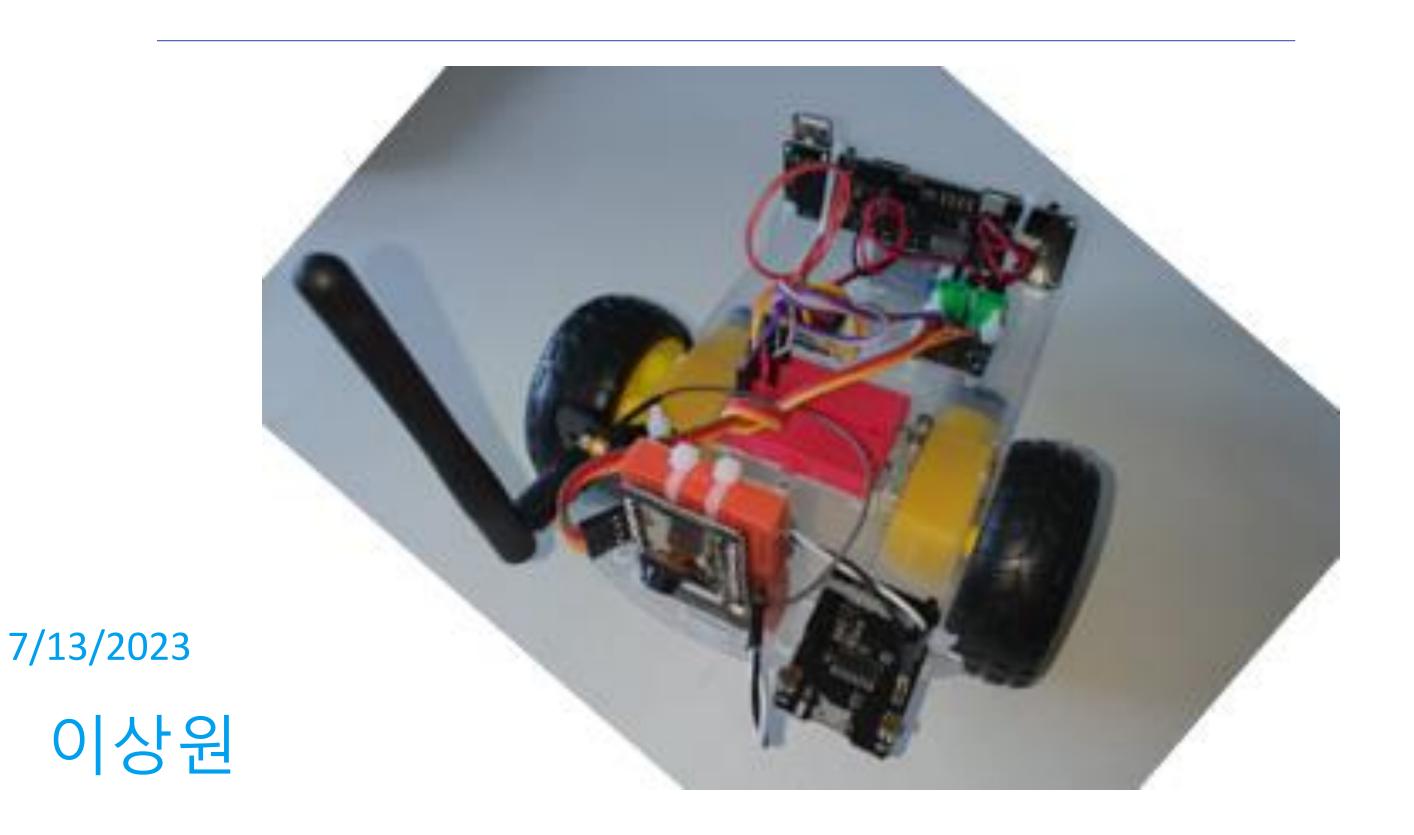
ASSEMBLY OF ESP32-CAM ROBOT



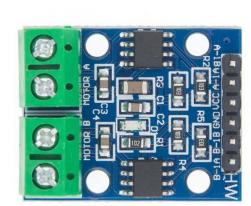
목 차

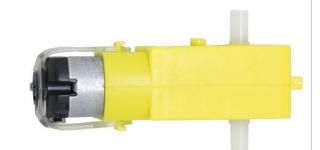
- □ ESP32CAM 로봇 부품 구성
- □ 배송 상자
- □ 캐스터 바퀴 조립 및 모터 브라켓 조립
- □ L9110S Board 및 Mini Broad Board 장착
- ☐ ESP32-CAM 및 안테나 설치
- □ 18650 충전기에 점퍼 납땜 및 프레임에 고정
- □ 배선

로봇부품구성







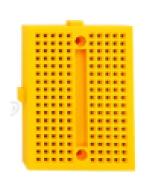
















배송상자

RC 카 프레임 상자



부품 상자

바퀴 및 모터 조립 1

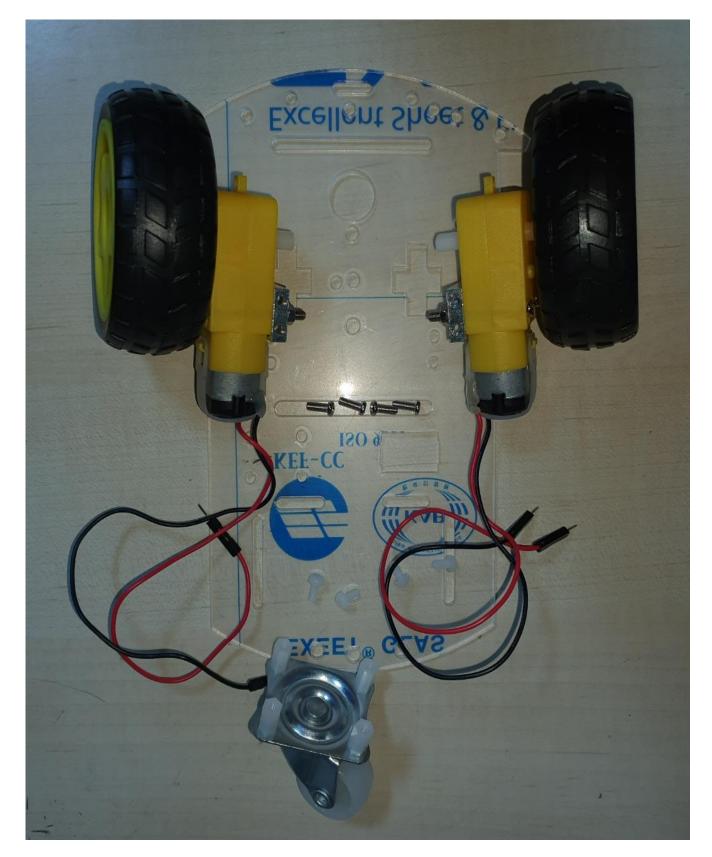
캐스터 바퀴 조립



DC 모터 브라켓 및 바퀴 조립

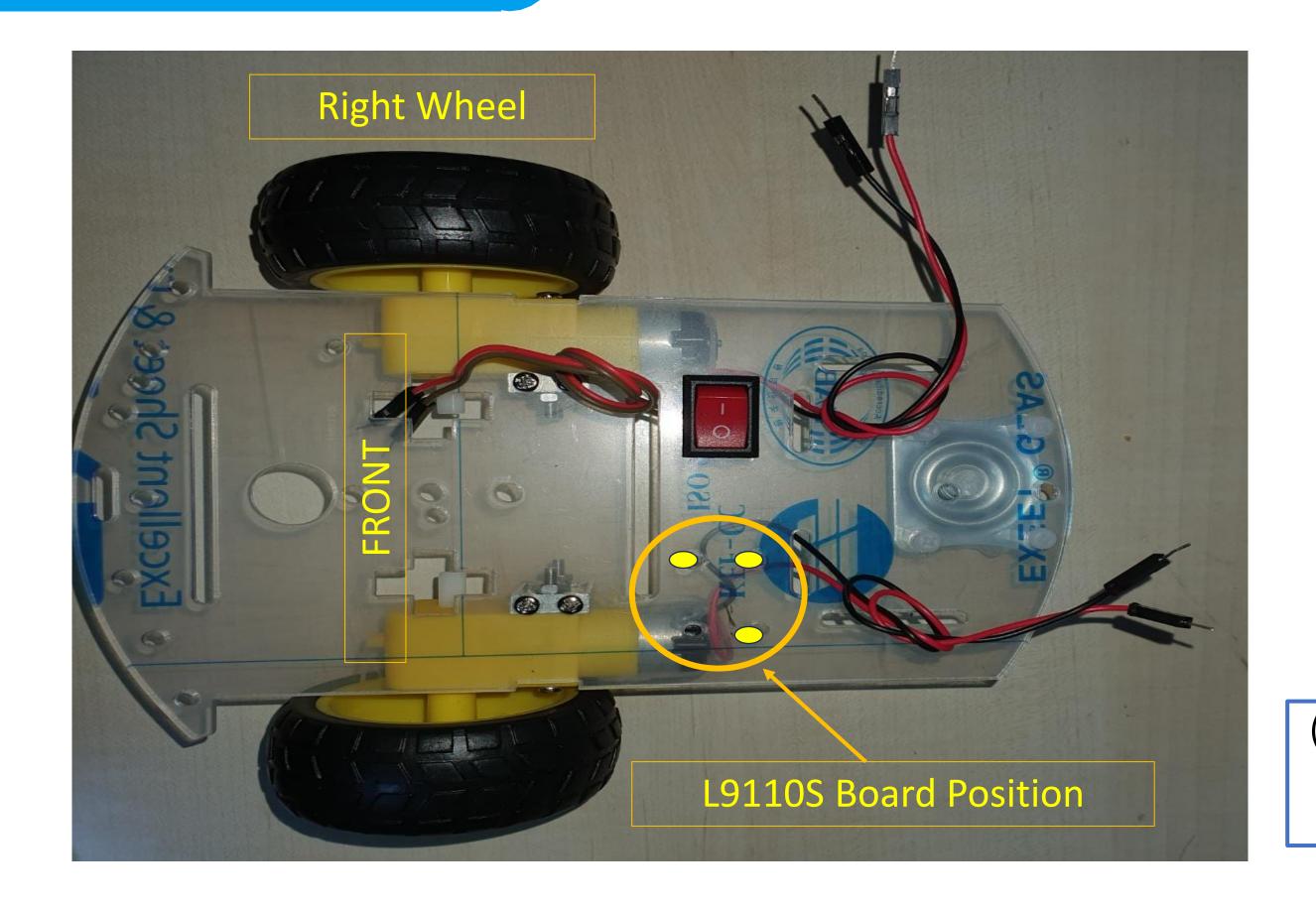
FRONT

L E F T



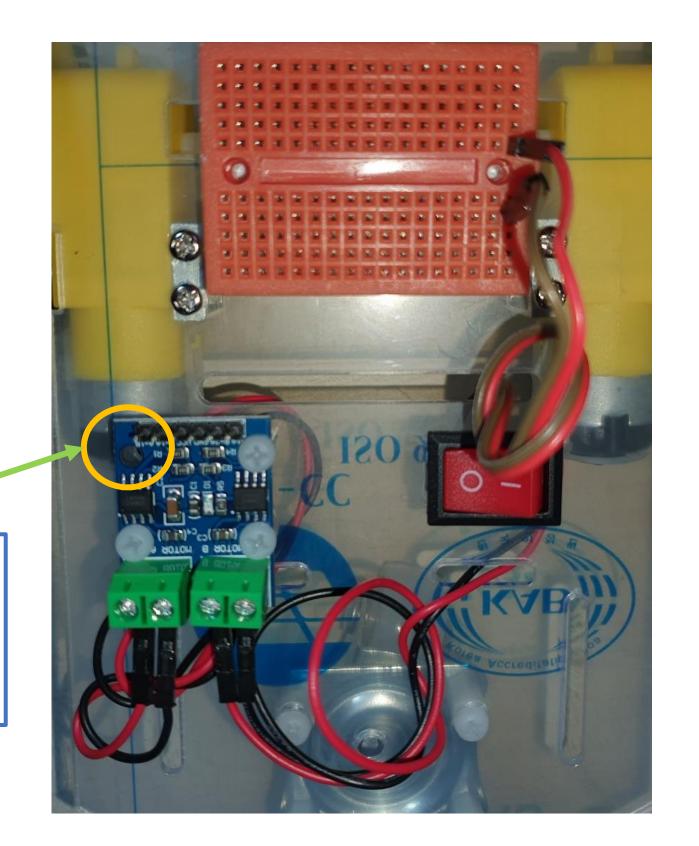
R I G H T

바퀴 및 모터 조립 2

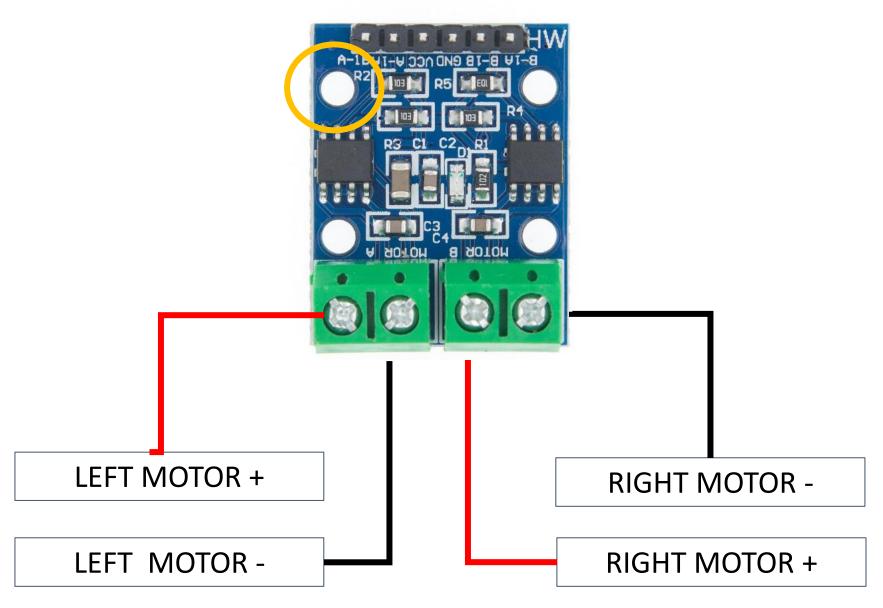


(왼쪽 모터 간섭으로 L9110S 기판의 지지대 한 곳이 조립이 어려움. 삭제)

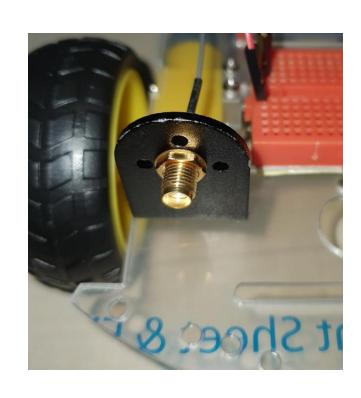
L9110S 보드 및 Mini Breadboard 조립

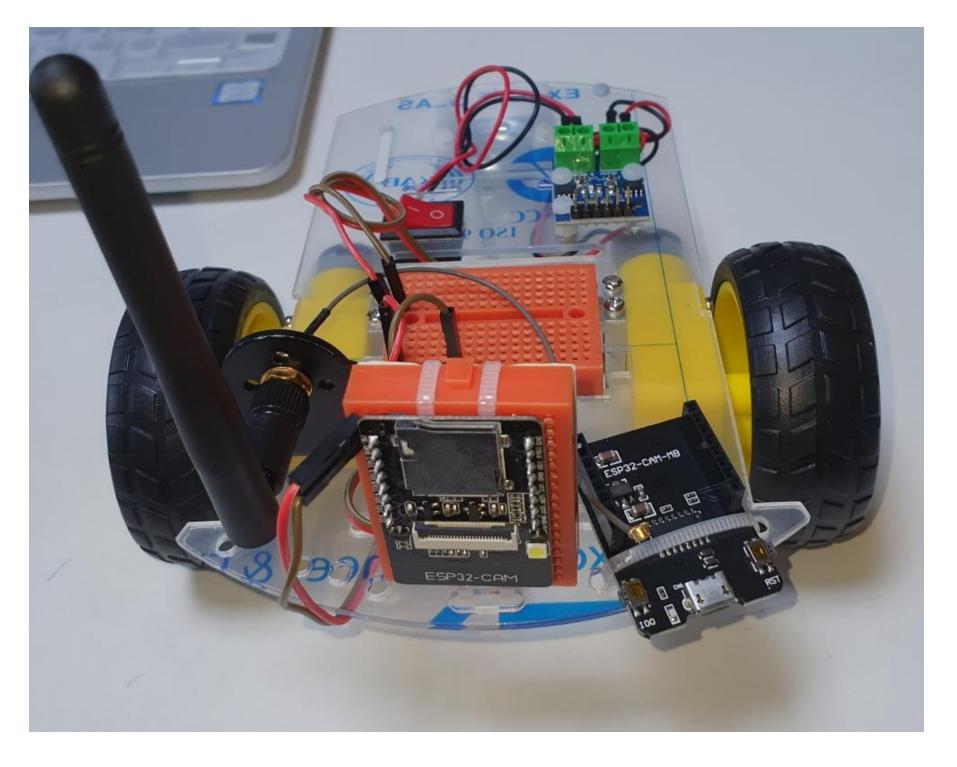


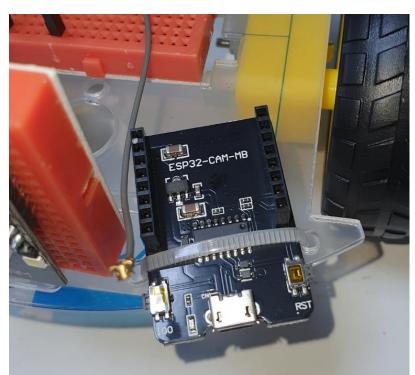
(왼쪽 모터 간섭으로 L9110S 기판의 지지대 한 곳이 조립이 어려움. 삭제) (L9110S Wiring)



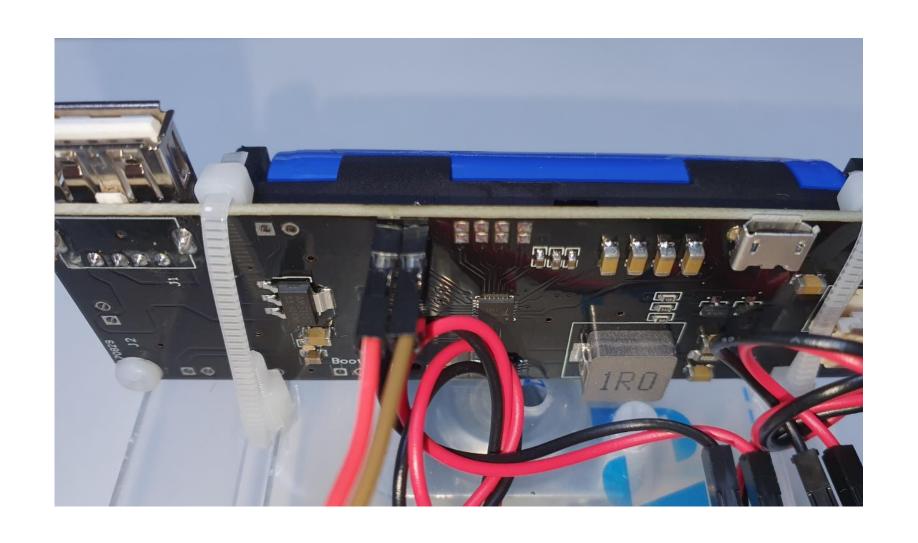
ESP32-CAM 및 안테나설치





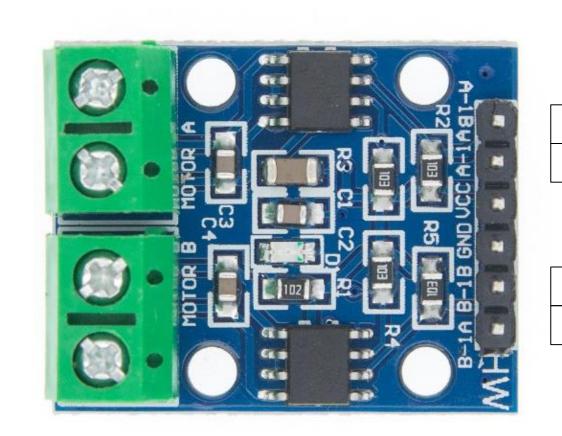


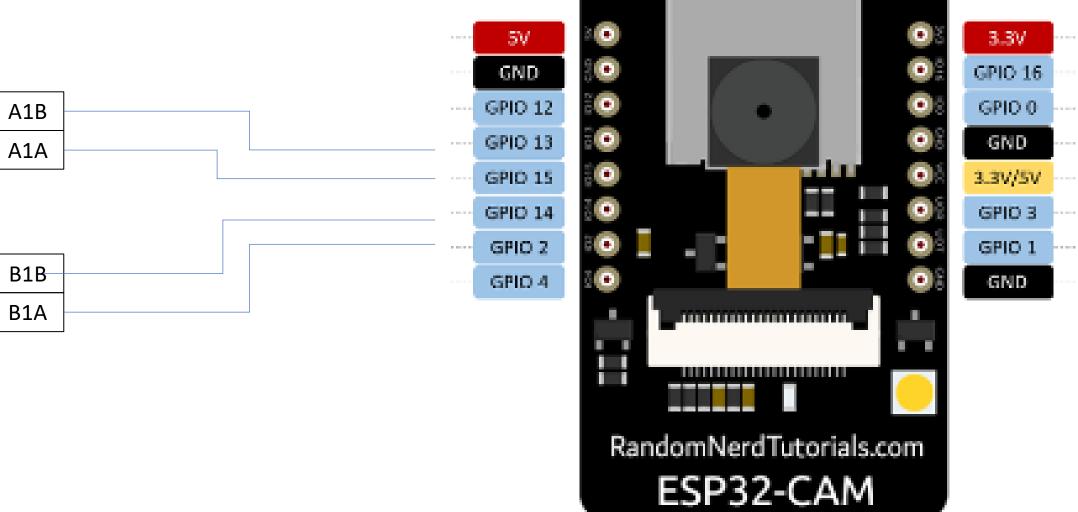
18650 배터리 장착



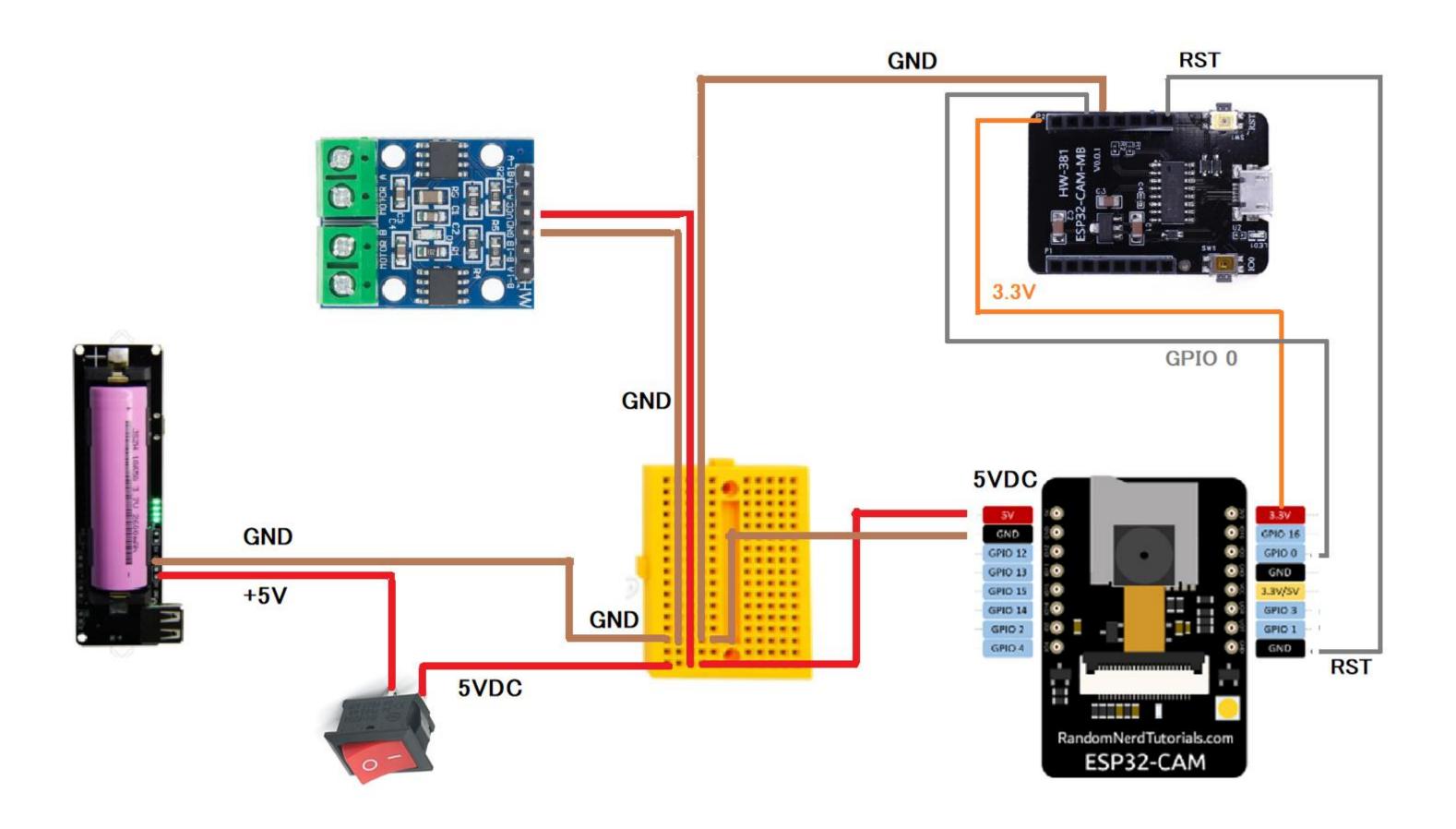


L9110S and ESP32CAM

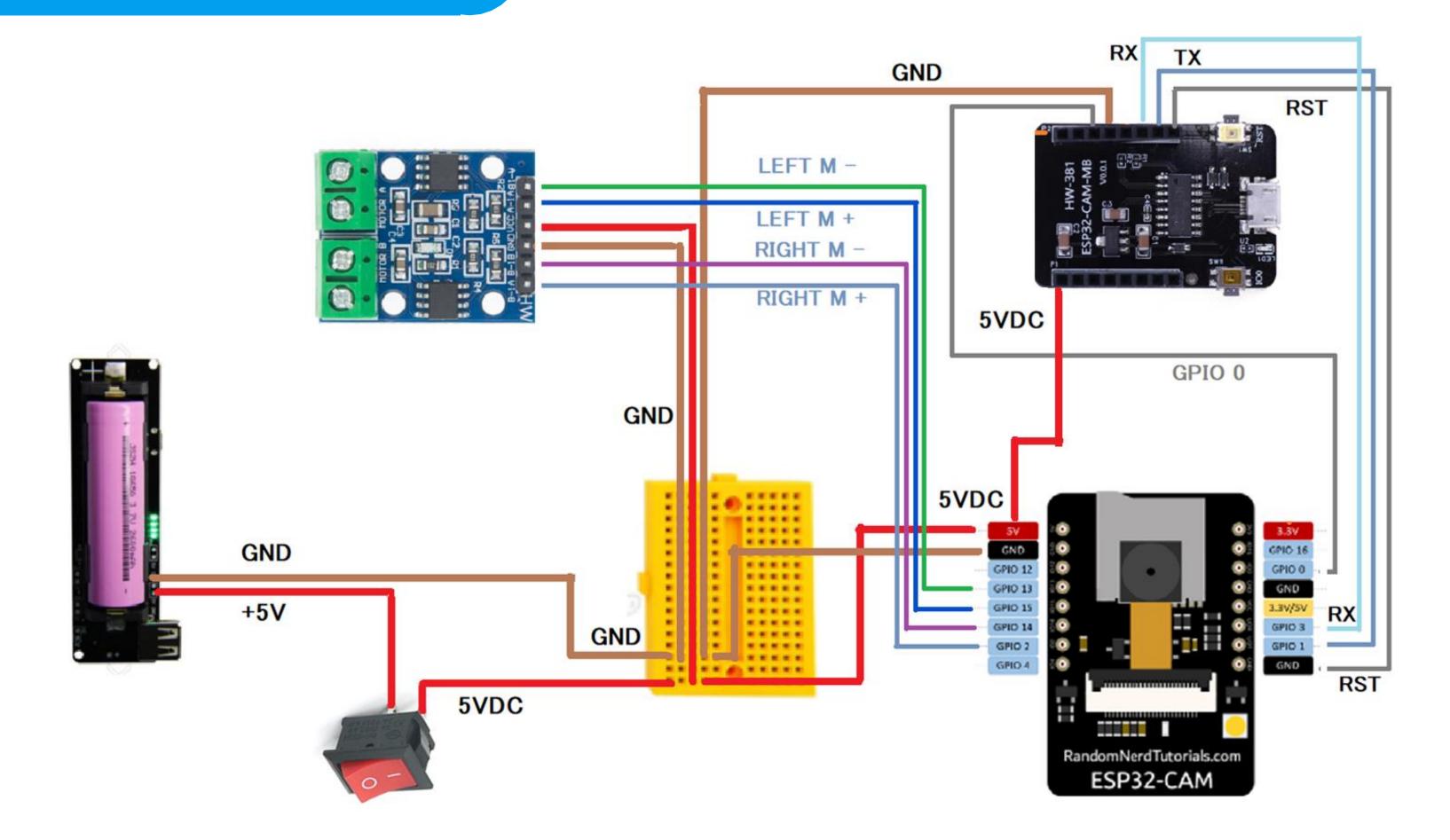




Power Lines at Mini Bread Board



Wiring All Parts



Wiring All Parts

