

$$x_{k+1} = Ax_k + Bu_k \quad \text{CTI}$$

$$\min_{u \in \mathbb{R}^{mT}} J(u) := x_T^T Q_T x_T + \sum_{t=0}^{T-1} x_t^T Q x_t + u_t^T R u_t$$

equivalent to

$$\min_{u \in \mathbb{R}^{mT}} \frac{1}{2} u^T \tilde{Q} u - \tilde{b}^T u$$

$$x_1 = Ax_0 + Bu_0$$

$$x_2 = A(Ax_0 + Bu_0) + Bu_1 \\ = A^2 x_0 + ABu_0 + Bu_1$$

$$x_3 = A^3 x_0 + A^2 Bu_0 + ABu_1 + Bu_2$$

$$\Rightarrow x_T = A^T x_0 + \sum_{i=0}^{T-1} A^{T-1-i} B u_i$$

$$x_t = A^t x_0 + \sum_{i=0}^{t-1} A^{t-1-i} B u_i$$

$$x_t^T Q x_t + u_t^T R u_t = \left(A^t x_0 + \sum_{i=0}^{t-1} A^{t-1-i} B u_i \right)^T Q \left(A^t x_0 + \sum_{i=0}^{t-1} A^{t-1-i} B u_i \right) \\ + u_t^T R u_t$$

$$\because \left(\sum_{i=0}^{t-1} A^{t-1-i} B u_i \right)^T Q A^t x_0 \text{ is a scalar} \\ = (A^t x_0)^T Q \left(\sum_{i=0}^{t-1} A^{t-1-i} B u_i \right)$$

$$\therefore x_t^T Q x_t + u_t^T R u_t = x_0^T A^t Q A^t x_0 + \left(\sum_{i=0}^{t-1} A^{t-1-i} B u_i \right)^T Q \left(\sum_{i=0}^{t-1} A^{t-1-i} B u_i \right) \\ + 2 x_0^T A^t Q \left(\sum_{i=0}^{t-1} A^{t-1-i} B u_i \right) + u_t^T R u_t$$

$$\text{We can write } \left(\sum_{i=0}^{t-1} A^{t-1-i} B u_i \right) = \begin{bmatrix} A^{t-1} B & & 0 \\ & A^{t-2} B & \\ 0 & \ddots & AB \\ & & & B \end{bmatrix} \begin{bmatrix} u_0 \\ \vdots \\ u_{t-1} \end{bmatrix} \\ = C(t) u_{0:t-1}$$

$$C(t) \in \mathbb{R}^{m \times mt} \quad u_{0:t-1} \in \mathbb{R}^{mt}$$

$$\therefore x_t^T Q x_t + u_t^T R u_t = x_0^T A^t Q A^t x_0 + u_{0:t-1}^T C(t)^T Q C(t) u_{0:t-1} \\ + 2 x_0^T A^t Q C(t) u_{0:t-1} + u_t^T R u_t$$

$$\sum_{t=0}^{T-1} x_t^T Q x_t + u_t^T R u_t = \underbrace{\sum_{t=0}^{T-1} x_0^T A^t Q A^t x_0}_{(1)} + \underbrace{\sum_{t=0}^{T-1} u_{0:t-1}^T C(t)^T Q C(t) u_{0:t-1}}_{(2)} \\ + \underbrace{\sum_{t=0}^{T-1} 2 x_0^T A^t Q C(t) u_{0:t-1}}_{(3)} + \underbrace{\sum_{t=0}^{T-1} u_t^T R u_t}_{(4)}$$

power T

$$\therefore x_T = A^T x_0 + \sum_{i=0}^{T-1} A^{T-1-i} B u_i = A^T x_0 + C(T) u_{0:T-1}$$

power T

$$\begin{aligned}
 J(u) &= u_T' \otimes_T u_T + \textcircled{1} + \textcircled{2} + \textcircled{3} + \textcircled{4} \\
 &= \underbrace{u_0' (A^T)' \otimes_T A^T u_0}_{\textcircled{5}} + \underbrace{u_{0:T-1}' C(T)' \otimes_T C(T) u_{0:T-1}}_{\textcircled{6}} \\
 &\quad + \underbrace{2 u_0' (A^T)' \otimes_T C(T) u_{0:T-1}}_{\textcircled{7}} + \textcircled{1} + \textcircled{2} + \textcircled{3} + \textcircled{4}
 \end{aligned}$$

① and ⑤ are constant wrt u and are only functions of u_0 so we can leave them out of $\min_{u \in \mathbb{R}^{mT}} J(u)$

$$\begin{aligned}
 \textcircled{6} \text{ and } \textcircled{7} \quad & \sum_{t=0}^{T-1} 2 u_0' A^t \otimes C(t) u_{0:t-1} + 2 u_0' (A^T)' \otimes_T C(T) u_{0:T-1} \\
 &= 2 u_0' \left[\begin{aligned} & (A^0 \otimes A^0 B + A^1 \otimes A^1 B + \dots + A^{T-1} \otimes A^{T-1} B) u_0 \\ & + (A^1 \otimes A^0 B + A^2 \otimes A^1 B + \dots + A^{T-1} \otimes A^{T-2} B) u_1 \\ & + (A^2 \otimes A^0 B + A^3 \otimes A^1 B + \dots + A^{T-1} \otimes A^{T-3} B) u_2 \\ & + \dots \\ & + (A^{T-1} \otimes A^0 B) u_{T-1} \end{aligned} \right] \\
 &\quad + 2 u_0' (A^T)' \otimes_T \left[A^{T-1} B u_0 + A^{T-2} B u_1 + \dots + A^0 B u_{T-1} \right] \\
 &= 2 u_0' \left[\begin{aligned} & \sum_{i=0}^{T-1} (A^i)' \otimes A^i B + (A^T)' \otimes_T A^{T-1} B, \quad \sum_{i=1}^{T-1} (A^i)' \otimes A^{i-1} B + (A^T)' \otimes_T A^{T-2} B \\ & \dots \quad \sum_{i=T-1}^{T-1} (A^i)' \otimes A^{i-(T-1)} B + (A^T)' \otimes_T B \end{aligned} \right] \\
 &= -2 \tilde{b}^T u
 \end{aligned}$$

where $\tilde{b} = \begin{bmatrix} \tilde{b}_0 \\ \tilde{b}_1 \\ \vdots \\ \tilde{b}_{T-1} \end{bmatrix}$ $\tilde{b}_j = u_0' \left(\sum_{i=j}^{T-1} (A^i)' \otimes A^i B + (A^T)' \otimes_T A^{T-1-j} B \right)$

Check $\tilde{b}_j : 1 \times n \quad n \times n \quad n \times n \quad n \times n \quad n \times m = 1 \times m$
 $\Rightarrow \tilde{b} : 1 \times mT \Rightarrow \tilde{b}^T : \mathbb{R}^{mT}$

$$A^k = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A^n = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\text{Solving } u^* = \tilde{Q}^{-1} \tilde{b}$$

uStar =

-0.0622
-0.0645
-0.0666
-0.0687
-0.0706
-0.0723
-0.0738
-0.0752
-0.0763
-0.0773
-0.0779
-0.0783
-0.0784
-0.0783
-0.0777
-0.0766
-0.0749
-0.0720
-0.0664
-0.0509

cost

J =

2.0933e+03

AA 203 HW 1 Question 5

Somrita Banerjee

```
clc
clear all
close all
Q = eye(2);
QT = 10 * eye(2);
R = eye(1);
A=[1 1; 0 1];
B=[0;1];
x0=[1;0];
T=20;
btilde = zeros(T,1);
Qtild = zeros(T,T);
for j = 0: T-1
    sumb = 0;
    sumQ = 0;
    for i = j: T-1
        sumb = sumb + (-x0' * (A^i)' * Q * (A^i) * B);
        sumQ = sumQ + B' * (A^i)' * Q * (A^i) * B;
    end
    btilde(j+1,1) = sumb - x0'*((A^T)'*QT*(A^(T-1-j))*B);
    Qtild(j+1,j+1) = sumQ + R + B' * (A^(T-1-j))' * QT * (A^(T-1-j)) * B;
end
uStar = inv(Qtild)*btilde;
x = zeros(2, 21);
x(:,1) = [1; 0];
i = 1;
u = uStar;

sumJ = 0;
for t = 0:T-1
    x(:,t+2) = A*x(:,t+1) + B*u(t+1);
    sumJ = sumJ + x(:,t+1)'*Q*x(:,t+1) + u(t+1)'*R*u(t+1);
end
J = x(:,T+1)'*QT*x(:,T+1) + sumJ

QuadCost = 0.5*u'*Qtild*u - btilde'*u
```

J =

2.0933e+03

QuadCost =

-164.2338