```
% Cost of the problem
function c = cost(var)
global N;
% Note that var = [y;v;m;u]
y = var(1:N+1); v = var(N+2:2*N+2); m = var(2*N+3:3*N+3); u = var(3*N+4:4*N+3);
% Put here the cost
c = -y(end);
```

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