

# **Introduction to Ada**

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This course will teach you the basics of the Ada programming language and is intended for those who already have a basic understanding of programming techniques. You will learn how to apply those techniques to programming in Ada.

This document was written by Raphaël Amiard and Gustavo A. Hoffmann, with review from Richard Kenner.

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#### INTRODUCTION

### 1.1 History

In the 1970s the United States Department of Defense (DOD) suffered from an explosion of the number of programming languages, with different projects using different and non-standard dialects or language subsets / supersets. The DOD decided to solve this problem by issuing a request for proposals for a common, modern programming language. The winning proposal was one submitted by Jean Ichbiah from CII Honeywell-Bull.

The first Ada standard was issued in 1983; it was subsequently revised and enhanced in 1995, 2005 and 2012, with each revision bringing useful new features.

This tutorial will focus on Ada 2012 as a whole, rather than teaching different versions of the language.

### 1.2 Ada today

Today, Ada is heavily used in embedded real-time systems, many of which are safety critical. While Ada is and can be used as a general-purpose language, it will really shine in low-level applications:

- Embedded systems with low memory requirements (no garbage collector allowed).
- · Direct interfacing with hardware.
- · Soft or hard real-time systems.
- Low-level systems programming.

Specific domains seeing Ada usage include Aerospace & Defense, civil aviation, rail, and many others. These applications require a high degree of safety: a software defect is not just an annoyance, but may have severe consequences. Ada provides safety features that detect defects at an early stage — usually at compilation time or using static analysis tools. Ada can also be used to create applications in a variety of other areas, such as:

- Video game programming<sup>2</sup>
- Real-time audio<sup>3</sup>
- Kernel modules<sup>4</sup>

This is a non-comprehensive list that hopefully sheds light on which kind of programming Ada is good at.

<sup>&</sup>lt;sup>2</sup> https://github.com/AdaDoom3/AdaDoom3

<sup>&</sup>lt;sup>3</sup> http://www.electronicdesign.com/embedded-revolution/assessing-ada-language-audio-applications

<sup>&</sup>lt;sup>4</sup> http://www.nihamkin.com/tag/kernel.html

In terms of modern languages, the closest in terms of targets and level of abstraction are probably  $C++^5$  and  $Rust^6$ .

# 1.3 Philosophy

Ada's philosophy is different from most other languages. Underlying Ada's design are principles that include the following:

- Readability is more important than conciseness. Syntactically this shows through the fact that keywords are preferred to symbols, that no keyword is an abbreviation, etc.
- Very strong typing. It is very easy to introduce new types in Ada, with the benefit of preventing data usage errors.
  - It is similar to many functional languages in that regard, except that the programmer has to be much more explicit about typing in Ada, because there is almost no type inference.
- Explicit is better than implicit. Although this is a Python<sup>7</sup> commandment, Ada takes it way further than any language we know of:
  - There is mostly no structural typing, and most types need to be explicitly named by the programmer.
  - As previously said, there is mostly no type inference.
  - Semantics are very well defined, and undefined behavior is limited to an absolute minimum.
  - The programmer can generally give a *lot* of information about what their program means to the compiler (and other programmers). This allows the compiler to be extremely helpful (read: strict) with the programmer.

During this course, we will explain the individual language features that are building blocks for that philosophy.

#### 1.4 SPARK

While this class is solely about the Ada language, it is worth mentioning that another language, extremely close to and interoperable with Ada, exists: the SPARK language.

SPARK is a subset of Ada, designed so that the code written in SPARK is amenable to automatic proof. This provides a level of assurance with regard to the correctness of your code that is much higher than with a regular programming language.

There is a dedicated course for the SPARK language<sup>8</sup> but keep in mind that every time we speak about the specification power of Ada during this course, it is power that you can leverage in SPARK to help proving the correctness of program properties ranging from absence of run-time errors to compliance with formally specified functional requirements.

<sup>&</sup>lt;sup>5</sup> https://en.wikipedia.org/wiki/C%2B%2B

<sup>&</sup>lt;sup>6</sup> https://www.rust-lang.org/en-US/

<sup>&</sup>lt;sup>7</sup> https://www.python.org

<sup>&</sup>lt;sup>8</sup> https://learn.adacore.com/courses/intro-to-spark/index.html

**CHAPTER** 

**TWO** 

### **IMPERATIVE LANGUAGE**

Ada is a multi-paradigm language with support for object orientation and some elements of functional programming, but its core is a simple, coherent procedural/imperative language akin to C or Pascal.

#### In other languages

One important distinction between Ada and a language like C is that statements and expressions are very clearly distinguished. In Ada, if you try to use an expression where a statement is required then your program will fail to compile. This rule supports a useful stylistic principle: expressions are intended to deliver values, not to have side effects. It can also prevent some programming errors, such as mistakenly using the equality operator "=" instead of the assignment operation ":=" in an assignment statement.

#### 2.1 Hello world

Here's a very simple imperative Ada program:

```
with Ada.Text_IO;
procedure Greet is
begin
   -- Print "Hello, World!" to the screen
   Ada.Text_IO.Put_Line ("Hello, World!");
end Greet;
```

which we'll assume is in the source file greet.adb.

If you compile that source with the GNAT compiler and run the executable, you will get an unsurprising result.

```
$ gprbuild greet.adb
using project file [...]_default.gpr
Compile
   [Ada]
                  greet.adb
Bind
   [gprbind]
                  greet.bexch
   [Ada]
                  greet.ali
Link
                  greet.adb
   [link]
 $ ./greet
Hello, World!
 $
```

There are several noteworthy things in the above program:

- A subprogram in Ada can be either a procedure or a function. A procedure, as illustrated above, does not return a value when called.
- with is used to reference external modules that are needed in the procedure. This is similar
  to import in various languages or roughly similar to #include in C and C++. We'll see later
  how they work in detail. Here, we are requesting a standard library module, the Ada. Text\_IO
  package, which contains a procedure to print text on the screen: Put\_Line.
- Greet is a procedure, and the main entry point for our first program. Unlike in C or C++, it can be named anything you prefer. The builder will determine the entry point. In our simple example, **gprbuild**, GNAT's builder, will use the file you passed as parameter.
- Put\_Line is a procedure, just like Greet, except it is declared in the Ada.Text\_IO module. It is the Ada equivalent of C's printf.
- Comments start with - and go to the end of the line. There is no multi-line comment syntax, that is, it is not possible to start a comment in one line and continue it in the next line. The only way to create multiple lines of comments in Ada is by using - on each line. For example:

```
-- We start a comment in this line...
-- and we continue on the second line...
```

#### In other languages

Procedures are similar to functions in C or C++ that return void. We'll see later how to declare functions in Ada.

Here is a minor variant of the "Hello, World" example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Greet is
begin
   -- Print "Hello, World!" to the screen
   Put_Line ("Hello, World!");
end Greet;
```

This version utilizes an Ada feature known as a use clause, which has the form use *package-name*. As illustrated by the call on Put\_Line, the effect is that entities from the named package can be referenced directly, without the *package-name*. prefix.

# 2.2 Imperative language - If/Then/Else

This section describes Ada's if statement and introduces several other fundamental language facilities including integer I/O, data declarations, and subprogram parameter modes.

Ada's if statement is pretty unsurprising in form and function:

```
with Ada.Text_IO; use Ada.Text_IO;
with Ada.Integer_Text_IO; use Ada.Integer_Text_IO;

procedure Check_Positive is
    N : Integer;
begin
    Put ("Enter an integer value: "); -- Put a String
    Get (N); -- Read in an integer value
    if N > 0 then
        Put (N); -- Put an Integer
        Put_Line (" is a positive number");
```

```
end if;
end Check_Positive;
```

The if statement minimally consists of the reserved word if, a condition (which must be a Boolean value), the reserved word then and a non-empty sequence of statements (the then part) which is executed if the condition evaluates to True, and a terminating end if.

This example declares an integer variable N, prompts the user for an integer, checks if the value is positive and, if so, displays the integer's value followed by the string " is a positive number". If the value is not positive, the procedure does not display any output.

The type Integer is a predefined signed type, and its range depends on the computer architecture. On typical current processors Integer is 32-bit signed.

The example illustrates some of the basic functionality for integer input-output. The relevant subprograms are in the predefined package Ada. Integer\_Text\_IO and include the Get procedure (which reads in a number from the keyboard) and the Put procedure (which displays an integer value).

Here's a slight variation on the example, which illustrates an if statement with an else part:

```
with Ada.Text_IO; use Ada.Text_IO;
with Ada.Integer_Text_IO; use Ada.Integer_Text_IO;

procedure Check_Positive is
   N : Integer;
begin
   Put ("Enter an integer value: "); -- Put a String
   Get (N); -- Reads in an integer value
   Put (N); -- Put an Integer
   if N > 0 then
        Put_Line (" is a positive number");
   else
        Put_Line (" is not a positive number");
   end if;
end Check_Positive;
```

In this example, if the input value is not positive then the program displays the value followed by the String " is not a positive number".

Our final variation illustrates an if statement with elsif sections:

```
with Ada.Text IO; use Ada.Text IO;
with Ada.Integer_Text_IO; use Ada.Integer_Text_IO;
procedure Check Direction is
   N : Integer;
begin
   Put ("Enter an integer value: "); -- Puts a String
   Get (N); -- Reads an Integer
   Put (N); -- Puts an Integer
   if N = 0 or N = 360 then
      Put Line (" is due east");
   elsif \overline{N} in 1 .. 89 then
      Put_Line (" is in the northeast quadrant");
   elsif \overline{N} = 90 then
      Put_Line (" is due north");
   elsif N in 91 .. 179 then
   Put_Line (" is in the northwest quadrant");
   elsif \overline{N} = 180 then
      Put_Line (" is due west");
   elsif N in 181 .. 269 then
```

```
Put_Line (" is in the southwest quadrant");
elsif N = 270 then
   Put_Line (" is due south");
elsif N in 271 .. 359 then
   Put_Line (" is in the southeast quadrant");
else
   Put_Line (" is not in the range 0..360");
end if;
end Check_Direction;
```

This example expects the user to input an integer between 0 and 360 inclusive, and displays which quadrant or axis the value corresponds to. The in operator in Ada tests whether a scalar value is within a specified range and returns a Boolean result. The effect of the program should be self-explanatory; later we'll see an alternative and more efficient style to accomplish the same effect, through a case statement.

Ada's elsif keyword differs from C or C++, where nested else .. if blocks would be used instead. And another difference is the presence of the end if in Ada, which avoids the problem known as the "dangling else".

### 2.3 Imperative language - Loops

Ada has three ways of specifying loops. They differ from the C / Java / Javascript for-loop, however, with simpler syntax and semantics in line with Ada's philosophy.

#### 2.3.1 For loops

The first kind of loop is the for loop, which allows iteration through a discrete range.

Executing this procedure yields the following output:

```
Hello, World! 1
Hello, World! 2
Hello, World! 3
Hello, World! 4
Hello, World! 5
```

A few things to note:

- 1 ... 5 is a discrete range, from 1 to 5 inclusive.
- The loop parameter I (the name is arbitrary) in the body of the loop has a value within this range.
- I is local to the loop, so you cannot refer to I outside the loop.
- Although the value of *l'* is incremented at each iteration, from the program's perspective it is constant. An attempt to modify its value is illegal; the compiler would reject the program.

- Integer'Image is a function that takes an Integer and converts it to a String. It is an example of a language construct known as an *attribute*, indicated by the "" syntax, which will be covered in more detail later.
- The & symbol is the concatenation operator for String values
- The end loop marks the end of the loop

The "step" of the loop is limited to 1 (forward direction) and -1 (backward). To iterate backwards over a range, use the reverse keyword:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Greet_5a_Reverse is
begin
   for I in reverse 1 .. 5 loop
        Put_Line ("Hello, World!" & Integer'Image (I));
   end loop;
end Greet_5a_Reverse;
```

Executing this procedure yields the following output:

```
Hello, World! 5
Hello, World! 4
Hello, World! 3
Hello, World! 2
Hello, World! 1
```

The bounds of a for loop may be computed at run-time; they are evaluated once, before the loop body is executed. If the value of the upper bound is less than the value of the lower bound, then the loop is not executed at all. This is the case also for reverse loops. Thus no output is produced in the following example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Greet_No_Op is
begin
   for I in reverse 5 . . 1 loop
        Put_Line ("Hello, World!" & Integer'Image (I));
   end loop;
end Greet_No_Op;
```

The for loop is more general than what we illustrated here; more on that later.

#### 2.3.2 Bare loops

The simplest loop in Ada is the bare loop, which forms the foundation of the other kinds of Ada loops.

```
-- Assignment
I := I + 1; -- There is no I++ short form to increment a variable
end loop;
end Greet_5b;
```

This example has the same effect as Greet 5a shown earlier.

It illustrates several concepts:

- We have declared a variable named I between the is and the begin. This constitutes a
   declarative region. Ada clearly separates the declarative region from the statement part of a
   subprogram. A declaration can appear in a declarative region but is not allowed as a statement.
- The bare loop statement is introduced by the keyword loop on its own and, like every kind of loop statement, is terminated by the combination of keywords end loop. On its own, it is an infinite loop. You can break out of it with an exit statement.
- The syntax for assignment is :=, and the one for equality is =. There is no way to confuse them, because as previously noted, in Ada, statements and expressions are distinct, and expressions are not valid statements.

#### 2.3.3 While loops

The last kind of loop in Ada is the while loop.

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Greet_5c is
    I : Integer := 1;
begin
    -- Condition must be a Boolean value (no Integers).
    -- Operator "<=" returns a Boolean
    while I <= 5 loop
        Put_Line ("Hello, World!" & Integer'Image (I));

        I := I + 1;
        end loop;
end Greet_5c;</pre>
```

The condition is evaluated before each iteration. If the result is false, then the loop is terminated.

This program has the same effect as the previous examples.

#### In other languages

Note that Ada has different semantics than C-based languages with respect to the condition in a while loop. In Ada the condition has to be a Boolean value or the compiler will reject the program; the condition is not an integer that is treated as either True or False depending on whether it is non-zero or zero.

# 2.4 Imperative language - Case statement

Ada's case statement is similar to the C and C++ switch statement, but with some important differences.

Here's an example, a variation of a program that was shown earlier with an if statement:

```
with Ada.Text IO; use Ada.Text IO;
with Ada. Integer Text IO; use Ada. Integer Text IO;
procedure Check Direction is
  N : Integer;
begin
  loop
      Put ("Enter an integer value: "); -- Puts a String
      Get (N); -- Reads an Integer
      Put (N); -- Puts an Integer
      case N is
         when 0 \mid 360 =>
            Put Line (" is due east");
         when 1 ... 89 =>
           Put Line (" is in the northeast quadrant");
         when 90 =>
           Put_Line (" is due north");
         when 91 .. 179 =>
           Put Line (" is in the northwest quadrant");
         when 180 =>
           Put Line (" is due west");
         when 181 ... 269 =>
            Put Line (" is in the southwest quadrant");
         when 270 =>
           Put Line (" is due south");
         when 271 .. 359 =>
            Put_Line (" is in the southeast quadrant");
         when others =>
            Put Line (" Au revoir");
            exit:
      end case;
  end loop;
end Check Direction;
```

This program repeatedly prompts for an integer value and then, if the value is in the range 0..360, displays the associated quadrant or axis. If the value is an Integer outside this range, the loop (and the program) terminate after outputting a farewell message.

The effect of the case statement is similar to the if statement in an earlier example, but the case statement can be more efficient because it does not involve multiple range tests.

Notable points about Ada's case statement:

- The case expression (here the variable N) must be of a discrete type, i.e. either an integer type or an enumeration type. Discrete types will be covered in more detail later *discrete types* (page 25).
- Every possible value for the case expression needs to be covered by a unique branch of the case statement. This will be checked at compile time.
- A branch can specify a single value, such as 0; a range of values, such as 1 ... 89; or any combination of the two (separated by a |).
- As a special case, an optional final branch can specify others, which covers all values not included in the earlier branches.
- Execution consists of the evaluation of the case expression and then a transfer of control to the statement sequence in the unique branch that covers that value.
- When execution of the statements in the selected branch has completed, control resumes after the end case. Unlike C, execution does not fall through to the next branch. So Ada doesn't need (and doesn't have) a break statement.

### 2.5 Imperative language - Declarative regions

As mentioned earlier, Ada draws a clear syntactic separation between declarations, which introduce names for entities that will be used in the program, and statements, which perform the processing. The areas in the program where declarations may appear are known as declarative regions.

- In any subprogram, the section between the is and the begin is a declarative region.
- You can have variables, constants, types, inner subprograms, and other entities there. For example:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Main is
    procedure Nested is
    begin
        Put_Line ("Hello World");
    end Nested;

begin
    Nested;
    -- Call to Nested
end Main;
```

• A declaration cannot appear as a statement if you need to declare a local variable amidst the statements, you can introduce a new declarative region with a block statement:

**Attention:** The Get\_Line function allows you to receive input from the user, and get the result as a string. It is more or less equivalent to the scanf C function.

It returns a String, which, as we will see later, is an *Unconstrained array type* (page 41). For now we simply note that, if you wish to declare a String variable and do not know its size in advance, then you need to initialize the variable during its declaration.

# 2.6 Imperative language - conditional expressions

Ada 2012 introduced an expression analog for conditional statements (if and case).

#### 2.6.1 If expressions

Here's an alternative version of an example we saw earlier; the if statement has been replaced by an if expression:

```
with Ada.Text_IO; use Ada.Text_IO;
with Ada.Integer_Text_IO; use Ada.Integer_Text_IO;

procedure Check_Positive is
    N : Integer;
begin
    Put ("Enter an integer value: "); -- Put a String
    Get (N); -- Reads in an integer value
    Put (N); -- Put an Integer
    declare
    S : String :=
        (if N > 0 then " is a positive number"
        else " is not a positive number");
begin
    Put_Line (S);
end;
end Check_Positive;
```

The if expression evaluates to one of the two Strings depending on N, and assigns that value to the local variable S.

Ada's if expressions are similar to if statements. However, there are a few differences that stem from the fact that it is an expression:

- All branches' expressions must be of the same type
- It *must* be surrounded by parentheses if the surrounding expression does not already contain them
- An else branch is mandatory unless the expression following then has a Boolean value. In that case an else branch is optional and, if not present, defaults to else True.

Here's another example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Main is
begin
   for I in 1 .. 10 loop
      Put_Line (if I mod 2 = 0 then "Even" else "Odd");
   end loop;
end Main;
```

This program produces 10 lines of output, alternating between "Odd" and "Even".

#### 2.6.2 Case expressions

Analogous to if expressions, Ada also has case expressions. They work just as you would expect.

end loop;
end Main;

This program has the same effect as the preceding example.

The syntax differs from case statements, with branches separated by commas.

**CHAPTER** 

THREE

#### **SUBPROGRAMS**

### 3.1 Subprograms

So far, we have used procedures, mostly to have a main body of code to execute. Procedures are one kind of *subprogram*.

There are two kinds of subprograms in Ada, *functions* and *procedures*. The distinction between the two is that a function returns a value, and a procedure does not.

This example shows the declaration and definition of a function:

```
function Increment (I : Integer) return Integer;
-- We declare (but don't define) a function with one
-- parameter, returning an integer value
```

```
-- We define the Increment function

function Increment (I : Integer) return Integer is
begin
    return I + 1;
end Increment;
```

Subprograms in Ada can, of course, have parameters. One syntactically important note is that a subprogram which has no parameters does not have a parameter section at all, for example:

```
procedure Proc;
function Func return Integer;
```

Here's another variation on the previous example:

In this example, we see that parameters can have default values. When calling the subprogram, you can then omit parameters if they have a default value. Unlike C/C++, a call to a subprogram without parameters does not include parentheses.

This is the implementation of the function above:

```
function Increment_By
  (I : Integer := 0;
   Incr : Integer := 1) return Integer is
begin
   return I + Incr;
end Increment_By;
```

#### 3.1.1 Subprogram calls

We can then call our subprogram this way:

```
with Ada.Text_IO; use Ada.Text_IO;
with Increment_By;
procedure Show_Increment is
  A, B, C : Integer;
begin
  C := Increment By;
                  ^{\circ} Parameterless call, value of I is 0
                   and Incr is 1
  Put_Line ("Using defaults for Increment_By is "
            & Integer'Image (C));
  A := 10;
  B := 3;
  C := Increment_By (A, B);
                    ^ Regular parameter passing
  Put_Line ("Increment of " & Integer'Image (A)
           & " with " & Integer' Image (B)
            & " is "
                         & Integer'Image (C));
  A := 20;
  B := 5;
  C := Increment_By (I => A,
                    Incr => B);
                    ^ Named parameter passing
  end Show_Increment;
```

Ada allows you to name the parameters when you pass them, whether they have a default or not. There are some rules:

- Positional parameters come first.
- A positional parameter cannot follow a named parameter.

As a convention, people usually name parameters at the call site if the function's corresponding parameters has a default value. However, it is also perfectly acceptable to name every parameter if it makes the code clearer.

#### 3.1.2 Nested subprograms

As briefly mentioned earlier, Ada allows you to declare one subprogram inside of another.

This is useful for two reasons:

- It lets you organize your programs in a cleaner fashion. If you need a subprogram only as a "helper" for another subprogram, then the principle of localization indicates that the helper subprogram should be declared nested.
- It allows you to share state easily in a controlled fashion, because the nested subprograms have access to the parameters, as well as any local variables, declared in the outer scope.

For the previous example, we can move the duplicated code (call to Put\_Line) to a separate procedure. This is a shortened version with the nested Display Result procedure.

#### 3.1.3 Function calls

An important feature of function calls in Ada is that the return value at a call cannot be ignored; that is, a function call cannot be used as a statement.

If you want to call a function and do not need its result, you will still need to explicitly store it in a local variable.

#### In the GNAT toolchain

In GNAT, with all warnings activated, it becomes even harder to ignore the result of a function, because unused variables will be flagged. For example, this code would not be valid:

```
function Read_Int
   (Stream : Network_Stream; Result : out Integer) return Boolean;

procedure Main is
   Stream : Network_Stream := Get_Stream;
   My_Int : Integer;
   B : Boolean := Read_Int (Stream, My_Int); -- Warning here, B is never read
begin
   null;
end Main;
```

You then have two solutions to silence this warning:

• Either annotate the variable with pragma Unreferenced, thus:

```
B : Boolean := Read_Int (Stream, My_Int);
pragma Unreferenced (B);
```

 Or give the variable a name that contains any of the strings discard dummy ignore junk unused (case insensitive)

#### 3.2 Parameters modes

So far we have seen that Ada is a safety-focused language. There are many ways this is realized, but two important points are:

- Ada makes the user specify as much as possible about the behavior expected for the program, so that the compiler can warn or reject if there is an inconsistency.
- Ada provides a variety of techniques for achieving the generality and flexibility of pointers and dynamic memory management, but without the latter's drawbacks (such as memory leakage and dangling references).

Parameters modes are a feature that helps achieve the two design goals above. A subprogram parameter can be specified with a mode, which is one of the following:

in	Parameter can only be read, not written
out	Parameter can be written to, then read
in out	Parameter can be both read and written

The default mode for parameters is in; so far, most of the examples have been using in parameters.

#### Historically

Functions and procedures were originally more different in philosophy. Before Ada 2012, functions could only take "in" parameters.

# 3.3 Subprogram calls

#### 3.3.1 In parameters

The first mode for parameters is the one we have been implicitly using so far. Parameters passed using this mode cannot be modified, so that the following program will cause an error:

```
procedure Swap (A, B : Integer) is
   Tmp : Integer;
begin
   Tmp := A;

-- Error: assignment to "in" mode parameter not allowed
   A := B;
   -- Error: assignment to "in" mode parameter not allowed
   B := Tmp;
end Swap;
```

The fact that this is the default mode is in itself very important. It means that a parameter will not be modified unless you explicitly specify a mode in which modification is allowed.

#### 3.3.2 In out parameters

To correct our code above, we can use an "in out" parameter.

```
with Ada.Text_IO; use Ada.Text_IO;

procedure In_Out_Params is
    procedure Swap (A, B : in out Integer) is
        Tmp : Integer;
begin
        Tmp := A;
        A := B;
        B := Tmp;
end Swap;

A : Integer := 12;
B : Integer := 44;
begin
    Swap (A, B);
    Put_Line (Integer'Image (A)); -- Prints 44
end In_Out_Params;
```

An in out parameter will allow read and write access to the object passed as parameter, so in the example above, we can see that A is modified after the call to Swap.

**Attention:** While in out parameters look a bit like references in C++, or regular parameters in Java that are passed by-reference, the Ada language standard does not mandate "by reference" passing for in out parameters except for certain categories of types as will be explained later.

In general, it is better to think of modes as higher level than by-value versus by-reference semantics. For the compiler, it means that an array passed as an in parameter might be passed by reference, because it is more efficient (which does not change anything for the user since the parameter is not assignable). However, a parameter of a discrete type will always be passed by copy, regardless of its mode (which is more efficient on most architectures).

#### 3.3.3 Out parameters

The "out" mode applies when the subprogram needs to write to a parameter that might be uninitialized at the point of call. Reading the value of an out parameter is permitted, but it should only be done after the subprogram has assigned a value to the parameter. Out parameters behave a bit like return values for functions. When the subprogram returns, the actual parameter (a variable) will have the value of the out parameter at the point of return.

#### In other languages

Ada doesn't have a tuple construct and does not allow returning multiple values from a subprogram (except by declaring a full-fledged record type). Hence, a way to return multiple values from a subprogram is to use out parameters.

For example, a procedure reading integers from the network could have one of the following specifications:

```
procedure Read_Int
  (Stream : Network_Stream; Success : out Boolean; Result : out Integer);
function Read_Int
  (Stream : Network_Stream; Result : out Integer) return Boolean;
```

While reading an out variable before writing to it should, ideally, trigger an error, imposing that as a rule would cause either inefficient run-time checks or complex compile-time rules. So from the user's perspective an out parameter acts like an uninitialized variable when the subprogram is invoked.

#### In the GNAT toolchain

GNAT will detect simple cases of incorrect use of out parameters. For example, the compiler will emit a warning for the following program:

```
procedure Outp is
   procedure Foo (A : out Integer) is
        B : Integer := A; -- Warning on reference to uninitialized A
   begin
        A := B;
   end Foo;
begin
   null;
end Outp;
```

#### 3.3.4 Forward declaration of subprograms

As we saw earlier, a subprogram can be declared without being fully defined, This is possible in general, and can be useful if you need subprograms to be mutually recursive, as in the example below:

```
procedure Mutually_Recursive_Subprograms is
    procedure Compute_A (V : Natural);
    -- Forward declaration of Compute_A
    procedure Compute_B (V : Natural) is
    begin
       if V > 5 then
          Compute A (V - 1);
             Call to Compute A
       end if;
    end Compute B;
    procedure Compute_A (V : Natural) is
    begin
       if V > 2 then
          Compute_B (V - 1);
          -- Call to Compute_B
       end if;
    end Compute A;
begin
   Compute_A (15);
end Mutually_Recursive_Subprograms;
```

**CHAPTER** 

**FOUR** 

#### MODULAR PROGRAMMING

So far, our examples have been simple standalone subprograms. Ada is helpful in that regard, since it allows arbitrary declarations in a declarative part. We were thus able to declare our types and variables in the bodies of main procedures.

However, it is easy to see that this is not going to scale up for real-world applications. We need a better way to structure our programs into modular and distinct units.

Ada encourages the separation of programs into multiple packages and sub-packages, providing many tools to a programmer on a quest for a perfectly organized code-base.

# 4.1 Packages

Here is an example of a package declaration in Ada:

```
package Week is

Mon : constant String := "Monday";
  Tue : constant String := "Tuesday";
  Wed : constant String := "Wednesday";
  Thu : constant String := "Thursday";
  Fri : constant String := "Friday";
  Sat : constant String := "Saturday";
  Sun : constant String := "Sunday";
end Week;
```

And here is how you use it:

```
with Ada.Text_IO; use Ada.Text_IO;
with Week;
-- References the Week package, and adds a dependency from Main
-- to Week

procedure Main is
begin
    Put_Line ("First day of the week is " & Week.Mon);
end Main;
```

Packages let you make your code modular, separating your programs into semantically significant units. Additionally the separation of a package's specification from its body (which we will see below) can reduce compilation time.

While the with clause indicates a dependency, you can see in the example above that you still need to prefix the referencing of entities from the Week package by the name of the package. (If we had included a use Week clause, then such a prefix would not have been necessary.)

Accessing entities from a package uses the dot notation, A.B, which is the same notation as the one used to access record fields.

A with clause can *only* appear in the prelude of a compilation unit (i.e., before the reserved word, such as procedure, that marks the beginning of the unit). It is not allowed anywhere else. This rule is only needed for methodological reasons: the person reading your code should be able to see immediately which units the code depends on.

#### In other languages

Packages look similar to, but are semantically very different from, header files in C/C++.

- The first and most important distinction is that packages are a language-level mechanism. This is in contrast to a #include'd header file, which is a functionality of the C preprocessor.
- An immediate consequence is that the with construct is a semantic inclusion mechanism, not a text inclusion mechanism. Hence, when you with a package, you are saying to the compiler "I'm depending on this semantic unit", and not "include this bunch of text in place here".
- The effect of a package thus does not vary depending on where it has been withed from. Contrast this with C/C++, where the meaning of the included text depends on the context in which the #include appears.

This allows compilation/recompilation to be more efficient. It also allows tools like IDEs to have correct information about the semantics of a program. In turn, this allows better tooling in general, and code that is more analyzable, even by humans.

An important benefit of Ada with clauses when compared to #include is that it is stateless. The order of with and use clauses does not matter, and can be changed without side effects.

#### In the GNAT toolchain

The Ada language standard does not mandate any particular relationship between source files and packages; for example, in theory you can put all your code in one file, or use your own file naming conventions. In practice, however, an implementation will have specific rules. With GNAT, each top-level compilation unit needs to go into a separate file. In the example above, the Week package will be in an .ads file (for Ada specification), and the Main procedure will be in an .adb file (for Ada body).

# 4.2 Using a package

As we have seen above, the with clause indicates a dependency on another package. However, every reference to an entity coming from the Week package had to be prefixed by the full name of the package. It is possible to make every entity of a package visible directly in the current scope, using the use clause.

In fact, we have been using the use clause since almost the beginning of this tutorial.

```
Put_Line ("First day of the week is " & Mon);
end Main;
```

As you can see in the example above:

- Put\_Line is a subprogram that comes from the Ada.Text\_IO package. We can reference it directly because we have used the package at the top of the Main unit.
- Unlike with clauses, a use clause can be placed either in the prelude, or in any declarative region. In the latter case the use clause will have an effect in its containing lexical scope.

# 4.3 Package body

In the simple example above, the Week package only has declarations and no body. That's not a mistake: in a package specification, which is what is illustrated above, you cannot declare bodies. Those have to be in the package body.

```
package Operations is

-- Declaration
function Increment_By
   (I : Integer;
    Incr : Integer := 0) return Integer;

function Get_Increment_Value return Integer;
end Operations;
```

```
package body Operations is
  Last_Increment : Integer := 1;
  function Increment By
     (I : Integer;
      Incr : Integer := 0) return Integer is
  begin
     if Incr /= 0 then
        Last Increment := Incr;
     end if;
      return I + Last_Increment;
  end Increment By;
  function Get_Increment_Value return Integer is
  begin
      return Last Increment;
  end Get_Increment_Value;
end Operations;
```

Here we can see that the body of the Increment\_By function has to be declared in the body. Coincidentally, introducing a body allows us to put the Last\_Increment variable in the body, and make them inaccessible to the user of the Operations package, providing a first form of encapsulation.

This works because entities declared in the body are *only* visible in the body.

This example shows how Last\_Increment is used indirectly:

```
with Ada.Text_IO; use Ada.Text_IO;
with Operations;
procedure Main is
   use Operations;
   I : Integer := 0;
   R : Integer;
   procedure Display Update Values is
     Incr : constant Integer := Get_Increment_Value;
   begin
      Put Line (Integer'Image (I)
                & " incremented by " & Integer'Image (Incr)
                & " is "
                                     & Integer'Image (R));
      I := R;
   end Display_Update_Values;
begin
   R := Increment_By (I);
   Display_Update_Values;
   R := Increment_By (I);
   Display_Update_Values;
   R := Increment By (I, 5);
   Display_Update_Values;
   R := Increment_By (I);
   Display_Update_Values;
   R := Increment_By (I, 10);
   Display Update Values;
   R := Increment By (I);
   Display_Update_Values;
end Main;
```

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**CHAPTER** 

**FIVE** 

#### STRONGLY TYPED LANGUAGE

Ada is a strongly typed language. It is interestingly modern in that respect: strong static typing has been increasing in popularity in programming language design, owing to factors such as the growth of statically typed functional programming, a big push from the research community in the typing domain, and many practical languages with strong type systems.

### 5.1 What is a type?

In statically typed languages, a type is mainly (but not only) a *compile time* construct. It is a construct to enforce invariants about the behavior of a program. Invariants are unchangeable properties that hold for all variables of a given type. Enforcing them ensures, for example, that variables of a data type never have invalid values.

A type is used to reason about the *objects* a program manipulates (an object is a variable or a constant). The aim is to classify objects by what you can accomplish with them (i.e., the operations that are permitted), and this way you can reason about the correctness of the objects' values.

# **5.2 Integers**

A nice feature of Ada is that you can define your own integer types, based on the requirements of your program (i.e., the range of values that makes sense). In fact, the definitional mechanism that Ada provides forms the semantic basis for the predefined integer types. There is no "magical" built-in type in that regard, which is unlike most languages, and arguably very elegant.

This example illustrates the declaration of a signed integer type, and several things we can do with them.

Every type declaration in Ada starts with the type keyword (except for *task types* (page 90)). After the type, we can see a range that looks a lot like the ranges that we use in for loops, that defines the low and high bound of the type. Every integer in the inclusive range of the bounds is a valid value for the type.

#### Ada integer types

In Ada, an integer type is not specified in terms of its machine representation, but rather by its range. The compiler will then choose the most appropriate representation.

Another point to note in the above example is the My\_Int'Image (I) expression. The Name'Attribute (optional params) notation is used for what is called an attribute in Ada. An attribute is a built-in operation on a type, a value, or some other program entity. It is accessed by using a 'symbol (the ASCII apostrophe).

Ada has several types available as "built-ins"; Integer is one of them. Here is how Integer might be defined for a typical processor:

```
type Integer is range -(2 ** 31) .. +(2 ** 31 - 1);
```

\*\* is the exponent operator, which means that the first valid value for Integer is  $-2^{31}$ , and the last valid value is  $2^{31} - 1$ .

Ada does not mandate the range of the built-in type Integer. An implementation for a 16-bit target would likely choose the range  $-2^{15}$  through  $2^{15}-1$ .

#### 5.2.1 Operational semantics

Unlike some other languages, Ada requires that operations on integers should be checked for overflow.

```
procedure Main is
   A: Integer := Integer'Last;
   B: Integer;
begin
   B:= A + 5;
   -- This operation will overflow, eg. it will
   -- raise an exception at run time.
end Main;
```

There are two types of overflow checks:

- Machine-level overflow, when the result of an operation exceeds the maximum value (or is less than the minimum value) that can be represented in the storage reserved for an object of the type, and
- Type-level overflow, when the result of an operation is outside the range defined for the type.

Mainly for efficiency reasons, while machine level overflow always results in an exception, type level overflows will only be checked at specific boundaries, like assignment:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Main is
  type My_Int is range 1 .. 20;
  A : My_Int := 12;
  B : My_Int := 15;
  M : My_Int := (A + B) / 2;
  -- No overflow here, overflow checks are done at
  -- specific boundaries.
```

```
begin
   for I in 1 .. M loop
     Put_Line ("Hello, World!");
   end loop;
   -- Loop body executed 13 times
end Main;
```

Type level overflow will only be checked at specific points in the execution. The result, as we see above, is that you might have an operation that overflows in an intermediate computation, but no exception will be raised because the final result does not overflow.

### 5.3 Unsigned types

Ada also features unsigned Integer types. They're called *modular* types in Ada parlance. The reason for this designation is due to their behavior in case of overflow: They simply "wrap around", as if a modulo operation was applied.

For machine sized modular types, for example a modulus of 2\*\*32, this mimics the most common implementation behavior of unsigned types. However, an advantage of Ada is that the modulus is more general:

Unlike in C/C++, since this behavior is guaranteed by the Ada specification, you can rely on it to implement portable code. Also, being able to leverage the wrapping on arbitrary bounds is very useful – the modulus does not need to be a power of 2 – to implement certain algorithms and data structures, such as ring buffers<sup>9</sup>.

#### 5.4 Enumerations

Enumeration types are another nicety of Ada's type system. Unlike C's enums, they are *not* integers, and each new enumeration type is incompatible with other enumeration types. Enumeration types are part of the bigger family of discrete types, which makes them usable in certain situations that we will describe later but one context that we have already seen is a case statement.

<sup>&</sup>lt;sup>9</sup> https://en.m.wikipedia.org/wiki/Circular\_buffer

```
Thursday, Friday, Saturday, Sunday);
-- An enumeration type
begin
for I in Days loop
    case I is
        when Saturday .. Sunday =>
            Put_Line ("Week end!");

        when Monday .. Friday =>
            Put_Line ("Hello on " & Days'Image (I));
        -- 'Image attribute, works on enums too
        end case;
    end loop;
end Enumeration_Example;
```

Enumeration types are powerful enough that, unlike in most languages, they're used to define the standard Boolean type:

```
type Boolean is (False, True);
```

As mentioned previously, every "built-in" type in Ada is defined with facilities generally available to the user.

### 5.5 Floating-point types

#### 5.5.1 Basic properties

Like most languages, Ada supports floating-point types. The most commonly used floating-point type is Float:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Floating_Point_Demo is
    A : Float := 2.5;
begin
    Put_Line ("The value of A is " & Float'Image (A));
end Floating_Point_Demo;
```

The application will display 2.5 as the value of A.

The Ada language does not specify the precision (number of decimal digits in the mantissa) for Float; on a typical 32-bit machine the precision will be 6.

All common operations that could be expected for floating-point types are available, including absolute value and exponentiation. For example:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Floating_Point_Operations is
    A : Float := 2.5;
begin
    A := abs (A - 4.5);
    Put_Line ("The value of A is " & Float'Image (A));
    A := A ** 2 + 1.0;
    Put_Line ("The value of A is " & Float'Image (A));
end Floating_Point_Operations;
```

The value of A is 2.0 after the first operation and 5.0 after the second operation.

In addition to Float, an Ada implementation may offer data types with higher precision such as Long\_Float and Long\_Long\_Float. Like Float, the standard does not indicate the exact precision of these types: it only guarantees that the type Long\_Float, for example, has at least the precision of Float. In order to guarantee that a certain precision requirement is met, we can define custom floating-point types, as we will see in the next section.

#### 5.5.2 Precision of floating-point types

Ada allows the user to specify the precision for a floating-point type, expressed in terms of decimal digits. Operations on these custom types will then have at least the specified precision. The syntax for a simple floating-point type declaration is:

```
type T is digits <number_of_decimal_digits>;
```

The compiler will choose a floating-point representation that supports the required precision. For example:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Custom_Floating_Types is
   type T3   is digits 3;
   type T15   is digits 15;
   type T18   is digits 18;

begin
   Put_Line ("T3   requires " & Integer'Image (T3'Size) & " bits");
   Put_Line ("T15   requires " & Integer'Image (T15'Size) & " bits");
   Put_Line ("T18   requires " & Integer'Image (T18'Size) & " bits");
end Custom_Floating_Types;
```

In this example, the attribute 'Size is used to retrieve the number of bits used for the specified data type. As we can see by running this example, the compiler allocates 32 bits for T3, 64 bits for T15 and 128 bits for T18. This includes both the mantissa and the exponent.

The number of digits specified in the data type is also used in the format when displaying floating-point variables. For example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Display_Custom_Floating_Types is
    type T3    is digits 3;
    type T18 is digits 18;

C1 : constant := 1.0e-4;

A : T3 := 1.0 + C1;
B : T18 := 1.0 + C1;
begin
    Put_Line ("The value of A is " & T3'Image (A));
    Put_Line ("The value of B is " & T18'Image (B));
end Display_Custom_Floating_Types;
```

As expected, the application will display the variables according to specified precision (1.00E+00 and 1.000100000000000E+00).

#### 5.5.3 Range of floating-point types

In addition to the precision, a range can also be specified for a floating-point type. The syntax is similar to the one used for integer data types — using the range keyword. This simple example

creates a new floating-point type based on the type Float, for a normalized range between -1.0 and 1.0:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Floating_Point_Range is
   type T_Norm is new Float range -1.0 .. 1.0;
   A : T_Norm;

begin
   A := 1.0;
   Put_Line ("The value of A is " & T_Norm'Image (A));
end Floating_Point_Range;
```

The application is responsible for ensuring that variables of this type stay within this range; otherwise an exception is raised. In this example, the exception Constraint\_Error is raised when assigning 2.0 to the variable A:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Floating_Point_Range_Exception is
    type T_Norm is new Float range -1.0 .. 1.0;
    A : T_Norm;

begin
    A := 2.0;
    Put_Line ("The value of A is " & T_Norm'Image (A));
end Floating_Point_Range_Exception;
```

Ranges can also be specified for custom floating-point types. For example:

```
with Ada.Text_IO; use Ada.Text_IO;
with Ada.Numerics; use Ada.Numerics;

procedure Custom_Range_Types is
   type T6_Inv_Trig is digits 6 range -Pi / 2.0 .. Pi / 2.0;
begin
   null;
end Custom_Range_Types;
```

In this example, we are defining a type called T6\_Inv\_Trig, which has a range from  $-\pi/2$  to  $\pi/2$  with a minimum precision of 6 digits. (Pi is defined in the predefined package Ada. Numerics.)

# 5.6 Strong typing

As noted earlier, Ada is strongly typed. As a result, different types of the same family are incompatible with each other; a value of one type cannot be assigned to a variable from the other type. For example:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Illegal_Example is
    -- Declare two different floating point types
    type Meters is new Float;
    type Miles is new Float;

Dist_Imperial: Miles;

-- Declare a constant
    Dist_Metric: constant Meters := 100.0;
begin
```

```
-- Not correct: types mismatch
Dist_Imperial := (Dist_Metric * 1609.0) / 1000.0;
Put_Line (Miles'Image (Dist_Imperial));
end Illegal_Example;
```

A consequence of these rules is that, in the general case, a "mixed mode" expression like 2 \* 3.0 will trigger a compilation error. In a language like C or Python, such expressions are made valid by implicit conversions. In Ada, such conversions must be made explicit:

Of course, we probably do not want to write the conversion code every time we convert from meters to miles. The idiomatic Ada way in that case would be to introduce conversion functions along with the types.

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Conv is
   type Meters is new Float;
   type Miles is new Float;
      Function declaration, like procedure but returns a value.
  function To_Miles (M : Meters) return Miles is
                                  ^ Return type
  begin
     return (Miles (M) * 1609.0) / 1000.0;
  end To_Miles;
  Dist Imperial : Miles;
  Dist Metric
                : constant Meters := 100.0;
  Dist Imperial := To Miles (Dist Metric);
  Put_Line (Miles'Image (Dist_Imperial));
end Conv;
```

If you write a lot of numeric code, having to explicitly provide such conversions might seem painful at first. However, this approach brings some advantages. Notably, you can rely on the absence of implicit conversions, which will in turn prevent some subtle errors.

#### In other languages

In C, for example, the rules for implicit conversions may not always be completely obvious. In Ada, however, the code will always do exactly what it seems to do. For example:

```
int a = 3, b = 2;
float f = a / b;
```

This code will compile fine, but the result of f will be 1.0 instead of 1.5, because the compiler will generate an integer division (three divided by two) that results in one. The software developer

must be aware of data conversion issues and use an appropriate casting:

```
int a = 3, b = 2;
float f = (float)a / b;
```

In the corrected example, the compiler will convert both variables to their corresponding floating-point representation before performing the division. This will produce the expected result.

This example is very simple, and experienced C developers will probably notice and correct it before it creates bigger problems. However, in more complex applications where the type declaration is not always visible — e.g. when referring to elements of a struct — this situation might not always be evident and quickly lead to software defects that can be harder to find.

The Ada compiler, in contrast, will always reject code that mixes floating-point and integer variables without explicit conversion. The following Ada code, based on the erroneous example in C, will not compile:

```
procedure Main is
   A : Integer := 3;
   B : Integer := 2;
   F : Float;
begin
   F := A / B;
end Main;
```

The offending line must be changed to F := Float(A) / Float(B); in order to be accepted by the compiler.

• You can use Ada's strong typing to help enforce invariants in your code, as in the example above: Since Miles and Meters are two different types, you cannot mistakenly convert an instance of one to an instance of the other.

# 5.7 Derived types

In Ada you can create new types based on existing ones. This is very useful: you get a type that has the same properties as some existing type but is treated as a distinct type in the interest of strong typing.

```
procedure Main is
   -- ID card number type, incompatible with Integer.
   type Social Security Number
   is new Integer range 0 .. 999 99 9999;
                         ^{\wedge} Since \overline{a} \overline{SSN} has 9 digits max, and cannot be
                            negative, we enforce a validity constraint.
   SSN : Social Security Number := 555 55 5555;
                                      ^ You can put underscores as formatting in
   - -
                                       any number.
       : Integer;
   Invalid : Social Security Number := -1;
                                          ^ This will cause a runtime error
   - -
                                            (and a compile time warning with
                                             GNAT)
begin
   I := SSN;
                                          -- Illegal, they have different types
   SSN := I;
                                         -- Likewise illegal
   I := Integer (SSN);
                                          -- OK with explicit conversion
```

(continues on next page)

```
SSN := Social_Security_Number (I); -- Likewise OK
end Main;
```

The type Social\_Security is said to be a derived type; its parent type is Integer.

As illustrated in this example, you can refine the valid range when defining a derived scalar type (such as integer, floating-point and enumeration).

The syntax for enumerations uses the range < range > syntax:

## 5.8 Subtypes

As we are starting to see, types may be used in Ada to enforce constraints on the valid range of values. However, we sometimes want to enforce constraints on some values while staying within a single type. This is where subtypes come into play. A subtype does not introduce a new type.

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Greet is
  type Days is (Monday, Tuesday, Wednesday, Thursday,
                 Friday, Saturday, Sunday);
   -- Declaration of a subtype
  subtype Weekend_Days is Days range Saturday .. Sunday;
                                ^ Constraint of the subtype
  M : Days := Sunday;
  S : Weekend_Days := M;
  -- No error here, Days and Weekend_Days are of the same type.
begin
   for I in Days loop
     case I is
         -- Just like a type, a subtype can be used as a
         -- range
         when Weekend Days =>
           Put_Line ("Week end!");
         when others =>
           Put_Line ("Hello on " & Days'Image (I));
      end case;
  end loop;
end Greet;
```

Several subtypes are predefined in the standard package in Ada, and are automatically available to you:

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```
subtype Natural is Integer range 0 .. Integer'Last;
subtype Positive is Integer range 1 .. Integer'Last;
```

While subtypes of a type are statically compatible with each other, constraints are enforced at run time: if you violate a subtype constraint, an exception will be raised.

**CHAPTER** 

SIX

#### **RECORDS**

So far, all the types we have encountered have values that are not decomposable: each instance represents a single piece of data. Now we are going to see our first class of composite types: records.

Records allow composing a value out of instances of other types. Each of those instances will be given a name. The pair consisting of a name and an instance of a specific type is called a field, or a component.

### 6.1 Record type declaration

Here is an example of a simple record declaration:

```
type Date is record
    -- The following declarations are components of the record
    Day : Integer range 1 .. 31;
    Month : Month_Type;
    Year : Integer range 1 .. 3000; -- You can add custom constraints on fields
end record;
```

Fields look a lot like variable declarations, except that they are inside of a record definition. And as with variable declarations, you can specify additional constraints when supplying the subtype of the field.

Record components can have default values. When a variable having the record type is declared, a field with a default initialization will be automatically set to this value. The value can be any expression of the component type, and may be run-time computable.

# **6.2 Aggregates**

Records have a convenient notation for expressing values, illustrated above. This notation is called aggregate notation, and the literals are called aggregates. They can be used in a variety of contexts that we will see throughout the course, one of which is to initalize records.

An aggregate is a list of values separated by commas and enclosed in parentheses. It is allowed in any context where a value of the record is expected.

Values for the components can be specified positionally, as in Ada\_Birthday example, or by name, as in Leap\_Day\_2020. A mixture of positional and named values is permitted, but you cannot use a positional notation after a named one.

# **6.3 Component selection**

To access components of a record instance, you use an operation that is called component selection:

```
with Ada.Text IO; use Ada.Text IO;
procedure Record Selection is
   type Month Type is
     (January, February, March, April, May, June, July,
      August, September, October, November, December);
   type Date is record
      Day : Integer range 1 .. 31;
      Month: Month Type;
      Year : Integer range 1 .. 3000 := 2032;
   end record:
   Some Day : Date := (1, January, 2000);
begin
   Some Day. Year := 2001;
   Put Line ("Day:" & Integer'Image (Some Day.Day)
              & ", Month: " & Month_Type'Image (Some_Day.Month) & ", Year:" & Integer'Image (Some_Day.Year));
end Record Selection;
```

CHAPTER

**SEVEN** 

#### **ARRAYS**

Arrays provide another fundamental family of composite types in Ada.

## 7.1 Array type declaration

Arrays in Ada are used to define contiguous collections of elements that can be selected by indexing. Here's a simple example:

```
with Ada.Text IO; use Ada.Text IO;
procedure Greet is
   type My Int is range 0 .. 1000;
   type Index is range 1 .. 5;
  type My_Int_Array is array (Index) of My_Int;
                                         ^ Type of elements
                               ^ Bounds of the array
  Arr : My_Int_Array := (2, 3, 5, 7, 11);
                         ^ Array literal, called aggregate in Ada
begin
   for I in Index loop
     Put (My_Int'Image (Arr (I)));
                              `Take the Ith element
  end loop;
  New Line;
end Greet;
```

The first point to note is that we specify the index type for the array, rather than its size. Here we declared an integer type named Index ranging from 1 to 5, so each array instance will have 5 elements, with the initial element at index 1 and the last element at index 5.

Although this example used an integer type for the index, Ada is more general: any discrete type is permitted to index an array, including *Enum types* (page 27). We will soon see what that means.

Another point to note is that querying an element of the array at a given index uses the same syntax as for function calls: that is, the array object followed by the index in parentheses.

Thus when you see an expression such as A (B), whether it is a function call or an array subscript depends on what A refers to.

Finally, notice how we initialize the array with the (2, 3, 5, 7, 11) expression. This is another kind of aggregate in Ada, and is in a sense a literal expression for an array, in the same way that 3 is a literal expression for an integer. The notation is very powerful, with a number of properties that we will introduce later. A detailed overview appears in the notation of aggregate types (page 47).

Unrelated to arrays, the example also illustrated two procedures from Ada.Text\_IO:

• Put, which displays a string without a terminating end of line

New Line, which outputs an end of line

Let's now delve into what it means to be able to use any discrete type to index into the array.

#### In other languages

Semantically, an array object in Ada is the entire data structure, and not simply a handle or pointer. Unlike C and C++, there is no implicit equivalence between an array and a pointer to its initial element.

One effect is that the bounds of an array can be any values. In the first example we constructed an array type whose first index is 1, but in the example above we declare an array type whose first index is 11.

That's perfectly fine in Ada, and moreover since we use the index type as a range to iterate over the array indices, the code using the array does not need to change.

That leads us to an important consequence with regard to code dealing with arrays. Since the bounds can vary, you should not assume / hard-code specific bounds when iterating / using arrays. That means the code above is good, because it uses the index type, but a for loop as shown below is bad practice even though it works correctly:

```
for I in 11 .. 15 loop
   Tab (I) := Tab (I) * 2;
end loop;
```

Since you can use any discrete type to index an array, enumeration types are permitted.

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In the example above, we are:

- Creating an array type mapping months to month durations in days.
- Creating an array, and instantiating it with an aggregate mapping months to their actual durations in days.
- Iterating over the array, printing out the months, and the number of days for each.

Being able to use enumeration values as indices is very helpful in creating mappings such as shown above one, and is an often used feature in Ada.

## 7.2 Indexing

We have already seen the syntax for selecting elements of an array. There are however a few more points to note.

First, as is true in general in Ada, the indexing operation is strongly typed. If you use a value of the wrong type to index the array, you will get a compile-time error.

Second, arrays in Ada are bounds checked. This means that if you try to access an element outside of the bounds of the array, you will get a run-time error instead of accessing random memory as in unsafe languages.

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Greet is
  type My_Int is range 0 .. 1000;
  type Index is range 1 .. 5;
  type My_Int_Array is array (Index) of My_Int;
  Tab : My_Int_Array := (2, 3, 5, 7, 11);
  (continues on next page)
```

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## 7.3 Simpler array declarations

In the previous examples, we have always explicitly created an index type for the array. While this can be useful for typing and readability purposes, sometimes you simply want to express a range of values. Ada allows you to do that, too.

This example defines the range of the array via the range syntax, which specifies an anonymous subtype of Integer and uses it to index the array.

This means that the type of the index is Integer. Similarly, when you use an anonymous range in a for loop as in the example above, the type of the iteration variable is also Integer, so you can use I to index Tab.

You can also use a named subtype for the bounds for an array.

# 7.4 Range attribute

We noted earlier that hard coding bounds when iterating over an array is a bad idea, and showed how to use the array's index type/subtype to iterate over its range in a for loop. That raises the question of how to write an iteration when the array has an anonymous range for its bounds, since there is no name to refer to the range. Ada solves that via several attributes of array objects:

(continues on next page)

```
Put (My_Int'Image (Tab (I)));
end loop;
New_Line;
end Range_Example;
```

If you want more fine grained control, you can use the separate attributes 'First and 'Last.

The 'Range, 'First and 'Last attributes in these examples could also have been applied to the array type name, and not just the array instances.

Although not illustrated in the above examples, another useful attribute for an array instance A is A'Length, which is the number of elements that A contains.

It is legal and sometimes useful to have a "null array", which contains no elements. To get this effect, define an index range whose upper bound is less than the lower bound.

# 7.5 Unconstrained arrays

Let's now consider one of the most powerful aspects of Ada's array facility.

Every array type we have defined so far has a fixed size: every instance of this type will have the same bounds and therefore the same number of elements and the same size.

However, Ada also allows you to declare array types whose bounds are not fixed: in that case, the bounds will need to be provided when creating instances of the type.

```
with Ada.Text IO; use Ada.Text IO;
procedure Unconstrained Array Example is
   type Days is (Monday, Tuesday, Wednesday,
                 Thursday, Friday, Saturday, Sunday);
  type Workload Type is array (Days range <>) of Natural;
   -- Indefinite array type
                                ^ Bounds are of type Days,
                                  but not known
  Workload : constant Workload Type (Monday .. Friday) :=
                                       ^ Specify the bounds
                                        when declaring
      (Friday => 7, others => 8);
                    ^ Default value
       ^ Specify element by name of index
begin
  for I in Workload'Range loop
```

(continues on next page)

```
Put_Line (Integer'Image (Workload (I)));
end loop;
end Unconstrained_Array_Example;
```

The fact that the bounds of the array are not known is indicated by the Days range <> syntax. Given a discrete type Discrete\_Type, if we use Discrete\_Type for the index in an array type then Discrete\_Type serves as the type of the index and comprises the range of index values for each array instance.

If we define the index as Discrete\_Type range <> then Discrete\_Type serves as the type of the index, but different array instances may have different bounds from this type

An array type that is defined with the Discrete\_Type range <> syntax for its index is referred to as an unconstrained array type, and, as illustrated above, the bounds need to be provided when an instance is created.

The above example also shows other forms of the aggregate syntax. You can specify associations by name, by giving the value of the index on the left side of an arrow association.  $1 \Rightarrow 2$  thus means "assign value 2 to the element at index 1 in my array". others  $\Rightarrow$  8 means "assign value 8 to every element that wasn't previously assigned in this aggregate".

**Attention:** The so-called "box" notation (<>) is commonly used as a wildcard or placeholder in Ada. You will often see it when the meaning is "what is expected here can be anything".

#### In other languages

While unconstrained arrays in Ada might seem similar to variable length arrays in C, they are in reality much more powerful, because they're truly first-class values in the language. You can pass them as parameters to subprograms or return them from functions, and they implicitly contain their bounds as part of their value. This means that it is useless to pass the bounds or length of an array explictly along with the array, because they are accessible via the 'First, 'Last, 'Range and 'Length attributes explained earlier.

Although different instances of the same unconstrained array type can have different bounds, a specific instance has the same bounds throughout its lifetime. This allows Ada to implement unbounded arrays efficiently; instances can be stored on the stack and do not require heap allocation as in languages like lava.

# 7.6 Predefined array type: String

A recurring theme in our introduction to Ada types has been the way important built-in types like Boolean or Integer are defined through the same facilities that are available to the user. This is also true for strings: The String type in Ada is a simple array.

Here is how the string type is defined in Ada:

```
type String is array (Positive range <>) of Character;
```

The only built-in feature Ada adds to make strings more ergonomic is custom literals, as we can see in the example below.

**Hint:** String literals are a syntactic sugar for aggregates, so that in the following example, A and B have the same value.

However, specifying the bounds of the object explicitly is a bit of a hassle; you have to manually count the number of characters in the literal. Fortunately, Ada gives you an easier way.

You can omit the bounds when creating an instance of an unconstrained array type if you supply an initialization, since the bounds can be deduced from the initialization expression.

**Attention:** As you can see above, the standard String type in Ada is an array. As such, it shares the advantages and drawbacks of arrays: a String value is stack allocated, it is accessed efficiently, and its bounds are immutable.

If you want something akin to C++'s std::string, you can use *Unbounded Strings* (page 148) from Ada's standard library. This type is more like a mutable, automatically managed string buffer to which you can add content.

#### 7.7 Restrictions

A very important point about arrays: bounds *have* to be known when instances are created. It is for example illegal to do the following.

```
declare
   A : String;
begin
   A := "World";
end;
```

Also, while you of course can change the values of elements in an array, you cannot change the array's bounds (and therefore its size) after it has been initialized. So this is also illegal:

Also, while you can expect a warning for this kind of error in very simple cases like this one, it is impossible for a compiler to know in the general case if you are assigning a value of the correct length, so this violation will generally result in a run-time error.

**Attention:** While we will learn more about this later, it is important to know that arrays are not the only types whose instances might be of unknown size at compile-time.

Such objects are said to be of an *indefinite subtype*, which means that the subtype size is not known at compile time, but is dynamically computed (at run time).

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Indefinite_Subtypes is
    function Get_Number return Integer is
    begin
        return Integer'Value (Get_Line);
    end Get_Number;

A : String := "Hello";
    -- Indefinite subtype

B : String (1 .. 5) := "Hello";
    -- Definite subtype

C : String (1 .. Get_Number);
    -- Indefinite subtype (Get_Number's value is computed at run-time)
begin
    null;
end Indefinite_Subtypes;
```

# 7.8 Returning unconstrained arrays

The return type of a function can be any type; a function can return a value whose size is unknown at compile time. Likewise, the parameters can be of any type.

For example, this is a function that returns an unconstrained String:

```
with Ada.Text IO; use Ada.Text IO;
procedure Main is
   type Days is (Monday, Tuesday, Wednesday,
                 Thursday, Friday, Saturday, Sunday);
  function Get Day Name (Day : Days := Monday) return String is
  begin
      return
        (case Day is
         when Monday => "Monday",
         when Tuesday => "Tuesday",
         when Wednesday => "Wednesday",
         when Thursday => "Thursday",
         when Friday => "Friday",
         when Saturday => "Saturday",
         when Sunday => "Sunday");
  end Get Day Name;
begin
  Put Line ("First day is " & Get Day Name (Days'First));
end Main;
```

(This example is for illustrative purposes only. There is a built-in mechanism, the 'Image attribute for scalar types, that returns the name (as a String) of any element of an enumeration type. For example Days'Image(Monday) is "MONDAY".)

#### In other languages

Returning variable size objects in languages lacking a garbage collector is a bit complicated implementation-wise, which is why C and C++ don't allow it, preferring to depend on explicit dynamic allocation / free from the user.

The problem is that explicit storage management is unsafe as soon as you want to collect unused memory. Ada's ability to return variable size objects will remove one use case for dynamic allocation, and hence, remove one potential source of bugs from your programs.

Rust follows the C/C++ model, but with safe pointer semantics. However, dynamic allocation is still used. Ada can benefit from an eventual performance edge because it can use any model.

# 7.9 Declaring arrays (2)

While we can have array types whose size and bounds are determined at run time, the array's component type needs to be of a definite and constrained type.

Thus, if you need to declare, for example, an array of Strings, the String subtype used as component will need to have a fixed size.

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## 7.10 Array slices

One last feature of Ada arrays that we're going to cover is array slices. It is possible to take and use a slice of an array (a contiguous sequence of elements) as a name or a value.

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Main is
    Buf : String := "Hello ...";

Full_Name : String := "John Smith";

begin
    Buf (7 .. 9) := "Bob";
    -- Careful! This works because the string on the right side is the
    -- same length as the replaced slice!

Put_Line (Buf); -- Prints "Hello Bob"

Put_Line ("Hi " & Full_Name (1 .. 4)); -- Prints "Hi John"
end Main;
```

As we can see above, you can use a slice on the left side of an assignment, to replace only part of an array.

A slice of an array is of the same type as the array, but has a different subtype, constrained by the bounds of the slice.

**Attention:** Ada has multidimensional arrays<sup>10</sup>, which are not covered in this course. Slices will only work on one dimensional arrays.

<sup>&</sup>lt;sup>10</sup> http://www.adaic.org/resources/add\_content/standards/12rm/html/RM-3-6.html

**CHAPTER** 

**EIGHT** 

#### **MORE ABOUT TYPES**

### 8.1 Aggregates: A primer

So far, we have talked about aggregates quite a bit and have seen a number of examples. Now we will revisit this feature in some more detail.

An Ada aggregate is, in effect, a literal value for a composite type. It's a very powerful notation that helps you to avoid writing procedural code for the initialization of your data structures in many cases.

A basic rule when writing aggregates is that *every component* of the array or record has to be specified, even components that have a default value.

This means that the following code is incorrect:

```
package Incorrect is
  type Point is record
    X, Y : Integer := 0;
  end record;

Origin : Point := (X => 0);
end Incorrect;
```

There are a few shortcuts that you can use to make the notation more convenient:

- To specify the default value for a component, you can use the <> notation.
- You can use the | symbol to give several components the same value.
- You can use the others choice to refer to every component that has not yet been specified, provided all those fields have the same type.
- You can use the range notation . . to refer to specify a contiguous sequence of indices in an array.

However, note that as soon as you used a named association, all subsequent components likewise need to be specified with names associations.

```
package Points is
  type Point is record
    X, Y : Integer := 0;
end record;

type Point_Array is array (Positive range <>) of Point;

Origin : Point := (X | Y => <>); -- use the default values
Origin_2 : Point := (others => <>); -- likewise use the defaults

Points_1 : Point_Array := ((1, 2), (3, 4));
Points_2 : Point_Array := (1 => (1, 2), 2 => (3, 4), 3 ... 20 => <>);
end Points;
```

### 8.2 Overloading and qualified expressions

Ada has a general concept of name overloading, which we saw earlier in the section on *enumeration types* (page 27).

Let's take a simple example: it is possible in Ada to have functions that have the same name, but different types for their parameters.

```
package Pkg is
  function F (A : Integer) return Integer;
  function F (A : Character) return Integer;
end Pkg;
```

This is a common concept in programming languages, called overloading<sup>11</sup>, or name overloading.

One of the novel aspects of Ada's overloading facility is the ability to resolve overloading based on the return type of a function.

```
package Pkg is
    type SSID is new Integer;

function Convert (Self : SSID) return Integer;
    function Convert (Self : SSID) return String;
end Pkg;

with Ada.Text_IO; use Ada.Text_IO;
```

**Attention:** Note that overload resolution based on the type is allowed for both functions and enumeration literals in Ada - which is why you can have multiple enumeration literals with the same name. Semantically, an enumeration literal is treated like a function that has no parameters.

However, sometimes an ambiguity makes it impossible to resolve which declaration of an overloaded name a given occurrence of the name refers to. This is where a qualified expression becomes useful.

```
package Pkg is
   type SSID is new Integer;

function Convert (Self : SSID) return Integer;
  function Convert (Self : SSID) return String;
  function Convert (Self : Integer) return String;
end Pkg;
```

```
with Ada.Text_IO; use Ada.Text_IO;
with Pkg; use Pkg;
procedure Main is
   S : String := Convert (123_145_299);
```

(continues on next page)

<sup>11</sup> https://en.m.wikipedia.org/wiki/Function\_overloading

Syntactically the target of a qualified expression can be either any expression in parentheses, or an aggregate:

```
package Qual_Expr is
  type Point is record
    A, B : Integer;
  end record;

P : Point := Point'(12, 15);

A : Integer := Integer'(12);
end Qual_Expr;
```

This illustrates that qualified expressions are a convenient (and sometimes necessary) way for the programmer to make the type of an expression explicit, for the compiler of course, but also for other programmers.

**Attention:** While they look and feel similar, type conversions and qualified expressions are *not* the same.

A qualified expression specifies the exact type that the target expression will be resolved to, whereas a type conversion will try to convert the target and issue a run-time error if the target value cannot be so converted.

Note that you can use a qualified expression to convert from one subtype to another, with an exception raised if a constraint is violated.

```
X : Integer := Natural'(1);
```

# 8.3 Access types (pointers)

Pointers are a potentially dangerous construct, which conflicts with Ada's underlying philosophy.

There are two ways in which Ada helps shield programmers from the dangers of pointers:

- 1. One approach, which we have already seen, is to provide alternative features so that the programmer does not need to use pointers. Parameter modes, arrays, and varying size types are all constructs that can replace typical pointer usages in C.
- 2. Second, Ada has made pointers as safe and restricted as possible, but allows "escape hatches" when the programmer explicitly requests them and presumably will be exercising such features with appropriate care.

Here is how you declare a simple pointer type, or access type, in Ada:

This illustrates how to:

- Declare an access type whose values point to ("designate") objects from a specific type
- Declare a variable (access value) from this access type
- Give it a value of null

In line with Ada's strong typing philosophy, if you declare a second access type whose designated type is Date, the two access types will be incompatible with each other, and you will need an explicit type conversion to convert from one to the other:

#### In other languages

In most other languages, pointer types are structurally, not nominally typed, like they are in Ada, which means that two pointer types will be the same as long as they share the same target type and accessibility rules.

Not so in Ada, which takes some time getting used to. A seemingly simple problem is, if you want to have a canonical access to a type, where should it be declared? A commonly used pattern is that if you need an access type to a specific type you "own", you will declare it along with the type:

```
package Access_Types is
   type Point is record
    X, Y : Natural;
   end record;

   type Point_Access is access Point;
end Access_Types;
```

#### 8.3.1 Allocation (by type)

Once we have declared an access type, we need a way to give variables of the types a meaningful value! You can allocate a value of an access type with the new keyword in Ada.

```
with Dates; use Dates;

package Access_Types is
    type Date_Acc is access Date;

D : Date_Acc := new Date;
    ^ Allocate a new Date record
end Access_Types;
```

If the type you want to allocate needs constraints, you can put them in the subtype indication, just as you would do in a variable declaration:

In some cases, though, allocating just by specifiying the type is not ideal, so Ada also allows you to initialize along with the allocation. This is done via the qualified expression syntax:

```
with Dates; use Dates;

package Access_Types is
   type Date_Acc is access Date;
   type String_Acc is access String;

D : Date_Acc := new Date'(30, November, 2011);
   Msg : String_Acc := new String'("Hello");
end Access_Types;
```

#### 8.3.2 Dereferencing

The last important piece of Ada's access type facility is how to get from an access value to the object that is pointed to, that is, how to dereference the pointer. Dereferencing a pointer uses the .all syntax in Ada, but is often not needed - in many cases, the access value will be implicitly dereferenced for you:

#### 8.3.3 Other features

As you might know if you have used pointers in C or C++, we are still missing features that are considered fundamental to the use of pointers, such as:

- Pointer arithmetic (being able to increment or decrement a pointer in order to point to the next or previous object)
- Manual deallocation what is called free or delete in C. This is a potentially unsafe operation. To keep within the realm of safe Ada, you need to never deallocate manually.

Those features exist in Ada, but are only available through specific standard library APIs.

**Attention:** The guideline in Ada is that most of the time you can avoid manual allocation, and you should.

There are many ways to avoid manual allocation, some of which have been covered (such as parameter modes). The language also provides library abstractions to avoid pointers:

- 1. One is the use of *containers* (page 119). Containers help users avoid pointers, because container memory is automatically managed.
- 2. A container to note in this context is the Indefinite holder<sup>12</sup>. This container allows you to store a value of an indefinite type such as String.
- 3. GNATCOLL has a library for smart pointers, called Refcount<sup>13</sup> Those pointers' memory is automatically managed, so that when an allocated object has no more references to it, the memory is automatically deallocated.

# 8.4 Mutually recursive types

The linked list is a common idiom in data structures; in Ada this would be most naturally defined through two types, a record type and an access type, that are mutually dependent. To declare mutually dependent types, you can use an incomplete type declaration:

```
package Simple_List is
   type Node;
   -- This is an incomplete type declaration, which is
   -- completed in the same declarative region.

(continues on next page)
```

<sup>&</sup>lt;sup>12</sup> http://www.ada-auth.org/standards/12rat/html/Rat12-8-5.html

<sup>13</sup> https://github.com/AdaCore/gnatcoll-core/blob/master/src/gnatcoll-refcount.ads

```
type Node_Acc is access Node;

type Node is record
    Content : Natural;
    Prev, Next : Node_Acc;
end record;
end Simple_List;
```

#### 8.5 More about records

#### 8.5.1 Dynamically sized record types

We have previously seen some simple examples of record types. Let's now look at some of the more advanced properties of this fundamental language feature.

One point to note is that object size for a record type does not need to be known at compile time. This is illustrated in the example below:

```
package Runtime_Length is
   function Compute_Max_Len return Natural;
end Runtime_Length;
```

It is completely fine to determine the size of your records at run time, but note that all objects of this type will have the same size.

#### 8.5.2 Records with discriminant

In the example above, the size of the Items field is determined once, at run-time, but every Growable\_Stack instance will be exactly the same size. But maybe that's not what you want to do. We saw that arrays in general offer this flexibility: for an unconstrained array type, different objects can have different sizes.

You can get analogous functionality for records, too, using a special kind of field that is called a discriminant:

Discriminants, in their simple forms, are constant: You cannot modify them once you have initialized the object. This intuitively makes sense since they determine the size of the object.

Also, they make a type indefinite: Whether or not the discriminant is used to specify the size of an object, a type with a discriminant will be indefinite if the discriminant is not declared with an initialization:

```
package Test_Discriminants is
   type Point (X, Y : Natural) is record
      null;
   end record;

P : Point;
   -- ERROR: Point is indefinite, so you need to specify the discriminants
   -- or give a default value

P2 : Point (1, 2);
   P3 : Point := (1, 2);
   -- Those two declarations are equivalent.

end Test_Discriminants;
```

This also means that, in the example above, you cannot declare an array of Point values, because the size of a Point is not known.

In most other respects discriminants behave like regular fields: You have to specify their values in aggregates, as seen above, and you can access their values via the dot notation.

```
with Var Size Record 2; use Var Size Record 2;
with Ada.Text_IO; use Ada.Text_IO;
procedure Main is
   procedure Print_Stack (G : Growable_Stack) is
   begin
      Put ("<Stack, items: [");</pre>
      for I in G.Items'Range loop
         exit when I > G.Len;
         Put (" " & Integer'Image (G.Items (I)));
      end loop;
      Put_Line ("]>");
   end Print_Stack;
   S : Growable_Stack :=
     (Max_Len => 128, Items => (1, 2, 3, 4, others => <>), Len => 4);
begin
   Print_Stack (S);
end Main;
```

#### 8.5.3 Variant records

The examples of discriminants thus far have illustrated the declaration of records of varying size, by having components whose size depends on the discriminant.

However, discriminants can also be used to obtain the functionality of what are sometimes called "variant records": records that can contain different sets of fields.

```
package Variant Record is
  type Expr;
                                    -- Forward declaration of Expr
   type Expr_Access is access Expr; -- Access to a Expr
  type Expr_Kind_Type is (Bin_Op_Plus, Bin_Op_Minus, Num);
   -- A regular enumeration type
  type Expr (Kind : Expr_Kind_Type) is record
              ^ The discriminant is an enumeration value
      case Kind is
        when Bin_Op_Plus | Bin_Op_Minus =>
            Left, Right : Expr_Access;
        when Num =>
           Val : Integer;
      end case;
      -- Variant part. Only one, at the end of the record
      -- definition, but can be nested
   end record;
end Variant_Record;
```

The fields that are in a when branch will be only available when the value of the discriminant is covered by the branch. In the example above, you will only be able to access the fields Left and Right when the Kind is Bin Op Plus or Bin Op Minus.

If you try to access a field that is not valid for your record, a Constraint\_Error will be raised.

```
with Variant_Record; use Variant_Record;
procedure Main is
    E : Expr := (Num, 12);
begin
    E.Left := new Expr'(Num, 15);
    -- Will compile but fail at runtime
end Main;
```

Here is how you could write an evaluator for expressions:

#### In other languages

Ada's variant records are very similar to Sum types in functional languages such as OCaml or Haskell. A major difference is that the discriminant is a separate field in Ada, whereas the 'tag' of a Sum type is kind of built in, and only accessible with pattern matching.

There are other differences (you can have several discriminants in a variant record in Ada). Nevertheless, they allow the same kind of type modeling as sum types in functional languages.

Compared to C/C++ unions, Ada variant records are more powerful in what they allow, and are also checked at run time, which makes them safer.

### 8.6 Fixed-point types

#### 8.6.1 Decimal fixed-point types

We have already seen how to specify floating-point types. However, in some applications floating-point is not appropriate since, for example, the roundoff error from binary arithmetic may be unacceptable or perhaps the hardware does not support floating-point instructions. Ada provides a category of types, the decimal fixed-point types, that allows the programmer to specify the required decimal precision (number of digits) as well as the scalaing factor (a power of ten) and, optionally, a range. In effect the values will be represented as integers implicitly scaled by the specified power of 10. This is useful, for example, for financial applications.

The syntax for a simple decimal fixed-point type is

```
type <type-name> is delta <delta-value> digits <digits-value>;
```

In this case, the delta and the digits will be used by the compiler to derive a range.

Several attributes are useful for dealing with decimal types:

Attribute Name	Meaning
First	The first value of the type
Last	The last value of the type
Delta	The delta value of the type

In the example below, we declare two data types: T3\_D3 and T6\_D3. For both types, the delta value is the same: 0.001.

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Decimal_Fixed_Point_Types is
    type T3_D3 is delta 10.0 ** (-3) digits 3;
    type T6_D3 is delta 10.0 ** (-3) digits 6;

begin
    Put_Line ("The delta value of T3_D3 is " & T3_D3'Image (T3_D3'Delta));
    Put_Line ("The minimum value of T3_D3 is " & T3_D3'Image (T3_D3'First));
    Put_Line ("The maximum value of T3_D3 is " & T3_D3'Image (T3_D3'Last));
    New_Line;
    Put_Line ("The delta value of T6_D3 is " & T6_D3'Image (T6_D3'Delta));
    Put_Line ("The minimum value of T6_D3 is " & T6_D3'Image (T6_D3'First));
    Put_Line ("The maximum value of T6_D3 is " & T6_D3'Image (T6_D3'Last));
end Decimal_Fixed_Point_Types;
```

When running the application, we see that the delta value of both types is indeed the same: 0.001. However, because T3\_D3 is restricted to 3 digits, its range is -0.999 to 0.999. For the T6\_D3, we have defined a precision of 6 digits, so the range is -999.999 to 999.999.

Similar to the type definition using the range syntax, because we have an implicit range, the compiled code will check that the variables contain values that are not out-of-range. Also, if the result of a multiplication or division on decimal fixed-point types is smaller than the delta value required for the context, the actual result will be zero. For example:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Decimal_Fixed_Point_Smaller is
   type T3_D3 is delta 10.0 ** (-3) digits 3;
   type T6_D6 is delta 10.0 ** (-6) digits 6;
   A : T3_D3 := T3_D3'Delta;
   B : T3_D3 := 0.5;
   C : T6_D6;

begin
   Put_Line ("The value of A is " & T3_D3'Image (A));
   A := A * B;
   Put_Line ("The value of A * B is " & T3_D3'Image (A));
   A := T3_D3'Delta;
   C := A * B;
   Put_Line ("The value of A * B is " & T6_D6'Image (C));
end Decimal_Fixed_Point_Smaller;
```

In this example, the result of the operation 0.001\*0.5 is 0.0005. Since this value is not representable for the T3\_D3 type because the delta value is 0.001, the actual value stored in variable A is zero. However, accuracy is preserved during the arithmetic operations if the target has sufficient precision, and the value displayed for C is 0.000500.

#### 8.6.2 Fixed-point types

Ordinary fixed-point types are similar to decimal fixed-point types in that the values are, in effect, scaled integers. The difference between them is in the scale factor: for a decimal fixed-point type, the scaling, given explicitly by the type's delta, is always a power of ten.

In contrast, for an ordinary fixed-point type, the scaling is defined by the type's small, which is derived from the specified delta and, by default, is a power of two. Therefore, ordinary fixed-point types are sometimes called binary fixed-point types.

**Note:** Ordinary fixed-point types can be thought of being closer to the actual representation on the machine, since hardware support for decimal fixed-point arithmetic is not widespread (rescalings by a power of ten), while ordinary fixed-point types make use of the available integer shift instructions.

The syntax for an ordinary fixed-point type is

```
type <type-name> is delta <delta-value> range <lower-bound> .. <upper-bound>;
```

By default the compiler will choose a scale factor, or small, that is a power of 2 no greater than <delta-value>.

For example, we may define a normalized range between -1.0 and 1.0 as following:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Normalized_Fixed_Point_Type is
D : constant := 2.0 ** (-31);
(continues on next page)
```

```
type TQ31 is delta D range -1.0 .. 1.0 - D;
begin
   Put_Line ("TQ31 requires " & Integer'Image (TQ31'Size) & " bits");
   Put_Line ("The delta value of TQ31 is " & TQ31'Image (TQ31'Delta));
   Put_Line ("The minimum value of TQ31 is " & TQ31'Image (TQ31'First));
   Put_Line ("The maximum value of TQ31 is " & TQ31'Image (TQ31'Last));
end Normalized_Fixed_Point_Type;
```

In this example, we are defining a 32-bit fixed-point data type for our normalized range. When running the application, we notice that the upper bound is close to one, but not exact one. This is a typical effect of fixed-point data types — you can find more details in this discussion about the Q format<sup>14</sup>. We may also rewrite this code with an exact type definition:

```
procedure Normalized_Adapted_Fixed_Point_Type is
   type TQ31 is delta 2.0 ** (-31) range -1.0 .. 1.0 - 2.0 ** (-31);
begin
   null;
end Normalized_Adapted_Fixed_Point_Type;
```

We may also use any other range. For example:

```
with Ada.Text_IO; use Ada.Text_IO;
with Ada.Numerics; use Ada.Numerics;

procedure Custom_Fixed_Point_Range is
    type T_Inv_Trig is delta 2.0 ** (-15) * Pi range -Pi / 2.0 .. Pi / 2.0;
begin
    Put_Line ("T_Inv_Trig requires " & Integer'Image (T_Inv_Trig'Size)
        & " bits");
    Put_Line ("The delta value of T_Inv_Trig is "
        & T_Inv_Trig'Image (T_Inv_Trig'Delta));
    Put_Line ("The minimum value of T_Inv_Trig is "
        & T_Inv_Trig'Image (T_Inv_Trig'First));
    Put_Line ("The maximum value of T_Inv_Trig is "
        & T_Inv_Trig'Image (T_Inv_Trig is "
        & T_Inv_Trig'Image (T_Inv_Trig'Last));
end Custom_Fixed_Point_Range;
```

In this example, we are defining a 16-bit type called T\_Inv\_Trig, which has a range from  $-\pi/2$  to  $\pi/2$ .

All standard operations are available for fixed-point types. For example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Fixed_Point_Op is
    type TQ31 is delta 2.0 ** (-31) range -1.0 .. 1.0 - 2.0 ** (-31);

A, B, R : TQ31;
begin
    A := 0.25;
    B := 0.50;
    R := A + B;
    Put_Line ("R is " & TQ31'Image (R));
end Fixed_Point_Op;
```

As expected, R contains 0.75 after the addition of A and B.

In fact the language is more general that these examples imply, since in practice it is typical to need to multiply or divide values from different fixed-point types, and obtain a result that may be of a third fixed-point type. The details are outside the scope of this introductory course.

<sup>14</sup> https://en.wikipedia.org/wiki/Q\_(number\_format)

It is also worth noting, although again the details are outside the scope of this course, that you can explicitly specify a value for an ordinary fixed-point type's small. This allows non-binary scaling, for example:

```
type Angle is delta 1.0/3600.0 range 0.0 .. 360.0 - 1.0/3600.0;
for Angle'Small use Angle'Delta;
```

## 8.7 Character types

As noted earlier, each enumeration type is distinct and incompatible with every other enumeration type. However, what we did not mention previously is that character literals are permitted as enumeration literals. This means that in addition to the language's strongly typed character types, user-defined character types are also permitted:

```
with Ada.Text IO; use Ada.Text IO;
procedure Character_Example is
  type My_Char is ('a', 'b', 'c');
   -- Our custom character type, an enumeration type with 3 valid values.
  C : Character;
     ^ Built-in character type (it's an enumeration type)
  M : My_Char;
begin
  C := '?':
       ^ Character literal (enumeration literal)
  M := 'a';
  C := 65;
       ^ Invalid: 65 is not a Character value
  C := Character'Val (65);
   -- Assign the character at position 65 in the enumeration (which is 'A')
   -- ^ Invalid: C is of type Character, and M is a My Char
  M := 'd';
  -- ^ Invalid: 'd' is not a valid literal for type My_Char
end Character Example;
```

**CHAPTER** 

**NINE** 

#### **PRIVACY**

One of the main principles of modular programming, as well as object oriented programming, is encapsulation<sup>15</sup>.

Encapsulation, briefly, is the concept that the implementer of a piece of software will distinguish between the code's public interface and its private implementation.

This is not only applicable to software libraries but wherever abstraction is used.

In Ada, the granularity of encapsulation is a bit different from most object-oriented languages, because privacy is generally specified at the package level.

### 9.1 Basic encapsulation

```
package Encapsulate is
    procedure Hello;

private

    procedure Hello2;
    -- Not visible from external units
end Encapsulate;

with Encapsulate;

procedure Main is
begin
    Encapsulate.Hello;
    Encapsulate.Hello2;
    -- Invalid: Hello2 is not visible
end Main;
```

# 9.2 Abstract data types

With this high-level granularity, it might not seem obvious how to hide the implementation details of a type. Here is how it can be done in Ada:

```
package Stacks is
   type Stack is private;
   -- Declare a private type: You cannot depend on its
   -- implementation. You can only assign and test for
   -- equality.
```

(continues on next page)

<sup>&</sup>lt;sup>15</sup> https://en.wikipedia.org/wiki/Encapsulation\_(computer\_programming)

```
procedure Push (S : in out Stack; Val : Integer);
procedure Pop (S : in out Stack; Val : out Integer);
private

subtype Stack_Index is Natural range 1 .. 10;
type Content_Type is array (Stack_Index) of Natural;

type Stack is record
    Top : Stack_Index;
    Content : Content_Type;
end record;
end Stacks;
```

In the above example, we define a stack type in the public part (known as the *visible part* of the package spec in Ada), but the exact representation of that type is private.

Then, in the private part, we define the representation of that type. We can also declare other types that will be used as *helpers* for our main public type. This is useful since declaring helper types is common in Ada.

A few words about terminology:

- The Stack type as viewed from the public part is called the partial view of the type. This is what clients have access to.
- The Stack type as viewed from the private part or the body of the package is called the full view of the type. This is what implementers have access to.

From the point of view of the client (the *with*'ing unit), only the public (visible) part is important, and the private part could as well not exist. It makes it very easy to read linearly the part of the package that is important for you.

```
-- No need to read the private part to use the package
package Stacks is
   type Stack is private;

procedure Push (S : in out Stack; Val : Integer);
   procedure Pop (S : in out Stack; Val : out Integer);
private
...
end Stacks;
```

Here is how the Stacks package would be used:

```
-- Example of use
with Stacks; use Stacks;

procedure Test_Stack is
   S : Stack;
   Res : Integer;
begin
   Push (S, 5);
   Push (S, 7);
   Push (S, 7);
   Pop (S, Res);
end Test_Stack;
```

## 9.3 Limited types

Ada's *limited type* facility allows you to declare a type for which assignment and comparison operations are not automatically provided.

```
package Stacks is
   type Stack is limited private;
   -- Limited type. Cannot assign nor compare.

procedure Push (S : in out Stack; Val : Integer);
procedure Pop (S : in out Stack; Val : out Integer);
private
   subtype Stack_Index is Natural range 1 .. 10;
   type Content_Type is array (Stack_Index) of Natural;

type Stack is limited record
   Top : Stack_Index;
   Content : Content_Type;
end record;
end Stacks;
```

```
with Stacks; use Stacks;

procedure Main is
    S, S2 : Stack;
begin
    S := S2;
    -- Illegal: S is limited.
end Main;
```

This is useful because, for example, for some data types the built-in assignment operation might be incorrect (for example when a deep copy is required).

Ada does allow you to overload the comparison operators = and /= for limited types (and to override the built-in declarations for non-limited types).

Ada also allows you to implement special semantics for assignment via controlled types<sup>16</sup>. However, in some cases assignment is simply inappropriate; one example is the File\_Type from the Ada.Text\_IO package, which is declared as a limited type and thus attempts to assign one file to another would be detected as illegal.

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<sup>&</sup>lt;sup>16</sup> https://www.adaic.org/resources/add\_content/standards/12rm/html/RM-7-6.html

**CHAPTER** 

**TEN** 

#### **GENERICS**

#### 10.1 Introduction

Generics are used for metaprogramming in Ada. They are useful for abstract algorithms that share common properties with each other.

Either a subprogram or a package can be generic. A generic is declared by using the keyword generic. For example:

#### 10.1.1 Formal type declaration

Formal types are abstractions of a specific type. For example, we may want to create an algorithm that works on any integer type, or even on any type at all, whether a numeric type or not. The following example declares a formal type T for the Set procedure.

```
generic
    type T is private;
    -- T is a formal type that indicates that any type can be used,
    -- possibly a numeric type or possibly even a record type.
procedure Set (E : T);
procedure Set (E : T) is null;
begin
    null;
end Show_Formal_Type_Declaration;
```

The declaration of T as private indicates that you can map any type to it. But you can also restrict the declaration to allow only some types to be mapped to that formal type. Here are some examples:

Formal Type	Format
Any type	type T is private;
Any discrete type	type T is (<>);
Any floating-point type	<pre>type T is digits &lt;&gt;;</pre>

#### 10.1.2 Formal object declaration

Formal objects are similar to subprogram parameters. They can reference formal types declared in the formal specification. For example:

```
generic
    type T is private;
    X : in out T;
    -- X can be used in the Set procedure
procedure Set (E : T);

procedure Set (E : T) is null;

begin
    null;
end Show_Formal_Object_Declaration;
```

Formal objects can be either input parameters or specified using the in out mode.

#### 10.1.3 Generic body definition

We don't repeat the generic keyword for the body declaration of a generic subprogram or package. Instead, we start with the actual declaration and use the generic types and objects we declared. For example:

```
procedure Show_Generic_Body_Definition is

generic
    type T is private;
    X : in out T;
procedure Set (E : T);

procedure Set (E : T) is
    -- Body definition: "generic" keyword is not used
    begin
    X := E;
end Set;
begin
null;
end Show_Generic_Body_Definition;
```

#### 10.1.4 Generic instantiation

Generic subprograms or packages can't be used directly. Instead, they need to be instantiated, which we do using the new keyword, as shown in the following example:

```
with Ada. Text IO; use Ada. Text IO;
procedure Show Generic Instantiation is
  generic
     type T is private;
     X : in out T;
     -- X can be used in the Set procedure
  procedure Set (E : T);
  procedure Set (E : T) is
  begin
     X := E;
  end Set;
  Main
         : Integer := 0;
  Current : Integer;
  procedure Set Main is new Set (T => Integer,
                                  X \Rightarrow Main:
   -- Here, we map the formal parameters to actual types and objects.
   -- The same approach can be used to instantiate functions or
   -- packages, e.g.:
      function Get_Main is new ...
   -- package Integer_Queue is new ...
beain
  Current := 10;
  Set Main (Current);
  Put Line ("Value of Main is " & Integer'Image (Main));
end Show_Generic_Instantiation;
```

In the example above, we instantiate the procedure Set by mapping the formal parameters T and X to actual existing elements, in this case the Integer type and the Main variable.

## 10.1.5 Generic packages

The previous examples focused on generic subprograms. In this section, we look at generic packages. The syntax is similar to that used for generic subprograms: we start with the generic keyword and continue with formal declarations. The only difference is that package is specified instead of a subprogram keyword.

Here's an example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Generic_Package is

generic
    type T is private;
package Element is

procedure Set (E : T);
procedure Reset;
function Get return T;
function Is_Valid return Boolean;

Invalid_Element : exception;

(continues on next page)
```

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```
private
      Value : T;
      Valid : Boolean := False;
   end Element;
   package body Element is
      procedure Set (E : T) is
      begin
         Value := E;
         Valid := True;
      end Set;
      procedure Reset is
      begin
         Valid := False;
      end Reset;
      function Get return T is
      begin
         if not Valid then
            raise Invalid Element;
         end if;
         return Value;
      end Get;
      function Is_Valid return Boolean is (Valid);
   end Element;
   package I is new Element (T => Integer);
   procedure Display Initialized is
   begin
      if I.Is Valid then
         Put Line ("Value is initialized");
         Put Line ("Value is not initialized");
      end if;
   end Display_Initialized;
   Display Initialized;
   Put Line ("Initializing...");
   I.Set (5);
   Display_Initialized;
   Put_Line ("Value is now set to " & Integer'Image (I.Get));
   Put_Line ("Reseting...");
   I.Reset;
   Display_Initialized;
end Show Generic Package;
```

In the example above, we created a simple container named Element, with just one single element. This container tracks whether the element has been initialized or not.

After writing package definition, we create the instance I of the Element. We use the instance by calling the package subprograms (Set, Reset, and Get).

## 10.1.6 Formal subprograms

In addition to formal types and objects, we can also declare formal subprograms or packages. This course only describes formal subprograms; formal packages are discussed in the advanced course.

We use the with keyword to declare a formal subprogram. In the example below, we declare a formal function (Comparison) to be used by the generic procedure Check.

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show Formal Subprogram is
  generic
      Description : String;
      type T is private;
     with function Comparison (X, Y : T) return Boolean;
  procedure Check (X, Y : T);
  procedure Check (X, Y : T) is
      Result : Boolean;
  begin
      Result := Comparison (X, Y);
      if Result then
         Put Line ("Comparison (" & Description &
                   ") between arguments is OK!");
         Put_Line ("Comparison (" & Description &
                   ") between arguments is not OK!");
      end if;
  end Check;
  A, B : Integer;
  procedure Check Is_Equal is new Check (Description => "equality",
                                                      => Integer,
                                          Comparison => Standard."=");
   -- Here, we are mapping the standard equality operator for Integer
   -- types to the Comparison formal function
begin
  A := 0;
  B := 1;
  Check_Is_Equal (A, B);
end Show_Formal_Subprogram;
```

# **10.2 Examples of using generics**

In this section, we look at examples and strategies for abstracting algorithms using generics.

## **10.2.1 Application: ADTs**

An important application of generics is to model abstract data types (ADTs). In fact, Ada includes a library with numerous ADTs using generics: Ada. Containers (described in the *containers section* (page 119)).

A typical example of an ADT is a stack:

```
with Ada.Text IO; use Ada.Text IO;
procedure Show Stack is
   generic
      Max : Positive;
      type T is private;
   package Stacks is
      type Stack is limited private;
      Stack_Underflow, Stack_Overflow : exception;
      function Is_Empty (S : Stack) return Boolean;
      function Pop (S : in out Stack) return T;
      procedure Push (S : in out Stack; V : T);
   private
      type Stack Array is array (Natural range <>) of T;
      Min : constant := 1;
      type Stack is record
         Container : Stack_Array (Min .. Max);
                   : Natural := Min - 1;
         qoT
      end record;
   end Stacks;
   package body Stacks is
      function Is_Empty (S : Stack) return Boolean is
        (S.Top < S.Container'First);</pre>
      function Is_Full (S : Stack) return Boolean is
        (S.Top >= S.Container'Last);
      function Pop (S : in out Stack) return T is
      begin
         if Is Empty (S) then
            raise Stack_Underflow;
         else
            \textbf{return}\ X\ :\ T\ \textbf{do}
               X := S.Container (S.Top);
               S.Top := S.Top - 1;
            end return;
         end if;
      end Pop;
      procedure Push (S : in out Stack; V : T) is
         if Is Full (S) then
            raise Stack_Overflow;
         else
            S.Top
                                 := S.Top + 1;
            S.Container (S.Top) := V;
         end if;
      end Push;
```

In this example, we first create a generic stack package (Stacks) and then instantiate it to create a stack of 10 integer values.

### 10.2.2 Abstracting a swap algorithm

Let's look at a simple procedure that swaps variables of type Color:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Test_Non_Generic_Swap_Colors is
   type Color is (Black, Red, Green, Blue, White);
   procedure Swap_Colors (X, Y : in out Color);
   procedure Swap_Colors (X, Y : in out Color) is
      Tmp : constant Color := X;
   begin
      X := Y;
      Y := Tmp;
   end Swap_Colors;
   A, B, C : Color;
begin
   A := Blue;
   B := White;
   C := Red;
   Put Line ("Value of A is " & Color'Image (A));
   Put_Line ("Value of B is " & Color'Image (B));
   Put_Line ("Value of C is " & Color'Image (C));
   New_Line;
   Put_Line ("Swapping A and C...");
   New_Line;
   Swap_Colors (A, C);
   Put_Line ("Value of A is " & Color'Image (A));
   Put_Line ("Value of B is " & Color'Image (B));
Put_Line ("Value of C is " & Color'Image (C));
end Test Non Generic Swap Colors;
```

In this example, Swap\_Colors can only be used for the Color type. However, this algorithm can theoretically be used for any type, whether an enumeration type or a complex record type with many elements. The algorithm itself is the same: it's only the type that differs. If, for example, we

want to swap variables of Integer type, we don't want to duplicate the implementation. Therefore, such an algorithm is a perfect candidate for abstraction using generics.

In the example below, we create a generic version of Swap\_Colors and name it Generic\_Swap. This generic version can operate on any type due to the declaration of formal type T.

```
with Ada. Text IO; use Ada. Text IO;
procedure Test Swap Colors is
   generic
      type T is private;
  procedure Generic_Swap (X, Y : in out T);
  procedure Generic_Swap (X, Y : in out T) is
     Tmp : constant T := X;
  begin
     X := Y;
     Y := Tmp;
  end Generic Swap;
  type Color is (Black, Red, Green, Blue, White);
  procedure Swap Colors is new Generic Swap (T => Color);
  A, B, C : Color;
begin
  A := Blue:
  B := White:
  C := Red;
  Put Line ("Value of A is " & Color'Image (A));
  Put Line ("Value of B is " & Color'Image (B));
  Put_Line ("Value of C is " & Color'Image (C));
  New Line;
  Put_Line ("Swapping A and C...");
  New Line;
  Swap_Colors (A, C);
  Put Line ("Value of A is " & Color'Image (A));
  Put Line ("Value of B is " & Color'Image (B));
   Put Line ("Value of C is " & Color'Image (C));
end Test_Swap_Colors;
```

As we can see in the example, we can create the same Swap\_Colors procedure as we had in the non-generic version of the algorithm by declaring it as an instance of the generic Generic\_Swap procedure. We specify that the generic T type will be mapped to the Color type by passing it as an argument to the Generic\_Swap instantiation,

### 10.2.3 Abstracting a reversing algorithm

The previous example, with an algorithm to swap two values, is one of the simplest examples of using generics. Next we study an algorithm for reversing elements of an array. First, let's start with a non-generic version of the algorithm, one that works specifically for the Color type:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Test_Non_Generic_Reverse_Colors is
   type Color is (Black, Red, Green, Blue, White);
```

```
type Color_Array is array (Integer range <>) of Color;
  procedure Reverse_Color_Array (X : in out Color_Array);
  procedure Reverse_Color_Array (X : in out Color_Array) is
  begin
      for I in X'First .. (X'Last + X'First) / 2 loop
         declare
                    : Color;
            Tmp
            X_Left : Color renames X (I);
            X_Right : Color renames X (X'Last + X'First - I);
         begin
            Tmp
                    := X Left;
            X_Left := X_Right;
            X_Right := Tmp;
         end;
      end loop;
  end Reverse_Color_Array;
  My_Colors : Color_Array (1 .. 5) := (Black, Red, Green, Blue, White);
begin
   for C of My Colors loop
      Put Line ("My Color: " & Color'Image (C));
  end loop;
  New_Line;
  Put Line ("Reversing My_Color...");
  New Line;
  Reverse_Color_Array (My_Colors);
   for C of My_Colors loop
     Put_Line ("My_Color: " & Color'Image (C));
   end loop;
end Test Non Generic Reverse Colors;
```

The procedure Reverse\_Color\_Array takes an array of colors, starts by swapping the first and last elements of the array, and continues doing that with successive elements until it reaches the middle of array. At that point, the entire array has been reversed, as we see from the output of the test program.

To abstract this procedure, we declare formal types for three components of the algorithm:

- the elements of the array (Color type in the example)
- the range used for the array (Integer range in the example)
- the actual array type (Color Array type in the example)

This is a generic version of the algorithm:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Test_Reverse_Colors is
   generic
    type T is private;
   type Index is range <>;
    type Array_T is array (Index range <>) of T;
   procedure Generic_Reverse_Array (X : in out Array_T);

procedure Generic_Reverse_Array (X : in out Array_T) is
   begin
```

```
for I in X'First .. (X'Last + X'First) / 2 loop
         declare
            Tmp
            X_Left : T renames X (I);
            X_Right : T renames X (X'Last + X'First - I);
                   := X_Left;
            Tmp
            X_Left := X_Right;
            X_Right := Tmp;
         end;
     end loop;
  end Generic_Reverse_Array;
  type Color is (Black, Red, Green, Blue, White);
   type Color_Array is array (Integer range <>) of Color;
  procedure Reverse_Color_Array is new Generic Reverse_Array
     (T => Color, Index => Integer, Array_T => Color_Array);
  My_Colors : Color_Array (1 .. 5) := (Black, Red, Green, Blue, White);
begin
   for C of My Colors loop
     Put Line ("My Color: " & Color'Image (C));
  end loop;
  New_Line;
  Put Line ("Reversing My_Color...");
  New Line;
  Reverse_Color_Array (My_Colors);
   for C of My_Colors loop
     Put_Line ("My_Color: " & Color'Image (C));
  end loop;
end Test Reverse Colors;
```

As mentioned above, we're abstracting three components of the algorithm:

- the T type abstracts the elements of the array
- the Index type abstracts the range used for the array
- the Array\_T type abstracts the array type and uses the formal declarations of the T and Index types.

### 10.2.4 Abstracting the test application

In the previous example we've focused only on abstracting the reversing algorithm itself. However, we could have decided to also abstract our small test application. This could be useful if we, for example, decide to test other procedures that change elements of an array.

In order to do this, we again have to choose the elements to abstract. We therefore declare the following formal parameters:

- S: the string containing the array name
- a function Image that converts an element of type T to a string
- a procedure Test that performs some operation on the array

Note that Image and Test are examples of formal subprograms and S is an example of a formal object.

Here is a version of the test application making use of the generic Perform Test procedure:

```
with Ada. Text IO; use Ada. Text IO;
procedure Test_Reverse_Colors is
  generic
      type T is private;
      type Index is range <>;
      type Array_T is array (Index range <>) of T;
  procedure Generic_Reverse_Array (X : in out Array_T);
  generic
      type T is private;
      type Index is range <>;
      type Array_T is array (Index range <>) of T;
      S : String;
     with function Image (E : T) return String is <>;
     with procedure Test (X : in out Array_T);
  procedure Perform_Test (X : in out Array_T);
  procedure Generic_Reverse_Array (X : in out Array_T) is
  begin
      for I in X'First .. (X'Last + X'First) / 2 loop
         declare
            Tmp
                    : T;
            X_Left : T renames X (I);
            X Right : T renames X (X'Last + X'First - I);
         begin
                   := X_Left;
            Tmp
            X_Left := X_Right;
            X_Right := Tmp;
         end;
      end loop;
  end Generic_Reverse_Array;
  procedure Perform_Test (X : in out Array_T) is
  begin
      for C of X loop
        Put_Line (S & ": " & Image (C));
      end loop;
     New Line;
     Put Line ("Testing " & S & "...");
     New Line;
     Test (X);
      for C of X loop
         Put Line (S & ": " & Image (C));
      end loop;
  end Perform_Test;
  type Color is (Black, Red, Green, Blue, White);
   type Color_Array is array (Integer range <>) of Color;
  procedure Reverse Color Array is new
     Generic Reverse Array (T
                                    => Color,
                            Index => Integer,
                            Array_T => Color_Array);
  procedure Perform_Test_Reverse_Color_Array is new
                          => Color,
     Perform_Test (T
                   Index
                           => Integer,
                                                                    (continues on next page)
```

In this example, we create the procedure Perform\_Test\_Reverse\_Color\_Array as an instance of the generic procedure (Perform Test). Note that:

- For the formal Image function, we use the 'Image attribute of the Color type
- For the formal Test procedure, we reference the Reverse\_Array procedure from the package.

**CHAPTER** 

**ELEVEN** 

### **EXCEPTIONS**

Ada uses exceptions for error handling. Unlike many other languages, Ada speaks about *raising*, not *throwing*, an exception and *handling*, not *catching*, an exception.

## 11.1 Exception declaration

Ada exceptions are not types, but instead objects, which may be peculiar to you if you're used to the way Java or Python support exceptions. Here's how you declare an exception:

```
package Exceptions is
    My_Except : exception;
    -- Like an object. *NOT* a type !
end Exceptions;
```

Even though they're objects, you're going to use each declared exception object as a "kind" or "family" of exceptions. Ada does not require that a subprogram declare every exception it can potentially raise.

# 11.2 Raising an exception

To raise an exception of our newly declared exception kind, do the following:

```
with Exceptions; use Exceptions;

procedure Main is
begin
    raise My_Except;
    -- Execution of current control flow abandoned; an exception of kind
    -- "My_Except" will bubble up until it is caught.

    raise My_Except with "My exception message";
    -- Execution of current control flow abandoned; an exception of
    -- kind "My_Except" with associated string will bubble up until
    -- it is caught.
end Main;
```

# 11.3 Handling an exception

Next, we address how to handle exceptions that were raised by us or libraries that we call. The neat thing in Ada is that you can add an exception handler to any statement block as follows:

```
with Ada.Text IO; use Ada.Text IO;
with Ada. Exceptions; use Ada. Exceptions;
procedure Open File is
  File : File Type;
begin
   -- Block (sequence of statements)
  begin
      Open (File, In_File, "input.txt");
  exception
     when E : Name Error =>
               ^ Exception to be handled
         Put ("Cannot open input file : ");
         Put_Line (Exception_Message (E));
         raise;
         -- Reraise current occurence
  end:
end Open File;
```

In the example above, we're using the Exception\_Message function from the Ada. Exceptions package. This function returns the message associated with the exception as a string.

You don't need to introduce a block just to handle an exception: you can add it to the statements block of your current subprogram:

```
with Ada.Text_IO; use Ada.Text_IO;
with Ada.Exceptions; use Ada.Exceptions;

procedure Open_File is
   File : File_Type;
begin
   Open (File, In_File, "input.txt");
-- Exception block can be added to any block
exception
   when Name_Error =>
        Put ("Cannot open input file");
end Open_File;
```

**Attention:** Exception handlers have an important restriction that you need to be careful about: Exceptions raised in the declarative section are not caught by the handlers of that block. So for example, in the following code, the exception will not be caught.

```
with Ada.Text_IO; use Ada.Text_IO;
with Ada.Exceptions; use Ada.Exceptions;

procedure Be_Careful is
   function Dangerous return Integer is
   begin
     raise Constraint_Error;
     return 42;
   end Dangerous;

begin
   declare
     A : Integer := Dangerous;
   begin
     Put_Line (Integer'Image (A));
   exception
     when Constraint_Error => Put_Line ("error!");
   end;
end Be_Careful;
```

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This is also the case for the top-level exception block that is part of the current subprogram.

## 11.4 Predefined exceptions

Ada has a very small number of predefined exceptions:

- Constraint\_Error is the main one you might see. It's raised:
  - When bounds don't match or, in general, any violation of constraints.
  - In case of overflow
  - In case of null dereferences
  - In case of division by 0
- Program\_Error might appear, but probably less often. It's raised in more arcane situations, such as for order of elaboration issues and some cases of detectable erroneous execution.
- Storage Error will happen because of memory issues, such as:
  - Not enough memory (allocator)
  - Not enough stack
- Tasking\_Error will happen with task related errors, such as any error happening during task activation.

You should not reuse predefined exceptions. If you do then, it won't be obvious when one is raised that it is because something went wrong in a built-in language operation.

**CHAPTER** 

### **TWELVE**

### **TASKING**

Tasks and protected objects allow the implementation of concurrency in Ada. The following sections explain these concepts in more details.

### **12.1 Tasks**

A task can be thought as an application that runs *concurrently* with the main application. In other programming languages, a task can be called a thread <sup>17</sup>, and tasking can be called multithreading <sup>18</sup>.

Tasks may synchronize with the main application but may also process information completely independent from the main application. Here we show how this is accomplished.

### 12.1.1 Simple task

Tasks are declared using the keyword task. The task implementation is specified in a task body block. For example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Simple_Task is
   task T;

  task body T is
  begin
    Put_Line ("In task T");
  end T;
begin
    Put_Line ("In main");
end Show_Simple_Task;
```

Here, we're declaring and implementing the task T. As soon as the main application starts, task T starts automatically — it's not necessary to manually start this task. By running the application above, we can see that both calls to Put\_Line are performed.

Note that:

- The main application is itself a task (the main task).
  - In this example, the subprogram Show\_Simple\_Task is the main task of the application.
- Task T is a subtask.
  - Each subtask has a master task.
  - Therefore the main task is also the master task of task T.

<sup>&</sup>lt;sup>17</sup> https://en.wikipedia.org/wiki/Thread\_(computing)

<sup>18</sup> https://en.wikipedia.org/wiki/Thread\_(computing)#Multithreading

- The number of tasks is not limited to one: we could include a task T2 in the example above.
  - This task also starts automatically and runs *concurrently* with both task T and the main task. For example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Simple_Tasks is
  task T;
  task T2;

  task body T is
  begin
    Put_Line ("In task T");
  end T;

  task body T2 is
  begin
    Put_Line ("In task T2");
  end T2;

begin
    Put_Line ("In main");
  end Show_Simple_Tasks;
```

### 12.1.2 Simple synchronization

As we've just seen, as soon as the main task starts, its subtasks also start automatically. The main task continues its processing until it has nothing more to do. At that point, however, it will not terminate. Instead, the task waits until its subtasks have finished before it allows itself to terminate. In other words, this waiting process provides synchronization between the main task and its subtasks. After this synchronization, the main task will terminate. For example:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Show_Simple_Sync is
   task T;
   task body T is
   begin
     for I in 1 .. 10 loop
        Put_Line ("hello");
     end loop;
   end T;
begin
   null;
   -- Will wait here until all tasks have terminated
end Show_Simple_Sync;
```

The same mechanism is used for other subprograms that contain subtasks: the subprogram's master task will wait for its subtasks to finish. So this mechanism is not limited to the main application and also applies to any subprogram called by the main application or its subprograms.

Synchronization also occurs if we move the task to a separate package. In the example below, we declare a task T in the package Simple\_Sync\_Pkg.

```
package Simple_Sync_Pkg is
   task T;
end Simple_Sync_Pkg;
```

This is the corresponding package body:

```
with Ada.Text_IO; use Ada.Text_IO;

package body Simple_Sync_Pkg is
   task body T is
   begin
    for I in 1 .. 10 loop
        Put_Line ("hello");
    end loop;
   end T;
end Simple_Sync_Pkg;
```

Because the package is with'ed by the main procedure, the task T defined in the package is part of the main task. For example:

```
with Simple_Sync_Pkg;

procedure Test_Simple_Sync_Pkg is
begin
   null;
   -- Will wait here until all tasks have terminated
end Test_Simple_Sync_Pkg;
```

Again, as soon as the main task reaches its end, it synchronizes with task T from Simple\_Sync\_Pkg before terminating.

### 12.1.3 **Delay**

We can introduce a delay by using the keyword delay. This puts the task to sleep for the length of time (in seconds) specified in the delay statement. For example:

In this example, we're making the task T wait one second after each time it displays the "hello" message. In addition, the main task is waiting 1.5 seconds before displaying its own "hello" message

### 12.1.4 Synchronization: rendez-vous

The only type of synchronization we've seen so far is the one that happens automatically at the end of the main task. You can also define custom synchronization points using the keyword entry. An *entry* can be viewed as a special kind of subprogram, which is called by the master task using a similar syntax, as we will see later.

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In the task definition, you define which part of the task will accept the entries by using the keyword accept. A task proceeds until it reaches an accept statement and then waits for the master task to synchronize with it. Specifically,

- The subtask waits at that point (in the accept statement), ready to accept a call to the corresponding entry from the master task.
- The master task calls the task entry, in a manner similar to a procedure call, to synchronize with the subtask.

This synchronization between tasks is called *rendez-vous*. Let's see an example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Rendezvous is

task T is
    entry Start;
end T;

task body T is
begin
    accept Start; -- Waiting for somebody to call the entry
    Put_Line ("In T");
end T;

begin
    Put_Line ("In Main");
    T.Start; -- Calling T's entry
end Show_Rendezvous;
```

In this example, we declare an entry Start for task T. In the task body, we implement this entry using accept Start. When task T reaches this point, it waits for the master task. This synchronization occurs in the T. Start statement. After the synchronization completes, the main task and task T again run concurrently until they synchronize one final time when the main task finishes.

An entry may be used to perform more than a simple task synchronization: it also may perform multiple statements during the time both tasks are synchronized. We do this with a do ... end block. For the previous example, we would simply write accept Start do <statements>; end;. We use this kind of block in the next example.

### 12.1.5 Select loop

There's no limit to the number of times an entry can be accepted. We could even create an infinite loop in the task and accept calls to the same entry over and over again. An infinite loop, however, prevents the subtask from finishing, so it blocks the master task when it reaches the end of its processing. Therefore, a loop containing accept statements in a task body is normally used in conjunction with a select ... or terminate statement. In simple terms, this statement allows the master task to automatically terminate the subtask when the master task finishes. For example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Rendezvous_Loop is

task T is
    entry Reset;
    entry Increment;
end T;

task body T is
    Cnt : Integer := 0;
```

```
begin
      loop
         select
            accept Reset do
               Cnt := 0;
            end Reset;
            Put_Line ("Reset");
         or
            accept Increment do
               Cnt := Cnt + 1;
            end Increment;
            Put_Line ("In T's loop (" & Integer'Image (Cnt) & ")");
            terminate;
         end select;
      end loop;
   end T;
begin
   Put_Line ("In Main");
   for I in 1 .. 4 loop
      T.Increment; -- Calling T's entry multiple times
   end loop;
   T.Reset;
   for I in 1 \dots 4 loop
      T.Increment; -- Calling T's entry multiple times
   end loop;
end Show Rendezvous Loop;
```

In this example, the task body implements an infinite loop that accepts calls to the Reset and Increment entry. We make the following observations:

- The accept E do ... end block is used to increment a counter.
  - As long as task T is performing the do ... end block, the main task waits for the block to complete.
- The main task is calling the Increment entry multiple times in the loop from 1 .. 4. It is also calling the Reset entry before and the loop.
  - Because task T contains an infinite loop, it always accepts calls to the Reset and Increment entries.
  - When the main task finishes, it checks the status of the T task. Even though task T could accept new calls to the Reset or Increment entries, the master task is allowed to terminate task T due to the or terminate part of the select statement.

## 12.1.6 Cycling tasks

In a previous example, we saw how to delay a task a specified time by using the delay keyword. However, using delay statements in a loop is not enough to guarantee regular intervals between those delay statements. For example, we may have a call to a computationally intensive procedure between executions of successive delay statements:

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```
Computational_Intensive_App;
end loop;
```

In this case, we can't guarantee that exactly 10 seconds have elapsed after 10 calls to the delay statement because a time drift may be introduced by the Computational\_Intensive\_App procedure. In many cases, this time drift is not relevant, so using the delay keyword is good enough.

However, there are situations where a time drift isn't acceptable. In those cases, we need to use the delay until statement, which accepts a precise time for the end of the delay, allowing us to define a regular interval. This is useful, for example, in real-time applications.

We will soon see an example of how this time drift may be introduced and how the delay until statement circumvents the problem. But before we do that, we look at a package containing a procedure allowing us to measure the elapsed time (Show\_Elapsed\_Time) and a dummy Computational\_Intensive\_App procedure which is simulated by using a simple delay. This is the package specification:

```
with Ada.Real_Time; use Ada.Real_Time;
package Delay_Aux_Pkg is

function Get_Start_Time return Time
   with Inline;

procedure Show_Elapsed_Time
   with Inline;

procedure Computational_Intensive_App;
private
   Start_Time : Time := Clock;
function Get_Start_Time return Time is (Start_Time);
end Delay_Aux_Pkg;
```

And this is the package body:

```
with Ada.Text IO; use Ada.Text IO;
package body Delay Aux Pkg is
   procedure Show Elapsed Time is
      Now Time
                 : Time;
      Elapsed_Time : Time_Span;
  begin
      Now Time
                   := Clock;
      Elapsed_Time := Now_Time - Start_Time;
      Put_Line ("Elapsed time "
                & Duration'Image (To_Duration (Elapsed_Time))
                & " seconds"):
  end Show Elapsed Time;
  procedure Computational Intensive App is
  begin
      delay 0.5;
  end Computational_Intensive_App;
end Delay_Aux_Pkg;
```

Using this auxiliary package, we're now ready to write our time-drifting application:

```
with Ada.Text IO; use Ada.Text IO;
with Ada.Real Time; use Ada.Real Time;
with Delay_Aux_Pkg;
procedure Show_Time_Drifting_Task is
  package Aux renames Delay_Aux_Pkg;
  task T:
   task body T is
     Cnt
          : Integer := 1;
      for I in 1 .. 5 loop
         delay 1.0;
         Aux.Show_Elapsed_Time;
         Aux.Computational_Intensive_App;
         Put_Line ("Cycle # " & Integer'Image (Cnt));
         Cnt := Cnt + 1;
      end loop;
      Put Line ("Finished time-drifting loop");
  end T;
begin
  null:
end Show_Time_Drifting_Task;
```

We can see by running the application that we already have a time difference of about four seconds after three iterations of the loop due to the drift introduced by Computational\_Intensive\_App. Using the delay until statement, however, we're able to avoid this time drift and have a regular interval of exactly one second:

```
with Ada.Text_IO;
                  use Ada.Text IO;
with Ada.Real_Time; use Ada.Real_Time;
with Delay_Aux_Pkg;
procedure Show_Cycling_Task is
  package Aux renames Delay_Aux_Pkg;
  task T;
  task body T is
      Cycle : constant Time_Span := Milliseconds (1000);
     Next : Time := Aux.Get_Start_Time + Cycle;
      Cnt
          : Integer := 1;
  begin
      for I in 1 .. 5 loop
         delay until Next;
         Aux. Show Elapsed Time;
         Aux.Computational_Intensive_App;
         -- Calculate next execution time using a
         -- cycle of one second
         Next := Next + Cycle;
         Put_Line ("Cycle # " & Integer'Image (Cnt));
         Cnt := Cnt + 1;
                                                                    (continues on next page)
```

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```
end loop;
   Put_Line ("Finished cycling");
end T;

begin
   null;
end Show_Cycling_Task;
```

Now, as we can see by running the application, the delay until statement ensures that the Computational\_Intensive\_App doesn't disturb the regular interval of one second between iterations.

## 12.2 Protected objects

When multiple tasks are accessing shared data, corruption of that data may occur. For example, data may be inconsistent if one task overwrites parts of the information that's being read by another task at the same time. In order to avoid these kinds of problems and ensure information is accessed in a coordinated way, we use *protected objects*.

Protected objects encapsulate data and provide access to that data by means of *protected operations*, which may be subprograms or protected entries. Using protected objects ensures that data is not corrupted by race conditions or other simultaneous access.

#### **Important**

Protected objects can be implemented using Ada tasks. In fact, this was the *only* possible way of implementing them in Ada 83 (the first version of the Ada language). However, the use of protected objects is much simpler than using similar mechanisms implemented using only tasks. Therefore, you should use protected objects when your main goal is only to protect data.

## 12.2.1 Simple object

You declare a protected object with the protected keyword. The syntax is similar to that used for packages: you can declare operations (e.g., procedures and functions) in the public part and data in the private part. The corresponding implementation of the operations is included in the protected body of the object. For example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Protected_Objects is

protected Obj is
    -- Operations go here (only subprograms)
    procedure Set (V : Integer);
    function Get return Integer;
private
    -- Data goes here
    Local : Integer := 0;
end Obj;

protected body Obj is
    -- procedures can modify the data
    procedure Set (V : Integer) is
    begin
```

```
Local := V;
end Set;

-- functions cannot modify the data
function Get return Integer is
begin
    return Local;
end Get;
end Obj;

begin
Obj.Set (5);
Put_Line ("Number is: " & Integer'Image (Obj.Get));
end Show_Protected_Objects;
```

In this example, we define two operations for <code>Obj</code>: <code>Set</code> and <code>Get</code>. The implementation of these operations is in the <code>Obj</code> body. The syntax used for writing these operations is the same as that for normal procedures and functions. The implementation of protected objects is straightforward — we simply access and update <code>Local</code> in these subprograms. To call these operations in the main application, we use prefixed notation, e.g., <code>Obj.Get</code>.

#### **12.2.2 Entries**

In addition to protected procedures and functions, you can also define protected entry points. Do this using the entry keyword. Protected entry points allow you to define barriers using the when keyword. Barriers are conditions that must be fulfilled before the entry can start performing its actual processing — we speak of *releasing* the barrier when the condition is fulfilled.

The previous example used procedures and functions to define operations on the protected objects. However, doing so permits reading protected information (via Obj.Get) before it's set (via Obj.Set). To allow that to be a defined operation, we specified a default value (0). Instead, by rewriting Obj.Get using an *entry* instead of a function, we implement a barrier, ensuring no task can read the information before it's been set.

The following example implements the barrier for the Obj.Get operation. It also contains two concurrent subprograms (main task and task T) that try to access the protected object.

```
with Ada. Text IO; use Ada. Text IO;
procedure Show Protected Objects Entries is
  protected Obj is
      procedure Set (V : Integer);
      entry Get (V : out Integer);
      Local : Integer;
      Is Set : Boolean := False;
  end Obj;
   protected body Obj is
      procedure Set (V : Integer) is
      begin
         Local := V;
         Is Set := True;
      end Set;
      entry Get (V : out Integer)
       when Is Set is
         -- Entry is blocked until the condition is true.
```

```
-- The barrier is evaluated at call of entries and at exits of
         -- procedures and entries.
         -- The calling task sleeps until the barrier is released.
     begin
         V := Local;
         Is_Set := False;
     end Get;
  end Obj;
  N : Integer := 0;
  task T;
  task body T is
  begin
     Put Line ("Task T will delay for 4 seconds...");
      delay 4.0;
     Put_Line ("Task T will set Obj...");
      Obj.Set (5);
      Put_Line ("Task T has just set Obj...");
  end T:
begin
  Put Line ("Main application will get Obj...");
  Obj.Get (N);
  Put_Line ("Main application has just retrieved Obj...");
  Put Line ("Number is: " & Integer'Image (N));
end Show_Protected_Objects_Entries;
```

As we see by running it, the main application waits until the protected object is set (by the call to <code>Obj.Set</code> in task T) before it reads the information (via <code>Obj.Get</code>). Because a 4-second delay has been added in task T, the main application is also delayed by 4 seconds. Only after this delay does task T set the object and release the barrier in <code>Obj.Get</code> so that the main application can then resume processing (after the information is retrieved from the protected object).

# 12.3 Task and protected types

In the previous examples, we defined single tasks and protected objects. We can, however, generalize tasks and protected objects using type definitions. This allows us, for example, to create multiple tasks based on just a single task type.

## **12.3.1 Task types**

A task type is a generalization of a task. The declaration is similar to simple tasks: you replace task with task type. The difference between simple tasks and task types is that task types don't create actual tasks that automatically start. Instead, a task declaration is needed. This is exactly the way normal variables and types work: objects are only created by variable definitions, not type definitions.

To illustrate this, we repeat our first example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Simple_Task is
   task T;

(continues on next page)
```

```
task body T is
begin
    Put_Line ("In task T");
end T;
begin
    Put_Line ("In main");
end Show_Simple_Task;
```

We now rewrite it by replacing task T with task type TT. We declare a task (A\_Task) based on the task type TT after its definition:

```
with Ada.Text_IO; use Ada.Text_IO;

procedure Show_Simple_Task_Type is
   task type TT;

  task body TT is
  begin
    Put_Line ("In task type TT");
  end TT;

  A_Task : TT;

begin
  Put_Line ("In main");
end Show_Simple_Task_Type;
```

We can extend this example and create an array of tasks. Since we're using the same syntax as for variable declarations, we use a similar syntax for task types: array (<>) of Task\_Type. Also, we can pass information to the individual tasks by defining a Start entry. Here's the updated example:

```
with Ada.Text IO; use Ada.Text IO;
procedure Show_Task_Type_Array is
   task type TT is
     entry Start (N : Integer);
  end TT;
  task body TT is
     Task_N : Integer;
  begin
     accept Start (N : Integer) do
        Task N := N;
      end Start;
      Put_Line ("In task T: " & Integer'Image (Task_N));
  end TT;
  My_Tasks : array (1 .. 5) of TT;
begin
  Put_Line ("In main");
   for I in My_Tasks'Range loop
     My_Tasks (I).Start (I);
  end loop;
end Show_Task_Type_Array;
```

In this example, we're declaring five tasks in the array My\_Tasks. We pass the array index to the individual tasks in the entry point (Start). After the synchronization between the individual subtasks and the main task, each subtask calls Put Line concurrently.

### **12.3.2 Protected types**

A protected type is a generalization of a protected object. The declaration is similar to that for protected objects: you replace protected with protected type. Like task types, protected types require an object declaration to create actual objects. Again, this is similar to variable declarations and allows for creating arrays (or other composite objects) of protected objects.

We can reuse a previous example and rewrite it to use a protected type:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Protected_Object_Type is
  protected type Obj_Type is
      procedure Set (V : Integer);
      function Get return Integer;
      Local : Integer := 0;
  end Obj_Type;
  protected body Obj_Type is
      procedure Set (V : Integer) is
      begin
         Local := V;
     end Set;
      function Get return Integer is
         return Local;
      end Get;
  end Obj_Type;
  Obj : Obj_Type;
  Obj.Set (5);
  Put Line ("Number is: " & Integer'Image (Obj.Get));
end Show_Protected_Object_Type;
```

In this example, instead of directly defining the protected object <code>Obj</code>, we first define a protected type <code>Obj\_Type</code> and then declare <code>Obj</code> as an object of that protected type. Note that the main application hasn't changed: we still use <code>Obj.Set</code> and <code>Obj.Get</code> to access the protected object, just like in the original example.

**CHAPTER** 

### **THIRTEEN**

### **DESIGN BY CONTRACTS**

Contracts are used in programming to codify expectations. Parameter modes of a subprogram can be viewed as a simple form of contracts. When the specification of subprogram **Op** declares a parameter using **in** mode, the caller of **Op** knows that the **in** argument won't be changed by **Op**. In other words, the caller expects that **Op** doesn't modify the argument it's providing, but just reads the information stored in the argument. Constraints and subtypes are other examples of contracts. In general, these specifications improve the consistency of the application.

*Design-by-contract* programming refers to techniques that include pre- and postconditions, subtype predicates, and type invariants. We study those topics in this chapter.

## 13.1 Pre- and postconditions

Pre- and postconditions provide expectations regarding input and output parameters of subprograms and return value of functions. If we say that certain requirements must be met before calling a subprogram 0p, those are preconditions. Similarly, if certain requirements must be met after a call to the subprogram 0p, those are postconditions. We can think of preconditions and postconditions as promises between the subprogram caller and the callee: a precondition is a promise from the caller to the callee, and a postcondition is a promise in the other direction.

Pre- and postconditions are specified using a with clause in the subprogram declaration. A with Pre => <condition> clause specifies a precondition and a with Post => <condition> clause specifies a postcondition.

The following code shows an example of preconditions:

In this example, we want to prevent the name field in our database from containing an empty string. We implement this requirement by using a precondition requiring that the length of the string used for the Name parameter of the DB\_Entry procedure is greater than zero. If the DB\_Entry procedure is called with an empty string for the Name parameter, the call will fail because the precondition is not met.

The pragma Assertion\_Policy statement is used to force the compiler to generate code to check the precondition. The same pragma is used similarly for the other kinds of contracts shown in the rest of this chapter. When using GNAT, you can get that behavior globally via a configuration pragma or a command-line switch — please consult the GNAT documentation on configuration pragmas<sup>19</sup> for details.

Before we get to our next example, let's briefly discuss quantified expressions, which are quite useful in concisely writing pre- and postconditions. Quantified expressions return a Boolean value indicating whether elements of an array or container match the expected condition. They have the form: (for all I in A'Range => <condition on A(I)>, where A is an array and I is an index. Quantified expressions using for all check whether the condition is true for every element. For example:

```
(for all I in A'Range => A (I) = 0)
```

This quantified expression is only true when all elements of the array A have a value of zero.

Another kind of quantified expressions uses for some. The form looks similar: (for some I in A'Range  $\Rightarrow$  <condition on A(I)>. However, in this case the qualified expression tests whether the condition is true only on *some* elements (hence the name) instead of all elements.

We illustrate postconditions using the following example:

```
with Ada.Text IO; use Ada.Text IO;
procedure Show Simple Postcondition is
  pragma Assertion Policy (Post => Check);
  type Int 8 is range -2 ** 7 .. 2 ** 7 - 1;
  type Int_8_Array is array (Integer range <>) of Int_8;
   function Square (A : Int_8) return Int_8 is
     (A * A)
    with Post => Square'Result > A;
  procedure Square (A : in out Int 8 Array)
    with Post => (for all I in A'Range =>
                     A (I) = A'Old (I) * A'Old (I))
  is
  begin
     for V of A loop
        V := Square (V);
     end loop;
  end Square;
  V : Int_8_Array := (9, 10, 11);
begin
   for E of V loop
     Put_Line ("Original: " & Int_8'Image (E));
  end loop;
  New_Line;
  Square (V);
   for E of V loop
      Put_Line ("Square: " & Int_8'Image (E));
  end loop;
end Show Simple Postcondition;
```

We declare a signed 8-bit type Int\_8 and an array of that type (Int\_8\_Array). We want to ensure each element of the array is doubled after calling the procedure Square for an object of the

 $<sup>^{19}\</sup> http://docs.adacore.com/live/wave/gnat_ugn/html/gnat_ugn/gnat_ugn/the_gnat_compilation_model.html# configuration-pragmas$ 

Int\_8\_Array type. We do this with a postcondition using a for all expression. This postcondition also uses the 'Old attribute to refer to the original value of the parameter (before the call).

We also want to ensure that the result of calls to the Square function for the Int\_8 type are greater than the input to that call. To do that, we write a postcondition using the 'Result attribute of the function and comparing it to the input value.

We can use both pre- and postconditions in the declaration of a single subprogram. For example:

```
with Ada.Text IO; use Ada.Text IO;
procedure Show Simple Contract is
  pragma Assertion Policy (Pre => Check,
                            Post => Check);
  type Int_8 is range -2 ** 7 .. 2 ** 7 - 1;
   function Square (A : Int 8) return Int 8 is
     (A * A)
    with
          Pre => (Integer'Size >= Int 8'Size * 2 and
                   Integer (A) * Integer (A) < Integer (Int_8'Last)),</pre>
          Post => Square'Result > A;
  V : Int 8;
begin
  V := Square (11);
  Put Line ("Square of 11 is " & Int 8'Image (V));
  V := Square (12); -- Precondition will fail...
  Put Line ("Square of 12 is " & Int 8'Image (V));
end Show Simple Contract;
```

In this example, we want to ensure that the input value of calls to the Square function for the Int\_8 type won't cause overflow in that function. We do this by converting the input value to the Integer type, which is used for the temporary calculation, and check if the result is in the appropriate range for the Int 8 type. We have the same postcondition in this example as in the previous one.

## 13.2 Predicates

Predicates specify expectations regarding types. They're similar to pre- and postconditions, but apply to types instead of subprograms. Their conditions are checked for each object of a given type, which allows verifying that an object of type T is conformant to the requirements of its type.

There are two kinds of predicates: static and dynamic. In simple terms, static predicates are used to check objects at compile-time, while dynamic predicates are used for checks at run time. Normally, static predicates are used for scalar types and dynamic predicates for the more complex types.

Static and dynamic predicates are specified using the following clauses, respectively:

```
with Static_Predicate => <property>with Dynamic Predicate => <property>
```

Let's use the following example to illustrate dynamic predicates:

```
with Ada.Strings.Unbounded; use Ada.Strings.Unbounded;
with Ada.Calendar; use Ada.Calendar;
with Ada.Containers.Vectors;
procedure Show_Dynamic_Predicate_Courses is

(continues on next page)
```

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```
pragma Assertion_Policy (Dynamic_Predicate => Check);
   package Courses is
      type Course_Container is private;
      type Course is record
                : Unbounded_String;
         Name
         Start_Date : Time;
         End Date
                  : Time;
      end record
        with Dynamic_Predicate => Course.Start_Date <= Course.End_Date;</pre>
      procedure Add (CC : in out Course_Container; C : Course);
   private
      package Course_Vectors is new Ada.Containers.Vectors
        (Index_Type => Natural,
         Element_Type => Course);
      type Course_Container is record
         V : Course Vectors. Vector;
      end record;
   end Courses;
   package body Courses is
      procedure Add (CC : in out Course Container; C : Course) is
      begin
         CC.V.Append (C);
      end Add;
   end Courses;
   use Courses;
   CC : Course Container;
begin
   Add (CC,
        Course'(
                     => To Unbounded String ("Intro to Photography"),
          Name
          Start Date \Rightarrow Time Of (2018, 5, 1),
          End_Date => Time_Of (2018, 5, 10)));
   -- This should trigger an error in the dynamic predicate check
   Add (CC,
        Course'(
                     => To Unbounded String ("Intro to Video Recording"),
          Name
          Start_Date => Time_Of (2019, 5, 1),
          End Date \Rightarrow Time Of (2018, 5, 10)));
end Show_Dynamic_Predicate_Courses;
```

In this example, the package Courses defines a type Course and a type Course\_Container, an object of which contains all courses. We want to ensure that the dates of each course are consistent, specifically that the start date is no later than the end date. To enforce this rule, we declare a dynamic predicate for the Course type that performs the check for each object. The predicate uses the type name where a variable of that type would normally be used: this is a reference to the instance of the object being tested.

Static predicates, as mentioned above, are mostly used for scalar types and checked during compilation. They're particularly useful for representing non-contiguous elements of an enumeration. A classic example is a list of week days:

```
type Week is (Mon, Tue, Wed, Thu, Fri, Sat, Sun);
```

We can easily create a sub-list of work days in the week by specifying a subtype with a range based on Week. For example:

```
subtype Work_Week is Week range Mon .. Fri;
```

Ranges in Ada can only be specified as contiguous lists: they don't allow us to pick specific days. However, we may want to create a list containing just the first, middle and last day of the work week. To do that, we use a static predicate:

```
subtype Check_Days is Work_Week
with Static_Predicate => Check_Days in Mon | Wed | Fri;
```

Let's look at a complete example:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Predicates is
   pragma Assertion Policy (Static Predicate => Check,
                             Dynamic_Predicate => Check);
   type Week is (Mon, Tue, Wed, Thu, Fri, Sat, Sun);
   subtype Work Week is Week range Mon .. Fri;
   subtype Test_Days is Work_Week
     with Static_Predicate => Test_Days in Mon | Wed | Fri;
   type Tests_Week is array (Week) of Natural
     with Dynamic Predicate =>
       (for all I in Tests_Week'Range =>
          (case I is
               when Test_Days => Tests_Week (I) > 0,
                             => Tests_Week (I) = 0));
               when others
   Num_Tests : Tests_Week :=
                 (Mon \Rightarrow 3, Tue \Rightarrow 0,
                  Wed \Rightarrow 4, Thu \Rightarrow 0,
                  Fri => 2, Sat => 0, Sun => 0);
   procedure Display_Tests (N : Tests_Week) is
   begin
      for I in Test Days loop
         Put_Line ("# tests on " & Test_Days'Image (I)
                   & " => " & Integer'Image (N (I)));
      end loop;
   end Display_Tests;
begin
   Display_Tests (Num_Tests);
   -- Assigning non-conformant values to individual elements of
   -- the Tests_Week type does not trigger a predicate check:
   Num_Tests (Tue) := 2;
   -- However, assignments with the "complete" Tests_Week type
      trigger a predicate check. For example:
   -- Num_Tests := (others => 0);
```

(continues on next page)

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```
    -- Also, calling any subprogram with parameters of Tests_Week
    -- type triggers a predicate check.
    -- Therefore, the following line will fail:
    Display_Tests (Num_Tests);
    end Show_Predicates;
```

Here we have an application that wants to perform tests only on three days of the work week. These days are specified in the Test\_Days subtype. We want to track the number of tests that occur each day. We declare the type Tests\_Week as an array, an object of which will contain the number of tests done each day. According to our requirements, these tests should happen only in the aforementioned three days; on other days, no tests should be performed. This requirement is implemented with a dynamic predicate of the type Tests\_Week. Finally, the actual information about these tests is stored in the array Num Tests, which is an instance of the Tests Week type.

The dynamic predicate of the Tests\_Week type is verified during the initialization of Num\_Tests. If we have a non-conformant value there, the check will fail. However, as we can see in our example, individual assignments to elements of the array do not trigger a check. We can't check for consistency at this point because the initialization of the a complex data structure (such as arrays or records) may not be performed with a single assignment. However, as soon as the object is passed as an argument to a subprogram, the dynamic predicate is checked because the subprogram requires the object to be consistent. This happens in the last call to Display\_Tests in our example. Here, the predicate check fails because the previous assignment has a non-conformant value.

## **13.3 Type invariants**

Type invariants are another way of specifying expectations regarding types. While predicates are used for *non-private* types, type invariants are used exclusively to define expectations about private types. If a type T from a package P has a type invariant, the results of operations on objects of type T are always consistent with that invariant.

Type invariants are specified with a with Type\_Invariant => roperty> clause. Like predicates, the *property* defines a condition that allows us to check if an object of type T is conformant to its requirements. In this sense, type invariants can be viewed as a sort of predicate for private types. However, there are some differences in terms of checks. The following table summarizes the differences:

Element	Subprogram parameter checks	Assignment checks
Predi-	On all in and out parameters	On assignments and ex-
cates		plicit initializations
Type in-	On out parameters returned from subprograms de-	On all initializations
variants	clared in the same public scope	

We could rewrite our previous example and replace dynamic predicates by type invariants. It would look like this:

```
with Type_Invariant => Check (Course);
      type Course_Container is private;
      procedure Add (CC : in out Course_Container; C : Course);
      function Init
        (Name : String; Start_Date, End_Date : Time) return Course;
      function Check (C : Course) return Boolean;
  private
      type Course is record
                : Unbounded_String;
         Start_Date : Time;
                  : Time;
         End Date
      end record;
      function Check (C
                               : Course) return Boolean is
        (C.Start_Date <= C.End_Date);</pre>
      package Course_Vectors is new Ada.Containers.Vectors
        (Index Type => Natural,
         Element Type => Course);
      type Course Container is record
         V : Course_Vectors.Vector;
      end record;
  end Courses;
  package body Courses is
      procedure Add (CC : in out Course Container; C : Course) is
      begin
         CC.V.Append (C);
      end Add;
      function Init
        (Name : String; Start_Date, End_Date : Time) return Course is
      begin
         return Course'(Name
                                   => To_Unbounded_String (Name),
                        Start_Date => Start_Date,
                        End Date => End Date);
      end Init;
  end Courses;
  use Courses;
  CC : Course_Container;
begin
  Add (CC,
        Init (Name
                       => "Intro to Photography",
              Start_Date => Time_Of (2018, 5, 1),
              End_Date => Time_Of (2018, 5, 10)));
      This should trigger an error in the type-invariant check
  Add (CC,
                        => "Intro to Video Recording",
        Init (Name
              Start Date => Time Of (2019, 5, 1),
                       => Time_Of (2018, 5, 10)));
              End Date
end Show_Type_Invariant;
```

The major difference is that the Course type was a visible (public) type of the Courses package in

the previous example, but in this example is a private type.		

**CHAPTER** 

## **FOURTEEN**

## INTERFACING WITH C

Ada allows us to interface with code in many languages, including C and C++. This section discusses how to interface with C.

# 14.1 Multi-language project

By default, when using **gprbuild** we only compile Ada source files. To compile C files as well, we need to modify the project file used by **gprbuild**. We use the **Languages** entry, as in the following example:

```
project Multilang is

for Languages use ("ada", "c");

for Source_Dirs use ("src");
  for Main use ("main.adb");
  for Object_Dir use "obj";

end Multilang;
```

# 14.2 Type convention

To interface with data types declared in a C application, you specify the Convention aspect on the corresponding Ada type declaration. In the following example, we interface with the C\_Enum enumeration declared in a C source file:

```
procedure Show_C_Enum is

type C_Enum is (A, B, C) with Convention => C;
-- Use C convention for C_Enum
begin
   null;
end Show_C_Enum;
```

To interface with C's built-in types, we use the Interfaces. C package, which contains most of the type definitions we need. For example:

```
with Interfaces.C; use Interfaces.C;
procedure Show_C_Struct is

type c_struct is record
    a : int;
```

```
b : long;
c : unsigned;
d : double;
end record
with Convention => C;

begin
null;
end Show_C_Struct;
```

Here, we're interfacing with a C struct (C\_Struct) and using the corresponding data types in C (int, long, unsigned and double). This is the declaration in C:

```
struct c_struct
{
    int         a;
    long        b;
    unsigned    c;
    double    d;
};
```

## 14.3 Foreign subprograms

## 14.3.1 Calling C subprograms in Ada

We use a similar approach when interfacing with subprograms written in C. In this case, an additional aspect is required: Import. For example:

```
with Interfaces.C; use Interfaces.C;

procedure Show_C_Func is

function my_func (a : int) return int
    with
        Import => True,
        Convention => C;
    -- Imports function 'my_func' from C.
    -- You can now call it from Ada.

begin
    null;
end Show_C_Func;
```

This code interfaces with the following declaration in the C header file:

```
int my_func (int a);
```

Here's the corresponding C definition:

```
#include "my_func.h"

int my_func (int a)
{
    return a * 2;
}
```

If you want, you can use a different subprogram name in the Ada code. For example, we could call the C function Get Value:

```
with Interfaces.C; use Interfaces.C;
with Ada.Text IO; use Ada.Text IO;
procedure Show_C_Func is
  function Get_Value (a : int) return int
    with
                    => True.
      Import
      Convention => C,
      External Name => "my func";
   -- Imports function 'my func' from C and
  -- rename it to 'Get Value'
  V : int;
begin
  V := Get_Value (2);
  Put_Line ("Result is " & int'Image (V));
end Show_C_Func;
```

## 14.3.2 Calling Ada subprograms in C

You can also call Ada subprograms from C applications. You do this with the Export aspect. For example:

This is the corresponding body that implements that function:

```
package body C_API is

function My_Func (a : int) return int is
begin
    return a * 2;
end My_Func;
end C_API;
```

On the C side, we do the same as we would if the function were written in C: simply declare it using the extern keyword. For example:

```
#include <stdio.h>
extern int my_func (int a);
int main (int argc, char **argv) {
  int v = my_func(2);
```

```
printf("Result is %d\n", v);
  return 0;
}
```

# 14.4 Foreign variables

## 14.4.1 Using C global variables in Ada

To use global variables from C code, we use the same method as subprograms: we specify the Import and Convention aspects for each variable we want to import.

Let's reuse an example from the previous section. We'll add a global variable (func\_cnt) to count the number of times the function (my\_func) is called:

```
/*% filename: test.h */
extern int func_cnt;
int my_func (int a);
```

The variable is declared in the C file and incremented in my\_func:

```
#include "test.h"
int func_cnt = 0;
int my_func (int a)
{
  func_cnt++;
  return a * 2;
}
```

In the Ada application, we just reference the foreign variable:

```
with Interfaces.C; use Interfaces.C;
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_C_Func is
  function my_func (a : int) return int
      Import
                   => True,
      Convention
                    => C;
  V : int;
  func_cnt : int
    with
      Import
                  => True,
      Convention => C;
   -- We can access the func_cnt variable from test.c
begin
  V := my_func (1);
  V := my_func(2);
```

```
V := my_func (3);
Put_Line ("Result is " & int'Image (V));

Put_Line ("Function was called " & int'Image (func_cnt) & " times");
end Show_C_Func;
```

As we see by running the application, the value of the counter is the number of times my\_func was called.

We can use the External\_Name aspect to give a different name for the variable in the Ada application in the same we do for subprograms.

## 14.4.2 Using Ada variables in C

You can also use variables declared in Ada files in C applications. In the same way as we did for subprograms, you do this with the Export aspect.

Let's reuse a past example and add a counter, as in the previous example, but this time have the counter incremented in Ada code:

```
with Interfaces.C; use Interfaces.C;

package C_API is

func_cnt : int := 0
    with
        Export => True,
        Convention => C;

function My_Func (a : int) return int
    with
        Export => True,
        Convention => C,
        External_Name => "my_func";

end C_API;
```

The variable is then increment in My Func:

```
--% filename: c_api.adb
package body C_API is

function My_Func (a : int) return int is
begin
    func_cnt := func_cnt + 1;
    return a * 2;
end My_Func;

end C_API;
```

In the C application, we just need to declare the variable and use it:

```
#include <stdio.h>
extern int my_func (int a);
extern int func_cnt;
int main (int argc, char **argv) {
```

```
int v;

v = my_func(1);
v = my_func(2);
v = my_func(3);

printf("Result is %d\n", v);

printf("Function was called %d times\n", func_cnt);

return 0;
}
```

Again, by running the application, we see that the value from the counter is the number of times that my func was called.

# 14.5 Generating bindings

In the examples above, we manually added aspects to our Ada code to correspond to the C source-code we're interfacing with. This is called creating a *binding*. We can automate this process by using the *Ada spec dump* compiler option: -fdump-ada-spec. We illustrate this by revisiting our previous example.

This was our C header file:

```
extern int func_cnt;
int my_func (int a);
```

To create Ada bindings, we'll call the compiler like this:

```
gcc -c -fdump-ada-spec -C ./test.h
```

The result is an Ada spec file called test h.ads:

```
pragma Ada_2005;
pragma Style_Checks (Off);
with Interfaces.C; use Interfaces.C;

package test_h is
  func_cnt : aliased int; -- ./test.h:3
    pragma Import (C, func_cnt, "func_cnt");
  function my_func (argl : int) return int; -- ./test.h:5
    pragma Import (C, my_func, "my_func");
end test_h;
```

Now we simply refer to this test\_h package in our Ada application:

```
with Interfaces.C; use Interfaces.C;
with Ada.Text_IO; use Ada.Text_IO;
with test_h; use test_h;
procedure Show_C_Func is
```

```
V : int;
begin

V := my_func (1);
V := my_func (2);
V := my_func (3);
Put_Line ("Result is " & int'Image (V));

Put_Line ("Function was called " & int'Image (func_cnt) & " times");
end Show_C_Func;
```

You can specify the name of the parent unit for the bindings you're creating as the operand to fdump-ada-spec:

```
gcc -c -fdump-ada-spec -fada-spec-parent=Ext_C_Code -C ./test.h
```

This creates the file ext c code-test h.ads:

```
package Ext_C_Code.test_h is
    -- automatic generated bindings...
end Ext_C_Code.test_h;
```

## 14.5.1 Adapting bindings

The compiler does the best it can when creating bindings for a C header file. However, sometimes it has to guess about the translation and the generated bindings don't always match our expectations. For example, this can happen when creating bindings for functions that have pointers as arguments. In this case, the compiler may use System. Address as the type of one or more pointers. Although this approach works fine (as we'll see later), this is usually not how a human would interpret the C header file. The following example illustrates this issue.

Let's start with this C header file:

```
/*% filename: test.h */
struct test;
struct test * test_create(void);
void test_destroy(struct test *t);
void test_reset(struct test *t);
void test_set_name(struct test *t, char *name);
void test_set_address(struct test *t, char *address);
void test_display(const struct test *t);
```

And the corresponding C implementation:

```
#include <stdlib.h>
#include <string.h>
#include <stdio.h>

#include "test.h"

struct test {
```

```
char name[80];
 char address[120];
};
static size_t
strlcpy(char *dst, const char *src, size_t dstsize)
 size_t len = strlen(src);
 if (dstsize) {
   size_t bl = (len < dstsize-1 ? len : dstsize-1);</pre>
    ((char*)memcpy(dst, src, bl))[bl] = 0;
  return len;
struct test * test_create(void)
  return malloc (sizeof (struct test));
}
void test destroy(struct test *t)
 if (t != NULL) {
   free(t);
}
void test_reset(struct test *t)
              = '\0';
  t->name[0]
  t->address[0] = '\setminus 0';
void test set name(struct test *t, char *name)
{
 strlcpy(t->name, name, sizeof(t->name));
void test set address(struct test *t, char *address)
 strlcpy(t->address, address, sizeof(t->address));
}
void test display(const struct test *t)
 printf("Name:
                %s\n", t->name);
 printf("Address: %s\n", t->address);
}
```

Next, we'll create our bindings:

```
gcc -c -fdump-ada-spec -C ./test.h
```

This creates the following specification in test\_h.ads:

```
pragma Ada_2005;
pragma Style_Checks (Off);
with Interfaces.C; use Interfaces.C;
with System;
with Interfaces.C.Strings;
(continues on next page)
```

```
package test h is
   -- skipped empty struct test
  function test_create return System.Address; -- ./test.h:5
  pragma Import (C, test_create, "test_create");
  procedure test_destroy (arg1 : System.Address); -- ./test.h:7
  pragma Import (C, test_destroy, "test_destroy");
  procedure test_reset (arg1 : System.Address); -- ./test.h:9
  pragma Import (C, test_reset, "test_reset");
  procedure test_set_name (arg1 : System.Address; arg2 : Interfaces.C.Strings.
⇔chars_ptr); -- ./test.h:11
  pragma Import (C, test_set_name, "test_set_name");
  procedure test set address (arg1 : System.Address; arg2 : Interfaces.C.Strings.
⇔chars_ptr); -- ./test.h:13
  pragma Import (C, test set address, "test set address");
  procedure test display (arg1 : System.Address); -- ./test.h:15
  pragma Import (C, test display, "test display");
end test h;
```

As we can see, the binding generator completely ignores the declaration struct test and all references to the test struct are replaced by addresses (System.Address). Nevertheless, these bindings are good enough to allow us to create a test application in Ada:

```
with Interfaces.C:
                         use Interfaces.C:
with Interfaces.C.Strings; use Interfaces.C.Strings;
with Ada.Text_IO; use Ada.Text_IO;
with test h;
                         use test h;
with System;
procedure Show Automatic C Struct Bindings is
          : constant chars ptr := New String ("John Doe");
  Address : constant chars_ptr := New_String ("Small Town");
  T : System. Address := test create;
begin
  test reset (T);
  test_set_name (T, Name);
  test set address (T, Address);
  test_display (T);
   test destroy (T);
end Show Automatic C Struct Bindings;
```

We can successfully bind our C code with Ada using the automatically-generated bindings, but they aren't ideal. Instead, we would prefer Ada bindings that match our (human) interpretation of the C header file. This requires manual analysis of the header file. The good news is that we can use the automatic generated bindings as a starting point and adapt them to our needs. For example, we can:

1. Define a Test type based on System. Address and use it in all relevant functions.

2. Remove the test\_prefix in all operations on the Test type.

This is the resulting specification:

```
with Interfaces.C; use Interfaces.C;
with System;
with Interfaces.C.Strings;
package adapted test h is
  type Test is new System. Address;
  function Create return Test;
  pragma Import (C, Create, "test create");
  procedure Destroy (T : Test);
  pragma Import (C, Destroy, "test destroy");
  procedure Reset (T : Test);
  pragma Import (C, Reset, "test_reset");
  procedure Set_Name (T : Test;
                       Name : Interfaces C. Strings chars ptr); -- ./test.h:11
  pragma Import (C, Set Name, "test set name");
  procedure Set_Address (T
                                  : Test:
                          Address : Interfaces C. Strings chars ptr);
  pragma Import (C, Set_Address, "test_set_address");
  procedure Display (T : Test); -- ./test.h:15
  pragma Import (C, Display, "test_display");
end adapted test h;
```

And this is the corresponding Ada body:

```
with Interfaces.C;
                            use Interfaces.C;
with Interfaces.C.Strings; use Interfaces.C.Strings;
with Ada.Text_IO;      use Ada.Text_IO;
with adapted_test_h;      use adapted_test_h;
with System;
procedure Show_Adapted_C_Struct_Bindings is
            : constant chars ptr := New String ("John Doe");
   Address : constant chars ptr := New String ("Small Town");
   T : Test := Create;
begin
   Reset (T);
   Set_Name (T, Name);
   Set_Address (T, Address);
   Display (T);
   Destroy (T);
end Show_Adapted_C_Struct_Bindings;
```

Now we can use the Test type and its operations in a clean, readable way.

# **OBJECT-ORIENTED PROGRAMMING**

Object-oriented programming (OOP) is a large and ill-defined concept in programming languages and one that tends to encompass many different meanings because different languages often implement their own vision of it, with similarities and differences from the implementations in other languages.

However, one model mostly "won" the battle of what object-oriented means, if only by sheer popularity. It's the model used in the Java programming language, which is very similar to the one used by C++. Here are some defining characteristics:

- Type derivation and extension: Most object oriented languages allow the user to add fields to derived types.
- Subtyping: Objects of a type derived from a base type can, in some instances, be substituted for objects of the base type.
- Runtime polymorphism: Calling a subprogram, usually called a *method*, attached to an object type can dispatch at runtime depending on the exact type of the object.
- Encapsulation: Objects can hide some of their data.
- Extensibility: People from the "outside" of your package, or even your whole library, can derive from your object types and define their own behaviors.

Ada dates from before object-oriented programming was as popular as it is today. Some of the mechanisms and concepts from the above list were in the earliest version of Ada even before what we would call OOP was added:

- As we saw, encapsulation is not implemented at the type level in Ada, but instead at the package level.
- Subtyping can be implemented using, well, subtypes, which have a full and permissive static substitability model. The substitution will fail at runtime if the dynamic constraints of the subtype are not fulfilled.
- Runtime polymorphism can be implemented using variant records.

However, this lists leaves out type extensions, if you don't consider variant records, and extensibility.

The 1995 revision of Ada added a feature filling the gaps, which allowed people to program following the object-oriented paradigm in an easier fashion. This feature is called *tagged types*.

**Note:** It's possible to program in Ada without ever creating tagged types. If that's your prefered style of programming or you have no specific use for tagged types, feel free to not use them, as is the case for many features of Ada.

However, they can be the best way to express solutions to certain problems and they may be the best way to solve your problem. If that's the case, read on!

# 15.1 Derived types

Before presenting tagged types, we should discuss a topic we have brushed on, but not really covered, up to now:

You can create one or more new types from every type in Ada. Type derivation is built into the language.

```
package Newtypes is
  type Point is record
    X, Y : Integer;
  end record;

type New_Point is new Point;
end Newtypes;
```

Type derivation is useful to enforce strong typing because the type system treats the two types as incompatible.

But the benefits are not limited to that: you can inherit things from the type you derive from. You not only inherit the representation of the data, but you can also inherit behavior.

When you inherit a type you also inherit what are called *primitive operations*. A primitive operation (or just a *primitive*) is a subprogram attached to a type. Ada defines primitives as subprograms defined in the same scope as the type.

**Attention:** A subprogram will only become a primitive of the type if:

- 1. The subprogram is declared in the same scope as the type and
- 2. The type and the subprogram are declared in a package

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Primitives is
 package Week is
    type Days is (Monday, Tuesday, Wednesday, Thursday,
                  Friday, Saturday, Sunday);
     -- Print day is a primitive of the type Days
    procedure Print_Day (D : Days);
 end Week;
 package body Week is
    procedure Print_Day (D : Days) is
    begin
       Put Line (Days'Image (D));
    end Print_Day;
 end Week;
 use Week;
 type Weekend_Days is new Days range Saturday .. Sunday;
  -- A procedure Print_Day is automatically inherited here. It is as if
  -- the procedure
  -- procedure Print Day (D : Weekend Days);
  -- has been declared with the same body
```

```
Sat : Weekend_Days := Saturday;
begin
    Print_Day (Sat);
end Primitives;
```

This kind of inheritance can be very useful, and is not limited to record types (you can use it on discrete types, as in the example above), but it's only superficially similar to object-oriented inheritance:

- Records can't be extended using this mechanism alone. You also can't specify a new representation for the new type: it will **always** have the same representation as the base type.
- There's no facility for dynamic dispatch or polymorphism. Objects are of a fixed, static type.

There are other differences, but it's not useful to list them all here. Just remember that this is a kind of inheritance you can use if you only want to statically inherit behavior without duplicating code or using composition, but a kind you can't use if you want any dynamic features that are usually associated with OOP.

# 15.2 Tagged types

The 1995 revision of the Ada language introduced tagged types to fullfil the need for an unified solution that allows programming in an object-oriented style similar to the one described at the beginning of this chapter.

Tagged types are very similar to normal records except that some functionality is added:

- Types have a tag, stored inside each object, that identifies the runtime type<sup>20</sup> of that object.
- Primitives can dispatch. A primitive on a tagged type is what you would call a *method* in Java or C++. If you derive a base type and override a primitive of it, you can often call it on an object with the result that which primitive is called depends on the exact runtime type of the object.
- Subtyping rules are introduced allowing a tagged type derived from a base type to be statically compatible with the base type.

Let's see our first tagged type declarations:

```
package P is
   type My_Class is tagged null record;
   -- Just like a regular record, but with tagged qualifier

-- Methods are outside of the type definition:

procedure Foo (Self : in out My_Class);
   -- If you define a procedure taking a My_Class argument
   -- in the same package, it will be a method.

-- Here's how you derive a tagged type:

type Derived is new My_Class with record
   A : Integer;
   -- You can add fields in derived types.
end record;

overriding procedure Foo (Self : in out Derived);
   -- The "overriding" qualifier is optional, but if it is present,

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```

15.2. Tagged types

<sup>&</sup>lt;sup>20</sup> https://en.wikipedia.org/wiki/Run-time\_type\_information

```
-- it must be valid.
end P;
```

```
with Ada.Text_IO; use Ada.Text_IO;

package body P is
    procedure Foo (Self : in out My_Class) is
    begin
        Put_Line ("In My_Class.Foo");
    end Foo;

procedure Foo (Self : in out Derived) is
    begin
        Put_Line ("In Derived.Foo, A = " & Integer'Image (Self.A));
    end Foo;
end P;
```

# **15.3 Classwide types**

To remain consistent with the rest of the language, a new notation needed to be introduced to say "This object is of this type or any descendent derives tagged type".

In Ada, we call this the *classwide type*. It's used in OOP as soon as you need polymorphism. For example, you can't do the following:

```
with P; use P;
procedure Main is

01 : My_Class;
-- Declaring an object of type My_Class

02 : Derived := (A => 12);
-- Declaring an object of type Derived

03 : My_Class := 02;
-- INVALID: Trying to assign a value of type derived to a variable of -- type My_Class.
begin
    null;
end Main;
```

This is because an object of a type T is exactly of the type T, whether T is tagged or not. What you want to say as a programmer is "I want O3 to be able to hold an object of type My\_Class or any type descending from My Class". Here's how you do that:

```
with P; use P;
procedure Main is
    01 : My_Class;
    -- Declare an object of type My_Class

02 : Derived := (A => 12);
    -- Declare an object of type Derived

03 : My_Class'Class := 02;
    -- Now valid: My_Class'Class designates the classwide type for
```

```
-- My_Class, which is the set of all types descending from My_Class
-- (including My_Class).
begin
  null;
end Main;
```

**Attention:** Because an object of a classwide type can be the size of any descendent of its base type, it has an unknown size. It's therefore an indefinite type, with the expected restrictions:

- It can't be stored as a field/component of a record
- An object of a classwide type needs to be initialized immediately (you can't specify the constraints of such a type in any way other than by initializing it).

# 15.4 Dispatching operations

We saw that you can override operations in types derived from another tagged type. The eventual goal of OOP is to make a dispatching call: a call to a primitive (method) that depends on the exact type of the object.

But, if you think carefully about it, a variable of type My\_Class always contains an object of exactly that type. If you want to have a variable that can contain a My\_Class or any derived type, it has to be of type My Class'Class.

In other words, to make a dispatching call, you must first have an object that can be either of a type or any type derived from this type, namely an object of a classwide type.

```
with P; use P;
procedure Main is
  01 : My Class;
   -- Declare an object of type My Class
  02 : Derived := (A => 12);
   -- Declare an object of type Derived
  03 : My Class'Class := 02;
  04 : My Class'Class := 01;
begin
  Foo (01);
   -- Non dispatching: Calls My Class.Foo
  Foo (02):
   -- Non dispatching: Calls Derived.Foo
  Foo (03):
   -- Dispatching: Calls Derived.Foo
   Foo (04);
   -- Dispatching: Calls My Class.Foo
end Main;
```

**Attention:** You can convert an object of type Derived to an object of type My\_Class. This is called a *view conversion* in Ada parlance and is useful, for example, if you want to call a parent method.

In that case, the object really is converted to a My\_Class object, which means its tag is changed. Since tagged objects are always passed by reference, you can use this kind of conversion to

## 15.5 Dot notation

You can also call primitives of tagged types with a notation that's more familiar to object oriented programmers. Given the Foo primitive above, you can also write the above program this way:

```
with P; use P;
procedure Main is
  01 : My Class;
   -- Declare an object of type My Class
  02 : Derived := (A => 12);
   -- Declare an object of type Derived
  03 : My_Class'Class := 02;
  04 : My_Class'Class := 01;
begin
  01.Foo;
   -- Non dispatching: Calls My Class.Foo
  02.Foo:
   -- Non dispatching: Calls Derived.Foo
  03.Foo;
   -- Dispatching: Calls Derived.Foo
  04.Foo;
   -- Dispatching: Calls My_Class.Foo
end Main;
```

If the dispatching parameter of a primitive is the first parameter, which is the case in our examples, you can call the primitive using the dot notation. Any remaining parameter are passed normally:

```
with P; use P;
procedure Main is
   package Extend is
   type D2 is new Derived with null record;
```

```
procedure Bar (Self : in out D2; Val : Integer);
end Extend;

package body Extend is
    procedure Bar (Self : in out D2; Val : Integer) is
    begin
        Self.A := Self.A + Val;
    end Bar;
end Extend;

use Extend;

Obj : D2 := (A => 15);
begin
    Obj.Bar (2);
Obj.Foo;
end Main;
```

15.5. Dot notation

**CHAPTER** 

SIXTEEN

## STANDARD LIBRARY

# 16.1 Standard package

### 16.2 Containers

Ada's standard library includes support for containers (such as vectors and sets). We present an introduction to them here. For a list of all containers available in Ada, see Appendix B.

### **16.2.1 Vectors**

In the following sections, we present a general overview of vectors, including instantiation, initialization, and operations on vector elements and vectors.

#### 16.2.1.1 Instantiation

Here's an example showing the instantiation and declaration of a vector V:

```
with Ada.Containers.Vectors;
procedure Show_Vector_Inst is

package Integer_Vectors is new Ada.Containers.Vectors
   (Index_Type => Natural,
        Element_Type => Integer);

V : Integer_Vectors.Vector;
begin
   null;
end Show_Vector_Inst;
```

Containers are based on generic packages, so we can't simply declare a vector as we would declare an array of a specific type:

```
A : array (1 .. 10) of Integer;
```

Instead, we first need to instantiate one of those packages. We with the container package (Ada. Containers. Vectors in this case) and instantiate it to create an instance of the generic package for the desired type. Only then can we declare the vector using the type from the instantiated package. This instantiation needs to be done for any container type from the standard library.

In the instantiation of Integer\_Vectors, we indicate that the vector contains elements of Integer type by specifying it as the Element\_Type. By setting Index\_Type to Natural, we specify that the allowed range includes all natural numbers. We could have used a more restrictive range if desired.

#### 16.2.1.2 Initialization

One way to initialize a vector is from a concatenation of elements. We use the & operator, as shown in the following example:

We specify use Integer\_Vectors, so we have direct access to the types and operations from the instantiated package. Also, the example introduces another operation on the vector: Length, which retrieves the number of elements in the vector. We can use the dot notation because Vector is a tagged type, allowing us to write either V. Length or Length (V).

### 16.2.1.3 Appending and prepending elements

You add elements to a vector using the Prepend and Append operations. As the names suggest, these operations add elements to the beginning or end of a vector, respectively. For example:

```
with Ada. Containers; use Ada. Containers;
with Ada.Containers.Vectors;
with Ada. Text IO; use Ada. Text IO;
procedure Show Vector Append is
   package Integer_Vectors is new Ada.Containers.Vectors
     (Index Type => Natural,
      Element Type => Integer);
   use Integer Vectors;
   V : Vector;
begin
   Put Line ("Appending some elements to the vector...");
   V.Append (20);
   V.Append (10);
   V.Append (0);
   V.Append (13);
   Put Line ("Finished appending.");
   Put Line ("Prepending some elements to the vector...");
   V. Prepend (30);
   V.Prepend (40);
   V. Prepend (100);
```

This example puts elements into the vector in the following sequence: (100, 40, 30, 20, 10, 0, 13).

The Reference Manual specifies that the worst-case complexity must be:

- O(log N) for the Append operation, and
- O(NlogN) for the Prepend operation.

#### 16.2.1.4 Accessing first and last elements

We access the first and last elements of a vector using the First\_Element and Last\_Element functions. For example:

```
with Ada. Containers; use Ada. Containers;
with Ada. Containers. Vectors:
with Ada. Text IO; use Ada. Text IO;
procedure Show Vector First Last Element is
  package Integer_Vectors is new Ada.Containers.Vectors
     (Index_Type => Natural,
     Element_Type => Integer);
  use Integer_Vectors;
  function Img (I : Integer) return String renames Integer'Image;
   function Img (I : Count_Type) return String renames Count_Type'Image;
  V : Vector := 20 & 10 & 0 & 13;
begin
  Put Line ("Vector has " & Img (V.Length) & " elements");
   -- Using V.First Element to retrieve first element
  Put_Line ("First element is " & Img (V.First_Element));
   -- Using V.Last Element to retrieve last element
  Put Line ("Last element is " & Img (V.Last Element));
end Show_Vector_First_Last_Element;
```

You can swap elements by calling the procedure Swap and retrieving a reference (a *cursor*) to the first and last elements of the vector by calling First and Last. A cursor allows us to iterate over a container and process individual elements from it.

With these operations, we're able to write code to swap the first and last elements of a vector:

```
with Ada.Containers; use Ada.Containers;
with Ada.Containers.Vectors;

with Ada.Text_IO; use Ada.Text_IO;

procedure Show_Vector_First_Last_Element is

package Integer_Vectors is new Ada.Containers.Vectors
    (Index_Type => Natural,
```

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```
Integer_Vectors;

function Img (I : Integer) return String renames Integer'Image;

V : Vector := 20 & 10 & 0 & 13;

begin
-- We use V.First and V.Last to retrieve cursor for first and
-- last elements.
-- We use V.Swap to swap elements.
V.Swap (V.First, V.Last);

Put_Line ("First element is now " & Img (V.First_Element));
Put_Line ("Last element is now " & Img (V.Last_Element));
end Show_Vector_First_Last_Element;
```

#### **16.2.1.5** Iterating

The easiest way to iterate over a container is to use a for E of Our\_Container loop. This gives us a reference (E) to the element at the current position. We can then use E directly. For example:

```
with Ada. Containers. Vectors;
with Ada.Text IO; use Ada.Text IO;
procedure Show Vector Iteration is
   package Integer_Vectors is new Ada.Containers.Vectors
     (Index_Type => Natural,
     Element Type => Integer);
  use Integer_Vectors;
  function Img (I : Integer) return String renames Integer'Image;
  V : Vector := 20 & 10 & 0 & 13;
begin
  Put Line ("Vector elements are: ");
   -- Using for ... of loop to iterate:
   for E of V loop
     Put Line ("- " & Img (E));
  end loop;
end Show Vector Iteration;
```

This code displays each element from the vector V.

Because we're given a reference, we can display not only the value of an element but also modify it. For example, we could easily write a loop to add one to each element of vector V:

```
for E of V loop
    E := E + 1;
end loop;
```

We can also use indices to access vector elements. The format is similar to a loop over array elements: we use a for I in <range> loop. The range is provided by V.First\_Index and V.

Last\_Index. We can access the current element by using it as an array index: V (I). For example:

```
with Ada. Containers. Vectors;
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Vector_Index_Iteration is
   package Integer_Vectors is new Ada.Containers.Vectors
     (Index Type => Natural,
      Element_Type => Integer);
  use Integer_Vectors;
  V : Vector := 20 & 10 & 0 & 13;
begin
  Put Line ("Vector elements are: ");
   -- Using indices in a "for I in ..." loop to iterate:
   for I in V.First_Index .. V.Last_Index loop
      -- Displaying current index I
     Put ("- ["
           & Extended_Index'Image (I)
           & "] ");
      Put (Integer'Image (V (I)));
      -- We could also use the V.Element (I) function to retrieve the
      -- element at the current index I
      New Line;
  end loop;
end Show_Vector_Index_Iteration;
```

Here, in addition to displaying the vector elements, we're also displaying each index, I, just like what we can do for array indices. Also, we can access the element by using either the short form V (I) or the longer form V.Element (I) but not V.I.

As mentioned in the previous section, you can use cursors to iterate over containers. For this, use the function Iterate, which retrieves a cursor for each position in the vector. The corresponding loop has the format for C in V.Iterate loop. Like the previous example using indices, you can again access the current element by using the cursor as an array index: V (C). For example:

```
with Ada.Containers.Vectors;
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Vector_Cursor_Iteration is

package Integer_Vectors is new Ada.Containers.Vectors
   (Index_Type => Natural,
        Element_Type => Integer);

use Integer_Vectors;

V : Vector := 20 & 10 & 0 & 13;
begin
   Put_Line ("Vector elements are: ");

(continues on next page)
```

```
-- Use a cursor to iterate in a loop:
   for C in V.Iterate loop
     -- Using To_Index function to retrieve index
      -- for the cursor position
     Put ("- ["
           & Extended_Index'Image (To_Index (C))
           & "] ");
     Put (Integer'Image (V (C)));
      -- We could use Element (C) to retrieve the vector
         element for the cursor position
     New_Line;
  end loop;
   -- Alternatively, we could iterate with a while-loop:
      declare
         C : Cursor := V.First;
   -- begin
         while C /= No_Element loop
   - -
   - -
             some processing here...
   - -
   - -
             C := Next(C);
          end loop;
   - -
   -- end:
end Show Vector Cursor Iteration;
```

Instead of accessing an element in the loop using V (C), we could also have used the longer form Element (C). In this example, we're using the function To\_Index to retrieve the index corresponding to the current cursor.

As shown in the comments after the loop, we could also use a while ... loop to iterate over the vector. In this case, we would start with a cursor for the first element (retrieved by calling V. First) and then call Next (C) to retrieve a cursor for subsequent elements. Next (C) returns No Element when the cursor reaches the end of the vector.

You can directly modify the elements using a reference. This is what it looks like when using both indices and cursors:

```
-- Modify vector elements using index
for I in V.First_Index .. V.Last_Index loop
    V (I) := V (I) + 1;
end loop;

-- Modify vector elements using cursor
for C in V.Iterate loop
    V (C) := V (C) + 1;
end loop;
```

The Reference Manual requires that the worst-case complexity for accessing an element be O(log N).

Another way of modifing elements of a vector is using a *process procedure*, which takes an individual element and does some processing on it. You can call <code>Update\_Element</code> and pass both a cursor and an access to the process procedure. For example:

```
with Ada. Containers. Vectors;
with Ada.Text IO; use Ada.Text IO;
procedure Show Vector Update is
  package Integer_Vectors is new Ada.Containers.Vectors
     (Index Type => Natural,
     Element Type => Integer);
  use Integer Vectors;
  procedure Add One (I : in out Integer) is
  begin
     I := I + 1;
  end Add One;
  V : Vector := 20 & 10 & 12;
begin
   -- Use V. Update Element to process elements
  for C in V.Iterate loop
     V.Update Element (C, Add One'Access);
  end loop;
end Show_Vector_Update;
```

#### 16.2.1.6 Finding and changing elements

You can locate a specific element in a vector by retrieving its index. Find\_Index retrieves the index of the first element matching the value you're looking for. Alternatively, you can use Find to retrieve a cursor referencing that element. For example:

```
with Ada. Containers. Vectors;
with Ada.Text IO; use Ada.Text IO;
procedure Show_Find_Vector_Element is
  package Integer_Vectors is new Ada.Containers.Vectors
     (Index_Type => Natural,
     Element_Type => Integer);
  use Integer_Vectors;
  V : Vector := 20 & 10 & 0 & 13;
  Idx : Extended Index;
  C : Cursor;
begin
   -- Using Find_Index to retrieve index of element with value 10
  Idx := V.Find_Index (10);
  Put_Line ("Index of element with value 10 is "
             & Extended_Index'Image (Idx));
   -- Using Find to retrieve cursor for element with value 13
  C := V.Find (13);
  Idx := To Index (C);
  Put Line ("Index of element with value 13 is "
```

(continues on next page)

```
& Extended_Index'Image (Idx));
end Show_Find_Vector_Element;
```

As we saw in the previous section, we can directly access vector elements by using either an index or cursor. However, an exception is raised if we try to access an element with an invalid index or cursor, so we must check whether the index or cursor is valid before using it to access an element. In our example, Find\_Index or Find might not have found the element in the vector. We check for this possibility by comparing the index to No Index or the cursor to No Element. For example:

```
-- Modify vector element using index
if Idx /= No_Index then
   V (Idx) := 11;
end if;

-- Modify vector element using cursor
if C /= No_Element then
   V (C) := 14;
end if;
```

Instead of writing V (C) := 14, we could use the longer form V. Replace Element (C, 14).

#### 16.2.1.7 Inserting elements

In the previous sections, we've seen examples of how to add elements to a vector:

- using the concatenation operator (&) at the vector declaration, or
- calling the Prepend and Append procedures.

You may want to insert an element at a specific position, e.g. before a certain element in the vector. You do this by calling Insert. For example:

```
with Ada. Containers; use Ada. Containers;
with Ada. Containers. Vectors;
with Ada. Text IO; use Ada. Text IO;
procedure Show Vector Insert is
   package Integer_Vectors is new Ada.Containers.Vectors
     (Index Type => Natural,
      Element Type => Integer);
   use Integer Vectors;
   procedure Show Elements (V : Vector) is
   begin
      New Line:
      Put Line ("Vector has "
                & Count Type'Image (V.Length) & " elements");
      if not V.Is Empty then
         Put_Line ("Vector elements are: ");
         for E of V loop
            Put_Line ("- " & Integer'Image (E));
         end loop:
      end if;
   end Show Elements;
   V : Vector := 20 & 10 & 12;
```

```
C : Cursor;
begin
    Show_Elements (V);

New_Line;
Put_Line ("Adding element with value 9 (before 10)...");

--
-- Using V.Insert to insert element into vector
--
C := V.Find (10);
if C /= No_Element then
    V.Insert (C, 9);
end if;
Show_Elements (V);
end Show_Vector_Insert;
```

In this example, we're looking for an element with the value of 10. If we find it, we insert an element with the value of 9 before it.

#### 16.2.1.8 Removing elements

You can remove elements from a vector by passing either a valid index or cursor to the Delete procedure. If we combine this with the functions Find\_Index and Find from the previous section, we can write a program that searches for a specific element and deletes it, if found:

```
with Ada. Containers. Vectors;
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Remove_Vector_Element is
  package Integer_Vectors is new Ada.Containers.Vectors
     (Index_Type => Natural,
      Element Type => Integer);
  use Integer_Vectors;
  V : Vector := 20 & 10 & 0 & 13 & 10 & 13;
  Idx : Extended_Index;
  C
      : Cursor;
begin
   -- Use Find_Index to retrieve index of element with value 10
  Idx := V.Find_Index (10);
   -- Checking whether index is valid
  if Idx /= No Index then
      -- Removing element using V.Delete
     V.Delete (Idx);
  end if;
   -- Use Find to retrieve cursor for element with value 13
  C := V.Find (13);
   -- Check whether index is valid
  if C /= No_Element then
      -- Remove element using V.Delete
     V.Delete (C);
```

(continues on next page)

```
end if;
end Show_Remove_Vector_Element;
```

We can extend this approach to delete all elements matching a certain value. We just need to keep searching for the element in a loop until we get an invalid index or cursor. For example:

```
with Ada. Containers: use Ada. Containers:
with Ada. Containers. Vectors;
with Ada.Text IO; use Ada.Text IO;
procedure Show_Remove_Vector_Elements is
  package Integer_Vectors is new Ada.Containers.Vectors
     (Index_Type => Natural,
     Element_Type => Integer);
  use Integer Vectors;
  procedure Show Elements (V : Vector) is
  begin
      New Line;
      Put Line ("Vector has " & Count Type'Image (V.Length) & " elements");
      if not V.Is_Empty then
         Put_Line ("Vector elements are: ");
         for E of V loop
            Put_Line ("- " & Integer'Image (E));
         end loop;
      end if;
  end Show Elements;
  V : Vector := 20 & 10 & 0 & 13 & 10 & 14 & 13;
begin
  Show_Elements (V);
   -- Remove elements using an index
  declare
     E : constant Integer := 10;
     I : Extended Index;
  begin
      New Line;
      Put Line ("Removing all elements with value of "
                & Integer'Image (E) & "...");
      loop
         I := V.Find Index (E);
         exit when I = No Index;
         V.Delete (I);
      end loop;
  end;
   -- Remove elements using a cursor
  declare
     E : constant Integer := 13;
      C : Cursor;
  begin
```

In this example, we remove all elements with the value 10 from the vector by retrieving their index. Likewise, we remove all elements with the value 13 by retrieving their cursor.

#### 16.2.1.9 Other Operations

We've seen some operations on vector elements. Here, we'll see operations on the vector as a whole. The most prominent is the concatenation of multiple vectors, but we'll also see operations on vectors, such as sorting and sorted merging operations, that view the vector as a sequence of elements and operate on the vector considering the element's relations to each other.

We do vector concatenation using the & operator on vectors. Let's consider two vectors V1 and V2. We can concatenate them by doing V := V1 & V2. V contains the resulting vector.

The generic package Generic\_Sorting is a child package of Ada.Containers.Vectors. It contains sorting and merging operations. Because it's a generic package, you can't use it directly, but have to instantiate it. In order to use these operations on a vector of integer values (Integer\_Vectors, in our example), you need to instantiate it directly as a child of Integer\_Vectors. The next example makes it clear how to do this.

After instantiating Generic\_Sorting, we make all the operations available to us with the use statement. We can then call Sort to sort the vector and Merge to merge one vector into another.

The following example presents code that manipulates three vectors (V1, V2, V3) using the concatenation, sorting and merging operations:

```
with Ada. Containers; use Ada. Containers;
with Ada. Containers. Vectors;
with Ada.Text IO; use Ada.Text IO;
procedure Show Vector Ops is
   package Integer_Vectors is new Ada.Containers.Vectors
     (Index Type => Natural,
      Element Type => Integer);
   package Integer Vectors Sorting is new Integer Vectors. Generic Sorting;
   use Integer Vectors;
   use Integer Vectors Sorting;
   procedure Show Elements (V : Vector) is
   begin
      New_Line;
      Put Line ("Vector has " & Count Type'Image (V.Length) & " elements");
      if not V.Is Empty then
                                                                     (continues on next page)
```

```
Put_Line ("Vector elements are: ");
         for E of V loop
            Put Line ("- " & Integer'Image (E));
      end if;
   end Show_Elements;
   V, V1, V2, V3 : Vector;
begin
   V1 := 10 & 12 & 18;
   V2 := 11 & 13 & 19;
   V3 := 15 & 19;
   New_Line;
   Put_Line ("---- V1 ----");
   Show_Elements (V1);
   New_Line;
   Put Line ("---- V2 ----");
   Show_Elements (V2);
   New Line;
   Put Line ("---- V3 ----");
   Show Elements (V3);
   New Line;
   Put_Line ("Concatenating V1, V2 and V3 into V:");
   V := V1 & V2 & V3;
   Show Elements (V);
   New_Line;
   Put Line ("Sorting V:");
   Sort (V);
   Show Elements (V);
   New Line;
   Put_Line ("Merging V2 into V1:");
   Merge (V1, V2);
   Show Elements (V1);
end Show Vector Ops;
```

The Reference Manual requires that the worst-case complexity of a call to Sort be  $O(N^2)$  and the average complexity be better than  $O(N^2)$ .

### 16.2.2 Sets

Sets are another class of containers. While vectors allow duplicated elements to be inserted, sets ensure that no duplicated elements exist.

In the following sections, we'll see operations you can perform on sets. However, since many of the operations on vectors are similar to the ones used for sets, we'll cover them more quickly here. Please refer back to the section on vectors for a more detailed discussion.

#### 16.2.2.1 Initialization and iteration

To initialize a set, you can call the Insert procedure. However, if you do, you need to ensure no duplicate elements are being inserted: if you try to insert a duplicate, you'll get an exception. If you have less control over the elements to be inserted so that there may be duplicates, you can use another option instead:

- a version of Insert that returns a Boolean value indicating whether the insertion was successful;
- the Include procedure, which silently ignores any attempt to insert a duplicated element.

To iterate over a set, you can use a for E of S loop, as you saw for vectors. This gives you a reference to each element in the set.

Let's see an example:

```
with Ada.Containers; use Ada.Containers;
with Ada.Containers.Ordered_Sets;
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Set_Init is
  package Integer_Sets is new Ada.Containers.Ordered_Sets
     (Element_Type => Integer);
  use Integer_Sets;
  S : Set;
   -- Same as: S : Integer_Sets.Set;
  C : Cursor;
  Ins : Boolean;
begin
  S.Insert (20);
  S.Insert (10);
  S.Insert (0);
  S.Insert (13);
  -- Calling S.Insert(0) now would raise Constraint Error
  -- because this element is already in the set.
   -- We instead call a version of Insert that doesn't raise an
   -- exception but instead returns a Boolean indicating the status
  S.Insert (0, C, Ins);
  if not Ins then
     Put_Line ("Inserting 0 into set was not successful");
  end if;
   -- We can also call S.Include instead
   -- If the element is already present, the set remains unchanged
  S.Include (0);
  S.Include (13);
  S.Include (14);
  Put_Line ("Set has " & Count_Type'Image (S.Length) & " elements");
   -- Iterate over set using for .. of loop
  Put Line ("Elements:");
   for E of S loop
       Put_Line ("- " & Integer'Image (E));
```

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```
end loop;
end Show_Set_Init;
```

#### 16.2.2.2 Operations on elements

In this section, we briefly explore the following operations on sets:

- Delete and Exclude to remove elements;
- Contains and Find to verify the existence of elements.

To delete elements, you call the procedure Delete. However, analogously to the Insert procedure above, Delete raises an exception if the element to be deleted isn't present in the set. If you want to permit the case where an element might not exist, you can call Exclude, which silently ignores any attempt to delete a non-existent element.

Contains returns a Boolean value indicating whether a value is contained in the set. Find also looks for an element in a set, but returns a cursor to the element or No\_Element if the element doesn't exist. You can use either function to search for elements in a set.

Let's look at an example that makes use of these operations:

```
with Ada.Containers; use Ada.Containers;
with Ada.Containers.Ordered_Sets;
with Ada.Text_IO; use Ada.Text_IO;
procedure Show Set Element Ops is
  package Integer Sets is new Ada.Containers.Ordered Sets
     (Element Type => Integer);
  use Integer_Sets;
  procedure Show_Elements (S : Set) is
  begin
      New_Line;
      Put_Line ("Set has " & Count_Type'Image (S.Length) & " elements");
      Put_Line ("Elements:");
      for E of S loop
         Put Line ("- " & Integer'Image (E));
     end loop;
  end Show_Elements;
  S : Set;
begin
  S.Insert (20);
  S.Insert (10);
  S.Insert (0);
  S.Insert (13);
  S.Delete (13);
   -- Calling S.Delete (13) again raises Constraint_Error
   -- because the element is no longer present
   -- in the set, so it can't be deleted.
  -- We can call V.Exclude instead:
  S.Exclude (13);
  if S.Contains (20) then
```

```
Put_Line ("Found element 20 in set");
end if;

-- Alternatively, we could use S.Find instead of S.Contains
if S.Find (0) /= No_Element then
    Put_Line ("Found element 0 in set");
end if;

Show_Elements (S);
end Show_Set_Element_Ops;
```

In addition to ordered sets used in the examples above, the standard library also offers hashed sets. The Reference Manual requires the following average complexity of each operation:

Operations	Ordered_Sets	Hashed_Sets
<ul><li>Insert</li><li>Include</li><li>Replace</li><li>Delete</li><li>Exclude</li><li>Find</li></ul>	$O((logN)^2)$ or better	O(logN)
Subprogram using cursor	O(1)	O(1)

### 16.2.2.3 Other Operations

The previous sections mostly dealt with operations on individual elements of a set. But Ada also provides typical set operations: union, intersection, difference and symmetric difference. In contrast to some vector operations we've seen before (e.g. Merge), here you can use built-in operators, such as -. The following table lists the operations and its associated operator:

Set Operation	Operator
Union	and
Intersection	or
Difference	-
Symmetric difference	xor

The following example makes use of these operators:

```
with Ada.Containers; use Ada.Containers;
with Ada.Containers.Ordered_Sets;

with Ada.Text_IO; use Ada.Text_IO;

procedure Show_Set_Ops is

package Integer_Sets is new Ada.Containers.Ordered_Sets
    (Element_Type => Integer);

use Integer_Sets;

procedure Show_Elements (S : Set) is
begin
    Put_Line ("Elements:");
    for E of S loop
```

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```
Put_Line ("- " & Integer'Image (E));
      end loop;
  end Show_Elements;
  procedure Show_Op (5
                           : Set;
                     Op_Name : String) is
  begin
     New_Line;
     Put_Line (Op_Name & "(set #1, set #2) has "
                & Count_Type'Image (S.Length) & " elements");
  end Show_Op;
  S1, S2, S3 : Set;
begin
  S1.Insert (0);
  S1.Insert (10);
  S1.Insert (13);
  S2.Insert (0);
  S2.Insert (10);
  S2.Insert (14);
  S3.Insert (0);
  S3.Insert (10);
  New Line;
  Put_Line ("---- Set #1 ----");
  Show_Elements (S1);
  New_Line;
  Put Line ("---- Set #2 ----");
  Show_Elements (S2);
  New Line;
  Put_Line ("---- Set #3 ----");
  Show Elements (S3);
  New_Line;
  if S3.Is_Subset (S1) then
     Put_Line ("S3 is a subset of S1");
     Put Line ("S3 is not a subset of S1");
  end if;
  S3 := S1 and S2;
  Show Op (S3, "Union");
  Show Elements (S3);
  S3 := S1 or S2;
  Show Op (S3, "Intersection");
  Show_Elements (S3);
  S3 := S1 - S2;
  Show_Op (S3, "Difference");
  Show_Elements (S3);
  S3 := S1 xor S2;
  Show Op (S3, "Symmetric difference");
  Show_Elements (S3);
end Show_Set_Ops;
```

## 16.2.3 Indefinite maps

The previous sections presented containers for elements of definite types. Although most examples in those sections presented Integer types as element type of the containers, containers can also be used with indefinite types, an example of which is the String type. However, indefinite types require a different kind of containers designed specially for them.

We'll also be exploring a different class of containers: maps. They associate a key with a specific value. An example of a map is the one-to-one association between a person and their age. If we consider a person's name to be the key, the value is the person's age.

#### **16.2.3.1 Hashed maps**

Hashed maps are maps that make use of a hash as a key. The hash itself is calculated by a function you provide.

### In other languages

Hashed maps are similar to dictionaries in Python and hashes in Perl. One of the main differences is that these scripting languages allow using different types for the values contained in a single map, while in Ada, both the type of key and value are specified in the package instantiation and remains constant for that specific map. You can't have a map where two elements are of different types or two keys are of different types. If you want to use multiple types, you must create a different map for each and use only one type in each map.

When instantiating a hashed map from Ada.Containers.Indefinite\_Hashed\_Maps, we specify following elements:

- Key Type: type of the key
- Element Type: type of the element
- Hash: hash function for the Key Type
- Equivalent\_Keys: an equality operator (e.g. =) that indicates whether two keys are to be considered equal.
  - If the type specified in Key\_Type has a standard operator, you can use it, which you do
    by specifing using that operator as the value of Equivalent\_Keys.

In the next example, we'll use a string as a key type. We'll use the Hash function provided by the standard library for strings (in the Ada.Strings package) and the standard equality operator.

You add elements to a hashed map by calling Insert. If an element is already contained in a map M, you can access it directly by using its key. For example, you can change the value of an element by calling M ("My\_Key") := 10. If the key is not found, an exception is raised. To verify if a key is available, use the function Contains (as we've seen above in the section on sets).

Let's see an example:

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```
=> Ada.Strings.Hash,
        Equivalent Keys => "=");
  use Integer_Hashed_Maps;
  M : Map;
      Same as: M : Integer_Hashed_Maps.Map;
begin
  M.Include ("Alice", 24);
  M.Include ("John", 40);
  M.Include ("Bob",
                      28);
  if M.Contains ("Alice") then
      Put_Line ("Alice's age is "
                & Integer'Image (M ("Alice")));
  end if;
   -- Update Alice's age
   -- Key must already exist in M.
   -- Otherwise an exception is raised.
  M ("Alice") := 25;
  New Line; Put Line ("Name & Age:");
   for C in M.Iterate loop
      Put_Line (Key (C) & ": " & Integer'Image (M (C)));
  end loop;
end Show_Hashed_Map;
```

#### 16.2.3.2 Ordered maps

Ordered maps share many features with hashed maps. The main differences are:

- A hash function isn't needed. Instead, you must provide an ordering function (< operator), which the ordered map will use to order elements and allow fast access, O(logn), using a binary search.
  - If the type specified in Key\_Type has a standard < operator, you can use it in a similar way as we did for Equivalent\_Keys above for hashed maps.

Let's see an example:

You can see a great similarity between the examples above and from the previous section. In fact, since both kinds of maps share many operations, we didn't need to make extensive modifications when we changed our example to use ordered maps instead of hashed maps. The main difference is seen when we run the examples: the output of a hashed map is usually unordered, but the output of a ordered map is always ordered, as implied by its name.

#### 16.2.3.3 Complexity

Hashed maps are generally the fastest data structure available to you in Ada if you need to associate heterogeneous keys to values and search for them quickly. In most cases, they are slightly faster than ordered maps. So if you don't need ordering, use hashed maps.

The Reference Manual requires the following average complexity of operations:

Operations	Ordered_Maps	Hashed_Maps
<ul><li>Insert</li><li>Include</li><li>Replace</li><li>Delete</li><li>Exclude</li><li>Find</li></ul>	$O((logN)^2)$ or better	O(logN)
Subprogram using cursor	O(1)	O(1)

### 16.3 Dates & Times

## 16.3.1 Date and time handling

The standard library supports representing and handling dates and times. This is part of the Ada. Calendar package. Let's look at a simple example:

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```
begin
  Put_Line ("Current time: " & Image (Now));
end Display_Current_Time;
```

This example displays the current date and time, which is retrieved by a call to the Clock function. We call the function Image from the Ada. Calendar. Formatting package to get a String for the current date and time. We could instead retrieve each component using the Split function. For example:

```
with Ada.Calendar;
                             use Ada. Calendar;
with Ada.Text IO;
                             use Ada.Text_I0;
procedure Display_Current_Year is
              : Time := Clock:
  Now Year
              : Year Number;
  Now Month : Month Number;
  Now Day : Day Number;
  Now Seconds : Day Duration;
begin
  Split (Now,
         Now_Year,
          Now_Month,
         Now_Day,
          Now_Seconds);
  Put_Line ("Current year is: " & Year_Number'Image (Now Year));
  Put_Line ("Current month is: " & Month_Number'Image (Now_Month));
  Put Line ("Current day
                          is: " & Day Number'Image (Now Day));
end Display_Current_Year;
```

Here, we're retrieving each element and displaying it separately.

#### 16.3.1.1 Delaying using date

You can delay an application so that it restarts at a specific date and time. We saw something similar in the chapter on tasking. You do this using a delay until statement. For example:

```
with Ada. Calendar;
                              use Ada. Calendar;
with Ada. Calendar. Formatting; use Ada. Calendar. Formatting;
with Ada.Calendar.Time Zones; use Ada.Calendar.Time Zones;
with Ada.Text_IO;
                             use Ada.Text IO;
procedure Display_Delay_Next_Specific_Time is
  TZ : Time Offset := UTC Time Offset;
  Next : Time := Ada.Calendar.Formatting.Time Of
     (Year
                 => 2018.
     Month
                 => 5,
     Day
                 => 1,
     Hour
                 => 15,
     Minute
                 => 0,
                 => 0,
     Second
     Sub Second \Rightarrow 0.0,
     Leap_Second => False,
     Time Zone => TZ);
   -- Next = 2018-05-01 15:00:00.00 (local time-zone)
begin
  Put Line ("Let's wait until...");
```

```
Put_Line (Image (Next, True, TZ));

delay until Next;

Put_Line ("Enough waiting!");
end Display_Delay_Next_Specific_Time;
```

In this example, we specify the date and time by initializing Next using a call to Time\_Of, a function taking the various components of a date (year, month, etc) and returning an element of the Time type. Because the date specified is in the past, the delay until statement won't produce any noticeable effect. However, if we passed a date in the future, the program would wait until that specific date and time arrived.

Here we're converting the time to the local timezone. If we don't specify a timezone, *Coordinated Universal Time* (abbreviated to UTC) is used by default. By retrieving the time offset to UTC with a call to UTC\_Time\_Offset from the Ada.Calendar.Time\_Zones package, we can initialize TZ and use it in the call to Time\_Of. This is all we need do to make the information provided to Time\_Of relative to the local time zone.

We could achieve a similar result by initializing Next with a String. We can do this with a call to Value from the Ada. Calendar. Formatting package. This is the modified code:

```
with Ada. Calendar;
                              use Ada. Calendar;
with Ada.Calendar.Formatting; use Ada.Calendar.Formatting;
with Ada. Calendar. Time Zones; use Ada. Calendar. Time Zones;
with Ada.Text_IO;
                              use Ada.Text IO;
procedure Display Delay Next Specific Time is
  TZ : Time Offset := UTC Time Offset;
  Next : Time
                      := Ada.Calendar.Formatting.Value
     ("2018-05-01 15:00:00.00", TZ);
   -- Next = 2018-05-01 15:00:00.00 (local time-zone)
begin
  Put Line ("Let's wait until...");
  Put_Line (Image (Next, True, TZ));
  delay until Next;
  Put Line ("Enough waiting!");
end Display Delay Next Specific Time;
```

In this example, we're again using TZ in the call to Value to adjust the input time to the current time zone.

In the examples above, we were delaying to a specific date and time. Just like we saw in the tasking chapter, we could instead specify the delay relative to the current time. For example, we could delay by 5 seconds, using the current time:

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```
Put_Line ("Enough waiting!");
end Display_Delay_Next;
```

Here, we're specifying a duration of 5 seconds in D, adding it to the current time from Now, and storing the sum in Next. We then use it in the delay until statement.

#### 16.3.2 Real-time

In addition to Ada.Calendar, the standard library also supports time operations for real-time applications. These are included in the Ada.Real\_Time package. This package also include a Time type. However, in the Ada.Real\_Time package, the Time type is used to represent an absolute clock and handle a time span. This contrasts with the Ada.Calendar, which uses the Time type to represent dates and times.

In the previous section, we used the Time type from the Ada.Calendar and the delay until statement to delay an application by 5 seconds. We could have used the Ada.Real\_Time package instead. Let's modify that example:

The main difference is that D is now a variable of type Time\_Span, defined in the Ada.Real\_Time package. We call the function Seconds to initialize D, but could have gotten a finer granularity by calling Nanoseconds instead. Also, we need to first convert D to the Duration type using To\_Duration before we can display it.

## 16.3.2.1 Benchmarking

One interesting application using the Ada.Real\_Time package is benchmarking. We've used that package before in a previous section when discussing tasking. Let's look at an example of benchmarking:

```
with Ada.Text_IO;    use Ada.Text_IO;
with Ada.Real_Time; use Ada.Real_Time;

procedure Display_Benchmarking is

    procedure Computational_Intensive_App is
    begin
        delay 0.5;
end Computational_Intensive_App;

Start_Time, Stop_Time : Time;
Elapsed_Time : Time_Span;

begin
    Start_Time := Clock;
```

This example defines a dummy Computational\_Intensive\_App implemented using a simple delay statement. We initialize Start\_Time and Stop\_Time from the then-current clock and calculate the elapsed time. By running this program, we see that the time is roughly 5 seconds, which is expected due to the delay statement.

A similar application is benchmarking of CPU time. We can implement this using the Execution\_Time package. Let's modify the previous example to measure CPU time:

```
with Ada. Text IO;
                         use Ada.Text_I0;
with Ada.Real Time;
                         use Ada.Real Time;
with Ada. Execution_Time; use Ada. Execution_Time;
procedure Display Benchmarking CPU Time is
  procedure Computational Intensive App is
  begin
      delay 0.5;
  end Computational Intensive App;
  Start_Time, Stop_Time : CPU_Time;
  Elapsed Time
                    : Time Span;
begin
  Start_Time := Clock;
  Computational Intensive App;
  Stop Time
              := Clock;
  Elapsed_Time := Stop_Time - Start_Time;
  Put Line ("CPU time: "
             & Duration'Image (To Duration (Elapsed Time))
             & " seconds");
end Display Benchmarking CPU Time;
```

In this example, Start\_Time and Stop\_Time are of type CPU\_Time instead of Time. However, we still call the Clock function to initialize both variables and calculate the elapsed time in the same way as before. By running this program, we see that the CPU time is significantly lower than the 5 seconds we've seen before. This is because the delay statement doesn't require much CPU time. The results will be different if we change the implementation of Computational\_Intensive\_App to use a mathematical functions in a long loop. For example:

(continues on next page)

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```
procedure Computational_Intensive_App is
      package Funcs is new Ada. Numerics. Generic Elementary Functions
        (Float Type => Long Long Float);
      use Funcs;
     X : Long_Long_Float;
  begin
      for I in 0 .. 1_000_000 loop
         X := Tan (Arctan
                   (Tan (Arctan
                      (Tan (Arctan
                         (Tan (Arctan
                            (Tan (Arctan
                               (Tan (Arctan
                                   (0.577)))))))))))));
      end loop;
  end Computational_Intensive_App;
  procedure Benchm Elapsed Time is
      Start_Time, Stop_Time : Time;
                            : Time_Span;
      Elapsed Time
      Start Time := Clock;
      Computational Intensive App;
     Stop_Time
                   := Clock;
     Elapsed Time := Stop Time - Start Time;
      Put Line ("Elapsed time: "
                & Duration'Image (To_Duration (Elapsed_Time))
                & " seconds");
  end Benchm Elapsed Time;
  procedure Benchm CPU Time is
      Start_Time, Stop_Time : CPU_Time;
     Elapsed Time
                            : Time Span;
  begin
     Start_Time := Clock;
      Computational_Intensive_App;
      Stop Time
                  := Clock;
     Elapsed_Time := Stop_Time - Start_Time;
      Put Line ("CPU time: "
                & Duration'Image (To_Duration (Elapsed_Time))
                & " seconds");
  end Benchm_CPU_Time;
begin
   Benchm Elapsed Time;
  Benchm CPU Time;
end Display Benchmarking Math;
```

Now that our dummy Computational\_Intensive\_App involves mathematical operations requiring significant CPU time, the measured elapsed and CPU time are much closer to each other than before.

## 16.4 Strings

We've used strings in many previous examples. In this section, we'll cover them in more detail.

## **16.4.1 String operations**

Operations on standard strings are available in the Ada.Strings.Fixed package. As mentioned previously, standard strings are arrays of elements of Character type with a fixed-length. That's why this child package is called Fixed.

One of the simplest operations provided is counting the number of substrings available in a string (Count) and finding their corresponding indices (Index). Let's look at an example:

```
with Ada.Strings.Fixed; use Ada.Strings.Fixed;
with Ada. Text IO;
                        use Ada.Text IO;
procedure Show Find Substring is
      : String := "Hello" & 3 * " World";
      : constant String := "World":
   Idx : Natural;
   Cnt : Natural;
begin
   Cnt := Ada.Strings.Fixed.Count
     (Source => S,
      Pattern => P);
   Put Line ("String: " & S);
   Put Line ("Count for '" & P & "': " & Natural'Image (Cnt));
   Idx := 0:
   for I in 1 .. Cnt loop
      Idx := Index
        (Source => S,
         Pattern => P,
         From \Rightarrow Idx + 1);
      Put Line ("Found instance of '" & P & "' at position: "
                & Natural'Image (Idx));
   end loop;
end Show Find Substring;
```

We initialize the string S using a multiplication. Writing "Hello" & 3 \* " World" creates the string Hello World World World. We then call the function Count' to get the number of instances of the word World in S. Next we call the function Index in a loop to find the index of each instance of World in S.

That example looked for instances of a specific substring. In the next example, we retrieve all the words in the string. We do this using Find Token and specifying whitespaces as separators. For example:

```
with Ada.Strings; use Ada.Strings;
with Ada.Strings.Fixed; use Ada.Strings.Fixed;
with Ada.Strings.Maps; use Ada.Strings.Maps;
                     use Ada.Text IO;
with Ada.Text IO;
procedure Show Find Words is
     : String := "Hello" & 3 * " World";
```

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```
: Positive;
     : Natural;
     : Natural := 1;
  Whitespace : constant Character_Set :=
    To_Set (' ');
begin
  Put_Line ("String: " & S);
  Put_Line ("String length: " & Integer'Image (S'Length));
  while I in S'Range loop
      Find_Token
        (Source => S,
                => Whitespace,
         Set
         From
                => I,
                => Outside,
        Test
         First => F,
         Last
                => L);
      exit when L = 0;
      Put_Line ("Found word instance at position "
               & Natural'Image (F)
               & ": '" & S (F .. L) & "'");
          & "-" & F'Img & "-" & L'Img
     I := L + 1;
  end loop;
end Show Find Words;
```

We pass a set of characters to be used as delimitators to the procedure Find\_Token. This set is a member of the Character\_Set type from the Ada.Strings.Maps package. We call the To\_Set function (from the same package) to initialize the set to Whitespace and then call Find\_Token to loop over each valid index and find the starting index of each word. We pass Outside to the Test parameter of the Find\_Token procedure to indicate that we're looking for indices that are outside the Whitespace set, i.e. actual words. The First and Last parameters of Find\_Token are output parameters that indicate the valid range of the substring. We use this information to display the string (S (F .. L)).

The operations we've looked at so far read strings, but don't modify them. We next discuss operations that change the content of strings:

Operation	Description
Insert	Insert substring in a string
Overwrite	Overwrite a string with a substring
Delete	Delete a substring
Trim	Remove whitespaces from a string

All these operations are available both as functions or procedures. Functions create a new string but procedures perform the operations in place. The procedure will raise an exception if the constraints of the string are not satisfied. For example, if we have a string S containing 10 characters, inserting a string with two characters (e.g. "!!") into it produces a string containing 12 characters. Since it has a fixed length, we can't increase its size. One possible solution in this case is to specify that truncation should be applied while inserting the substring. This keeps the length of S fixed. Let's see an example that makes use of both function and procedure versions of Insert, Overwrite, and Delete:

```
with Ada.Text_IO;
                        use Ada.Text_IO;
procedure Show Adapted Strings is
      : String := "Hello World";
      : constant String := "World";
     : constant String := "Beautiful";
   procedure Display_Adapted_String
     (Source : String;
      Before : Positive;
      New_Item : String;
      Pattern : String)
   is
      S_Ins_In : String := Source;
      S_Ovr_In : String := Source;
      S_Del_In : String := Source;
      S Ins : String := Insert (Source, Before, New Item & " ");
      S_Ovr : String := Overwrite (Source, Before, New_Item);
      S Del : String := Trim (Delete (Source,
                                       Before + Pattern'Length - 1),
                               Ada.Strings.Right);
   begin
      Insert (S Ins In,
                           Before, New Item, Right);
      Overwrite (S_Ovr_In, Before, New_Item, Right);
                           Before, Before + Pattern'Length - 1);
      Delete (S_Del_In,
      Put_Line ("Original: '" & Source & "'");
      Put_Line ("Insert: '" & S_Ins & "'");
      Put_Line ("Overwrite: '" & S_Ovr & "'");
Put_Line ("Delete: '" & S_Del & "'");
      Put Line ("Insert
                            (in-place): '" & S Ins In & "'");
      Put Line ("Overwrite (in-place): '" & S Ovr In & "'");
                            (in-place): '" & S_Del_In & "'");
      Put Line ("Delete
   end Display Adapted String;
   Idx : Natural;
begin
   Idx := Index
     (Source => S,
      Pattern => P);
   if Idx > 0 then
      Display Adapted String (S, Idx, N, P);
   end if;
end Show Adapted Strings;
```

In this example, we look for the index of the substring World and perform operations on this substring within the outer string. The procedure <code>Display\_Adapted\_String</code> uses both versions of the operations. For the procedural version of <code>Insert</code> and <code>Overwrite</code>, we apply truncation to the right side of the string (Right). For the <code>Delete</code> procedure, we specify the range of the substring, which is replaced by whitespaces. For the function version of <code>Delete</code>, we also call <code>Trim</code> which trims the trailing whitespace.

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## 16.4.2 Bounded and unbounded strings

Using fixed-length strings is usually good enough for strings that are initialized when they are declared. However, as seen in the previous section, procedural operations on strings cause difficulties when done on fixed-length strings because fixed-length strings are arrays of characters. The following example shows how cumbersome the initialization of fixed-length strings can be when it's not performed in the declaration:

```
with Ada.Text IO;
                          use Ada.Text IO;
procedure Show Char Array is
  S : String (1 .. 15);
   -- Strings are arrays of Character
begin
  S := "Hello
   -- Alternatively:
   -- #1:
          S (1 .. 5) := "Hello";
   - -
          S (6 .. S'Last) := (others => ' ');
   - -
   - -
   -- #2:
          S := ('H', 'e', 'l', 'l', 'o', others => ' ');
  Put Line ("String: " & S);
  Put Line ("String Length: " & Integer'Image (S'Length));
end Show Char Array;
```

In this case, we can't simply write S := "Hello" because the resulting array of characters for the Hello constant has a different length than the S string. Therefore, we need to include trailing whitespaces to match the length of S. As shown in the example, we could use an exact range for the initialization (S(1...5)) or use an explicit array of individual characters.

When strings are initialized or manipulated at run-time, it's usually better to use bounded or unbounded strings. An important feature of these types is that they aren't arrays, so the difficulties presented above don't apply. Let's start with bounded strings.

#### 16.4.2.1 Bounded strings

Bounded strings are defined in the Ada.Strings.Bounded.Generic\_Bounded\_Length package. Because this is a generic package, you need to instantiate it and set the maximum length of the bounded string. You can then declare bounded strings of the Bounded\_String type.

Both bounded and fixed-length strings have a maximum length that they can hold. However, bounded strings are not arrays, so initializing them at run-time is much easier. For example:

```
with Ada.Strings;     use Ada.Strings;
with Ada.Strings.Bounded;
with Ada.Text_IO;     use Ada.Text_IO;

procedure Show_Bounded_String is
    package B_Str is new
        Ada.Strings.Bounded.Generic_Bounded_Length (Max => 15);
    use B_Str;

S1, S2 : Bounded_String;

procedure Display_String_Info (S : Bounded_String) is
begin
    Put_Line ("String: " & To_String (S));
```

By using bounded strings, we can easily assign to S1 and S2 multiple times during execution. We use the To\_Bounded\_String and To\_String functions to convert, in the respective direction, between fixed-length and bounded strings. A call to To\_Bounded\_String raises an exception if the length of the input string is greater than the maximum capacity of the bounded string. To avoid this, we can use the truncation parameter (Right in our example).

Bounded strings are not arrays, so we can't use the 'Length attribute as we did for fixed-length strings. Instead, we call the Length function, which returns the length of the bounded string. The Max\_Length constant represents the maximum length of the bounded string that we set when we instantiated the package.

After initializing a bounded string, we can manipulate it. For example, we can append a string to a bounded string using Append or concatenate bounded strings using the & operator. Like so:

```
with Ada.Strings;
                          use Ada.Strings;
with Ada.Strings.Bounded;
with Ada. Text IO;
                          use Ada. Text IO;
procedure Show Bounded String Op is
   package B Str is new
     Ada.Strings.Bounded.Generic Bounded Length (Max => 30);
  use B Str;
  S1, S2 : Bounded String;
beain
  S1 := To_Bounded_String ("Hello");
   -- Alternatively: A := Null Bounded String & "Hello";
  Append (S1, "World");
   -- Alternatively: Append (A, " World", Right);
  Put Line ("String: " & To String (S1));
  S2 := To Bounded String ("Hello!");
  S1 := S1 \& " " \& S2;
  Put Line ("String: " & To String (S1));
end Show Bounded String Op;
```

We can initialize a bounded string with an empty string using the Null\_Bounded\_String constant. Also, we can use the Append procedure and specify the truncation mode like we do with the To Bounded String function.

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#### 16.4.2.2 Unbounded strings

Unbounded strings are defined in the Ada.Strings.Unbounded package. This is *not* a generic package, so we don't need to instantiate it before using the Unbounded\_String type. As you may recall from the previous section, bounded strings require a package instantiation.

Unbounded strings are similar to bounded strings. The main difference is that they can hold strings of any size and adjust according to the input string: if we assign, e.g., a 10-character string to an unbounded string and later assign a 50-character string, internal operations in the container ensure that memory is allocated to store the new string. In most cases, developers don't need to worry about these operations. Also, no truncation is necessary.

Initialization of unbounded strings is very similar to bounded strings. Let's look at an example:

```
use Ada.Strings;
with Ada.Strings;
with Ada.Strings.Unbounded; use Ada.Strings.Unbounded;
with Ada. Text IO;
                            use Ada.Text IO;
procedure Show_Unbounded_String is
  S1, S2 : Unbounded_String;
  procedure Display String Info (S : Unbounded String) is
  begin
      Put Line ("String: " & To String (S));
      Put Line ("String Length: " & Integer'Image (Length (S)));
  end Display String Info;
begin
  S1 := To_Unbounded_String ("Hello");
   -- Alternatively: A := Null_Unbounded_String & "Hello";
  Display_String_Info (S1);
  S2 := To Unbounded String ("Hello World");
  Display_String_Info (S2);
  S1 := To Unbounded String ("Something longer to say here...");
  Display_String_Info (S1);
end Show_Unbounded_String;
```

Like bounded strings, we can assign to S1 and S2 multiple times during execution and use the To\_Unbounded\_String and To\_String functions to convert back-and-forth between fixed-length strings and unbounded strings. However, in this case, truncation is not needed.

And, just like for bounded strings, you can use the Append function and the & operator for unbounded strings. For example:

## 16.5 Files and streams

This section presents the different options available in Ada for file input/output (I/O).

#### 16.5.1 Text I/O

In most parts of this course, we used the Put\_Line procedure to display information on the console. However, this procedure also accepts a File\_Type parameter. For example, you can select between standard output and standard error by setting this parameter explicitly:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Std_Text_Out is
begin
   Put_Line (Standard_Output, "Hello World #1");
   Put_Line (Standard_Error, "Hello World #2");
end Show_Std_Text_Out;
```

You can also use this parameter to write information to any text file. To create a new file for writing, use the Create procedure, which initializes a File\_Type element that you can later pass to Put\_Line (instead of, e.g., Standard\_Output). After you finish writing information, you can close the file by calling the Close procedure.

You use a similar method to read information from a text file. However, when opening the file, you must specify that it's an input file (In\_File) instead of an output file. Also, instead of calling the Put Line procedure, you call the Get Line function to read information from the file.

Let's see an example that writes information into a new text file and then reads it back from the same file:

```
with Ada.Text_IO; use Ada.Text_IO;
procedure Show_Simple_Text_File_I0 is
  F
       : File Type;
  File_Name : constant String := "simple.txt";
begin
  Create (F, Out_File, File_Name);
  Put_Line (F, "Hello World #1");
  Put_Line (F, "Hello World #2");
  Put_Line (F, "Hello World #3");
  Close (F);
  Open (F, In_File, File_Name);
  while not End Of File (F) loop
      Put_Line (Get_Line (F));
   end loop;
  Close (F);
end Show_Simple_Text_File_I0;
```

In addition to the Create and Close procedures, the standard library also includes a Reset procedure, which, as the name implies, resets (erases) all the information from the file. For example:

```
Put_Line (F, "Hello World #1");
Reset (F);
Put_Line (F, "Hello World #2");
Close (F);

Open (F, In_File, File_Name);
while not End_Of_File (F) loop
    Put_Line (Get_Line (F));
end loop;
Close (F);
end Show_Text_File_Reset;
```

By running this program, we notice that, although we've written the first string (Hello World #1) to the file, it has been erased because of the call to Reset.

In addition to opening a file for reading or writing, you can also open an existing file and append to it. Do this by calling the Open procedure with the Append\_File option.

When calling the **0**pen procedure, an exception is raised if the specified file isn't found. Therefore, you should handle exceptions in that context. The following example deletes a file and then tries to open the same file for reading:

```
with Ada.Text IO; use Ada.Text IO;
procedure Show_Text_File_Input_Except is
  F : File Type;
  File_Name : constant String := "simple.txt";
begin
      Open output file and delete it
  Create (F, Out_File, File_Name);
  Delete (F);
   -- Try to open deleted file
  Open (F, In File, File Name);
  Close (F);
exception
  when Name_Error =>
     Put_Line ("File does not exist");
  when others =>
     Put_Line ("Error while processing input file");
end Show_Text_File_Input_Except;
```

In this example, we create the file by calling Create and then delete it by calling Delete. After the call to Delete, we can no longer use the File\_Type element'. After deleting the file, we try to open the non-existent file, which raises a Name Error exception.

## 16.5.2 Sequential I/O

The previous section presented details about text file I/O. Here, we discuss doing file I/O in binary format. The first package we'll explore is the Ada. Sequential\_IO package. Because this package is a generic package, you need to instantiate it for the data type you want to use for file I/O. Once you've done that, you can use the same procedures we've seen in the previous section: Create, Open, Close, Reset and Delete. However, instead of calling the Get\_Line and Put\_Line procedures, you'd call the Read and Write procedures.

In the following example, we instantiate the Ada. Sequential IO package for floating-point types:

```
procedure Show Seq Float IO is
   package Float_IO is new Ada.Sequential_IO (Float);
   use Float_IO;
             : Float_I0.File_Type;
   File_Name : constant String := "float_file.bin";
begin
   Create (F, Out_File, File_Name);
  Write (F, 1.5);
Write (F, 2.4);
Write (F, 6.7);
   Close (F);
   declare
      Value : Float;
   begin
      Open (F, In_File, File_Name);
      while not End Of File (F) loop
         Read (F, Value);
         Ada.Text IO.Put Line (Float'Image (Value));
      end loop;
      Close (F);
   end;
end Show_Seq_Float_I0;
```

We use the same approach to read and write complex information. The following example uses a record that includes a Boolean and a floating-point value:

```
with Ada.Text IO;
with Ada. Sequential IO;
procedure Show Seq Rec IO is
   type Num Info is record
     Valid : Boolean := False;
     Value : Float;
  end record;
  procedure Put Line (N : Num Info) is
  begin
     if N. Valid then
        Ada.Text IO.Put Line ("(ok, " & Float'Image (N.Value) & ")");
     else
         Ada.Text IO.Put Line ("(not ok, -----)");
     end if;
  end Put Line;
  package Num Info IO is new Ada.Sequential IO (Num Info);
  use Num Info IO;
            : Num Info_IO.File_Type;
  File Name : constant String := "float file.bin";
  Create (F, Out_File, File_Name);
  Write (F, (True, 1.5));
  Write (F, (False, 2.4));
  Write (F, (True, 6.7));
  Close (F);
  declare
     Value : Num Info;
```

```
begin
   Open (F, In_File, File_Name);
   while not End_Of_File (F) loop
        Read (F, Value);
        Put_Line (Value);
   end loop;
   Close (F);
  end;
end Show_Seq_Rec_IO;
```

As the example shows, we can use the same approach we used for floating-point types to perform file I/O for this record. Once we instantiate the Ada. Sequential\_IO package for the record type, file I/O operations are performed the same way.

## 16.5.3 Direct I/O

Direct I/O is available in the Ada.Direct\_I0 package. This mechanism is similar to the sequential I/O approach just presented, but allows us to access any position in the file. The package instantiation and most operations are very similar to sequential I/O. To rewrite the Show\_Seq\_Float\_I0 application presented in the previous section to use the Ada.Direct\_I0 package, we just need to replace the instances of the Ada.Sequential\_I0 package by the Ada.Direct\_I0 package. This is the new source code:

```
with Ada. Text IO;
with Ada.Direct_IO;
procedure Show_Dir_Float_IO is
  package Float_IO is new Ada.Direct_IO (Float);
  use Float IO;
            : Float_IO.File_Type;
  File Name : constant String := "float file.bin";
begin
  Create (F, Out_File, File_Name);
  Write (F, 1.5);
  Write (F, 2.4);
  Write (F, 6.7);
  Close (F);
  declare
      Value : Float;
  begin
      Open (F, In File, File Name);
     while not End_Of_File (F) loop
         Read (F, Value);
         Ada.Text_IO.Put_Line (Float'Image (Value));
      end loop;
      Close (F);
  end:
end Show_Dir_Float_I0;
```

Unlike sequential I/O, direct I/O allows you to access any position in the file. However, it doesn't offer an option to append information to a file. Instead, it provides an Inout\_File mode allowing reading and writing to a file via the same File\_Type element.

To access any position in the file, call the Set\_Index procedure to set the new position / index. You can use the Index function to retrieve the current index. Let's see an example:

```
with Ada. Text IO;
with Ada.Direct_IO;
procedure Show Dir Float In Out File is
   package Float IO is new Ada.Direct IO (Float);
  use Float IO;
             : Float IO.File Type;
  File Name : constant String := "float file.bin";
begin
      Open file for input / output
  Create (F, Inout File, File Name);
  Write (F, 1.5);
  Write (F, 2.4);
  Write (F, 6.7);
   -- Set index to previous position and overwrite value
  Set Index (F, Index (F) - 1);
  Write (F, 7.7);
  declare
     Value : Float;
  begin
         Set index to start of file
      Set_Index (F, 1);
     while not End_Of_File (F) loop
         Read (F, Value);
         Ada.Text_IO.Put_Line (Float'Image (Value));
      end loop:
      Close (F);
end Show Dir Float In Out File;
```

By running this example, we see that the file contains 7.7, rather than the previous 6.7 that we wrote. We overwrote the value by changing the index to the previous position before doing another write.

In this example we used the Inout\_File mode. Using that mode, we just changed the index back to the initial position before reading from the file (Set\_Index (F, 1)) instead of closing the file and reopening it for reading.

#### 16.5.4 Stream I/O

All the previous approaches for file I/O in binary format (sequential and direct I/O) are specific for a single data type (the one we instantiate them with). You can use these approaches to write objects of a single data type that may be an array or record (potentially with many fields), but if you need to create and process files that include different data types, or any objects of an unbounded type, these approaches are not sufficient. Instead, you should use stream I/O.

Stream I/O shares some similarities with the previous approaches. We still use the Create, Open and Close procedures. However, instead of accessing the file directly via a File\_Type element, you use a Stream\_Access element. To read and write information, you use the 'Read or 'Write attributes of the data types you're reading or writing.

Let's look at a version of the Show\_Dir\_Float\_I0 procedure from the previous section that makes use of stream I/O instead of direct I/O:

```
procedure Show Float Stream is
  F
            : File Type;
  S
            : Stream_Access;
  File_Name : constant String := "float_file.bin";
  Create (F, Out_File, File_Name);
  S := Stream(F);
  Float'Write (S, 1.5);
  Float'Write (S, 2.4);
  Float'Write (S, 6.7);
  Close (F);
  declare
     Value : Float;
  begin
      Open (F, In File, File Name);
     S := Stream(F);
     while not End_Of_File (F) loop
         Float'Read (S, Value);
         Ada.Text IO.Put Line (Float'Image (Value));
      end loop;
      Close (F);
  end;
end Show_Float_Stream;
```

After the call to Create, we retrieve the corresponding Stream\_Access element by calling the Stream function. We then use this stream to write information to the file via the 'Write attribute of the Float type. After closing the file and reopening it for reading, we again retrieve the corresponding Stream\_Access element and processed to read information from the file via the 'Read attribute of the Float type.

You can use streams to create and process files containing different data types within the same file. You can also read and write unbounded data types such as strings. However, when using unbounded data types you must call the 'Input and 'Output attributes of the unbounded data type: these attributes write information about bounds or discriminants in addition to the object's actual data.

The following example shows file I/O that mixes both strings of different lengths and floating-point values:

```
SV : String := String'Input (S);
      FV : Float := Float'Input (S);
      Ada.Text_IO.Put_Line (Float'Image (FV) & " --- " & SV);
   end Input_Display;
begin
   Create (F, Out_File, File_Name);
   S := Stream(F);
   Output (S, 1.5, "Hi!!");
Output (S, 2.4, "Hello world!");
Output (S, 6.7, "Something longer here...");
   Close (F);
   Open (F, In_File, File_Name);
   S := Stream(F);
   while not End_Of_File (F) loop
      Input Display (S);
   end loop;
   Close (F);
end Show_String_Stream;
```

When you use Stream I/O, no information is written into the file indicating the type of the data that you wrote. If a file contains data from different types, you must reference types in the same order when reading a file as when you wrote it. If not, the information you get will be corrupted. Unfortunately, strong data typing doesn't help you in this case. Writing simple procedures for file I/O (as in the example above) may help ensuring that the file format is consistent.

Like direct I/O, stream I/O supports also allows you to access any location in the file. However, when doing so, you need to be extremely careful that the position of the new index is consistent with the data types you're expecting.

#### 16.6 Numerics

The standard library provides support for common numeric operations on floating-point types as well as on complex types and matrices. This section presents a brief introduction to them.

## **16.6.1 Elementary Functions**

The Ada.Numerics.Elementary\_Functions package provides common operations for floating-point types, such as square root, logarithm, and the trigonometric functions (e.g., sin, cos). For example:

```
with Ada.Text_IO; use Ada.Text_IO;
with Ada.Numerics; use Ada.Numerics;
with Ada.Numerics.Elementary_Functions;
use Ada.Numerics.Elementary_Functions;
procedure Show_Elem_Math is
    X : Float;
begin
```

(continues on next page)

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```
X := 2.0;
  Put Line ("Square root of " & Float'Image (X)
            & " is " & Float'Image (Sqrt (X)));
  X := e;
  Put_Line ("Natural log of " & Float'Image (X)
            & " is " & Float'Image (Log (X)));
  X := 10.0 ** 6.0;
  Put_Line ("Log_10
                        of " & Float'Image (X)
            & " is " & Float'Image (Log (X, 10.0)));
  X := 2.0 ** 8.0;
                        of " & Float'Image (X)
  Put_Line ("Log_2
            & " is " & Float'Image (Log (X, 2.0)));
  X := Pi;
  Put_Line ("Cos
                       of " & Float'Image (X)
            & " is " & Float'Image (Cos (X)));
  X := -1.0;
                      of " & Float'Image (X)
  Put_Line ("Arccos
            & " is " & Float'Image (Arccos (X)));
end Show_Elem_Math;
```

Here we use the standard e and Pi constants from the Ada. Numerics package.

The Ada.Numerics.Elementary\_Functions package provides operations for the Float type. Similar packages are available for Long\_Float and Long\_Long\_Float types. For example, the Ada.Numerics.Long\_Elementary\_Functions package offers the same set of operations for the Long\_Float type. In addition, the Ada.Numerics.Generic\_Elementary\_Functions package is a generic version of the package that you can instantiate for custom floating-point types. In fact, the Elementary\_Functions package can be defined as follows:

```
package Elementary_Functions is new
Ada.Numerics.Generic_Elementary_Functions (Float);
```

#### 16.6.2 Random Number Generation

The Ada. Numerics. Float\_Random package provides a simple random number generator for the range between 0.0 and 1.0. To use it, declare a generator G, which you pass to Random. For example:

```
end loop;
end Show_Float_Random_Num;
```

The standard library also includes a random number generator for discrete numbers, which is part of the Ada.Numerics.Discrete\_Random package. Since it's a generic package, you have to instantiate it for the desired discrete type. This allows you to specify a range for the generator. In the following example, we create an application that displays random integers between 1 and 10:

```
with Ada.Text IO; use Ada.Text IO;
with Ada. Numerics. Discrete Random;
procedure Show_Discrete_Random_Num is
  subtype Random Range is Integer range 1 .. 10;
  package R is new Ada.Numerics.Discrete Random (Random Range);
  use R;
  G : Generator;
  X : Random Range;
begin
  Reset (G);
  Put Line ("Some random numbers between "
             & Integer'Image (Random Range'First) & " and "
             & Integer'Image (Random Range'Last) & ":");
   for I in 1 .. 15 loop
     X := Random(G);
      Put_Line (Integer'Image (X));
  end loop;
end Show Discrete Random Num;
```

Here, package R is instantiated with the Random\_Range type, which has a constrained range between 1 and 10. This allows us to control the range used for the random numbers. We could easily modify the application to display random integers between 0 and 20 by changing the specification of the Random Range type. We can also use floating-point or fixed-point types.

## 16.6.3 Complex Types

The Ada.Numerics.Complex\_Types package provides support for complex number types and the Ada.Numerics.Complex\_Elementary\_Functions package provides support for common operations on complex number types, similar to the Ada.Numerics.Elementary\_Functions package. Finally, you can use the Ada.Text\_IO.Complex\_IO package to perform I/O operations on complex numbers. In the following example, we declare variables of the Complex type and initialize them using an aggregate:

```
with Ada.Text_IO; use Ada.Text_IO;
with Ada.Numerics; use Ada.Numerics;

with Ada.Numerics.Complex_Types;
use Ada.Numerics.Complex_Elementary_Functions;
use Ada.Numerics.Complex_Elementary_Functions;
use Ada.Numerics.Complex_Elementary_Functions;

with Ada.Text_IO.Complex_IO;
procedure Show_Elem_Math is

(continues on next page)
```

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```
package C IO is new Ada.Text IO.Complex IO (Complex Types);
  use C IO;
  X, Y : Complex;
  R, Th : Float;
begin
  X := (2.0, -1.0);
  Y := (3.0, 4.0);
  Put (X);
  Put (" * ");
  Put (Y);
  Put (" is ");
Put (X * Y);
  New Line;
  New_Line;
  R := 3.0;
  Th := Pi / 2.0;
  X := Compose From Polar (R, Th);
   -- Alternatively:
   -- X := R * Exp ((0.0, Th));
   -- X := R * e ** Complex'(0.0, Th);
  Put ("Polar form:
        & Float'Image (R) & " * e^{**}(i * "
        & Float'Image (Th) & ")");
  New Line;
  Put ("Modulus of ");
  Put (X);
  Put (" is ");
  Put (Float'Image (abs (X)));
  New_Line;
  Put ("Argument of ");
  Put (X);
  Put (" is ");
  Put (Float'Image (Argument (X)));
  New Line;
  New Line;
  Put ("Sqrt
                   of ");
  Put (X);
  Put (" is ");
  Put (Sqrt (X));
  New Line;
end Show Elem Math;
```

As we can see from this example, all the common operators, such as \* and +, are available for complex types. You also have typical operations on complex numbers, such as Argument and Exp. In addition to initializing complex numbers in the cartesian form using aggregates, you can do so from the polar form by calling the Compose From Polar function.

The Ada.Numerics.Complex\_Types and Ada.Numerics.Complex\_Elementary\_Functions packages provide operations for the Float type. Similar packages are available for Long\_Float and Long\_Long\_Float types. In addition, the Ada.Numerics.Generic\_Complex\_Types and Ada.Numerics.Generic\_Complex\_Elementary\_Functions packages are generic versions that you can instantiate for custom or pre-defined floating-point types. For example:

```
with Ada.Numerics.Generic_Complex_Types;
with Ada.Numerics.Generic_Complex_Elementary_Functions;
with Ada.Text_IO.Complex_IO;

procedure Show_Elem_Math is

   package Complex_Types is new
        Ada.Numerics.Generic_Complex_Types (Float);
   use Complex_Types;

   package Elementary_Functions is new
        Ada.Numerics.Generic_Complex_Elementary_Functions (Complex_Types);
   use Elementary_Functions;

   package C_IO is new Ada.Text_IO.Complex_IO (Complex_Types);
   use C_IO;

   X, Y : Complex;
   R, Th : Float;
```

## 16.6.4 Vector and Matrix Manipulation

The Ada. Numerics. Real\_Arrays package provides support for vectors and matrices. It includes common matrix operations such as inverse, determinant, eigenvalues in addition to simpler operators such as matrix addition and multiplication. You can declare vectors and matrices using the Real\_Vector and Real\_Matrix types, respectively.

The following example uses some of the operations from the Ada. Numerics. Real\_Arrays package:

```
with Ada.Text IO; use Ada.Text IO;
with Ada. Numerics. Real Arrays;
use Ada.Numerics.Real Arrays;
procedure Show Matrix is
   procedure Put_Vector (V : Real_Vector) is
  begin
      Put ("
               (");
      for I in V'Range loop
         Put (Float'Image (V (I)) & " ");
      end loop;
      Put_Line (")");
  end Put Vector;
   procedure Put Matrix (M : Real Matrix) is
  begin
      for I in M'Range (1) loop
         Put ("
                   (");
         for J in M'Range (2) loop
            Put (Float'Image (M (I, J)) & " ");
         end loop;
         Put Line (")");
      end loop;
  end Put_Matrix;
            : Real_Vector := (1.0, 3.0);
  V2
            : Real_Vector := (75.0, 11.0);
```

(continues on next page)

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```
M1
            : Real Matrix :=
                 ((1.0, 5.0, 1.0),
                  (2.0, 2.0, 1.0));
   M2
            : Real_Matrix :=
                 ((31.0, 11.0, 10.0),
                  (34.0, 16.0, 11.0),
                  (32.0, 12.0, 10.0),
                  (31.0, 13.0, 10.0));
   М3
            : Real\_Matrix := ((1.0, 2.0),
                               (2.0, 3.0));
begin
   Put_Line ("V1");
   Put_Vector (V1);
   Put_Line ("V2");
   Put_Vector (V2);
Put_Line ("V1 * V2 =");
   Put_Line ("
             & Float'Image (V1 * V2));
   Put Line ("V1 * V2 =");
   Put_Matrix (V1 * V2);
   New_Line;
   Put Line ("M1");
   Put Matrix (M1);
   Put_Line ("M2");
   Put Matrix (M2);
   Put_Line ("M2 * Transpose(M1) =");
   Put_Matrix (M2 * Transpose (M1));
   New Line;
   Put Line ("M3");
   Put_Matrix (M3);
   Put_Line ("Inverse (M3) =");
   Put Matrix (Inverse (M3));
   Put_Line ("abs Inverse (M3) =");
   Put Matrix (abs Inverse (M3));
   Put Line ("Determinant (M3) =");
   Put_Line ("
             & Float'Image (Determinant (M3)));
   Put_Line ("Solve (M3, V1) =");
   Put_Vector (Solve (M3, V1));
   Put Line ("Eigenvalues (M3) =");
   Put Vector (Eigenvalues (M3));
   New Line;
end Show Matrix;
```

Matrix dimensions are automatically determined from the aggregate used for initialization when you don't specify them. You can, however, also use explicit ranges. For example:

```
M1 : Real_Matrix (1 .. 2, 1 .. 3) := ((1.0, 5.0, 1.0), (2.0, 2.0, 1.0));
```

The Ada.Numerics.Real\_Arrays package implements operations for the Float type. Similar packages are available for Long\_Float and Long\_Long\_Float types. In addition, the Ada. Numerics.Generic\_Real\_Arrays package is a generic version that you can instantiate with custom floating-point types. For example, the Real\_Arrays package can be defined as follows:

```
package Real_Arrays is new
Ada.Numerics.Generic_Real_Arrays (Float);
```

# **SEVENTEEN**

## **APPENDICES**

# **17.1 Appendix A: Generic Formal Types**

The following tables contain examples of available formal types for generics:

Formal type	Actual type			
Incomplete type	Any type			
Format: type T;				
Discrete type	Any integer, modular or enumeration type			
Format: type T is (<>);				
Range type	Any signed integer type			
<pre>Format: type T is range &lt;&gt;;</pre>				
Modular type	Any modular type			
<pre>Format: type T is mod &lt;&gt;;</pre>				
Floating-point type	Any floating-point type			
<pre>Format: type T is digits &lt;&gt;;</pre>				
Binary fixed-point type	Any binary fixed-point type			
<pre>Format: type T is delta &lt;&gt;;</pre>				
Decimal fixed-point type	Any decimal fixed-point type			
<b>Format</b> : type T is delta <> digits				
<>;				
Definite nonlimited private type	Any nonlimited, definite type			
<pre>Format: type T is private;</pre>				
Nonlimited Private type with discriminant	Any nonlimited type with discriminant			
<pre>Format: type T (D : DT) is private;</pre>				
Access type	Any access type for type T			
Format: type A is access T;				
Definite derived type	Any concrete type derived from base type B			
Format: type T is new B;				
Limited private type	Any definite type, limited or not			
<pre>Format: type T is limited private;</pre>				
Incomplete tagged type	Any concrete, definite, tagged type			
<pre>Format: type T is tagged;</pre>				
Definite tagged private type	Any concrete, definite, tagged type			
<pre>Format: type T is tagged private;</pre>				
Definite tagged limited private type	Any concrete definite tagged type, limited or			
<b>Format</b> : type T is tagged limited	not			
private;				
Definite abstract tagged private type	Any nonlimited, definite tagged type, abstract			
<b>Format</b> : type T is abstract tagged	or concrete			
private;	Continued on post page			

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Table 1 – continued from previous page

	Troffi previous page			
Formal type	Actual type			
Definite abstract tagged limited private type	Any definite tagged type, limited or not, abstract or concrete			
<b>Format</b> : type T is abstract tagged				
limited private;				
Definite derived tagged type	Any concrete tagged type derived from bar			
Format: type T is new B with	type B			
private;				
Definite abstract derived tagged type	Any tagged type derived from base type B ab-			
Format: type T is abstract new B	stract or concrete  Any array type with range R containing ele-			
with private;				
Array type				
Format: type A is array (R) of T;	ments of type T			
Interface type	Any interface type T			
Format: type T is interface;	Any interface type i			
	Any limited interface type T			
Limited interface type	Any limited interface type T			
Format: type T is limited interface;	Any took interferent year			
Task interface type	Any task interface type T			
Format: type T is task interface;				
Synchronized interface type	Any synchronized interface type T			
Format: type T is synchronized				
interface;				
Protected interface type	Any protected interface type T			
Format: type T is protected				
interface;				
Derived interface type	Any type T derived from base type B and inter-			
Format: type T is new B and I with	face I			
private;				
Derived type with multiple interfaces	Any type T derived from base type B and inter-			
Format: type T is new B and I1 and	faces I1 and I2			
I2 with private;				
Abstract derived interface type	Any type T derived from abstract base type B			
Format: type T is abstract new B and	and interface I			
I with private;				
Limited derived interface type	Any type T derived from limited base type B			
Format: type T is limited new B and	and limited interface I			
I with private;				
Abstract limited derived interface type	Any type T derived from abstract limited base			
Format: type T is abstract limited	type B and limited interface I			
new B and I with private;	type b and minica interface i			
Synchronized interface type	Any type T derived from synchronized inter-			
Format: type T is synchronized new	face SI			
	ומנפ או			
SI with private;	Any type T devised from symplectical later			
Abstract synchronized interface type	Any type T derived from synchronized inter-			
Format: type T is abstract	face SI			
synchronized new SI with private;				

## 17.1.1 Indefinite version

Many of the examples above can be used for formal indefinite types:

Formal type	Actual type		
Indefinite incomplete type	Any type		
Format: type T (<>);			
Indefinite nonlimited private type	Any nonlimited type indefinite or defi-		
<pre>Format: type T (&lt;&gt;) is private;</pre>	nite		
Indefinite limited private type	Any type, limited or not, indefinite or		
<pre>Format: type T (&lt;&gt;) is limited private;</pre>	definite		
Incomplete indefinite tagged private type	Any concrete tagged type, indefinite or		
<pre>Format: type T (&lt;&gt;) is tagged;</pre>	definite		
Indefinite tagged private type	Any concrete, limited tagged type, in-		
<pre>Format: type T (&lt;&gt;) is tagged private;</pre>	definite or definite		
Indefinite tagged limited private type	Any concrete tagged type, limited or		
<b>Format</b> : type T (<>) is tagged limited	not, indefinite or definite		
private;			
Indefinite abstract tagged private type	Any nonlimited tagged type, indefinite		
<b>Format</b> : type T (<>) is abstract tagged	or definite, abstract or concrete		
private;			
Indefinite abstract tagged limited private type	Any tagged type, limited or not, indefi-		
<b>Format</b> : type T (<>) is abstract tagged	nite or definite abstract or concrete		
limited private;			
Indefinite derived tagged type	Any tagged type derived from base		
<pre>Format: type T (&lt;&gt;) is new B with private;</pre>	type B, indefinite or definite		
Indefinite abstract derived tagged type	Any tagged type derived from base		
Format: type T (<>) is abstract new B with	type B, indefinite or definite abstract or		
private;	concrete		

The same examples could also contain discriminants. In this case, (<>) is replaced by a list of discriminants, e.g.: (D: DT).

# **17.2 Appendix B: Containers**

The following table shows all containers available in Ada, including their versions (standard, bounded, unbounded, indefinite):

Category	Container	Std	Bounded	Unbounded	Indefinite
Vector	Vectors	Υ	Υ		Υ
List	Doubly_Linked_Lists	Υ	Υ		Υ
Мар	Hashed_Maps	Υ	Υ		Υ
Мар	Ordered_Maps	Υ	Υ		Υ
Set	Hashed_Sets	Υ	Υ		Υ
Set	Ordered_Sets	Υ	Υ		Υ
Tree	Multiway_Trees	Υ	Υ		Υ
Generic	Holders				Υ
Queue	Synchronized_Queue_Interfaces	Υ			
Queue	Synchronized_Queues		Υ	Υ	
Queue	Priority_Queues		Υ	Υ	

The following table presents the prefixing applied to the container name that depends on its version. As indicated in the table, the standard version does not have a prefix associated with it.

Version	Naming prefix		
Std			
Bounded	Bounded_		
Unbounded	Unbounded_		
Indefinite	<pre>Indefinite_</pre>		