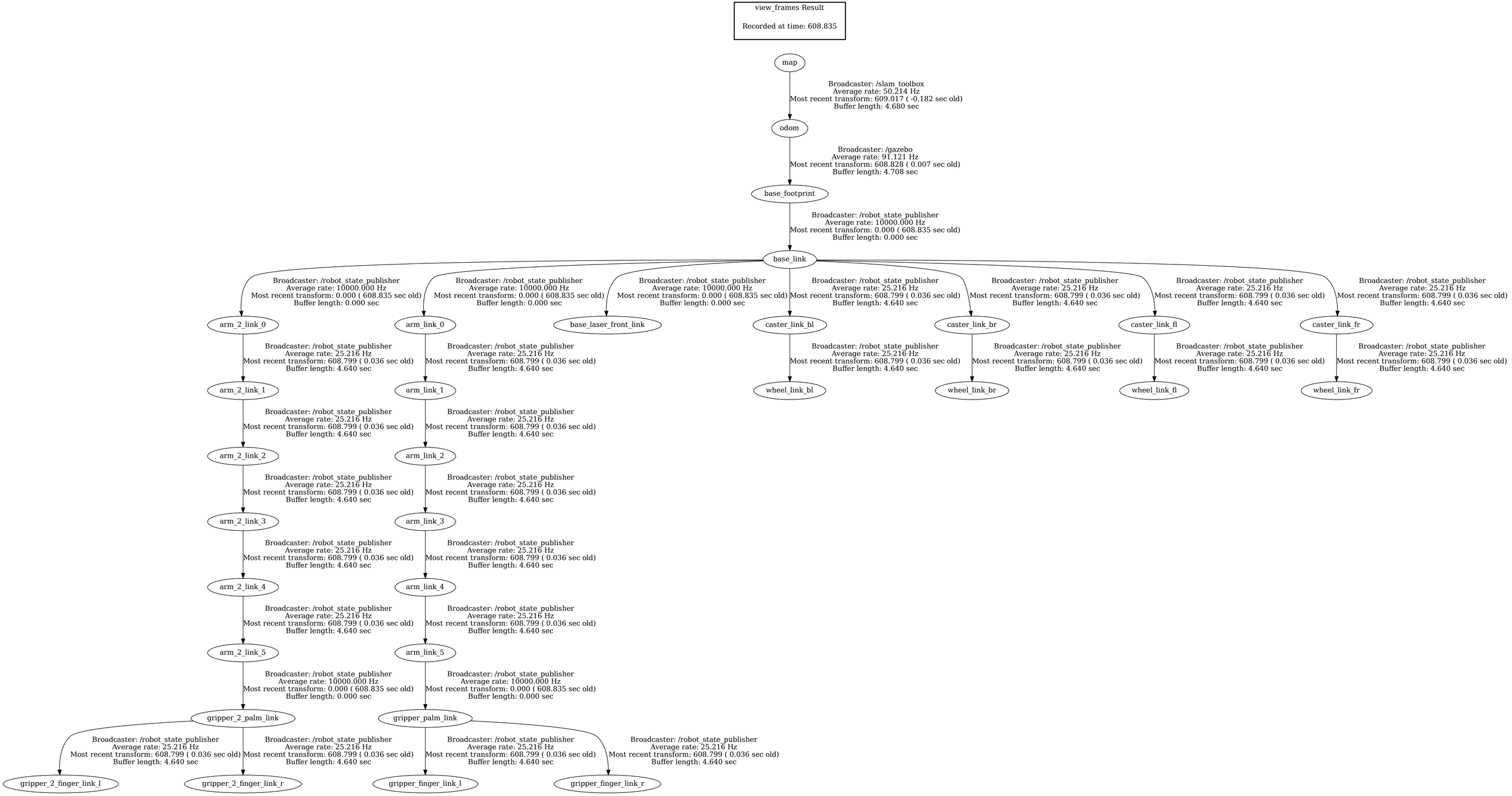
view_frames Result
Recorded at time: 608.835
map
Broadcaster: /slam_toolbox
Average rate: 50.214 Hz
Most recent transform: 609.017 (-0.182 sec old)
Buffer length: 4.680 sec
odom
Broadcaster: /gazebo
Average rate: 91.121 Hz
Most recent transform: 608.828 (0.007 sec old)
Buffer length: 4.708 sec
base_footprint
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (608.835 sec old)
Buffer length: 0.000 sec
base_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (608.835 sec old)
Buffer length: 0.000 sec
arm_2_link_0
arm_link_0
base_laser_front_link
caster_link_bl
Broadcaster: /robot_state_publisher
Average rate: 25.216 Hz
Most recent transform: 608.799 (0.036 sec old)
Buffer length: 4.640 sec
caster_link_br
caster_link_fl
caster_link_fr
arm_2_link_1
arm_link_1
wheel_link_bl
wheel_link_br
wheel_link_fl
wheel_link_fr
arm_2_link_2
arm_link_2
arm_2_link_3
arm_link_3
arm_2_link_4
arm_link_4
arm_2_link_5
arm_link_5
gripper_2_palm_link
gripper_palm_link
gripper_2_finger_link_l
gripper_2_finger_link_r
gripper_finger_link_l
gripper_finger_link_r