

ASSIGNMENT

1.1 A.1) $G_1(s) = \frac{10}{s+10}$

(1)

Pole: $s = -10$

$$G_1(0) = \frac{10}{0+10} = 1$$

(2) $G(s) = \frac{1}{1 + (\frac{s}{\omega_0})}$ ($\omega_0 = 10$)

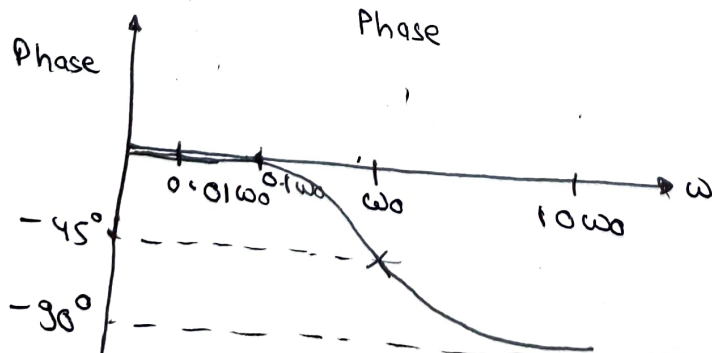
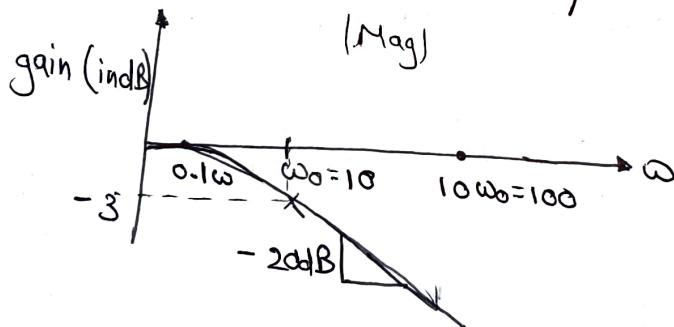
Put $s = j\omega$

$$\Rightarrow G(s) = \frac{1}{1 + (\frac{j\omega}{\omega_0})} = \frac{1 - j\omega/\omega_0}{1 + (\frac{\omega}{\omega_0})^2}$$

$$|G(j\omega)| = \left(1 + \frac{\omega^2}{\omega_0^2}\right)^{-1/2} \quad \arg(G(j\omega)) = \tan^{-1}\left(\frac{-\omega}{\omega_0}\right)$$

$$\text{gain} \Rightarrow 20 \log_{10} \left(1 + \frac{\omega^2}{\omega_0^2}\right)^{-1/2}$$

$$\phi = \text{Phase} = \tan^{-1}\left(\frac{-\omega}{\omega_0}\right)$$



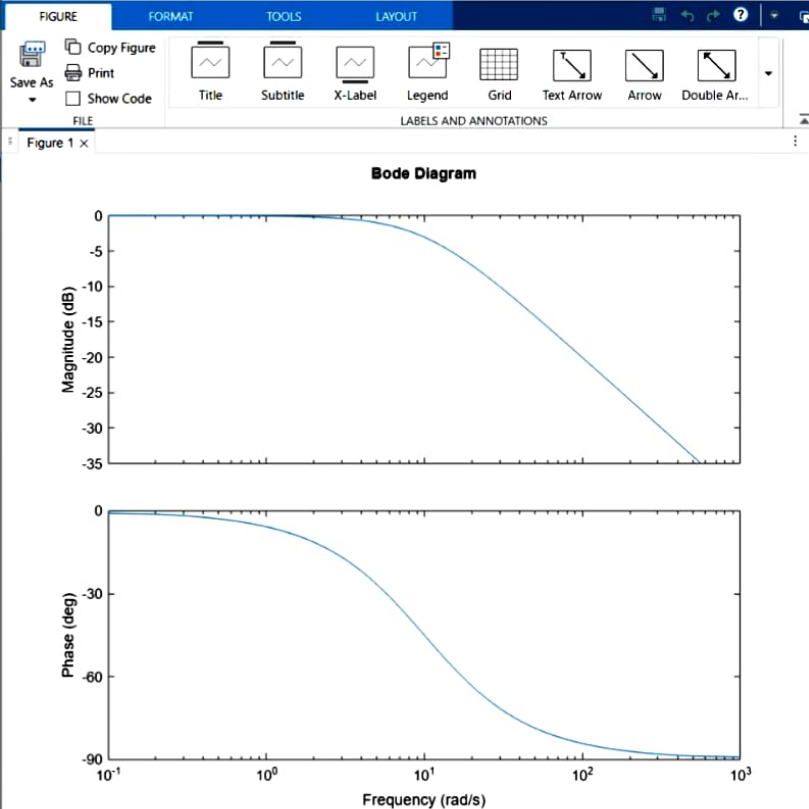
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Command Window

```
G1 =  
    10  
    ----  
    s + 10  
  
... Continuous-time transfer function.  
Model Properties  
  
    Numerator: {[0 10]}  
    Denominator: {[1 10]}  
    Variable: 's'  
    IODElay: 0  
    InputDelay: 0  
    OutputDelay: 0  
    InputName: {''}  
    InputUnit: {''}  
    InputGroup: [1x1 struct]  
    OutputName: {''}  
    OutputUnit: {''}  
    OutputGroup: [1x1 struct]  
    Notes: {0x1 string}  
    UserData: []  
    Name: ''  
    Ts: 0  
    TimeUnit: 'seconds'  
    SamplingGrid: [1x1 struct]  
  
>> bode(G1)  
  
>>
```



$$(1.2) \quad G_2(s) = \frac{s-2}{s+10}$$

zero: $s = 2$ Pole: $s = -10$ $G_2(0) = -0.2$

$$G_2(s) = \frac{s-2}{s+10}$$

\Rightarrow By logarithmic property

$$\text{Gain} = \cancel{s-2} \text{ gain}(s-2) - \text{gain}(s+10)$$

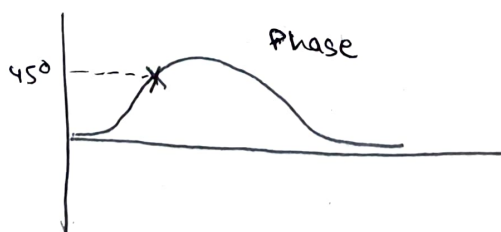
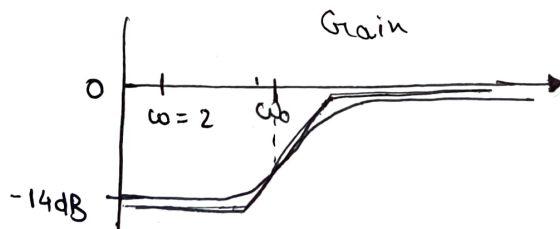
$$\text{gain}(s-2) = 20 \left(\frac{s}{2} - 1 \right) = \frac{20}{\frac{s}{2} - 1} = \frac{-20}{1 + \left(\frac{s}{-2} \right)} = \text{gain}(-2) - \text{gain of } \left(\frac{1}{1 + \left(\frac{s}{-2} \right)} \right)$$

$$\text{gain}(s+10) = \frac{10}{1 + \left(\frac{s}{10} \right)}$$

$$= \text{gain of } 10 - \text{gain of } \left(\frac{1}{1 + \frac{s}{10}} \right)$$

$$\left. \begin{array}{l} \text{gain}(-2) = 6 \text{ dB} \\ \text{gain}(+10) = 20 \text{ dB} \end{array} \right\} \text{CONSTANT}$$

Adding the gain plots $\forall \omega$ we get



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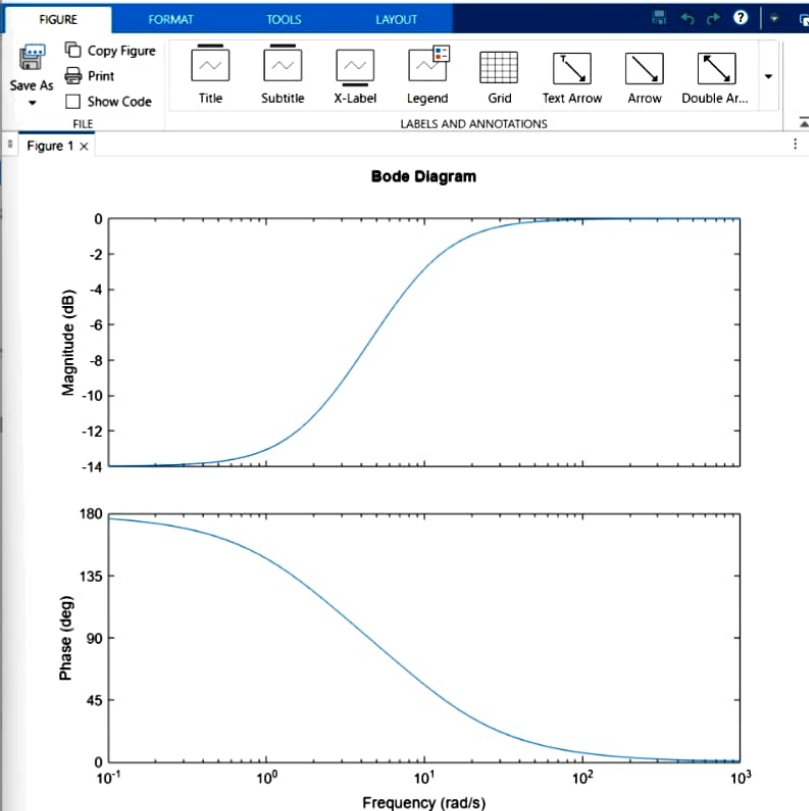
```
>> G2=tf([1 -2], [1 10])

G2 =

    s - 2
    -----
    s + 10

Continuous-time transfer function.
Model Properties
>> bode(G2)
>>
>>
>>
>> bode(G2)
>>
```

W... :
Name
G2



(1.3)

$$G_3(s) = \frac{100}{s^2 + 10s + 100}$$

(1)

$$\text{Pole: } s = 5 \pm 5\sqrt{3}j$$

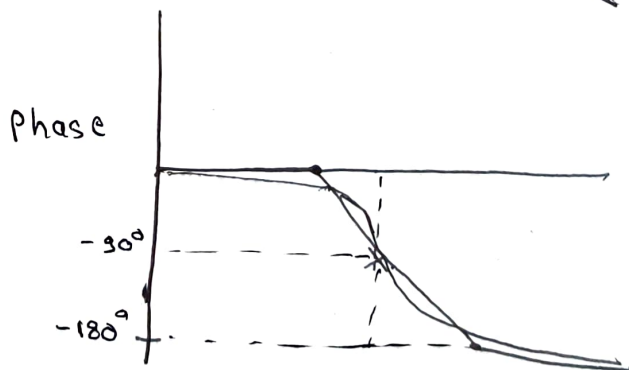
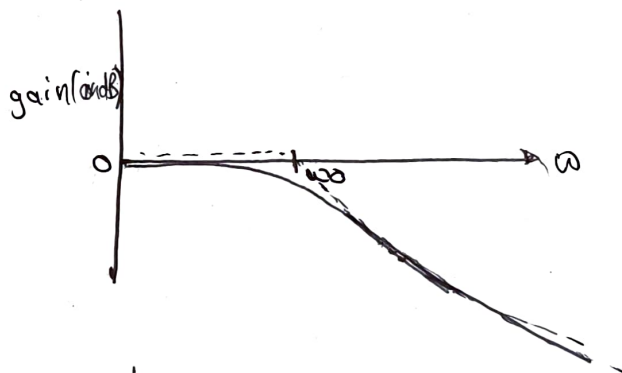
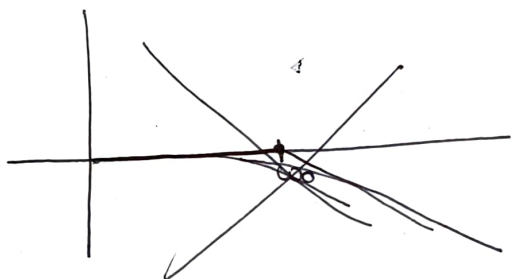
$$j = \sqrt{-1}$$

(2) BODE PLOT

$$G(s) = \frac{\omega_0^2}{s^2 + 2z\omega_0 s + \omega_0^2}$$

$$\omega_0 = 10, 2z\omega_0 = 10 \Rightarrow z = \frac{1}{2}$$

When $z = 0.5$, for $\omega = \omega_0$ gain = 0



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```
>> bode(G3)
>> G4=tf([0.1 1], [.01 1])

G4 =

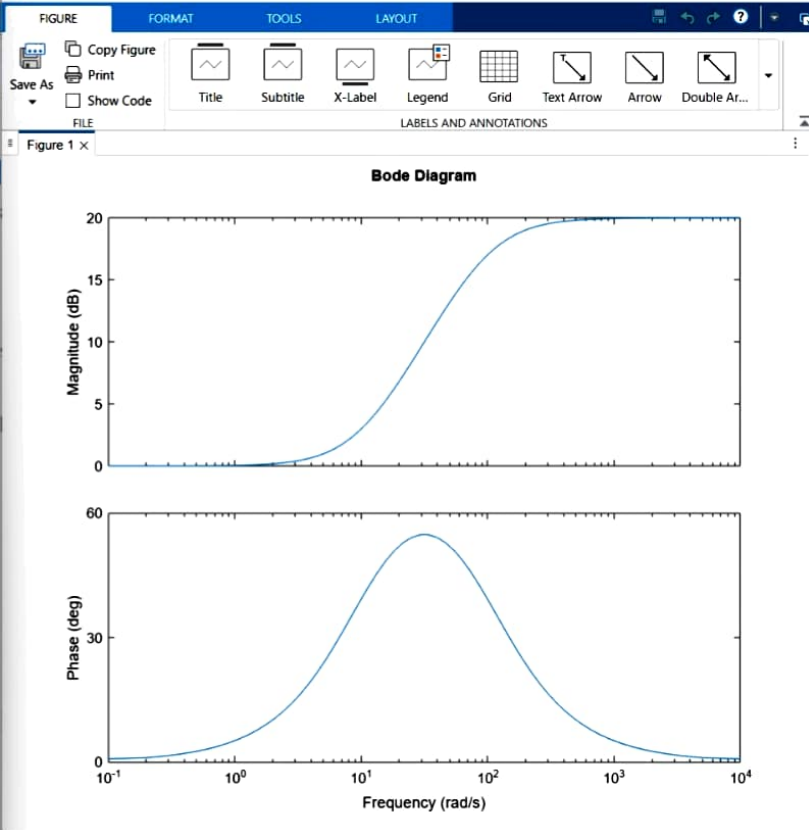
    0.1 s + 1
    -----
    0.01 s + 1

Continuous-time transfer function.
Model Properties
>> bode(G4)
>>
```

W...

Name

G3 G4

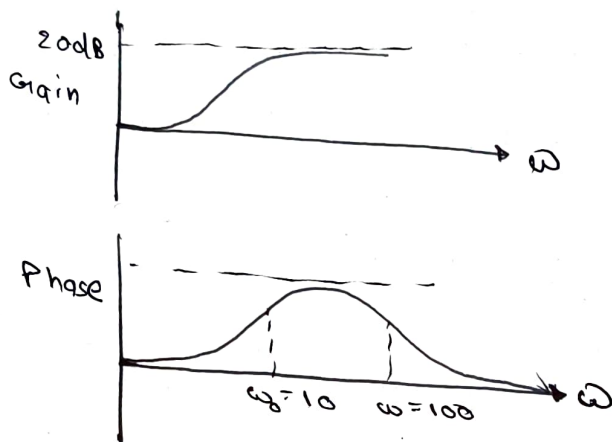


(1.4) $G_4(s) = \frac{0.1s + 1}{0.01s + 1}$

(1) zero at $s = -10$

Pole at $s = -100$

(2) Gain $\Rightarrow \text{gain} \left(1 + \frac{s}{10} \right) = \text{gain} \left(1 + \frac{s}{100} \right)$



(4) Zero is at $\omega = 10$

Pole at $\omega = 100$

\therefore Between zero and pole $G_4(s)$ tends to add positive phase as seen from the plots.

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Command Window

```
>> G2=tf([1 -2], [1 10])

G2 =

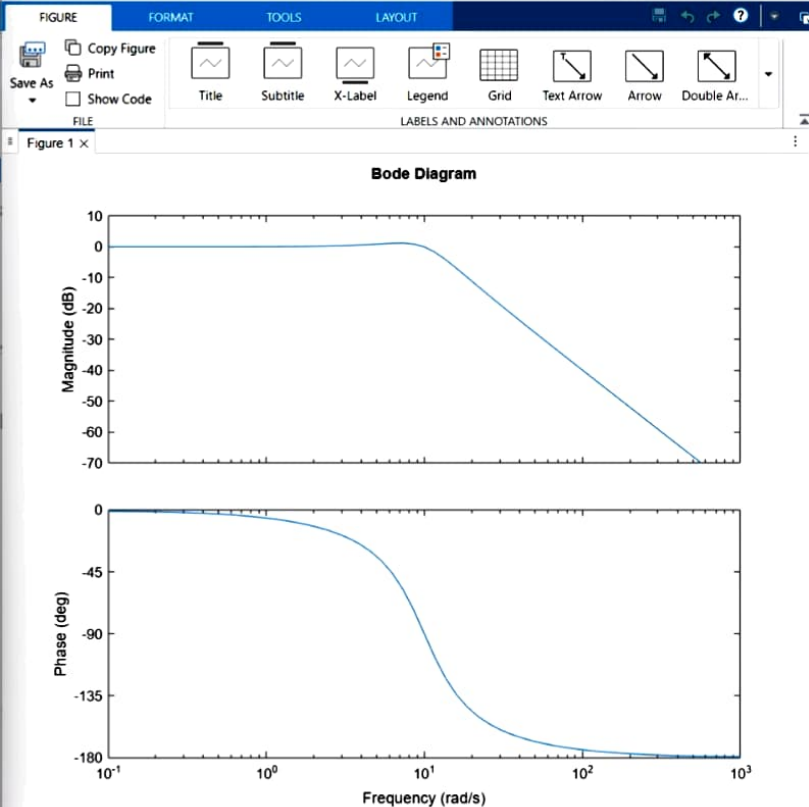
    s - 2
    -----
    s + 10

Continuous-time transfer function.
Model Properties
>> bode(G2)
>>
>>
>> bode(G2)
>> G3=tf([100], [1 10 100])

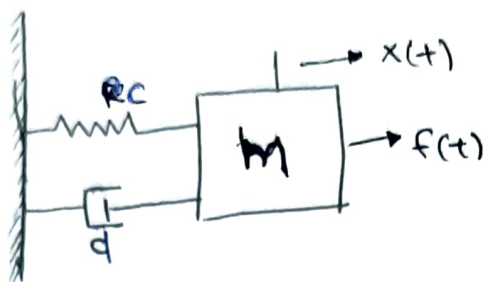
G3 =

    100
    -----
    s^2 + 10 s + 100

Continuous-time transfer function.
Model Properties
>> bode(G3)
>> |
```



B.1)



The force to spring is directly proportional to $x(t)$ while force of Damper is proportional to velocity of mass m .

$$\Rightarrow \boxed{f(t) - c \dot{x}(t) - d \frac{dx(t)}{dt} = m \frac{d^2x}{dt^2}}$$

$$\boxed{F(s) = c X(s) + d s X(s) + m s^2 X(s)}$$

$$F(s) = X(s) [c + d s + m s^2]$$

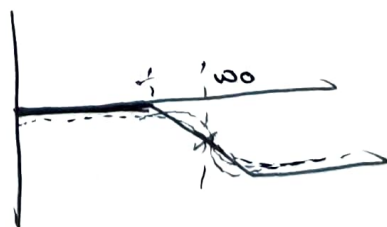
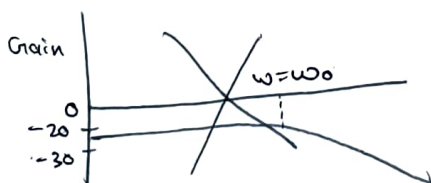
$$G(s) = \frac{X(s)}{F(s)}$$

$$\boxed{G(s) = \frac{1}{[c + d s + m s^2]}}$$

B.2)

$$\boxed{G(s) = \frac{1}{[16 + 4s + s^2]}}$$

Pole: $s = -2 \pm 2\sqrt{3}i$



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Command Window

```
>> G5=([1],[1 4 16])
G5=([1],[1 4 16])
      ↑
Error: Unexpected ', ' in parentheses. When creating a matrix, use square brackets [].
```

Explain Error

```
>> G5=tf([1],[1 4 16])
```

G5 =

$$\frac{1}{s^2 + 4s + 16}$$

Continuous-time transfer function.

Model Properties

```
>> bode(G5)
```

```
>>
```

