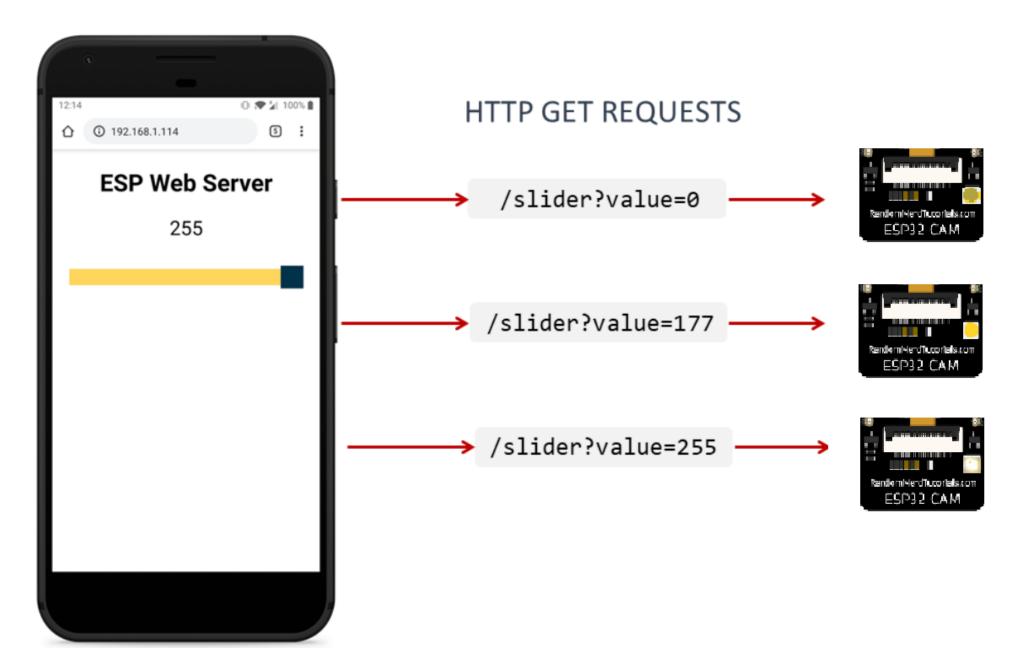
ESP32 ledcwrite PWM control



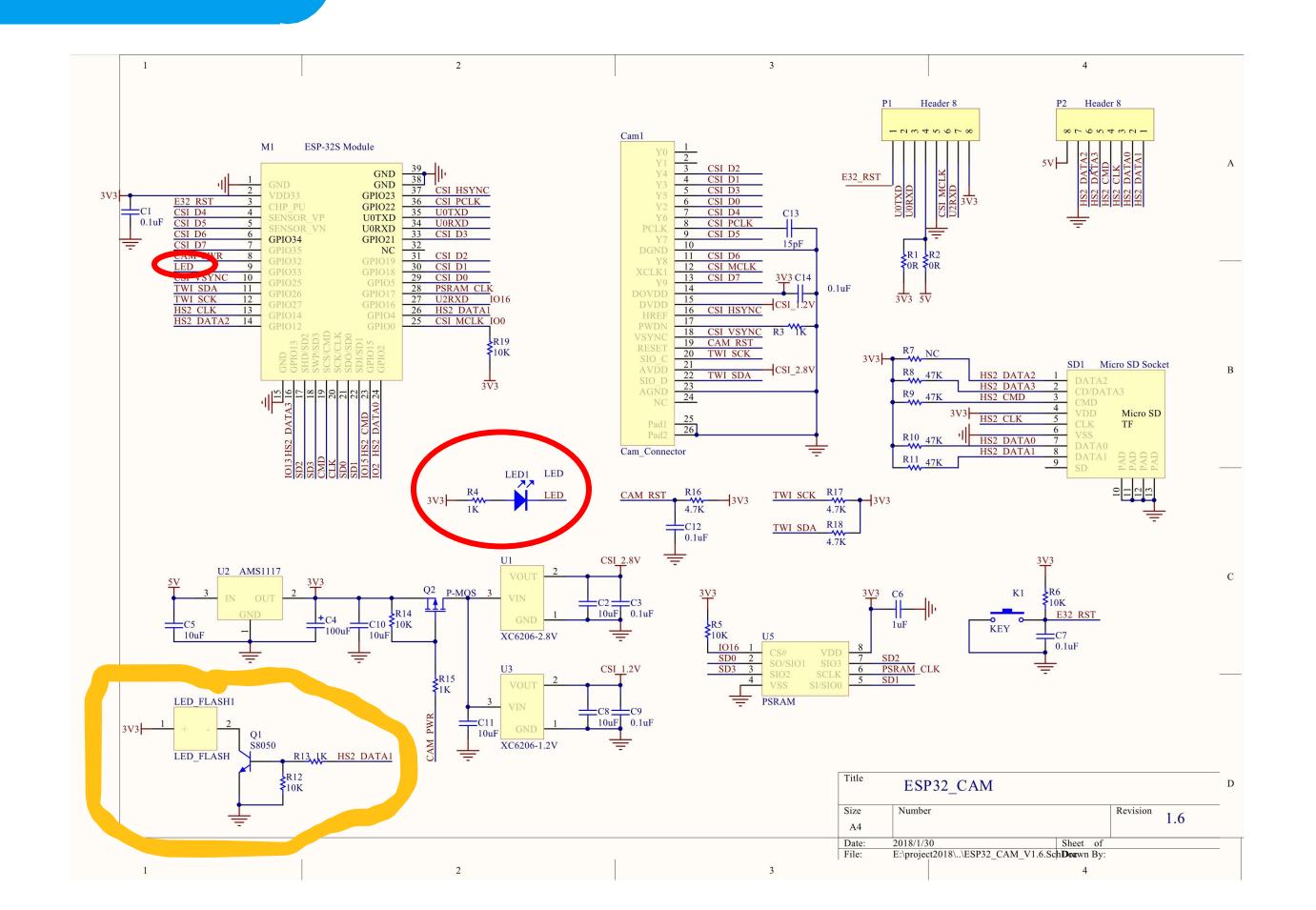
7/29/2023

Sangwon Lee

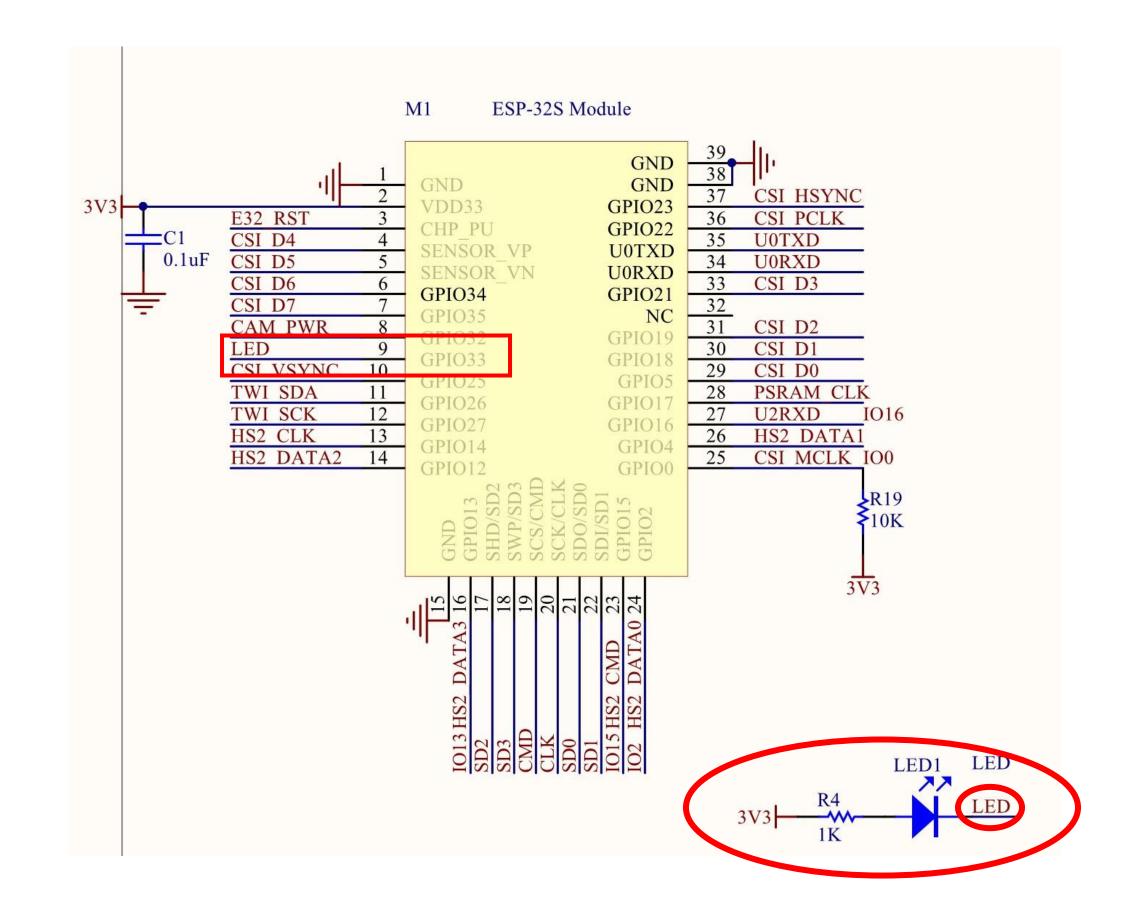
Contents

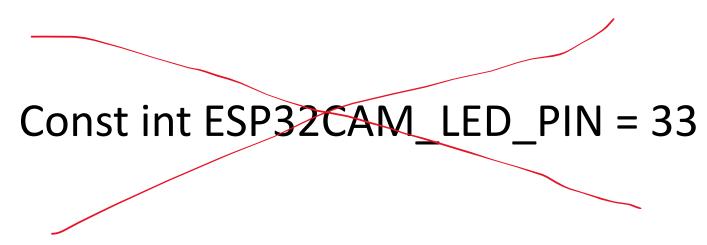
■ ESP32-CAM Schematic and LED Pin ■ ESP32 PWM Output "ledcSetup", "ledcAttachPin", "ledcwrite" ☐ Library Installation - AsyncTCP-master and ESPAsyncWebServer-master ☐ Setup SPIFFS — File System Uploader ☐ ESP32 LED Web Server Control ☐ Motor Web Server Control ☐ Reference: https://randomnerdtutorials.com/esp32-web-server-slider-pwm/

ESP32 CAM Schematic



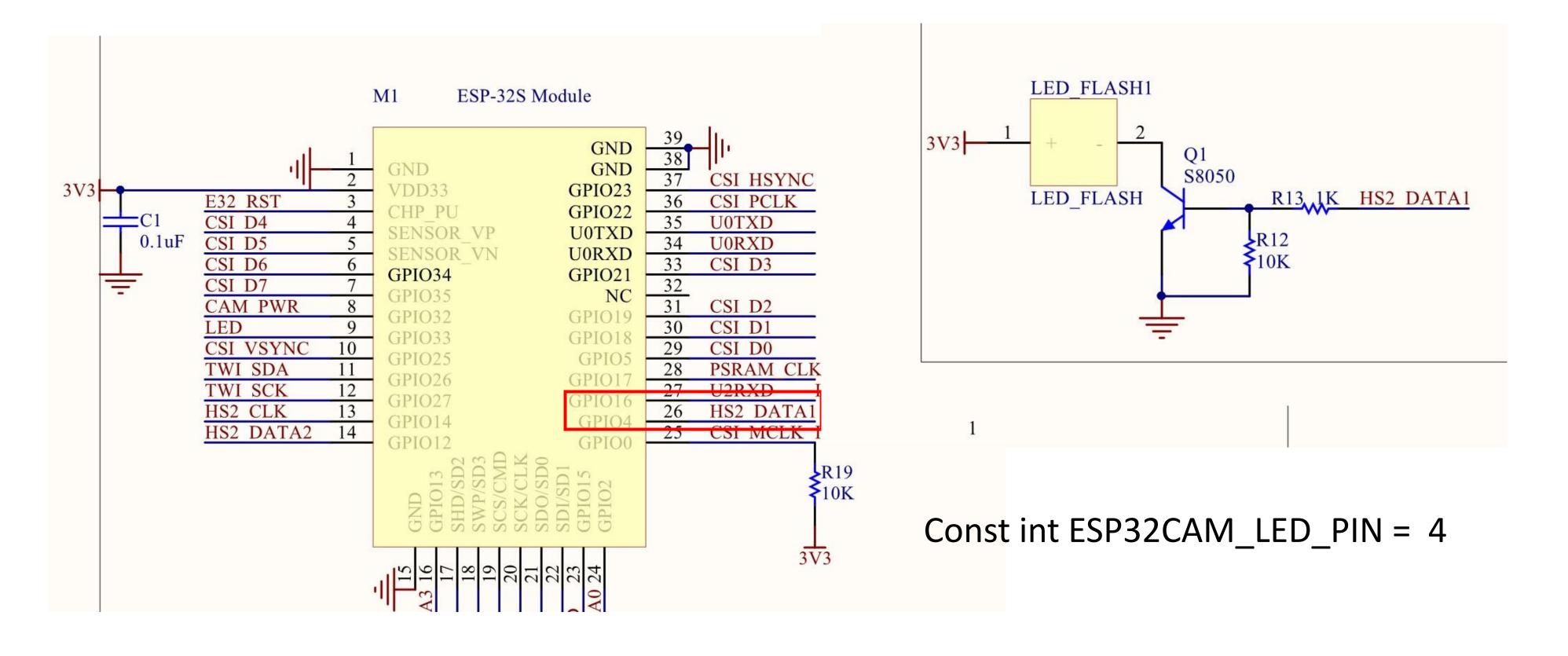
ESP32 CAM Internal LED Pin



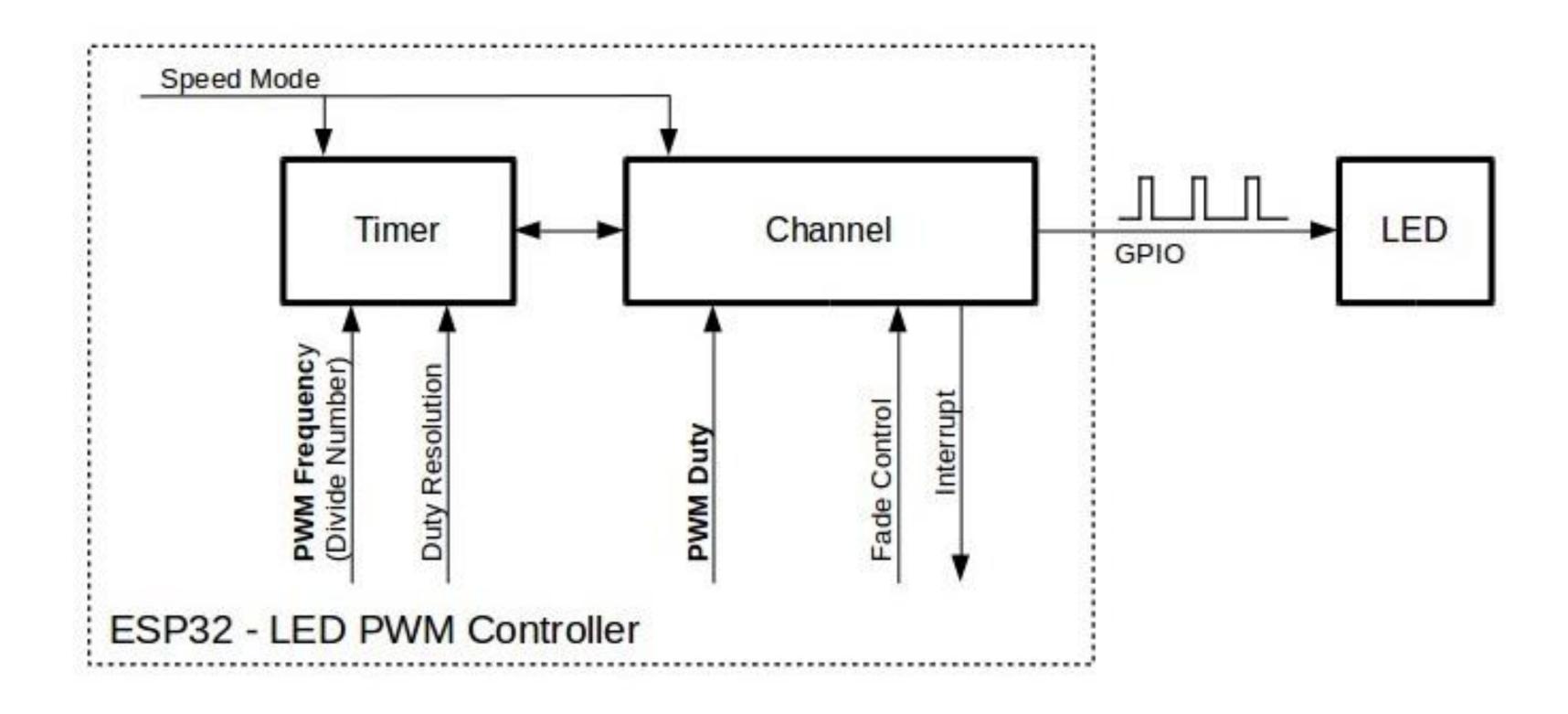


Const int ESP32CAM_LED_PIN = 4

ESP32 CAM Internal LED Pin

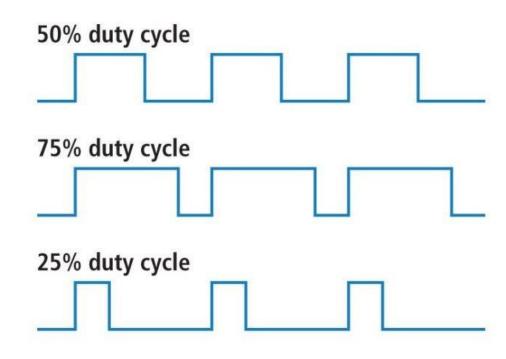


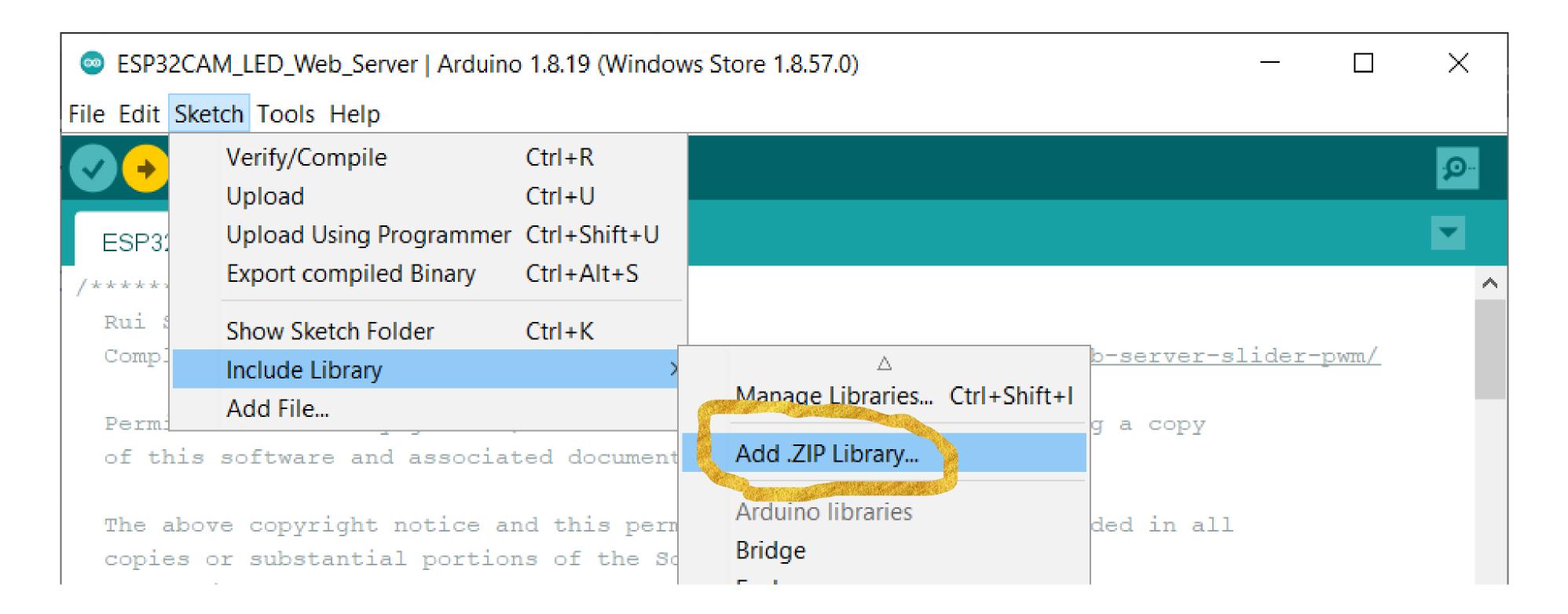
ESP32 PWM Output

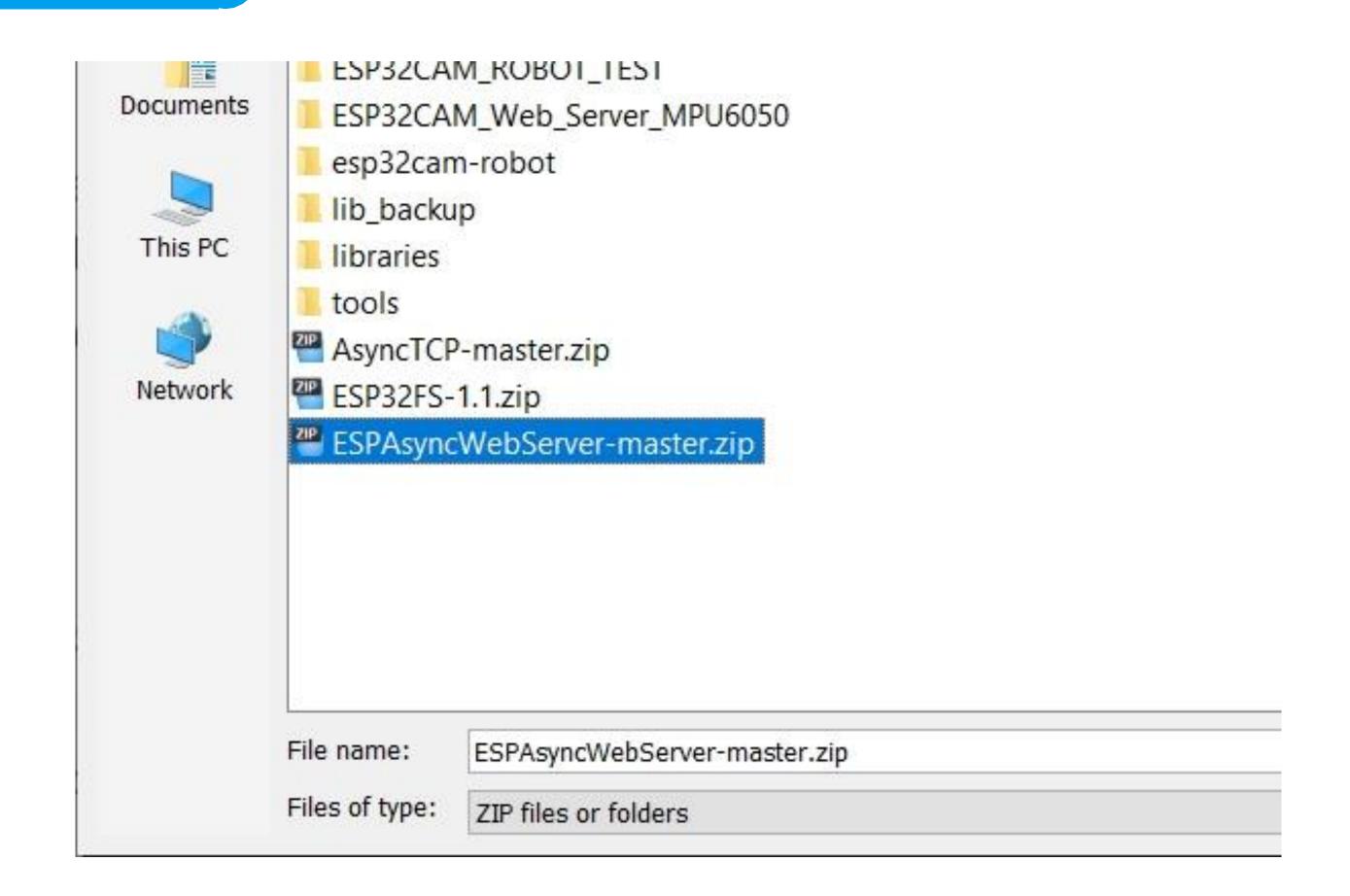


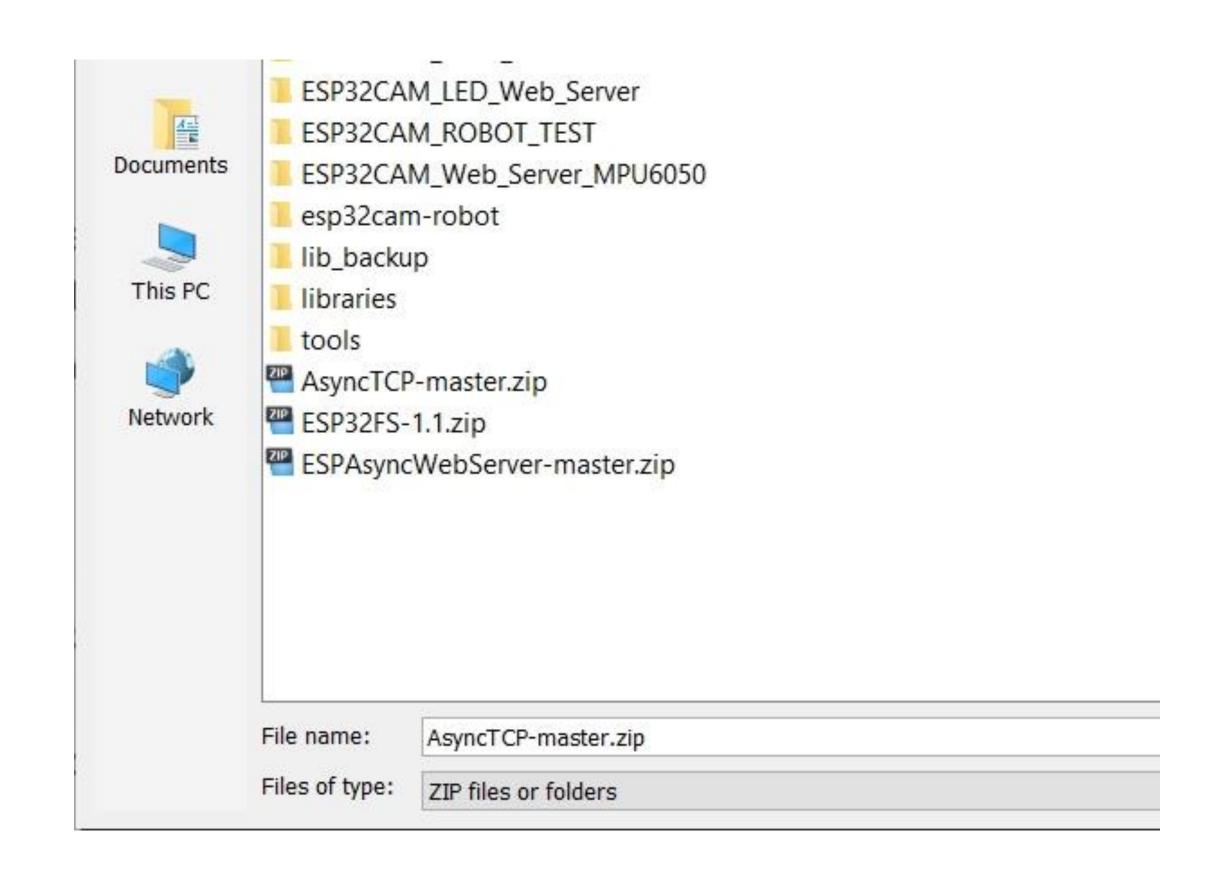
ledcSetup, ledcAttachPin, ledcwrite

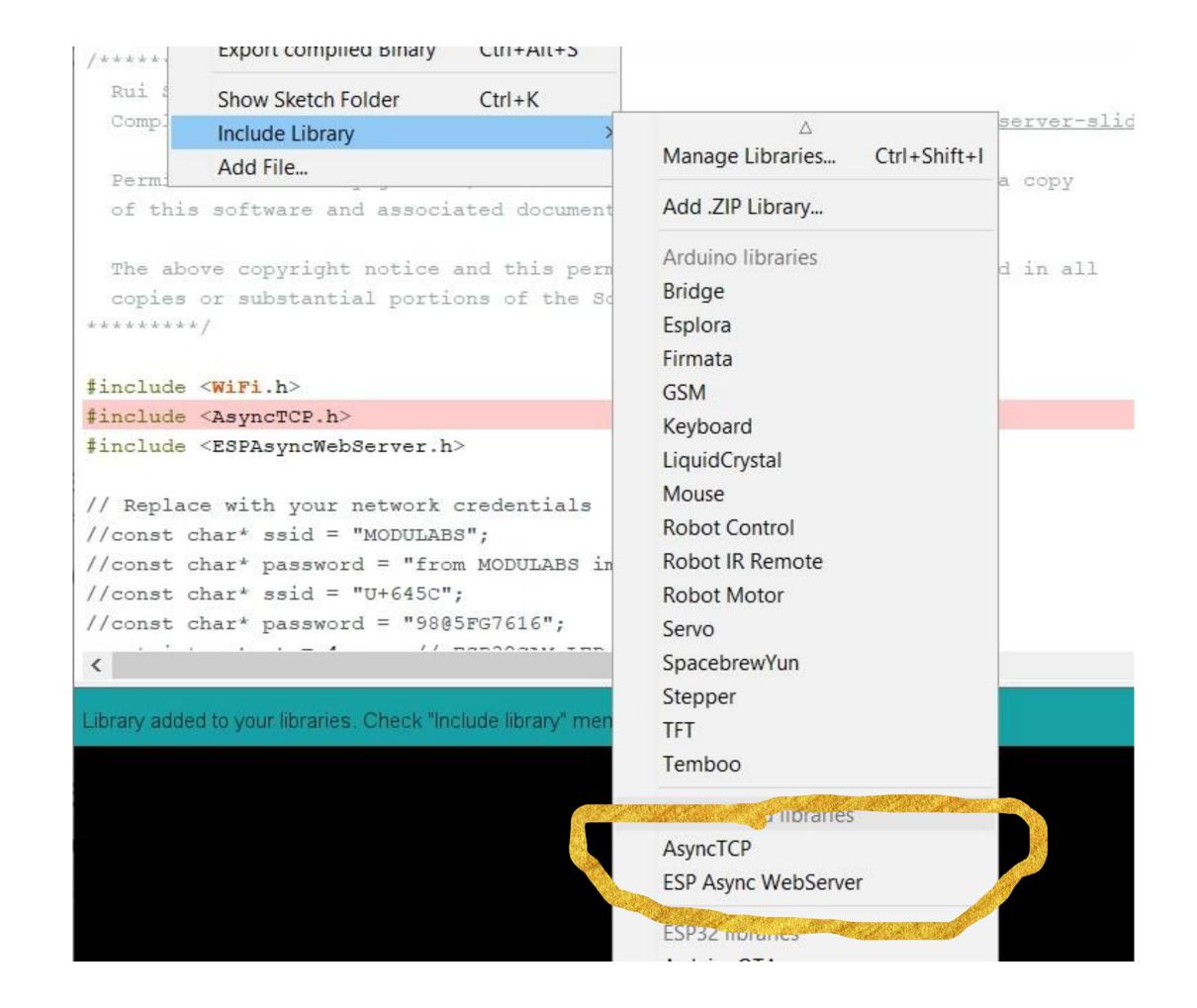
```
// ledcSetup (ledcChannel n, frequency, resolution)
    : ledcChannel n is the internal PWM generator number
    : frequency is the frequency of ledcChannel n
    : resolution is the 100% duty value
// for example,
// PWM generator 0 and 1 kHz frequency and 8-bit resolution
// ledcSetup(0, 1000, 8)
// ledcAttachPin(GPIO_n, ledcChannel_n)
    : connect PWM generator to real GPIO pin
    : ledcAttachPin(33, 0)
// ledcwrite(ledcChannel n, duty)
    : change PWM generator duty cycle
    : ledcwrite(0, 127)
```











☐ Reference:

https://randomnerdtutorials.com/esp32-web-server-slider-pwm/

☐ Source:

https://raw.githubusercontent.com/RuiSantosdotme/Random-Nerd-Tutorials/master/Projects/ESP32/ESP32 Slider PWM.ino

```
#include <WiFi.h>
#include <AsyncTCP.h>
#include <ESPAsyncWebServer.h>
// Replace with your network credentials
const char* ssid = "MODULABS";
const char* password = "from MODULABS import future";
const int output = 4; // ESP32CAM LED is connected to the GPIO4
String sliderValue = "0";
// setting PWM properties
const int freq = 1000;
const int ledChannel = 7; // ledc channel(PWM control unit) number 7
const int resolution = 8; // ledc pwm resolution
```

```
void setup(){

// Serial port for debugging purposes
Serial.begin(115200);

// configure LED PWM functionalitites
ledcSetup(ledChannel, freq, resolution);

// 7, 1000, 8

// attach the channel to the GPIO to be controlled
ledcAttachPin(output, ledChannel);

// 4, 7

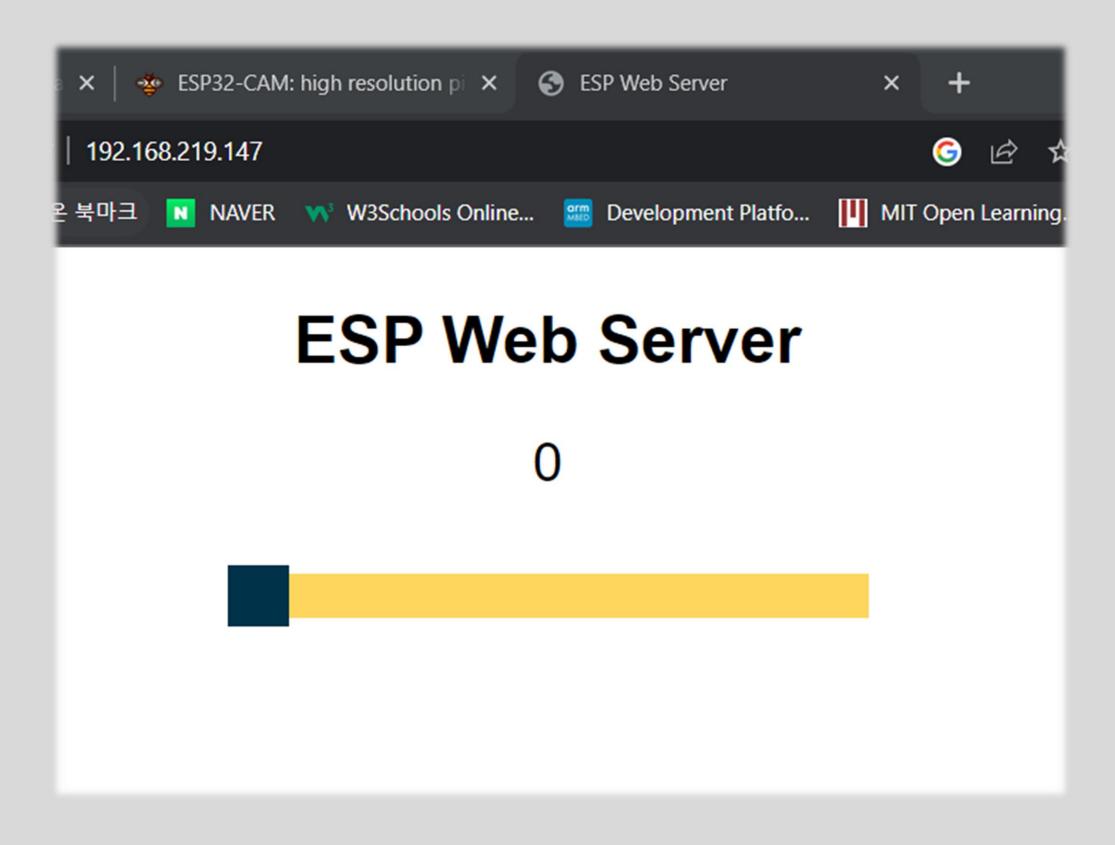
ledcWrite(ledChannel, sliderValue.toInt());

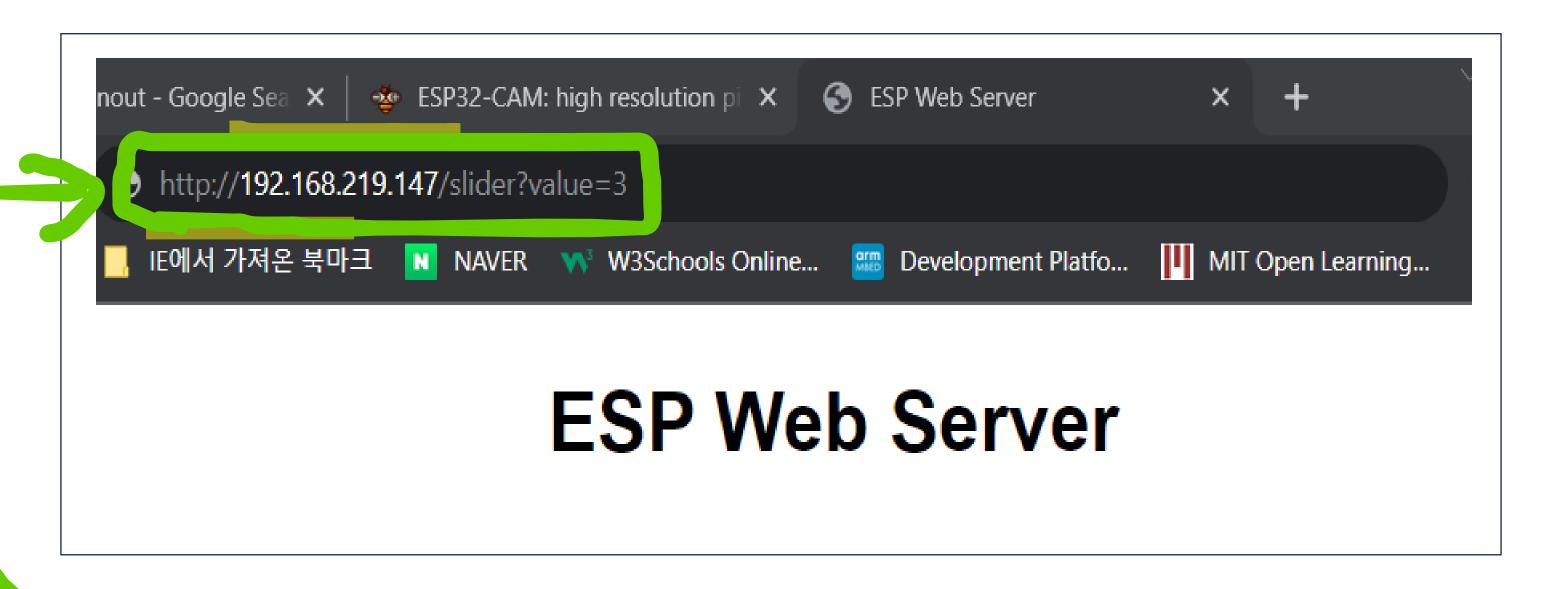
// 7, 0 ~ 255
```

```
// Send a GET request to <ESP_IP>/slider?value=<inputMessage>
server.on("/slider", HTTP_GET, [] (AsyncWebServerRequest *request) {
 String inputMessage;
 // GET input1 value on <ESP_IP>/slider?value=<inputMessage>
 if (request->hasParam(PARAM_INPUT)) {
  inputMessage = request->getParam(PARAM_INPUT)->value();
  sliderValue = inputMessage;
  ledcWrite(ledChannel, sliderValue.toInt());
 else {
  inputMessage = "No message sent";
 Serial.println(inputMessage);
 request->send(200, "text/plain", "OK");
});
```

```
<body> <h2>ESP Web Server</h2>
    <span id="textSliderValue">%SLIDERVALUE%</span>
    <input type="range" onchange="updateSliderPWM(this)" id="pwmSlider"</p>
     min="0" max="255" value="%SLIDERVALUE%" step="1" class="slider">
<script> function updateSliderPWM(element) {
    var sliderValue = document.getElementById("pwmSlider").value;
    document.getElementById("textSliderValue").innerHTML = sliderValue;
    console.log(sliderValue);
    var xhr = new XMLHttpRequest();
    xhr.open("GET", "/slider?value="+sliderValue, true);
    xhr.send(); }
</script>
</body>
```

ESP32 will receive a request like this "/slider?value=SLIDERVALUE"





http://YOUR_ESP32CAM_IP_ADDRESS/slider?value=10