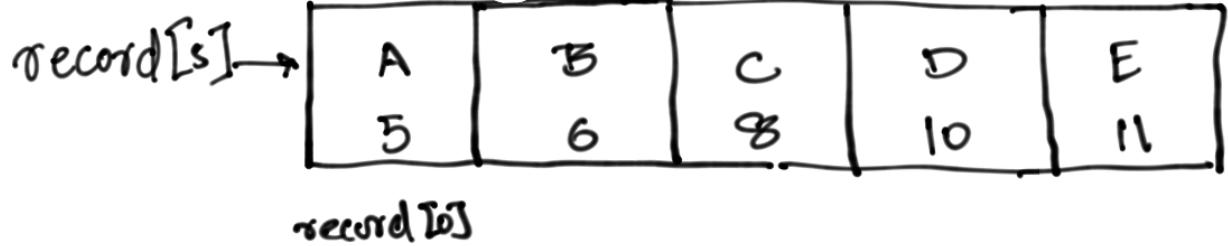


Data - Structure Question

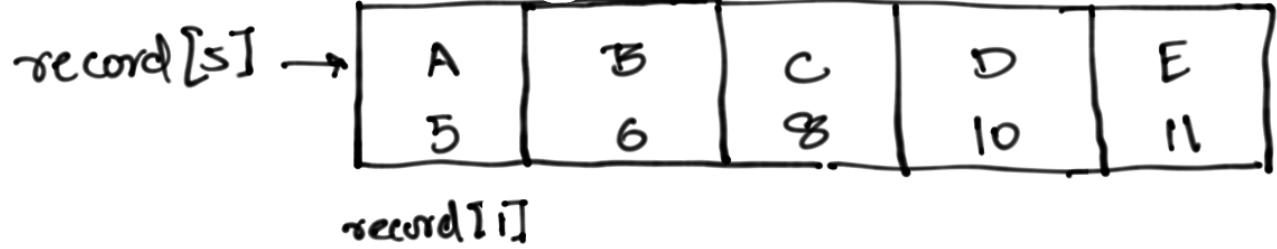
- (1) Assume that you are the owner of a company that has 5 employees.
- (2) Each employee is represented by { name, salary }

Which data-structure (that you know) will you use to represent these 5 employees?

Arrays



Arrays



Suppose a new employee {F, 10} joins the company. How will you update your data-structure?

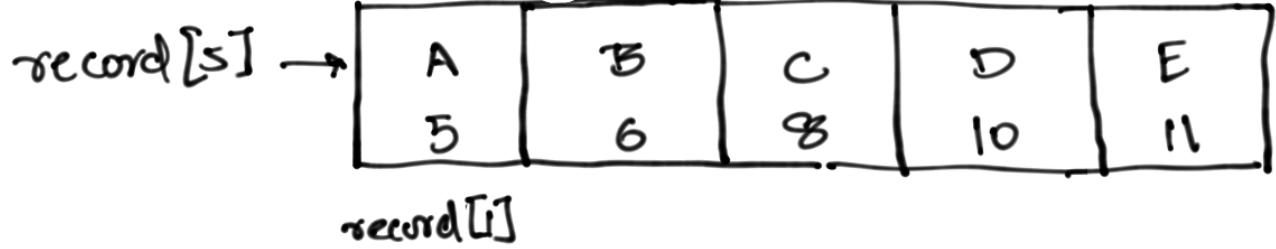
Arrays



Suppose a new employee {F, 10} joins the company. How will you update your data-structure?

↳ Add {F, 10} @ record[6]

Arrays



Suppose a new employee {F, 10} joins the company. How will you update your data-structure?

- ▲ Add {F, 10} @ record[6]
- :(But record[6] does not exists. The array record is of size 5 only.

Now what will you do?

- (1) Make a new array newrecord of size 6
- (2) Copy the five records from record to newrecord.
- (3) Add {F, 10} @ newrecord[6]

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Q: What is the running time of this procedure?

A : $O(n)$ if there are n records in record array.

When an employee leaves

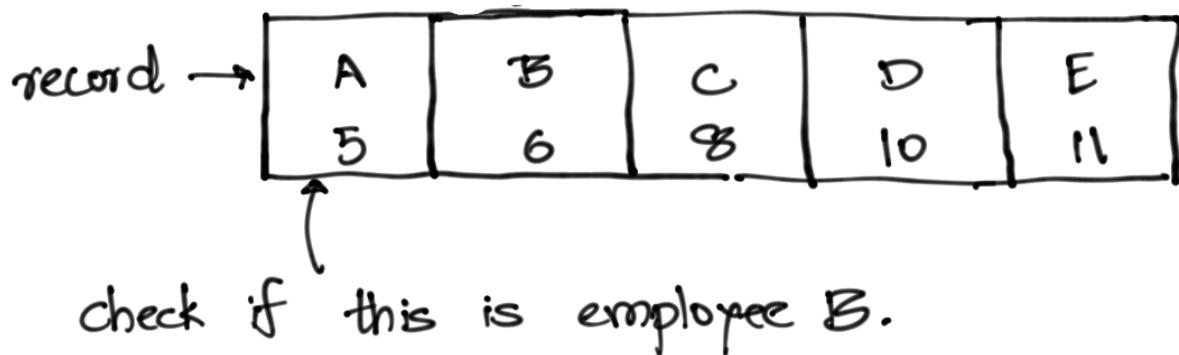
Suppose employee B leaves, so we have to remove the record of employee B.

Q: How would you do that?

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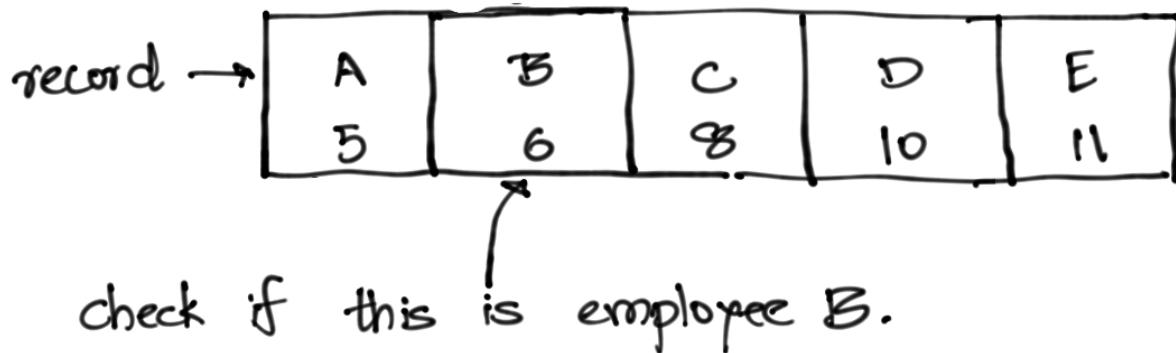
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When an employee leaves

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Q: How would you do that?

record →

| | | | | |
|---|---|---|----|----|
| A | B | C | D | E |
| 5 | 6 | 8 | 10 | 11 |

check if this is employee B.

record →

| | | | | |
|---|--|---|----|----|
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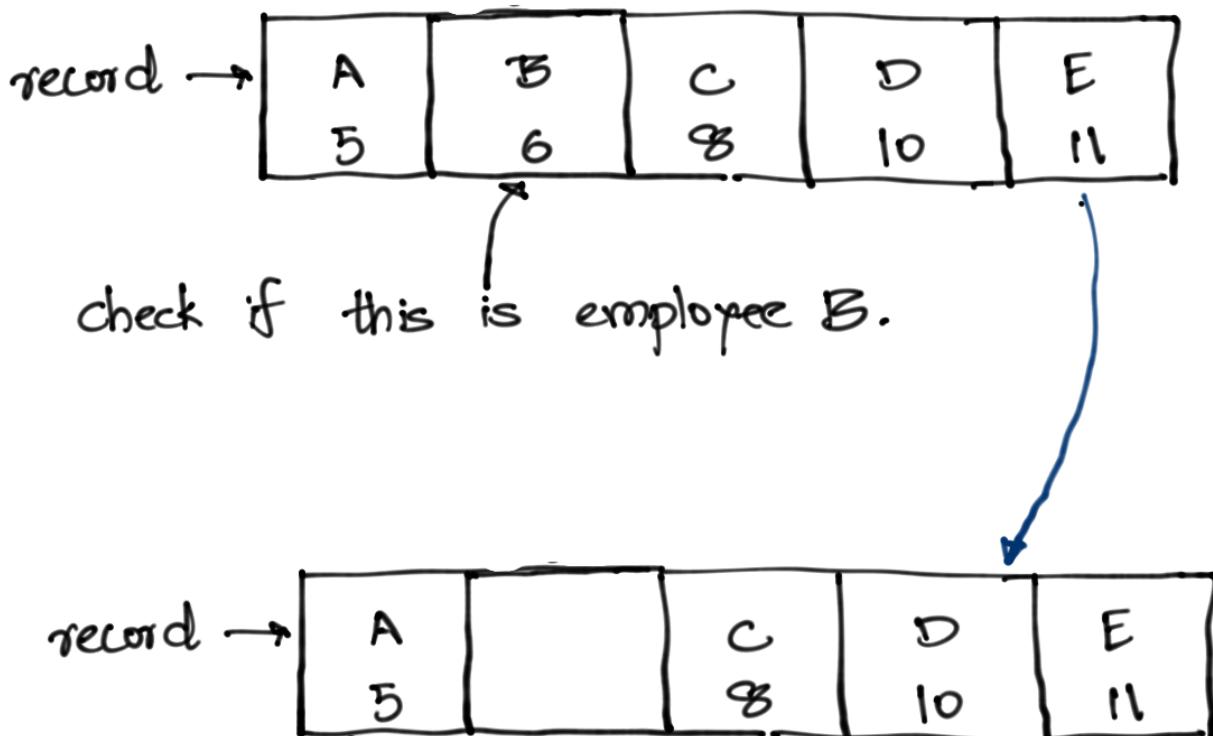
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When an employee leaves

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Q: What is the running time of this method?

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- (2) The time taken to search an employee will not be proportional to the # employees.

| | | | | |
|---|--|--|--|----|
| A | | | | E |
| 5 | | | | 11 |

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| | | | | |
|---|--|--|--|----|
| A | | | | E |
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Holy Grail for data-structure

The space taken by your data-structure should be proportional to the number of current employees in the company.

Performance of Arrays.

| | |
|----------|--------|
| Insert | $O(n)$ |
| Deletion | $O(n)$ |
| Search | |

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So, array nearly always give worst case performance.

Q: Where are arrays good ?

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A : Give me the 5th element of record array.

return record[5]

Running Time = ??

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A : Give me the 5th element of record array.

return record[5]

Running Time = $O(1)$.

Performance of Arrays.

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There is a simple data-structure which solves this problem.

Mimics arrays.

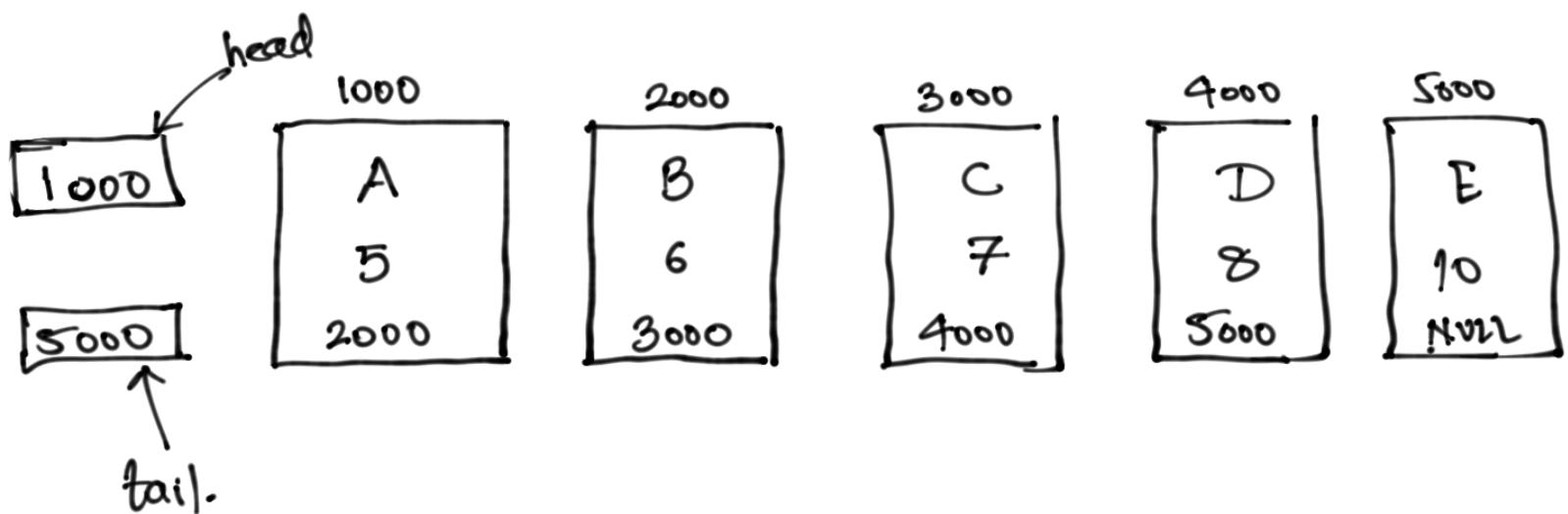
Holy Grail for data-structure

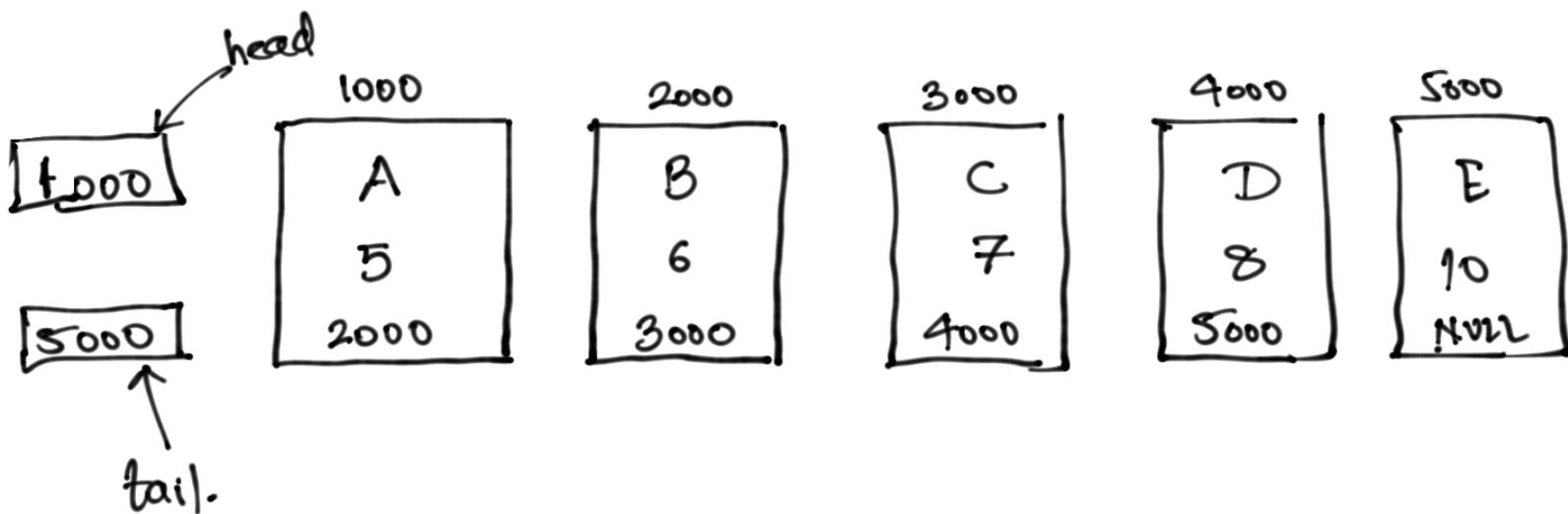
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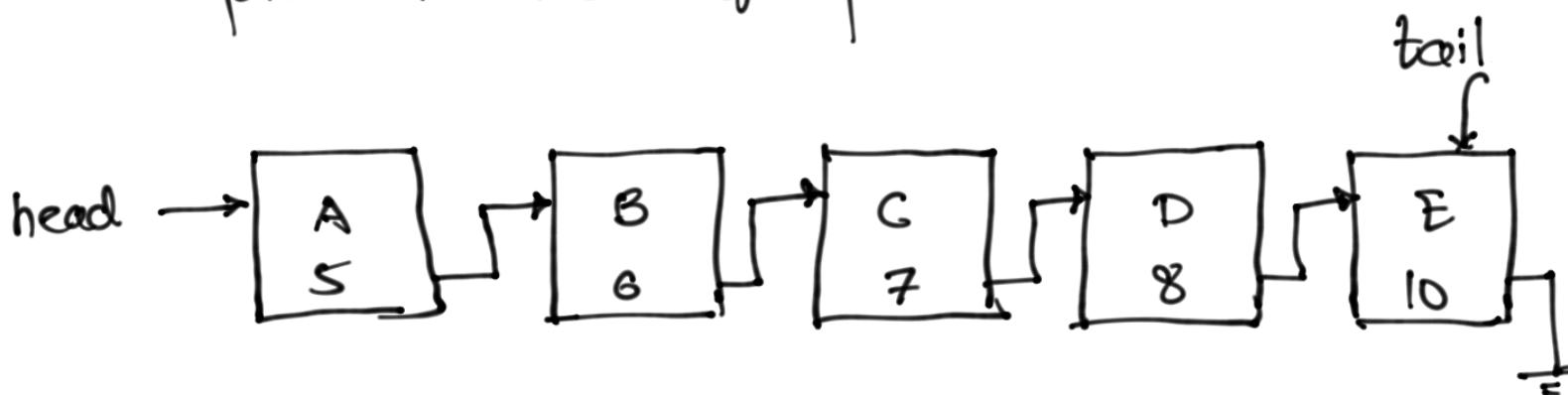
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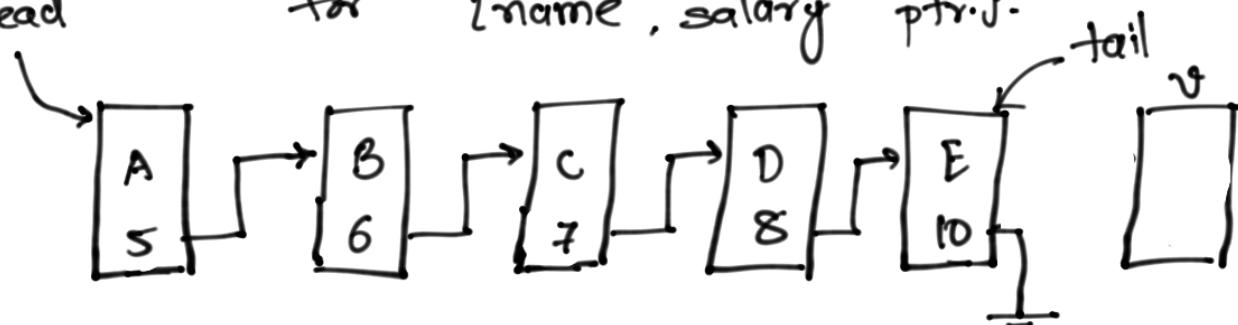
However, we will have a simpler pictorial view of pointers.



Insert {F, 10}.

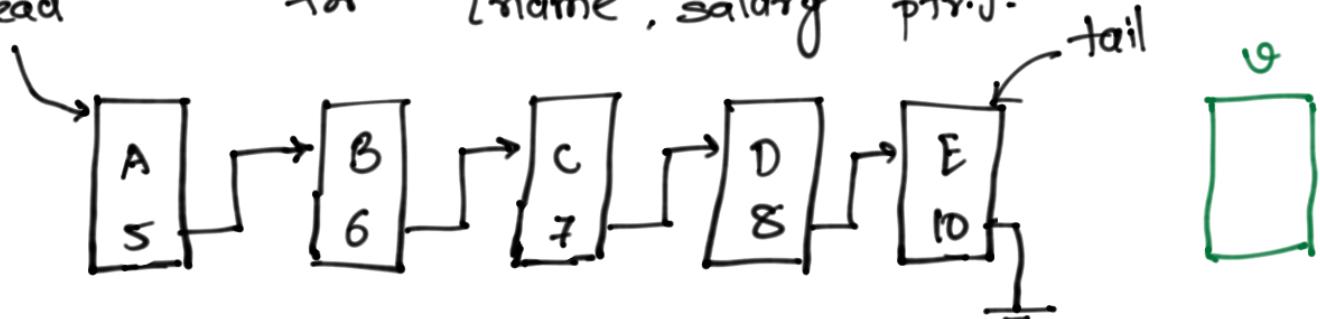
Insert {F, 10}.

- ① $v \leftarrow$ Request the OS to allocate enough space
head for {name, salary ptr.}.

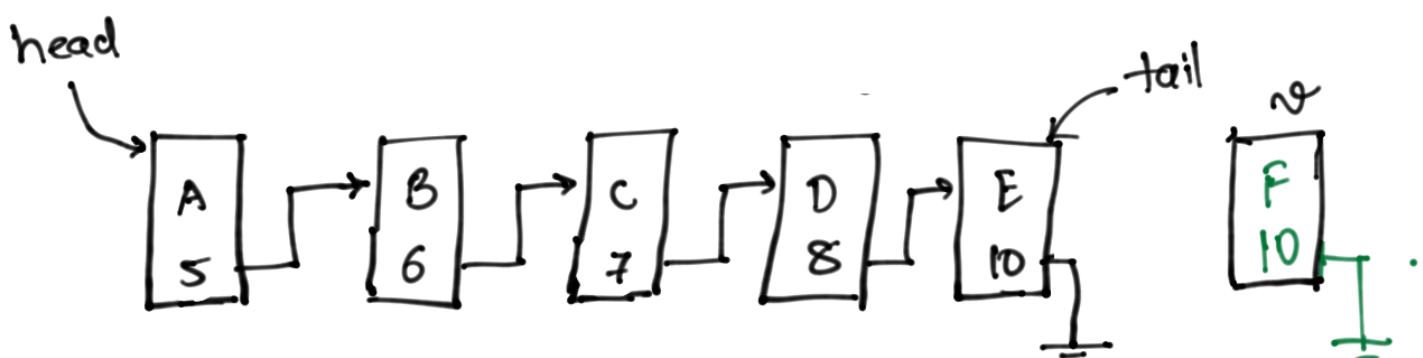


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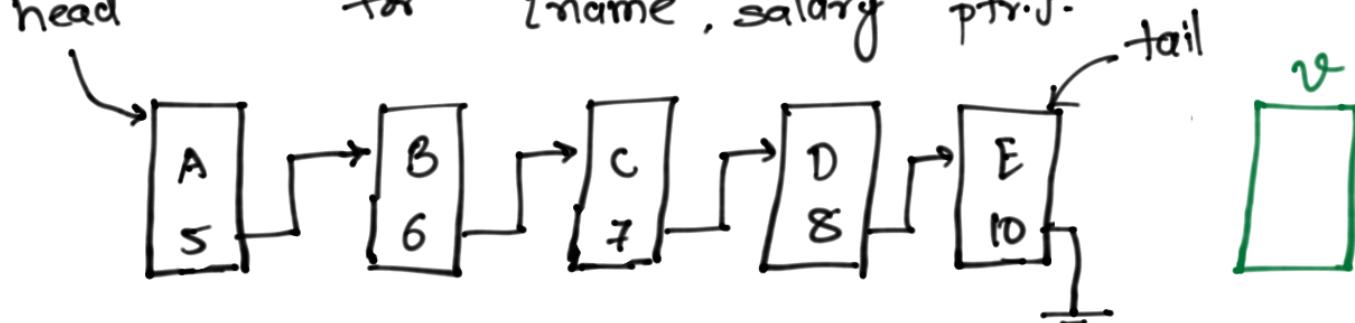


- ② $v.name \leftarrow F;$
 $v.salary \leftarrow 10;$
 $v.ptr \leftarrow \text{NULL}$

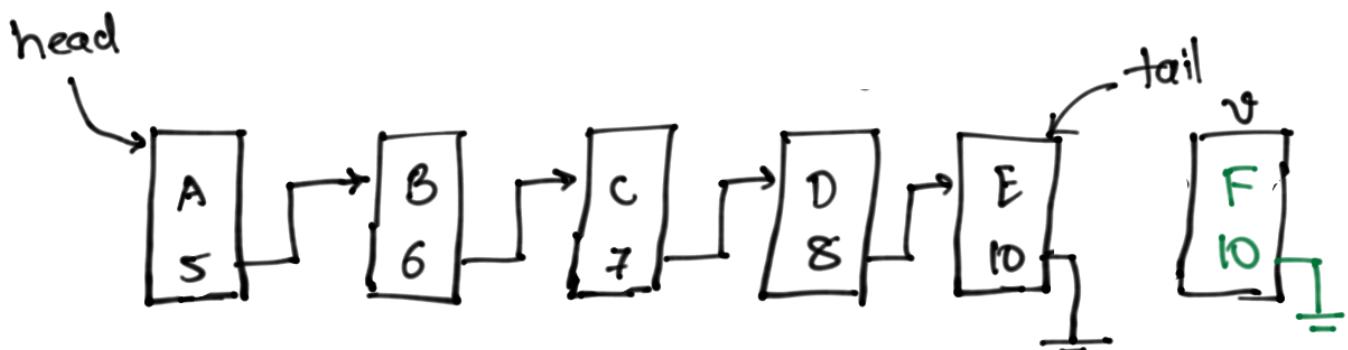


Insert {F, 10}.

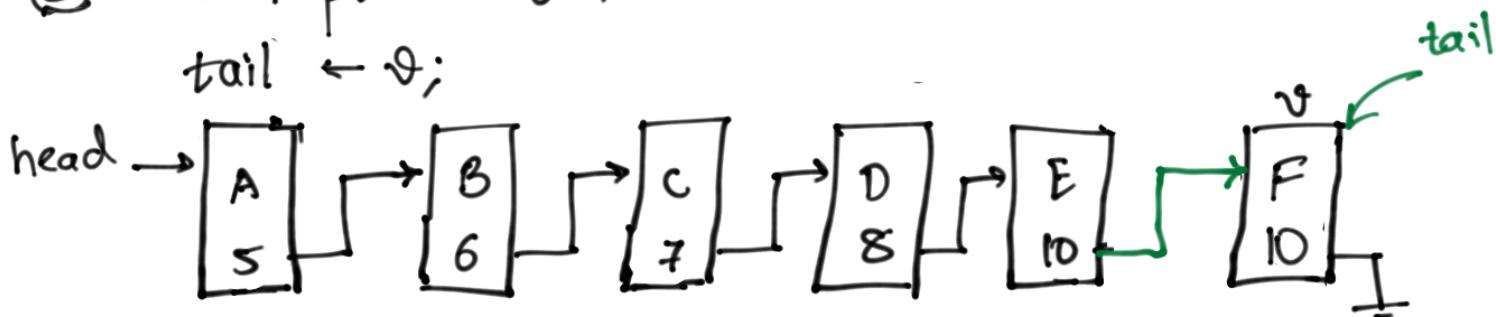
- ① $v \leftarrow$ Request the OS to allocate enough space
for {name, salary ptr.}.



- ② $v.\text{name} \leftarrow F;$
 $v.\text{salary} \leftarrow 10;$
 $v.\text{ptr} \leftarrow \text{NULL}$



- ③ $\text{tail.ptr} \leftarrow v;$
 $\text{tail} \leftarrow v;$



Insert (name, salary)
{

v ← allocate me a new memory location;
v.name ← name;
v.salary ← salary;
v.ptr ← NULL;

if (head is null).

{

Insert (name, salary)
{

v \leftarrow allocate me a new memory location ;

v. name \leftarrow name ;

v. salary \leftarrow salary ;

v. ptr \leftarrow NULL ;

if (head is NULL). // list is empty

{

head \leftarrow v ;

tail \leftarrow v ;

}

else

{

```
Insert (name, salary)
{
```

```
    v ← allocate me a new memory location;
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    v.name ← name;
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```
{
```

```
    head ← v;
```

```
    tail ← v;
```

```
}
```

```
else
```

```
{
```

```
    tail.ptr ← v;
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```
    tail ← v;
```

```
}
```

```
}
```

Q: What is the running time of this procedure?

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{
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```

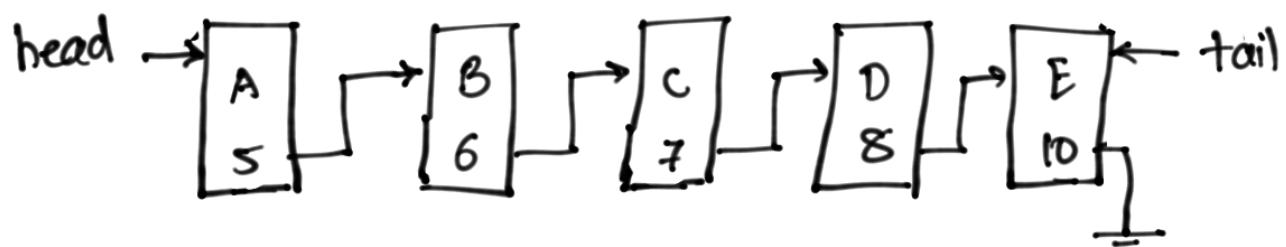
```
}
```

```
}
```

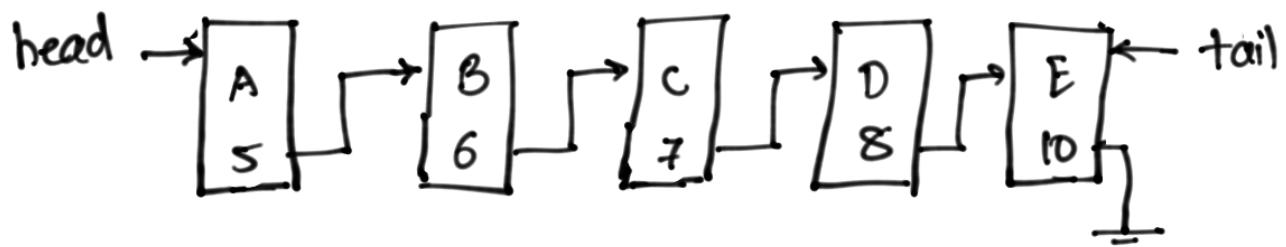
Q: What is the running time of this procedure?

A: O(1).

delete Employee C

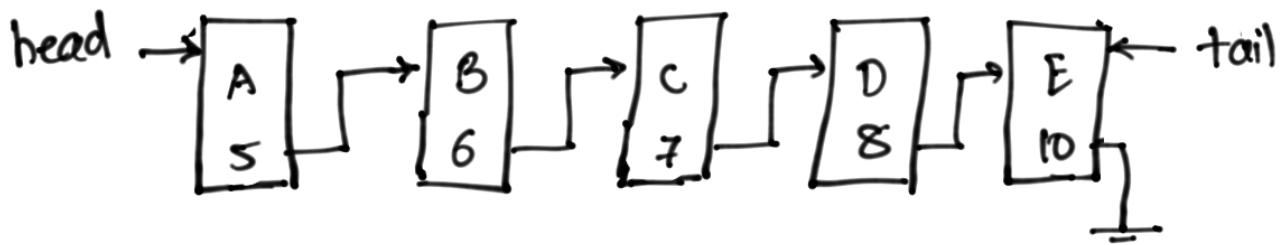


delete Employee C

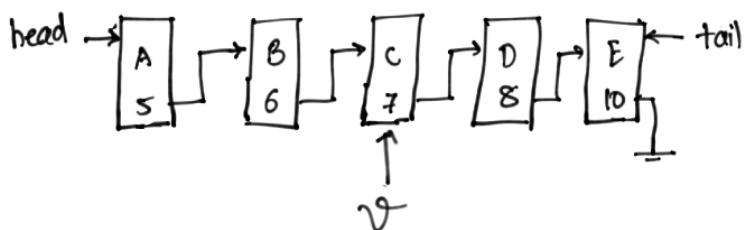
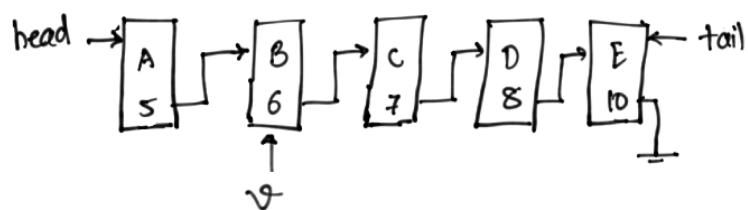
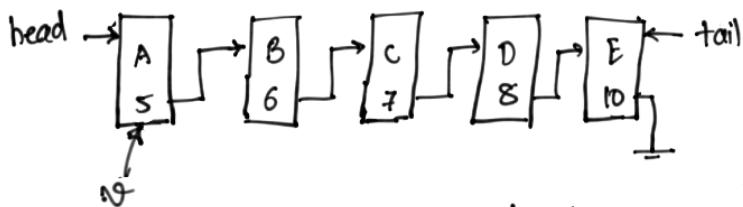


① $v \leftarrow \text{head}$ (start with the head).

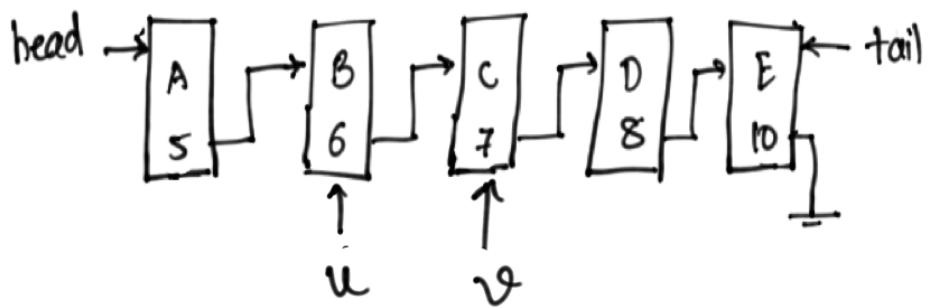
delete Employee C



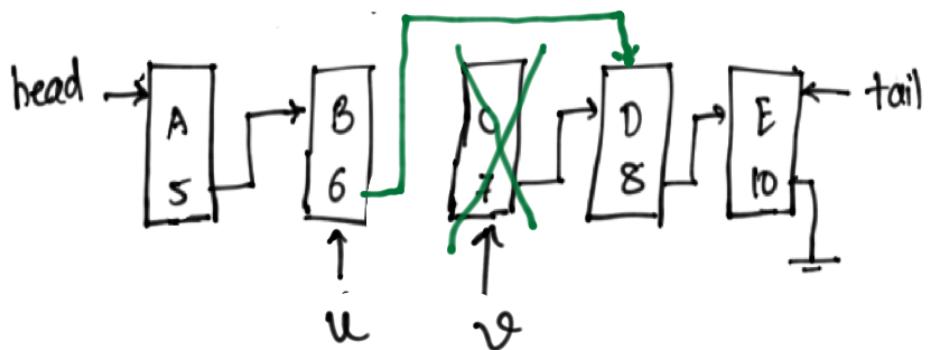
- ① $v \leftarrow \text{head}$ (start with the head).
- ② Move through the list (using pointers) till you hit employee C



③ Maintain a ptr that follows v, say u.



④ $u.\text{ptr} \leftarrow v.\text{ptr}$
deallocate the memory associated with
recor



```
Delete( name)
{
    if ( head is NULL)
        return;
```

Delete(name)

{

if (head is NULL)

return;

if (

{

}

else

{ v ← head.ptr

u ← head;

while (v is not NULL)

{

if (v.name = name)

{ u.ptr ← v.ptr

deallocate the memory allocated
to record v;

}

else

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} v ← v.ptr

}

}

Delete(name)

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Q: What is the running time of
Delete(.)

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Delete(·)

A $\Theta(n)$

Performance of Linked List

Insert

$O(1)$

Delete

$O(n)$

Search

?!

Performance of Linked List

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$O(1)$

Delete

$O(n)$

Search

$O(n)$

Performance of Linked List

| | |
|--------|--------|
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But the most important thing:
Holy Grail for data-structure

The space taken by your data-structure
should be proportional to the number
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Q: When is linked list worse than arrays?

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Query : Get me k^{th} record.

Time taken by linked list = ?!

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| Search | $O(n)$ |
| Get the k^{th} element | $O(1)$. |

Performance of Linked List

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| Search | $O(n)$ |
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Balanced Parenthesis

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int main()
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    for(i=0; i<n; i++)
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        printf ("Hello World");
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The compiler does a lot of things out of which one thing is check if the parenthesis are balanced.

Q: What is a balanced parenthesis?

Balanced Parenthesis

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The compiler does a lot of things out of which one thing is check if the parenthesis are balanced.

Q: What is a balanced parenthesis?

- (1) Each opening symbol has a corresponding closed symbol.
- (2) Parenthesis are properly nested.

Examples

(1) { } ()

(2) (({ }))

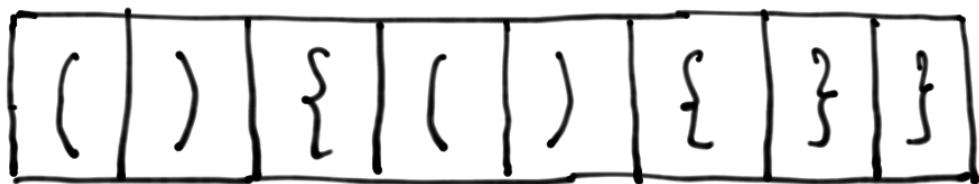
(3) (({ }))

Examples

- (1) $\{ \} ()$
- (2) $((\{) \})$
- (3) $((\{ \}))$

Q: Given a string of '{', '}', '(', ')', find if it is balanced.

What will be your algorithm?

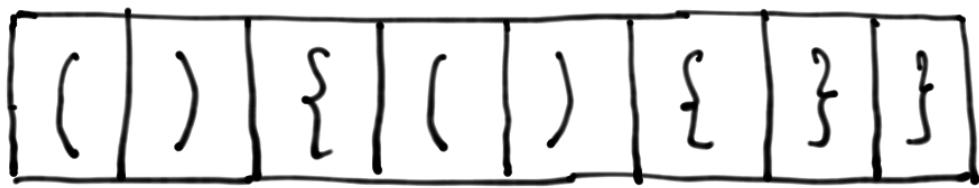


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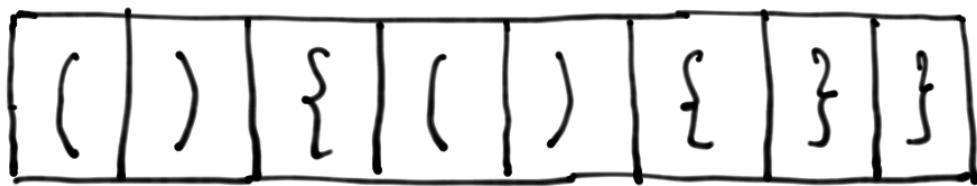
↑
find the first
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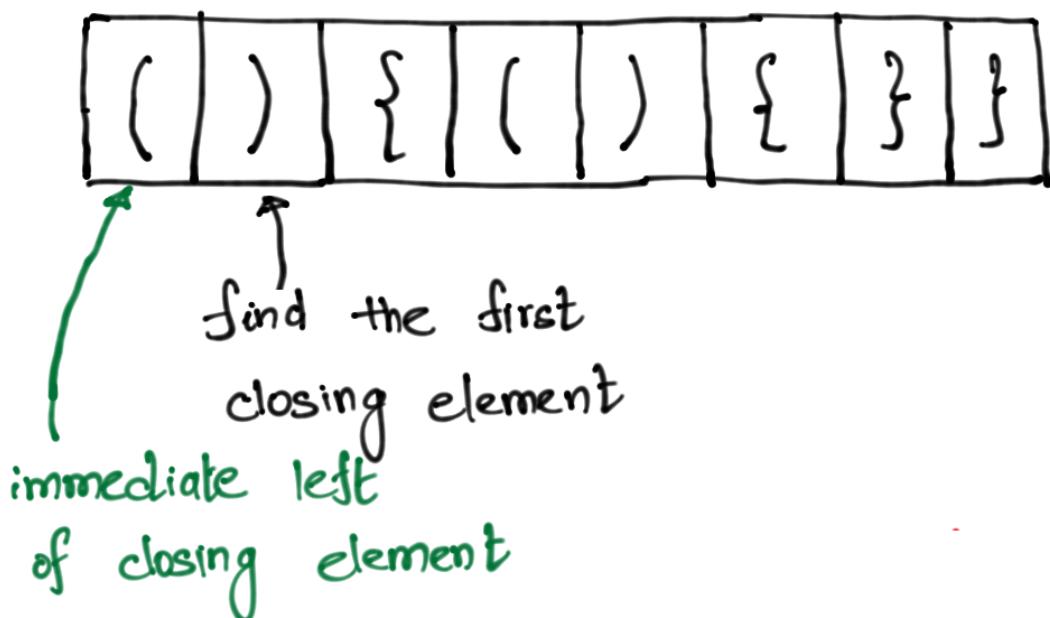
Q: Where will the corresponding opening element lie?

Examples

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Examples

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{ } ()

(2)

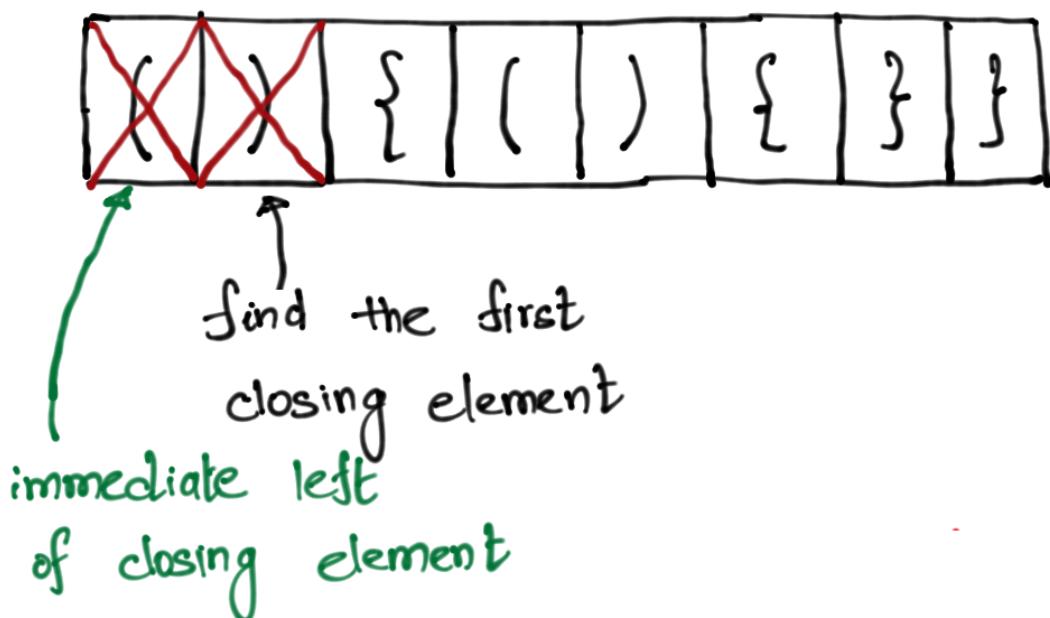
(({}}))

(3)

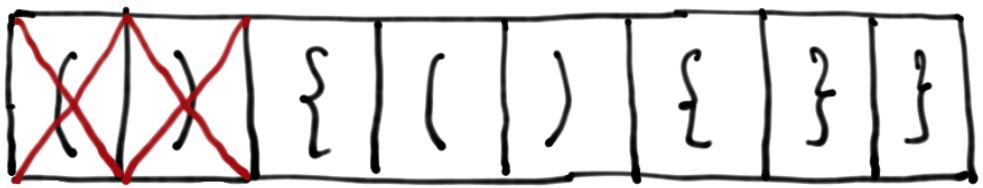
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What will be your algorithm?



Delete these two elements



Repeat till all the elements are deleted

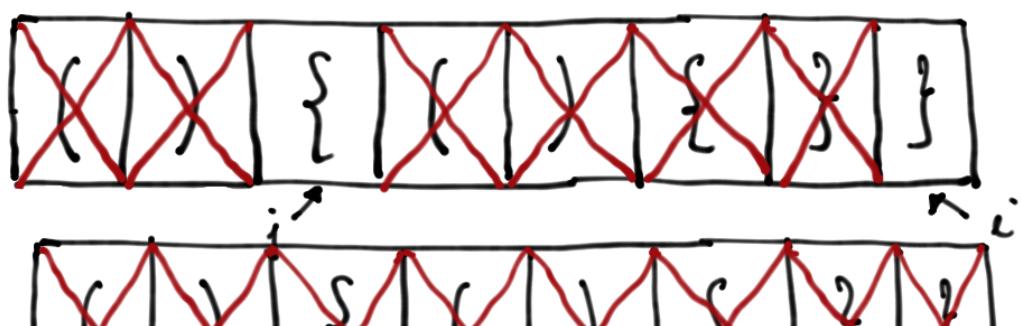
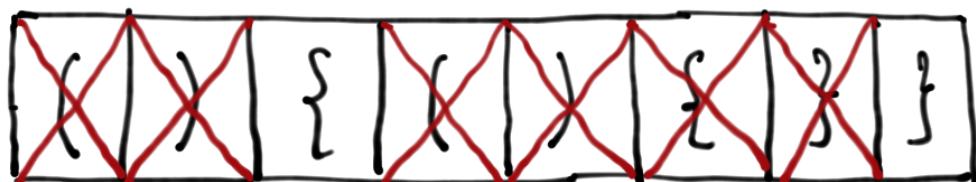
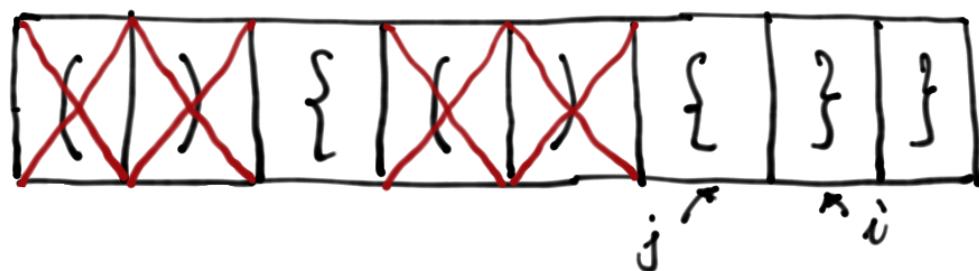
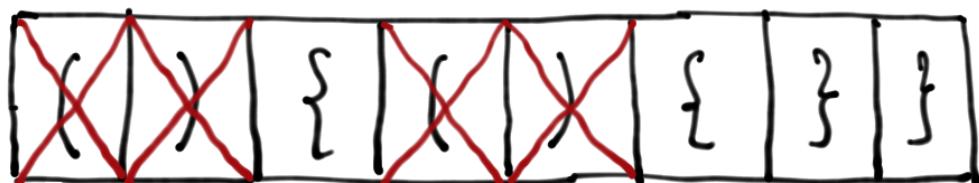
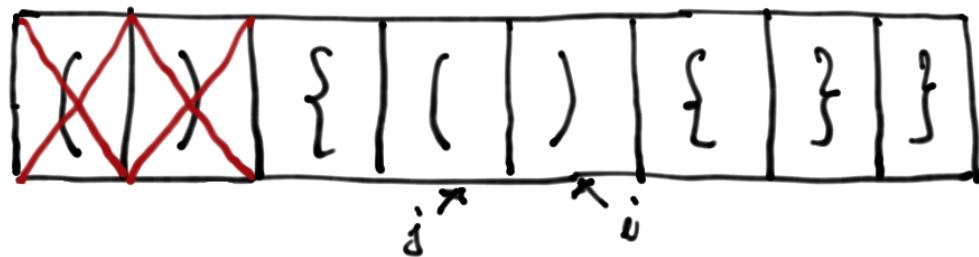
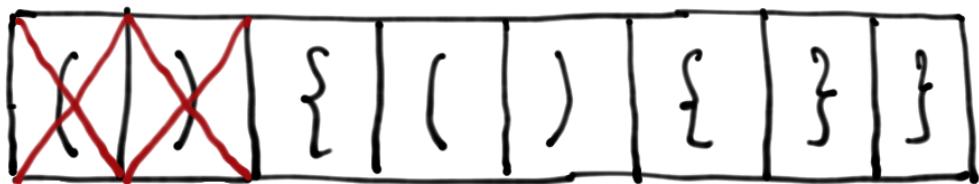
- (1) Find the first closing element, say at location i.

(2)

| | | | | | | | |
|--------------|--------------|---|---|---|---|---|---|
| (|) | { | (|) | { | } | { |
|--------------|--------------|---|---|---|---|---|---|

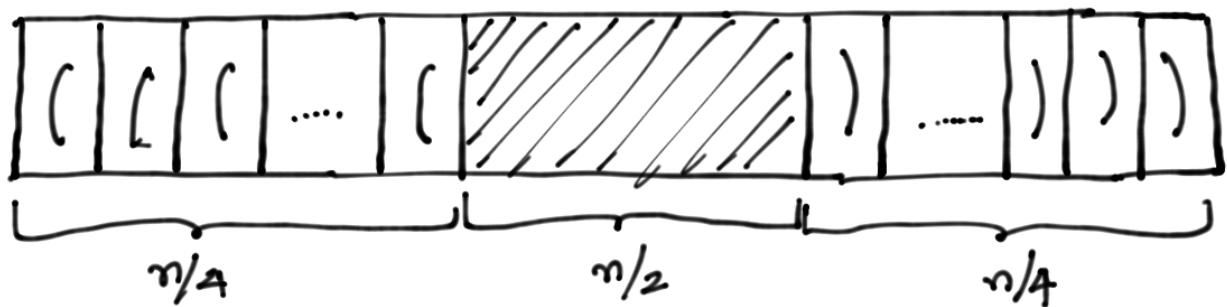
Repeat till all elements are deleted

- (1) Find the first closing element, say at location i .
- (2) Let j be the first non-deleted location to the left of i .
- (3) If the closing element does not match with opening element, then report that string is not balanced.

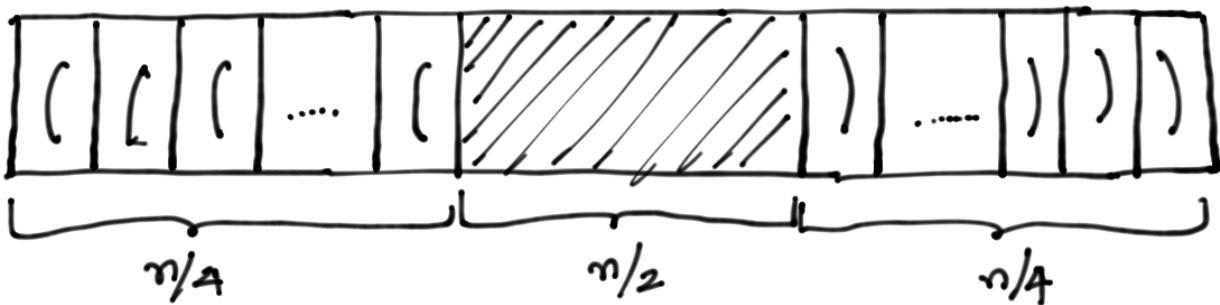


Q: What is the worst case running time
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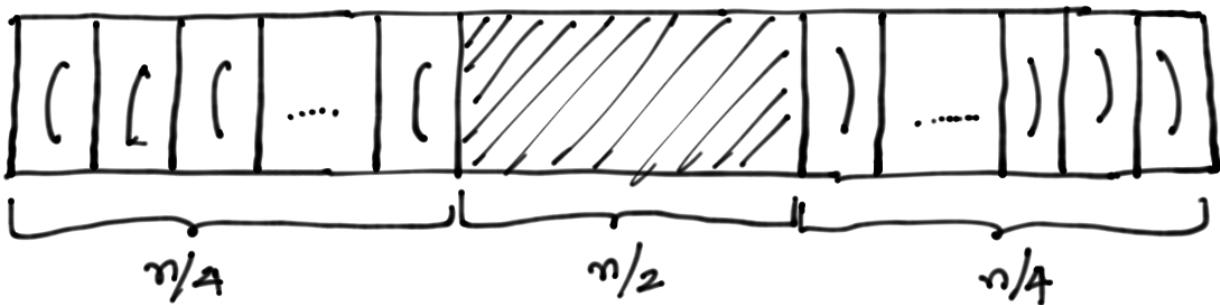


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For each closing parenthesis on the right, we travel $\geq \frac{n}{2}$ deleted elements.

Q: What is the worst case running time of this algorithm?



For each closing parenthesis on the right, we travel $\geq \frac{n}{2}$ deleted elements.

\Rightarrow Total number of steps in the algorithm $\geq \frac{n}{4} \times \frac{n}{2} = \frac{n^2}{8}$

\Rightarrow Running time = $O(n^2)$.

// Input: S is an array of strings

while (S contains a closing element).

{

 let i be the location of first closing
 element.

 let j ← be the first non-empty location
 to the left of i

 if (S[j] f S[i] are of some type)
 remove S[i] f S[j]

 else

 { print ("Not balanced");
 return;

 }

}

// Input: S is an array of strings

while (S contains a closing element).

{

 let i be the location of first closing
 element.

 let j ← be the first non-empty location
 to the left of i

 if (S[j] & S[i] are of same type)
 remove S[i] & S[j]

else

 {
 print ("Not balanced");
 return;

}

}

if (S contains non-deleted element).

 {
 print ("Not balanced");
 return;

}

print ("Balanced");

return;

// Input: S is an array of strings

O(n) → while (S contains a closing element).
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 element.

O(n) → let j ← be the first non-empty location
 to the left of i

 if (s[j] & s[i] are of some type)
 remove s[i] & s[j]

 else

 { print ("Not balanced");
 return;

 }

}

 if (S contains non-deleted element).

 { print ("Not balanced");
 return;

 }

print ("Balanced");
return;

Q: Can you do better? May be $O(n)$.

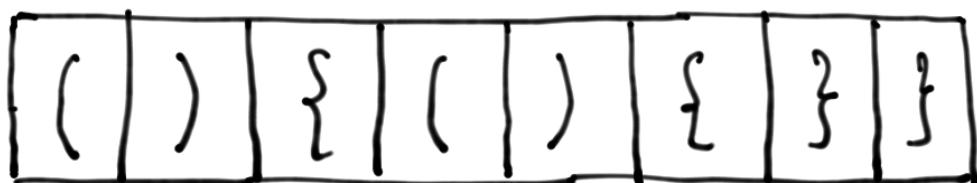
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Q: Given a closing element i , can we find the corresponding location i in $O(1)$ time?

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& Use another data-structure.

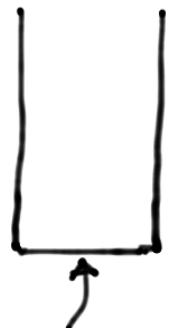
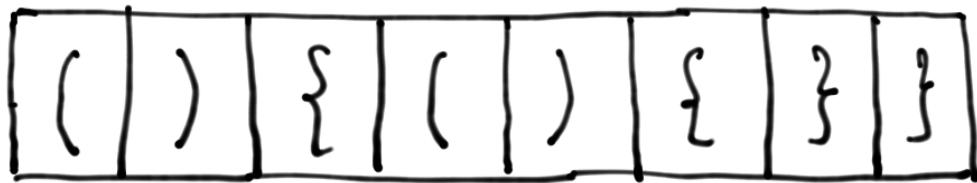


Opening elements
as seen in the
array

Q: Can you do better? May be $O(n)$.

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& Use another data-structure.

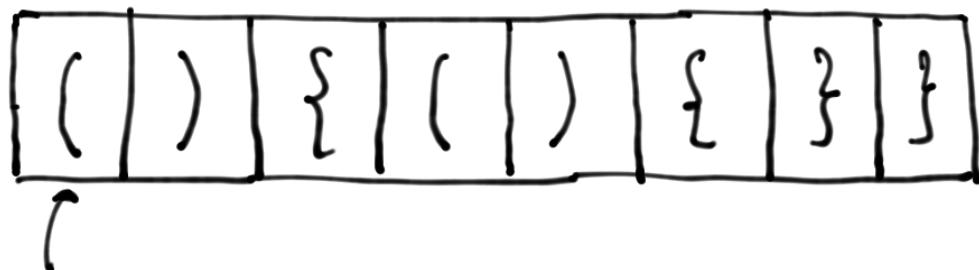


"Non deleted" Opening elements
as seen in the
array

Q: Can you do better? May be $O(n)$.

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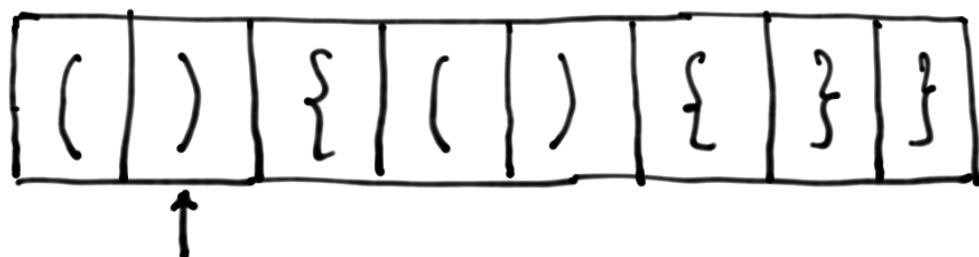
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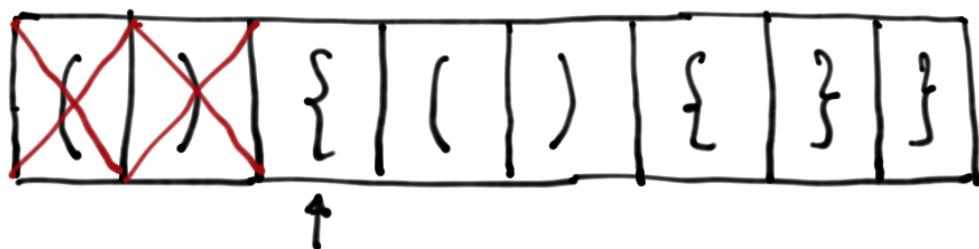
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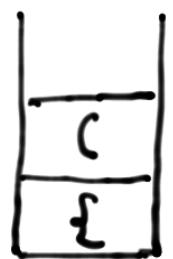
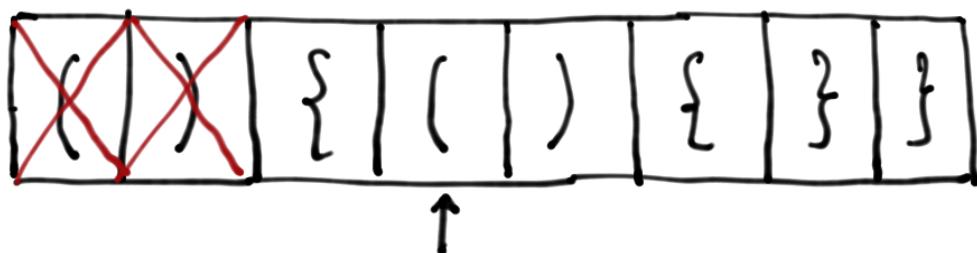
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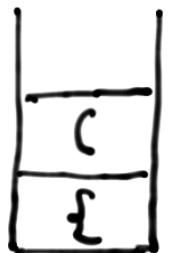
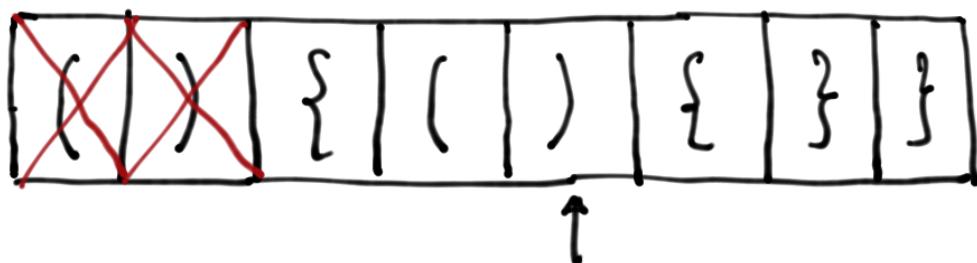
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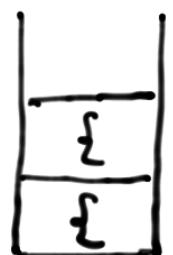
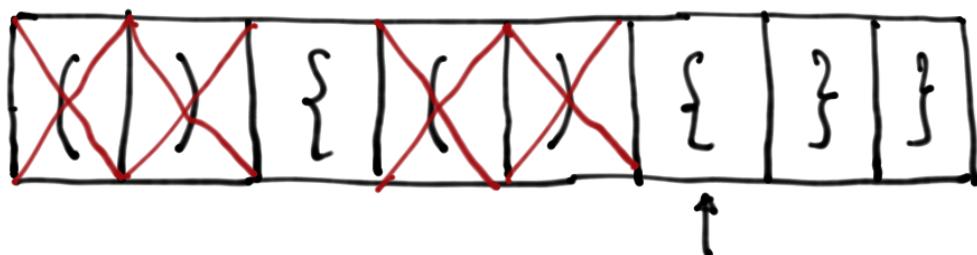
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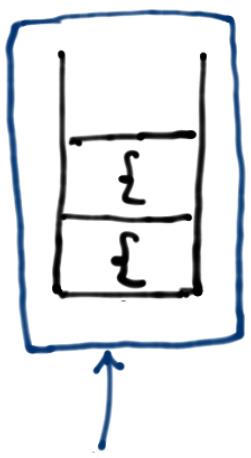
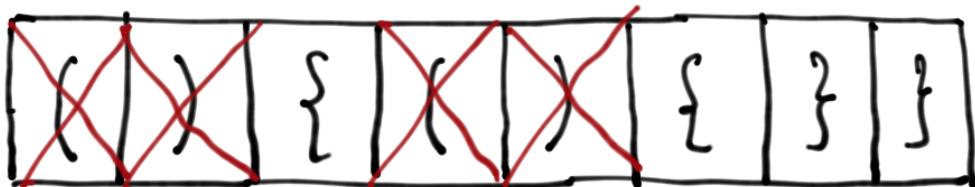
& Use another data-structure.



Q: Can you do better? May be $O(n)$.

Q: Given a closing element i , can we find the corresponding location i in $O(1)$ time?

& Use another data-structure.



Stack

Following important observation about stack.

- (1) The last element inserted onto stack is the first element removed.
(Last In First Out) LIFO.

- (2) Two operations :

Push (element e)

Pop()

Q: How would you implement Stack?

Q: How would you implement Stack?

- (1) Using Arrays
- (2) Using Lists.

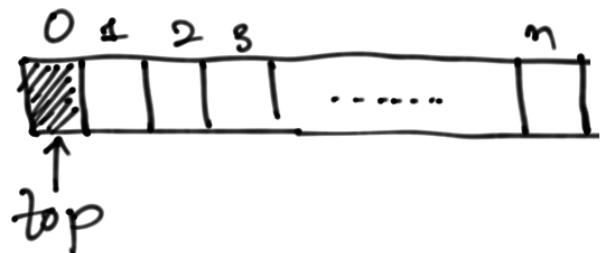
Using Arrays : $A[1 \dots n]$

Create-Empty()

{

} $\text{top} \leftarrow 0;$

represents the topmost element
in the stack.



Push(a)

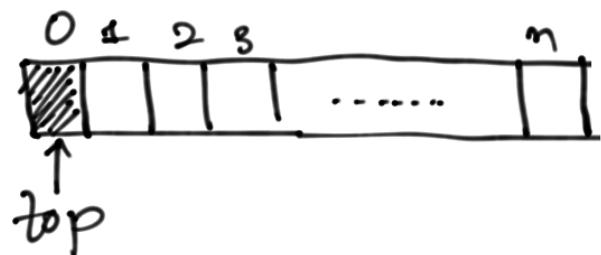
Using Arrays : $A[1 \dots n]$

Create-Empty()

{

} $\text{top} \leftarrow 0;$

represents the topmost element
in the stack.



Push(a)

{ if (top < n)

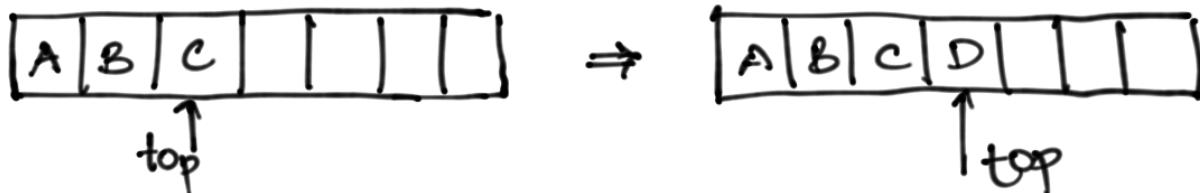
{

$\text{top} \leftarrow \text{top} + 1;$
 $A[\text{top}] \leftarrow a$

}

else print ("stack full")

}



Pop()

```
Pop()
{   if ( top = 0 )
    print "Stack Empty"
else
{   a ← A[top];
    top ← top-1;
    return a;
}
}
```

What is the running time of push & pop procedure?

```
Pop()
{ if ( top = 0 )
    print "Stack Empty"
else
{ a ← A[top];
  top ← top-1;
  return a;
}
}
```

What is the running time of push & pop procedure?

A O(1).

```

Pop()
{
    if ( top = 0 )
        print "Stack Empty"
    else
    {
        a ← A[top];
        top ← top - 1;
        return a;
    }
}

```

What is the running time of push & pop procedure?

A O(1).

Q: What is the problem with this implementation?

```

Pop()
{
    if ( top = 0 )
        print "Stack Empty"
    else
    {
        a ← A[top];
        top ← top - 1;
        return a;
    }
}

```

What is the running time of push & pop procedure?

Ans: O(1).

Q: What is the problem with this implementation?

Ans: Array size is fixed.

List Implementation

value
next

Create - Empty ()
{

List Implementation

Create - Empty ()
{ top ← null ;
}

Push(a)
{

List Implementation

Create-Empty()

```
{   top ← null;  
}
```

Push(a)

```
{   v ← ask for memory for a new node;  
   v.value ← a;  
   v.next ← null;  
   if ( top is not null )  
   {      v.next ← top;  
   }  
   top ← v;  
}
```

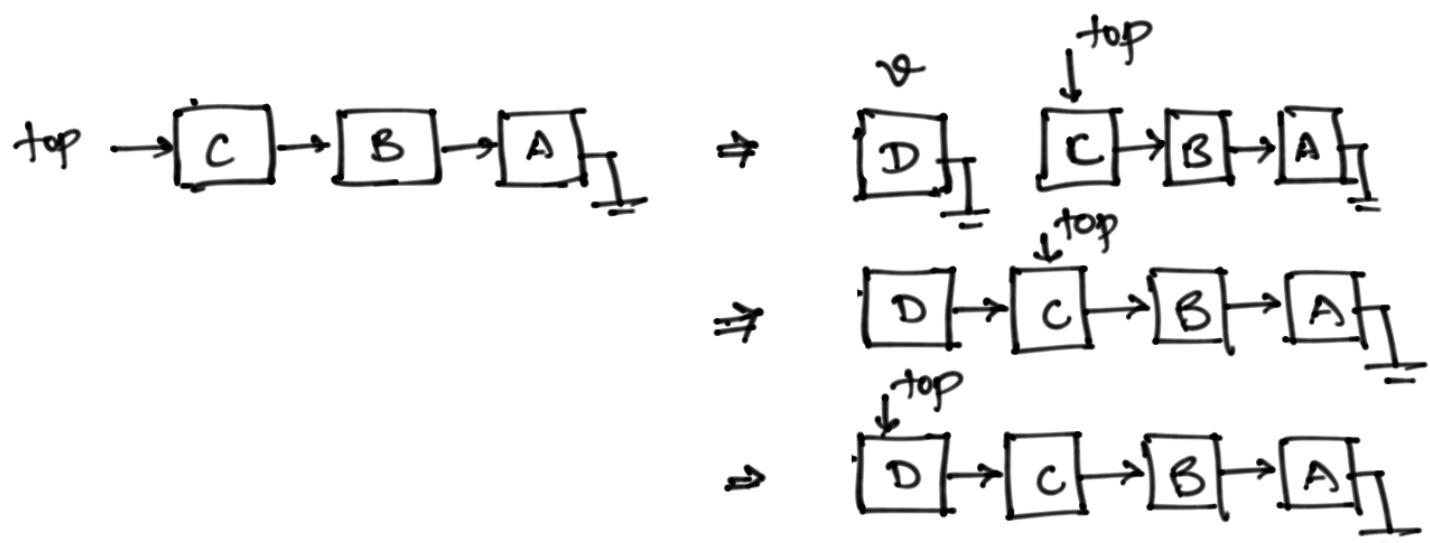
List Implementation

Create-Empty ()

```
{   top ← null;  
}
```

Push(a)

```
{   v ← ask for memory for a new node;  
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    v.next ← null;  
    if ( top is not null )  
    {      v.next ← top;  
    }  
    top ← v;  
}
```



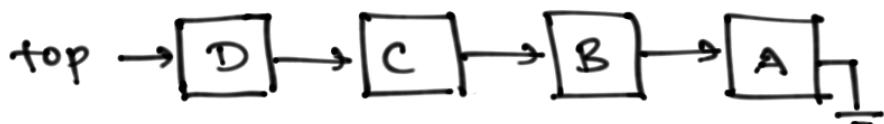
Pop()

```
{ if( top is null)
    { print "Stack Empty";
    }
else
{
```

```
Pop()
{ if( top is null)
  { print "Stack Empty";
  }
else
{ v ← top;
  a ← v.value;
  top ← top.next;
  deallocate the memory associated with
  node v;
  return a;
}
}
```

Pop()

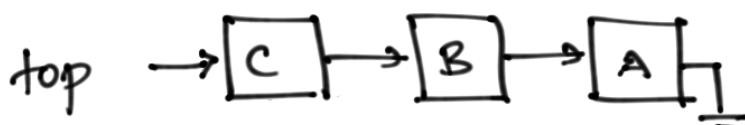
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    deallocate the memory associated with
    node v;
    return a;
}
}
```



a [D]



a [D]



a [D]

Running time of push & pop = 17

Running time of push & pop = $O(1)$.

Q: Now you have all the ingredients in hand. Can you design an $O(n)$ time algorithm for balanced parenthesis problem?

// Input: S is an array of strings

while (S contains a closing element).

{

 let i be the location of first closing
 element.

 let j ← be the first non-empty location
 to the left of i

 if (s[j] f s[i] are of same type)
 remove s[i] f s[j]

else

 {
 print ("Not balanced");
 return;

}

if (S contains non-deleted element).

{
 print ("Not balanced");
 return;

}

point ("Balanced");

return;

for (i←1 to n)
{ if (s[i] is an opening element)

```
for ( i←1 to n )  
{   if ( s[i] is an opening element)  
    Push (s[i]);  
else
```

```
for ( i←1 to n )
{   if ( s[i] is an opening element)
    Push(s[i]);
else
{   a ← Pop();
if( a='(' & s[i]=')' ) or
a='{' & s[i]='}' )
```

```
for ( i←1 to n )
{   if ( s[i] is an opening element)
    Push(s[i]);
else
{   a ← Pop();
if( a='(' & s[i]=')' ) or
    a='{' & s[i]='}'
    continue;
else
{   print "Not balanced";
    return;
}
}
}
```

```

for ( i←1 to n)
{
    if ( s[i] is an opening element)
        Push(s[i]);
    else
    {
        a ← Pop();
        if ( a = '(' & s[i] = ')' ) or
           a = '{' & s[i] = '}' )
            continue;
        else
        {
            print "Not balanced";
            return;
        }
    }
}

if ( Stack is not empty)
    print "Not balanced"
else
    print "Balanced";

```

Running Time :

```

for ( i←1 to n)
{
    if ( s[i] is an opening element)
        Push(s[i]);
    else
    {
        a ← Pop();
        if ( a = '(' & s[i] = ')' ) or
           a = '{' & s[i] = '}' )
            continue;
        else
        {
            print "Not balanced";
            return;
        }
    }
}

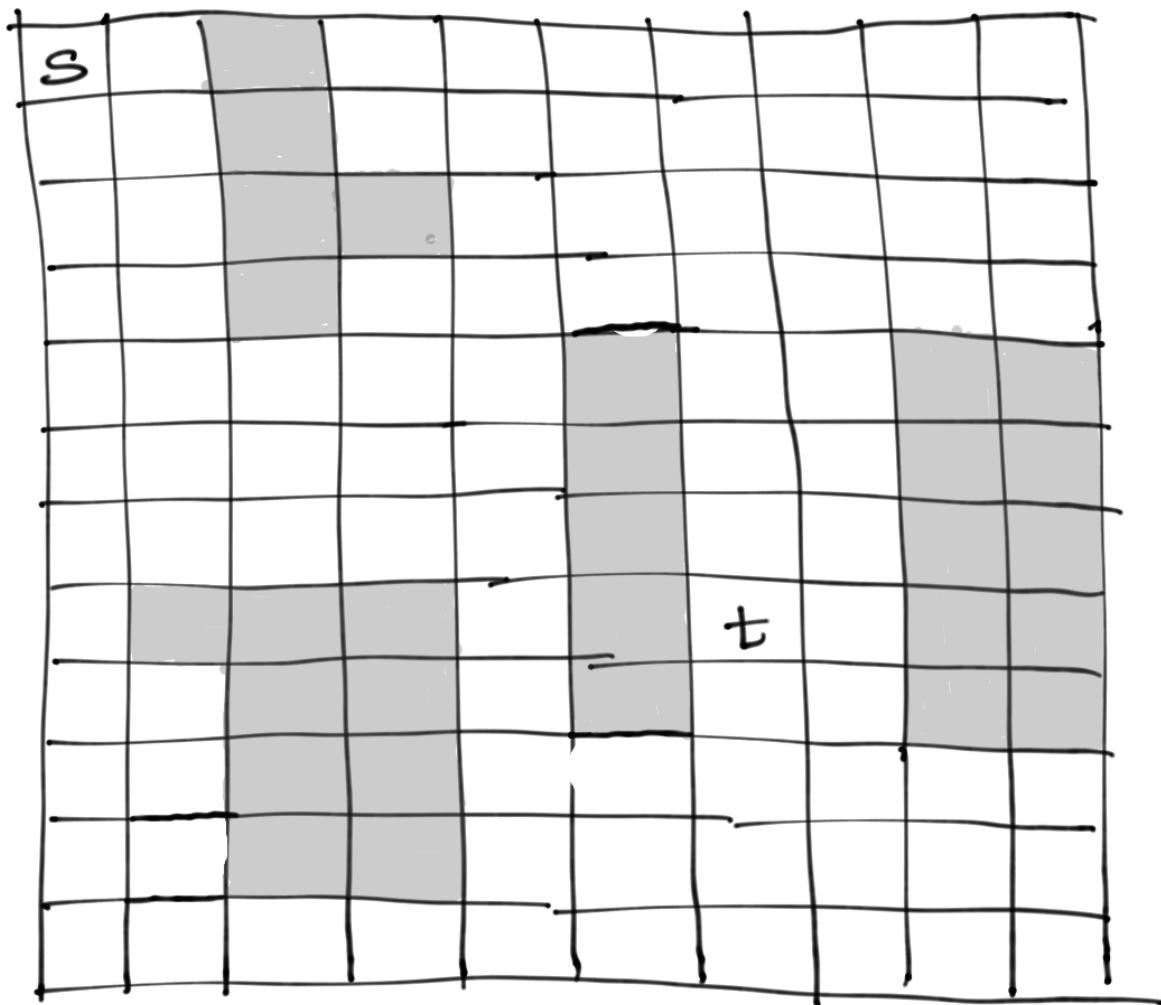
if ( Stack is not empty)
    print "Not balanced"
else
    print "Balanced";

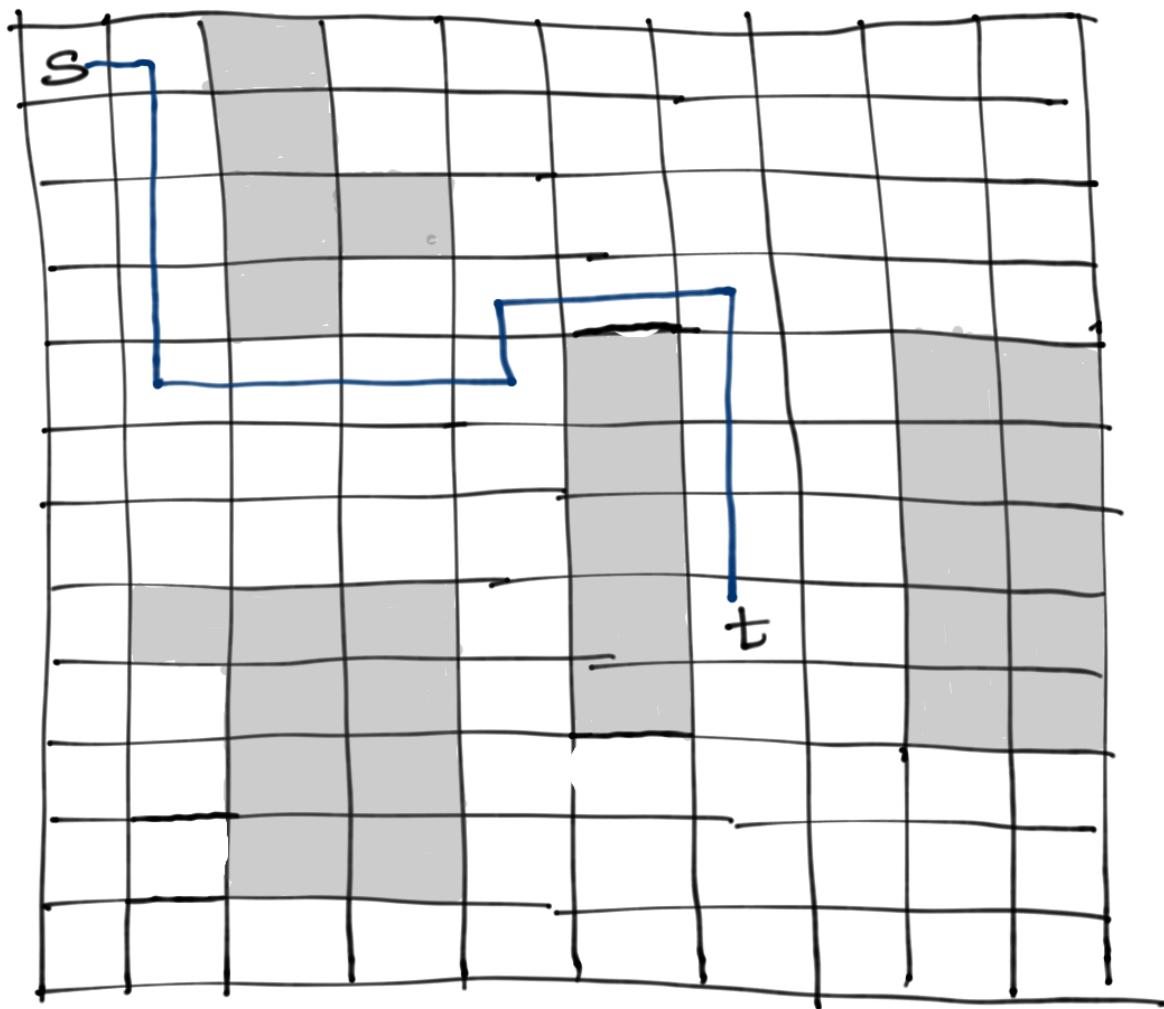
```

Running Time : $O(n)$.

- Assume that you are given a $n \times n$ grid
- Some of the cells in the grid are obstacles.
- Start location $s(0,0)$.
- Ending location $t(i,j)$

Find the shortest path from s to t avoiding obstacles?





Q: Give such a grid, find the shortest path between s & t?

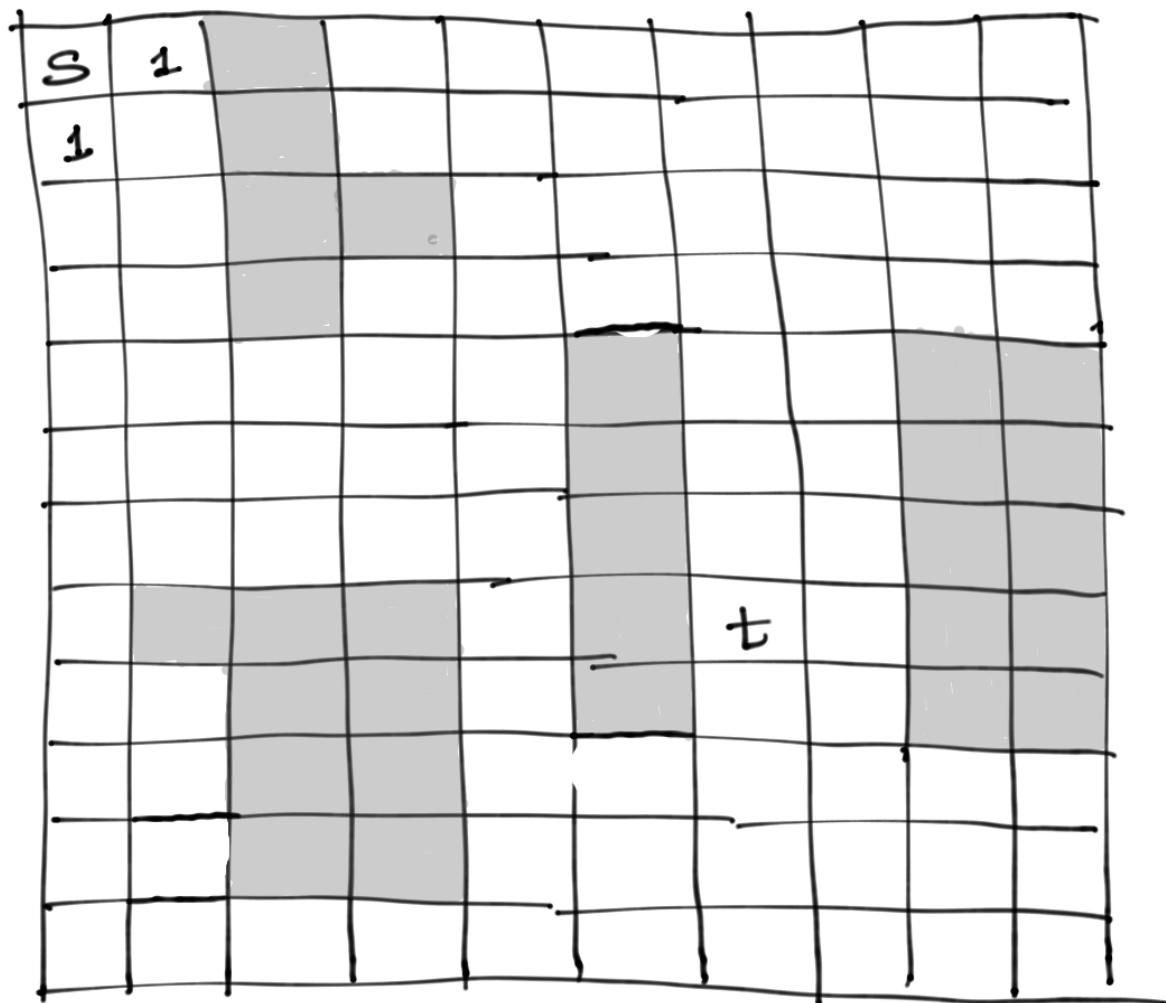
Q: What will you do?

Q_s : Can you find all the cells that are at distance 0 from s ?

Q: Can you find all the cells that are at distance 0 from s?

A: $L_0 = \{s\}$

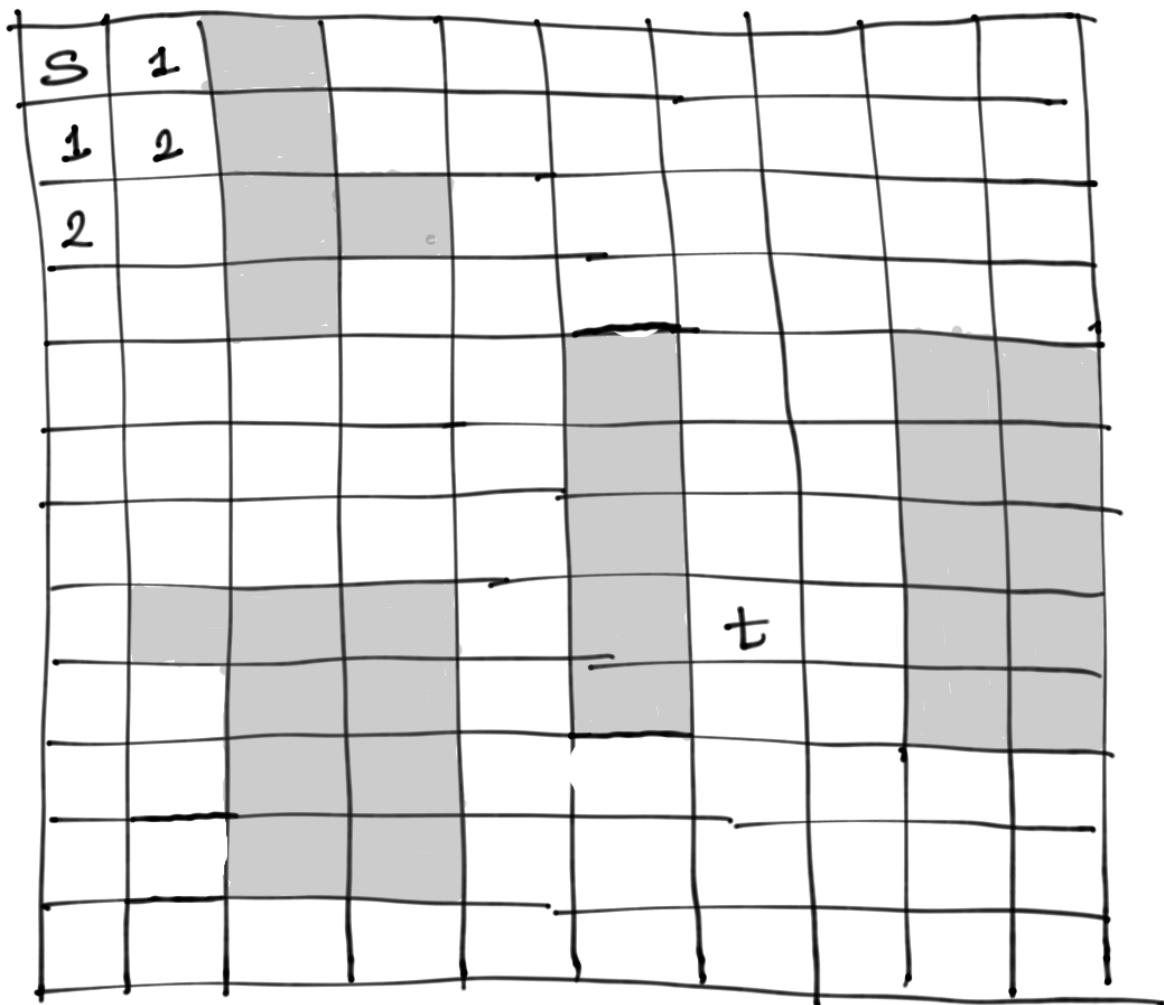
Q: Given L_0 , can you find all the cells at a distance 1 from s?



Q: Can you find all the cells that are at distance 0 from s?

A: $L_0 = \{s\}$

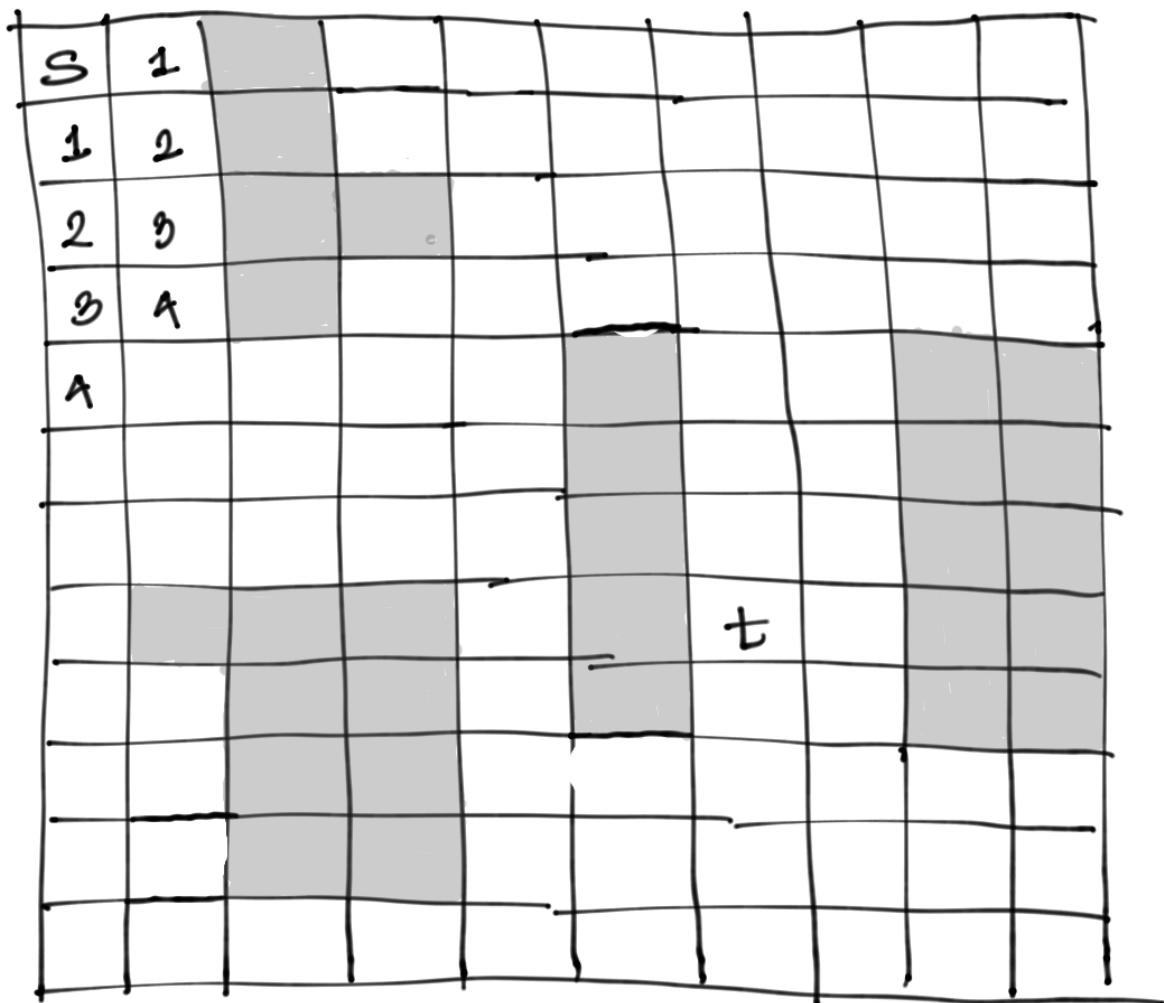
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Q: Can you find all the cells that are at distance 0 from s?

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Q: Can you find all the cells that are at distance 0 from s?

A: $L_0 = \{s\}$

Q: Given L_0 , can you find all the cells at a distance 1 from s?

| | | | | | | | | | |
|----|----|----|----|----|----|----|----|----|--|
| S | 1 | | 13 | 12 | 13 | 14 | 15 | | |
| 1 | 2 | | 12 | 11 | 12 | 13 | 14 | 15 | |
| 2 | 3 | | | 10 | 11 | 12 | 13 | | |
| 3 | 4 | | 8 | 9 | 10 | 11 | 12 | | |
| 4 | 5 | 6 | X | 8 | | 12 | 13 | | |
| 5 | 6 | X | 8 | 9 | | 13 | 14 | | |
| 6 | X | 8 | 9 | 10 | | 14 | 15 | | |
| X | | | | | 15 | T | | | |
| 8 | 9 | | | | | | | | |
| 9 | 10 | | | | | | | | |
| 10 | 11 | | | | | | | | |
| 0 | 12 | 13 | 14 | 15 | | | | | |

Q: Any idea about the running time
of this algorithm

Q: Any idea about the running time
of this algorithm

A: At least n^2 as the grid size
is n^2 .

```
main()
{
    for each cell c in the grid
        distance [c]  $\leftarrow \infty$ ;
    L0  $\leftarrow \{s\}$ 
    i  $\leftarrow 0$ ;
    while ( Li does not contain t or
            Li is not empty)
    {
        Find-Next-Layer(Li)
        i  $\leftarrow i+1$ 
    }
}
```

main()

{ for each cell c in the grid
 distance [c] $\leftarrow \infty$;
 $L_0 \leftarrow \{s\}$
 $i \leftarrow 0$;
 while (L_i does not contain t or
 L_i is not empty)
 { Find-Next-Layer(L_i)
 g $i \leftarrow i + 1$
}

Find-Next-Layer(L_i)

{ $L_{i+1} \leftarrow \emptyset$;
 for each cell c in L_i
 {

main()

{ for each cell c in the grid
 distance [c] $\leftarrow \infty$;
 $L_0 \leftarrow \{s\}$
 $i \leftarrow 0$;
 while (L_i does not contain t or
 L_i is not empty)
 { Find-Next-Layer(L_i)
 g $i \leftarrow i+1$
}

Find-Next-Layer(L_i)

{ $L_{i+1} \leftarrow \emptyset$;
 for each cell c in L_i
 { for each neighbor b of c s.t
 b is not an obstacle
 g }

main()

```
{   for each cell c in the grid  
       distance[c]  $\leftarrow \infty$ ;  
   L0  $\leftarrow \{s\}$   
   i  $\leftarrow 0$ ;  
   while ( Li does not contain t or  
          Li is not empty)  
   {     Find-Next-Layer(Li)  
   }     i  $\leftarrow i+1$   
}  
}
```

Find-Next-Layer(L_i)

```
{   Li+1  $\leftarrow \emptyset$ ;  
   for each cell c in Li  
   {     for each neighbor b of c s.t  
         b is not an obstacle  
         { if ( distance[b] =  $\infty$ )  
             { distance[b]  $\leftarrow i+1$ ;  
              Li+1  $\leftarrow L_{i+1} \cup \{b\}$ ;  
             }  
         }  
     }  
   }  
}
```

Q: Running Time

```

main()
{
    O(n2) { for each cell c in the grid
                distance[c] ← ∞;
    }
    O(1) { L0 ← {s}
            i ← 0;
            while ( Li does not contain t or
                    Li is not empty)
            {
                Find-Next-Layer(Li)
                i ← i+1
            }
    }
}

```

Find-Next-Layer(L_i)

```

{
    Li+1 ← φ;                                } O(1)
|Li| { for each cell c in Li
    { for each neighbor b of c s.t.
        { if ( distance[b] = ∞)
            { distance[b] ← i+1;
                Li+1 ← Li+1 ∪ {b}; }
        }
    }
}

```

$$\text{Running Time} = O(n^2 + \sum_{i=1}^{\infty} |L_i|)$$

Q: How much is $\sum_{i=1}^{\infty} |L_i|$

Q: How much is $\sum_{i=1}^{\infty} |L_i|$

Observation : Each cell is a part of one layer L_i .

Q: How much is $\sum_{i=1}^{\infty} |L_i|$

Observation : Each cell is a part of one layer i.e.

$$\sum_{i=1}^{\infty} |L_i| \underset{\downarrow}{=} O(n^2).$$

$$\Rightarrow \text{Running Time} = O(n^2).$$

We will focus on an implementation problem.

Q: What data-structure will you use to implement it?

We will focus on an implementation problem.

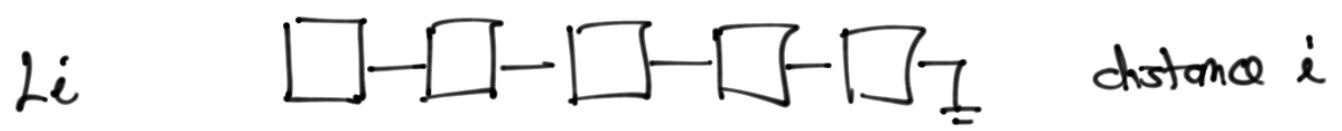
Q: What data-structure will you use to implement it?

A: Linked-List.

So, we would be using many linked list.

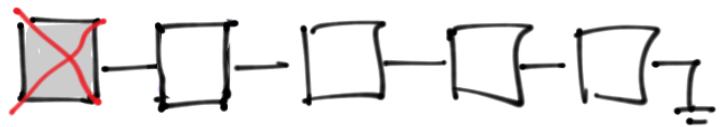
Q: Can we use only one linked list instead?

Current algo



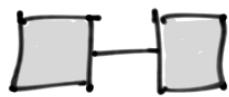
Current algo

L_i



distance i

L_{i+1}



distance $i+1$

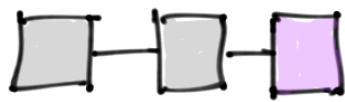
Current algo

L_i



distance i

L_{i+1}



distance $i+1$

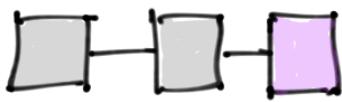
Current algo

L_i



distance i

L_{i+1}



distance $i+1$

Observation

- (1) We are visiting cells in the non-decreasing order of their distance from s .
- (2) We can add L_{i+1} at the end of L_i

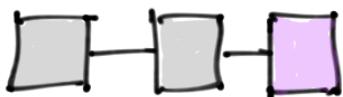
Current algo

L_i



distance i

L_{i+1}



distance $i+1$

Observation

- (1) We are visiting cells in the non-decreasing order of their distance from s .
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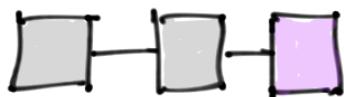
Current algo

L_i



distance i

L_{i+1}



distance $i+1$

Observation

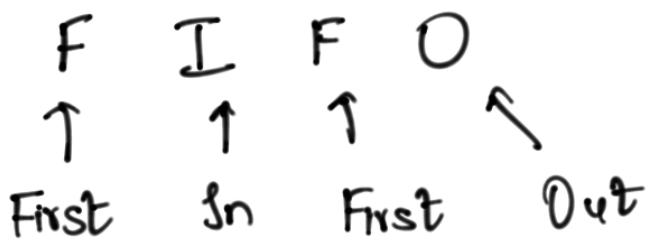
- (1) We are visiting cells in the non-decreasing order of their distance from s .
- (2) We can add L_{i+1} at the end of L_i



Observation : Analogue to stack

Push - Not at top but at bottom

Pop - Element at top



Datastructure : Queue

Two operations

- (1) Enqueue(a) : Add an element a at the end of the queue.
- (2) Dequeue() : remove an element from the start of the queue.

$Q \leftarrow \text{Create-Empty}()$

for each cell c in the grid
 $\text{distance}[c] \leftarrow \infty;$

$\text{distance}[s] \leftarrow 0;$

$Q.\text{enqueue}(s);$ // setting up to

while (Q is not empty)

{

$c \leftarrow \text{Dequeue}();$

for each neighbor b of c that is not
an obstacle

{

if $\text{distance}[b] = \infty$

{

$\text{distance}[b] \leftarrow \text{distance}[c] + 1;$

$\text{Enqueue}(b);$

}

}

}

Q: How would you implement Queues:

Q: How would you implement Queues:

- ① Arrays
- ② Linked List

Queues Using Linked Lists

Create-Empty()

{

 front \leftarrow null;

 rear \leftarrow null;

}

Enqueue(a)

Queues Using Linked Lists

Create-Empty()

{

front \leftarrow null;

rear \leftarrow null;

}

Enqueue(a)

{ v \leftarrow allocate memory for a new node;

v.value \leftarrow a;

v.next \leftarrow null;

if ()

{

j

else

{

j

}

Queues Using Linked Lists

Create-Empty()

{

front \leftarrow null;

rear \leftarrow null;

}

Enqueue(a)

{ v \leftarrow allocate memory for a new node;

v.value \leftarrow a;

v.next \leftarrow null;

if ()

{

j

else

{ rear.next \leftarrow v;

rear \leftarrow v;

}

}

Queues Using Linked Lists

Create-Empty()

{

front \leftarrow null;

rear \leftarrow null;

}

Enqueue(a)

{ v \leftarrow allocate memory for a new node;

v.value \leftarrow a;

v.next \leftarrow null;

if (rear = null)

{

front \leftarrow v;

rear \leftarrow v;

}

else

{

rear.next \leftarrow v;

rear \leftarrow v;

}

}

Dequeue()

h

// Queue is empty

Dequeue()

{

// Queue is empty
if (front = null) // or rear = null
 print "Queue Empty";

else

{

Dequeue()

{

// Queue is empty
if (front = null) // or rear = null
 print "Queue Empty";

else

{ v ← front;
 a ← v.value;
 if ()
 {

}

else

{

}

}

}

Dequeue()

{

// Queue is empty
if (front = null) // or rear = null
 print "Queue Empty";

else

{ v ← front;
 a ← v.value;
 if ()
 {

}

else

{ front ← front.next
}

deallocate the memory associated
to node v;

return a;

}

}

Dequeue()

{

// Queue is empty
if (front = null) // or rear = null
 print "Queue Empty";

else

{ v ← front;

 a ← v.value;

 if (front = rear)

{ // Queue is empty now

 front ← null;

 rear ← null;

}

else

{ front ← front.next

}

deallocate the memory associated
to node v;

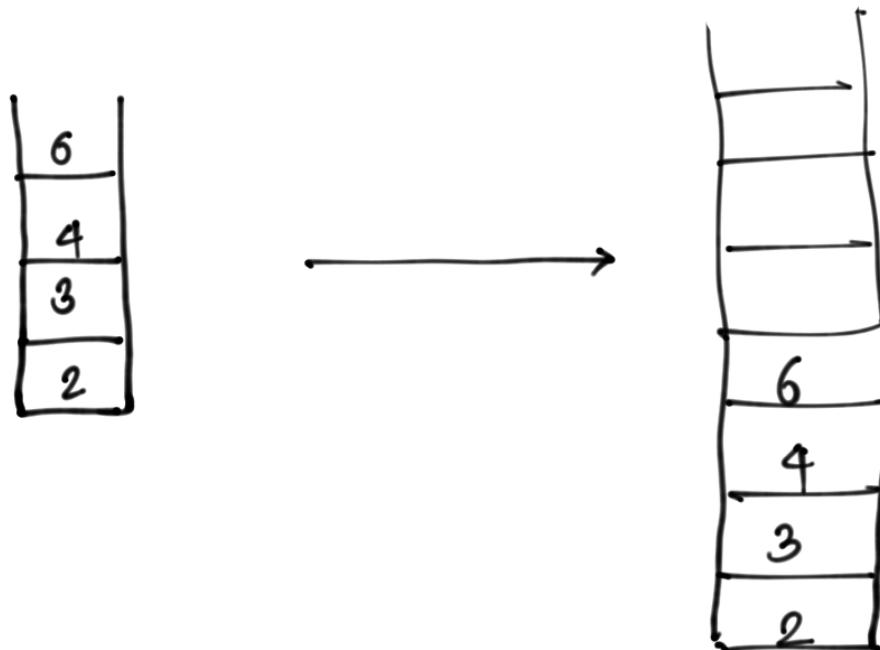
return a;

}

}

PROBLEM: ASSUME THAT YOU HAVE
IMPLEMENTED STACK USING AN ARRAY. WHILE
PUSHING AN ELEMENT, IF THE ARRAY IS FULL,
THEN WE DO THE FOLLOWING.

PROBLEM: ASSUME THAT YOU HAVE IMPLEMENTED STACK USING AN ARRAY. WHILE PUSHING AN ELEMENT, IF THE ARRAY IS FULL, THEN WE DO THE FOLLOWING.



ASSUMING THAT WE START WITH AN ARRAY OF SIZE 1, SHOW THAT A SEQUENCE OF n PUSH TAKES $O(n)$ TIME.

$$\sum_{i=1}^n \text{TIME TAKEN TO PUSH } i^{\text{th}} \text{ ELEMENT} = O(n).$$

PROBLEM 2 : GIVEN A LINKED LIST OF TWO NUMBERS a & b , REVERSE THE SUBLIST BETWEEN a^{th} & b^{th} NODE IN THE LINKED LIST.

$$a = 3, b = 6$$



TIME TAKEN : $O(b)$.

$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$PREVp \leftarrow$ THE $(a-1)^{th}$ NODE IN THE LINKED LIST
 $NEXTq \leftarrow$ THE $(b+1)^{th}$ NODE IN THE LINKED LIST.

$temp \leftarrow p;$

$NEXTp \leftarrow p.next$

WHILE ($NEXTp$ IS NOT $NEXTq$)
{

$NEXTNEXTp \leftarrow NEXTp.next;$

$NEXTp.next \leftarrow temp;$

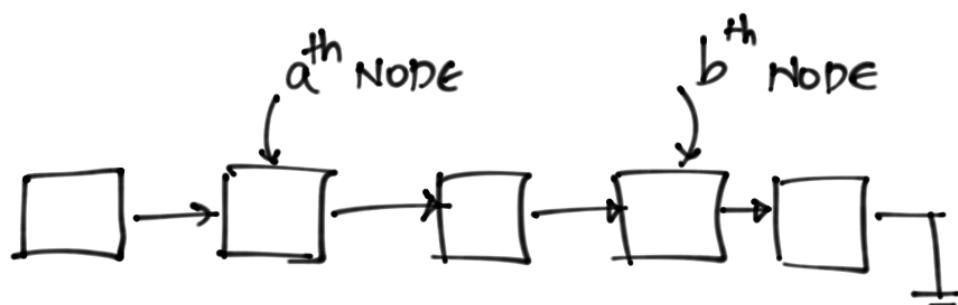
$temp \leftarrow NEXTp;$

$NEXTp \leftarrow NEXTNEXTp;$

}

$PREVp.next \leftarrow q;$

$p.next \leftarrow NEXTq$



$\rightarrow p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $\rightarrow q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST
 $\rightarrow PREP \leftarrow$ THE $(a-1)^{th}$ NODE IN THE LINKED LIST
 $\rightarrow NEXTq \leftarrow$ THE $(b+1)^{th}$ NODE IN THE LINKED LIST.

$\rightarrow temp \leftarrow p;$
 $\rightarrow NEXTp \leftarrow p.next$

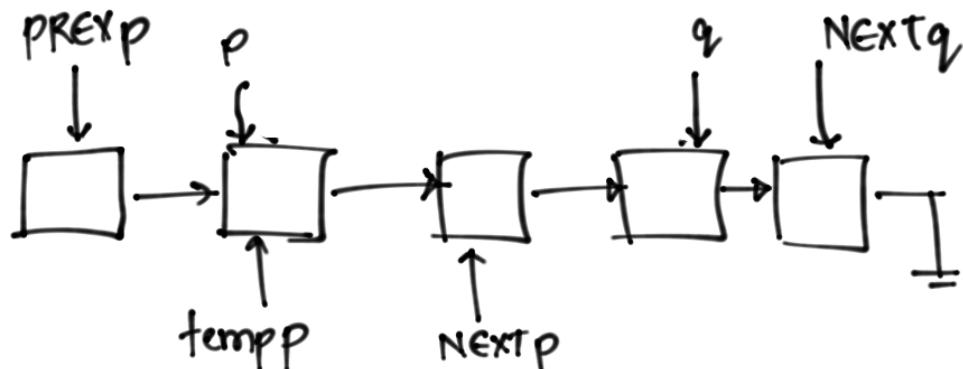
WHILE ($NEXTp$ IS NOT $NEXTq$)

{

$NEXTNEXTp \leftarrow NEXTp.next;$
 $NEXTp.next \leftarrow temp;$
 $temp \leftarrow NEXTp;$
 $NEXTp \leftarrow NEXTNEXTp;$

}

$PREP.next \leftarrow q;$
 $p.next \leftarrow NEXTq$

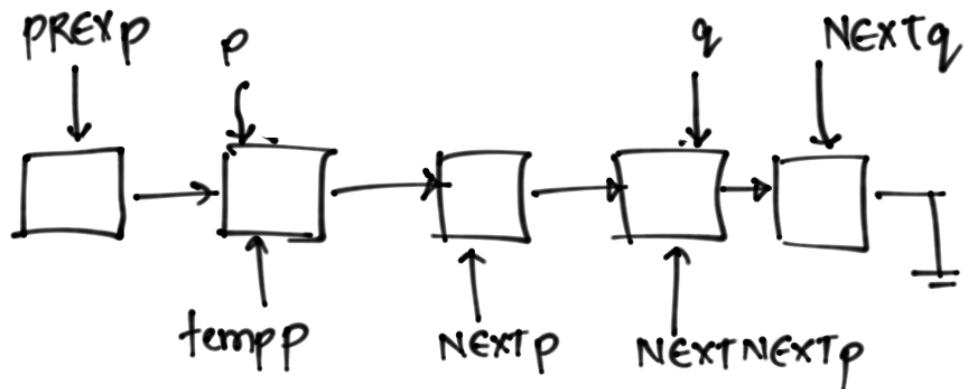


$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$PREXP \leftarrow$ THE $(a-1)^{th}$ NODE IN THE LINKED LIST
 $NEXTq \leftarrow$ THE $(b+1)^{th}$ NODE IN THE LINKED LIST.

$tempP \leftarrow p;$
 $NEXTp \leftarrow p.next$
WHILE ($NEXTp$ IS NOT $NEXTq$)
{
→ $NEXTNEXTp \leftarrow NEXTp.next;$
 $NEXTp.next \leftarrow tempP;$
 $tempP \leftarrow NEXTp;$
 $NEXTp \leftarrow NEXTNEXTp;$
}

 $PREXP.next \leftarrow q;$
 $p.next \leftarrow NEXTq$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$PREVP \leftarrow$ THE $(a-1)^{th}$ NODE IN THE LINKED LIST
 $NEXTq \leftarrow$ THE $(b+1)^{th}$ NODE IN THE LINKED LIST.

$tempP \leftarrow p;$

$NEXTp \leftarrow p.next$

WHILE ($NEXTp$ IS NOT $NEXTq$)
{

$NEXTNEXTp \leftarrow NEXTp.next;$

$\rightarrow NEXTp.next \leftarrow tempP;$

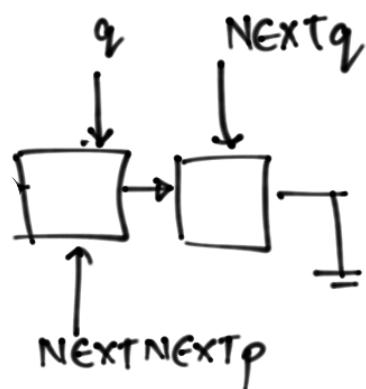
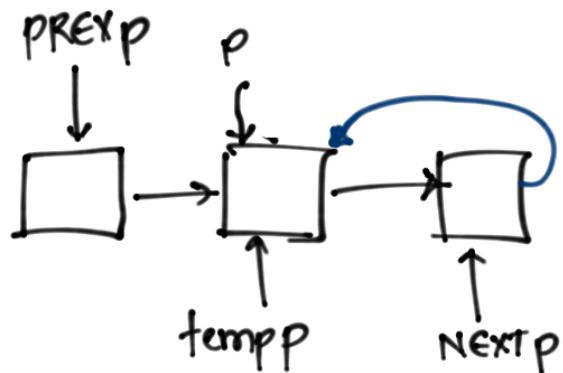
$tempP \leftarrow NEXTp;$

$NEXTp \leftarrow NEXTNEXTp;$

}

$PREVP.next \leftarrow q;$

$p.next \leftarrow NEXTq$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$PREVP \leftarrow$ THE $(a-1)^{th}$ NODE IN THE LINKED LIST
 $NEXTq \leftarrow$ THE $(b+1)^{th}$ NODE IN THE LINKED LIST.

$temp \leftarrow p;$

$NEXTp \leftarrow p.next$

WHILE ($NEXTp$ IS NOT $NEXTq$)
{

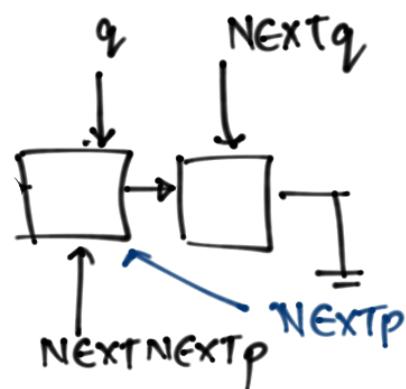
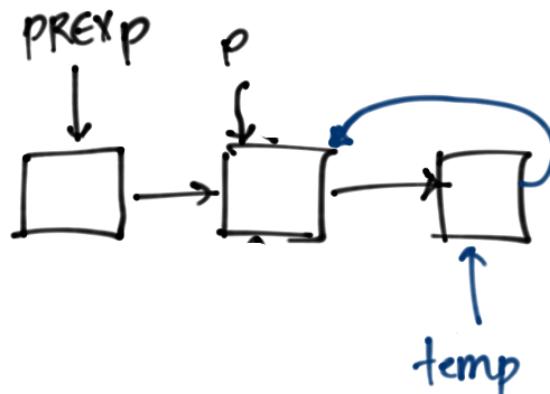
$NEXTNEXTp \leftarrow NEXTp.next;$

$NEXTp.next \leftarrow temp;$

$\rightarrow \begin{cases} temp \leftarrow NEXTp, \\ NEXTp \leftarrow NEXTNEXTp; \end{cases}$
}

$PREVP.next \leftarrow q;$

$p.next \leftarrow NEXTq$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$PREVP \leftarrow$ THE $(a-1)^{th}$ NODE IN THE LINKED LIST
 $NEXTq \leftarrow$ THE $(b+1)^{th}$ NODE IN THE LINKED LIST.

$temp \leftarrow p;$

$NEXTp \leftarrow p.next$

→ WHILE ($NEXTp$ IS NOT $NEXTq$)
{

$NEXTNEXTp \leftarrow NEXTp.next;$

$NEXTp.next \leftarrow temp;$

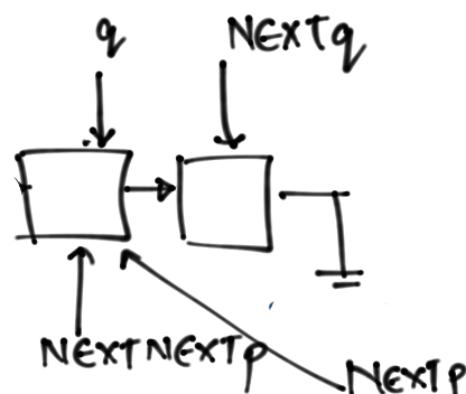
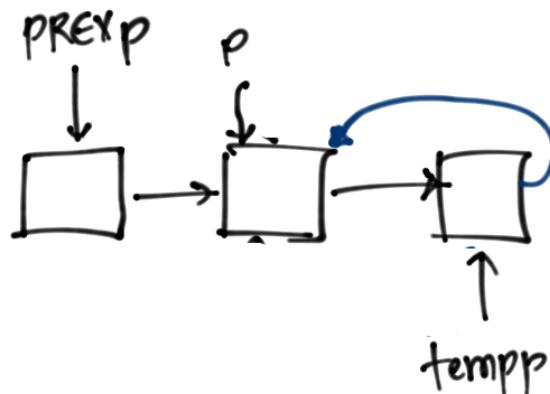
$temp \leftarrow NEXTp;$

$NEXTp \leftarrow NEXTNEXTp;$

}

$PREVP.next \leftarrow q;$

$p.next \leftarrow NEXTq$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

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 $NEXTq \leftarrow$ THE $(b+1)^{th}$ NODE IN THE LINKED LIST.

$temp \leftarrow p;$

$NEXTp \leftarrow p.next$

WHILE ($NEXTp$ IS NOT $NEXTq$)
{

→ $NEXTNEXTp \leftarrow NEXTp.next;$

$NEXTp.next \leftarrow temp;$

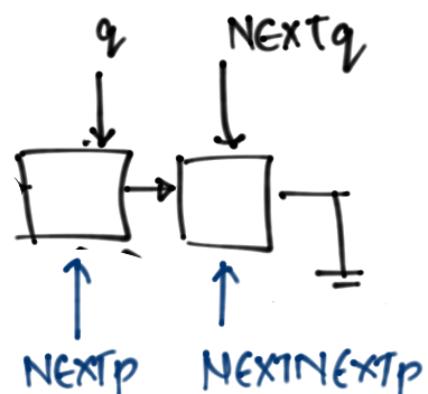
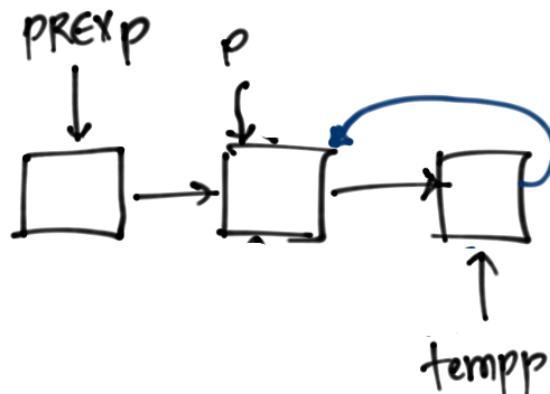
$temp \leftarrow NEXTp;$

$NEXTp \leftarrow NEXTNEXTp;$

}

$PREVP.next \leftarrow q;$

$p.next \leftarrow NEXTq$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$\text{PREXP} \leftarrow$ THE $(a-1)^{\text{th}}$ NODE IN THE LINKED LIST
 $\text{NEXTq} \leftarrow$ THE $(b+1)^{\text{th}}$ NODE IN THE LINKED LIST.

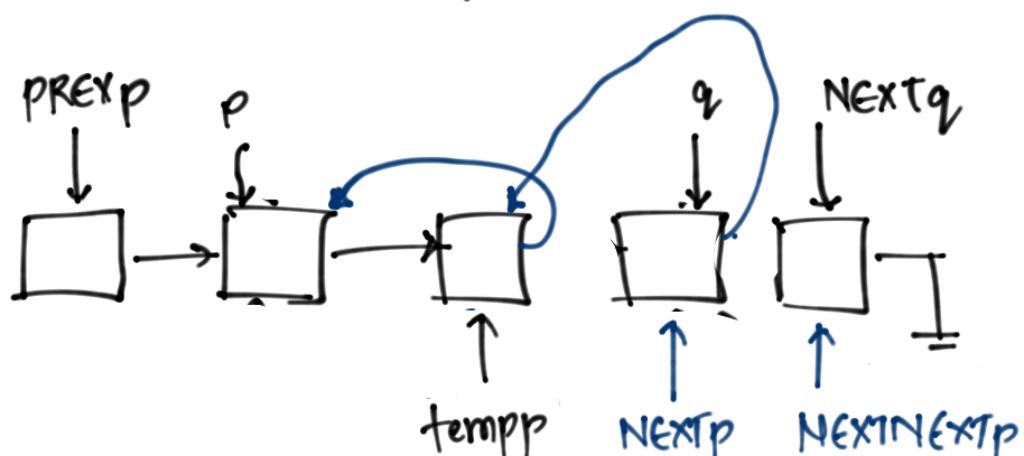
$\text{temp} \leftarrow p;$
 $\text{NEXTp} \leftarrow p.\text{next}$

WHILE (NEXTp IS NOT NEXTq)
{

$\text{NEXTNEXTp} \leftarrow \text{NEXTp}.\text{next};$
→ $\text{NEXTp}.\text{next} \leftarrow \text{temp};$
 $\text{temp} \leftarrow \text{NEXTp};$
 $\text{NEXTp} \leftarrow \text{NEXTNEXTp};$

}

$\text{PREXP}.\text{next} \leftarrow q;$
 $p.\text{next} \leftarrow \text{NEXTq}$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$\text{PREXP} \leftarrow$ THE $(a-1)^{\text{th}}$ NODE IN THE LINKED LIST
 $\text{NEXTq} \leftarrow$ THE $(b+1)^{\text{th}}$ NODE IN THE LINKED LIST.

$\text{temp} \leftarrow p;$

$\text{NEXTp} \leftarrow p.\text{next}$

WHILE (NEXTp IS NOT NEXTq)
{

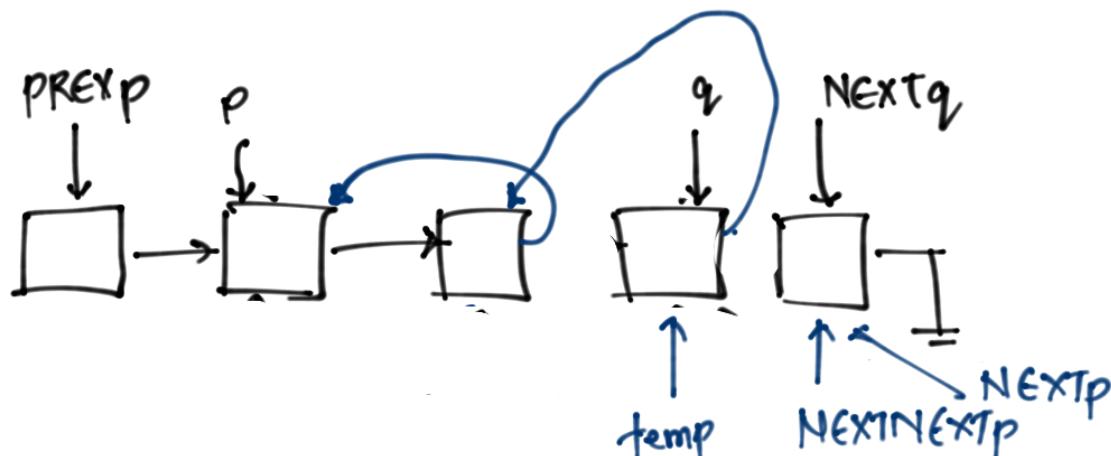
$\text{NEXTNEXTp} \leftarrow \text{NEXTp}.\text{next};$

$\text{NEXTp}.\text{next} \leftarrow \text{temp};$

$\rightarrow \left\{ \begin{array}{l} \text{temp} \leftarrow \text{NEXTp}, \\ \text{NEXTp} \leftarrow \text{NEXTNEXTp}; \end{array} \right.$
}

$\text{PREXP}.\text{next} \leftarrow q;$

$p.\text{next} \leftarrow \text{NEXTq}$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$\text{PREXP} \leftarrow$ THE $(a-1)^{\text{th}}$ NODE IN THE LINKED LIST
 $\text{NEXTq} \leftarrow$ THE $(b+1)^{\text{th}}$ NODE IN THE LINKED LIST.

$\text{temp} \leftarrow p;$

$\text{NEXTp} \leftarrow p.\text{next}$

→ WHILE (NEXTp IS NOT NEXTq)

COME

{

OUT OF
WHILE
LOOP

$\text{NEXTNEXTp} \leftarrow \text{NEXTp}.\text{next};$

$\text{NEXTp}.\text{next} \leftarrow \text{temp};$

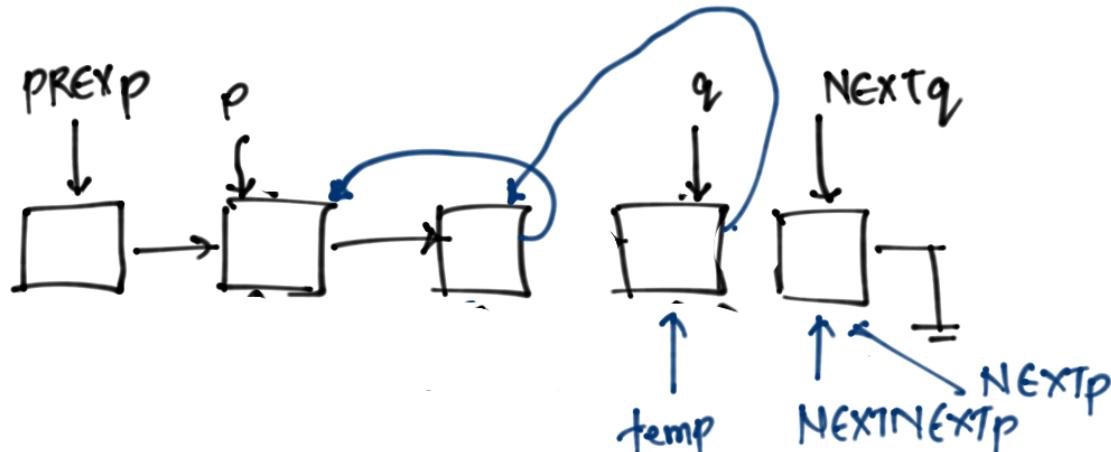
$\text{temp} \leftarrow \text{NEXTp};$

$\text{NEXTp} \leftarrow \text{NEXTNEXTp};$

}

$\text{PREXP}.\text{next} \leftarrow q;$

$p.\text{next} \leftarrow \text{NEXTq}$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$PREVP \leftarrow$ THE $(a-1)^{th}$ NODE IN THE LINKED LIST
 $NEXTq \leftarrow$ THE $(b+1)^{th}$ NODE IN THE LINKED LIST.

$temp \leftarrow p;$

$NEXTp \leftarrow p.next$

\rightarrow WHILE ($NEXTp$ IS NOT $NEXTq$)

COME OUT OF
WHILE LOOP

$NEXTNEXTp \leftarrow NEXTp.next;$

$NEXTp.next \leftarrow temp;$

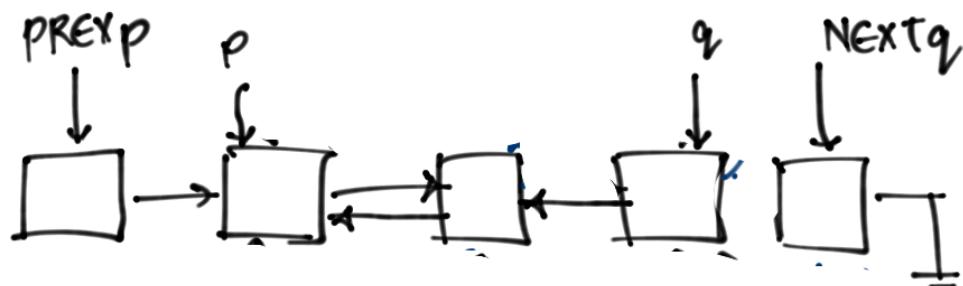
$temp \leftarrow NEXTp;$

$NEXTp \leftarrow NEXTNEXTp;$

}

$PREVP.next \leftarrow q;$

$p.next \leftarrow NEXTq$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
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$\text{PREXP} \leftarrow$ THE $(a-1)^{\text{th}}$ NODE IN THE LINKED LIST
 $\text{NEXTq} \leftarrow$ THE $(b+1)^{\text{th}}$ NODE IN THE LINKED LIST.

$\text{temp} \leftarrow p;$

$\text{NEXTp} \leftarrow p.\text{next}$

\rightarrow WHILE (NEXTp IS NOT NEXTq)

COME OUT OF WHILE LOOP

$\text{NEXTNEXTp} \leftarrow \text{NEXTp}.\text{next};$

$\text{NEXTp}.\text{next} \leftarrow \text{temp};$

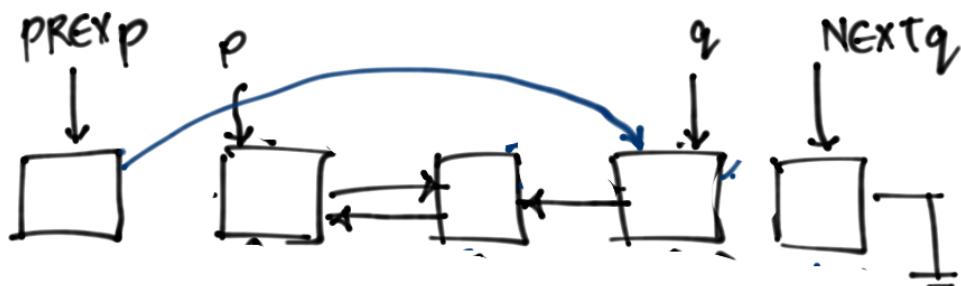
$\text{temp} \leftarrow \text{NEXTp};$

$\text{NEXTp} \leftarrow \text{NEXTNEXTp};$

}

$\rightarrow \text{PREXP}.\text{next} \leftarrow q;$

$p.\text{next} \leftarrow \text{NEXTq}$



$p \leftarrow$ THE a^{th} NODE IN THE LINKED LIST
 $q \leftarrow$ THE b^{th} NODE IN THE LINKED LIST

$\text{PREXP} \leftarrow$ THE $(a-1)^{\text{th}}$ NODE IN THE LINKED LIST
 $\text{NEXTq} \leftarrow$ THE $(b+1)^{\text{th}}$ NODE IN THE LINKED LIST.

$\text{temp} \leftarrow p;$

$\text{NEXTp} \leftarrow p.\text{next}$

→ WHILE (NEXTp IS NOT NEXTq)

COME

{

OUT OF

WHILE
LOOP

$\text{NEXTNEXTp} \leftarrow \text{NEXTp}.\text{next};$

$\text{NEXTp}.\text{next} \leftarrow \text{temp};$

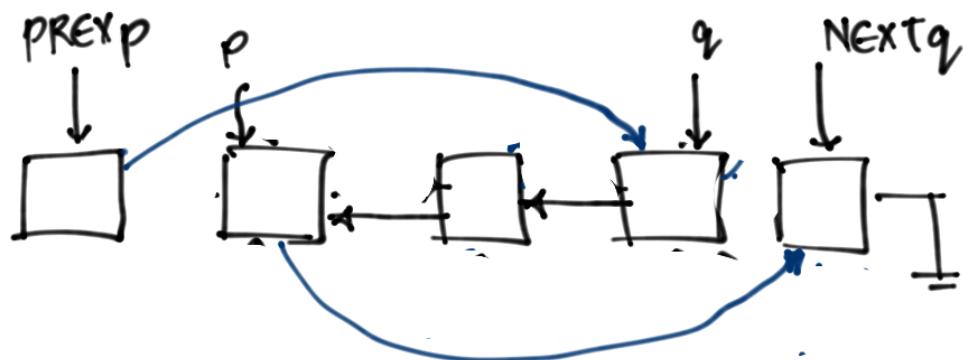
$\text{temp} \leftarrow \text{NEXTp};$

$\text{NEXTp} \leftarrow \text{NEXTNEXTp};$

}

$\text{PREXP}.\text{next} \leftarrow q;$

→ $p.\text{next} \leftarrow \text{NEXTq}$



END