Linear Algebra and Vector Calculus Notes and Exercises

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Chapter 1

Linear Algebra Basics

1.1 Linear Functions

A function $L: \mathbb{R}^m \to \mathbb{R}^n$ is a linear function if for all $x, y \in \mathbb{R}^m$ and for all $a, b \in \mathbb{R}$

$$L(a\boldsymbol{x} + b\boldsymbol{y}) = aL(\boldsymbol{x}) + bL(\boldsymbol{y}).$$

It follows (by induction) that for all $x_1, \ldots, x_r \in \mathbf{R}^m$ and all $a_1, \ldots, a_r \in \mathbf{R}$

$$L(a_1\boldsymbol{x}_1 + \cdots + a_r\boldsymbol{x}_r) = a_1L(\boldsymbol{x}_1) + \cdots + a_rL(\boldsymbol{x}_r).$$

Theorem 1.1. A linear function $L: \mathbf{R}^m \to \mathbf{R}^n$ is completely determined by its effect on the standard basis vectors $\mathbf{e}_1, \dots, \mathbf{e}_m$ of \mathbf{R}^m . An arbitrary choice of vectors $L(\mathbf{e}_1), \dots, L(\mathbf{e}_m)$ of \mathbf{R}^n determines a linear function from \mathbf{R}^m to \mathbf{R}^n .

Proof. Given any vector $x \in \mathbb{R}^m$, we can express it as a unique linear combination $\sum_{i=1}^m \alpha_i e_i$ of the basis vectors. By the linearity of L, $L(x) = \sum_i \alpha_i L(e_i)$ which is completely specified by $L(e_1), \ldots, L(e_m)$.

Let b_1, \ldots, b_m be any vectors in \mathbb{R}^n . Define a map L from \mathbb{R}^m to \mathbb{R}^n as follows: for $\mathbf{x} = \sum_{i=1}^m \alpha_i \mathbf{e}_i \in \mathbb{R}^m$, $L(\mathbf{x}) = \sum_{i=1}^m \alpha_i \mathbf{b}_i$. Then $L(\mathbf{e}_i) = \mathbf{b}_i$ for all $1 \leq i \leq m$ and for all $\mathbf{x}, \mathbf{y} \in \mathbb{R}^m$ and all $a, b \in \mathbb{R}$:

$$L(a\boldsymbol{x} + b\boldsymbol{y}) = \sum_{i=1}^{m} (ax_i + by_i)\boldsymbol{b}_i = a\sum_i x_i \boldsymbol{b}_i + b\sum_i y_i \boldsymbol{b}_i = aL(\boldsymbol{x}) + bL(\boldsymbol{y})$$