

$$\min_{x \in \mathbb{R}^n} f(x) := \frac{1}{2} x^T Q x - b^T x$$

$$Q \in \mathbb{R}^{n \times n} \text{ pos def } \lambda_1, \dots, \lambda_n > 0 \text{ (symm)}$$

$$b \in \mathbb{R}^n$$

a) candidate x^* for local min^m

$$\nabla f(x^*) = 0 \quad \text{and} \quad \nabla^2 f(x^*) \text{ pos def}$$

$$\Rightarrow Q x^* - b = 0 \quad \Rightarrow Q \text{ pos def}$$

$$\Rightarrow \boxed{x^* = Q^{-1} b} \quad \checkmark \text{ given!}$$

\therefore only candidate is $x^* = Q^{-1} b$

$\because Q$ is pos def everywhere

$$\Rightarrow \nabla^2 f(x) \text{ " " " "}$$

$\Rightarrow f$ is strictly convex

$\therefore \boxed{x^* = Q^{-1} b \text{ is both local \& global min}^m}$

b) After $x^{(0)} \in \mathbb{R}^n$, we pick

$$x^{(1)} = x^{(0)} - \alpha^k (\nabla^2 f(x^{(0)}))^{-1} \nabla f(x^{(0)})$$

If we pick step size $\alpha = 1 = \eta_0$

$$x^{(1)} = x^{(0)} - 1 \cdot Q^{-1} (Q x^{(0)} - b)$$

$$\Rightarrow x^{(1)} = x^{(0)} - x^{(0)} + Q^{-1} b$$

$$\Rightarrow \boxed{x^{(1)} = Q^{-1} b = x^*}$$

So, we converge in 1 iteration to x^*

If n is large and Q has no particular structure, then computing inverse of $Q \in \mathbb{R}^{n \times n}$ is very computationally expensive, making this method intractable.

c) $S \in \mathbb{R}^{n \times n}$ is symm

$$\Rightarrow S = U \Sigma U^T \quad U \in \mathbb{R}^{n \times n} \text{ orthogonal}$$

$$\Sigma = \text{diag}(\mu_1, \dots, \mu_n)$$

$x \in \mathbb{R}^n$

$$\|Sx\|_2 = \|U \Sigma U^T x\|_2$$

$$\text{Let } \Sigma U^T x = y \Rightarrow y \in \mathbb{R}^{n \times n} \mathbb{R}^{n \times n} \mathbb{R}^{n \times 1}$$

$$\Rightarrow y \in \mathbb{R}^n$$

$$\therefore \|Uy\|_2 = \|U^T y\|_2 = \|y\|_2$$

$\because U$ is orthogonal

$$\therefore \|Sx\|_2 = \|U \underbrace{\Sigma U^T x}_y\|_2 = \|\Sigma U^T x\|_2$$

For any $z \in \mathbb{R}^n$

$$\Sigma z = \begin{bmatrix} \mu_1 & & 0 \\ & \mu_2 & \\ 0 & & \ddots \\ & & & \mu_n \end{bmatrix} \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix} = \begin{bmatrix} \mu_1 z_1 \\ \mu_2 z_2 \\ \vdots \\ \mu_n z_n \end{bmatrix}$$

$$\text{Let } \mu^* = \max_{i=1:n} |\mu_i|$$

$$\Rightarrow \|\Sigma z\| = \left\| \begin{bmatrix} \mu_1 z_1 \\ \vdots \\ \mu_n z_n \end{bmatrix} \right\| = \left(\sum_{i=1:n} \mu_i^2 z_i^2 \right)^{1/2}$$

$$\text{Each } \mu_i^2 z_i^2 \leq \mu^{*2} z_i^2 \quad \because |\mu^*| \geq |\mu_i|$$

by defⁿ

$$\Rightarrow \|\Sigma z\|_2 \leq \left(\mu^{*2} \sum_{i=1:n} z_i^2 \right)^{1/2} = \mu^* \|z\|_2$$

$$\Rightarrow \|\Sigma z\|_2 \leq \left(\max_{i=1:n} |\mu_i| \right) \|z\|_2$$

$$\text{We showed } \|Sx\|_2 = \|\Sigma \underbrace{U^T x}_z\|_2$$

$$\text{Let } U^T x = z$$

$$\|\Sigma z\|_2 \leq \left(\max_{i=1:n} |\mu_i| \right) \|z\|_2$$

$$\Rightarrow \|Sx\|_2 \leq \left(\max_{i=1:n} |\mu_i| \right) \|U^T x\|_2$$

$$\because U \text{ orthogonal } \|U^T x\|_2 = \|x\|_2$$

$$\Rightarrow \|Sx\|_2 \leq \left(\max_{i=1:n} |\mu_i| \right) \|x\|_2$$

$$d) \eta > 0 \quad \text{eig of } Q \rightarrow \lambda_1, \dots, \lambda_n \quad \|Q - \lambda I\| = 0$$

$$\Rightarrow Q v_i = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} v_i$$

eig of $I - \eta Q$. Choose $v_i = \text{eig vectors of } Q$.

$$\begin{aligned} (I - \eta Q) v_i &= I v_i - \eta Q v_i \\ &= v_i - \eta \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} v_i \\ &= \begin{bmatrix} 1 - \eta \lambda_1 & & 0 \\ & \ddots & \\ 0 & & 1 - \eta \lambda_n \end{bmatrix} v_i \end{aligned}$$

$$\therefore (1 - \eta \lambda_1), (1 - \eta \lambda_2), \dots, (1 - \eta \lambda_n) \text{ are eigenvalues of } (I - \eta Q).$$

$$e) \quad x^{(k+1)} = x^{(k)} - \eta \nabla f(x^{(k)})$$

$$\delta_{k+1} := \|x^{(k+1)} - x^*\|_2 \quad \delta_k := \|x^{(k)} - x^*\|_2$$

$$x^* = Q^{-1} b \Rightarrow b = Q x^*$$

$$\delta_{k+1} = \|x^{(k)} - \eta \nabla f(x^{(k)}) - x^*\|_2$$

$$f(x) = \frac{1}{2} x^T Q x - b^T x$$

$$\nabla f(x^{(k)}) = Q x^{(k)} - b$$

$$\begin{aligned} \delta_{k+1} &= \|x^{(k)} - \eta Q x^{(k)} + \eta b - x^*\|_2 \\ &= \|x^{(k)} - x^* - \eta Q x^{(k)} + \eta Q x^*\|_2 \\ &= \|\underbrace{(I - \eta Q)}_S \underbrace{(x^{(k)} - x^*)}_y\|_2 \end{aligned}$$

$$\text{We showed } \|Sy\|_2 \leq \left(\max_{i=1:n} |\mu_i| \right) \|y\|_2$$

where μ_i are eigenvalues of S

Here eigenvalues of $I - \eta Q$ are $1 - \eta \lambda_i$
 where λ_i are eigenvalues of Q

$$\therefore \delta_{k+1} = \|(I - \eta Q)(x^{(k)} - x^*)\|_2 \\ \leq \left(\max_{i=1:n} |1 - \eta \lambda_i| \right) \|x^{(k)} - x^*\|_2$$

$$\Rightarrow \boxed{\delta_{k+1} \leq \gamma(\eta) \delta_k}$$

where $\gamma(\eta) = \max_{i=1:n} |1 - \eta \lambda_i|$

By induction,

$$\delta_1 \leq \gamma(\eta) \delta_0$$

$$\delta_k \leq \gamma(\eta) \delta_{k-1} \leq \gamma(\eta)^2 \delta_{k-2} \leq \gamma(\eta)^3 \delta_{k-3} \dots$$

$$\Rightarrow \boxed{\delta_k \leq \gamma(\eta)^k \delta_0}$$

We want $\lim_{k \rightarrow \infty} x^{(k)} = x^*$

$$\Rightarrow \lim_{k \rightarrow \infty} \delta_k = 0$$

$$\Rightarrow \text{reqd } 0 < \gamma(\eta) < 1$$

$$\Rightarrow \max_{i=1:n} |1 - \eta \lambda_i| < 1$$

$$\Rightarrow \forall i=1:n \quad 0 < \eta \lambda_i < 2$$

$$\Rightarrow \forall i=1:n \quad 0 < \eta < 2/\lambda_i$$

f) $d_k = -\nabla f(x^{(k)})$

$$\eta_k = \underset{\eta \geq 0}{\operatorname{argmin}} f(x^{(k)} + \eta d_k)$$

$$f(x^{(k)}) = \frac{1}{2} x^{(k)T} Q x^{(k)} - b^T x^{(k)}$$

$$\nabla f(x^{(k)}) = Q x^{(k)} - b$$

$$\Rightarrow d_k = -Q x^{(k)} + b \quad \Rightarrow x^{(k)} = Q^{-1}(b - d_k)$$

$$\eta_k \text{ st } f(x^{(k)} + \eta d_k) \text{ minimized wrt } \eta$$

$$x^{(k)} + \eta d_k = Q^{-1}b - Q^{-1}d_k + \eta d_k$$

$$\bullet \quad f(x^{(k)} + \eta d_k) = \frac{1}{2} (x^{(k)} + \eta d_k)^T Q (x^{(k)} + \eta d_k) - b^T (x^{(k)} + \eta d_k)$$

$$\dots f(x^k + \eta d_k) - \frac{1}{2} (Q^T b - Q^T d_k + \eta d_k)^T (Q^T b - Q^T d_k + \eta d_k) = 0$$

$$\frac{\partial f(x^k + \eta d_k)}{\partial \eta} = 0$$

$$\Rightarrow d_k^T Q (Q^T b - Q^T d_k + \eta d_k) - d_k^T b = 0$$

$$\Rightarrow \cancel{d_k^T b} - d_k^T d_k + \eta d_k^T Q \cdot d_k - \cancel{d_k^T b} = 0$$

$$\Rightarrow \eta d_k^T Q d_k = \|d_k\|_2^2$$

$$\Rightarrow \boxed{\eta_k = \frac{\|d_k\|_2^2}{d_k^T Q d_k}}$$

$$g) x^* = Q^{-1} b \quad n=2 \quad r=10$$

$$f(x) = \frac{1}{2} (x_1^2 + r x_2^2) \quad Q: \mathbb{R}^{2 \times 2}$$

$$= \frac{1}{2} \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} \alpha & \beta \\ \delta & \varepsilon \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \begin{bmatrix} b_1 & b_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} \alpha x_1 + \delta x_2 & \beta x_1 + \varepsilon x_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - (b_1 x_1 + b_2 x_2)$$

$$= \frac{1}{2} (\alpha x_1^2 + (\delta + \beta) x_1 x_2 + \varepsilon x_2^2) - (b_1 x_1 + b_2 x_2)$$

$$\Rightarrow \alpha=1 \quad \varepsilon=r \quad \beta=\delta=0$$

$$b_1=b_2=0$$

$$\Rightarrow x^* = \begin{bmatrix} 1 & 0 \\ 0 & r \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\nabla f(x^{(k)}) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix} = \begin{bmatrix} x_1 \\ r x_2 \end{bmatrix}$$

$$\lambda_i = \text{eig}(Q) = 1, \quad r$$

reqd for const step size $0 < \eta < \frac{2}{\lambda_i} \quad \forall i$

$$\Rightarrow 0 < \eta < 2 \quad \text{and} \\ 0 < \eta < \frac{2}{r}$$

So we pick $\eta < 2/10$

$\eta = 0.05$ for example

Optimal soln: $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Exact line search:

- finds soln faster
- for lower $\gamma = 2$, it overshoots the solution
- we see a zig zag close to the optimal solution where slight (+)ve or (-)ve gradients cause zig zagging due to sharp change in η

Constant step size:

- takes many iterations to find solution
- takes a smooth path to origin for both $\gamma = 10$ and $\gamma = 2$

