## ML Notes

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## Contents

1 Bias-Variance Decomposition

2

## Chapter 1

## Bias-Variance Decomposition

The bias-variance decomposition is the decomposition of the generalization error of a learning algorithm into the sum of the bias, the variance and an irreducible error term.

Consider a setting where a response variable Y is related to a set of predictor variables  $X \in \mathbf{R}^p$  as follows:  $Y = f(X) + \varepsilon$ , where  $f : \mathbf{R}^p \to \mathbf{R}$  is some deterministic function and  $\varepsilon$  is white noise. That is,  $\mathbf{E}\left[\varepsilon|X=x\right] = 0$  and  $\operatorname{Var}(\varepsilon|X=x) = \sigma^2$ , for some variance  $\sigma^2$ . Let us assume that there is an underlying data distribution  $\mathfrak{D}(X,Y)$  which is unknown to us. We have an algorithm that, given an n-sized training set  $S = \{(x_1, y_1), \ldots, (x_n, y_n)\}$  sampled iid from this distribution  $\mathfrak{D}$ , yields  $\hat{f}_S$ , which is an approximation to the true function f. We assume that the algorithm itself is deterministic: that is, given the same n-sized sample S, it produces the same output  $\hat{f}_S$ .

What is the expected generalization error of this algorithm? This is defined as:

$$\mathbf{E}_{S \sim \mathcal{D}^n, (X,Y) \sim \mathcal{D}} \left[ (Y - f_S(X))^2 \right]. \tag{1.1}$$

This is the expected error when we input the random sample S to our algorithm to obtain  $\hat{f}_S$  and then evaluate it on the random point (X,Y). We may write this expected error as:

$$\mathbf{E}_{S \sim \mathfrak{D}^n, (X,Y) \sim \mathfrak{D}} \left[ (Y - \hat{f}_S(X))^2 \right] = \int \mathbf{E}_{(X,Y) \sim \mathfrak{D}} \left[ (Y - \hat{f}_S(X))^2 \mid S \right] \cdot \mathbf{Pr}_{\mathfrak{D}^n} \left\{ S \right\} dS. \tag{1.2}$$

We will first work with the expectation term on the right-hand side of the above equation. That is, we will assume that the sample S is fixed and then calculate the expected error wrt the approximation  $\hat{f}_S$ . In order to implify our notation a bit, we will index the expectation operator with the random variable to indicate which distribution is being referred to.

Let us write  $(Y - \hat{f}_S(X))^2$  as  $(Y - f(X) + f(X) - \hat{f}_S(X))^2$ . Expanding, we get:

$$\mathbf{E}_{(X,Y)} \left[ (Y - \hat{f}_S(X))^2 | S \right] = \mathbf{E}_{(X,Y)} \left[ (f(X) - \hat{f}_S(X))^2 | S \right] +$$

$$\mathbf{E}_{(X,Y)} \left[ (Y - f(X))^2 | S \right] +$$

$$\mathbf{E}_{(X,Y)} \left[ 2(Y - f(X))(f(X) - \hat{f}_S(X)) | S \right]$$
(1.3)

Consider the last term on the right-hand side. We claim that this is 0. Indeed, we may write  $\mathbf{E}_{(X,Y)}\left[2(Y-f(X))(f(X)-\hat{f}_S(X))|S\right]$  as

$$= \iint 2 \cdot (y - f(x)) \cdot (f(x) - \hat{f}_S(x)) \cdot p_{X,Y}(x,y) dy dx$$

$$= \iint 2 \cdot (y - f(x)) \cdot (f(x) - \hat{f}_S(x)) \cdot p_{Y|X}(y|x) \cdot p_X(x) dy dx$$

$$= \int 2 \cdot (f(x) - \hat{f}_S(x)) \cdot \mathbf{E}_{Y|X} [Y - f(x)|X = x] \cdot p_X(x) dx.$$

Now we know that  $\mathbf{E}_{Y|X}[Y - f(x)|X = x] = \mathbf{E}_{Y|X}[\varepsilon|X = x] = 0$ . Hence this whole expression evaluates to 0 as claimed.

Next consider the second term  $\mathbf{E}_{(X,Y)}[(Y-f(X))^2|S]$  of Equation (1.3). Since the term  $(Y-f(X))^2$  does not depend on the sample S that is chosen, this further simplifies to  $\mathbf{E}_{(X,Y)}[(Y-f(X))^2]$ . This is simply the variance of the error term and is equal to  $\sigma^2$ . Finally, consider the first term of Equation (1.3) which is  $\mathbf{E}_{(X,Y)}[(f(X)-\hat{f}_S(X))^2|S]$ . We use the trick of adding and subtracting as before. This time around, we add and subtract the term  $g(X) := \mathbf{E}_S[\hat{f}_S(X)]$  to obtain:

$$(f(X) - g(X) + g(X) - \hat{f}_S(X))^2 = (f(X) - g(X))^2 + (g(X) - \hat{f}_S(X))^2 + 2 \cdot (f(X) - g(X)) \cdot (g(X) - \hat{f}_S(X)).$$
(1.4)

We will evaluate each of these terms by directly plugging them in the expression in Equation (1.2). Let's examine the first term  $(f(X) - g(X))^2$ . Plugging this in the said expression, we see that we have to evaluate:

$$\int \mathbf{E}_{(X,Y)} \left[ (f(X) - g(X))^2 | S \right] \mathbf{Pr}_{S \sim \mathfrak{D}^n} \left\{ S \right\} dS = \mathbf{E}_{(X,Y)} \left[ (f(X) - g(X))^2 \right] \int \mathbf{Pr}_{S \sim \mathfrak{D}^n} \left\{ S \right\} dS 
= \mathbf{E}_{(X,Y)} \left[ (f(X) - g(X))^2 \right].$$
(1.5)

The first equality holds because neither f(X) nor g(X) depends on the sample S chosen. The resulting expression is the expected squared bias of the estimator  $\hat{f}_S$ .

Forging ahead, we evaluate the next term which is  $(g(X) - \hat{f}_S(X))^2$ .

$$\int \mathbf{E}_{(X,Y)} \left[ (g(X) - \hat{f}_S(X))^2 | S \right] \mathbf{Pr}_{S \sim \mathcal{D}^n} \left\{ S \right\} dS = \mathbf{E}_{S,(X,Y)} \left[ (g(X) - \hat{f}_S(X))^2 \right]. \tag{1.6}$$

This term is the variance of the estimator  $\hat{f}_S$  obtained by our algorithm.

Finally, we evaluate the term  $2 \cdot (f(X) - g(X)) \cdot (g(X) - \hat{f}_S(X))$ . We now have to evaluate this integral:

$$\int \mathbf{E}_{(X,Y)} \left[ 2 \cdot (f(X) - g(X)) \cdot (g(X) - \hat{f}_S(X)) | S \right] \mathbf{Pr}_{S \sim \mathcal{D}^n} \left\{ S \right\} dS$$
(1.7)

Recall that this is just the expectation wrt the distribution of the random sample S and the random data point (X,Y) at which we want to evaluate the predictor  $\hat{f}_S$  output by our

algorithm. Instead of first conditioning on S, we can condition on the random data point (X,Y) and write:

$$\iint \mathbf{E}_S \left[ 2 \cdot (f(x) - g(x)) \cdot (g(x) - \hat{f}_S(x)) | X = x, Y = y \right] p_{X,Y}(x,y) dy dx. \tag{1.8}$$

Now the term f(x) - g(x) does not depend on S and  $\mathbf{E}_S \left[ g(x) - \hat{f}_S(x) \right] = 0$  and hence the above integral evaluates to 0.

To summarize, we may write the expected generalization error of our algorithm as:

$$\mathbf{E}_{S \sim \mathcal{D}^n, (X,Y) \sim \mathcal{D}} \left[ (Y - \hat{f}_S(X))^2 \right] = \underbrace{\mathbf{E}_{(X,Y)} \left[ (\mathbf{E}_S \left[ \hat{f}_S(X) \right] - f(X))^2 \right]}_{\text{expected squared bias}} + \underbrace{\mathbf{E}_{S,(X,Y)} \left[ (\hat{f}_S(X) - \mathbf{E}_S \left[ \hat{f}_S(X) \right])^2 \right]}_{\text{variance}} + \underbrace{\sigma^2}_{\text{irreducible error}}.$$