

# Phys209: Mathematical Methods in Physics I

## Homework 4

Soner Albayrak<sup>†</sup>

<sup>†</sup>*Middle East Technical University, Ankara 06800, Turkey*

### Policies

- Please adhere to the *academic integrity* rules: see my explanations [here](#) for further details!
- For the overall grading scheme or any other course-related details, see [the syllabus](#).
- Non-graded question(s) are for your own practice!
- Unless stated otherwise, you are expected to show your derivation of the results.
- The homework is due November 3<sup>rd</sup> 2023, 23:59 TSI.

## (1) Problem One

(3 points)

We have seen in class that the solution for a linear ordinary differential equation with constant coefficients for the unknown function  $f$  is

$$\left( a_n \frac{d^n}{dx^n} + \cdots + a_1 \frac{d}{dx} + a_0 \right) f(x) = h(x)$$

$$\Downarrow$$

$$f(x) = \sum_i \left[ \left( \sum_{k=0}^{\alpha_i} c_{ik} x^k \right) e^{r_i x} \right] + \int_0^\infty h(x-y) i(y) dy \quad (1.1)$$

for the impulse response  $i(x)$  and the roots of the characteristic equation  $r_i$ .

A similar general solution can not be found for differential equations with *functional coefficients*; nevertheless, there are some exceptions: we will discuss a few such cases in this homework.

### (1.1) (0.6pt)

Consider the differential operator

$$\text{👻}_a :: (\mathbb{C} \rightarrow \mathbb{C}) \rightarrow (\mathbb{C} \rightarrow \mathbb{C}) \quad (1.2a)$$

$$\text{👻}_a = (x \rightarrow f(x)) \rightarrow (x \rightarrow [x f'(x) - a f(x)]) \quad (1.2b)$$

and remember the zero function (denoted with pumpkin in this homework) defined as follows

$$\text{🎃} :: \mathbb{C} \rightarrow \mathbb{C} \quad (1.3a)$$

$$\text{🎃} = x \rightarrow 0 \quad (1.3b)$$

We claim that the “ghost” function  $\text{👻}_\Delta$  defined as

$$\text{👻}_\Delta :: \mathbb{C} \rightarrow \mathbb{C} \quad (1.4a)$$

$$\text{👻}_\Delta = x \rightarrow x^\Delta \quad (1.4b)$$

solves the following differential equation

$$\text{👻}_a \cdot \text{👻}_\Delta = \text{🎃} \quad (1.5)$$

for a particular value of  $\Delta$ . What is that value?

Hint: This question is equivalent to asking “What is the parameter  $\Delta$  for

which  $\left( x \frac{d}{dx} - a \right) x^\Delta = 0$ ?”

**(1.2) (0.6pt)**

Two operators  $\mathcal{D}_1$  and  $\mathcal{D}_2$  are said to commute if their action on a function can be interchanged, i.e.  $\mathcal{D}_1 \cdot \mathcal{D}_2 \cdot f = \mathcal{D}_2 \cdot \mathcal{D}_1 \cdot f$  for any function  $f$  if  $\mathcal{D}_1$  and  $\mathcal{D}_2$  commute.

The commutation of the differential operators (or its lack of) is vitally important in many physical applications; in the case of differential equations, it actually helps us solve them generically to any order.

Remember the linear ordinary differential equations *with constant coefficients*, which can be rewritten in the form

$$\mathcal{D}_{a_1} \cdot \mathcal{D}_{a_2} \cdots \mathcal{D}_{a_n} \cdot f = 0 \quad (1.6)$$

if we define the following differential operator

$$\mathcal{D}_a :: (\mathbb{C} \rightarrow \mathbb{C}) \rightarrow (\mathbb{C} \rightarrow \mathbb{C}) \quad (1.7a)$$

$$\mathcal{D}_a = (x \rightarrow f(x)) \rightarrow (x \rightarrow [f'(x) - af(x)]) \quad (1.7b)$$

The main reason we can solve such equations generically is because **(a)** differential equations with constant coefficients can be rewritten in this product form, and **(b)** these operators commute with themselves: if we define *the commutator of two operators A and B* as

$$[A, B] \cdot f := A \cdot B \cdot f - B \cdot A \cdot f \quad (1.8)$$

for any function  $f$ , then we can actually show that

$$[\mathcal{D}_a, \mathcal{D}_b] \cdot f = 0 \quad (1.9)$$

Prove this relation!

**(1.3) (0.6pt)**

The relation in (1.9) is the reason why we can solve differential equations with constant coefficients to any generic order! To see that, observe the following: if  $f$  satisfies the relation

$$\mathcal{D}_{a_n} \cdot f = 0 \quad (1.10)$$

then it immediately satisfies the equation in (1.6) as the following relation is trivially satisfied:

$$\mathcal{D}_{a_1} \cdot \mathcal{D}_{a_2} \cdots \mathcal{D}_{a_{n-1}} \cdot 0 = 0 \quad (1.11)$$

In values, this equation simply means “*multiplication with any constant*” and “*taking any order of derivatives*” would always take 0 to 0.

We can solve  $\text{skull}_{a_n} \cdot f = \text{smiley}$  as it is a simple first order differential equation—we have derived this in class, also see the notes for explicit computation. This leads to the well known result  $f = x \rightarrow e^{a_n x}$ . The commutation in equation (1.9) is then sufficient to get the full solution: by symmetry, we also should have solutions such as  $f = x \rightarrow e^{a_1 x}$ , and by linearity the full solution should be the superposition:  $\sum_{i=1}^n c_i e^{a_i x}$  for arbitrary coefficients  $c_i$ . As this solution contains  $n$  unknowns, our order- $n$  differential equation cannot have any other homogeneous solution, which concludes the derivation of the most general solution.

We discussed in class that there are some differential equations *with functional coefficients* that we can solve for generic order. The main reason for this is because they can be recast in the product form

$$\mathcal{D}_{a_1} \cdot \mathcal{D}_{a_2} \cdots \mathcal{D}_{a_n} \cdot f = \text{smiley} \quad (1.12)$$

for some first order differential operator  $\mathcal{D}_a$  which commutes with itself. Indeed, we can also solve the differential equation

$$\text{bat}_{a_1} \cdot \text{bat}_{a_2} \cdots \text{bat}_{a_n} \cdot f = \text{smiley} \quad (1.13)$$

as

$$[\text{bat}_a, \text{bat}_b] \cdot f = \text{smiley} \quad (1.14)$$

Prove this commutation!

#### (1.4) (0.6pt)

Derive the following commutator:

$$[\text{skull}_a, \text{bat}_b] = ??? \quad (1.15)$$

You will see that this commutator is not the zero function: this means, we cannot write down a generic result for an arbitrary order differential equation of the form

$$\text{skull}_{a_1} \cdot \text{skull}_{a_2} \cdot \text{bat}_{b_1} \cdot \text{skull}_{a_3} \cdots \text{bat}_{b_k} \cdot \text{skull}_{a_\ell} \cdot f = \text{smiley} \quad (1.16)$$

**(1.5) (0.6pt)**

In § 1.1, you solved the differential equation

$$\text{🦇}_a \cdot \text{👻}_\Delta = \text{😊} \quad (1.17)$$

and we showed in § 1.3 that

$$[\text{🦇}_a, \text{🦇}_b] \cdot f = \text{😊} \quad (1.18)$$

Using these information, solve the generic differential equation

$$\text{🦇}_{a_1} \cdot \text{🦇}_{a_2} \cdots \text{🦇}_{a_n} \cdot f = \text{😊} \quad (1.19)$$

**(2) Problem Two**

(3 points)

A second order linear ordinary differential equation can generically be brought to the form

$$\left[ \frac{d^2}{dx^2} + p(x) \frac{d}{dx} + q(x) \right] f(x) = 0 \quad (2.1)$$

which can be rewritten as a linear ordinary differential equation *with constant coefficients* via the change of variables from  $x$  to  $u(x)$  for

$$u(x) = \int \sqrt{q(x)} dx \quad (2.2)$$

if the following equality is satisfied as we have derived in class:

$$\frac{q'(x) + 2p(x)q(x)}{2q(x)^{3/2}} = \text{constant} \quad (2.3)$$

Since we know how to solve differential equations with constant coefficients, we can then immediately compute the result. In this problem, we are going to review this methodology.

**(2.1) (0.5pt)**

Consider the following differential equation:

$$\left[ \frac{d^2}{dx^2} + \pi \tan(\pi x) \frac{d}{dx} + \pi^4 \cos^2(\pi x) \right] f(x) = 0 \quad (2.4)$$

What should be the new parameter  $u(x)$ ?

**(2.2) (0.5pt)**

Is the necessary condition in equation (2.3) satisfied for this differential equation?

**(2.3) (0.5pt)**

What is the new differential equation in terms of the parameter  $u$ ?

**(2.4) (0.5pt)**

What is the solution to this differential equation? Write down the function  $f$  in terms of the variable  $u$ .

*Hint: Any function of the form  $c_1 \exp(ix) + c_2 \exp(-ix)$  for arbitrary  $c_i$  can be rewritten as  $d_1 \cos(x) + d_2 \sin(x)$  for arbitrary  $d_i$ . Both expressions are mathematically same, but the second one makes more intuitive sense in many physical systems of real parameters.*

**(2.5) (0.5pt)**

Write down the answer in terms of the original variable  $x$ .

**(2.6) (0.5pt)**

Assume that you are given the initial conditions

$$f(x=0) = 12000212\sqrt{2} \quad (2.5a)$$

$$f'(x=0) = 17101711\sqrt{2}\pi^2 \quad (2.5b)$$

What would be the value of this function at  $x = \text{asin}(1/4)/\pi$ , i.e

$$f\left(x = \frac{\text{asin}(1/4)}{\pi}\right) = ??? \quad (2.6)$$

**(2.7) Bonus question**

*(not graded)*

The result of the previous question is a 8-digit number  $\#_1\#_2\#_3\#_4\#_5\#_6\#_7\#_8$  which can be reinterpreted as a date, i.e.  $\#_1\#_2 / \#_3\#_4 / \#_5\#_6\#_7\#_8$ . Let's talk about it in this part.

For international students, I suggest that you google this date: it leads to a Wikipedia page with English as a language option. It would

be good for you to know a little bit about the country that you are currently residing, so I suggest that you check out that Wikipedia page!

I expect that all non-international students are already aware of this date and (hopefully) are celebrating it! Enjoy being in a part of the modern world!

In these non-graded questions, we usually introduce some Mathematica code to solve some problems; let us do something similar in this homework. You may explicitly check that the following code finds out which day of the week  $\#_1\#_2 / \#_3\#_4 / \#_5\#_6\#_7\#_8$  was:

```
DateObject[{year, month, day}, "Day", "Gregorian", 0]
```

Or you may wanna check out the population of Turkey on that year:

```
CountryData["Turkey", {"Population", year}]
```

If you are interested, you may play with similar commands to get more information about the history of Turkey. Enjoy!