Intensity Values

BIOMEDICAL IMAGE ANALYSIS IN PYTHON



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Instructor



Pixels and voxels

- Pixels are 2D picture elements
- Voxels are 3D volume elements
- Two properties: intensity and location



Data types and image size

Array's data type controls range of possible intensities

Type	Range	No. Val.
uint8	0, 255	256
int8	- 128, 127	256
uint16	O, 2 ¹⁶	2 ¹⁶
int16	-2 ¹⁵ , 2 ¹⁵	2 ¹⁶
float16	~-2 ¹⁶ , ~2 ¹⁶	>>2 ¹⁶

```
import imageio
im=imageio.imread('foot-xray.jpg')
im.dtype
        dtype('uint8')
im.size
```

153600

```
im_int64 = im.astype(np.uint64)
im_int64.size
```

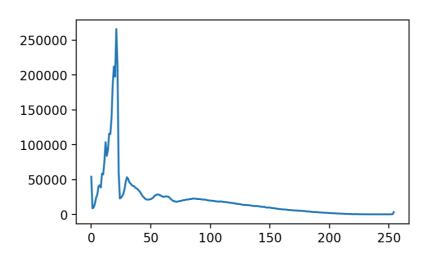
1228800

Histograms

- Histograms: count number of pixels at each intensity value.
- Implemented in scipy.ndimage
 - higher-dimensional arrays
 - masked data
- Advanced techniques and functionality in scikit-image.

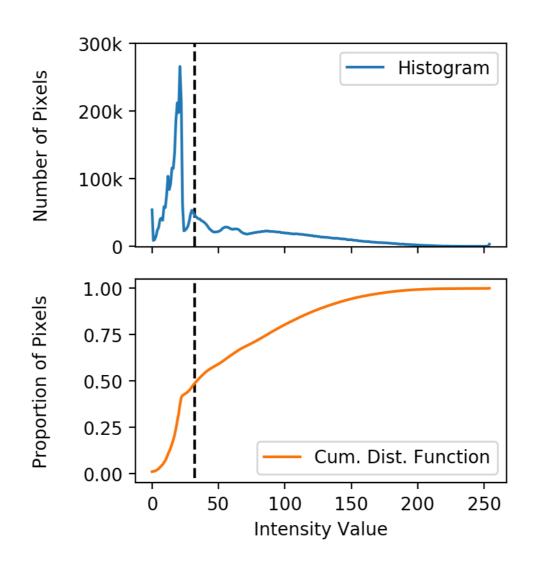
```
plt.plot(hist)
plt.show()
```

(256,)



Equalization

- Distributions often skewed toward low intensities (background values).
- Equalization: redistribute values to optimize full intensity range.
- Cumulative distribution
 function: (CDF) shows
 proportion of pixels in range.



Equalization

Dx P

(256,)

```
im_equalized = cdf[im] * 255
fig, axes = plt.subplots(2, 1)
axes[0].imshow(im)
axes[1].imshow(im_equalized)
plt.show()
```



Let's practice!

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Masks

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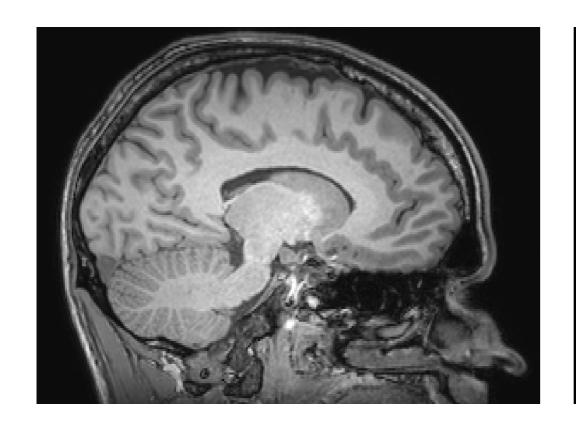
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Masks

Raw image







Creating masks

Logical operations result in

True / False at each pixel

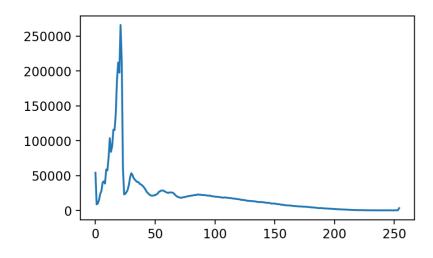
Sample Operations

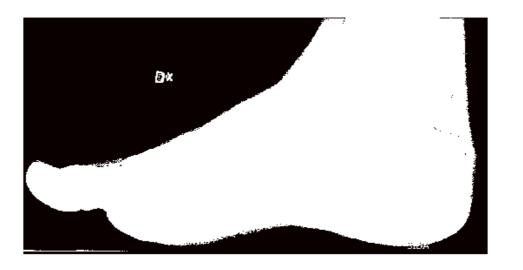
Operation	Example		
Greater	im > 0		
Equal to	im == 1		
X and Y	(im > 0) & (im < 5)		
X or Y	(im > 10) (im < 5)		

Creating masks

hist=ndi.histogram(im, 0, 255, 256)

$$mask1 = im > 32$$

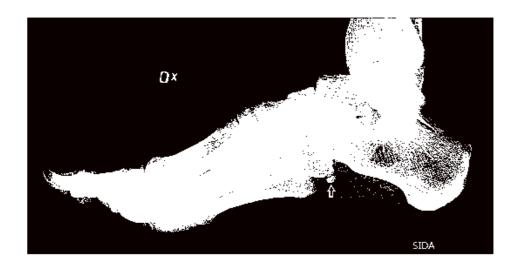




Creating masks

mask2 = im > 64

mask3 = mask1 & ~mask2





Applying masks

np.where(condition, x, y)
controls what data passes
through the mask.

```
import numpy as np
im_bone = np.where(im > 64, im, 0)
```

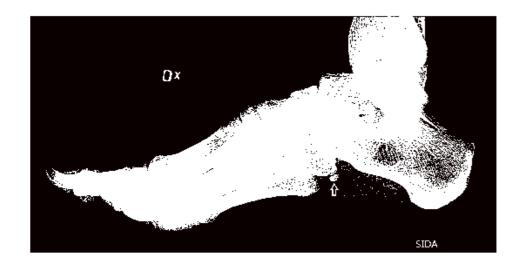
```
plt.imshow(im_bone, cmap='gray')
plt.axis('off')
plt.show()
```



Tuning masks

```
m = np.where(im > 64, 1, 0)
```

ndi.binary_dilation(m,iterations=5)





Tuning masks

ndi.binary_erosion(m,iterations=5)



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Filters

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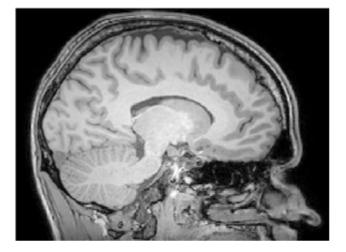


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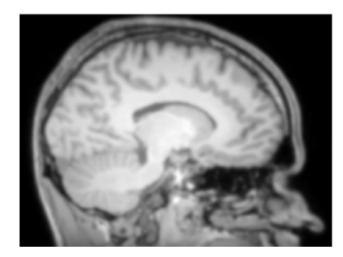


Filters

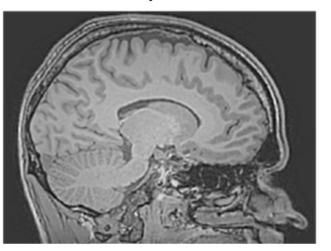
Original



Smoothed



Sharpened



Convolution with a sharpening filter

*

Input Array

1	1	1	1	1
1	1	1	1	1
1	1	2	1	1
1	1	1	1	1
1	1	1	1	1

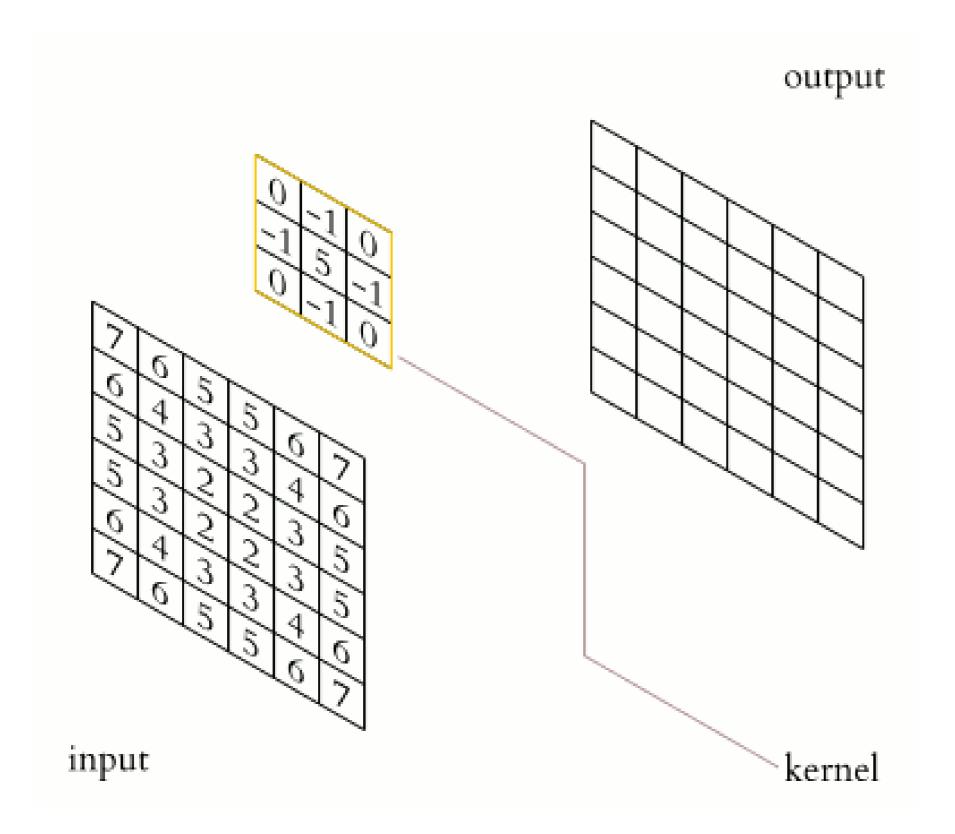
Filter Weights / Kernel

0	-1	0
-1	5	-1
0	-1	0



Convolution with a sharpening filter

(
	1 * 0	1 * -1	1 * 0		
Sum	1 * -1	2 * 5	1 * -1	=	6
	1 * 0	1 * -1	1 * 0		
				J	



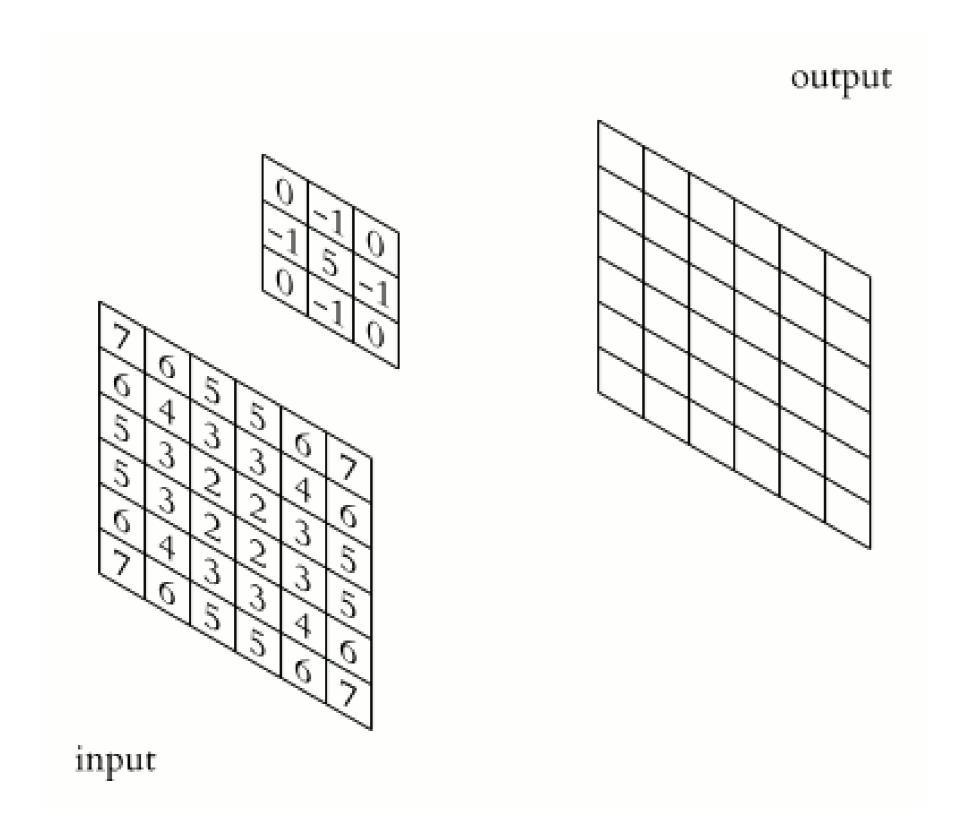


Image convolution

```
fig, axes = plt.subplots(2, 1)
axes[0].imshow(im, cmap='gray')
axes[1].imshow(im_filt,cmap='gray')
plt.imshow()
```





Filtering functions

scipy.ndimage.filters
includes:

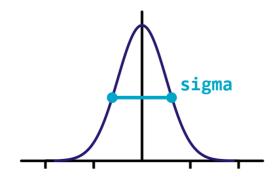
- median_filter()
- uniform_filter()
- maximum_filter()
- percentile_filter()

ndi.median_filter(im, size=10)



Gaussian filtering

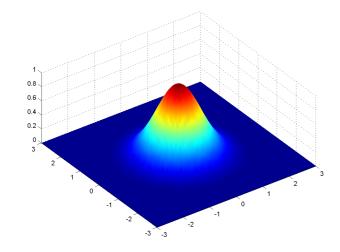
Gaussian distribution in 1 dimension



ndi.gaussian_filter(im, sigma=5)



Gaussian distribution in 2 dimensions



ndi.gaussian_filter(im, sigma=10)



Let's practice!

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Feature detection

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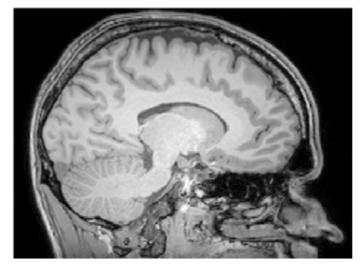
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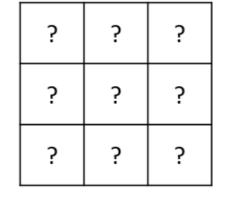
Edges: sharp changes in intensity

*

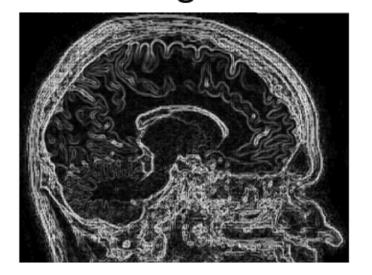
Original

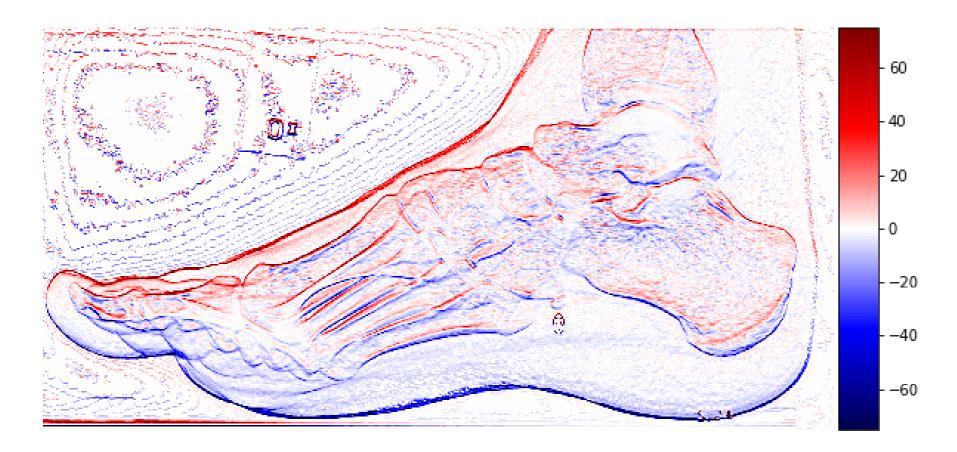


Kernel



Edges





Sobel filters

Sobel (H)

1	2	1
0	0	0
-1	-2	-1

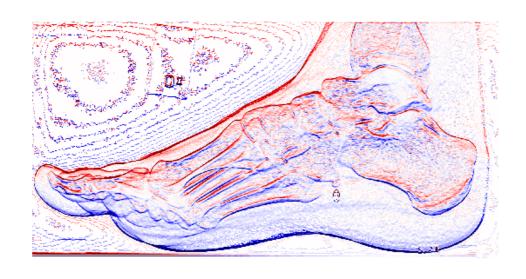
Sobel (V)

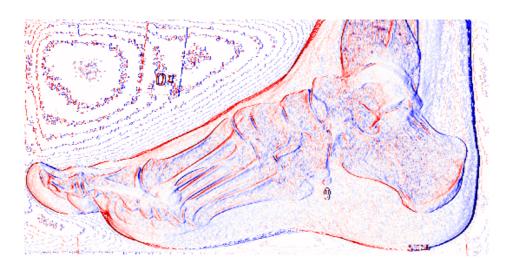
1	0	-1
2	0	-2
1	0	-1

Sobel filters

ndi.sobel(im, axis=0)

ndi.sobel(im, axis=1)



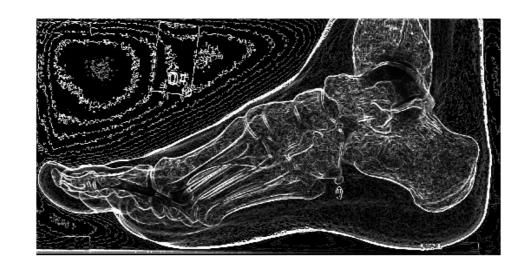


Sobel filter magnitude

Combine horizontal and vertical edge data by calculating distance:

$$z=\sqrt{x^2+y^2}$$

plt.imshow(edges, cmap='gray')



Let's practice!

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