3650 Galleria Circle Hoover Alabama 35244-2346 2 8251 Eastchase Parkway Montgomery Alabama 36117 32.363889 -86.150884 5225 Commercial Boulevard Juneau Alaska 99801-7210 58.359200 -134.483000 4 330 West Dimond Blvd Anchorage Alaska 99515-1950 61.143266 -149.884217 In [5]: df ppg.head() ORB DRB TRB AST STL BLK TO PF PTS Out[5]: G MIN FGM FGA **FGP** FTM FTA **FTP** 3PM 3PA 3PP Name 0.491 1.3 3.4 2.3 **Dwyane Wade** 79 38.6 30.2 10.8 22.0 7.5 9.8 0.765 1.1 3.5 0.317 1.1 3.9 5.0 7.5 2.2 **LeBron James** 81 37.7 28.4 19.9 0.489 7.3 0.780 0.344 1.3 6.3 7.6 7.2 3.0 9.4 1.6 1.7 1.1 Kobe Bryant 82 36.2 26.8 0.467 9.8 20.9 5.9 6.9 0.856 1.4 4.1 0.351 1.1 4.1 5.2 4.9 1.5 0.5 2.6 2.3 Dirk Nowitzki 81 37.7 25.9 20.0 9.6 0.479 6.0 0.890 0.8 2.1 0.359 7.3 8.4 2.4 8.0 8.0 1.9 2.2 1.1 Danny 67 36.2 25.8 8.5 19.1 0.447 6.9 0.878 6.7 0.404 1.4 2.5 Granger **Heat Map** In [6]: sns.heatmap(df ppg,cmap='Blues',linewidth=0.30) plt.xticks(rotation=90) plt.yticks(fontsize=7) plt.xlabel("Statistics", size=18) plt.ylabel("Basketball Player", size=18) plt.title("2008 Basketball Statistics", size=18) plt.show() 2008 Basketball Statistics 80 Dirk Nowitzki Kevin Martin 70 Basketball Player Carmelo Anthony Antawn Jamison 60 joe Johnson David West 50 Vince Carter Dwight Howard 40 Jamal Crawford 30 Monta Ellis Andre Iguodala John Salmons arcus Aldridge Shaquille O'neal Allen Iverson - 0 Statistics **Spatial Plot** In [7]: map=folium.Map(prefer\_canvas=True) def plot(point): folium.CircleMarker(location=[point.Latitude,point.Longitude], radius=2, popup=point.Address+" "+point.City+" "+point.State+" "+point["Zip Code"], fill color=point.State, fill=True, fill\_opacity=0.7, weight=5).add to(map) In [8]: df costco.apply(plot,axis=1) map.fit bounds(map.get bounds()) output file="Map Python.html" map.save(output file) webbrowser.open(output file,new=2) Out[8]: **Contour Plot** In [9]: Z=df\_ppg.pivot\_table(index='FGA',columns='PTS',values='FGP').T.values x unique=np.sort(df ppg.FGA.unique()) y\_unique=np.sort(df\_ppg.PTS.unique()) In [10]: X,Y=np.meshgrid(x\_unique,y\_unique) Z[np.isnan(Z)]=0pd.DataFrame(Z).round(3) pd.DataFrame(Y).round(3) pd.DataFrame(X).round(3) 0 2 3 4 5 6 7 8 9 29 30 31 32 33 34 35 36 37 38 Out[10]: 1 **0** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 20.0 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.9 **2** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 **3** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.5 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 14.1 **4** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 **6** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 ... 17.8 18.0 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 **8** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 12.9 13.2 13.9 14.0 18.3 19.1 19.5 19.9 20.0 20.9 22.0 13.4 13.8 14.1 14.5 ... 17.8 18.0 18.8 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 **11** 11.2 12.4 ... 17.8 18.0 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 **12** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 ... 17.8 18.0 18.3 20.0 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 18.8 19.1 19.5 19.9 **14** 11.2 12.4 14.0 14.1 14.5 12.9 13.2 13.4 13.8 13.9 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 ... 17.8 18.0 20.0 20.9 22.0 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 18.3 18.8 19.1 19.5 19.9 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 **17** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 20.0 20.9 11.2 12.4 18.3 18.8 19.1 19.5 19.9 22.0 ... 17.8 18.0 18.3 18.8 19.1 19.5 **20** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 19.9 20.0 20.9 22.0 18.3 18.8 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 19.5 19.9 20.0 19.1 **22** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 **23** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0 **24** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 **26** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 **27** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0 18.3 18.8 19.1 19.5 19.9 20.0 20.9 22.0

#Import libraries

import folium import webbrowser

import warnings

In [4]: df costco.head()

import numpy as np import pandas as pd import seaborn as sns import matplotlib

import matplotlib.pyplot as plt

from matplotlib import rcParams

warnings.filterwarnings('ignore')

1205 N. Memorial Parkway

from IPython.display import set matplotlib formats

df costco=pd.read csv("costcos-geocoded.csv") df ppg=pd.read csv("ppg2008.csv",index col=0)

City

Huntsville

State

Alabama

**Zip Code** 

35801-5930

Latitude

34.743095

33.377649

Longitude

-86.600955

-86.812420

**Address** 

In [1]:

In [2]:

In [3]:

Out[4]:

plt.xticks(rotation=90) plt.xticks(fontsize=7)

plt.title("Contour Plot")

plt.xlabel('Goal Attempts', size=8) plt.ylabel('Goal Poitns', size=8)

**32** 11.2 12.4

**35** 11.2 12.4

39 rows × 39 columns

fig=plt.figure()

ax=plt.gca()

plt.show()

In [ ]:

In [ ]:

In [11]: set matplotlib formats('svg')

ax=fig.add subplot(111)

PCM=ax.get children()[2] plt.colorbar(PCM, ax=ax)

cp=ax.contourf(X,Y,Z)

**Contour Plot** 1.0 30 28 0.8 26 - 0.6 Goal Poitns 24 - 0.4 22 **Goal Attempts** 

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**33** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5

**34** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5

**36** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5

11.2 12.4 12.9 13.2 13.4 13.8

rcParams['figure.figsize']=5,5

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**31** 11.2 12.4 12.9 13.2 13.4 13.8 13.9 14.0 14.1 14.5 ... 17.8 18.0

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