp) {}

    bool empty() { return st.empty(); }
    const T& top() { return rev_upd.rbegin()->first; }
    void push(T value) {
        inner.push(value);
        st.push_back(rev_upd.insert({value, sz(st)}));
    }
    void pop() {
        vector<iter> extra;
        iter curr = rev_upd.end();
        int min_ind = sz(st);
        do {
            extra.push_back(--curr);
            min_ind = min(min_ind, curr->second);
        } while (2*sz(extra) < sz(st) - min_ind);
        while (sz(st) > min_ind) {
            if (rev_upd.value_comp()(*st.back(), *curr))
                extra.push_back(st.back());
            inner.pop(); st.pop_back();
        }
        rev_upd.erase(extra[0]);
        for (auto it : extra | views::drop(1) | views::reverse) {
            it->second = sz(st);
            inner.push(it->first);
            st.push_back(it);
        }
    }
};
```

WaveletTree.h

Description: kth: finds k+1th smallest number in [l,r], count: rank of k (how many < k) in [l,r]. Doesn't support negative numbers, and requires a[i] <= maxval. Use BitVector to make 1.6x faster and 4x less memory.

Time: $\mathcal{O}(\log MAX)$

11aee1, 38 lines

```
struct WaveletTree {
    int n; vvi bv; // vector<BitVector> bv;
    WaveletTree(vl a, ll max_val):
        n(sz(a)), bv(1+__lg(max_val), {a}) {
        vl nxt(n);
        for (int h = sz(bv); h-->) {
            vector<bool> b(n);
            rep(i, 0, n) b[i] = ((a[i] >> h) & 1);
            bv[h] = vi(n+1); // bv[h] = b;
            rep(i, 0, n) bv[h][i+1] = bv[h][i] + !b[i]; // delete
```

```
        array it{begin(nxt), begin(nxt) + bv[h][n]};
        rep(i, 0, n) *it[b[i]] += a[i];
        swap(a, nxt);
    }
}
ll kth(int l, int r, int k) {
    ll res = 0;
    for (int h = sz(bv); h-->) {
        int l0 = bv[h][l], r0 = bv[h][r];
        if (k < r0 - l0) l = l0, r = r0;
        else
            k -= r0 - l0, res |= 1ULL << h,
            l += bv[h][n] - l0, r += bv[h][n] - r0;
    }
    return res;
}
int count(int l, int r, ll ub) {
    int res = 0;
    for (int h = sz(bv); h-->) {
        int l0 = bv[h][l], r0 = bv[h][r];
        if ((~ub >> h) & 1) l = l0, r = r0;
        else
            res += r0 - l0, l += bv[h][n] - l0,
            r += bv[h][n] - r0;
    }
    return res;
}
};
```

Numerical (4)

4.1 Polynomials and recurrences

Polynomial.h

c9b7b0, 17 lines

```
struct Poly {
    vector<double> a;
    double operator()(double x) const {
        double val = 0;
        for (int i = sz(a); i-->) (val *= x) += a[i];
        return val;
    }
    void diff() {
        rep(i, 1, sz(a)) a[i-1] = i*a[i];
        a.pop_back();
    }
    void divroot(double x0) {
        double b = a.back(), c; a.back() = 0;
        for(int i=sz(a)-1; i-->) c = a[i], a[i] = a[i+1]*x0+b, b=c;
        a.pop_back();
    }
};
```

PolyRoots.h

Description: Finds the real roots to a polynomial.

Usage: polyRoots({{2, -3, 1}}, -1e9, 1e9) // solve $x^2 - 3x + 2 = 0$

Time: $\mathcal{O}(n^2 \log(1/\epsilon))$

b00bfe, 23 lines

```
vector<double> polyRoots(Poly p, double xmin, double xmax) {
    if (sz(p.a) == 2) { return {-p.a[0]/p.a[1]}; }
    vector<double> ret;
    Poly der = p;
    der.diff();
    auto dr = polyRoots(der, xmin, xmax);
    dr.push_back(xmin-1);
    dr.push_back(xmax+1);
    sort(all(dr));
    rep(i, 0, sz(dr)-1) {
```

```
double l = dr[i], h = dr[i+1];
bool sign = p(l) > 0;
if (sign ^ (p(h) > 0)) {
    rep(it,0,60) { // while (h - l > 1e-8)
        double m = (l + h) / 2, f = p(m);
        if ((f <= 0) ^ sign) l = m;
        else h = m;
    }
    ret.push_back((l + h) / 2);
}
}
return ret;
}
```

PolyInterpolate.h

Description: Given n points $(x[i], y[i])$, computes an $n-1$ -degree polynomial p that passes through them: $p(x) = a[0] * x^0 + ... + a[n-1] * x^{n-1}$. For numerical precision, pick $x[k] = c * \cos(k / (n-1) * \pi), k = 0 \dots n-1$.
Time: $\mathcal{O}(n^2)$

```
typedef vector<double> vd;
vd interpolate(vd x, vd y, int n) {
    vd res(n), temp(n);
    rep(k,0,n-1) rep(i,k+1,n)
        y[i] = (y[i] - y[k]) / (x[i] - x[k]);
    double last = 0; temp[0] = 1;
    rep(k,0,n) rep(i,0,n) {
        res[i] += y[k] * temp[i];
        swap(last, temp[i]);
        temp[i] -= last * x[k];
    }
    return res;
}
```

BerlekampMassey.h

Description: Recovers any n -order linear recurrence relation from the first $2n$ terms of the recurrence. Useful for guessing linear recurrences after brute-forcing the first terms. Should work on any field, but numerical stability for floats is not guaranteed. Output will have size $\leq n$.
Usage: berlekampMassey({0, 1, 1, 3, 5, 11}) // {1, 2}
Time: $\mathcal{O}(N^2)$

```
.../number-theory/ModPow.h
vll berlekampMassey(vll s) {
    int n = sz(s), L = 0, m = 0;
    vll C(n), B(n), T;
    C[0] = B[0] = 1;

    ll b = 1;
    rep(i,0,n) { ++m;
        ll d = s[i] % mod;
        rep(j,1,L+1) d = (d + C[j] * s[i - j]) % mod;
        if (!d) continue;
        T = C; ll coef = d * modpow(b, mod-2) % mod;
        rep(j,m,n) C[j] = (C[j] - coef * B[j - m]) % mod;
        if (2 * L > i) continue;
        L = i + 1 - L; B = T; b = d; m = 0;
    }

    C.resize(L + 1); C.erase(C.begin());
    for (ll& x : C) x = (mod - x) % mod;
    return C;
}
```

LinearRecurrence.h

Description: Generates the k 'th term of an n -order linear recurrence $S[i] = \sum_j S[i-j-1]tr[j]$, given $S[0 \dots \geq n-1]$ and $tr[0 \dots n-1]$. Faster than matrix multiplication. Useful together with Berlekamp–Massey.
Usage: linearRec({0, 1}, {1, 1}, k) // k 'th Fibonacci number
Time: $\mathcal{O}(n^2 \log k)$

```
typedef vector<ll> Poly;
ll linearRec(Poly S, Poly tr, ll k) {
    int n = sz(tr);

    auto combine = [&](Poly a, Poly b) {
        Poly res(n * 2 + 1);
        rep(i,0,n+1) rep(j,0,n+1)
            res[i + j] = (res[i + j] + a[i] * b[j]) % mod;
        for (int i = 2 * n; i > n; --i) rep(j,0,n)
            res[i - 1 - j] = (res[i - 1 - j] + res[i] * tr[j]) % mod;
        res.resize(n + 1);
        return res;
    };

    Poly pol(n + 1), e(pol);
    pol[0] = e[1] = 1;

    for (++k; k; k /= 2) {
        if (k % 2) pol = combine(pol, e);
        e = combine(e, e);
    }

    ll res = 0;
    rep(i,0,n) res = (res + pol[i + 1] * S[i]) % mod;
    return res;
}
```

4.2 Optimization

GoldenSectionSearch.h

Description: Finds the argument minimizing the function f in the interval $[a,b]$ assuming f is unimodal on the interval, i.e. has only one local minimum and no local maximum. The maximum error in the result is eps . Works equally well for maximization with a small change in the code. See Ternary-Search.h in the Various chapter for a discrete version.
Usage: double func(double x) { return 4+x+.3*x*x; }
double xmin = gss(-1000,1000,func);
Time: $\mathcal{O}(\log((b-a)/\epsilon))$

```
double gss(double a, double b, double (*f)(double)) {
    double r = (sqrt(5)-1)/2, eps = 1e-7;
    double x1 = b - r*(b-a), x2 = a + r*(b-a);
    double f1 = f(x1), f2 = f(x2);
    while (b-a > eps)
        if (f1 < f2) { //change to > to find maximum
            b = x2; x2 = x1; f2 = f1;
            x1 = b - r*(b-a); f1 = f(x1);
        } else {
            a = x1; x1 = x2; f1 = f2;
            x2 = a + r*(b-a); f2 = f(x2);
        }
    return a;
}
```

HillClimbing.h

Description: Poor man's optimization for unimodal functions.

```
typedef array<double, 2> P;

template<class F> pair<double, P> hillClimb(P start, F f) {
    pair<double, P> cur(f(start), start);
    for (double jmp = 1e9; jmp > 1e-20; jmp /= 2) {
        rep(j,0,100) rep(dx,-1,2) rep(dy,-1,2) {
```

```
        P p = cur.second;
        p[0] += dx*jmp;
        p[1] += dy*jmp;
        cur = min(cur, make_pair(f(p), p));
    }
}
return cur;
}
```

Integrate.h

Description: Simple integration of a function over an interval using Simpson's rule. The error should be proportional to h^4 , although in practice you will want to verify that the result is stable to desired precision when epsilon changes.

```
template<class F>
double quad(double a, double b, F f, const int n = 1000) {
    double h = (b - a) / 2 / n, v = f(a) + f(b);
    rep(i,1,n*2)
        v += f(a + i*h) * (i&1 ? 4 : 2);
    return v * h / 3;
}
```

IntegrateAdaptive.h

Description: Fast integration using an adaptive Simpson's rule.
Usage: double sphereVolume = quad(-1, 1, [](double x) { return quad(-1, 1, [&](double y) { return quad(-1, 1, [&](double z) { return x*x + y*y + z*z < 1; });});});

```
typedef double d;
#define S(a,b) (f(a) + 4*f((a+b) / 2) + f(b)) * (b-a) / 6
```

```
template <class F>
d rec(F& f, d a, d b, d eps, d S) {
    d c = (a + b) / 2;
    d S1 = S(a, c), S2 = S(c, b), T = S1 + S2;
    if (abs(T - S) <= 15 * eps || b - a < 1e-10)
        return T + (T - S) / 15;
    return rec(f, a, c, eps / 2, S1) + rec(f, c, b, eps / 2, S2);
}

template<class F>
d quad(d a, d b, F f, d eps = 1e-8) {
    return rec(f, a, b, eps, S(a, b));
}
```

RungeKutta.h

Description: Numerically approximates the solution to a system of Differential Equations

```
template<class F, class T>
T solveSystem(F f, T x, double time, int iters) {
    double h = time / iters;
    for(int iter = 0; iter < iters; iter++) {
        T k1 = f(x);
        A k2 = f(x + 0.5 * h * k1);
        A k3 = f(x + 0.5 * h * k2);
        A k4 = f(x + h * k3);
        x = x + h / 6.0 * (k1 + 2.0 * k2 + 2.0 * k3 + k4);
    }
    return x;
}
```


Simplex.h

Description: Solves a general linear maximization problem: maximize $c^T x$ subject to $Ax \leq b$, $x \geq 0$. Returns -inf if there is no solution, inf if there are arbitrarily good solutions, or the maximum value of $c^T x$ otherwise. The input vector is set to an optimal x (or in the unbounded case, an arbitrary solution fulfilling the constraints). Numerical stability is not guaranteed. For better performance, define variables such that $x = 0$ is viable.
Usage: vvd A = {{1,-1}, {-1,1}, {-1,-2}};
vd b = {1,1,-4}, c = {-1,-1}, x;
T val = LPSolver(A, b, c).solve(x);
Time: $\mathcal{O}(NM * \#pivots)$, where a pivot may be e.g. an edge relaxation. $\mathcal{O}(2^n)$ in the general case.

aa8530, 68 lines

```
typedef double T; // long double, Rational, double + mod<P>...
typedef vector<T> vd;
typedef vector<vd> vvd;
```

```
const T eps = 1e-8, inf = 1/.0;
#define MP make_pair
#define ltj(X) if(s == -1 || MP(X[j],N[j]) < MP(X[s],N[s])) s=j
```

```
struct LPSolver {
    int m, n;
    vi N, B;
    vvd D;

    LPSolver(const vvd& A, const vd& b, const vd& c) :
        m(sz(b)), n(sz(c)), N(n+1), B(m), D(m+2, vd(n+2)) {
        rep(i,0,m) rep(j,0,n) D[i][j] = A[i][j];
        rep(i,0,m) { B[i] = n+i; D[i][n] = -1; D[i][n+1] = b[i]; }
        rep(j,0,n) { N[j] = j; D[m][j] = -c[j]; }
        N[n] = -1; D[m+1][n] = 1;
    }

    void pivot(int r, int s) {
        T *a = D[r].data(), inv = 1 / a[s];
        rep(i,0,m+2) if (i != r && abs(D[i][s]) > eps) {
            T *b = D[i].data(), inv2 = b[s] * inv;
            rep(j,0,n+2) b[j] -= a[j] * inv2;
            b[s] = a[s] * inv2;
        }
        rep(j,0,n+2) if (j != s) D[r][j] *= inv;
        rep(i,0,m+2) if (i != r) D[i][s] *= -inv;
        D[r][s] = inv;
        swap(B[r], N[s]);
    }
}
```

```
bool simplex(int phase) {
    int x = m + phase - 1;
    for (;;) {
        int s = -1;
        rep(j,0,n+1) if (N[j] != -phase) ltj(D[x]);
        if (D[x][s] >= -eps) return true;
        int r = -1;
        rep(i,0,m) {
            if (D[i][s] <= eps) continue;
            if (r == -1 || MP(D[i][n+1] / D[i][s], B[i])
                < MP(D[r][n+1] / D[r][s], B[r])) r = i;
        }
        if (r == -1) return false;
        pivot(r, s);
    }
}

T solve(vd &x) {
    int r = 0;
    rep(i,1,m) if (D[i][n+1] < D[r][n+1]) r = i;
    if (D[r][n+1] < -eps) {
        pivot(r, n);
```

```
        if (!simplex(2) || D[m+1][n+1] < -eps) return -inf;
        rep(i,0,m) if (B[i] == -1) {
            int s = 0;
            rep(j,1,n+1) ltj(D[i]);
            pivot(i, s);
        }
    }
    bool ok = simplex(1); x = vd(n);
    rep(i,0,m) if (B[i] < n) x[B[i]] = D[i][n+1];
    return ok ? D[m][n+1] : inf;
};
```

4.3 Matrices

Determinant.h

Description: Calculates determinant using modular arithmetics. Modulos can also be removed to get a pure-integer version.
Time: $\mathcal{O}(N^3)$

3313dc, 18 lines

```
const ll mod = 12345;
ll det(vector<vector<ll>>& a) {
    int n = sz(a); ll ans = 1;
    rep(i,0,n) {
        rep(j,i+1,n) {
            while (a[j][i] != 0) { // gcd step
                ll t = a[i][i] / a[j][i];
                if (t) rep(k,i,n)
                    a[i][k] = (a[i][k] - a[j][k] * t) % mod;
                swap(a[i], a[j]);
                ans *= -1;
            }
        }
        ans = ans * a[i][i] % mod;
        if (!ans) return 0;
    }
    return (ans + mod) % mod;
}
```

SolveLinear.h

Description: Solves $A * x = b$. If there are multiple solutions, an arbitrary one is returned. Returns rank, or -1 if no solutions. Data in A and b is lost.
Time: $\mathcal{O}(n^2 m)$

44c9ab, 38 lines

```
typedef vector<double> vd;
const double eps = 1e-12;

int solveLinear(vector<vd>& A, vd& b, vd& x) {
    int n = sz(A), m = sz(x), rank = 0, br, bc;
    if (n) assert(sz(A[0]) == m);
    vi col(m); iota(all(col), 0);

    rep(i,0,n) {
        double v, bv = 0;
        rep(r,i,n) rep(c,i,m)
            if ((v = fabs(A[r][c])) > bv)
                br = r, bc = c, bv = v;
        if (bv <= eps) {
            rep(j,i,n) if (fabs(b[j]) > eps) return -1;
            break;
        }
        swap(A[i], A[br]);
        swap(b[i], b[br]);
        swap(col[i], col[bc]);
        rep(j,0,n) swap(A[j][i], A[j][bc]);
        bv = 1/A[i][i];
        rep(j,i+1,n) {
            double fac = A[j][i] * bv;
            b[j] -= fac * b[i];
            rep(k,i+1,m) A[j][k] -= fac*A[i][k];
```

```
        }
        rank++;
    }

    x.assign(m, 0);
    for (int i = rank; i--;) {
        b[i] /= A[i][i];
        x[col[i]] = b[i];
        rep(j,0,i) b[j] -= A[j][i] * b[i];
    }
    return rank; // (multiple solutions if rank < m)
}
```

SolveLinear2.h

Description: To get all uniquely determined values of x back from SolveLinear, make the following changes:

"SolveLinear.h"08e495, 7 lines

```
rep(j,0,n) if (j != i) // instead of rep(j,i+1,n)
// ... then at the end:
x.assign(m, undefined);
rep(i,0,rank) {
    rep(j,rank,m) if (fabs(A[i][j]) > eps) goto fail;
    x[col[i]] = b[i] / A[i][i];
fail:; }
```

SolveLinearBinary.h

Description: Solves $Ax = b$ over \mathbb{F}_2 . If there are multiple solutions, one is returned arbitrarily. Returns rank, or -1 if no solutions. Destroys A and b .
Time: $\mathcal{O}(n^2 m)$

fa2d7a, 34 lines

```
typedef bitset<1000> bs;

int solveLinear(vector<bs>& A, vi& b, bs& x, int m) {
    int n = sz(A), rank = 0, br;
    assert(m <= sz(x));
    vi col(m); iota(all(col), 0);
    rep(i,0,n) {
        for (br=i; br<n; ++br) if (A[br].any()) break;
        if (br == n) {
            rep(j,i,n) if(b[j]) return -1;
            break;
        }
        int bc = (int)A[br]._Find_next(i-1);
        swap(A[i], A[br]);
        swap(b[i], b[br]);
        swap(col[i], col[bc]);
        rep(j,0,n) if (A[j][i] != A[j][bc]) {
            A[j].flip(i); A[j].flip(bc);
        }
        rep(j,i+1,n) if (A[j][i]) {
            b[j] ^= b[i];
            A[j] ^= A[i];
        }
        rank++;
    }

    x = bs();
    for (int i = rank; i--;) {
        if (!b[i]) continue;
        x[col[i]] = 1;
        rep(j,0,i) b[j] ^= A[j][i];
    }
    return rank; // (multiple solutions if rank < m)
}
```

MatrixInverse-mod.h

Description: Invert matrix A modulo a prime. Returns rank; result is stored in A unless singular (rank < n). For prime powers, repeatedly set $A^{-1} = A^{-1}(2I - AA^{-1}) \pmod{p^k}$ where A^{-1} starts as the inverse of A mod p , and k is doubled in each step.

Time: $\mathcal{O}(n^3)$

"/number-theory/ModPow.h"0b7b13, 37 lines

```
int matInv(vector<vector<ll>>& A) {
    int n = sz(A); vi col(n);
    vector<vector<ll>> tmp(n, vector<ll>(n));
    rep(i,0,n) tmp[i][i] = 1, col[i] = i;

    rep(i,0,n) {
        int r = i, c = i;
        rep(j,i,n) rep(k,i,n) if (A[j][k]) {
            r = j; c = k; goto found;
        }
        return i;
    found:
        A[i].swap(A[r]); tmp[i].swap(tmp[r]);
        rep(j,0,n)
            swap(A[j][i], A[j][c]), swap(tmp[j][i], tmp[j][c]);
        swap(col[i], col[c]);
        ll v = modpow(A[i][i], mod - 2);
        rep(j,i+1,n) {
            ll f = A[j][i] * v % mod;
            A[j][i] = 0;
            rep(k,i+1,n) A[j][k] = (A[j][k] - f*A[i][k]) % mod;
            rep(k,0,n) tmp[j][k] = (tmp[j][k] - f*tmp[i][k]) % mod;
        }
        rep(j,i+1,n) A[i][j] = A[i][j] * v % mod;
        rep(j,0,n) tmp[i][j] = tmp[i][j] * v % mod;
        A[i][i] = 1;
    }

    for (int i = n-1; i > 0; --i) rep(j,0,i) {
        ll v = A[j][i];
        rep(k,0,n) tmp[j][k] = (tmp[j][k] - v*tmp[i][k]) % mod;
    }

    rep(i,0,n) rep(j,0,n)
        A[col[i]][col[j]] = tmp[i][j] % mod + (tmp[i][j] < 0)*mod;
    return n;
}
```

Tridiagonal.h

Description: $x = \text{tridiagonal}(d,p,q,b)$ solves the equation system

$$\begin{pmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_{n-1} \end{pmatrix} = \begin{pmatrix} d_0 & p_0 & 0 & 0 & \cdots & 0 \\ q_0 & d_1 & p_1 & 0 & \cdots & 0 \\ 0 & q_1 & d_2 & p_2 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \cdots & q_{n-3} & d_{n-2} & p_{n-2} \\ 0 & 0 & \cdots & q_{n-2} & d_{n-1} & \end{pmatrix} \begin{pmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_{n-1} \end{pmatrix}.$$

This is useful for solving problems on the type

$$a_i = b_i a_{i-1} + c_i a_{i+1} + d_i, 1 \leq i \leq n,$$

where a_0, a_{n+1}, b_i, c_i and d_i are known. a can then be obtained from

$$\{a_i\} = \text{tridiagonal}(\{1, -1, -1, \dots, -1, 1\}, \{0, c_1, c_2, \dots, c_n\}, \{b_1, b_2, \dots, b_n, 0\}, \{a_0, d_1, d_2, \dots, d_n, a_{n+1}\}).$$

Fails if the solution is not unique.

If $|d_i| > |p_i| + |q_{i-1}|$ for all i , or $|d_i| > |p_{i-1}| + |q_i|$, or the matrix is positive definite, the algorithm is numerically stable and neither `tr` nor the check for `diag[i] == 0` is needed.

Time: $\mathcal{O}(N)$

```
typedef double T;
```

8f9fa8, 26 lines

```
vector<T> tridiagonal(vector<T> diag, const vector<T>& super,
    const vector<T>& sub, vector<T> b) {
    int n = sz(b); vi tr(n);
    rep(i,0,n-1) {
        if (abs(diag[i]) < 1e-9 * abs(super[i])) { // diag[i] == 0
            b[i+1] -= b[i] * diag[i+1] / super[i];
            if (i+2 < n) b[i+2] -= b[i] * sub[i+1] / super[i];
            diag[i+1] = sub[i]; tr[++i] = 1;
        } else {
            diag[i+1] -= super[i]*sub[i]/diag[i];
            b[i+1] -= b[i]*sub[i]/diag[i];
        }
    }
    for (int i = n; i--;) {
        if (tr[i]) {
            swap(b[i], b[i-1]);
            diag[i-1] = diag[i];
            b[i] /= super[i-1];
        } else {
            b[i] /= diag[i];
            if (i) b[i-1] -= b[i]*super[i-1];
        }
    }
    return b;
}
```

JacobianMatrix.h

Description: Makes Jacobian Matrix using finite differences

75dc90, 15 lines

```
template<class F, class T>
vector<vector<T>> makeJacobian(F &f, vector<T> &x) {
    int n = sz(x);
    vector<vector<T>> J(n, vector<T>(n));
    vector<T> fX0 = f(x);
    rep(i, 0, n) {
        x[i] += eps;
        vector<T> fX1 = f(x);
        rep(j, 0, n){
            J[j][i] = (fX1[j] - fX0[j]) / eps;
        }
        x[i] -= eps;
    }
    return J;
}
```

NewtonsMethod.h

Description: Solves a system on non-linear equations

jacobianMatrix.h6af945, 10 lines

```
template<class F, class T>
void solveNonlinear(F f, vector<T> &x){
    int n = sz(x);
    rep(iter, 0, 100) {
        vector<vector<T>> J = makeJacobian(f, x);
        matInv(J);
        vector<T> dx = J * f(x);
        x = x - dx;
    }
}
```

4.4 Fourier transforms

FastFourierTransform.h

Description: `fft(a)` computes $\hat{f}(k) = \sum_x a[x] \exp(2\pi i \cdot kx/N)$ for all k . N must be a power of 2. Useful for convolution: `conv(a, b) = c`, where $c[x] = \sum a[i]b[x-i]$. For convolution of complex numbers or more than two vectors: FFT, multiply pointwise, divide by n , reverse(start+1, end), FFT back. Rounding is safe if $(\sum a_i^2 + \sum b_i^2) \log_2 N < 9 \cdot 10^{14}$ (in practice 10^{16} ; higher for random inputs). Otherwise, use NTT/FFTMod.

Time: $\mathcal{O}(N \log N)$ with $N = |A| + |B|$ ($\sim 1s$ for $N = 2^{22}$)

00ced6, 35 lines

```
typedef complex<double> C;
typedef vector<double> vd;
void fft(vector<C>& a) {
    int n = sz(a), L = 31 - __builtin_clz(n);
    static vector<complex<long double>> R(2, 1);
    static vector<C> rt(2, 1); // (^ 10% faster if double)
    for (static int k = 2; k < n; k *= 2) {
        R.resize(n); rt.resize(n);
        auto x = polar(1.0L, acos(-1.0L) / k);
        rep(i,k,2*k) rt[i] = R[i] = i&1 ? R[i/2] * x : R[i/2];
    }
    vi rev(n);
    rep(i,0,n) rev[i] = (rev[i / 2] | (i & 1) << L) / 2;
    rep(i,0,n) if (i < rev[i]) swap(a[i], a[rev[i]]);
    for (int k = 1; k < n; k *= 2)
        for (int i = 0; i < n; i += 2 * k) rep(j,0,k) {
            C z = rt[j+k] * a[i+j+k]; // (25% faster if hand-rolled)
            a[i + j + k] = a[i + j] - z;
            a[i + j] += z;
        }
}
vd conv(const vd& a, const vd& b) {
    if (a.empty() || b.empty()) return {};
    vd res(sz(a) + sz(b) - 1);
    int L = 32 - __builtin_clz(sz(res)), n = 1 << L;
    vector<C> in(n), out(n);
    copy(all(a), begin(in));
    rep(i,0,sz(b)) in[i].imag(b[i]);
    fft(in);
    for (C& x : in) x *= x;
    rep(i,0,n) out[i] = in[-i & (n - 1)] - conj(in[i]);
    fft(out);
    rep(i,0,sz(res)) res[i] = imag(out[i]) / (4 * n);
    return res;
}
```

FastFourierTransformMod.h

Description: Higher precision FFT, can be used for convolutions modulo arbitrary integers as long as $N \log_2 N \cdot \text{mod} < 8.6 \cdot 10^{14}$ (in practice 10^{16} or higher). Inputs must be in $[0, \text{mod})$.

Time: $\mathcal{O}(N \log N)$, where $N = |A| + |B|$ (twice as slow as NTT or FFT)

"FastFourierTransform.h"b82773, 22 lines

```
typedef vector<ll> vl;
template<int M> vl convMod(const vl &a, const vl &b) {
    if (a.empty() || b.empty()) return {};
    vl res(sz(a) + sz(b) - 1);
    int B=32-__builtin_clz(sz(res)), n=1<<B, cut=int(sqrt(M));
    vector<C> L(n), R(n), outs(n), outl(n);
    rep(i,0,sz(a)) L[i] = C((int)a[i] / cut, (int)a[i] % cut);
    rep(i,0,sz(b)) R[i] = C((int)b[i] / cut, (int)b[i] % cut);
    fft(L), fft(R);
    rep(i,0,n) {
        int j = -i & (n - 1);
        outl[j] = (L[i] + conj(L[j])) * R[i] / (2.0 * n);
        outs[j] = (L[i] - conj(L[j])) * R[i] / (2.0 * n) / 1i;
    }
    fft(outl), fft(outs);
    rep(i,0,sz(res)) {
        ll av = ll(real(outl[i])+.5), cv = ll(imag(outs[i])+.5);
        ll bv = ll(imag(outl[i])+.5) + ll(real(outs[i])+.5);
        res[i] = ((av % M * cut + bv) % M * cut + cv) % M;
    }
    return res;
}
```

NumberTheoreticTransform.h

Description: ntt(a) computes $\hat{f}(k) = \sum_x a[x]g^{xk}$ for all k , where $g = \text{root}^{(\text{mod}-1)/N}$. N must be a power of 2. Useful for convolution modulo specific nice primes of the form $2^ab + 1$, where the convolution result has size at most 2^a . For arbitrary modulo, see FFTMod. conv(a, b) = c, where $c[x] = \sum a[i]b[x - i]$. For manual convolution: NTT the inputs, multiply pointwise, divide by n, reverse(start+1, end), NTT back. Inputs must be in [0, mod).

Time: $\mathcal{O}(N \log N)$

"../number-Theory/ModPow.h"	ced03d, 35 lines
<pre>const ll mod = (119 << 23) + 1, root = 62; // = 998244353 // For p < 2^30 there is also e.g. 5 << 25, 7 << 26, 479 << 21 // and 483 << 21 (same root). The last two are > 10^9. typedef vector<ll> vl; void ntt(vl &a) { int n = sz(a), L = 31 - __builtin_clz(n); static vl rt(2, 1); for (static int k = 2, s = 2; k < n; k *= 2, s++) { rt.resize(n); ll z[] = {1, modpow(root, mod >> s)}; rep(i,k,2*k) rt[i] = rt[i / 2] * z[i & 1] % mod; } vi rev(n); rep(i,0,n) rev[i] = (rev[i / 2] (i & 1) << L) / 2; rep(i,0,n) if (i < rev[i]) swap(a[i], a[rev[i]]); for (int k = 1; k < n; k *= 2) for (int i = 0; i < n; i += 2 * k) rep(j,0,k) { ll z = rt[j + k] * a[i + j + k] % mod, &ai = a[i + j]; a[i + j + k] = ai - z + (z > ai ? mod : 0); ai += (ai + z >= mod ? z - mod : z); } } vl conv(const vl &a, const vl &b) { if (a.empty() b.empty()) return {}; int s = sz(a) + sz(b) - 1, B = 32 - __builtin_clz(s), n = 1 << B; int inv = modpow(n, mod - 2); vl L(a), R(b), out(n); L.resize(n), R.resize(n); ntt(L), ntt(R); rep(i,0,n) out[-i & (n - 1)] = (ll)L[i] * R[i] % mod * inv % mod; ntt(out); return {out.begin(), out.begin() + s}; }</pre>	

FastSubsetTransform.h

Description: Transform to a basis with fast convolutions of the form $c[z] = \sum_{z=x\oplus y} a[x] \cdot b[y]$, where \oplus is one of AND, OR, XOR. The size of a must be a power of two.

Time: $\mathcal{O}(N \log N)$

```
void FST(vi& a, bool inv) {
    for (int n = sz(a), step = 1; step < n; step *= 2) {
        for (int i = 0; i < n; i += 2 * step) rep(j,i,i+step) {
            int &u = a[j], &v = a[j + step]; tie(u, v) =
                inv ? pii(v - u, u) : pii(v, u + v); // AND
                inv ? pii(v, u - v) : pii(u + v, u); // OR
                pii(u + v, u - v); // XOR
        }
    }
    if (inv) for (int& x : a) x /= sz(a); // XOR only
}

vi conv(vi a, vi b) {
    FST(a, 0); FST(b, 0);
    rep(i,0,sz(a)) a[i] *= b[i];
    FST(a, 1); return a;
}
```

Number theory (5)

5.1 Modular arithmetic

ModularArithmetic.h

Description: Operators for modular arithmetic. You need to set mod to some number first and then you can use the structure.

"euclid.h"	35bfea, 18 lines
<pre>const ll mod = 17; // change to something else struct Mod { ll x; Mod(ll xx) : x(xx) {} Mod operator+(Mod b) { return Mod((x + b.x) % mod); } Mod operator-(Mod b) { return Mod((x - b.x + mod) % mod); } Mod operator*(Mod b) { return Mod((x * b.x) % mod); } Mod operator/(Mod b) { return *this * invert(b); } Mod invert(Mod a) { ll x, y, g = euclid(a.x, mod, x, y); assert(g == 1); return Mod((x + mod) % mod); } Mod operator^(ll e) { if (!e) return Mod(1); Mod r = *this ^ (e / 2); r = r * r; return e&1 ? *this * r : r; } };</pre>	

ModInverse.h

Description: Pre-computation of modular inverses. Assumes $\text{LIM} \leq \text{mod}$ and that mod is a prime.

<pre>const ll mod = 1000000007, LIM = 200000; ll* inv = new ll[LIM] - 1; inv[1] = 1; rep(i,2,LIM) inv[i] = mod - (mod / i) * inv[mod % i] % mod;</pre>	
<h2>ModPow.h</h2>	
b83e45, 7 lines	<pre>const ll mod = 1000000007; // faster if const ll modpow(ll b, ll e) { ll ans = 1; for (; e; b = b * b % mod, e /= 2) if (e & 1) ans = ans * b % mod; return ans; }</pre>

ModLog.h

Description: Returns the smallest $x > 0$ s.t. $a^x = b \pmod m$, or -1 if no such x exists. modLog(a,1,m) can be used to calculate the order of a .

Time: $\mathcal{O}(\sqrt{m})$

```
ll modLog(ll a, ll b, ll m) {
    ll n = (ll) sqrt(m) + 1, e = 1, f = 1, j = 1;
    unordered_map<ll, ll> A;
    while (j <= n && (e = f = e * a % m) != b % m)
        A[e * b % m] = j++;
    if (e == b % m) return j;
    if (__gcd(m, e) == __gcd(m, b))
        rep(i, 2, n+2) if (A.count(e = e * f % m))
            return n * i - A[e];
    return -1;
}
```

ModSum.h

Description: Sums of mod'ed arithmetic progressions.

modsum(to, c, k, m) = $\sum_{i=0}^{\text{to}-1} (ki + c) \% m$. divsum is similar but for floored division.

Time: $\log(m)$, with a large constant.

```
typedef unsigned long long ull;
```

<pre>ull sumsq(ull to) { return to / 2 * ((to-1) 1); } ull divsum(ull to, ull c, ull k, ull m) { ull res = k / m * sumsq(to) + c / m * to; k %= m; c %= m; if (!k) return res; ull to2 = (to * k + c) / m; return res + (to - 1) * to2 - divsum(to2, m-1 - c, m, k); } ll modsum(ull to, ll c, ll k, ll m) { c = ((c % m) + m) % m; k = ((k % m) + m) % m; return to * c + k * sumsq(to) - m * divsum(to, c, k, m); }</pre>	
---	--

ModMulLL.h

Description: Calculate $a \cdot b \pmod c$ (or $a^b \pmod c$) for $0 \leq a, b \leq c \leq 7.2 \cdot 10^{18}$. **Time:** $\mathcal{O}(1)$ for modmul, $\mathcal{O}(\log b)$ for modpow

```
typedef unsigned long long ull;
ull modmul(ull a, ull b, ull M) {
    ll ret = a * b - M * ull(1.L / M * a * b);
    return ret + M * (ret < 0) - M * (ret >= (ll)M);
}
```

ModSqrt.h

Description: Tonelli-Shanks algorithm for modular square roots. Finds x s.t. $x^2 = a \pmod p$ ($-x$ gives the other solution).

Time: $\mathcal{O}(\log^2 p)$ worst case, $\mathcal{O}(\log p)$ for most p

ModPow.h"
19a793, 24 lines

```

ll sqrt(ll a, ll p) {
    a %= p; if (a < 0) a += p;
    if (a == 0) return 0;
    assert(modpow(a, (p-1)/2, p) == 1); // else no solution
    if (p % 4 == 3) return modpow(a, (p+1)/4, p);
    // a^(n+3)/8 or 2^(n+3)/8 * 2^(n-1)/4 works if p % 8 == 5
    ll s = p - 1, n = 2;
    int r = 0, m;
    while (s % 2 == 0)
        ++r, s /= 2;
    while (modpow(n, (p - 1) / 2, p) != p - 1) ++n;
    ll x = modpow(a, (s + 1) / 2, p);
    ll b = modpow(a, s, p), g = modpow(n, s, p);
    for (;;) {
        r = m;
        ll t = b;
        for (m = 0; m < r && t != 1; ++m)
            t = t * t % p;
        if (m == 0) return x;
        ll gs = modpow(g, 1LL << (r - m - 1), p);
        g = gs * gs % p;
        x = x * gs % p;
        b = b * g % p;
    }
}

```

5.2 Primality

Eratosthenes.h

Description: Prime sieve for generating all primes up to a certain limit. isprime[i] is true iff i is a prime.

Time: $\text{lim}=100'000'000 \approx 0.8$ s. Runs 30% faster if only odd indices are stored.

```
const int MAX_PR = 5e6;
bitset<MAX_PR> isprime;
vll eratosthenesSieve(int lim) {
    isprime.set(); isprime[0] = isprime[1] = 0;
    for (int i = 4; i < lim; i += 2) isprime[i] = 0;
    for (int i = 3; i*i < lim; i += 2) if (isprime[i])
        for (int j = i*i; j < lim; j += i*2) isprime[j] = 0;
}
```

```
vll pr;
rep(i,2,lim) if (isprime[i]) pr.push_back(i);
return pr;
}
```

FastEratosthenes.h

Description: Prime sieve for generating all primes smaller than LIM.
Time: LIM=1e9 ≈ 1.5s

<pre>const int LIM = 1e6; bitset<LIM> isPrime; vi eratosthenes() { const int S = (int)round(sqrt(LIM)), R = LIM / 2; vi pr = {2}, sieve(S+1); pr.reserve((int)(LIM/log(LIM)*1.1)); vector<pii> cp; for (int i = 3; i <= S; i += 2) if (!sieve[i]) { cp.push_back({i, i * i / 2}); for (int j = i * i; j <= S; j += 2 * i) sieve[j] = 1; } for (int L = 1; L <= R; L += S) { array<bool, S> block{}; for (auto &[p, idx] : cp) for (int i=idx; i < S+L; idx = (i+=p)) block[i-L] = 1; rep(i,0,min(S, R - L)) if (!block[i]) pr.push_back((L + i) * 2 + 1); } for (int i : pr) isPrime[i] = 1; return pr; }</pre>	6b2912, 20 lines
---	------------------

LinearSieve.h

Description: Finds smallest prime factor of each integer
Time: $\mathcal{O}(N)$

<pre>const int LIM = 1000000; vi lp(LIM+1), primes;</pre>	32eeca, 8 lines
---	-----------------

```
rep(i, 2, LIM + 1) {
    if (lp[i] == 0) primes.push_back(lp[i] = i);
    for (int j = 0; j < sz(primes) && i * primes[j] <= LIM &&
        primes[j] <= lp[i]; ++j)
        lp[i * primes[j]] = primes[j];
}
```

MillerRabin.h

Description: Deterministic Miller-Rabin primality test. Guaranteed to work for numbers up to $7 \cdot 10^{18}$; for larger numbers, use Python and extend A randomly.
Time: 7 times the complexity of $a^b \bmod c$.

<pre>"ModMulLL.h" bool isPrime(ull n) { if (n < 2 n % 6 % 4 != 1) return (n 1) == 3; ull A[] = {2, 325, 9375, 28178, 450775, 9780504, 1795265022}, s = __builtin_ctzll(n-1), d = n >> s; for (ull a : A) { // ^ count trailing zeroes ull p = modpow(a%n, d, n), i = s; while (p != 1 && p != n - 1 && a % n && i--) p = modmul(p, p, n); if (p != n-1 && i != s) return 0; } return 1; }</pre>	60dcd1, 12 lines
---	------------------

FindPrimeFactors.h

Description: Pollard-rho randomized factorization algorithm. Returns prime factors of a number, in arbitrary order (e.g. 2299 -> {11, 19, 11}).

<p>Time: $\mathcal{O}\left(n^{1/4}\right)$, less for numbers with small factors.</p> <pre>"ModMulLL.h", "MillerRabin.h" ull pollard(ull n) { ull x = 0, y = 0, t = 30, prd = 2, i = 1, q; auto f = [&](ull x) { return modmul(x, x, n) + i; }; while (t++ % 40 __gcd(prd, n) == 1) { if (x == y) x = ++i, y = f(x); if ((q = modmul(prd, max(x,y) - min(x,y), n))) prd = q; x = f(x), y = f(f(y)); } return __gcd(prd, n); }</pre>	d8d98d, 19 lines
---	------------------

```
vector<ull> factor(ull n) {
    if (n == 1) return {};
    if (isPrime(n)) return {n};
    ull x = pollard(n);
    auto l = factor(x), r = factor(n / x);
    l.insert(l.end(), all(r));
    return l;
}
```

GetFactors.h

Description: Gets all factors of a number N given the prime factorization of the number.

<p>Time: $\mathcal{O}\left(\sqrt[3]{N}\right)$</p> <pre>void getFactors(auto &primes, auto &pows, auto &factors, int i = 0, ll n = 1) { if(i == sz(primes)) return void(factors.push_back(n)); for(ll j = 0, pow = 1; j <= pows[i]; j++, pow *= primes[i]) getFactors(primes, pows, factors, i+1, n * pow); }</pre>	18bfb0, 5 lines
--	-----------------

5.3 Divisibility

euclid.h

Description: Finds two integers x and y , such that $ax + by = \gcd(a, b)$. If you just need gcd, use the built in `__gcd` instead. If a and b are coprime, then x is the inverse of $a \pmod b$.

<pre>ll euclid(ll a, ll b, ll &x, ll &y) { if (!b) return x = 1, y = 0, a; ll d = euclid(b, a % b, y, x); return y -= a/b * x, d; }</pre>	33ba8f, 5 lines
---	-----------------

CRT.h

Description: Chinese Remainder Theorem.
`crt(a, m, b, n)` computes x such that $x \equiv a \pmod m, x \equiv b \pmod n$. If $|a| < m$ and $|b| < n$, x will obey $0 \leq x < \text{lcm}(m, n)$. Assumes $mn < 2^{62}$.
Time: $\log(n)$

<pre>"euclid.h" ll crt(ll a, ll m, ll b, ll n) { if (n > m) swap(a, b), swap(m, n); ll x, y, g = euclid(m, n, x, y); assert((a - b) % g == 0); // else no solution x = (b - a) % n * x % n / g * m + a; return x < 0 ? x + m*n/g : x; }</pre>	04d93a, 7 lines
---	-----------------

5.3.1 Bézout’s identity

For $a \neq, b \neq 0$, then $d = \gcd(a, b)$ is the smallest positive integer for which there are integer solutions to

$$ax + by = d$$

If (x, y) is one solution, then all solutions are given by

$$\left(x + \frac{kb}{\gcd(a,b)}, y - \frac{ka}{\gcd(a,b)}\right), \quad k \in \mathbb{Z}$$

phiFunction.h

Description: *Euler’s* ϕ function is defined as $\phi(n) := \#$ of positive integers $\leq n$ that are coprime with n . $\phi(1) = 1, p$ prime $\Rightarrow \phi(p^k) = (p - 1)p^{k-1}$, m, n coprime $\Rightarrow \phi(mn) = \phi(m)\phi(n)$. If $n = p_1^{k_1}p_2^{k_2}...p_r^{k_r}$ then $\phi(n) = (p_1 - 1)p_1^{k_1-1}...(p_r - 1)p_r^{k_r-1}$. $\phi(n) = n \cdot \prod_{p|n}(1 - 1/p)$.
 $\sum_{d|n} \phi(d) = n, \sum_{1 \leq k \leq n, \gcd(k, n) = 1} k = n\phi(n)/2, n > 1$
Euler’s thm: a, n coprime $\Rightarrow a^{\phi(n)} \equiv 1 \pmod n$.
Fermat’s little thm: p prime $\Rightarrow a^{p-1} \equiv 1 \pmod p \ \forall a$.

<pre>const int LIM = 5000000; int phi[LIM]; void calculatePhi() { rep(i,0,LIM) phi[i] = i&1 ? i : i/2; for (int i = 3; i < LIM; i += 2) if(phi[i] == i) for (int j = i; j < LIM; j += i) phi[j] -= phi[j] / i; }</pre>	cf7d6d, 8 lines
---	-----------------

5.4 Fractions

ContinuedFractions.h

Description: Given N and a real number $x \geq 0$, finds the closest rational approximation p/q with $p, q \leq N$. It will obey $|p/q - x| \leq 1/qN$. For consecutive convergents, $p_{k+1}q_k - q_{k+1}p_k = (-1)^k$. $(p_k/q_k$ alternates between $> x$ and $< x$.) If x is rational, y eventually becomes ∞ ; if x is the root of a degree 2 polynomial the a ’s eventually become cyclic.
Time: $\mathcal{O}(\log N)$

<pre>typedef double d; // for N ~ 1e7; long double for N ~ 1e9 pair<ll, ll> approximate(d x, ll N) { ll LP = 0, LQ = 1, P = 1, Q = 0, inf = LLONG_MAX; d y = x; for (;;) { ll lim = min(P ? (N-LP) / P : inf, Q ? (N-LQ) / Q : inf), a = (ll)floor(y), b = min(a, lim), NP = b*P + LP, NQ = b*Q + LQ; if (a > b) { // If b > a/2, we have a semi-convergent that gives us a // better approximation; if b = a/2, we *may* have one. // Return {P, Q} here for a more canonical approximation. return (abs(x - (d)NP / (d)NQ) < abs(x - (d)P / (d)Q)) ? make_pair(NP, NQ) : make_pair(P, Q); } if (abs(y = 1/(y - (d)a)) > 3*N) { return {NP, NQ}; } LP = P; P = NP; LQ = Q; Q = NQ; } }</pre>	dd6c5e, 21 lines
--	------------------

FracBinarySearch.h

Description: Given f and N , finds the smallest fraction $p/q \in [0, 1]$ such that $f(p/q)$ is true, and $p, q \leq N$. You may want to throw an exception from f if it finds an exact solution, in which case N can be removed.

$$\approx \int_m^\infty f(x)dx + \frac{f(m)}{2} - \frac{f'(m)}{12} + \frac{f'''(m)}{720} + O(f^{(5)}(m))$$

6.3.2 Stirling numbers of the first kind

Number of permutations on n items with k cycles.

$$c(n,k) = c(n-1,k-1) + (n-1)c(n-1,k), \; c(0,0) = 1$$
$$\sum_{k=0}^n c(n,k)x^k = x(x+1)\dots(x+n-1)$$

$$c(8,k) = 8, 0, 5040, 13068, 13132, 6769, 1960, 322, 28, 1$$
$$c(n,2) = 0, 0, 1, 3, 11, 50, 274, 1764, 13068, 109584, \dots$$

6.3.3 Eulerian numbers

Number of permutations $\pi \in S_n$ in which exactly k elements are greater than the previous element. k j :s s.t. $\pi(j) > \pi(j+1)$, $k+1$ j :s s.t. $\pi(j) \geq j$, k j :s s.t. $\pi(j) > j$.

$$E(n,k) = (n-k)E(n-1,k-1) + (k+1)E(n-1,k)$$
$$E(n,0) = E(n,n-1) = 1$$

$$E(n,k) = \sum_{j=0}^k (-1)^j \binom{n+1}{j} (k+1-j)^n$$

6.3.4 Stirling numbers of the second kind

Partitions of n distinct elements into exactly k groups.

$$S(n,k) = S(n-1,k-1) + kS(n-1,k)$$
$$S(n,1) = S(n,n) = 1$$
$$S(n,k) = \frac{1}{k!} \sum_{j=0}^k (-1)^{k-j} \binom{k}{j} j^n$$

6.3.5 Bell numbers

Total number of partitions of n distinct elements. $B(n) = 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, \dots$. For p prime,

$$B(p^m + n) \equiv mB(n) + B(n+1) \pmod{p}$$

6.3.6 Labeled unrooted trees

on n vertices: n^{n-2}
on k existing trees of size n_i : $n_1n_2\cdots n_kn^{k-2}$
with degrees d_i : $(n-2)!/((d_1-1)!\cdots(d_n-1)!)$

6.3.7 Catalan numbers

$$C_n = \frac{1}{n+1} \binom{2n}{n} = \binom{2n}{n} - \binom{2n}{n+1} = \frac{(2n)!}{(n+1)!n!}$$
$$C_0 = 1, \; C_{n+1} = \frac{2(2n+1)}{n+2}C_n, \; C_{n+1} = \sum C_iC_{n-i}$$
$$C_n = 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, \dots$$

- sub-diagonal monotone paths in an $n \times n$ grid.

- strings with n pairs of parenthesis, correctly nested.
- binary trees with with $n+1$ leaves (0 or 2 children).
- ordered trees with $n+1$ vertices.
- ways a convex polygon with $n+2$ sides can be cut into triangles by connecting vertices with straight lines.
- permutations of $[n]$ with no 3-term increasing subseq.

Graphs (7)

7.1 Fundamentals

BellmanFord.h
Description: Calculates shortest paths from s in a graph that might have negative edge weights. Unreachable nodes get dist = inf; nodes reachable through negative-weight cycles get dist = -inf. Assumes $V^2 \max |w_i| < \sim 2^{63}$.
Time: $\mathcal{O}(VE)$

```
const ll inf = LLONG_MAX;
struct Ed { int a, b, w, s() { return a < b ? a : -a; } };
struct Node { ll dist = inf; int prev = -1; };

void bellmanFord(vector<Node>& nodes, vector<Ed>& eds, int s) {
    nodes[s].dist = 0;
    sort(all(eds), [](Ed a, Ed b) { return a.s() < b.s(); });

    int lim = sz(nodes) / 2 + 2; // /3+100 with shuffled vertices
    rep(i,0,lim) for (Ed ed : eds) {
        Node cur = nodes[ed.a], &dest = nodes[ed.b];
        if (abs(cur.dist) == inf) continue;
        ll d = cur.dist + ed.w;
        if (d < dest.dist) {
            dest.prev = ed.a;
            dest.dist = (i < lim-1 ? d : -inf);
        }
    }
    rep(i,0,lim) for (Ed e : eds) {
        if (nodes[e.a].dist == -inf)
            nodes[e.b].dist = -inf;
    }
}
```

FloydWarshall.h
Description: Calculates all-pairs shortest path in a directed graph that might have negative edge weights. Input is an distance matrix m , where $m[i][j] = \text{inf}$ if i and j are not adjacent. As output, $m[i][j]$ is set to the shortest distance between i and j , inf if no path, or -inf if the path goes through a negative-weight cycle.
Time: $\mathcal{O}(N^3)$

```
const ll inf = 1LL << 62;
void floydWarshall(vector<vector<ll>>& m) {
    int n = sz(m);
    rep(i,0,n) m[i][i] = min(m[i][i], 0LL);
    rep(k,0,n) rep(i,0,n) rep(j,0,n)
        if (m[i][k] != inf && m[k][j] != inf) {
            auto newDist = max(m[i][k] + m[k][j], -inf);
            m[i][j] = min(m[i][j], newDist);
        }
    rep(k,0,n) if (m[k][k] < 0) rep(i,0,n) rep(j,0,n)
        if (m[i][k] != inf && m[k][j] != inf) m[i][j] = -inf;
}
```

TopoSort.h
Description: Topological sorting. Given is an oriented graph. Output is an ordering of vertices, such that there are edges only from left to right. If there are cycles, the returned list will have size smaller than n – nodes reachable from cycles will not be returned.
Time: $\mathcal{O}(|V| + |E|)$

```
vi topoSort(const vector<vi>& gr) {
    vi indeg(sz(gr)), q;
    for (auto& li : gr) for (int x : li) indeg[x]++;
    rep(i,0,sz(gr)) if (indeg[i] == 0) q.push_back(i);
    rep(j,0,sz(q)) for (int x : gr[q[j]])
        if (--indeg[x] == 0) q.push_back(x);
    return q;
}
```

7.2 Network flow

PushRelabel.h
Description: Push-relabel using the highest label selection rule and the gap heuristic. Quite fast in practice. To obtain the actual flow, look at positive values only.
Time: $\mathcal{O}(V^2\sqrt{E})$

```
struct PushRelabel {
    struct Edge {
        int dest, back;
        ll f, c;
    };
    vector<vector<Edge>> g;
    vector<ll> ec;
    vector<Edge*> cur;
    vector<vi> hs; vi H;
    PushRelabel(int n) : g(n), ec(n), cur(n), hs(2*n), H(n) {}

    void addEdge(int s, int t, ll cap, ll rcap=0) {
        if (s == t) return;
        g[s].push_back({t, sz(g[t]), 0, cap});
        g[t].push_back({s, sz(g[s])-1, 0, rcap});
    }

    void addFlow(Edge& e, ll f) {
        Edge &back = g[e.dest][e.back];
        if (!ec[e.dest] && f) hs[H[e.dest]].push_back(e.dest);
        e.f += f; e.c -= f; ec[e.dest] += f;
        back.f -= f; back.c += f; ec[back.dest] -= f;
    }

    ll calc(int s, int t) {
        int v = sz(g); H[s] = v; ec[t] = 1;
        vi co(2*v); co[0] = v-1;
        rep(i,0,v) cur[i] = g[i].data();
        for (Edge& e : g[s]) addFlow(e, e.c);

        for (int hi = 0;;) {
            while (hs[hi].empty()) if (!hi--) return -ec[s];
            int u = hs[hi].back(); hs[hi].pop_back();
            while (ec[u] > 0) // discharge u
                if (cur[u] == g[u].data() + sz(g[u])) {
                    H[u] = 1e9;
                    for (Edge& e : g[u]) if (e.c && H[u] > H[e.dest]+1)
                        H[u] = H[e.dest]+1, cur[u] = &e;
                    if (++co[H[u]], !--co[hi] && hi < v)
                        rep(i,0,v) if (hi < H[i] && H[i] < v)
                            --co[H[i]], H[i] = v + 1;
                    hi = H[u];
                } else if (cur[u]->c && H[u] == H[cur[u]->dest]+1)
                    addFlow(*cur[u], min(ec[u], cur[u]->c));
                else ++cur[u];
        }
    }
}
```

```
bool leftOfMinCut(int a) { return H[a] >= sz(g); }
};
```

Dinic.h
Description: Flow algorithm with complexity $O(VE \log U)$ where $U = \max |cap|$. $O(\min(E^{1/2}, V^{2/3})E)$ if $U = 1$; $O(\sqrt{V}E)$ for bipartite matching.

d7f0f1, 42 lines

```
struct Dinic {
    struct Edge {
        int to, rev;
        ll c, oc;
        ll flow() { return max(oc - c, 0LL); } // if you need flows
    };
    vi lvl, ptr, q;
    vector<vector<Edge>> adj;
    Dinic(int n) : lvl(n), ptr(n), q(n), adj(n) {}
    void addEdge(int a, int b, ll c, ll rcap = 0) {
        adj[a].push_back({b, sz(adj[b]), c, c});
        adj[b].push_back({a, sz(adj[a]) - 1, rcap, rcap});
    }
    ll dfs(int v, int t, ll f) {
        if (v == t || !f) return f;
        for (int& i = ptr[v]; i < sz(adj[v]); i++) {
            Edge& e = adj[v][i];
            if (lvl[e.to] == lvl[v] + 1)
                if (ll p = dfs(e.to, t, min(f, e.c))) {
                    e.c -= p, adj[e.to][e.rev].c += p;
                    return p;
                }
        }
        return 0;
    }
    ll calc(int s, int t) {
        ll flow = 0; q[0] = s;
        rep(L,0,31) do { // 'int L=30' maybe faster for random data
            lvl = ptr = vi(sz(q));
            int qi = 0, qe = lvl[s] = 1;
            while (qi < qe && !lvl[t]) {
                int v = q[qi++];
                for (Edge e : adj[v])
                    if (!lvl[e.to] && e.c >> (30 - L))
                        q[qe++] = e.to, lvl[e.to] = lvl[v] + 1;
            }
            while (lvl p = dfs(s, t, LLONG_MAX)) flow += p;
        } while (lvl[t]);
        return flow;
    }
    bool leftOfMinCut(int a) { return lvl[a] != 0; }
};
```

MinCostMaxFlow.h
Description: Min-cost max-flow. Negative cost cycles not supported. To obtain the actual flow, look at positive values only.
Time: Approximately $\mathcal{O}(E^2)$, actually $\mathcal{O}(FS)$ where S is the time complexity of the SSSP alg used in find path (in this case SPFA)

27fafb, 55 lines

```
struct mcmf {
    const ll inf = LLONG_MAX >> 2;
    struct edge {
        int v;
        ll cap, flow, cost;
    };
    int n;
    vector<edge> edges;
    vvi adj; vvi par; vi in_q;
    vector<ll> dist, pi;
    mcmf(int n): n(n), adj(n), par(n), in_q(n), dist(n), pi(n) {}
    void add_edge(int u, int v, ll cap, ll cost) {
```

```
int idx = sz(edges);
edges.push_back({v, cap, 0, cost});
edges.push_back({u, cap, cap, -cost});
adj[u].push_back(idx);
adj[v].push_back(idx ^ 1);
}
bool find_path(int s, int t) {
    fill(all(dist), inf);
    fill(all(in_q), 0);
    queue<int> q; q.push(s);
    dist[s] = 0, in_q[s] = 1;
    while(!q.empty()) {
        int cur = q.front(); q.pop();
        in_q[cur] = 0;
        for(int idx: adj[cur]) {
            auto [nxt, cap, fl, wt] = edges[idx];
            ll nxtD = dist[cur] + wt;
            if(fl >= cap || nxtD >= dist[nxt]) continue;
            dist[nxt] = nxtD;
            par[nxt] = {cur, idx};
            if(in_q[nxt]) continue;
            q.push(nxt); in_q[nxt] = 1;
        }
    }
    return dist[t] < inf;
}
pair<ll, ll> calc(int s, int t) {
    ll flow = 0, cost = 0;
    while(find_path(s, t)) {
        ll f = inf;
        for(int i, u, v = t; tie(u, i) = par[v], v != s; v = u)
            f = min(f, edges[i].cap - edges[i].flow);
        flow += f;
        for(int i, u, v = t; tie(u, i) = par[v], v != s; v = u)
            edges[i].flow += f, edges[i^1].flow -= f;
    }
    rep(i, 0, sz(edges)>>1)
        cost += edges[i<<1].cost * edges[i<<1].flow;
    return {flow, cost};
}
};
```

MCMFdijkstra.h
Description: If SPFA TLEs, swap the find_path function in MCMF with the one below and in_q with seen. If negative edge weights can occur, initialize pi with the shortest path from the source to each node using Bellman-Ford. Negative weight cycles not supported.

7aec8f, 24 lines

```
bool find_path(int s, int t) {
    fill(all(dist), inf);
    fill(all(seen), 0);
    dist[s] = 0;
    __gnu_pbds::priority_queue<pair<ll, int>> pq;
    vector<decltype(pq)::point_iterator> its(n);
    pq.push({0, s});
    while(!pq.empty()) {
        auto [d, cur] = pq.top(); pq.pop(); d *= -1;
        seen[cur] = 1;
        if(dist[cur] < d) continue;
        for(int idx: adj[cur]) {
            auto [nxt, cap, f, wt] = edges[idx];
            ll nxtD = d + wt + pi[cur] - pi[nxt];
            if(f >= cap || nxtD >= dist[nxt] || seen[nxt]) continue;
            dist[nxt] = nxtD;
            par[nxt] = {cur, idx};
            if(its[nxt] == pq.end()) its[nxt] = pq.push({-nxtD, nxt});
        }
    }
};
```

```
else pq.modify(its[nxt], {-nxtD, nxt});
}
}
rep(i, 0, n) pi[i] = min(pi[i] + dist[i], inf);
return seen[t];
}
```

EdmondsKarp.h
Description: Flow algorithm with guaranteed complexity $O(VE^2)$. To get edge flow values, compare capacities before and after, and take the positive values only.

482fe0, 36 lines

```
template<class T> T edmondsKarp(vector<unordered_map<int, T>>&
    graph, int source, int sink) {
    assert(source != sink);
    T flow = 0;
    vi par(sz(graph)), q = par;

    for (;;) {
        fill(all(par), -1);
        par[source] = 0;
        int ptr = 1;
        q[0] = source;

        rep(i,0,ptr) {
            int x = q[i];
            for (auto e : graph[x]) {
                if (par[e.first] == -1 && e.second > 0) {
                    par[e.first] = x;
                    q[ptr++] = e.first;
                    if (e.first == sink) goto out;
                }
            }
        }
        return flow;
    }
out:
    T inc = numeric_limits<T>::max();
    for (int y = sink; y != source; y = par[y])
        inc = min(inc, graph[par[y]][y]);

    flow += inc;
    for (int y = sink; y != source; y = par[y]) {
        int p = par[y];
        if ((graph[p][y] -= inc) <= 0) graph[p].erase(y);
        graph[y][p] += inc;
    }
}
}
```

MinCut.h
Description: After running max-flow, the left side of a min-cut from s to t is given by all vertices reachable from s , only traversing edges with positive residual capacity.

GlobalMinCut.h
Description: Find a global minimum cut in an undirected graph, as represented by an adjacency matrix.
Time: $\mathcal{O}(V^3)$

8b0e19, 21 lines

```
pair<int, vi> globalMinCut(vector<vi> mat) {
    pair<int, vi> best = {INT_MAX, {}};
    int n = sz(mat);
    vector<vi> co(n);
    rep(i,0,n) co[i] = {i};
    rep(ph,1,n) {
        vi w = mat[0];
        size_t s = 0, t = 0;
        rep(it,0,n-ph) { //  $O(V^2) \rightarrow O(E \log V)$  with prio. queue
```

```
w[t] = INT_MIN;
s = t, t = max_element(all(w)) - w.begin();
rep(i,0,n) w[i] += mat[t][i];
}
best = min(best, {w[t] - mat[t][t], co[t]});
co[s].insert(co[s].end(), all(co[t]));
rep(i,0,n) mat[s][i] += mat[t][i];
rep(i,0,n) mat[i][s] = mat[s][i];
mat[0][t] = INT_MIN;
}
return best;
}
```

GomoryHu.h
Description: Given a list of edges representing an undirected flow graph, returns edges of the Gomory-Hu tree. The max flow between any pair of vertices is given by minimum edge weight along the Gomory-Hu tree path.
Time: $\mathcal{O}(V)$ Flow Computations

"PushRelabel.h"	0418b3, 13 lines
-----------------	------------------

```
typedef array<ll, 3> Edge;
vector<Edge> gomoryHu(int N, vector<Edge> ed) {
    vector<Edge> tree;
    vi par(N);
    rep(i,1,N) {
        PushRelabel D(N); // Dinic also works
        for (Edge t : ed) D.addEdge(t[0], t[1], t[2], t[2]);
        tree.push_back({i, par[i], D.calc(i, par[i])});
        rep(j,i+1,N)
            if (par[j] == par[i] && D.leftOfMinCut(j)) par[j] = i;
    }
    return tree;
}
```

MatroidIntersection.h
Description: Given two matroids, finds the largest common independent set. For the color and graph matroids, this would be the largest forest where no two edges are the same color. A matroid has 3 functions
- check(int x): returns if current matroid can add x without becoming dependent
- add(int x): adds an element to the matroid (guaranteed to never make it dependent)
- clear(): sets the matroid to the empty matroid
The matroid is given an int representing the element, and is expected to convert it (e.g: the color or the endpoints) Pass the matroid with more expensive add/clear operations to M1.
Time: $R^2N(M2.add + M1.check + M2.check) + R^3M1.add + R^2M1.clear + RM2.clear$

"../data-structures/UnionFind.h"	9812a7, 60 lines
----------------------------------	------------------

```
struct ColorMat {
    vi cnt, clr;
    ColorMat(int n, vector<int> clr) : cnt(n), clr(clr) {}
    bool check(int x) { return !cnt[clr[x]]; }
    void add(int x) { cnt[clr[x]]++; }
    void clear() { fill(all(cnt), 0); }
};
struct GraphMat {
    UF uf;
    vector<array<int, 2>> e;
    GraphMat(int n, vector<array<int, 2>> e) : uf(n), e(e) {}
    bool check(int x) { return !uf.sameSet(e[x][0], e[x][1]); }
    void add(int x) { uf.join(e[x][0], e[x][1]); }
    void clear() { uf = UF(sz(uf.e)); }
};
template <class M1, class M2> struct MatroidIsect {
    int n;
    vector<char> iset;
    M1 m1; M2 m2;
```

```
MatroidIsect(M1 m1, M2 m2, int n) : n(n), iset(n + 1), m1(m1)
    , m2(m2) {}
vi solve() {
    rep(i,0,n) if (m1.check(i) && m2.check(i))
        iset[i] = true, m1.add(i), m2.add(i);
    while (augment());
    vi ans;
    rep(i,0,n) if (iset[i]) ans.push_back(i);
    return ans;
}
bool augment() {
    vector<int> frm(n, -1);
    queue<int> q({n}); // starts at dummy node
    auto fwdE = [&](int a) {
        vi ans;
        m1.clear();
        rep(v, 0, n) if (iset[v] && v != a) m1.add(v);
        rep(b, 0, n) if (!iset[b] && frm[b] == -1 && m1.check(b))
            ans.push_back(b), frm[b] = a;
        return ans;
    };
    auto backE = [&](int b) {
        m2.clear();
        rep(cas, 0, 2) rep(v, 0, n)
            if ((v == b || iset[v]) && (frm[v] == -1) == cas) {
                if (!m2.check(v))
                    return cas ? q.push(v), frm[v] = b, v : -1;
                m2.add(v);
            }
        return n;
    };
    while (!q.empty()) {
        int a = q.front(), c; q.pop();
        for (int b : fwdE(a))
            while((c = backE(b)) >= 0) if (c == n) {
                while (b != n) iset[b] ^= 1, b = frm[b];
                return true;
            }
    }
    return false;
}
};
```

7.3 Matching

hopcroftKarp.h
Description: Fast bipartite matching algorithm. Graph g should be a list of neighbors of the left partition, and $btoa$ should be a vector full of -1's of the same size as the right partition. Returns the size of the matching. $btoa[i]$ will be the match for vertex i on the right side, or -1 if it's not matched.
Usage: vi btoa(m, -1); hopcroftKarp(g, btoa);
Time: $\mathcal{O}(\sqrt{VE})$

f612e4, 41 lines

```
bool dfs(int a, int L, vector<vi>& g, vi& btoa, vi& A, vi& B) {
    if (A[a] != L) return 0;
    A[a] = -1;
    for (int b : g[a]) if (B[b] == L + 1) {
        B[b] = 0;
        if (btoa[b] == -1 || dfs(btoa[b], L + 1, g, btoa, A, B))
            return btoa[b] = a, 1;
    }
    return 0;
}
int hopcroftKarp(vector<vi>& g, vi& btoa) {
    int res = 0;
    vi A(g.size()), B(btoa.size()), cur, next;
    for (;;) {
        fill(all(A), 0);
        fill(all(B), 0);
```

```
cur.clear();
for (int a : btoa) if(a != -1) A[a] = -1;
rep(a,0,sz(g)) if(A[a] == 0) cur.push_back(a);
for (int lay = 1;; lay++) {
    bool islast = 0;
    next.clear();
    for (int a : cur) for (int b : g[a]) {
        if (btoa[b] == -1) {
            B[b] = lay;
            islast = 1;
        }
        else if (btoa[b] != a && !B[b]) {
            B[b] = lay;
            next.push_back(btoa[b]);
        }
    }
    if (islast) break;
    if (next.empty()) return res;
    for (int a : next) A[a] = lay;
    cur.swap(next);
}
rep(a,0,sz(g))
    res += dfs(a, 0, g, btoa, A, B);
}
```

DFSMatching.h
Description: Maximum bipartite matching algorithm. Graph g should be a list of neighbors of the left partition, and $btoa$ should be a vector full of -1's of the same size as the right partition. Returns the size of the matching. $btoa[i]$ will be the match for vertex i on the right side, or -1 if it's not matched.
Usage: vi btoa(m, -1); dfsMatching(g, btoa);
Time: $\mathcal{O}(VE)$

522b98, 20 lines

```
bool find(int j, vector<vi>& g, vi& btoa, vi& vis) {
    if (btoa[j] == -1) return 1;
    vis[j] = 1; int di = btoa[j];
    for (int e : g[di])
        if (!vis[e] && find(e, g, btoa, vis)) {
            btoa[e] = di; return 1;
        }
    return 0;
}
int dfsMatching(vector<vi>& g, vi& btoa) {
    vi vis;
    rep(i,0,sz(g)) {
        vis.assign(sz(btoa), 0);
        for (int j : g[i])
            if (find(j, g, btoa, vis)) {
                btoa[j] = i; break;
            }
    }
    return sz(btoa) - (int)count(all(btoa), -1);
}
```

MinimumVertexCover.h
Description: Finds a minimum vertex cover in a bipartite graph. The size is the same as the size of a maximum matching, and the complement is a maximum independent set.

da4196, 20 lines

```
vi cover(vector<vi>& g, int n, int m) {
    vi match(m, -1);
    int res = dfsMatching(g, match);
    vector<bool> lfound(n, true), seen(m);
    for (int it : match) if (it != -1) lfound[it] = false;
    vi q, cover;
    rep(i,0,n) if (lfound[i]) q.push_back(i);
    while (!q.empty()) {
```



```
int i = q.back(); q.pop_back();
lfound[i] = 1;
for (int e : g[i]) if (!seen[e] && match[e] != -1) {
    seen[e] = true;
    q.push_back(match[e]);
}
}
rep(i,0,n) if (!lfound[i]) cover.push_back(i);
rep(i,0,m) if (seen[i]) cover.push_back(n+i);
assert(sz(cover) == res);
return cover;
}
```

WeightedMatching.h

Description: Given a weighted bipartite graph, matches every node on the left with a node on the right such that no nodes are in two matchings and the sum of the edge weights is minimal. Takes cost[N][M], where cost[i][j] = cost for L[i] to be matched with R[j] and returns (min cost, match), where L[i] is matched with R[match[i]]. Negate costs for max cost. Requires $N \leq M$.
Time: $\mathcal{O}(N^2M)$

```
pair<int, vi> hungarian(const vector<vi> &a) {
    if (a.empty()) return {0, {}};
    int n = sz(a) + 1, m = sz(a[0]) + 1;
    vi u(n), v(m), p(m), ans(n - 1);
    rep(i,1,n) {
        p[0] = i;
        int j0 = 0; // add "dummy" worker 0
        vi dist(m, INT_MAX), pre(m, -1);
        vector<bool> done(m + 1);
        do { // dijkstra
            done[j0] = true;
            int i0 = p[j0], j1, delta = INT_MAX;
            rep(j,1,m) if (!done[j]) {
                auto cur = a[i0 - 1][j - 1] - u[i0] - v[j];
                if (cur < dist[j]) dist[j] = cur, pre[j] = j0;
                if (dist[j] < delta) delta = dist[j], j1 = j;
            }
            rep(j,0,m) {
                if (done[j]) u[p[j]] += delta, v[j] -= delta;
                else dist[j] -= delta;
            }
            j0 = j1;
        } while (p[j0]);
        while (j0) { // update alternating path
            int j1 = pre[j0];
            p[j0] = p[j1], j0 = j1;
        }
    }
    rep(j,1,m) if (p[j]) ans[p[j] - 1] = j - 1;
    return {-v[0], ans}; // min cost
}
```

GeneralMatching.h

Description: Matching for general graphs. Fails with probability N/mod .
Time: $\mathcal{O}(N^3)$

```
vector<pii> generalMatching(int N, vector<pii>& ed) {
    vector<vector<ll>> mat(N, vector<ll>(N)), A;
    for (pii pa : ed) {
        int a = pa.first, b = pa.second, r = rand() % mod;
        mat[a][b] = r, mat[b][a] = (mod - r) % mod;
    }

    int r = matInv(A = mat), M = 2*N - r, fi, fj;
    assert(r % 2 == 0);

    if (M != N) do {
        mat.resize(M, vector<ll>(M));
    }
```

```
rep(i,0,N) {
    mat[i].resize(M);
    rep(j,N,M) {
        int r = rand() % mod;
        mat[i][j] = r, mat[j][i] = (mod - r) % mod;
    }
} while (matInv(A = mat) != M);

vi has(M, 1); vector<pii> ret;
rep(it,0,M/2) {
    rep(i,0,M) if (has[i])
        rep(j,i+1,M) if (A[i][j] && mat[i][j]) {
            fi = i; fj = j; goto done;
        } assert(0); done:
    if (fj < N) ret.emplace_back(fi, fj);
    has[fi] = has[fj] = 0;
    rep(sw,0,2) {
        ll a = modpow(A[fi][fj], mod-2);
        rep(i,0,M) if (has[i] && A[i][fj]) {
            ll b = A[i][fj] * a % mod;
            rep(j,0,M) A[i][j] = (A[i][j] - A[fi][j] * b) % mod;
        }
        swap(fi,fj);
    }
} return ret;
}
```

7.4 DFS algorithms

SCC.h

Description: Finds strongly connected components in a directed graph. If vertices u, v belong to the same component, we can reach u from v and vice versa.
Usage: scc(graph, [&](vi& v) { ... }) visits all components in reverse topological order. comp[i] holds the component index of a node (a component only has edges to components with lower index). ncomps will contain the number of components.
Time: $\mathcal{O}(E + V)$

```
vi val, comp, z, cont;
int Time, ncomps;
template<class G, class F> int dfs(int j, G& g, F& f) {
    int low = val[j] = ++Time, x; z.push_back(j);
    for (auto e : g[j]) if (comp[e] < 0)
        low = min(low, val[e] ?: dfs(e,g,f));

    if (low == val[j]) {
        do {
            x = z.back(); z.pop_back();
            comp[x] = ncomps;
            cont.push_back(x);
        } while (x != j);
        f(cont); cont.clear();
        ncomps++;
    }
    return val[j] = low;
}
template<class G, class F> void scc(G& g, F f) {
    int n = sz(g);
    val.assign(n, 0); comp.assign(n, -1);
    Time = ncomps = 0;
    rep(i,0,n) if (comp[i] < 0) dfs(i, g, f);
}
```

BCCs.h

Description: Finds all biconnected components in an undirected graph, and runs a callback for the edges in each. In a biconnected component there are at least two distinct paths between any two nodes. Note that a node can be in several components. An edge which is not in a component is a bridge, i.e., not part of any cycle.
Usage: int eid = 0; ed.resize(N); for each edge (a,b) { ed[a].emplace_back(b, eid); ed[b].emplace_back(a, eid++); } bicomps([&](const vi& edgelist) {...});
Time: $\mathcal{O}(E + V)$

```
vi num, st;
vector<vector<pii>> ed;
int Time;
template<class F>
int dfs(int at, int par, F& f) {
    int me = num[at] = ++Time, top = me;
    for (auto [y, e] : ed[at]) if (e != par) {
        if (num[y]) {
            top = min(top, num[y]);
            if (num[y] < me)
                st.push_back(e);
        } else {
            int si = sz(st);
            int up = dfs(y, e, f);
            top = min(top, up);
            if (up == me) {
                st.push_back(e);
                f(vi(st.begin() + si, st.end()));
                st.resize(si);
            }
        }
        else if (up < me) st.push_back(e);
        else { /* e is a bridge */ }
    }
} return top;
}
```

```
template<class F>
void bicomps(F f) {
    num.assign(sz(ed), 0);
    rep(i,0,sz(ed)) if (!num[i]) dfs(i, -1, f);
}
```

ArticulationPoints.h

Description: Finds the articulation points in a graph
Time: $\mathcal{O}(N + M)$

```
int n;
vector<vector<int>> adj;
vector<bool> visited;
vector<int> tin, low;
int timer;
void dfs(int v, int p = -1) {
    visited[v] = true;
    tin[v] = low[v] = timer++;
    int children = 0;
    for (int to : adj[v]) {
        if (to == p) continue;
        if (visited[to]) {
            low[v] = min(low[v], tin[to]);
        } else {
            dfs(to, v);
            low[v] = min(low[v], low[to]);
            if (low[to] >= tin[v] && p!=-1)
                // V IS A CUTPOINT;
            ++children;
        }
    }
```

```
    }
    if(p == -1 && children > 1) // V IS A CUTPOINT;
}
void findAP() {
    timer = 0;
    visited.assign(n, false);
    tin.assign(n, -1);
    low.assign(n, -1);
    for (int i = 0; i < n; ++i)
        if (!visited[i]) dfs (i);
}
```

2sat.h

Description: Calculates a valid assignment to boolean variables a, b, c,... to a 2-SAT problem, so that an expression of the type $(a||b)&\&(a||c)&\&(d||b)&\&...$ becomes true, or reports that it is unsatisfiable. Negated variables are represented by bit-inversions (~x).

Usage: TwoSat ts(number of boolean variables);
ts.either(0, ~3); // Var 0 is true or var 3 is false
ts.setValue(2); // Var 2 is true
ts.atMostOne({0,~1,2}); // <= 1 of vars 0, ~1 and 2 are true
ts.solve(); // Returns true iff it is solvable
ts.values[0..N-1] holds the assigned values to the vars

Time: $\mathcal{O}(N + E)$, where N is the number of boolean variables, and E is the number of clauses.

5f9706, 50 lines

```
struct TwoSat {
    int N;
    vector<vi> gr;
    vi values; // 0 = false, 1 = true
    TwoSat(int n = 0) : N(n), gr(2*n) {}
    int addVar() { // (optional)
        gr.emplace_back();
        gr.emplace_back();
        return N++;
    }
    void either(int f, int j) {
        f = max(2*f, -1-2*f);
        j = max(2*j, -1-2*j);
        gr[f].push_back(j^1);
        gr[j].push_back(f^1);
    }
    void setValue(int x) { either(x, x); }
    void atMostOne(const vi& li) { // (optional)
        if (sz(li) <= 1) return;
        int cur = ~li[0];
        rep(i,2,sz(li)) {
            int next = addVar();
            either(cur, ~li[i]);
            either(cur, next);
            either(~li[i], next);
            cur = ~next;
        }
        either(cur, ~li[1]);
    }
}
vi val, comp, z; int time = 0;
int dfs(int i) {
    int low = val[i] = ++time, x; z.push_back(i);
    for(int e : gr[i]) if (!comp[e])
        low = min(low, val[e] ? : dfs(e));
    if (low == val[i]) do {
        x = z.back(); z.pop_back();
        comp[x] = low;
        if (values[x>>1] == -1)
            values[x>>1] = x&1;
    } while (x != i);
    return val[i] = low;
}
bool solve() {
```

```
    values.assign(N, -1);
    val.assign(2*N, 0); comp = val;
    rep(i,0,2*N) if (!comp[i]) dfs(i);
    rep(i,0,N) if (comp[2*i] == comp[2*i+1]) return 0;
    return 1;
}
};
```

EulerWalk.h

Description: Eulerian undirected/directed path/cycle algorithm. (visits every edge once) Input should be a vector of (dest, global edge index), where for undirected graphs, forward/backward edges have the same index. Returns a list of nodes in the Eulerian path/cycle with src at both start and end, or empty list if no cycle/path exists. To get edge indices back, add .second to s and ret.

Time: $\mathcal{O}(V + E)$

a07095, 15 lines

```
vi eulerWalk(vector<vector<pii>>& gr, int nEdges, int src) {
    int n = sz(gr);
    vi D(n), its(n), eu(nEdges), ret, s = {src};
    D[src]++; // to allow Euler paths, not just cycles
    while (!s.empty()) {
        int x = s.back(), y, e, &it = its[x], end = sz(gr[x]);
        if (it == end){ ret.push_back(x); s.pop_back(); continue; }
        tie(y, e) = gr[x][it++];
        if (!eu[e]) {
            D[x]--, D[y]++;
            eu[e] = 1; s.push_back(y);
        }
    }
    for (int x : D) if (x < 0 || sz(ret) != nEdges+1) return {};
    return {ret.rbegin(), ret.rend()};
}
```

DominatorTree.h

Description: Builds a dominator tree on a directed graph. Output tree is a parent array with src as the root.

Time: $\mathcal{O}(V + E)$

1d35d2, 46 lines

```
vi getDomTree(vvi &adj, int src) {
    int n = sz(adj), t = 0;
    vvi revAdj(n), child(n), sdomChild(n);
    vi label(n, -1), revLabel(n), sdom(n), idom(n), par(n), best(n);

    auto dfs = [&](int cur, auto &dfs) -> void {
        label[cur] = t, revLabel[t] = cur;
        sdom[t] = par[t] = best[t] = t; t++;
        for(int nxt: adj[cur]) {
            if(label[nxt] == -1) {
                dfs(nxt, dfs);
                child[label[cur]].push_back(label[nxt]);
            }
            revAdj[label[nxt]].push_back(label[cur]);
        }
    };
    dfs(src, dfs);

    auto get = [&](int x, auto &get) -> int {
        if(par[x] != x) {
            int t = get(par[x], get);
            par[x] = par[par[x]];
            if(sdom[t] < sdom[best[x]]) best[x] = t;
        }
        return best[x];
    };

    for(int i = t-1; i >= 0; i--) {
        for(int j: revAdj[i]) sdom[i] = min(sdom[i], sdom[get(j, get)]);
    }
```

```
    if(i > 0) sdomChild[sdom[i]].push_back(i);
    for(int j: sdomChild[i]) {
        int k = get(j, get);
        if(sdom[j] == sdom[k]) idom[j] = sdom[j];
        else idom[j] = k;
    }
    for(int j: child[i]) par[j] = i;
}

vi dom(n);
rep(i, 1, t) {
    if(idom[i] != sdom[i]) idom[i] = idom[idom[i]];
    dom[revLabel[i]] = revLabel[idom[i]];
}

return dom;
}
```

7.5 Coloring

EdgeColoring.h

Description: Given a simple, undirected graph with max degree D , computes a $(D + 1)$ -coloring of the edges such that no neighboring edges share a color. (D -coloring is NP-hard, but can be done for bipartite graphs by repeated matchings of max-degree nodes.)

Time: $\mathcal{O}(NM)$

e210e2, 31 lines

```
vi edgeColoring(int N, vector<pii> eds) {
    vi cc(N + 1), ret(sz(eds)), fan(N), free(N), loc;
    for (pii e : eds) ++cc[e.first], ++cc[e.second];
    int u, v, ncols = *max_element(all(cc)) + 1;
    vector<vi> adj(N, vi(ncols, -1));
    for (pii e : eds) {
        tie(u, v) = e;
        fan[0] = v;
        loc.assign(ncols, 0);
        int at = u, end = u, d, c = free[u], ind = 0, i = 0;
        while (d = free[v], !loc[d] && (v = adj[u][d]) != -1)
            loc[d] = ++ind, cc[ind] = d, fan[ind] = v;
        cc[loc[d]] = c;
        for (int cd = d; at != -1; cd ^= c ^ d, at = adj[at][cd])
            swap(adj[at][cd], adj[end = at][cd ^ c ^ d]);
        while (adj[fan[i]][d] != -1) {
            int left = fan[i], right = fan[++i], e = cc[i];
            adj[u][e] = left;
            adj[left][e] = u;
            adj[right][e] = -1;
            free[right] = e;
        }
        adj[u][d] = fan[i];
        adj[fan[i]][d] = u;
        for (int y : {fan[0], u, end})
            for (int& z = free[y] = 0; adj[y][z] != -1; z++);
    }
    rep(i,0,sz(eds))
        for (tie(u, v) = eds[i]; adj[u][ret[i]] != v;) ++ret[i];
    return ret;
}
```

7.6 Heuristics

MaximalCliques.h

Description: Runs a callback for all maximal cliques in a graph (given as a symmetric bitset matrix; self-edges not allowed). Callback is given a bitset representing the maximal clique.

Time: $\mathcal{O}\left(3^{n/3}\right)$, much faster for sparse graphs

b0d5b1, 12 lines

```
typedef bitset<128> B;
template<class F>
void cliques(vector<B>& eds, F f, B P = ~B(), B X={}, B R={}) {
```

```
    if (!P.any()) { if (!X.any()) f(R); return; }
    auto q = (P | X)._Find_first();
    auto cand = P & ~eds[q];
    rep(i,0,sz(eds)) if (cand[i]) {
        R[i] = 1;
        cliques(eds, f, P & eds[i], X & eds[i], R);
        R[i] = P[i] = 0; X[i] = 1;
    }
}
```

MaximumClique.h

Description: Quickly finds a maximum clique of a graph (given as symmetric bitset matrix; self-edges not allowed). Can be used to find a maximum independent set by finding a clique of the complement graph.
Time: Runs in about 1s for n=155 and worst case random graphs (p=.90). Runs faster for sparse graphs.

```
typedef vector<bitset<200>> vb;
struct Maxclique {
    double limit=0.025, pk=0;
    struct Vertex { int i, d=0; };
    typedef vector<Vertex> vv;
    vb e;
    vv V;
    vector<vi> C;
    vi qmax, q, S, old;
    void init(vv& r) {
        for (auto& v : r) v.d = 0;
        for (auto& v : r) for (auto j : r) v.d += e[v.i][j.i];
        sort(all(r), [](auto a, auto b) { return a.d > b.d; });
        int mxD = r[0].d;
        rep(i,0,sz(r)) r[i].d = min(i, mxD) + 1;
    }
    void expand(vv& R, int lev = 1) {
        S[lev] += S[lev - 1] - old[lev];
        old[lev] = S[lev - 1];
        while (sz(R)) {
            if (sz(q) + R.back().d <= sz(qmax)) return;
            q.push_back(R.back().i);
            vv T;
            for(auto v:R) if (e[R.back().i][v.i]) T.push_back({v.i});
            if (sz(T)) {
                if (S[lev]++ / ++pk < limit) init(T);
                int j = 0, mxk = 1, mnk = max(sz(qmax) - sz(q) + 1, 1);
                C[1].clear(), C[2].clear();
                for (auto v : T) {
                    int k = 1;
                    auto f = [&](int i) { return e[v.i][i]; };
                    while (any_of(all(C[k]), f)) k++;
                    if (k > mxk) mxk = k, C[mxk + 1].clear();
                    if (k < mnk) T[j++].i = v.i;
                    C[k].push_back(v.i);
                }
                if (j > 0) T[j - 1].d = 0;
                rep(k,mn,mxk + 1) for (int i : C[k])
                    T[j].i = i, T[j++].d = k;
                expand(T, lev + 1);
            } else if (sz(q) > sz(qmax)) qmax = q;
            q.pop_back(), R.pop_back();
        }
    }
    vi maxClique() { init(V), expand(V); return qmax; }
    Maxclique(vb conn) : e(conn), C(sz(e)+1), S(sz(C)), old(S) {
        rep(i,0,sz(e)) V.push_back({i});
    }
};
```

f7c0bc, 49 lines

MaximumIndependentSet.h

Description: To obtain a maximum independent set of a graph, find a max clique of the complement. If the graph is bipartite, see MinimumVertex-Cover.

7.7 Trees

7.7.1 Number of Spanning Trees

Create an $N \times N$ matrix mat , and for each edge $a \rightarrow b \in G$, do $mat[a][b]--$, $mat[b][b]++$ (and $mat[b][a]--$, $mat[a][a]++$ if G is undirected). Remove the i th row and column and take the determinant; this yields the number of directed spanning trees rooted at i (if G is undirected, remove any row/column).

7.7.2 Erdős–Gallai theorem

A simple graph with node degrees $d_1 \geq \dots \geq d_n$ exists iff $d_1 + \dots + d_n$ is even and for every $k = 1 \dots n$,

$$\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k).$$

BinaryLifting.h

Description: Calculate power of two jumps in a tree, to support fast upward jumps and LCAs. Assumes the root node points to itself.
Time: construction $\mathcal{O}(N \log N)$, queries $\mathcal{O}(\log N)$

bfce85, 25 lines

```
vector<vi> treeJump(vi& P){
    int on = 1, d = 1;
    while(on < sz(P)) on *= 2, d++;
    vector<vi> jmp(d, P);
    rep(i,1,d) rep(j,0,sz(P))
        jmp[i][j] = jmp[i-1][jmp[i-1][j]];
    return jmp;
}

int jmp(vector<vi>& tbl, int nod, int steps){
    rep(i,0,sz(tbl))
        if(steps&(1<<i)) nod = tbl[i][nod];
    return nod;
}

int lca(vector<vi>& tbl, vi& depth, int a, int b) {
    if (depth[a] < depth[b]) swap(a, b);
    a = jmp(tbl, a, depth[a] - depth[b]);
    if (a == b) return a;
    for (int i = sz(tbl); i--;) {
        int c = tbl[i][a], d = tbl[i][b];
        if (c != d) a = c, b = d;
    }
    return tbl[0][a];
}

KthPath.h
Description: kth on path, goes in tree.lift
Time: O(log N)
```

080dbc, 9 lines

```
int kth_path(int u, int v, int k) {
    int lca_d = t[lca(u, v)].d;
    int u_lca = t[u].d - lca_d;
    int v_lca = t[v].d - lca_d;
    if (k <= u_lca) return kth_par(u, k);
    if (k <= u_lca + v_lca)
```

```
    return kth_par(v, u_lca + v_lca - k);
    return -1;
}

LCA.h
Description: Data structure for computing lowest common ancestors in a tree (with 0 as root). C should be an adjacency list of the tree, either directed or undirected.
Time: O(N log N + Q)
"./data-structures/RMQ.h"
0f62fb, 21 lines

struct LCA {
    int T = 0;
    vi time, path, ret;
    RMQ<int> rmq;

    LCA(vector<vi>& C) : time(sz(C)), rmq((dfs(C,0,-1), ret)) {}
    void dfs(vector<vi>& C, int v, int par) {
        time[v] = T++;
        for (int y : C[v]) if (y != par) {
            path.push_back(v), ret.push_back(time[v]);
            dfs(C, y, v);
        }
    }

    int lca(int a, int b) {
        if (a == b) return a;
        tie(a, b) = minmax(time[a], time[b]);
        return path[rmq.query(a, b)];
    }
    //dist(a,b){return depth[a] + depth[b] - 2*depth[lca(a,b)];}
};

CompressTree.h
Description: Given a rooted tree and a subset S of nodes, compute the minimal subtree that contains all the nodes by adding all (at most |S| - 1) pairwise LCA's and compressing edges. Returns a list of (par, orig_index) representing a tree rooted at 0. The root points to itself.
Time: O(|S|log|S|)
"LCA.h"
9775a0, 21 lines

typedef vector<pair<int, int>> vpi;
vpi compressTree(LCA& lca, const vi& subset) {
    static vi rev; rev.resize(sz(lca.time));
    vi li = subset, &T = lca.time;
    auto cmp = [&](int a, int b) { return T[a] < T[b]; };
    sort(all(li), cmp);
    int m = sz(li)-1;
    rep(i,0,m) {
        int a = li[i], b = li[i+1];
        li.push_back(lca.lca(a, b));
    }
    sort(all(li), cmp);
    li.erase(unique(all(li)), li.end());
    rep(i,0,sz(li)) rev[li[i]] = i;
    vpi ret = {pii(0, li[0])};
    rep(i,0,sz(li)-1) {
        int a = li[i], b = li[i+1];
        ret.emplace_back(rev[lca.lca(a, b)], b);
    }
    return ret;
}

CentroidDecomp.h
Description: Calls callback function on undirected forest for each centroid
Usage: centroid(adj, [&](const vector<vector<int>>& adj, int cent) { ... });
Time: O(n log n)
```

d2787e, 32 lines

```
template <class F, class G> struct centroid {
```

```

G adj;
F f;
vi sub_sz, par;
centroid(const G& adj, F f)
: adj(adj), f(f), sub_sz(sz(adj), -1), par(sz(adj), -1) {
    rep(i, 0, sz(adj))
        if (sub_sz[i] == -1) dfs(i);
}
void calc_sz(int u, int p) {
    sub_sz[u] = 1;
    for (int v : adj[u])
        if (v != p) calc_sz(v, u), sub_sz[u] += sub_sz[v];
}
int dfs(int u) {
    calc_sz(u, -1);
    for (int p = -1, sz_root = sub_sz[u];) {
        auto big_ch = find_if(all(adj[u]), [&](int v) {
            return v != p && 2 * sub_sz[v] > sz_root;
        });
        if (big_ch == end(adj[u])) break;
        p = u, u = *big_ch;
    }
    f(adj, u);
    for (int v : adj[u]) {
        iter_swap(find(all(adj[v]), u), rbegin(adj[v]));
        adj[v].pop_back();
        par[dfs(v)] = u;
    }
    return u;
}
};

```

EdgeCD.h

Description: Recursively splits a tree into two edge sets that share a centroid. Consider all paths that pass through the centroid and use at least one edge from each set. A node can be a centroid multiple times. Consider all length 1 paths separately. Callback takes the graph, centroid, and split, where edges $[0, split)$ from $adj[centroid]$ are in the first set and the rest are in the second set.

Usage: `edge_cd(adj, [&](const vector<vector<int>>& adj, int cent, int split) { ... });`

Time: $\mathcal{O}(n \log n)$

436f41, 34 lines

```

template <class F> struct edge_cd {
    vvi adj;
    F f;
    vi sub_sz;
    edge_cd(const vvi& adj, F f) : adj(adj), f(f),
        sub_sz(sz(adj)) {
        dfs(0, sz(adj) - 1);
    }
    int find_cent(int u, int p, int siz) {
        sub_sz[u] = 1;
        for (int v : adj[u]) if (v != p) {
            int cent = find_cent(v, u, siz);
            if (cent != -1) return cent;
            sub_sz[u] += sub_sz[v];
        }
        return 2 * sub_sz[u] > siz ?
            p >= 0 && (sub_sz[p] = siz + 1 - sub_sz[u]), u : -1;
    }
    void dfs(int u, int siz) {
        if (siz < 2) return;
        u = find_cent(u, -1, siz);
        int sum = 0;
        auto it = partition(all(adj[u]), [&](int v) {
            ll x = sum + sub_sz[v];
            return x * x < siz * (siz - x) ? sum += sub_sz[v], 1 : 0;
        });
    }
};

```

```

f(adj, u, it - begin(adj[u]));
vi oth(it, end(adj[u]));
adj[u].erase(it, end(adj[u]));
dfs(u, sum);
swap(adj[u], oth);
dfs(u, siz - sum);
}
};

```

HLD.h

Description: Decomposes a tree into vertex disjoint heavy paths and light edges such that the path from any leaf to the root contains at most $\log(n)$ light edges. Code does additive modifications and max queries, but can support commutative segtree modifications/queries on paths and subtrees. Takes as input the full adjacency list. VALS.EDGES being true means that values are stored in the edges, as opposed to the nodes. All values initialized to the segtree default. Root must be 0.

Usage: Maximum Values on path from any two arbitrary nodes

For node to root, use Euler Tour

Time: $\mathcal{O}((\log N)^2)$

../data-structures/LazySegmentTree.h

9547af, 46 lines

```

template <bool VALS_EDGES> struct HLD {
    int N, tim = 0;
    vector<vi> adj;
    vi par, siz, rt, pos;
    Node *tree;
    HLD(vector<vi> adj_)
        : N(sz(adj_)), adj(adj_), par(N, -1), siz(N, 1),
          rt(N), pos(N), tree(new Node(0, N)) { dfsSz(0); dfsHld(0); }
    void dfsSz(int v) {
        for (int& u : adj[v]) {
            adj[u].erase(find(all(adj[u]), v));
            par[u] = v;
            dfsSz(u);
            siz[v] += siz[u];
            if (siz[u] > siz[adj[v][0]]) swap(u, adj[v][0]);
        }
    }
    void dfsHld(int v) {
        pos[v] = tim++;
        for (int u : adj[v]) {
            rt[u] = (u == adj[v][0] ? rt[v] : u);
            dfsHld(u);
        }
    }
    template <class B> void process(int u, int v, B op) {
        for (; v = par[rt[v]]; ) {
            if (pos[u] > pos[v]) swap(u, v);
            if (rt[u] == rt[v]) break;
            op(pos[rt[v]], pos[v] + 1);
        }
        op(pos[u] + VALS_EDGES, pos[v] + 1);
    }
    void modifyPath(int u, int v, int val) {
        process(u, v, [&](int l, int r) { tree->add(l, r, val); });
    }
    int queryPath(int u, int v) { // Modify depending on problem
        int res = -1e9;
        process(u, v, [&](int l, int r) {
            res = max(res, tree->query(l, r));
        });
        return res;
    }
    int querySubtree(int v) { // modifySubtree is similar
        return tree->query(pos[v] + VALS_EDGES, pos[v] + siz[v]);
    }
};

```

LinkCutTree.h

Description: Represents a forest of unrooted trees. You can add and remove edges (as long as the result is still a forest), and check whether two nodes are in the same tree.

Time: All operations take amortized $\mathcal{O}(\log N)$.

0fb462, 90 lines

```

struct Node { // Splay tree. Root's pp contains tree's parent.
    Node *p = 0, *pp = 0, *c[2];
    bool flip = 0;
    Node() { c[0] = c[1] = 0; fix(); }
    void fix() {
        if (c[0]) c[0]->p = this;
        if (c[1]) c[1]->p = this;
        // (+ update sum of subtree elements etc. if wanted)
    }
    void pushFlip() {
        if (!flip) return;
        flip = 0; swap(c[0], c[1]);
        if (c[0]) c[0]->flip ^= 1;
        if (c[1]) c[1]->flip ^= 1;
    }
    int up() { return p ? p->c[1] == this : -1; }
    void rot(int i, int b) {
        int h = i ^ b;
        Node *x = c[i], *y = b == 2 ? x : x->c[h], *z = b ? y : x;
        if ((y->p = p)) p->c[up()] = y;
        c[i] = z->c[i ^ 1];
        if (b < 2) {
            x->c[h] = y->c[h ^ 1];
            y->c[h ^ 1] = x;
        }
        z->c[i ^ 1] = this;
        fix(); x->fix(); y->fix();
        if (p) p->fix();
        swap(pp, y->pp);
    }
    void splay() {
        for (pushFlip(); p; ) {
            if (p->p) p->p->pushFlip();
            p->pushFlip(); pushFlip();
            int c1 = up(), c2 = p->up();
            if (c2 == -1) p->rot(c1, 2);
            else p->p->rot(c2, c1 != c2);
        }
    }
    Node* first() {
        pushFlip();
        return c[0] ? c[0]->first() : (splay(), this);
    }
};

struct LinkCut {
    vector<Node> node;
    LinkCut(int N) : node(N) {}

    void link(int u, int v) { // add an edge (u, v)
        assert(!connected(u, v));
        makeRoot(&node[u]);
        node[u].pp = &node[v];
    }
    void cut(int u, int v) { // remove an edge (u, v)
        Node *x = &node[u], *top = &node[v];
        makeRoot(top); x->splay();
        assert(top == (x->pp ? x->c[0]));
        if (x->pp) x->pp = 0;
        else {
            x->c[0] = top->p = 0;
            x->fix();
        }
    }
};

```

```

}
bool connected(int u, int v) { // are u, v in the same tree?
    Node* nu = access(&node[u])->first();
    return nu == access(&node[v])->first();
}
void makeRoot(Node* u) {
    access(u);
    u->splay();
    if(u->c[0]) {
        u->c[0]->p = 0;
        u->c[0]->flip ^= 1;
        u->c[0]->pp = u;
        u->c[0] = 0;
        u->fix();
    }
}
Node* access(Node* u) {
    u->splay();
    while (Node* pp = u->pp) {
        pp->splay(); u->pp = 0;
        if (pp->c[1]) {
            pp->c[1]->p = 0; pp->c[1]->pp = pp; }
        pp->c[1] = u; pp->fix(); u = pp;
    }
    return u;
}
};
```

DirectedMST.h

Description: Finds a minimum spanning tree/arborescence of a directed graph, given a root node. If no MST exists, returns -1.
Time: $O(E \log V)$

../data-structures/UnionFindRollback.h"	39e620, 60 lines
---	------------------

```

struct Edge { int a, b; ll w; };
struct Node {
    Edge key;
    Node *l, *r;
    ll delta;
    void prop() {
        key.w += delta;
        if (l) l->delta += delta;
        if (r) r->delta += delta;
        delta = 0;
    }
    Edge top() { prop(); return key; }
};
Node *merge(Node *a, Node *b) {
    if (!a || !b) return a ? b;
    a->prop(), b->prop();
    if (a->key.w > b->key.w) swap(a, b);
    swap(a->l, (a->r = merge(b, a->r)));
    return a;
}
void pop(Node*& a) { a->prop(); a = merge(a->l, a->r); }
```

```

pair<ll, vi> dmst(int n, int r, vector<Edge>& g) {
    RollbackUF uf(n);
    vector<Node*> heap(n);
    for (Edge e : g) heap[e.b] = merge(heap[e.b], new Node{e});
    ll res = 0;
    vi seen(n, -1), path(n), par(n);
    seen[r] = r;
    vector<Edge> Q(n, in(n, {-1,-1}), comp;
    deque<tuple<int, int, vector<Edge>>> cycs;
    rep(s,0,n) {
        int u = s, qi = 0, w;
        while (seen[u] < 0) {
            if (!heap[u]) return {-1,{};};
            Edge e = heap[u]->top();
```

```

        heap[u]->delta -= e.w, pop(heap[u]);
        Q[qi] = e, path[qi++] = u, seen[u] = s;
        res += e.w, u = uf.find(e.a);
        if (seen[u] == s) {
            Node* cyc = 0;
            int end = qi, time = uf.time();
            do cyc = merge(cyc, heap[w = path[--qi]]);
            while (uf.join(u, w));
            u = uf.find(u), heap[u] = cyc, seen[u] = -1;
            cycs.push_front({u, time, {Q[qi], &Q[end]}});
        }
    }
    rep(i,0,qi) in[uf.find(Q[i].b)] = Q[i];
}

for (auto& [u,t,comp] : cycs) { // restore sol (optional)
    uf.rollback(t);
    Edge inEdge = in[u];
    for (auto& e : comp) in[uf.find(e.b)] = e;
    in[uf.find(inEdge.b)] = inEdge;
}
rep(i,0,n) par[i] = in[i].a;
return {res, par};
}
```

Geometry (8)

8.1 Geometric primitives

Point.h

Description: Class to handle points in the plane. T can be e.g. ld or long. (Avoid int.)

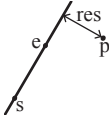
	0c250f, 25 lines
--	------------------

```

template <class T> int sgn(T x) { return (x > 0) - (x < 0); }
template<class T>
struct P {
    T x, y;
    explicit P(T x=0, T y=0) : x(x), y(y) {}
    bool operator<(P p) const { return tie(x,y) < tie(p.x,p.y); }
    bool operator==(P p) const { return tie(x,y)==tie(p.x,p.y); }
    P operator+(P p) const { return P(x+p.x, y+p.y); }
    P operator-(P p) const { return P(x-p.x, y-p.y); }
    P operator*(T d) const { return P(x*d, y*d); }
    P operator/(T d) const { return P(x/d, y/d); }
    T dot(P p) const { return x*p.x + y*p.y; }
    T cross(P p) const { return x*p.y - y*p.x; }
    T cross(P a, P b) const { return (a-*this).cross(b-*this); }
    T dist2() const { return x*x + y*y; }
    ld dist() const { return sqrt((ld)dist2()); }
    // angle to x-axis in interval [-pi, pi]
    ld angle() const { return atan2(y, x); }
    P unit() const { return *this/dist(); } // makes dist()==1
    P perp() const { return P(-y, x); } // rotates +90 degrees
    P normal() const { return perp().unit(); }
    // returns point rotated 'a' RADIANS ccw around the origin
    P rotate(ld a) const { return P(x*cos(a)-y*sin(a),x*sin(a)+y*cos(a)); }
    friend ostream& operator<<(ostream& os, P p) { return os << "
        (" << p.x << ", " << p.y << ")"; }
};
```

lineDistance.h

Description: Returns the signed distance between point p and the line containing points a and b. Positive value on left side and negative on right as seen from a towards b. a==b gives nan. P is supposed to be Point<T> or Point3D<T> where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long. Using Point3D will always give a non-negative distance. For Point3D, call .dist on the result of the cross product.



"Point.h"	f6bf6b, 4 lines
-----------	-----------------

```

template<class P>
double lineDist(const P& a, const P& b, const P& p) {
    return (double) (b-a).cross(p-a) / (b-a).dist();
}
```

LineProjectionReflection.h

Description: Projects point p onto line ab. Set refl=true to get reflection of point p across line ab instead. The wrong point will be returned if P is an integer point and the desired point doesn't have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow.

"Point.h"	b5562d, 5 lines
-----------	-----------------

```

template<class P>
P lineProj(P a, P b, P p, bool refl=false) {
    P v = b - a;
    return p - v.perp()*(1+refl)*v.cross(p-a)/v.dist2();
}
```

inAngle.h

Description: Returns true if p is in the angle between b and c. The angle starts at point a (b and c are endpoints). The angle is assumed to be at most 180 and the points are not colinear. Modify equals sign for exclusive inAngle check.

"sideOf.h", "Point.h"	7131bb, 6 lines
-----------------------	-----------------

```

bool inAngle(P a, P b, P c, P p)
{
    assert(sideOf(a, c, b) != 0);
    if (sideOf(a, c, b) < 0) swap(b, c);
    return sideOf(a, p, b) >= 0 && sideOf(a, p, c) <= 0;
}
```

Angle.h

Description: A class for ordering angles (as represented by int points and a number of rotations around the origin). Useful for rotational sweeping. Sometimes also represents points or vectors.

Usage: vector<Angle> v = {w[0], w[0].t360() ...}; // sorted
int j = 0; rep(i,0,n) { while (v[j] < v[i].t180()) ++j; }
// sweeps j such that (j-i) represents the number of positively oriented triangles with vertices at 0 and i

	0f0602, 36 lines
--	------------------

```

struct Angle {
    int x, y;
    int t;
    Angle(int x, int y, int t=0) : x(x), y(y), t(t) {}
    Angle operator-(Angle b) const { return {x-b.x, y-b.y, t}; }
    int half() const {
        assert(x || y);
        return y < 0 || (y == 0 && x < 0);
    }
    Angle t90() const { return {-y, x, t + (half() && x >= 0)}; }
    Angle t180() const { return {-x, -y, t + half()}; }
    Angle t360() const { return {x, y, t + 1}; }
};
```

```

bool operator<(Angle a, Angle b) {
    // add a.dist2() and b.dist2() to also compare distances
    return make_tuple(a.t, a.half(), a.y * (ll)b.x) <
```

```
        make_tuple(b.t, b.half(), a.x * (1l)b.y);
    }

    // Given two points, this calculates the smallest angle between
    // them, i.e., the angle that covers the defined line segment.
    pair<Angle, Angle> segmentAngles(Angle a, Angle b) {
        if (b < a) swap(a, b);
        return (b < a.tl80() ?
            make_pair(a, b) : make_pair(b, a.t360()));
    }
    Angle operator+(Angle a, Angle b) { // point a + vector b
        Angle r(a.x + b.x, a.y + b.y, a.t);
        if (a.tl80() < r) r.t--;
        return r.tl80() < a ? r.t360() : r;
    }
    Angle angleDiff(Angle a, Angle b) { // angle b - angle a
        int tu = b.t - a.t; a.t = b.t;
        return {a.x*b.x + a.y*b.y, a.x*b.y - a.y*b.x, tu - (b < a)};
    }
}
```

polarSort.h
Description: Sorts vectors radially based on angles [0, 2pi). For parallel vectors, larger magnitude come later.

```
"Point.h" c5aa4b, 13 lines

template<typename T>
bool half(const P<T> &p) {
    // DO NOT INCLUDE (0, 0)
    assert(p.x != 0 || p.y != 0);
    return p.y < 0 || (p.y == 0 && p.x < 0);
    // Use if you want the polar sort to start from Point V
    // return cross(v,p) < 0 || (cross(v,p) == 0 && dot(v,p) <
    0);
}

template<typename T>
bool comp(const P<T> &p, const P<T> &q) {
    return half(p) == half(q) ? cross(p, q) > 0 : half(p) <
        half(q);
}
}
```

lineSort.h
Description: Sorts points on a line s>e (or from their projections / parallel intersections) s and e represent the line we are comparing to

```
"Point.h" e353fa, 4 lines

bool cmpProj(P p, P q) {
    P v = e - s;
    return v.dot(p - s) < v.dot(q - s);
}
}
```

8.2 Lines and Segments

sideOf.h
Description: Returns where *p* is as seen from *s* towards *e*. 1/0/-1 ⇔ left/on line/right. If the optional argument *eps* is given 0 is returned if *p* is within distance *eps* from the line. P is supposed to be Point<T> where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long.
Usage: bool left = sideOf(p1,p2,q)==1;

```
"Point.h" 3af81c, 9 lines

template<class P>
int sideOf(P s, P e, P p) { return sgn(s.cross(e, p)); }
```

```
template<class P>
int sideOf(const P& s, const P& e, const P& p, double eps) {
    auto a = (e-s).cross(p-s);
    double l = (e-s).dist()*eps;
    return (a > l) - (a < -l);
}
}
```

OnSegment.h
Description: Returns true iff p lies on the line segment from s to e. Use (segDist(s,e,p)<=epsilon) instead when using Point<double>.

```
"Point.h" c597e8, 3 lines

template<class P> bool onSegment(P s, P e, P p) {
    return p.cross(s, e) == 0 && (s - p).dot(e - p) <= 0;
}
}
```

lineIntersection.h
Description:
If a unique intersection point of the lines going through s1,e1 and s2,e2 exists {1, point} is returned. If no intersection point exists {0, (0,0)} is returned and if infinitely many exists {-1, (0,0)} is returned. The wrong position will be returned if P is Point<ll> and the intersection point does not have integer coordinates. Products of three coordinates are used in inter-mediate steps so watch out for overflow if using int or ll.
Usage: auto res = lineInter(s1,e1,s2,e2);
if (res.first == 1)
cout << "intersection point at " << res.second << endl;

```
"Point.h" a01f81, 8 lines

template<class P>
pair<int, P> lineInter(P s1, P e1, P s2, P e2) {
    auto d = (e1 - s1).cross(e2 - s2);
    if (d == 0) // if parallel
        return {-(s1.cross(e1, s2) == 0), P(0, 0)};
    auto p = s2.cross(e1, e2), q = s2.cross(e2, s1);
    return {1, (s1 * p + e1 * q) / d};
}
}
```

linearTransformation.h
Description:
Apply the linear transformation (translation, rotation and scaling) which takes line p0-p1 to line q0-q1 to point r.

```
"Point.h" 03a306, 6 lines

typedef Point<double> P;
P linearTransformation(const P& p0, const P& p1,
    const P& q0, const P& q1, const P& r) {
    P dp = p1-p0, dq = q1-q0, num(dp.cross(dq), dp.dot(dq));
    return q0 + P((r-p0).cross(num), (r-p0).dot(num))/dp.dist2();
}
}
```

SegmentDistance.h
Description:
Returns the shortest distance between point p and the line segment from point s to e. For SEGMENT-SEGMENT DISTANCE, check for intersection. If there is no intersection, the closest distance is between one of the four points and the other segment.

```
"Point.h" 5c88f4, 6 lines

Usage: Point<double> a, b(2,2), p(1,1);
bool onSegment = segDist(a,b,p) < 1e-10;

"Point.h"

typedef Point<double> P;
double segDist(P& s, P& e, P& p) {
    if (s==e) return (p-s).dist();
    auto d = (e-s).dist2(), t = min(d,max(.0, (p-s).dot(e-s)));
    return ((p-s)*d-(e-s)*t).dist()/d;
}
}
```

SegmentIntersection.h
Description:
If a unique intersection point between the line segments going from s1 to e1 and from s2 to e2 exists then it is returned. If no intersection point exists an empty vector is returned. If infinitely many exist a vector with 2 elements is returned, containing the endpoints of the common line segment. The wrong position will be returned if P is Point<ll> and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or long long.

```
Usage: vector<P> inter = segInter(s1,e1,s2,e2);
if (sz(inter)==1)
cout << "segments intersect at " << inter[0] << endl;
"Point.h", "OnSegment.h" 9d57f2, 13 lines

template<class P> vector<P> segInter(P a, P b, P c, P d) {
    auto oa = c.cross(d, a), ob = c.cross(d, b),
        oc = a.cross(b, c), od = a.cross(b, d);
    // Checks if intersection is single non-endpoint point.
    if (sgn(oa) * sgn(ob) < 0 && sgn(oc) * sgn(od) < 0)
        return {(a * ob - b * oa) / (ob - oa)};
    set<P> s;
    if (onSegment(c, d, a)) s.insert(a);
    if (onSegment(c, d, b)) s.insert(b);
    if (onSegment(a, b, c)) s.insert(c);
    if (onSegment(a, b, d)) s.insert(d);
    return {all(s)};
}
}
```

8.3 Circles

Circle-Circle-Intersection.h
Description: Computes the pair of points at which two circles intersect. Returns false in case of no intersection.

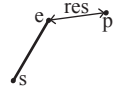
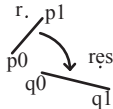
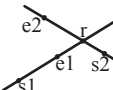
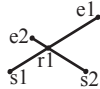
```
"Point.h" 84d6d3, 11 lines

typedef Point<double> P;
bool circleInter(P a, P b, double r1, double r2, pair<P, P>*
    out) {
    if (a == b) { assert(r1 != r2); return false; }
    P vec = b - a;
    double d2 = vec.dist2(), sum = r1+r2, dif = r1-r2,
        p = (d2 + r1*r1 - r2*r2)/(d2*2), h2 = r1*r1 - p*p*d2;
    if (sum*sum < d2 || dif*dif > d2) return false;
    P mid = a + vec*p, per = vec.perp() * sqrt(fmax(0, h2) / d2);
    *out = {mid + per, mid - per};
    return true;
}
}
```

CircleTangents.h
Description: Finds the external tangents of two circles, or internal if r2 is negated. Can return 0, 1, or 2 tangents – 0 if one circle contains the other (or overlaps it, in the internal case, or if the circles are the same); 1 if the circles are tangent to each other (in which case .first = .second and the tangent line is perpendicular to the line between the centers). .first and .second give the tangency points at circle 1 and 2 respectively. To find the tangents of a circle with a point set r2 to 0.

```
"Point.h" b0153d, 14 lines

template<class P>
vector<pair<P, P>> tangents(P c1, double r1, P c2, double r2) {
    // r2 = -r2 // Use for inner tangents
    P d = c2 - c1;
    double dr = r1 - r2, d2 = d.dist2(), h2 = d2 - dr * dr;
    if (d2 == 0 || h2 < 0) return {};
    vector<pair<P, P>> out;
    for (double sign : {-1, 1}) {
        P v = (d * dr + d.perp() * sqrt(h2) * sign) / d2;
        out.push_back({c1 + v * r1, c2 + v * r2});
    }
    if (h2 == 0) out.pop_back();
}
}
```



A diagram of a circle with center C . A radius r is shown as a line segment from the center C to the left edge of the circle. Two points, A and B , are marked on the circumference of the circle.


```
struct HalfPlane {
    P s, e, d;
    HalfPlane(P s = P(), P e = P()): s(s), e(e), d(e - s) {}
    bool contains(P p) { return d.cross(p - s) > -eps; }
    bool side() { return d.x<-eps || (abs(d.x)<=eps && d.y>0); }
    bool operator<(HalfPlane hp) {
        if(side() != hp.side()) return side();
        return d.cross(hp.d) > 0;
    }
    P inter(HalfPlane hp) {
        auto p = hp.s.cross(e, hp.e), q = hp.s.cross(hp.e, s);
        return (s * p + e * q) / d.cross(hp.d);
    }
};

vector<P> hpIntersection(vector<HalfPlane> hps) {
    sort(all(hps));
    int n = sz(hps), l = 1, r = 0;
    vector<HalfPlane> dq(n+1);
    rep(i, 0, n) {
        while(l<r && !hps[i].contains(dq[r].inter(dq[r-1]))) r--;
        while(l<r && !hps[i].contains(dq[l].inter(dq[l+1]))) l++;
        dq[++r] = hps[i];
        if(l < r && abs(dq[r].d.cross(dq[r-1].d)) < eps) {
            if(dq[r].d.dot(dq[r-1].d) < 0) return {};
            if(dq[--r].contains(hps[i].s)) dq[r] = hps[i];
        }
    }
    while(l<r-1 && !dq[l].contains(dq[r].inter(dq[r-1]))) r--;
    while(l<r-1 && !dq[r].contains(dq[l].inter(dq[l+1]))) l++;
    if(l > r-2) return {};
    vector<P> poly;
    rep(i, l, r) poly.push_back(dq[i].inter(dq[i+1]));
    poly.push_back(dq[r].inter(dq[l]));
    return poly;
}
```

```
vector<P> hpIntersection(vector<HalfPlane> hps) {
    sort(all(hps));
    int n = sz(hps), l = 1, r = 0;
    vector<HalfPlane> dq(n+1);
    rep(i, 0, n) {
        while(l<r && !hps[i].contains(dq[r].inter(dq[r-1]))) r--;
        while(l<r && !hps[i].contains(dq[l].inter(dq[l+1]))) l++;
        dq[++r] = hps[i];
        if(l < r && abs(dq[r].d.cross(dq[r-1].d)) < eps) {
            if(dq[r].d.dot(dq[r-1].d) < 0) return {};
            if(dq[--r].contains(hps[i].s)) dq[r] = hps[i];
        }
    }
    while(l<r-1 && !dq[l].contains(dq[r].inter(dq[r-1]))) r--;
    while(l<r-1 && !dq[r].contains(dq[l].inter(dq[l+1]))) l++;
    if(l > r-2) return {};
    vector<P> poly;
    rep(i, l, r) poly.push_back(dq[i].inter(dq[i+1]));
    poly.push_back(dq[r].inter(dq[l]));
    return poly;
}
```

ConvexHull.h
Description: Returns a vector of the points of the convex hull in counter-clockwise order. Points on the edge of the hull between two other points are not considered part of the hull.
Time: $\mathcal{O}(n \log n)$



```
"Point.h"
typedef Point<ll> P;
vector<P> convexHull(vector<P> pts) {
    if (sz(pts) <= 1) return pts;
    sort(all(pts));
    vector<P> h(2*sz(pts)); // modified for cses hack
    int s = 0, t = 0;
    for (int it = 2; it--; s = --t, reverse(all(pts)))
        for (P p : pts) {
            while (t >= s + 2 && h[t-2].cross(h[t-1], p) <= 0) t--;
            h[t++] = p;
        }
    return {h.begin(), h.begin() + t - (t == 2 && h[0] == h[1])};
}
```

HullDiameter.h
Description: Returns the two points with max distance on a convex hull (ccw, no duplicate/collinear points).
Time: $\mathcal{O}(n)$

```
"Point.h"
typedef Point<ll> P;
array<P, 2> hullDiameter(vector<P> S) {
    int n = sz(S), j = n < 2 ? 0 : 1;
    pair<ll, array<P, 2>> res({0, {S[0], S[0]}});
    rep(i, 0, j)
```

```
for (; j = (j + 1) % n) {
    res = max(res, {{S[i] - S[j]}.dist2(), {S[i], S[j]}});
    if ((S[(j + 1) % n] - S[j]).cross(S[i + 1] - S[i]) >= 0)
        break;
    }
return res.second;
}
```

PointInsideHull.h
Description: Determine whether a point t lies inside a convex hull (CCW order, with no collinear points). Returns true if point lies within the hull. If strict is true, points on the boundary aren't included.
Time: $\mathcal{O}(\log N)$

```
"Point.h", "sideOf.h", "OnSegment.h"
typedef Point<ll> P;

bool inHull(const vector<P>& h, P p, bool strict = true) {
    int a = 1, b = sz(h) - 1, r = !strict;
    if (sz(h) < 3) return r && onSegment(h[0], h.back(), p);
    if (sideOf(h[0], h[a], h[b]) > 0) swap(a, b);
    if (sideOf(h[0], h[a], p) >= r || sideOf(h[0], h[b], p) <= -r)
        return false;
    while (abs(a - b) > 1) {
        int c = (a + b) / 2;
        (sideOf(h[0], h[c], p) > 0 ? b : a) = c;
    }
    return sgn(h[a].cross(h[b], p)) < r;
}
```

ExtremeVertex.h
Description: returns the point of a hull with the max projection onto a line.
Time: $\mathcal{O}(\log n)$

```
"Point.h"
#define cmp(i, j) sgn(dir.perp().cross(poly[(i)%n]-poly[(j)%n]))
#define extr(i) cmp(i + 1, i) >= 0 && cmp(i, i - 1 + n) < 0
template <class P> int extrVertex(vector<P>& poly, P dir) {
    int n = sz(poly), lo = 0, hi = n;
    if (extr(0)) return 0;
    while (lo + 1 < hi) {
        int m = (lo + hi) / 2;
        if (extr(m)) return m;
        int ls = cmp(lo + 1, lo), ms = cmp(m + 1, m);
        (ls < ms || (ls == ms && ls == cmp(lo, m)) ? hi : lo) = m;
    }
    return lo;
}
```

LineHullIntersection.h
Description: Line-convex polygon intersection. The polygon must be ccw and have no collinear points. lineHull(line, poly) returns a pair describing the intersection of a line with the polygon: $\bullet(-1, -1)$ if no collision, $\bullet(i, -1)$ if touching the corner i , $\bullet(i, i)$ if along side $(i, i + 1)$, $\bullet(i, j)$ if crossing sides $(i, i + 1)$ and $(j, j + 1)$. In the last case, if a corner i is crossed, this is treated as happening on side $(i, i + 1)$. The points are returned in the same order as the line hits the polygon. extrVertex returns the point of a hull with the max projection onto a line.
Time: $\mathcal{O}(\log n)$

```
"Point.h"
#define cmp(i, j) sgn(dir.perp().cross(poly[(i)%n]-poly[(j)%n]))
#define extr(i) cmp(i + 1, i) >= 0 && cmp(i, i - 1 + n) < 0
template <class P> int extrVertex(vector<P>& poly, P dir) {
    int n = sz(poly), lo = 0, hi = n;
    if (extr(0)) return 0;
    while (lo + 1 < hi) {
        int m = (lo + hi) / 2;
        if (extr(m)) return m;
```

```
int ls = cmp(lo + 1, lo), ms = cmp(m + 1, m);
(ls < ms || (ls == ms && ls == cmp(lo, m)) ? hi : lo) = m;
}
return lo;
}
```

```
#define cmpL(i) sgn(a.cross(poly[i], b))
template <class P>
array<int, 2> lineHull(P a, P b, vector<P>& poly) {
    int endA = extrVertex(poly, (a - b).perp());
    int endB = extrVertex(poly, (b - a).perp());
    if (cmpL(endA) < 0 || cmpL(endB) > 0)
        return {-1, -1};
    array<int, 2> res;
    rep(i, 0, 2) {
        int lo = endB, hi = endA, n = sz(poly);
        while ((lo + 1) % n != hi) {
            int m = ((lo + hi + (lo < hi ? 0 : n)) / 2) % n;
            (cmpL(m) == cmpL(endB) ? lo : hi) = m;
        }
        res[i] = (lo + !cmpL(hi)) % n;
        swap(endA, endB);
    }
    if (res[0] == res[1]) return {res[0], -1};
    if (!cmpL(res[0]) && !cmpL(res[1]))
        switch ((res[0] - res[1] + sz(poly) + 1) % sz(poly)) {
            case 0: return {res[0], res[0]};
            case 2: return {res[1], res[1]};
        }
    return res;
}
```

HullTangents.h
Description: Finds the left and right, respectively, tangent points on convex hull from a point. If the point is colinear to side(s) of the polygon, the point further away is returned. Requires ccw, $n \geq 3$, and the point be on or outside the polygon. Can be used to check if a point is inside of a convex hull. Will return -1 if it is strictly inside. If the point is on the hull, the two adjacent points will be returned
Time: $\mathcal{O}(\log n)$

```
"Point.h"
#define cmp(i, j) p.cross(h[i], h[j == n ? 0 : j]) * (R ? 1 : -1)
template<bool R, class P> int getTangent(vector<P>& h, P p) {
    int n = sz(h), lo = 0, hi = n - 1, md;
    if (cmp(0, 1) >= R && cmp(0, n - 1) >= !R) return 0;
    while (md = (lo + hi + 1) / 2, lo < hi) {
        auto a = cmp(md, md + 1), b = cmp(md, lo);
        if (a >= R && cmp(md, md - 1) >= !R) return md;
        if (cmp(lo, lo + 1) < R)
            a < R && b >= 0 ? lo = md : hi = md - 1;
        else a < R || b <= 0 ? lo = md : hi = md - 1;
    }
    return -1; // point strictly inside hull
}
template<class P> pii hullTangents(vector<P>& h, P p) {
    return {getTangent<0>(h, p), getTangent<1>(h, p)};
}
```

MinkowskiSum.h
Description: Returns the minkowski sum of a set of convex polygons
Time: $\mathcal{O}(n \log n)$

```
#define side(p) (p.x > 0 || (p.x == 0 && p.y > 0))
template<class P>
vector<P> convolve(vector<vector<P>>& polys){
    P init; vector<P> dir;
    for(auto poly: polys) {
        int n = sz(poly);
```



```
    if(n) init = init + poly[0];
    if(n < 2) continue;
    rep(i, 0, n) dir.push_back(poly[(i+1)%n] - poly[i]);
}
if(size(dir) == 0) return { init };
stable_sort(all(dir), [&](P a, P b)->bool {
    if(side(a) != side(b)) return side(a);
    return a.cross(b) > 0;
});
vector<P> sum; P cur = init;
rep(i, 0, sz(dir))
    sum.push_back(cur), cur = cur + dir[i];
return sum;
}
```

lineTranslations.h

Description: Translates a line using a given translation vector u or given a distance dist

	1087de, 9 lines
<pre>void vectorTransaltion (P &s, P &e, P u) { s += u; e+=u; } void shiftLeft (P &s, P &e, ld dist) { P v = e-s, n = P(-v.y, v.x); n = n * (dist / abs(n)); s += u; e+=u; }</pre>	

8.5 Misc. Point Set Problems

ClosestPair.h

Description: Finds the closest pair of points.

Time: $\mathcal{O}(n \log n)$

"Point.h"	ac41a6, 17 lines
<pre>typedef Point<ll> P; pair<P, P> closest(vector<P> v) { assert(sz(v) > 1); set<P> S; sort(all(v), [](P a, P b) { return a.y < b.y; }); pair<ll, pair<P, P>> ret{LLONG_MAX, {P(), P()}}; int j = 0; for (P p : v) { P d{1 + (ll)sqrt(ret.first), 0}; while (v[j].y <= p.y - d.x) S.erase(v[j++]); auto lo = S.lower_bound(p - d), hi = S.upper_bound(p + d); for (; lo != hi; ++lo) ret = min(ret, {(*lo - p).dist2(), { *lo, p } }); S.insert(p); } return ret.second; }</pre>	

ManhattanMST.h

Description: Given N points, returns up to 4*N edges, which are guaranteed to contain a minimum spanning tree for the graph with edge weights $w(p, q) = -p.x - q.x - + -p.y - q.y-$. Edges are in the form (distance, src, dst). Use a standard MST algorithm on the result to find the final MST.

Time: $\mathcal{O}(N \log N)$

"Point.h"	df6f59, 23 lines
<pre>typedef Point<int> P; vector<array<int, 3>> manhattanMST(vector<P> ps) { vi id(sz(ps)); iota(all(id), 0); vector<array<int, 3>> edges; rep(k,0,4) { sort(all(id), [&](int i, int j) { return (ps[i]-ps[j]).x < (ps[j]-ps[i]).y;}); map<int, int> sweep;</pre>	

```
    for (int i : id) {
        for (auto it = sweep.lower_bound(-ps[i].y);
            it != sweep.end(); sweep.erase(it++)) {
            int j = it->second;
            P d = ps[i] - ps[j];
            if (d.y > d.x) break;
            edges.push_back({d.y + d.x, i, j});
        }
        sweep[-ps[i].y] = i;
    }
    for (P& p : ps) if (k & 1) p.x = -p.x; else swap(p.x, p.y);
}
return edges;
}
```

kdTree.h

Description: KD-tree (2d, can be extended to 3d)

"Point.h"	bac5b0, 63 lines
<pre>typedef long long T; typedef Point<T> P; const T INF = numeric_limits<T>::max(); bool on_x(const P& a, const P& b) { return a.x < b.x; } bool on_y(const P& a, const P& b) { return a.y < b.y; } struct Node { P pt; // if this is a leaf, the single point in it T x0 = INF, x1 = -INF, y0 = INF, y1 = -INF; // bounds Node *first = 0, *second = 0; T distance(const P& p) { // min squared distance to a point T x = (p.x < x0 ? x0 : p.x > x1 ? x1 : p.x); T y = (p.y < y0 ? y0 : p.y > y1 ? y1 : p.y); return (P(x,y) - p).dist2(); } Node(vector<P>&& vp) : pt(vp[0]) { for (P p : vp) { x0 = min(x0, p.x); x1 = max(x1, p.x); y0 = min(y0, p.y); y1 = max(y1, p.y); } if (vp.size() > 1) { // split on x if width >= height (not ideal...) sort(all(vp), x1 - x0 >= y1 - y0 ? on_x : on_y); // divide by taking half the array for each child (not // best performance with many duplicates in the middle) int half = sz(vp)/2; first = new Node({vp.begin(), vp.begin() + half}); second = new Node({vp.begin() + half, vp.end()}); } } }; struct KDTree { Node* root; KDTree(const vector<P>&& vp) : root(new Node({all(vp)})) {} pair<T, P> search(Node *node, const P& p) { if (!node->first) { // uncomment if we should not find the point itself: // if (p == node->pt) return {INF, P()}; return make_pair((p - node->pt).dist2(), node->pt); } Node *f = node->first, *s = node->second; T bfirst = f->distance(p), bsec = s->distance(p); if (bfirst > bsec) swap(bsec, bfirst), swap(f, s); // search closest side first, other side if needed</pre>	

```
    auto best = search(f, p);
    if (bsec < best.first)
        best = min(best, search(s, p));
    return best;
}

// find nearest point to a point, and its squared distance
// (requires an arbitrary operator< for Point)
pair<T, P> nearest(const P& p) {
    return search(root, p);
}
};
```

DelaunayTriangulation.h

Description: Computes the Delaunay triangulation of a set of points. Each circumcircle contains none of the input points. If any three points are collinear or any four are on the same circle, behavior is undefined.

Time: $\mathcal{O}(n^2)$

"Point.h", "3dHull.h"	c0e7bc, 10 lines
<pre>template<class P, class F> void delaunay(vector<P>& ps, F trifu) { if (sz(ps) == 3) { int d = (ps[0].cross(ps[1], ps[2]) < 0); trifu(0,1+d,2-d); } vector<P3> p3; for (P p : ps) p3.emplace_back(p.x, p.y, p.dist2()); if (sz(ps) > 3) for(auto t:hull3d(p3)) if ((p3[t.b]-p3[t.a]). cross(p3[t.c]-p3[t.a]).dot(P3(0,0,1)) < 0) trifu(t.a, t.c, t.b); }</pre>	

FastDelaunay.h

Description: Fast Delaunay triangulation. Each circumcircle contains none of the input points. There must be no duplicate points. If all points are on a line, no triangles will be returned. Should work for doubles as well, though there may be precision issues in 'circ'. Returns triangles in order {t[0][0], t[0][1], t[0][2], t[1][0], ...}, all counter-clockwise.

Time: $\mathcal{O}(n \log n)$

"Point.h"	eefdf5, 88 lines
<pre>typedef Point<ll> P; typedef struct Quad* Q; typedef __int128_t ll1; // (can be ll if coords are < 2e4) P arb(LLONG_MAX,LLONG_MAX); // not equal to any other point struct Quad { Q rot, o; P p = arb; bool mark; P& F() { return r()->p; } Q& r() { return rot->rot; } Q prev() { return rot->o->rot; } Q next() { return r()->prev(); } } *H; bool circ(P p, P a, P b, P c) { // is p in the circumcircle? ll1 p2 = p.dist2(), A = a.dist2()-p2, B = b.dist2()-p2, C = c.dist2()-p2; return p.cross(a,b)*C + p.cross(b,c)*A + p.cross(c,a)*B > 0; } Q makeEdge(P orig, P dest) { Q r = H ? H : new Quad{new Quad{new Quad{new Quad{0}}}}; H = r->o; r->r()->r() = r; rep(i,0,4) r = r->rot, r->p = arb, r->o = i & 1 ? r : r->r(); r->p = orig; r->F() = dest; return r; } void splice(Q a, Q b) { swap(a->o->rot->o, b->o->rot->o); swap(a->o, b->o); } Q connect(Q a, Q b) { Q q = makeEdge(a->F(), b->p);</pre>	

```
splice(q, a->next());
splice(q->r(), b);
return q;
}

pair<Q,Q> rec(const vector<P>& s) {
    if (sz(s) <= 3) {
        Q a = makeEdge(s[0], s[1]), b = makeEdge(s[1], s.back());
        if (sz(s) == 2) return { a, a->r() };
        splice(a->r(), b);
        auto side = s[0].cross(s[1], s[2]);
        Q c = side ? connect(b, a) : 0;
        return {side < 0 ? c->r() : a, side < 0 ? c : b->r() };
    }

#define H(e) e->F(), e->p
#define valid(e) (e->F().cross(H(base)) > 0)
    Q A, B, ra, rb;
    int half = sz(s) / 2;
    tie(ra, A) = rec({all(s) - half});
    tie(B, rb) = rec({sz(s) - half + all(s)});
    while ((B->p.cross(H(A)) < 0 && (A = A->next()) ||
            (A->p.cross(H(B)) > 0 && (B = B->r()->o)));
    Q base = connect(B->r(), A);
    if (A->p == ra->p) ra = base->r();
    if (B->p == rb->p) rb = base;

#define DEL(e, init, dir) Q e = init->dir; if (valid(e)) \
    while (circ(e->dir->F(), H(base), e->F())) { \
        Q t = e->dir; \
        splice(e, e->prev()); \
        splice(e->r(), e->r()->prev()); \
        e->o = H; H = e; e = t; \
    }
    for (;;) {
        DEL(LC, base->r(), o); DEL(RC, base, prev());
        if (!valid(LC) && !valid(RC)) break;
        if (!valid(LC) || (valid(RC) && circ(H(RC), H(LC))))
            base = connect(RC, base->r());
        else
            base = connect(base->r(), LC->r());
    }
    return { ra, rb };
}

vector<P> triangulate(vector<P> pts) {
    sort(all(pts)); assert(unique(all(pts)) == pts.end());
    if (sz(pts) < 2) return {};
    Q e = rec(pts).first;
    vector<Q> q = {e};
    int qi = 0;
    while (e->o->F().cross(e->F(), e->p) < 0) e = e->o;
#define ADD { Q c = e; do { c->mark = 1; pts.push_back(c->p); \
    q.push_back(c->r()); c = c->next(); } while (c != e); }
    ADD; pts.clear();
    while (qi < sz(q)) if (!(e = q[qi++]>mark) ADD;
    return pts;
}
```

PlanarFaceExtraction.h

Description: Given a planar graph and where the points are, extract the set of faces that the graph makes. The inner faces will be returned in counter-clockwise order, and the outermost face will be returned in clockwise order.

Time: $\mathcal{O}(E\log E)$

```
template<class P>
vector<vector<P>> extract_faces(vvi adj, vector<P> pts) {
    int n = sz(pts);
    #define cmp(i) [&](int pi, int qi) -> bool { \
```

```
P p = pts[pi] - pts[i], q = pts[qi] - pts[i]; \
bool sideP = p.y < 0 || (p.y == 0 && p.x < 0); \
bool sideQ = q.y < 0 || (q.y == 0 && q.x < 0); \
if(sideP != sideQ) return sideP; \
return p.cross(q) > 0; }
rep(i, 0, n)
    sort(all(adj[i]), cmp(i));
vii ed;
rep(i, 0, n) for(int j: adj[i])
    ed.emplace_back(i, j);
sort(all(ed));
auto get_idx = [&](int i, int j) -> int {
    return lower_bound(all(ed), pii(i, j))-begin(ed);
};
vector<vector<P>> faces;
vi used(sz(ed));
rep(i, 0, n) for(int j: adj[i]) {
    if(used[get_idx(i, j)])
        continue;
    used[get_idx(i, j)] = true;
    vector<P> face = {pts[i]};
    int prv = i, cur = j;
    while(cur != i) {
        face.push_back(pts[cur]);
        auto it = lower_bound(all(adj[cur]), prv, cmp(cur));
        if(it == begin(adj[cur]))
            it = end(adj[cur]);
        prv = cur, cur = *prev(it);
        used[get_idx(prv, cur)] = true;
    }
    faces.push_back(face);
}
#undef cmp
return faces;
}
```

8.6 3D PolyhedronVolume.h

Description: Magic formula for the volume of a polyhedron. Faces should point outwards.

```
template<class V, class L>
double signedPolyVolume(const V& p, const L& trilst) {
    double v = 0;
    for (auto i : trilst) v += p[i.a].cross(p[i.b]).dot(p[i.c]);
    return v / 6;
}
```

Point3D.h

Description: Class to handle points in 3D space. T can be e.g. double or long long.

```
template<class T> struct Point3D {
    typedef Point3D P;
    typedef const P& R;
    T x, y, z;
    explicit Point3D(T x=0, T y=0, T z=0) : x(x), y(y), z(z) {}
    bool operator<(R p) const {
        return tie(x, y, z) < tie(p.x, p.y, p.z); }
    bool operator==(R p) const {
        return tie(x, y, z) == tie(p.x, p.y, p.z); }
    P operator+(R p) const { return P(x+p.x, y+p.y, z+p.z); }
    P operator-(R p) const { return P(x-p.x, y-p.y, z-p.z); }
    P operator*(T d) const { return P(x*d, y*d, z*d); }
    P operator/(T d) const { return P(x/d, y/d, z/d); }
    T dot(R p) const { return x*p.x + y*p.y + z*p.z; }
    P cross(R p) const {
        return P(y*p.z - z*p.y, z*p.x - x*p.z, x*p.y - y*p.x);
    }
}
```

```
T dist2() const { return x*x + y*y + z*z; }
double dist() const { return sqrt((double)dist2()); }
//Azimuthal angle (longitude) to x-axis in interval [-pi, pi]
double phi() const { return atan2(y, x); }
//Zenith angle (latitude) to the z-axis in interval [0, pi]
double theta() const { return atan2(sqrt(x*x+y*y), z); }
P unit() const { return *this/(T)dist(); } //makes dist()==1
//returns unit vector normal to *this and p
P normal(P p) const { return cross(p).unit(); }
//returns point rotated 'angle' radians ccw around axis
P rotate(double angle, P axis) const {
    double s = sin(angle), c = cos(angle); P u = axis.unit();
    return u.dot(u)*(1-c) + (*this)*c - cross(u)*s;
}
};
```

3dHull.h

Description: Computes all faces of the 3-dimension hull of a point set. *No four points must be coplanar*, or else random results will be returned. All faces will point outwards.

Time: $\mathcal{O}(n^2)$

"Point3D.h" 5b45fc, 49 lines

typedef Point3D<double> P3;

```
struct PR {
    void ins(int x) { (a == -1 ? a : b) = x; }
    void rem(int x) { (a == x ? a : b) = -1; }
    int cnt() { return (a != -1) + (b != -1); }
    int a, b;
};
```

struct F { P3 q; int a, b, c; };

```
vector<F> hull3d(const vector<P3>& A) {
    assert(sz(A) >= 4);
    vector<vector<PR>> E(sz(A), vector<PR>(sz(A), {-1, -1}));
#define E(x,y) E[f.x][f.y]
    vector<F> FS;
    auto mf = [&](int i, int j, int k, int l) {
        P3 q = (A[j] - A[i]).cross((A[k] - A[i]));
        if (q.dot(A[l]) > q.dot(A[i]))
            q = q * -1;
        F f{q, i, j, k};
        E(a,b).ins(k); E(a,c).ins(j); E(b,c).ins(i);
        FS.push_back(f);
    };
    rep(i,0,4) rep(j,i+1,4) rep(k,j+1,4)
        mf(i, j, k, 6 - i - j - k);
```

```
rep(i,4,sz(A)) {
    rep(j,0,sz(FS)) {
        F f = FS[j];
        if(f.q.dot(A[i]) > f.q.dot(A[f.a])) {
            E(a,b).rem(f.c);
            E(a,c).rem(f.b);
            E(b,c).rem(f.a);
            swap(FS[j--], FS.back());
            FS.pop_back();
        }
        int nw = sz(FS);
        rep(j,0,nw) {
            F f = FS[j];
#define C(a, b, c) if (E(a,b).cnt() != 2) mf(f.a, f.b, i, f.c);
            C(a, b, c); C(a, c, b); C(b, c, a);
        }
        for (F& it : FS) if ((A[it.b] - A[it.a]).cross(
            A[it.c] - A[it.a]).dot(it.q) <= 0) swap(it.c, it.b);
    }
}
```

```
    return FS;
};
```

sphericalDistance.h

Description: Returns the shortest distance on the sphere with radius radius between the points with azimuthal angles (longitude) f1 (ϕ_1) and f2 (ϕ_2) from x axis and zenith angles (latitude) t1 (θ_1) and t2 (θ_2) from z axis (0 = north pole). All angles measured in radians. The algorithm starts by converting the spherical coordinates to cartesian coordinates so if that is what you have you can use only the two last rows. dx*radius is then the difference between the two points in the x direction and d*radius is the total distance between the points.

<pre>double sphericalDistance(double f1, double t1, double f2, double t2, double radius) { double dx = sin(t2)*cos(f2) - sin(t1)*cos(f1); double dy = sin(t2)*sin(f2) - sin(t1)*sin(f1); double dz = cos(t2) - cos(t1); double d = sqrt(dx*dx + dy*dy + dz*dz); return radius*2*asin(d/2); }</pre>	611f07, 8 lines
--	-----------------

Strings (9)

MatchingAutomation.h

Description: Creates substring searching automation

<pre>void computeAutomaton(string s, vector<vector<int>>& aut) { s += '#'; int n = s.size(); vector<int> pi = prefix_function(s); aut.assign(n, vector<int>(26)); for (int i = 0; i < n; i++) for (int c = 0; c < 26; c++) if (i > 0 && 'a' + c != s[i]) aut[i][c] = aut[pi[i] - 1][c]; else aut[i][c] = i + ('a' + c == s[i]); }</pre>	c3fe8a, 12 lines
---	------------------

KMP.h

Description: pi[x] computes the length of the longest prefix of s that ends at x, other than s[0...x] itself (abacaba -> 0010123). Can be used to find all occurrences of a string.

<pre>Time: $\mathcal{O}(n)$</pre>	d4375c, 16 lines
<pre>vi pi(const string& s) { vi p(sz(s)); rep(i,1,sz(s)) { int g = p[i-1]; while (g && s[i] != s[g]) g = p[g-1]; p[i] = g + (s[i] == s[g]); } return p; }</pre>	
<pre>vi match(const string& s, const string& pat) { vi p = pi(pat + '\0' + s), res; rep(i,sz(p)-sz(s),sz(p)) if (p[i] == sz(pat)) res.push_back(i - 2 * sz(pat)); return res; }</pre>	

Zfunc.h

Description: z[i] computes the length of the longest common prefix of s[i:] and s, except z[0] = 0. (abacaba -> 0010301) Used for Finding Periods CSES

<pre>Time: $\mathcal{O}(n)$</pre>	ee09e2, 12 lines
<pre>vi Z(const string& S) { vi z(sz(S)); int l = -1, r = -1; rep(i,1,sz(S)) { z[i] = i >= r ? 0 : min(r - i, z[i - l]); while (i + z[i] < sz(S) && S[i + z[i]] == S[z[i]]) z[i]++; if (i + z[i] > r) l = i, r = i + z[i]; } return z; }</pre>	

Manacher.h

Description: For each position in a string, computes p[0][i] = half length of longest even palindrome around pos i, p[1][i] = longest odd (half rounded down).

<pre>Time: $\mathcal{O}(N)$</pre>	e7ad79, 13 lines
<pre>array<vi,2> manacher(const string& s) { int n = sz(s); array<vi,2> p = {vi(n+1), vi(n)}; rep(z,0,2) for (int i=0,l=0,r=0; i < n; i++) { int t = r-i+!z; if (i<r) p[z][i] = min(t, p[z][l+t]); int L = i-p[z][i], R = i+p[z][i]-!z; while (L>=1 && R+1<n && s[L-1] == s[R+1]) p[z][i]++, L--, R++; if (R>r) l=L, r=R; } return p; }</pre>	

Eertree.h

Description: Generates an eertree on str. *cur* is accurate at the end of the main loop before the final assignment to *t*.

<pre>Time: $\mathcal{O}(S)$</pre>	2fc643, 24 lines
<pre>struct Eertree { vi slink = {0, 0}, len = {-1, 0}; vvi down; int cur = 0, t = 0; Eertree(string &str) : down(2, vi(26, -1)) { for (int i = 0; i < sz(str); i++) { char c = str[i]; int ci = c - 'a'; while (t <= 0 str[t-1] != c) t = i - len[cur = slink[cur]]; if (down[cur][ci] == -1) { down[cur][ci] = sz(slink); down.emplace_back(26, -1); len.push_back(len[cur] + 2); if (len.back() > 1) { do t = i - len[cur = slink[cur]]; while(t <= 0 str[t-1] != c); slink.push_back(down[cur][ci]); } else slink.push_back(1); cur = sz(slink) - 1; } else cur = down[cur][ci]; t = i - len[cur] + 1; } } };</pre>	

MinRotation.h

Description: Finds the lexicographically smallest rotation of a string.

Usage: rotate(v.begin(), v.begin()+minRotation(v), v.end());

<pre>Time: $\mathcal{O}(N)$</pre>	d07a42, 8 lines
<pre>int minRotation(string s) { int a=0, N=sz(s); s += s; rep(b,0,N) rep(k,0,N) { if (a+k == b s[a+k] < s[b+k]) {b += max(0, k-1); break;} if (s[a+k] > s[b+k]) { a = b; break; } } return a; }</pre>	

SuffixArray.h

Description: Builds suffix array for a string. sa[i] is the starting index of the suffix which is *i*'th in the sorted suffix array. The returned vector is of size *n* + 1, and sa[0] = n. The lcp array contains longest common prefixes for neighbouring strings in the suffix array: lcp[i] = lcp(sa[i], sa[i-1]), lcp[0] = 0. The input string must not contain any nul chars.

<pre>Time: $\mathcal{O}(n \log n)$</pre>	635552, 22 lines
<pre>struct SuffixArray { vi sa, lcp; SuffixArray(string s, int lim=256) { // or vector<int> s.push_back(0); int n = sz(s), k = 0, a, b; vi x(all(s)), y(n), ws(max(n, lim)); sa = lcp = y, iota(all(sa), 0); for (int j = 0, p = 0; p < n; j = max(1, j * 2), lim = p) { p = j, iota(all(y), n - j); rep(i,0,n) if (sa[i] >= j) y[p++] = sa[i] - j; fill(all(ws), 0); rep(i,0,n) ws[x[i]]++; rep(i,1,lim) ws[i] += ws[i - 1]; for (int i = n; i--;) sa[--ws[x[y[i]]]] = y[i]; swap(x, y), p = 1, x[sa[0]] = 0; rep(i,1,n) a = sa[i - 1], b = sa[i], x[b] = (y[a] == y[b] && y[a + j] == y[b + j]) ? p - 1 : p++; } for (int i = 0, j; i < n - 1; lcp[x[i+1]] = k) for (k && k--, j = sa[x[i] - 1]; s[i + k] == s[j + k]; k++); } };</pre>	

SuffixAutomaton.h

Description: Creates a partial DFA (DAG) that accepts all suffixes, with suffix links. One-to-one map between a path from the root and a substring. len is the longest-length substring ending here. pos is the first index in the string matching here. term is whether this node is a terminal (aka a suffix)

Time: construction takes $\mathcal{O}(N \log K)$, where *K* = Alphabet Size.

<pre>383afe, 27 lines</pre>	
<pre>struct st {int len, pos, term, link=-1; map<char, int> next;}; struct SuffixAutomaton { vector<st> a; SuffixAutomaton(string &str) { a.resize(1); int last = 0; for(auto c : str) { int p = last, cur = last = sz(a); a.push_back({a[p].len + 1, a[p].len}); while(p >= 0 && !a[p].next.count(c)) a[p].next[c] = cur, p = a[p].link; if (p == -1) a[cur].link = 0; else { int q = a[p].next[c]; if (a[p].len + 1 == a[q].len) a[cur].link = q; else { a.push_back({a[p].len+1, a[q].pos, 0, a[q].link, a[q].next});</pre>	

UCF

```
    for(; p >= 0 && a[p].next[c] == q; p = a[p].link)
        a[p].next[c] = sz(a)-1;
    a[q].link = a[cur].link = sz(a)-1;
}
}
}
while(last >= 0) a[last].term = 1, last = a[last].link;
}
};
```

SuffixTree.h

Description: Ukkonen's algorithm for online suffix tree construction. Each node contains indices [l, r) into the string, and a list of child nodes. Suffixes are given by traversals of this tree, joining [l, r) substrings. The root is 0 (has l = -1, r = 0), non-existent children are -1. To get a complete tree, append a dummy symbol – otherwise it may contain an incomplete path (still useful for substring matching, though).

Time: $\mathcal{O}(26N)$

aae0b8, 50 lines

```
struct SuffixTree {
    enum { N = 200010, ALPHA = 26 }; // N ~ 2*maxlen+10
    int toi(char c) { return c - 'a'; }
    string a; // v = cur node, q = cur position
    int t[N][ALPHA], l[N], r[N], p[N], s[N], v=0, q=0, m=2;

    void ukkadd(int i, int c) { suff:
        if (r[v]<=q) {
            if (t[v][c]==-1) { t[v][c]=m; l[m]=i;
                p[m++]=v; v=s[v]; q=r[v]; goto suff; }
            v=t[v][c]; q=l[v];
        }
        if (q==-1 || c==toi(a[q])) q++; else {
            l[m+1]=i; p[m+1]=m; l[m]=l[v]; r[m]=q;
            p[m]=p[v]; t[m][c]=m+1; t[m][toi(a[q])]=v;
            l[v]=q; p[v]=m; t[p[m]][toi(a[l[m])]]=m;
            v=s[p[m]]; q=l[m];
            while (q<r[m]) { v=t[v][toi(a[q])]; q+=r[v]-l[v]; }
            if (q==r[m]) s[m]=v; else s[m]=m+2;
            q=r[v]-(q-r[m]); m+=2; goto suff;
        }
    }

    SuffixTree(string a) : a(a) {
        fill(r, r+N, sz(a));
        memset(s, 0, sizeof s);
        memset(t, -1, sizeof t);
        fill(t[1], t[1]+ALPHA, 0);
        s[0] = 1; l[0] = l[1] = -1; r[0] = r[1] = p[0] = p[1] = 0;
        rep(i, 0, sz(a)) ukkadd(i, toi(a[i]));
    }

    // example: find longest common substring (uses ALPHA = 28)
    pii best;
    int lcs(int node, int i1, int i2, int olen) {
        if (l[node] <= i1 && i1 < r[node]) return 1;
        if (l[node] <= i2 && i2 < r[node]) return 2;
        int mask = 0, len = node ? olen + (r[node] - l[node]) : 0;
        rep(c, 0, ALPHA) if (t[node][c] != -1)
            mask |= lcs(t[node][c], i1, i2, len);
        if (mask == 3)
            best = max(best, {len, r[node] - l[node]});
        return mask;
    }
    static pii LCS(string s, string t) {
        SuffixTree st(s + (char)('z' + 1) + t + (char)('z' + 2));
        st.lcs(0, sz(s), sz(s) + 1 + sz(t), 0);
        return st.best;
    }
};
```

SuffixTree Hashing HashInterval AhoCorasick-Kactl

Hashing.h

Description: Self-explanatory methods for string hashing.

2d2a67, 44 lines

```
// Arithmetic mod 2^64-1. 2x slower than mod 2^64 and more
// code, but works on evil test data (e.g. Thue-Morse, where
// ABBA... and BAAB... of length 2^10 hash the same mod 2^64).
// "typedef ull H;" instead if you think test data is random,
// or work mod 10^9+7 if the Birthday paradox is not a problem.
typedef uint64_t ull;
struct H {
    ull x; H(ull x=0) : x(x) {}
    H operator+(H o) { return x + o.x + (x + o.x < x); }
    H operator-(H o) { return *this + ~o.x; }
    H operator*(H o) { auto m = (__uint128_t)x * o.x;
        return H((ull)m) + (ull)(m >> 64); }
    ull get() const { return x + !~x; }
    bool operator==(H o) const { return get() == o.get(); }
    bool operator<(H o) const { return get() < o.get(); }
};
static const H C = (1ll)1e11+3; // (order ~ 3e9; random also ok)

struct HashInterval {
    vector<H> ha, pw;
    HashInterval(string& str) : ha(sz(str)+1), pw(ha) {
        pw[0] = 1;
        rep(i, 0, sz(str))
            ha[i+1] = ha[i] * C + str[i],
            pw[i+1] = pw[i] * C;
    }
    H hashInterval(int a, int b) { // hash [a, b)
        return ha[b] - ha[a] * pw[b - a];
    }
};

vector<H> getHashes(string& str, int length) {
    if (sz(str) < length) return {};
    H h = 0, pw = 1;
    rep(i, 0, length)
        h = h * C + str[i], pw = pw * C;
    vector<H> ret = {h};
    rep(i, length, sz(str)) {
        ret.push_back(h = h * C + str[i] - pw * str[i-length]);
    }
    return ret;
}

H hashString(string& s){H h{}; for(char c:s) h=h*C+c;return h;}
```

HashInterval.h

Description: Various self-explanatory methods for string hashing.

"Hashing.h"

122649, 12 lines

```
struct HashInterval {
    vector<H> ha, pw;
    HashInterval(string& str) : ha(sz(str)+1), pw(ha) {
        pw[0] = 1;
        rep(i, 0, sz(str))
            ha[i+1] = ha[i] * C + str[i],
            pw[i+1] = pw[i] * C;
    }
    H hashInterval(int a, int b) { // hash [a, b)
        return ha[b] - ha[a] * pw[b - a];
    }
};
```

AhoCorasick-Kactl.h

Description: Aho-Corasick automaton, used for multiple pattern matching. Initialize with AhoCorasick ac(patterns); the automaton start node will be at index 0. find(word) returns for each position the index of the longest word that ends there, or -1 if none. findAll(–, word) finds all words (up to $N\sqrt{N}$ many if no duplicate patterns) that start at each position (shortest first). Duplicate patterns are allowed; empty patterns are not. To find the longest words that start at each position, reverse all input. For large alphabets, split each symbol into chunks, with sentinel bits for symbol boundaries.

Time: construction takes $\mathcal{O}(26N)$, where N = sum of length of patterns. find(x) is $\mathcal{O}(N)$, where N = length of x. findAll is $\mathcal{O}(NM)$.

f35677, 66 lines

```
struct AhoCorasick {
    enum {alpha = 26, first = 'A'}; // change this!
    struct Node {
        // (nmatches is optional)
        int back, next[alpha], start = -1, end = -1, nmatches = 0;
        Node(int v) { memset(next, v, sizeof(next)); }
    };
    vector<Node> N;
    vi backp;
    void insert(string& s, int j) {
        assert(!s.empty());
        int n = 0;
        for (char c : s) {
            int& m = N[n].next[c - first];
            if (m == -1) { n = m = sz(N); N.emplace_back(-1); }
            else n = m;
        }
        if (N[n].end == -1) N[n].start = j;
        backp.push_back(N[n].end);
        N[n].end = j;
        N[n].nmatches++;
    }
    AhoCorasick(vector<string>& pat) : N(1, -1) {
        rep(i, 0, sz(pat)) insert(pat[i], i);
        N[0].back = sz(N);
        N.emplace_back(0);

        queue<int> q;
        for (q.push(0); !q.empty(); q.pop()) {
            int n = q.front(), prev = N[n].back;
            rep(i, 0, alpha) {
                int &ed = N[n].next[i], y = N[prev].next[i];
                if (ed == -1) ed = y;
                else {
                    N[ed].back = y;
                    (N[ed].end == -1 ? N[ed].end : backp[N[ed].start])
                        = N[y].end;
                    N[ed].nmatches += N[y].nmatches;
                    q.push(ed);
                }
            }
        }
    }
    vi find(string word) {
        int n = 0;
        vi res; // ll count = 0;
        for (char c : word) {
            n = N[n].next[c - first];
            res.push_back(N[n].end);
            // count += N[n].nmatches;
        }
        return res;
    }
    vector<vi> findAll(vector<string>& pat, string word) {
        vi r = find(word);
        vector<vi> res(sz(word));
        rep(i, 0, sz(word)) {
```

```
int ind = r[i];
while (ind != -1) {
    res[i - sz(pat[ind]) + 1].push_back(ind);
    ind = backp[ind];
}
}
return res;
}
};
```

LyndonFactorization.h

Description: Computes the Lyndon Factorization of a string. A Lyndon word is a nonempty string that is strictly smaller in lexicographic order than any of its proper suffixes. Returns the starting indices of the Lyndon words in the string.
Time: $\mathcal{O}(n)$

09e827, 12 lines

```
vi duval(string &s) {
    vi ans;
    for(int start = 0; start < sz(s);) {
        int i = start+1, j = start;
        for(; i < sz(s) && s[i] >= s[j]; i++)
            if(s[i] > s[j]) j = start;
            else j++;
        for(int sz = i-j; start + sz <= i; start += sz)
            ans.push_back(start);
    }
    return ans;
}
```

SuffixAutomaton.h

Description: Creates a partial DFA (DAG) that accepts all suffixes, with suffix links. One-to-one map between a path from the root and a substring. len is the longest-length substring ending here. pos is the first index in the string matching here. term is whether this node is a terminal (aka a suffix)
Time: construction takes $\mathcal{O}(N \log K)$, where K = Alphabet Size.

383afe, 27 lines

```
struct st {int len, pos, term, link=-1; map<char, int> next;};
struct SuffixAutomaton {
    vector<st> a;
    SuffixAutomaton(string &str) {
        a.resize(1);
        int last = 0;
        for(auto c : str) {
            int p = last, cur = last = sz(a);
            a.push_back({a[p].len + 1, a[p].len});
            while(p >= 0 && !a[p].next.count(c))
                a[p].next[c] = cur, p = a[p].link;
            if (p == -1) a[cur].link = 0;
            else {
                int q = a[p].next[c];
                if (a[p].len + 1 == a[q].len) a[cur].link = q;
                else {
                    a.push_back({a[p].len+1, a[q].pos, 0, a[q].link, a[q].next});
                    for(; p >= 0 && a[p].next[c] == q; p = a[p].link)
                        a[p].next[c] = sz(a)-1;
                    a[q].link = a[cur].link = sz(a)-1;
                }
            }
        }
        while(last >= 0) a[last].term = 1, last = a[last].link;
    }
};
```

Various (10)

10.1 Intervals

IntervalContainer.h

Description: Add and remove intervals from a set of disjoint intervals. Will merge the added interval with any overlapping intervals in the set when adding. Intervals are [inclusive, exclusive).
Time: $\mathcal{O}(\log N)$

edce47, 23 lines

```
set<pii>::iterator addInterval(set<pii>& is, int L, int R) {
    if (L == R) return is.end();
    auto it = is.lower_bound({L, R}), before = it;
    while (it != is.end() && it->first <= R) {
        R = max(R, it->second);
        before = it = is.erase(it);
    }
    if (it != is.begin() && (--it)->second >= L) {
        L = min(L, it->first);
        R = max(R, it->second);
        is.erase(it);
    }
    return is.insert(before, {L,R});
}
```

```
void removeInterval(set<pii>& is, int L, int R) {
    if (L == R) return;
    auto it = addInterval(is, L, R);
    auto r2 = it->second;
    if (it->first == L) is.erase(it);
    else (int&)it->second = L;
    if (R != r2) is.emplace(R, r2);
}
```

IntervalCover.h

Description: Compute indices of smallest set of intervals covering another interval. Intervals should be [inclusive, exclusive). To support [inclusive, inclusive], change (A) to add || R.empty(). Returns empty set on failure (or if G is empty).
Time: $\mathcal{O}(N \log N)$

9e9d8d, 19 lines

```
template<class T>
vi cover(pair<T, T> G, vector<pair<T, T>> I) {
    vi S(sz(I)), R;
    iota(all(S), 0);
    sort(all(S), [&](int a, int b) { return I[a] < I[b]; });
    T cur = G.first;
    int at = 0;
    while (cur < G.second) { // (A)
        pair<T, int> mx = make_pair(cur, -1);
        while (at < sz(I) && I[S[at]].first <= cur) {
            mx = max(mx, make_pair(I[S[at]].second, S[at]));
            at++;
        }
        if (mx.second == -1) return {};
        cur = mx.first;
        R.push_back(mx.second);
    }
    return R;
}
```

ConstantIntervals.h

Description: Split a monotone function on [from, to) into a minimal set of half-open intervals on which it has the same value. Runs a callback g for each such interval.
Usage: constantIntervals(0, sz(v), [&](int x){return v[x];}, [&](int lo, int hi, T val){...});
Time: $\mathcal{O}(k \log \frac{n}{k})$

753a4c, 19 lines

```
template<class F, class G, class T>
void rec(int from, int to, F& f, G& g, int& i, T& p, T q) {
    if (p == q) return;
    if (from == to) {
        g(i, to, p);
        i = to; p = q;
    } else {
        int mid = (from + to) >> 1;
        rec(from, mid, f, g, i, p, f(mid));
        rec(mid+1, to, f, g, i, p, q);
    }
}

template<class F, class G>
void constantIntervals(int from, int to, F f, G g) {
    if (to <= from) return;
    int i = from; auto p = f(i), q = f(to-1);
    rec(from, to-1, f, g, i, p, q);
    g(i, to, q);
}
```

10.2 Misc. algorithms

TernarySearch.h

Description: Find the smallest i in $[a, b]$ that maximizes $f(i)$, assuming that $f(a) < \dots < f(i) \geq \dots \geq f(b)$. To reverse which of the sides allows non-strict inequalities, change the $<$ marked with (A) to $<=$, and reverse the loop at (B). To minimize f , change it to $>$, also at (B).
Usage: int ind = ternSearch(0,n-1,[&](int i){return a[i];});
Time: $\mathcal{O}(\log(b-a))$

9155b4, 11 lines

```
template<class F>
int ternSearch(int a, int b, F f) {
    assert(a <= b);
    while (b - a >= 5) {
        int mid = (a + b) / 2;
        if (f(mid) < f(mid+1)) a = mid; // (A)
        else b = mid+1;
    }
    rep(i,a+1,b+1) if (f(a) < f(i)) a = i; // (B)
    return a;
}
```

LIS.h

Description: Compute indices for the longest increasing subsequence.
Time: $\mathcal{O}(N \log N)$

2932a0, 17 lines

```
template<class I> vi lis(const vector<I>& S) {
    if (S.empty()) return {};
    vi prev(sz(S));
    typedef pair<I, int> p;
    vector<p> res;
    rep(i,0,sz(S)) {
        // change 0 -> i for longest non-decreasing subsequence
        auto it = lower_bound(all(res), p{S[i], 0});
        if (it == res.end()) res.emplace_back(), it = res.end()-1;
        *it = {S[i], i};
        prev[i] = it == res.begin() ? 0 : (it-1)->second;
    }
    int L = sz(res), cur = res.back().second;
    vi ans(L);
    while (L--) ans[L] = cur, cur = prev[cur];
    return ans;
}
```

FastKnapsack.h
Description: Given N non-negative integer weights w and a non-negative target t, computes the maximum S <= t such that S is the sum of some subset of the weights.
Time: $\mathcal{O}(N \max(w_i))$

```
int knapsack(vi w, int t) {
    int a = 0, b = 0, x;
    while (b < sz(w) && a + w[b] <= t) a += w[b++];
    if (b == sz(w)) return a;
    int m = *max_element(all(w));
    vi u, v(2*m, -1);
    v[a+m-t] = b;
    rep(i,b,sz(w)) {
        u = v;
        rep(x,0,m) v[x+w[i]] = max(v[x+w[i]], u[x]);
        for (x = 2*m; --x > m;) rep(j, max(0,u[x]), v[x])
            v[x-w[j]] = max(v[x-w[j]], j);
    }
    for (a = t; v[a+m-t] < 0; a--) ;
    return a;
}
```

10.3 Dynamic programming

KnuthDP.h
Description: When doing DP on intervals: $a[i][j] = \min_{i < k < j} (a[i][k] + a[k][j]) + f(i, j)$, where the (minimal) optimal k increases with both i and j , one can solve intervals in increasing order of length, and search $k = p[i][j]$ for $a[i][j]$ only between $p[i][j - 1]$ and $p[i + 1][j]$. This is known as Knuth DP. Sufficient criteria for this are if $f(b, c) \leq f(a, d)$ and $f(a, c) + f(b, d) \leq f(a, d) + f(b, c)$ for all $a \leq b \leq c \leq d$. Consider also: LineContainer (ch. Data structures), monotone queues, ternary search.
Time: $\mathcal{O}(N^2)$

DivideAndConquerDP.h
Description: Given $a[i] = \min_{lo(i) \leq k < hi(i)} (f(i, k))$ where the (minimal) optimal k increases with i , computes $a[i]$ for $i = L..R - 1$.
Time: $\mathcal{O}((N + (hi - lo)) \log N)$

```
struct DP { // Modify at will:
    int lo(int ind) { return 0; }
    int hi(int ind) { return ind; }
    ll f(int ind, int k) { return dp[ind][k]; }
    void store(int ind, int k, ll v) { res[ind] = pii(k, v); }

    void rec(int L, int R, int LO, int HI) {
        if (L >= R) return;
        int mid = (L + R) >> 1;
        pair<ll, int> best(LLONG_MAX, LO);
        rep(k, max(LO, lo(mid)), min(HI, hi(mid)))
            best = min(best, make_pair(f(mid, k), k));
        store(mid, best.second, best.first);
        rec(L, mid, LO, best.second+1);
        rec(mid+1, R, best.second, HI);
    }
    void solve(int L, int R) { rec(L, R, INT_MIN, INT_MAX); }
};
```

10.4 Debugging tricks

- feenableexcept (29); kills the program on NaNs (1), 0-divs (4), infinities (8) and denormals (16).

10.5 Optimization tricks

__builtin_ia32_ldmxcsr(40896); disables denormals (which make floats 20x slower near their minimum value).

10.5.1 Bit hacks

- x & -x is the least bit in x.
- for (int x = m; x;) { --x &= m; ... } loops over all subset masks of m (except m itself).
- c = x&-x, r = x+c; (((r^x) >> 2)/c) | r is the next number after x with the same number of bits set.
- rep(b,0,K) rep(i,0,(1 << K)) if (i & 1 << b) D[i] += D[i^(1 << b)]; computes all sums of subsets.

10.5.2 Pragmas

- #pragma GCC optimize ("Ofast") will make GCC auto-vectorize loops and optimizes floating points better.
- #pragma GCC target ("avx2") can double performance of vectorized code, but causes crashes on old machines.
- #pragma GCC optimize ("trapv") kills the program on integer overflows (but is really slow).

FastMod.h
Description: Compute $a \% b$ about 5 times faster than usual, where b is constant but not known at compile time. Returns a value congruent to a (mod b) in the range $[0, 2b)$.

```
typedef unsigned long long ull;
struct FastMod {
    ull b, m;
    FastMod(ull b) : b(b), m(-1ULL / b) {}
    ull reduce(ull a) { // a % b + (0 or b)
        return a - (ull)((__uint128_t(m) * a) >> 64) * b;
    }
};
```

FastInput.h
Description: Read an integer from stdin. Usage requires your program to pipe in input from file.
Usage: ./a.out < input.txt
Time: About 5x as fast as cin/scanf.

```
inline char gc() { // like getchar()
    static char buf[1 << 16];
    static size_t bc, be;
    if (bc >= be) {
        buf[0] = 0, bc = 0;
        be = fread(buf, 1, sizeof(buf), stdin);
    }
    return buf[bc++]; // returns 0 on EOF
}

int readInt() {
    int a, c;
    while ((a = gc()) < 40);
```

```
if (a == '-') return -readInt();
while ((c = gc()) >= 48) a = a * 10 + c - 48;
return a - 48;
}
```

BumpAllocator.h
Description: When you need to dynamically allocate many objects and don't care about freeing them. "new X" otherwise has an overhead of something like 0.05us + 16 bytes per allocation.

```
// Either globally or in a single class:
static char buf[450 << 20];
void* operator new(size_t s) {
    static size_t i = sizeof buf;
    assert(s < i);
    return (void*)&buf[i -= s];
}
void operator delete(void*) {}
```

SmallPtr.h
Description: A 32-bit pointer that points into BumpAllocator memory.
"BumpAllocator.h"
template<class T> struct ptr {
 unsigned ind;
 ptr(T* p = 0) : ind(p ? unsigned((char*)p - buf) : 0) {
 assert(ind < sizeof buf);
 }
 T& operator*() const { return *(T*)(buf + ind); }
 T* operator->() const { return &*this; }
 T& operator[](int a) const { return (&this)[a]; }
 explicit operator bool() const { return ind; }
};

BumpAllocatorSTL.h
Description: BumpAllocator for STL containers.
Usage: vector<vector<int, small<int>>>> ed(N);

```
char buf[450 << 20] alignas(16);
size_t buf_ind = sizeof buf;

template<class T> struct small {
    typedef T value_type;
    small() {}
    template<class U> small(const U&) {}
    T* allocate(size_t n) {
        buf_ind -= n * sizeof(T);
        buf_ind &= 0 - alignof(T);
        return (T*)(buf + buf_ind);
    }
    void deallocate(T*, size_t) {}
};
```

Unrolling.h
#define F {...; ++i;}
int i = from;
while (i&3 && i < to) F // for alignment, if needed
while (i + 4 <= to) { F F F F }
while (i < to) F