

Primary simulations with different schemes of “taboo”-ing

Name: Somak Laha (MB 2016)

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Multiple simulations of “Depreferential attachment random graph through preferential attachment” (denoted by $(G_t^{(m,p)})_{t \geq 1}$) has been performed to obtain ideas about distribution of various statistics of the model through simulation. In this document I shall mainly focus on the statistic **degree of fixed vertex**. For $(G_t^{(m,p)})_{t \geq 1}$, the notation $D_i(t)$ stands for the degree of the i -th vertex at time t . For this notation to make any sense, we must have $0 < i \leq t + 2$.

For simplification, we have taken $m = 1$, i.e., when a new vertex comes, it comes with only $m = 1$ many half-edges. Also, three different methods have been taken for choosing the *taboo* vertices.

- **Hard-code:** In this method, the model has a parameter p ($0 < p < 1$). At time point $t \geq 1$, we choose the $\lfloor (t+1)p \rfloor$ vertices in such a way that all the other vertices in $G_{t-1}^{(1,p)}$ had degree less than the chosen ones. The chosen vertices are made taboo.
- **Soft-code:** In this method too, the model has a parameter p ($0 < p < 1$). At time point $t \geq 1$, we choose the $\lfloor (t+1)p \rfloor$ vertices in a preferential way, i.e., choosing a vertex v_j is proportional to its degree in $G_{t-1}^{(1,p)}$.
- **Soft-code (alternative):** This method does not have the parameter p . Instead, in this method, at time $t \geq 1$, one will choose only one vertex preferentially. That chosen vertex will be made taboo.

Based on these different taboo-ing schemes, multiple simulations have been performed by using three different values of the parameter p , and changing the target vertex i . For each of the cases, 500 simulations have been performed to compute mean, variance and standard deviation.

1 Hard-code

Consider the ‘hard-code’ taboo-ing scheme. In the following plots, we show the mean, variance and standard deviation respectively of $D_i(t)$ with $p \in \{0.01, 0.1, 0.25\}$ and $i \in \{10, 50, 200\}$. The size of the graph is kept fixed at 2000 in all of the cases.

Please note that, in the following plots, we used the following colour code

- Yellow: Mean of $D_i(t)$

- Red: Variance of $D_i(t)$
- Blue: Standard deviation of $D_i(t)$

1.1 $p = 0.01$

Figure 1: $p = 0.01, i = 10$.

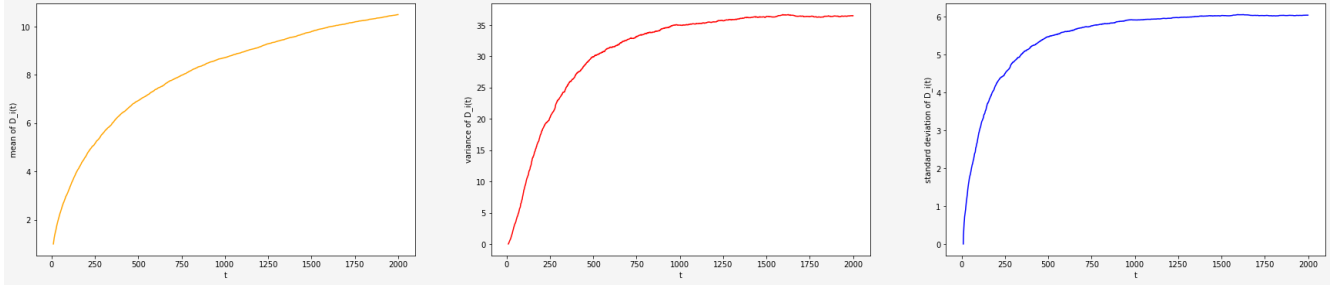


Figure 2: $p = 0.01, i = 50$.

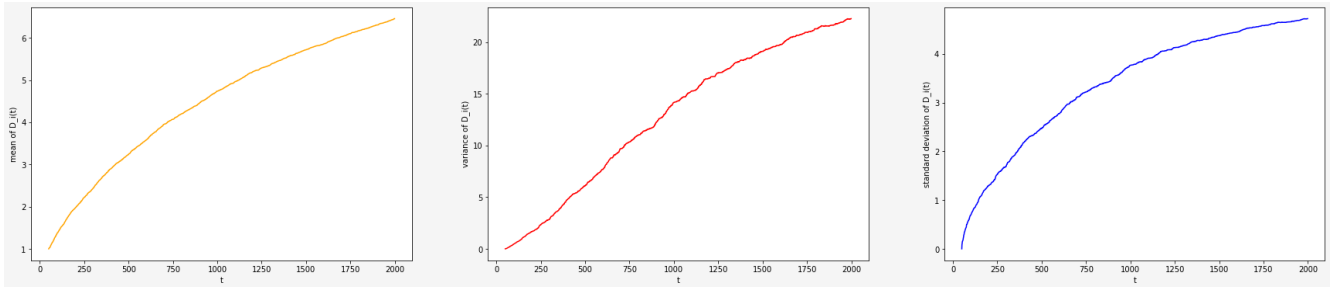
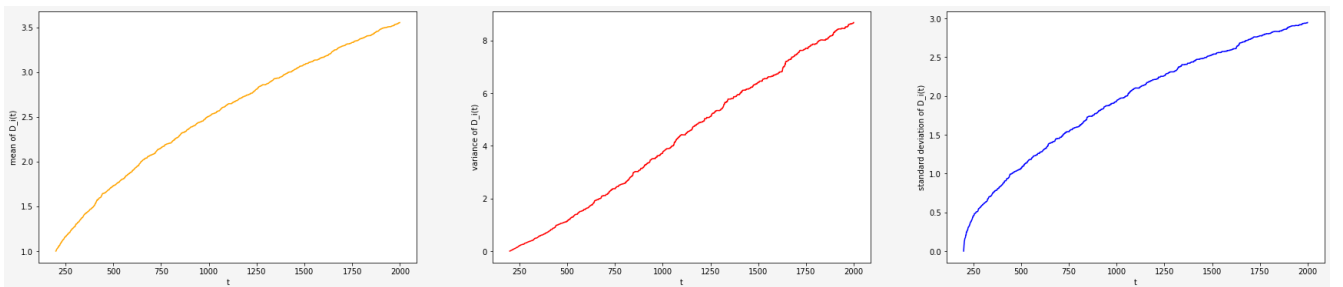


Figure 3: $p = 0.01, i = 200$.



1.2 $p=0.1$

Figure 4: $p = 0.1, i = 10$.

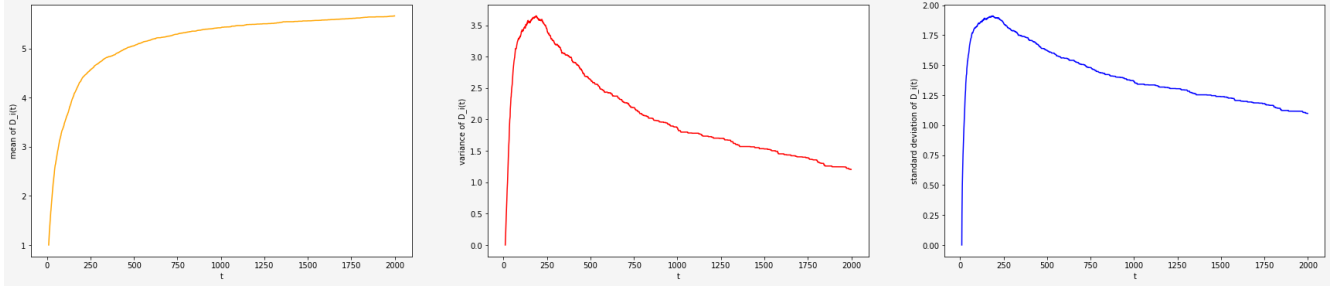


Figure 5: $p = 0.1, i = 50$.

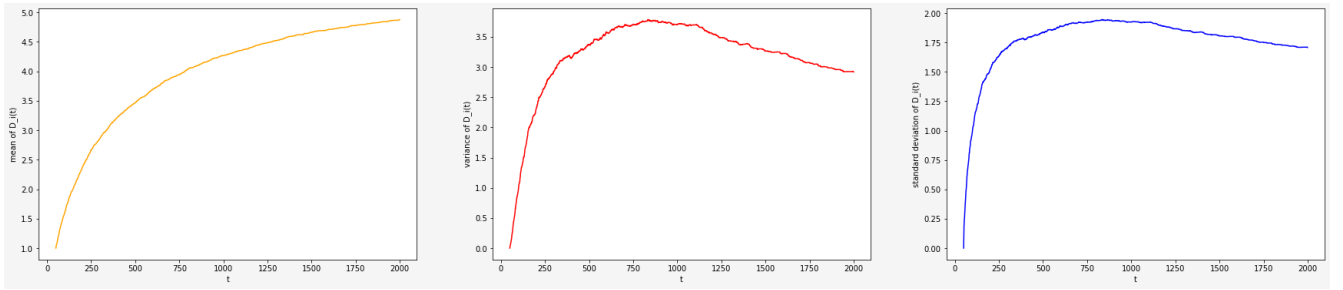
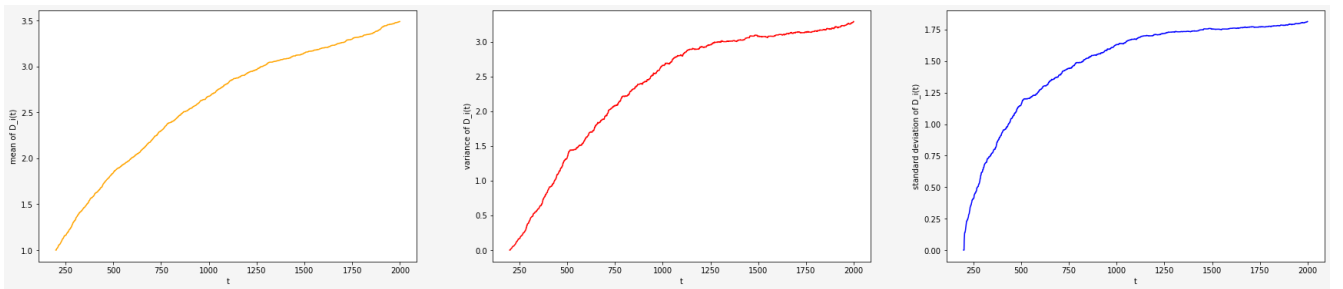


Figure 6: $p = 0.1, i = 200$.



1.3 $p=0.25$

Figure 7: $p = 0.25, i = 10$.

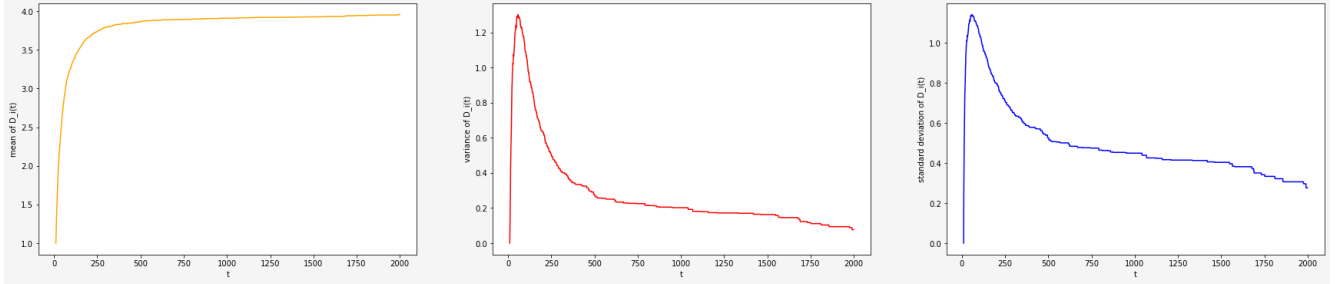


Figure 8: $p = 0.25, i = 50$.

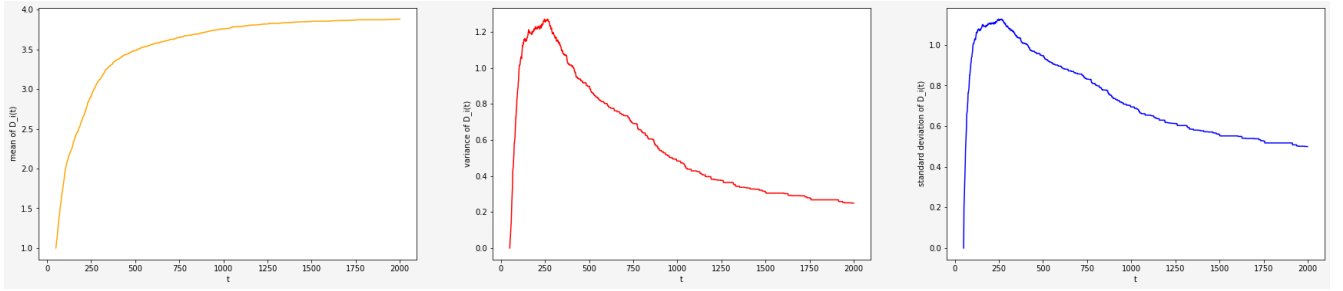
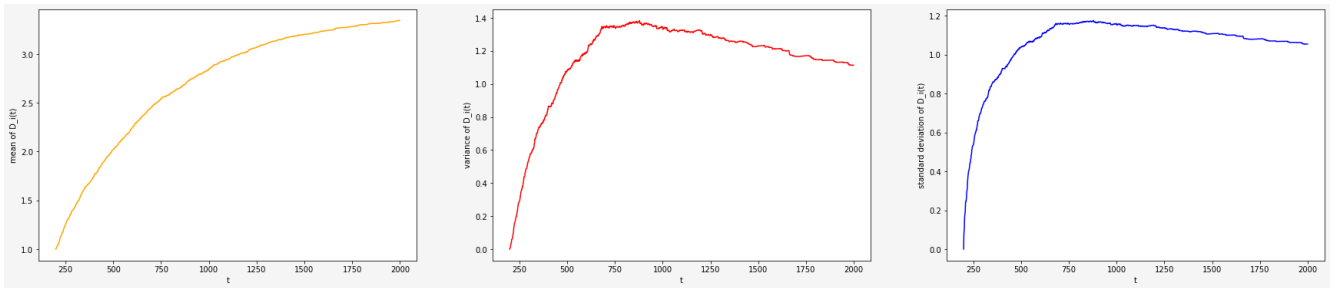


Figure 9: $p = 0.25, i = 200$.



2 Soft-code

Now we adopt the ‘soft-code’ taboo-ing scheme. The other parameters p and i is varied as before.

2.1 $p = 0.01$

Figure 10: $p = 0.01, i = 10$.

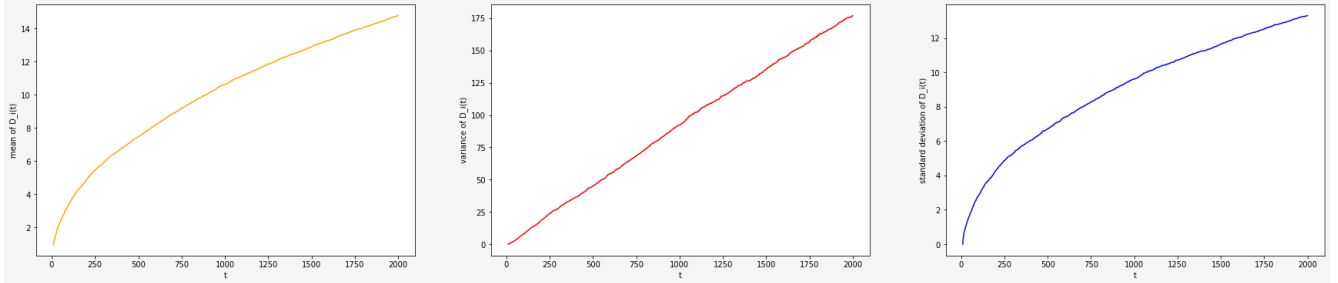


Figure 11: $p = 0.01, i = 50$.

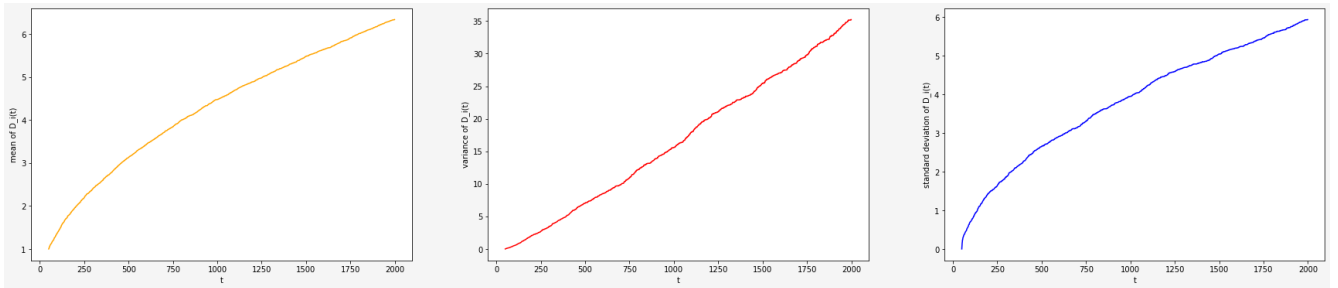
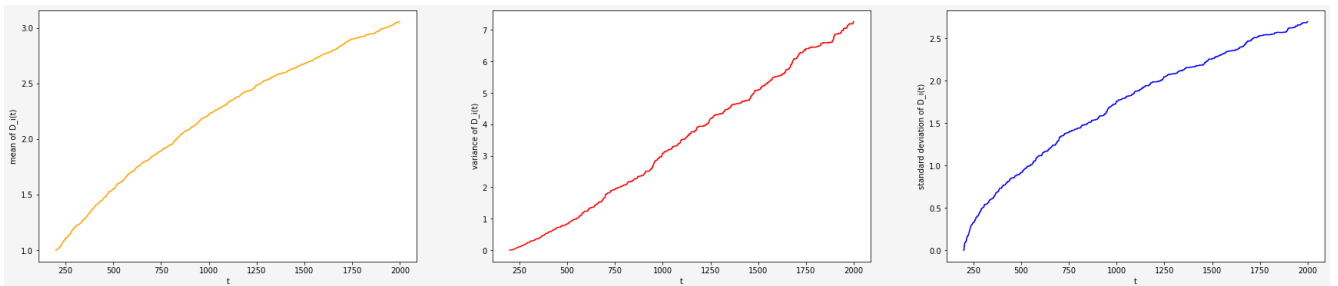


Figure 12: $p = 0.01, i = 200$.



2.2 $p=0.1$

Figure 13: $p = 0.1, i = 10$.

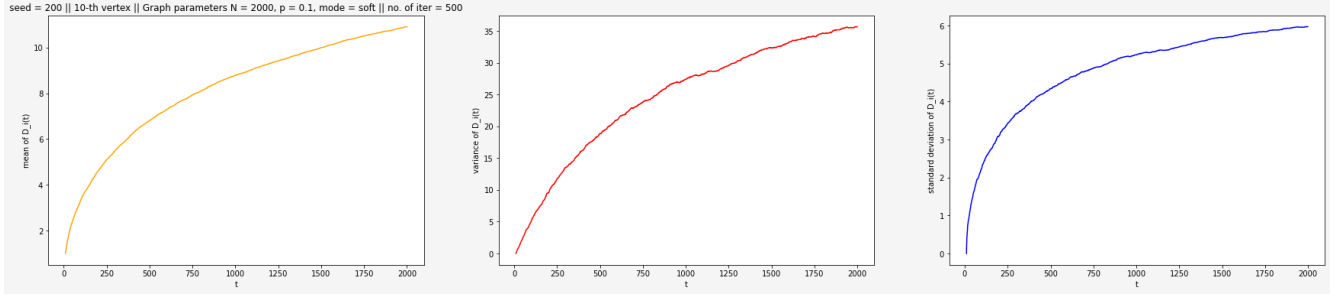


Figure 14: $p = 0.1, i = 50$.

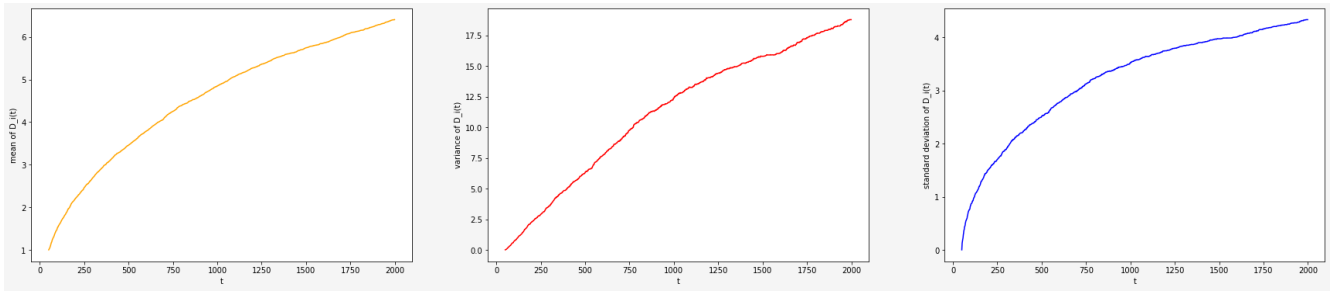
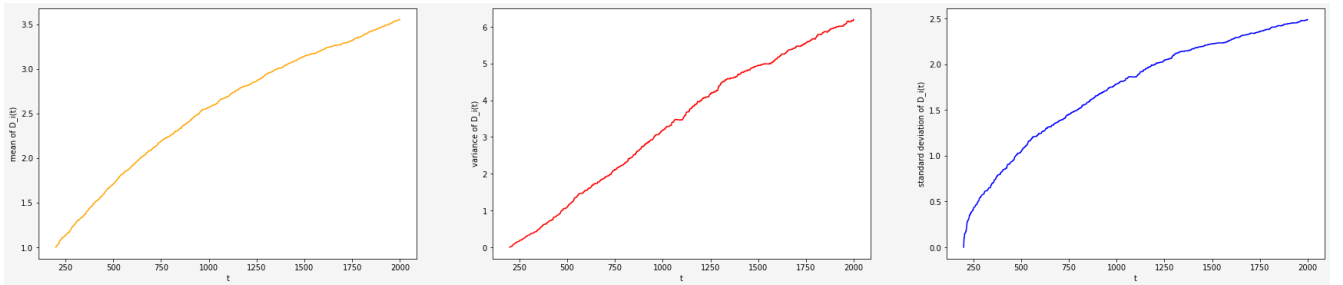


Figure 15: $p = 0.1, i = 200$.



2.3 $p=0.25$

Figure 16: $p = 0.25, i = 10$.

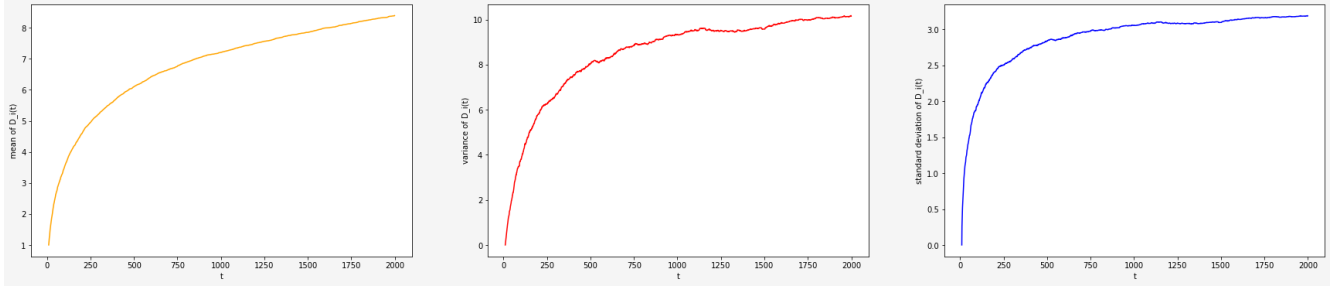


Figure 17: $p = 0.25, i = 50$.

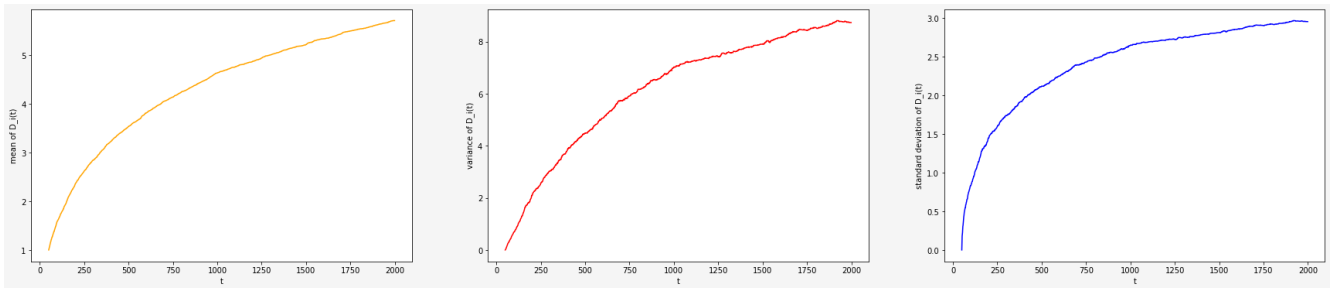
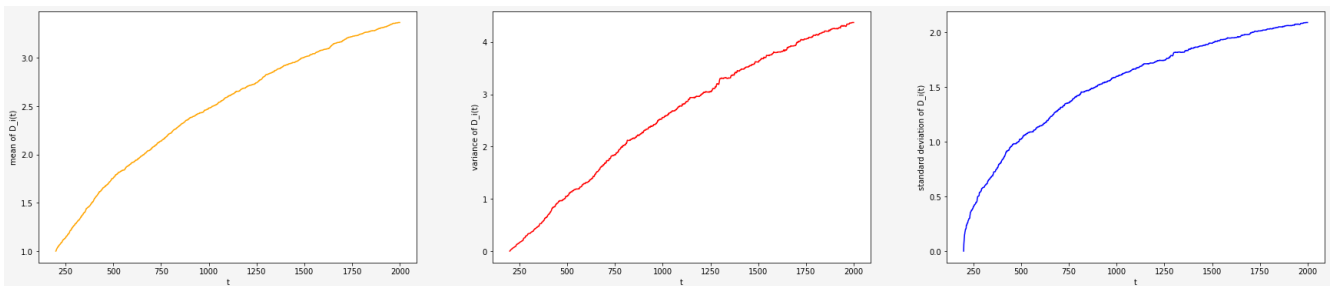


Figure 18: $p = 0.25, i = 200$.



3 Soft-code (alternative)

For this last part, we adopt the ‘soft-code (alternative)’ taboo-ing scheme. This scheme has no parameter p . So, we just vary i in the set $\{10, 50, 200\}$.

Figure 19: $i = 10$.

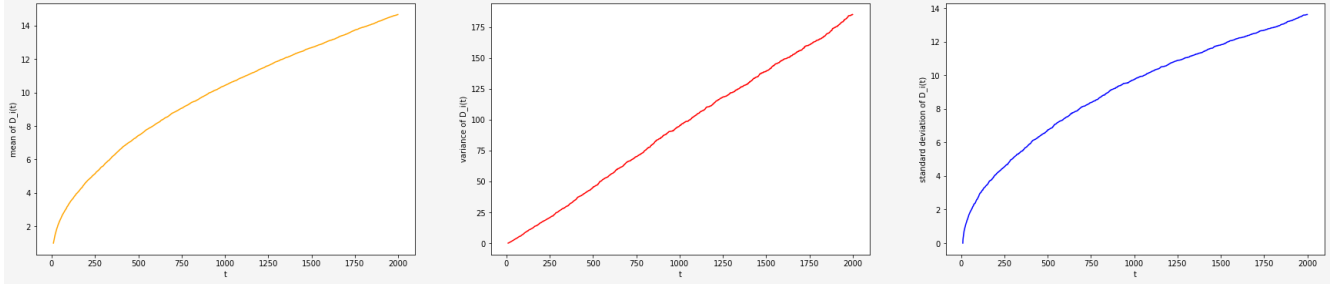


Figure 20: $i = 50$.

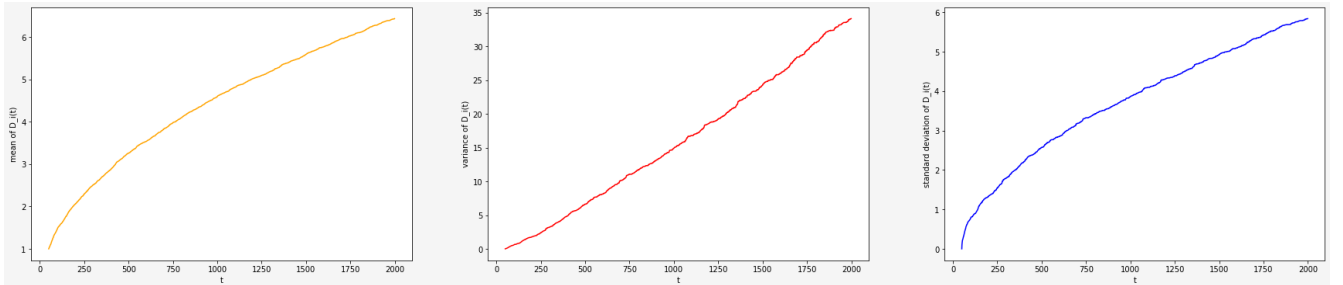


Figure 21: $i = 200$.

