

An Introduction to Occupancy Models with Collections Data

JT Miller University of Florida









Background: Species Distribution Models

Assumes that areas w/no detections are less suitable.

- Presence Only Data: Presence = More habitable
 - Flexibility of these model is limited
 - Subject to Biased Sampling, Detection Unknown
 - Niche Conservation (long-term modeling)

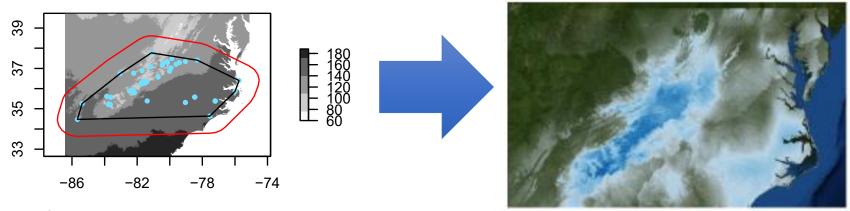


Figure from Gaynor et al. 2018

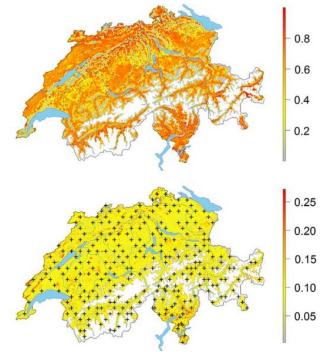
- 1) Presence only Data
- 2) 'Presence/Absence' Data
- 3) 'Presence/Absence' Data replicated over time
- 4) Count Data

ENMs

1) Presence only Data

2) 'Presence/Absence' Data

- 3) 'Presence/Absence' Data replicated over time
- 4) Count Data ← N-Mixture Models



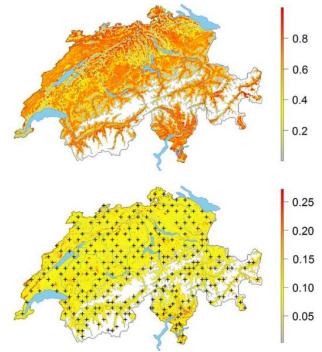
Occupancy Models (1/0)

Occupancy Modeling with replicates to model intensity Kery & Royle 2016

ENMs

- 1) Presence only Data
- 2) 'Presence/Absence' Data
- 3) 'Presence/Absence' Data replicated over time
- 4) Count Data ← N-Mixture Models

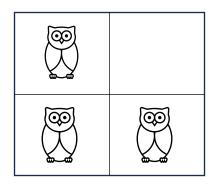
More Data Rich = Access To More Modeling Methods that allow finer inference



Occupancy Models (1/0)

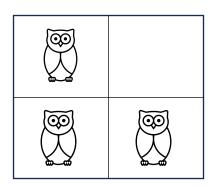
Occupancy Modeling with replicates to model intensity Kery & Royle 2016

 Goal: Estimate the probability that a species is present in a given site, while accounting for detection error



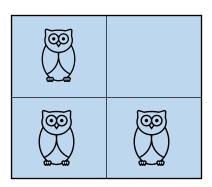
```
psi z y1 y2 y3
[1,] 0.05 0 0 0 0
[2,] 0.05 0 0 0 0
[3,] 0.07 0 0 0 0
[4,] 0.07 1 0 0 0
[5,] 0.07 0 0 0 0
[6,] 0.08 0 0 0 0
psi z y1 y2 y3
[95,] 0.92 1 0 1 1
[96,] 0.92 1 1 0 0
[97,] 0.93 1 1 0 1
[98,] 0.94 1 1 0 0
[99,] 0.94 1 0 1 0
[100,] 0.95 1 0 0 1
```

- Goal: Estimate the probability that a species is present in a given site, while accounting for detection error
- Requires "Presence/Absence" more accurately "Detection/NonDetection" data.



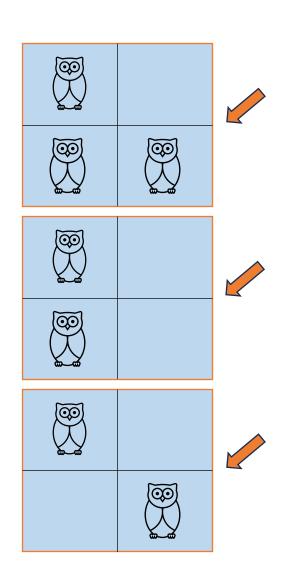
```
psi z y1 y2 y3
[1,] 0.05 0 0 0 0
[2,] 0.05 0 0 0 0
[3,] 0.07 0 0 0 0
[4,] 0.07 1 0 0 0
[5,] 0.07 0 0 0 0
[6,] 0.08 0 0 0 0
psi z y1 y2 y3
[95,] 0.92 1 0 1 1
[96,] 0.92 1 1 0 0
[97,] 0.93 1 1 0 1
[98,] 0.94 1 1 0 0
[99,] 0.94 1 0 1 0
[100,] 0.95 1 0 0 1
```

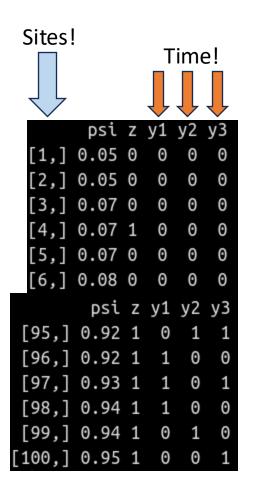
- Goal: Estimate the probability that a species is present in a given site, while accounting for detection error
- Requires "Presence/Absence" or more accurately, "Detection/NonDetection" data.
- Replicated Across Sites



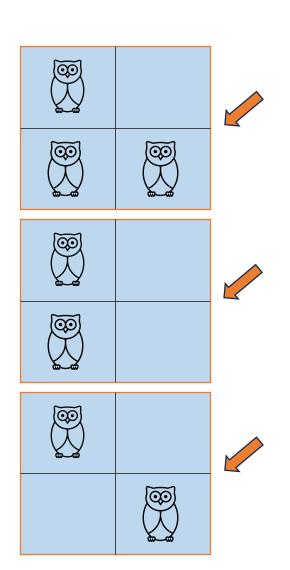
```
Sites!
       psi z y1 y2 y3
 [1,] 0.05 0 0 0 0
 [2,] 0.05 0 0 0 0
 [3,] 0.07 0 0 0
 [4,] 0.07 1 0 0 0
 [5,] 0.07 0 0
 [6,] 0.08 0 0 0 0
       psi z y1 y2 y3
 [95,] 0.92 1 0 1
[96,] 0.92 1 1
[97,] 0.93 1 1
[98,] 0.94 1
[99,] 0.94 1 0
[100,] 0.95 1 0 0
```

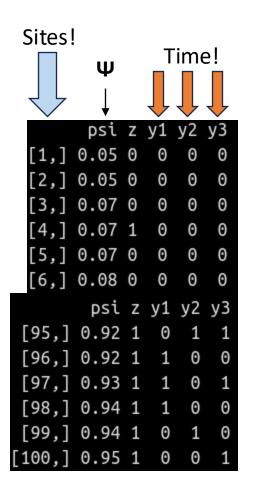
- Goal: Estimate the probability that a species is present in a given site, while accounting for detection error
- Requires "Presence/Absence" or more accurately, "Detection/NonDetection" data.
- Replicated Across Sites
- Replicated Across Time





- Goal: Estimate the probability that a species is present in a given site, while accounting for detection error
- Requires "Presence/Absence" or more accurately, "Detection/NonDetection" data.
- Replicated Across Sites
- Replicated Across Time
- Helps determine our uncertainty in the probability of detection





Detection Probability Can Be Quantified

- The aim of these occupancy models are to quantify true occurrence, by accounting for detection complexities
- NonDetections Namely
- Also False Detections if included



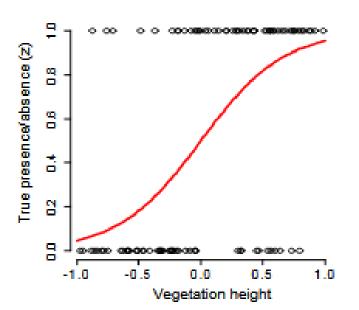


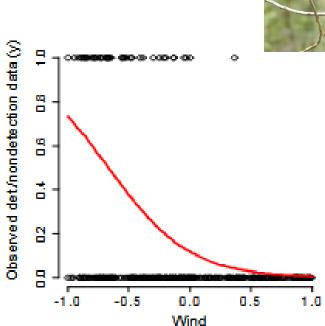




Covariates Can Be Added to the Model

- Covariates (things that we think may affect our detection or the P/A of the organism) can also be added to these models
- Say vegetation height (+) and wind speed (-)











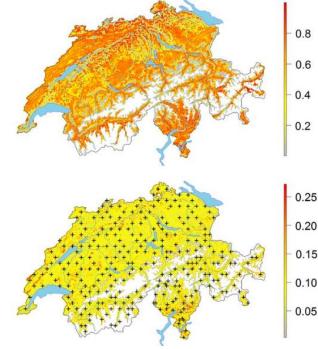


Kery & Royle 2016 Simulation Unmarked

ENMs + Occupancy Models?*

Occupancy Models (1/0)

- 1) Presence only Data
- 2) 'Presence/Absence' Data
- 3) 'Presence/Absence' Data replicated over time
- 4) Count Data ← N-Mixture Models



Occupancy Modeling with replicates to model intensity Kery & Royle 2016

Data

- Occupancy can be measured under certain conditions with museum/incidental data
- Provides a new framework for studying Global Change and Biodiversity across unprecedented scales in both time & space

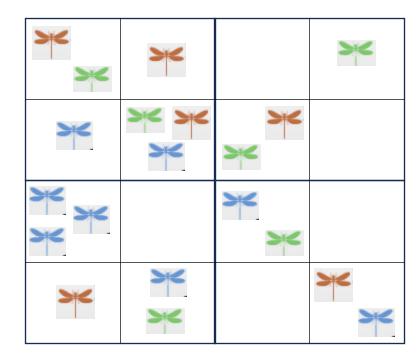


are unavailable.

global change, hierarchical model, museum specimens, occupancy-detection models

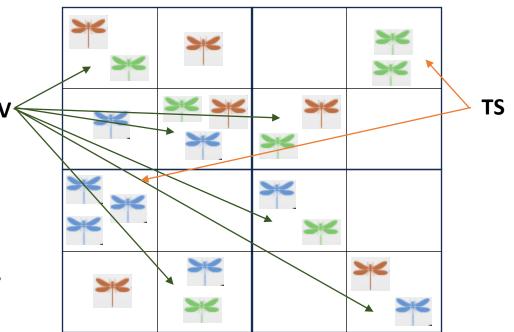
 Simulations with specimen/incidental based data suggests that we can reach the gold standard of correctly estimating the probability of detection by using community level observations, if they meet a certain standard

- Estimate Community Visits vs Target Sampling events. 50% safest, 25% can work with many temporal bins
- Restrict Analyses to only those places and times where collecting is known or likely to have occurred.
 Don't model all species at all sites/time intervals
- Infer non-detections from community (multispecies) visit data only, do not infer absence everywhere
- Split time across 'Occupancy Intervals', the more intervals the better (provided that you check how visit and detection probability changes in these intervals)



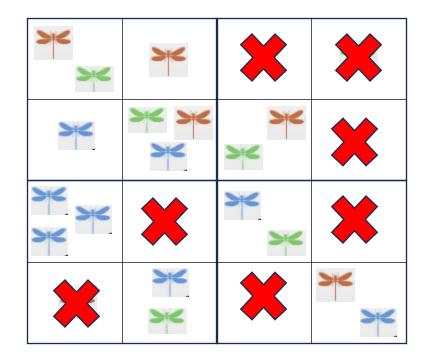
 Simulations with specimen/incidental based data suggests that we can reach the gold standard of correctly estimating the probability of detection by using community level observations, if they meet a certain standard

- Estimate **Community Visits** vs **Target Sampling** events. 50% safest, 25% can work with many temporal bins
- Restrict Analyses to only those places and times where collecting is known or likely to have occurred.
 Don't model all species at all sites/time intervals
- Infer non-detections from community (multispecies) visit data only, do not infer absence everywhere
- Split time across 'Occupancy Intervals', the more intervals the better (provided that you check how visit and detection probability changes in these intervals)



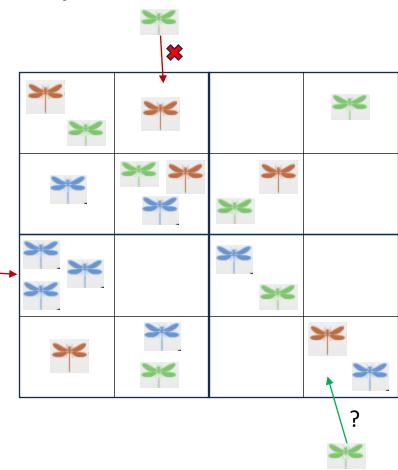
 Simulations with specimen/incidental based data suggests that we can reach the gold standard of correctly estimating the probability of detection by using community level observations, if they meet a certain standard

- Estimate Community Visits vs Target Sampling events. 50% safest, 25% can work with many temporal bins
- Restrict Analyses to only those places and times where collecting is known or likely to have occurred.
 Don't model all species at all sites/time intervals
- Infer non-detections from community (multispecies) visit data only, do not infer absence everywhere
- Split time across 'Occupancy Intervals', the more intervals the better (provided that you check how visit and detection probability changes in these intervals)



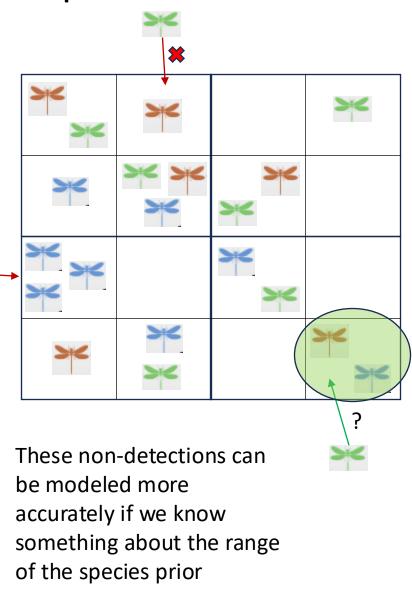
 Simulations with specimen/incidental based data suggests that we can reach the gold standard of correctly estimating the probability of detection by using community level observations, if they meet a certain standard

- Estimate Community Visits vs Target Sampling events. 50% safest, 25% can work with many temporal bins
- Restrict Analyses to only those places and times where collecting is known or likely to have occurred.
 Don't model all species at all sites/time intervals
- Infer non-detections from community (multispecies) visit data only, do not infer absence everywhere
- Split time across 'Occupancy Intervals', the more intervals the better (provided that you check how visit and detection probability changes in these intervals)



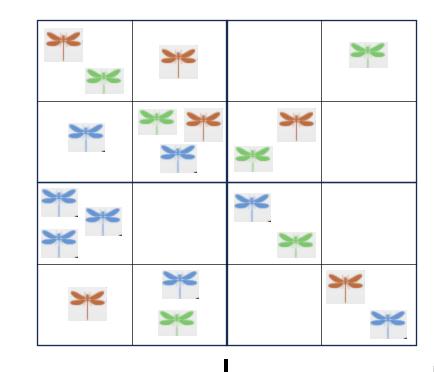
 Simulations with specimen/incidental based data suggests that we can reach the gold standard of correctly estimating the probability of detection by using community level observations, if they meet a certain standard

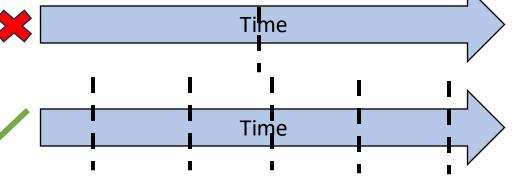
- Estimate Community Visits vs Target Sampling events. 50% safest, 25% can work with many temporal bins
- Restrict Analyses to only those places and times where collecting is known or likely to have occurred.
 Don't model all species at all sites/time intervals
- Infer non-detections from community (multispecies) visit data only, do not infer absence everywhere
- Split time across 'Occupancy Intervals', the more intervals the better (provided that you check how visit and detection probability changes in these intervals)



 Simulations with specimen/incidental based data suggests that we can reach the gold standard of correctly estimating the probability of detection by using community level observations, if they meet a certain standard

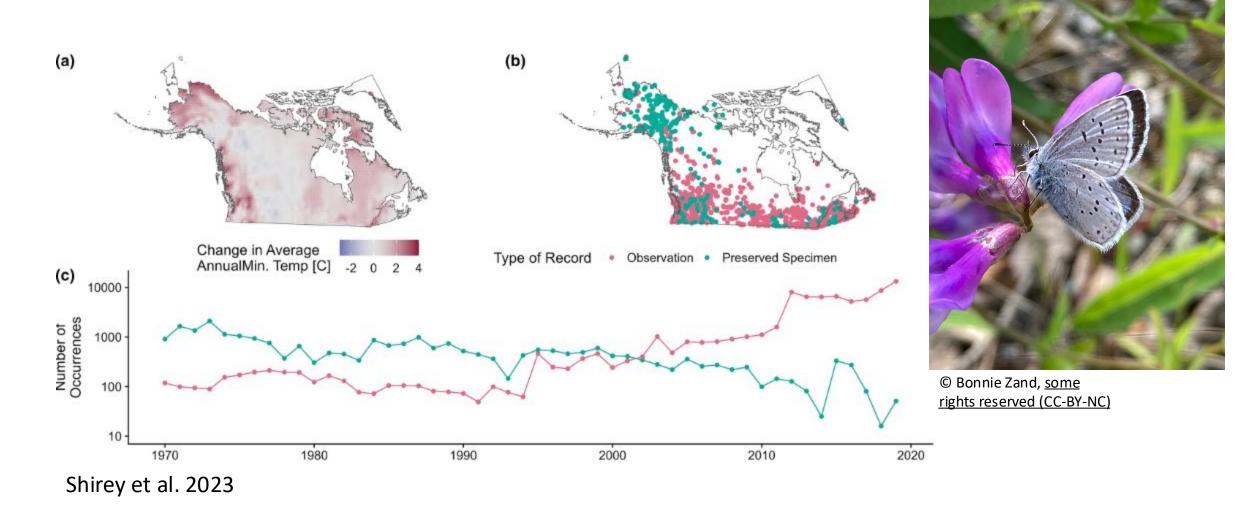
- Estimate Community Visits vs Target Sampling events. 50% safest, 25% can work with many temporal bins
- Restrict Analyses to only those places and times where collecting is known or likely to have occurred. Don't model all species at all sites/time intervals
- Infer non-detections from community (multispecies) visit data only, do not infer absence everywhere
- Split time across 'Occupancy Intervals', the more intervals the better (provided that you check how visit and detection probability changes in these intervals)





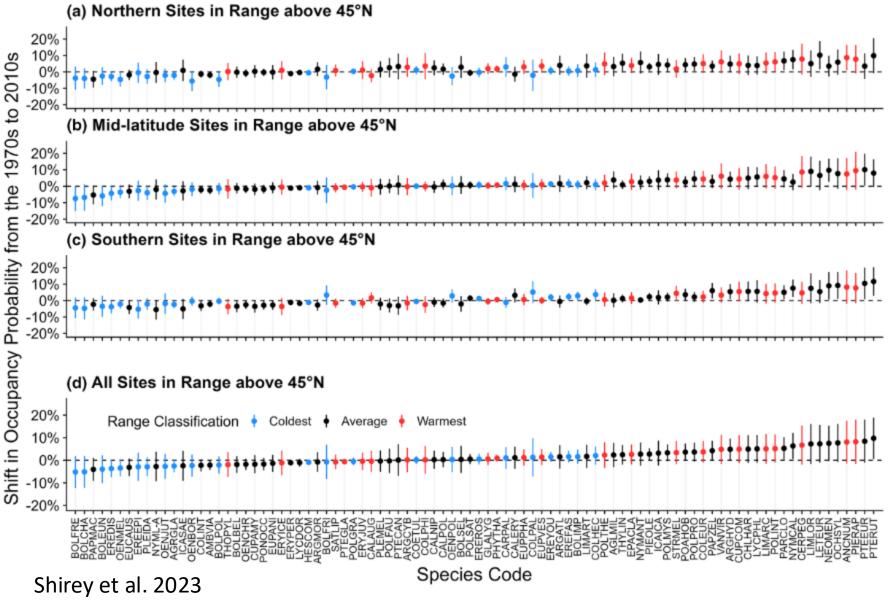
Multi-Species Occupancy Models: Case-study

with Arctic or Boreal Butterflies



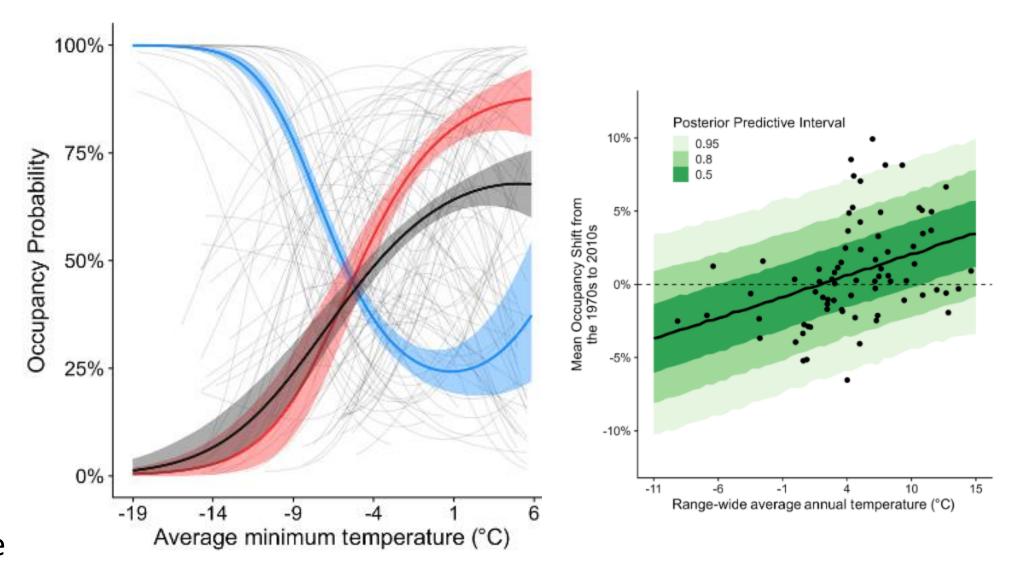
Multi-Species Occupancy Models: Case-study

Used Species
 Traits &
 Historical
 Temperature
 data as
 covariates in
 the model



Multi-Species Occupancy Models: Case-study

- Used Species Traits & Historical Temperature data as covariates in the model
- Range wide average for species is the best predictor for occupancy increase or decrease
- "winners & losers" of climate change



So much to do!

- Occupancy modeling is generally rarer in plants than animals, and has yet to be published with this presenceonly approach
- Endless amount of covariates & hypotheses to test in both what determines detection, and what influences occupancy of species
- Species Ranges (SDMs) are highly recommended.



© Michelle Orcutt, <u>some rights</u> reserved (CC-BY)



(c) Greg Lasley – some rights reserved (CC BY-NC)



© Bonnie Zand, <u>some rights reserved (CC-BY-NC)</u>