

PlatformIO CLI Cheat Sheet

Essential commands for embedded development • PlatformIO Core 6.x

PROJECT SETUP

<code>pio project init</code>	Init project in current dir
<code>pio project init --board esp32dev</code>	Init with specific board
<code>pio project init --ide vscode</code>	Init with IDE integration
<code>pio project config</code>	Show project config
<code>pio project metadata</code>	Dump project metadata

BUILD & UPLOAD

<code>pio run</code>	Build all environments
<code>pio run -e esp32dev</code>	Build specific environment
<code>pio run -t upload</code>	Build + upload firmware
<code>pio run -t clean</code>	Clean build files
<code>pio run -t uploadfs</code>	Upload filesystem image

SERIAL MONITOR

<code>pio device monitor</code>	Open serial monitor
<code>pio device monitor -b 115200</code>	Set baud rate
<code>pio device monitor -p /dev/cu.usbx</code>	Specify port (macOS)
<code>pio device monitor --filter log2file</code>	Log output to file
<code>pio device list</code>	List connected devices

LIBRARY MANAGEMENT

<code>pio lib install "WiFi"</code>	Install library by name
<code>pio lib install 13</code>	Install by registry ID
<code>pio lib uninstall "WiFi"</code>	Remove a library
<code>pio lib update</code>	Update all libraries
<code>pio lib search "sensor"</code>	Search library registry
<code>pio lib list</code>	List installed libs

BOARDS & PLATFORMS

<code>pio boards</code>	List all supported boards
<code>pio boards "esp32"</code>	Search for boards
<code>pio platform list</code>	List installed platforms
<code>pio platform install espressif32</code>	Install a platform
<code>pio platform update</code>	Update all platforms

DEBUGGING & TESTING

<code>pio debug</code>	Start debugger
<code>pio test</code>	Run unit tests
<code>pio test -e native</code>	Run tests on native
<code>pio check</code>	Static code analysis
<code>pio run -v</code>	Verbose build output

PLATFORMIO.INI — CONFIGURATION EXAMPLE

```
; Common settings for all environments
[platformio]
default_envs = esp32dev

[env:esp32dev]
platform = espressif32
```

```
board = esp32dev
framework = arduino
monitor_speed = 115200
lib_deps =
    adafruit/Adafruit_NeoPixel@^1.12
    bblanchon/ArduinoJson@^7.0
build_flags = -DCORE_DEBUG_LEVEL=3
```

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Advanced commands, flags, and workflow tips

SYSTEM & UPDATES

<code>pio --version</code>	Show PlatformIO version
<code>pio upgrade</code>	Upgrade PlatformIO Core
<code>pio system info</code>	System environment info
<code>pio system prune</code>	Remove unused data
<code>pio settings get</code>	Show all settings
<code>pio settings set auto_update_libraries No</code>	Disable auto-update

REMOTE DEVELOPMENT

<code>pio remote agent start</code>	Start remote agent
<code>pio remote run -t upload</code>	Upload to remote device
<code>pio remote device monitor</code>	Monitor remote serial
<code>pio remote device list</code>	List remote devices

USEFUL FLAGS

<code>-e <env></code>	Target specific environment
<code>-d <dir></code>	Specify project directory
<code>-v</code>	Verbose output
<code>-t <target></code>	Run specific target
<code>--upload-port <port></code>	Specify upload port
<code>-j <N></code>	Parallel build jobs
<code>--no-ansi</code>	Disable colored output

BUILD TARGETS (-T)

<code>upload</code>	Build & flash firmware
<code>clean</code>	Clean build artifacts
<code>uploadfs</code>	Upload SPIFFS/LittleFS
<code>erase</code>	Erase flash memory
<code>size</code>	Show firmware size
<code>monitor</code>	Build + upload + monitor

COMMON PLATFORMIO.INI OPTIONS

<code>platform</code>	Dev platform (espressif32, atmelavr...)
<code>board</code>	Target board ID
<code>framework</code>	arduino, espidf, mbed...
<code>lib_deps</code>	Library dependencies
<code>build_flags</code>	Compiler defines & flags
<code>monitor_speed</code>	Serial baud rate
<code>upload_port</code>	USB port for uploading
<code>upload_speed</code>	Upload baud rate
<code>board_build.partitions</code>	Custom partition table
<code>build_src_filter</code>	Include/exclude src files

COMMON WORKFLOWS

<code>build + upload + monitor</code>
<code>pio run -t upload && pio device monitor</code>
Or use: <code>pio run -t upload -t monitor</code>

<code>full clean rebuild</code>
<code>pio run -t clean && pio run</code>

Useful when builds are acting strange

CHECK FLASH USAGE

`pio run -t size`

Shows RAM and Flash usage breakdown

FIND YOUR BOARD ID

`pio boards "nano"`

Search by name, MCU, or framework

SERIAL MONITOR SHORTCUTS

Ctrl+J Quit monitor

Ctrl+T Menu / command mode

Ctrl+T → Ctrl+H Show help

Ctrl+T → Ctrl+D Toggle DTR

Ctrl+T → Ctrl+R Toggle RTS

Ctrl+T → Ctrl+P Change port

