

## Problem 2 Part 1 – Dichotomy solver

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% Exacly solving Goddard's problem.
% From the homework, we know that Goddard's problem is solved
% with switching time  $t_{Sw} = (m_0 - m_f)/(b*u_{Max})$ . We want to
% discover what is the optimal final time  $t_f$  that maximizes
% the final height  $h(t_f)$ . For this, we implement a dichotomic
% search on  $t_f$  with the following idea: the final time  $t_f$ 
% that maximizes  $h(t_f)$  is the time for which the time derivative
% of  $h(t)$  at  $t_f$  is zero, i.e.,  $0 = h'(t_f) = v(t_f)$ . Then, we
% seek  $t_f$  as the zero for  $v(t_f)$ , where the velocity  $v$  arises
% from integrating the rocket dynamics with the optimal control
% given in the homework, i.e.,  $u(t) = u_{Max}$  if  $t \leq t_{Sw}$  and
%  $u(t) = 0$  otherwise.

clear all; clf; clc; format long;

global g; g = 9.81;
global b;
global uMax;
global h0; h0 = 0.;
global v0; v0 = 0.;
global m0;
global mf;

% Scenario: recall that we must satisfy  $u_{Max} > m_0*g$ 
m0 = 12000; mf = 1000;
b = 1e-3; uMax = 1.2e5;

% Parameters for the dichotomic search.
% For given initial times  $t_A$ ,  $t_B$  such that  $v(t_A) > 0$ ,  $v(t_B) < 0$ ,
% we iteratively evaluate  $v$  at  $t_{Med} = (t_A + t_B)/2$  until we find
%  $v(t_{Med}) = 0$ . Therefore:  $t_f = t_{Med}$ .
tA = 1.;
tB = 500.;
dichotomyFuncTA = dichotomyFunc(tA);
dichotomyFuncTB = dichotomyFunc(tB);
tMed = (tA + tB)/2.;
dichotomyFuncTMed = dichotomyFunc(tMed);
iterDichotomy = 1;
iterDichotomyMax = 1000;
epsDichotomy = 1e-1;

if dichotomyFuncTA < 0 || dichotomyFuncTB > 0
    fprintf('Wrong guess times tA and tB! Choose them such that: v(tA) > 0 and v(tB) < 0...\n',iterDichotomy);
else
    % Classical dichotomic/binary/bisection search
    while ( abs(dichotomyFuncTMed) > epsDichotomy && iterDichotomy < iterDichotomyMax )
        % TODO: Implement dichotomic search. See initialization in
        % lines 32-37 for reference.
        if dichotomyFuncTMed > 0 % search between tMed and tB
            tA = tMed;
        else % search between tA and tMed
            tB = tMed;
        end
        dichotomyFuncTA = dichotomyFunc(tA);
        dichotomyFuncTB = dichotomyFunc(tB);
        tMed = (tA + tB)/2.;
        dichotomyFuncTMed = dichotomyFunc(tMed);
        iterDichotomy = iterDichotomy + 1;
    end
    tf = tMed;

    % Optimal switching time.
    tSw = (m0 - mf)/(b*uMax);
    if tSw > tf % Verifying that:  $0 < t_{Sw} \leq t_f$ 
        tSw = tf;
    end
end
```

Switching time  $t_{Sw} = 91.666667$   
Final time  $t_f = 253.302002$

