

Part d

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$$x(t+1) = c x(t) x(t-1) + w(t)$$

$$\underbrace{\begin{bmatrix} x(2) \\ \vdots \\ x(N) \end{bmatrix}}_Y = \underbrace{\begin{bmatrix} x(1) * x(0) \\ \vdots \\ x(N-1) * x(N-2) \end{bmatrix}}_H \underbrace{\begin{bmatrix} c \end{bmatrix}}_{\theta} + w$$

$w \sim \mathcal{N}(0, \sigma)$

$$\min_{\theta} \|Y - H\theta\|$$

$$\theta^d = H \setminus Y \quad \text{still applies!}$$

The system is linear in θ and we can compute the matrices Y & H from known data so the linear least squares approach still works.

See code:

N = 10 : Least squares estimate of c is mean 0.07 with std dev 0.44

N = 100 : Least squares estimate of c is mean 0.09 with std dev 0.09

N = 1000 : Least squares estimate of c is mean 0.10 with std dev 0.03

Again, we see that having more data makes our estimates better (closer to true value of $c = 0.10$ and smaller standard deviation).