21/03/23

1) 
$$\vec{V}_{1} = (1,0,1)$$
,  $\vec{V}_{2} = (0,1,0)$ ,  $\vec{V}_{3} = (1,1,2) \in \mathbb{R}^{3}$ 

Determinate be projectione entogenale  $\vec{V}_{1}$  di  $\vec{V}_{1}$  and phono the contient  $\vec{V}_{2}$  e  $\vec{V}_{3}$ 
 $\vec{V}_{2} \times \vec{V}_{3} = \begin{pmatrix} \delta & 0 & 0 \\ \sqrt{5} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & 0 & 0 \\ \sqrt{5} & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ \delta & \delta & \delta \\ \delta & \delta & \delta \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ \delta & \delta & \delta \\ \delta & \delta & \delta \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ \delta & \delta & \delta \\ \delta & \delta & \delta \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ \delta & \delta & \delta \\ \delta & \delta & \delta \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ \delta & \delta & \delta \\ \delta & \delta & \delta \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ \delta & \delta & \delta \\ \delta & \delta & \delta \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ \delta & \delta & \delta \\ \delta & \delta & \delta \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\ \delta & \delta & \delta \\ \delta & \delta & \delta \end{pmatrix} = \begin{pmatrix} \delta & \delta & \delta \\$ 

2) Stabilire QUALITRA I SEGUENTI SOTIOINDIEMI DI R3 E'UN SOTIOSPAZIO VETTORIALE DI TR3 V E W

a) 
$$W_1 = \{ (x, y, z) \in \mathbb{R}^3 : 2x + 3y - z = 0 \}$$

- $(I) \forall w_1, w_2 \in W_1, \forall c \in \mathbb{R} \Rightarrow cw_1 w_2 \in W_1$
- $(I) \cdot (0,0,0) \in W_1?$   $2 \cdot 0 + 3 \cdot 0 0 = 0$ 
  - .  $W_1 = (X_1, y_1, z_1)$   $W_2 = (X_2, y_2, z_2)$   $\in W_1$  (IPOTEST)

    DD:  $W_1 + W_2 \in W_1$   $(X_1 + X_2, y_1 + y_2, z_1 + z_2) \in W_1$

$$2(x_1+x_2)+3(y_1+y_2)-(z_1+z_2)=0?$$

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$$W_1 = (-3, -2)$$
  $W_2 = (5, 1)$   
 $W_1 \in W$  perche'  $-3 \cdot (-2) = 6 > 0$   
 $W_2 \in W$  perche'  $5 \cdot 1 = 5 > 0$   
 $W_1 + W_2 = (-3, -2) + (5, 1) = (2, -2) \Rightarrow 2 \cdot (-2) = 4 > 0$ 

$$= \{ (x,y) \in \mathbb{R}^2 : x = 0, y = 0 \} = \{ \overrightarrow{0} \}$$



- We'sottospazob

Vettoriale di R2=RxR

R

- y=1

R

$$\times 10^{10} \text{ W} = (x_1 y_1 z_1) \in \mathbb{R}^3 : (x - y_1 + 3z_1)^2 + (2x - y_1 + z_1)^2 = 0$$

- DATI I SEGUENTI SOTIOINSIEMI DI TR3 DIRE QUALI FRA QUESTI SONO RISPETILAMENTE
  - . INSIEME DI GENERATORI DI R3
  - OI R3 LINEARMENTE MOI PENDENTE lin. indip.
  - · UNA BASE DI R3

a) 
$$S_1 = \{(2,1,0), (\frac{1}{2},1,1), (0,1,0)\}$$

$$(x, y, z) = x(2,1,0) + \beta(\frac{1}{2},1,1) + x(0,1,0)$$

$$\begin{cases} x = 2\alpha + \frac{1}{2}\beta \\ y = \alpha + \beta + \delta \end{cases} \Leftrightarrow \begin{cases} \alpha = \frac{1}{2}x - \frac{1}{4}z \\ \delta = y - \alpha - \beta \end{cases}$$

$$\beta = z$$

 $\rightarrow$  sono generator di  $\mathbb{R}^3$ 

• 
$$(0,0,0) = \alpha(2,1,0) + \beta(\frac{1}{2},1,1) + 8(0,1,0)$$
  
•  $0 = 2\alpha + \beta$   
•  $0 = \alpha + \beta + \beta$   
•  $\beta = 0$   
•  $\beta = 0$   
•  $\beta = 0$   
•  $\beta = 0$ 

=> lin. indip.

. Creneratori + liu. inolip  $\implies$  lose di  $\mathbb{R}^3$ 

b) 
$$S_8 = \{ (1,3,1), (1,1,1), (1,-1,1) \}$$

 $(x_i, y_j, z) = \lambda(1, 3, \lambda) + \beta(1, 1, 1) + \delta(1, -1, 1)$ 

$$\begin{cases}
x = 2 + 3 + 8 \\
y = 32 + 3 + 8
\end{cases}$$

$$\begin{cases}
x = 2
\end{cases}$$

$$y = 32 + 3 + 8
\end{cases}$$

$$\begin{cases}
x = 2
\end{cases}$$

$$x = 2
\end{cases}$$

$$\begin{cases}
x = 2
\end{cases}$$

$$x = 2
\end{cases}$$

$$\begin{cases}
x = 2
\end{cases}$$

$$x = 2
\end{cases}$$

$$\begin{cases}
x = 2
\end{cases}$$

$$x = 2
\end{cases}$$

$$\begin{cases}
x = 2
\end{cases}$$

$$x = 2
\end{cases}$$

$$\begin{cases}
x = 2
\end{cases}$$

$$x =$$

- NON sono generatori

X I Vedere se sons linear. iudipendenti

## 22/03/23

## SPAZI VETTORIAL

(1) SIA W= { (x-y+2, ex+y-42, x-2): x,y,2 & R} e sottos perio di R3

a) THOUNDE BASE & DIMENSIONE DI W

 $W = \left\{ (X, 2X, X) + (-y, y, 0) + (2, -42, -2) : X, y, 2 \in \mathbb{R} \right\}$   $= \left\{ X(1,2,1) + y(-1, 1, 0) + 2(1, -4, -1) : X, y, 2 \in \mathbb{R} \right\} =$   $= (1,2,1), (-1,1,0), (1,-4,-1) \right\}$ 

 $(0,0,0) = 2(1,7,1) + \beta(-1,1,0) + 8(1,-4,-1)$ 

$$\begin{cases}
0 = \alpha - \beta + 8 \\
0 = 2\alpha + \beta - 48
\end{cases}$$

$$\begin{cases}
\beta = \alpha + 8 = 28 \\
\alpha = 8
\end{cases}$$

$$\Rightarrow \begin{cases} \alpha = \chi \\ \beta = 2 \ell \end{cases} \Rightarrow (\chi, 2\chi, \chi) \Rightarrow (1, 2, 1)$$

Ž a; v: = 0 → a; = 0 ∀ i = 1, ..., m

= I VETORI NON SONO LIN. INDIP

$$\begin{pmatrix} 0,0,0 \end{pmatrix} = \mathcal{A}(1,2,1) + \mathcal{B}(-1,1,0)$$

$$\begin{cases} 0 = \mathcal{A} - \mathcal{B} \\ 0 = 2\mathcal{A} + \mathcal{B} \end{cases} \Rightarrow \begin{cases} 0 = 3\mathcal{B} \\ 0 = 3\mathcal{B} \end{cases} \Rightarrow \begin{cases} 0 = 0 \\ 0 = 0 \end{cases} \Rightarrow \begin{cases} 0 = 0 \end{cases} \Rightarrow \begin{cases} 0 = 0 \\ 0 = 0 \end{cases} \Rightarrow \begin{cases} 0 = 0$$

 $\Rightarrow$  (1,2,1) e (-1,1,0) FOCTANO UNA BASE PER W  $\Rightarrow$  dimu(W) = 2

PER W => dim(W) = 2 b) VERIFICARE CHE (2,-S,-1) & W e TROVARE LE COORDINATE DEL VETTORE RISPETTO ALLA BASE TROVATA

(2) SIANO DATI I SEGUENTI SOTIOSPAZI DI R3  $W_1 = \{ (x, y, z) \in \mathbb{R}^3 : x + z = 0, x - y = 0 \}$  $W_2 = \{(x, y, z) \in \mathbb{R}^3 : x - 2y = 0\}$ 

a) DETERMINARE UNA BASE PER WI E WZ

$$W_{1} = \begin{cases} (x,y,\xi) \in \mathbb{R}^{3} \mid x = -\xi, x = y \end{cases} = (x,y,\xi)$$

$$= [(1,1,-1)] \qquad \qquad = (x,y,\xi)$$

$$(x,x,-x)$$

$$(x,x,-x)$$

= [(1,1,-1)] = [(1,1,-1)]  $W_{2} = \{(1,1,-1)\}$   $= \{(1,1,-1)\}$   $= \{(1,1,-1)\}$   $\times (1,1,-1)$   $\times (1,1,-1)$   $= \{(1,1,-1)\}$   $\times (1,1,-1)$   $= \{(1,1,-1)\}$   $\times (1,1,-1)$   $= \{(1,1,-1)\}$   $= \{(1,$ 

$$(2y_1y_1z) = (2y_1y_10) + (0,0,2) =$$
  
=  $y(2,1,0) + z(0,0,1)$ 

(RIWROD) SISTERM DI GENERATORI => BASE LIN. INDIP

$$\begin{cases}
0 = 2a \\
0 = b
\end{cases} = \begin{cases}
a = 0 = \sum_{b=0}^{a=0} |a = 0| = \sum_{b=0}^{a=0} |a = 0$$

b) DETERTINARE WI + WZ

 $W_1 + W_2 = [(1, 1, -1), (2, 1, 0), (0, 0, 1)]$ 

$$\dim(W_1 + W_2) = 3$$

$$W_1 + W_2 = \mathbb{R}^3$$

$$W_1 + W_2 = \mathbb{R}^3$$

TEORETHA SIA WEV

- . dim W = dim V
- dim W = dim V = V

C) STABILIRE SE E' SOMMA DIRETTA

(Ricords) W1, Wz = V, W1 1 Wz = 303 & W1+Wz = V ⇒ V = W, € W2 SOKULS DIRETA

RELAZIONE OI GRASSMAUN

WI, W, IV DI DIMENSIONE FILLIFA.

dim (W1 + W2) = dim W1 + dim W2 - dim (W1 1) W2)

 $3 = 1 + 2 - dim(W_1 \cap W_2)$ 

Edim (W1 A W2) = 0

 $\Rightarrow$   $W_1 + W_2 = W_1 \oplus W_2 = \mathbb{R}^3$ 

(4) S C R3 DETERMINARE SE S E' UN INSTEME DI GENERATORI, LIN. INDP, BASE?

 $S = \{ (0,0,1), (2, \frac{1}{2}, 0), (2, \frac{1}{2}, 1), (2, \frac{1}{2}, 2) \}$ 

 $(x, y, z) = d(0, 0, 1) + \beta(z, \frac{1}{2}, 0) + \delta(z, \frac{1}{2}, 1) + \delta(z, \frac{1}{2}, z)$ 

 $\begin{cases} x = 4y \\ y = \frac{1}{2} (\beta + y + \delta) \end{cases}$ 

=> 1 VETTORI DNO DEL TIPO (4y, y, Z) => NON GENERA TUTTO R3.