

PART 6

We know $\phi(t) < 0$ for $t=0$

We also know $\dot{\phi}(t) = \frac{1}{m(t)} > 0$

\therefore final time is free $\Rightarrow \delta t_f$ arbitrary

$$\Rightarrow \left[H + \frac{\partial h}{\partial t} \right]_{t_f} = 0$$

$$\Rightarrow p_y v + p_v \left(\frac{u}{m} - g \right) + p_m (-bu) + \left(-\frac{\partial y}{\partial t} \right) \Big|_{t_f} = 0$$

$\underbrace{p_y(t_f)}_{p_y(t_f)=-1} \underbrace{v(t_f)}_{v(t_f)=0} + \underbrace{p_v(t_f)}_{p_v(t_f)=0} \left(\frac{u(t_f)}{m(t_f)} - g \right) + p_m(t_f) (-bu(t_f)) - \underbrace{\frac{\partial y}{\partial t}}_{v(t)} \Big|_{t_f} = 0$

$$\Rightarrow -v(t_f) + 0 - \underbrace{bu(t_f)}_{b>0} p_m(t_f) - v(t_f) = 0$$

$$\Rightarrow u(t_f) p_m(t_f) = 0$$

$$\Rightarrow \text{either } u(t_f) = 0 \Rightarrow \phi(t_f) > 0$$

$$\text{or } p_m(t_f) = 0$$

$$\Rightarrow \phi(t_f) = \frac{p_v(t_f)}{m(t_f)} - p_m(t_f) b$$

$$= 0 - 0 = 0$$

A) if $p_m(t_f) = 0 \Rightarrow t_{sw} = t_f \Rightarrow \phi(t_f) = 0$

$$\text{and } \phi(t) < 0 \text{ for } t \in [0, t_{sw}]$$

$$\phi(t) > 0 \text{ for } t \in (t_{sw}, t_f]$$

$\therefore \phi(t)$ can't be 0 for a finite time interval

B) If $p_m(t_f) \neq 0$ and $u(t_f) = 0$

$$\Rightarrow \phi(t_f) > 0$$

$$\Rightarrow \exists t_{sw} \in (0, t_f)$$

$$\phi(t) < 0 \text{ for } t \in [0, t_{sw}]$$

$$\phi(t) > 0 \text{ for } t \in (t_{sw}, t_f]$$

$$\therefore \phi(0) < 0 \text{ and } \dot{\phi}(t) > 0$$

∴ In both cases, $\exists t_{sw} \in (0, t_f]$
 such that $\phi(t) < 0$ for $t \in [0, t_{sw}]$
 $\phi(t) > 0$ for $t \in (t_{sw}, t_f]$

Note: another way of showing same result

∴ final time is free δt_f arbitrary

$$\Rightarrow \mathcal{H} + \frac{\partial \mathcal{H}}{\partial t} \Big|_{t_f} = 0$$

$$\Rightarrow \left(p_y v + p_v \left(\frac{v}{m} - g \right) + p_m (-b v) \right) - \frac{\partial \mathcal{H}}{\partial t}(t_f) = 0$$

$$\Rightarrow \left(-1 v(t) + u(t) \left(\frac{p_v(t)}{m(t)} - b p_m(t) \right) - g(t - t_f) \right) \Big|_{t_f} - \dot{y}(t_f) = 0$$

$$\Rightarrow -v(t_f) + u(t_f) \phi(t_f) - \underbrace{\dot{y}(t_f)}_{\dot{y}=v} = 0$$

$$\Rightarrow u(t_f) \phi(t_f) = 0$$

∴ Either $\phi(t_f) = 0$ momentarily or
 $u(t_f) = 0 \Rightarrow \phi(t_f) > 0$

However, because \mathcal{H} does not depend explicitly on time,
 we also have the NOC

$$\mathcal{H}(x^*, u^*, p^*) = 0 \quad \forall t \in [t_0, t_f]$$

$$\Rightarrow p_y(t) v_0 + p_v(t) \left(\frac{u(t)}{m(t)} - g \right) + p_m(t) (-b u(t)) = 0$$

\downarrow
 $p_y(t) = -1$ $\rightarrow p_v(t) = t - t_f$

$$\Rightarrow -1 v(t) + u(t) \left(\frac{p_v(t)}{m(t)} - b p_m(t) \right) - (t - t_f) g = 0$$

$$\Rightarrow -v(t) + u(t) \phi(t) - (t - t_f) g = 0$$

$$\Rightarrow u(t) \phi(t) = v(t) + (t - t_f) g$$

$$\text{At } t = t_f \quad \mathcal{H} + \frac{\partial \mathcal{H}}{\partial t} = 0 \Rightarrow \mathcal{H}(t_f) + (-\dot{y}) = 0$$

$$\Rightarrow v(t_f) = 0$$

$$\Rightarrow u(t_f) \phi(t_f) = 0$$

∴ Either $\phi(t_f) = 0$ momentarily or $u(t_f) = 0 \Rightarrow \phi(t_f) > 0$