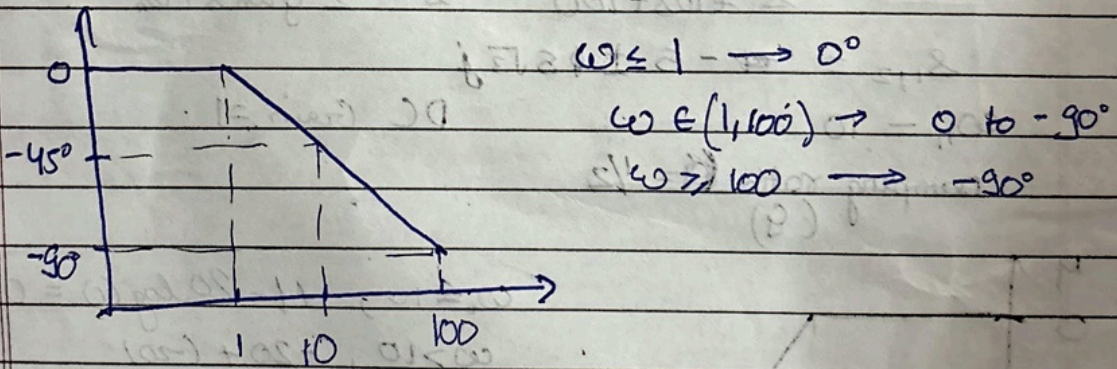
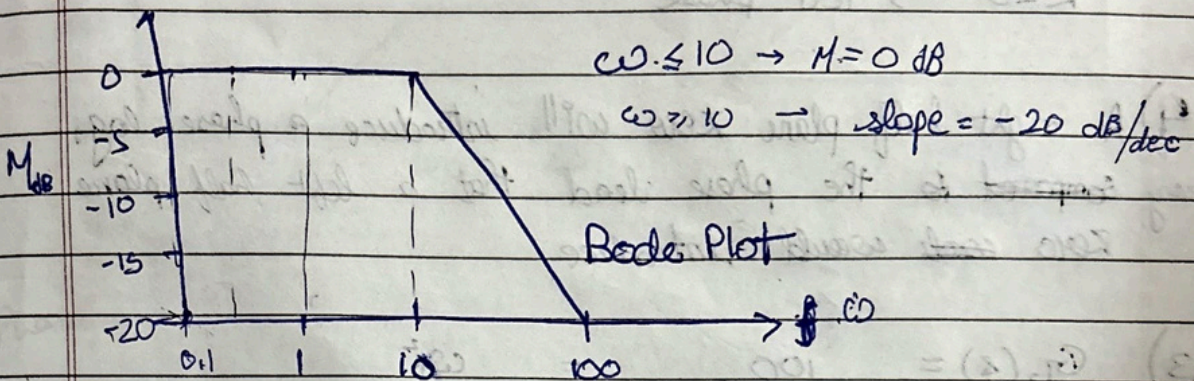


1.1) $G_1(s) = \frac{10}{s+10} \Rightarrow \text{Pole: } s = -10$
 $G_1(0) = 1$

$$= \frac{1}{1+s/10}$$

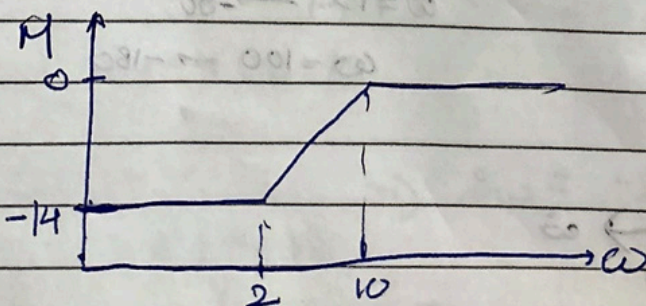
$$\Rightarrow \omega_c = 10 \text{ rad/s}$$

$$M_{dB} = 20 \log_{10} |G_1(j\omega)| = 0 \text{ dB (at } s=0)$$

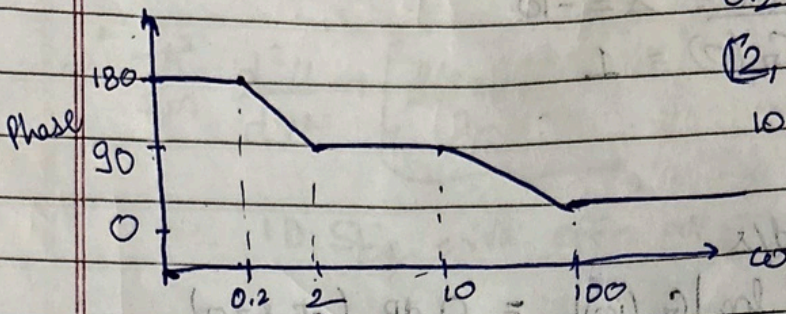


1.2) $G_2(s) = \frac{s-2}{s+10} \Rightarrow \text{Zero: } s = 2, \text{ Pole: } s = -10$
 $G_2(0) = -1/5$
 $= -1/5 \left(\frac{1-s/2}{1+s/10} \right) \Rightarrow \omega_z = 2, \omega_p = 10$
 $K = -0.2$

$$M_{dB} = 20 \log_{10} |-0.2| = -14 \text{ dB}$$



$\omega < 2 \rightarrow M = -14 \text{ dB}$
 $\omega \in (2, 10) \rightarrow \text{slope} = +20$
 $\omega > 10 \rightarrow \text{slope} = 0$

Phase Plot

$$0.2 \rightarrow 180^\circ$$

$$[2, 10] \rightarrow 90^\circ$$

$$100 \rightarrow 0^\circ$$

$K < 0 \rightarrow 180^\circ$ phase

- 4) A right half plane zero will introduce a phase lag, contrary ~~compared~~ to the phase lead that a left half plane zero ~~could~~ would introduce.

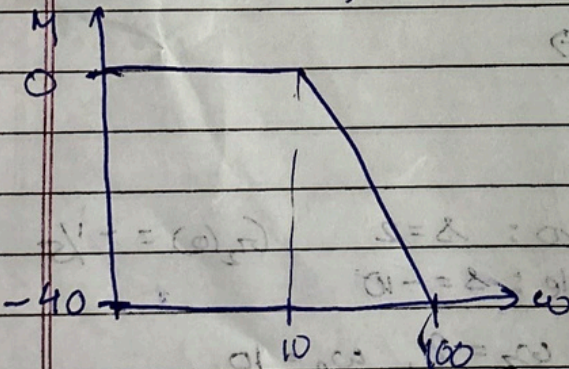
$$A3) G_3(s) = \frac{100}{s^2 + 10s + 100} = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$s_{1,2} = -5 \pm 5\sqrt{3}j$$

$$\omega_n = 10$$

DC Gain = 1

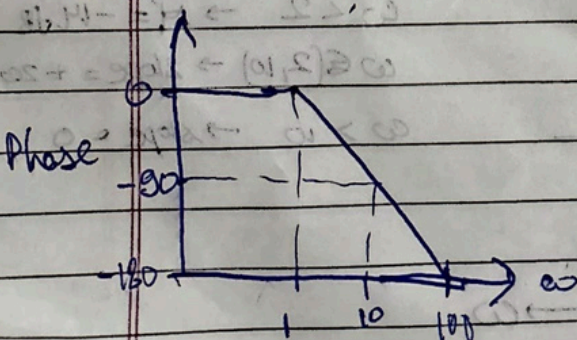
damping ratio $\zeta = 1/2$



$$\omega \leq 10, M = 20 \log(1) = 0 \text{ dB}$$

$$\omega > 10, -20 + (-20)$$

$$= -40 \rightarrow \text{slope}$$

Phase Plot

$$\omega \leq 1 \rightarrow 0^\circ$$

$$\omega = 10 \rightarrow -90^\circ$$

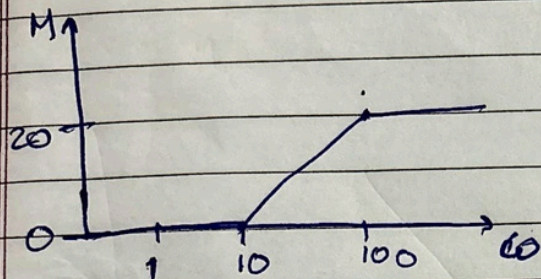
$$\omega = 100 \rightarrow -180^\circ$$

A4) $G(s) = \frac{0.1s + 1}{0.01s + 1}$, Zero: $s = -10$, Pole: $s = -100$

$$\omega_z = 10 \text{ rad/s}$$

$$\omega_p = 100 \text{ rad/s}$$

$$G_{Tq}(0) = 1$$



$$\omega < 10 \rightarrow M = 0$$

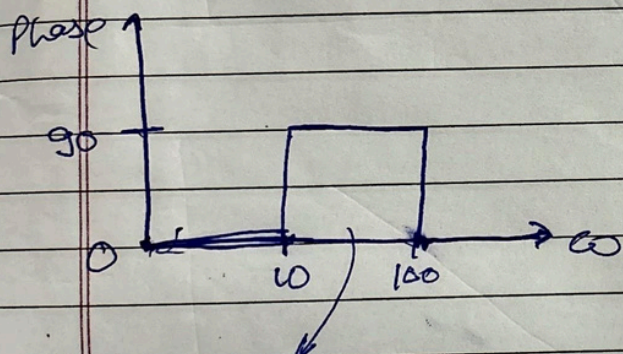
$$\omega = 10 \rightarrow +20 \text{ dB/dec}$$

$$\omega \geq 100 \rightarrow (20 - 20) = 0 \text{ dB/dec}$$

$$M = 20 \log(10)$$

$$M = 20 \text{ dB}$$

Phase Plot



$$\omega \leq 10 \rightarrow 0^\circ$$

$$\omega \in [10, 100) \rightarrow +90^\circ$$

$$\omega \geq 100 \rightarrow (90 - 90)^\circ = 0^\circ$$

4) B/w zero & Pole there is phase lead

B1) $m \ddot{x}(t) = F(t) - d \dot{x}(t) - c x(t)$
After Laplace Transform

$$ms^2 X(s) = F(s) - ds X(s) - c X(s)$$

$$\Rightarrow G(s) = \frac{X(s)}{F(s)} = \frac{1}{ms^2 + ds + c}$$

B2) $m=1, d=4, c=16$

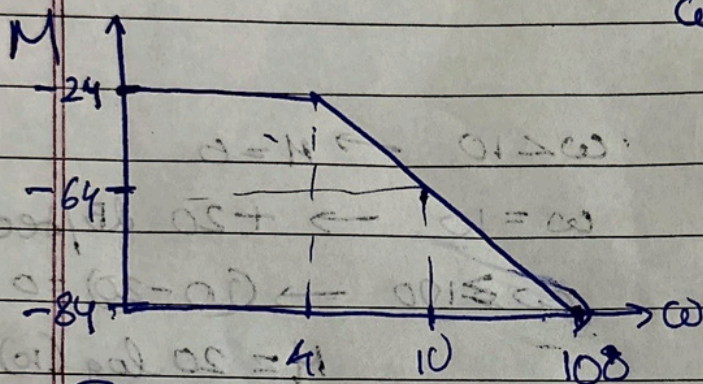
$$G(s) = \frac{1}{s^2 + 4s + 16} \Rightarrow s_{1,2} = -2 \pm 2\sqrt{3}j$$

By Comparing)

$$\omega_n = 4, \quad \zeta = 0.5 \quad 1 + 2\zeta\omega_n = (2)^2$$

$$M = 20 \log_{10} (1/16) \approx -24 \text{ dB}$$

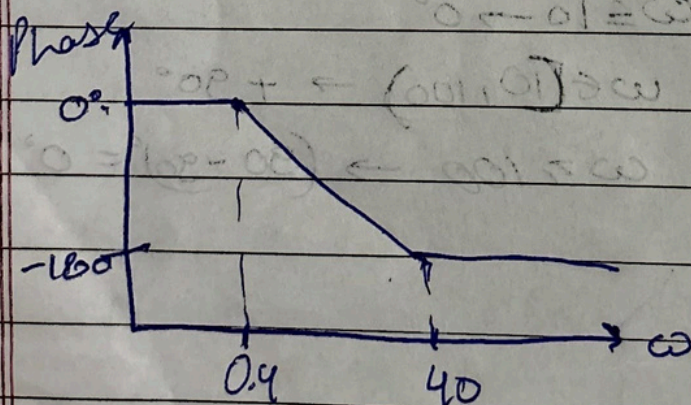
$$\omega > 4 \rightarrow \text{slope} = -40$$



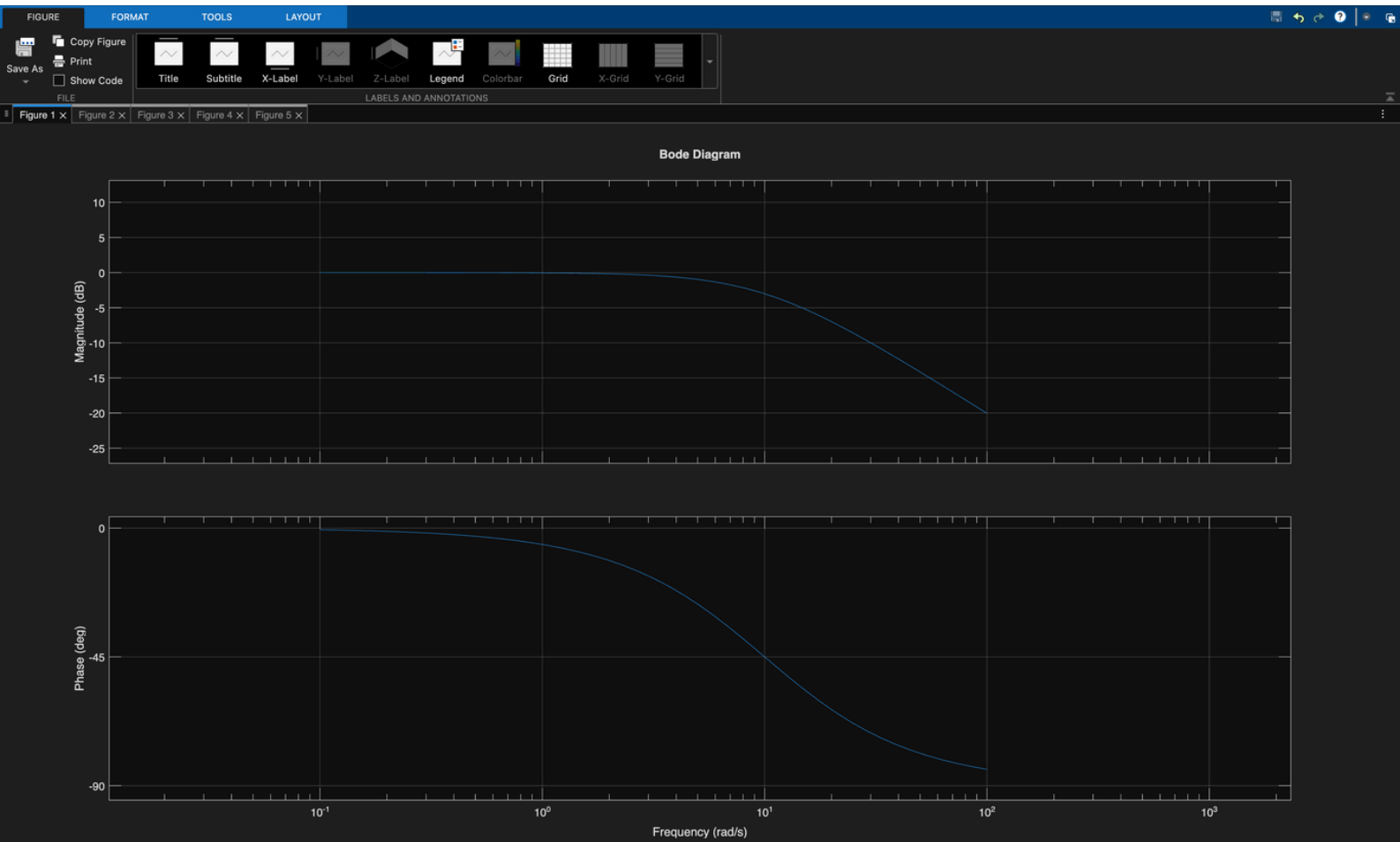
Phase Plot

$$\omega \leq \frac{\omega_n}{10} \rightarrow 0^\circ$$

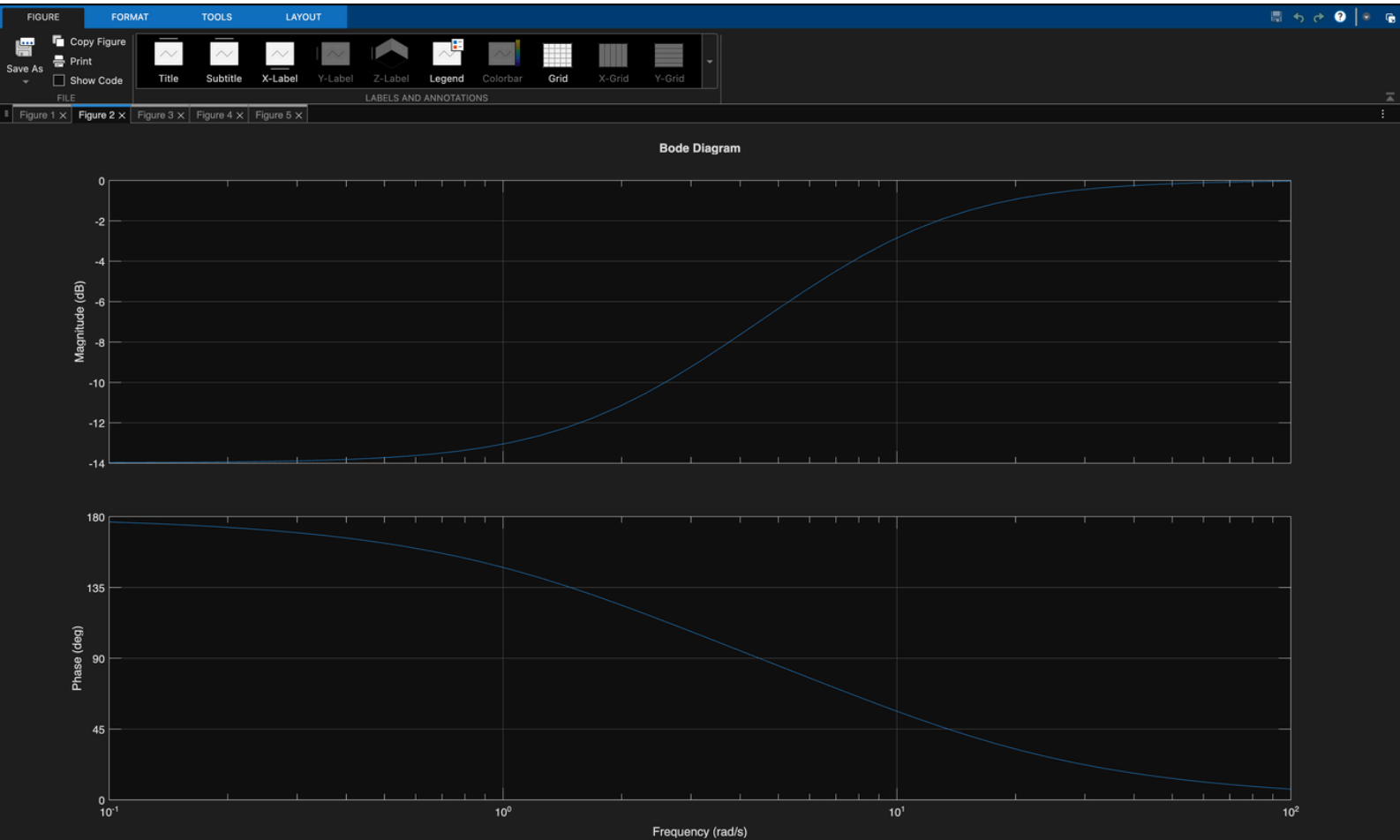
$$\omega \geq 10\omega_n \rightarrow -180^\circ$$



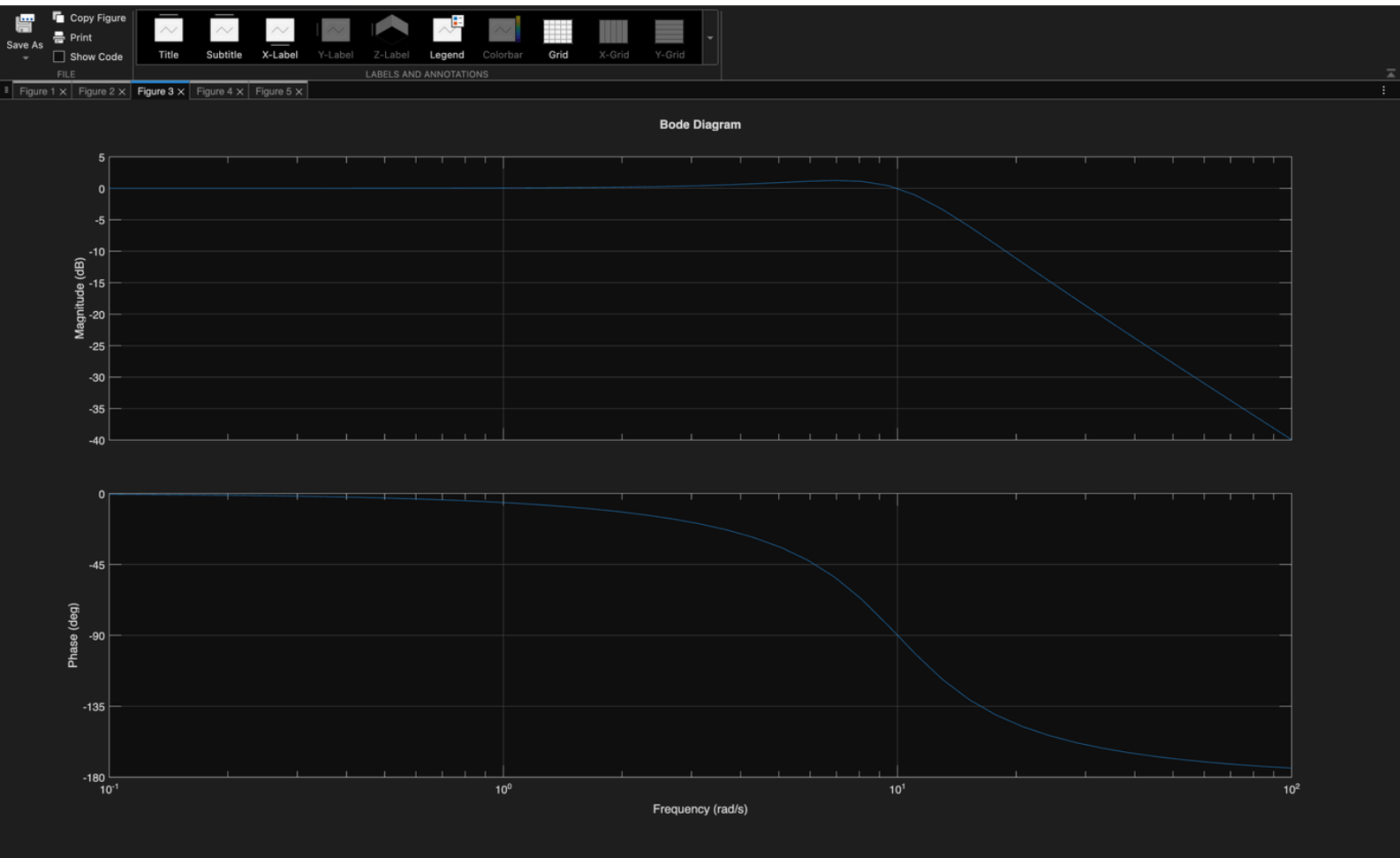
A1) Matlab Plots



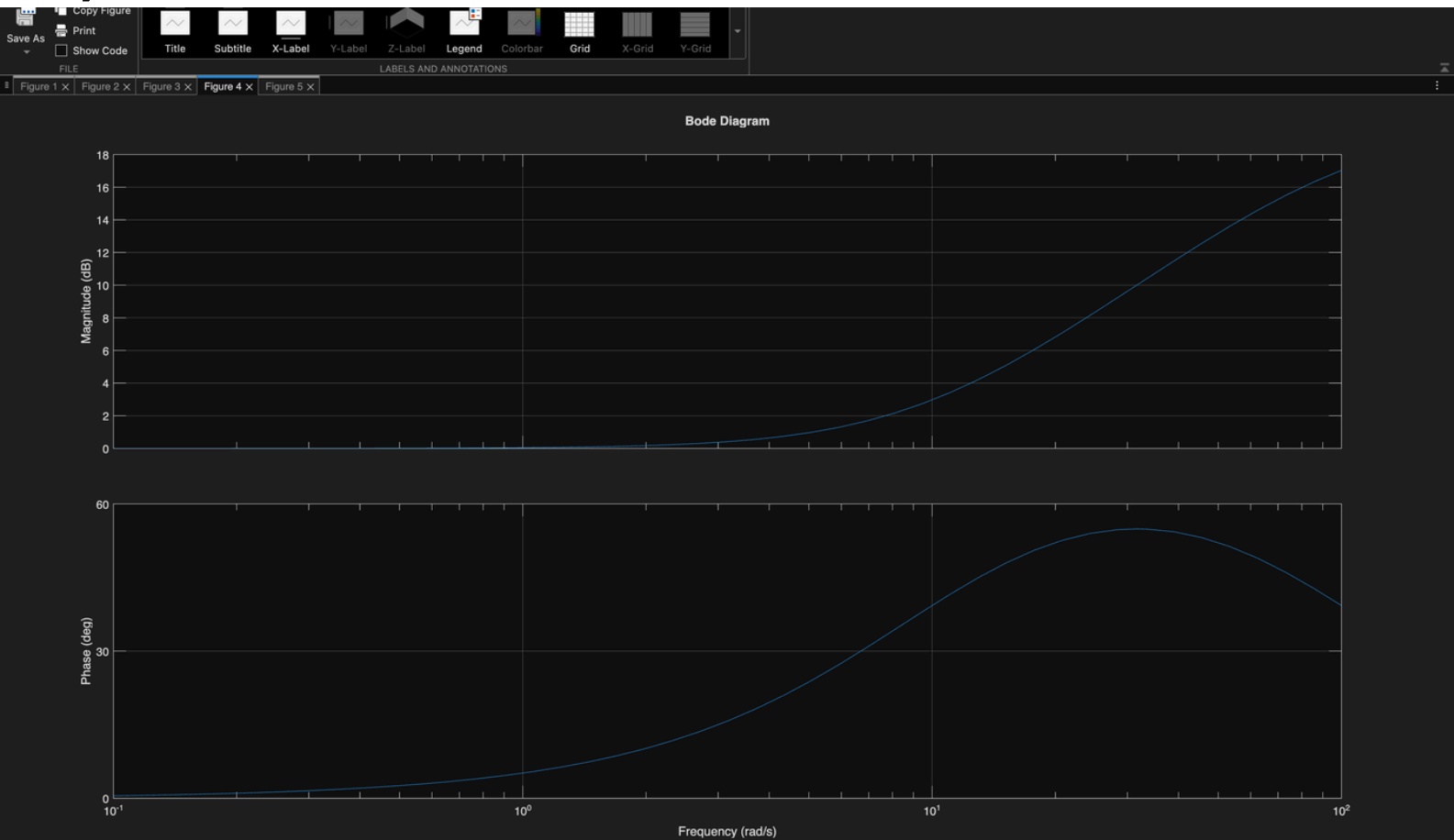
A2) Matlab Plots



A3) Matlab Plots



A4) Matlab Plots



B2) Matlab Plots

