

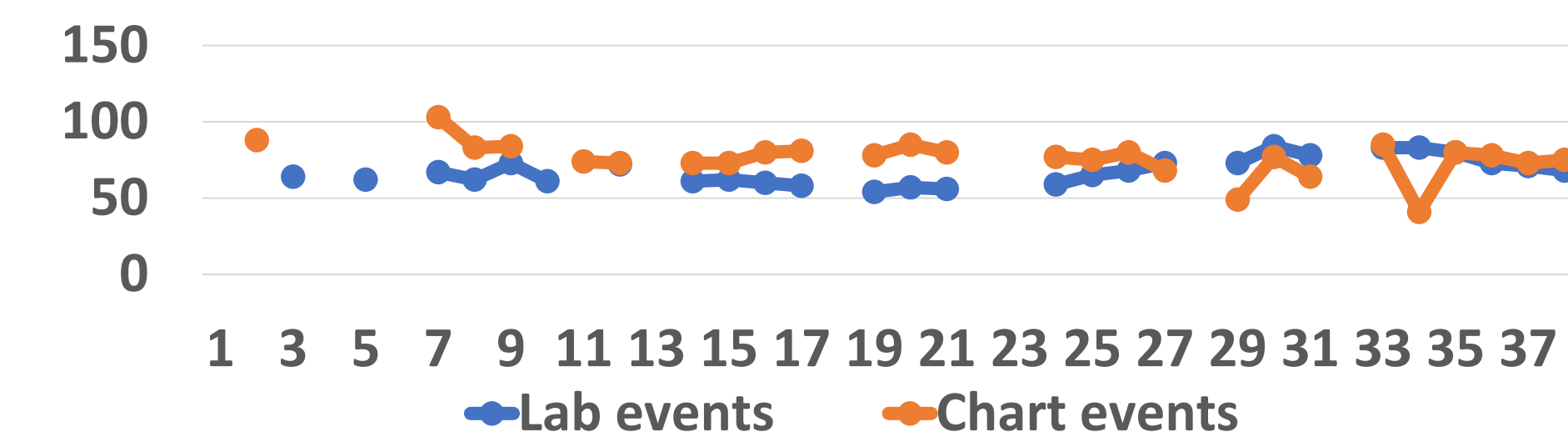
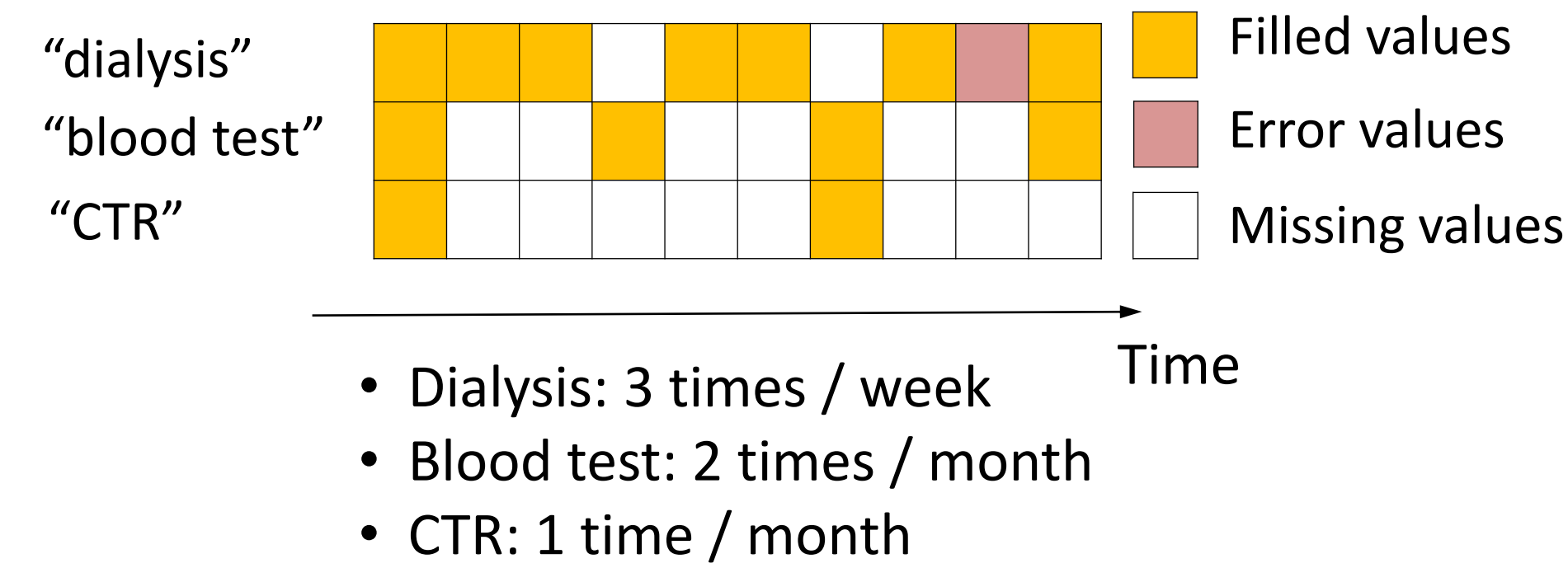
Dynamic Gaussian Mixture based Deep Generative Model For Robust Forecasting on Sparse Multivariate Time Series

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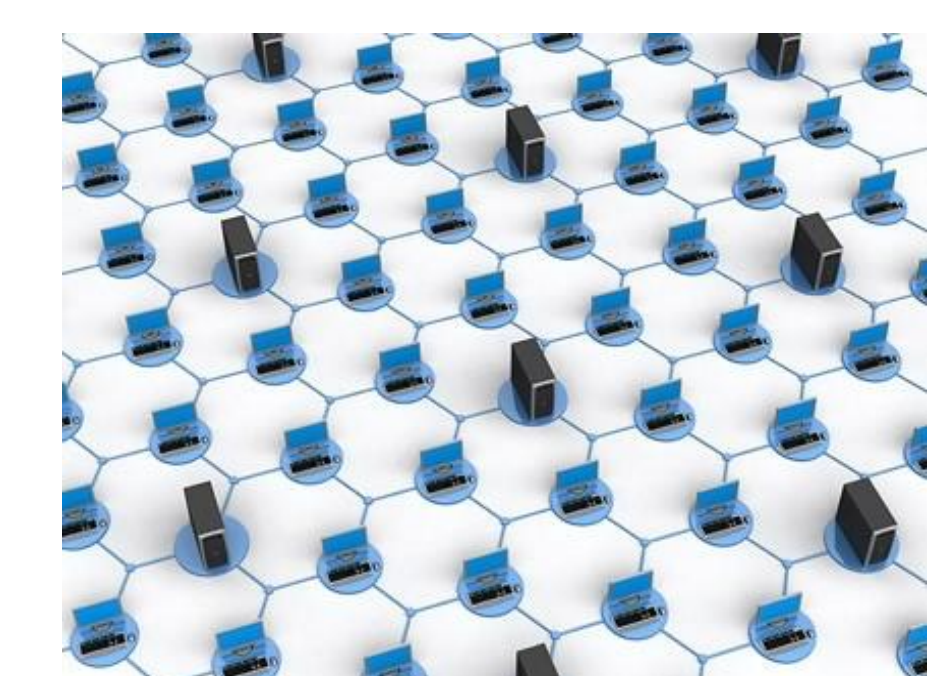
Background

High sparsity of the multivariate time series (MTS) in Medical Domain:

- Different sampling rates, e.g., dialysis is three times per week, blood test is biweekly
- Irregular measurements: patients may miss some visits for tests for a variety of reasons

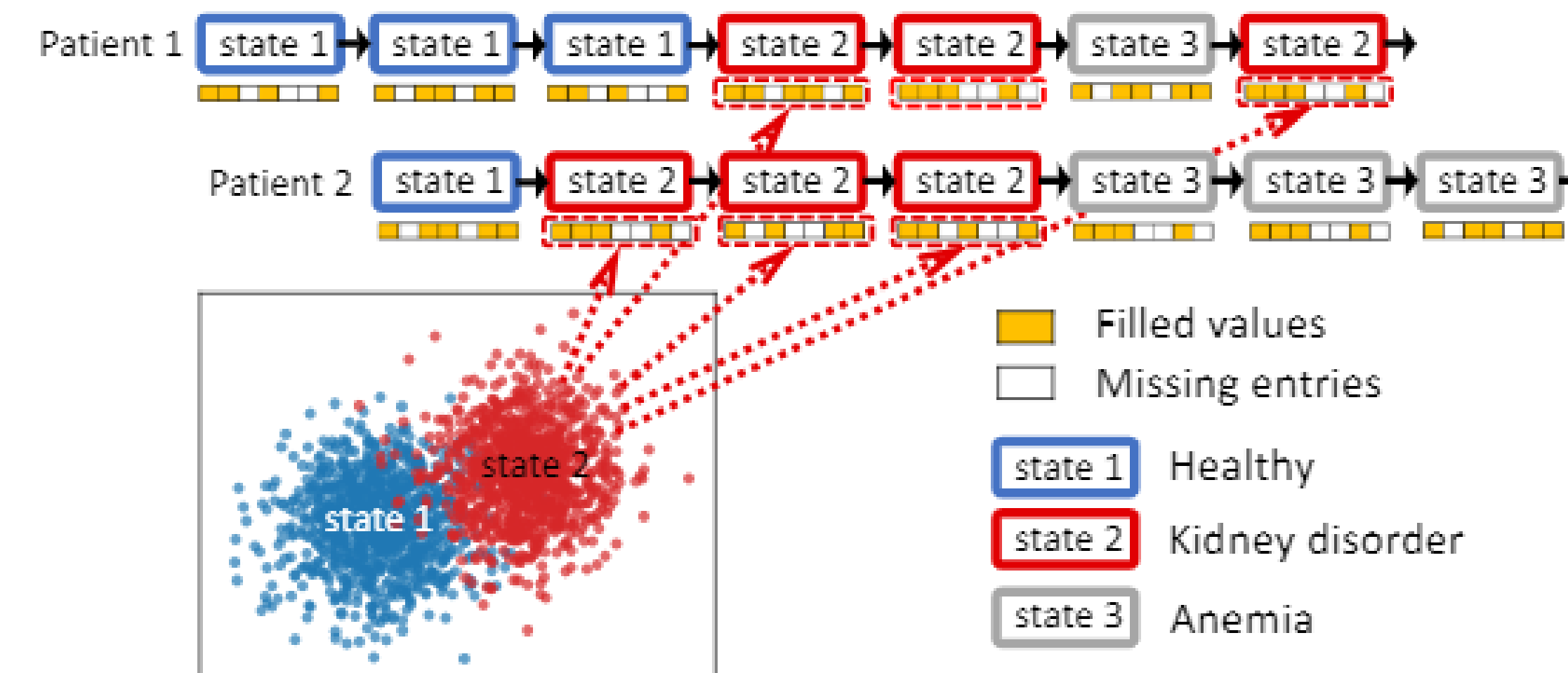


Finance: different sources such as financial news, analysis and market-makers in investment banks



Complex monitoring systems: sensors of different components have different rates

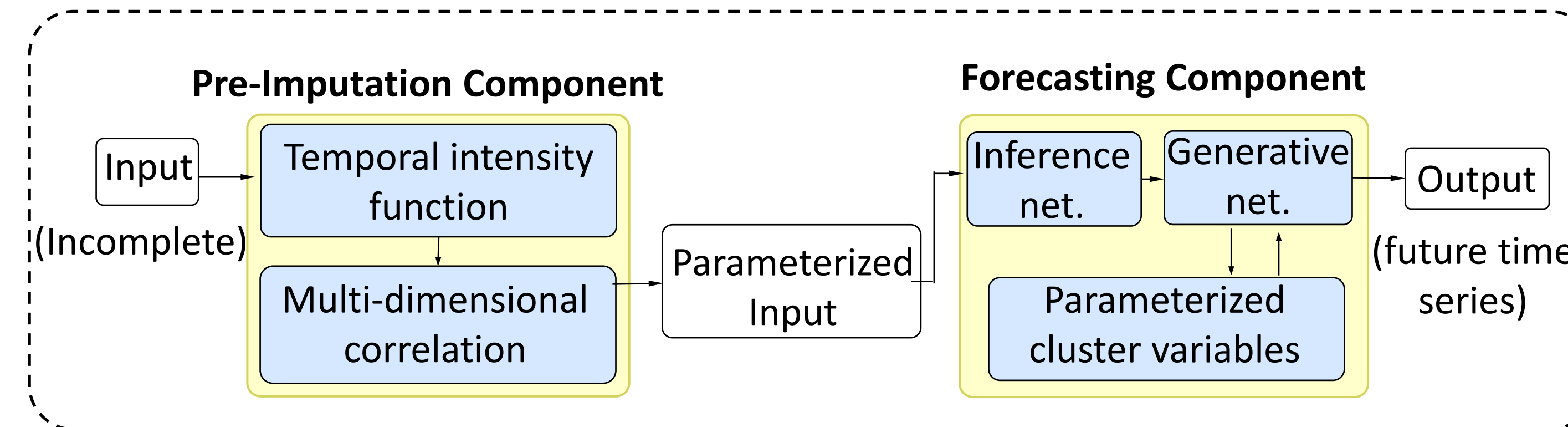
Our perspective



Similar patients may have similar latent states
 -> cluster latent states from different MTS's

Our framework

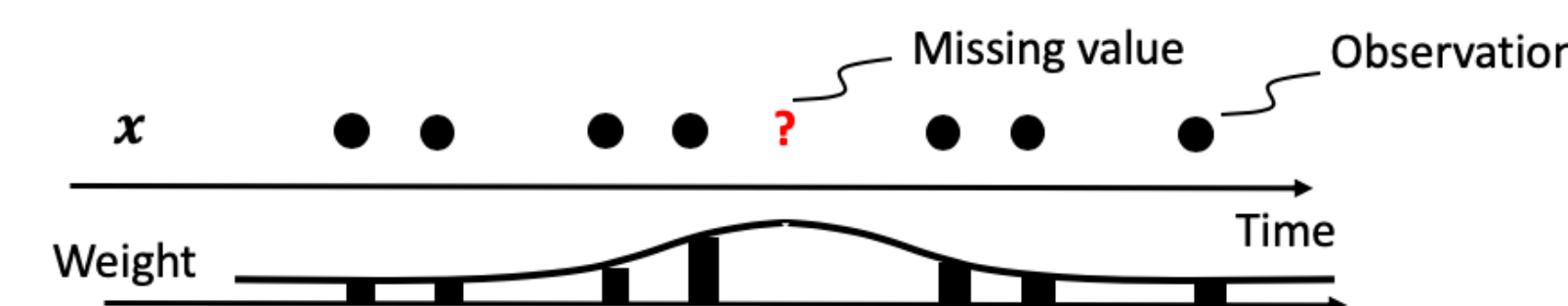
Joint imputation and forecasting framework



Imputation component

Parameterizing missing entries - interpolation

- Temporal intensity: $\bar{x}_{t^*}^i = \frac{1}{\lambda(t^*, \mathbf{m}^i; \alpha_i)} \sum_{t=1}^w \kappa(t^*, t; \alpha_i) m_t^i x_t^i$

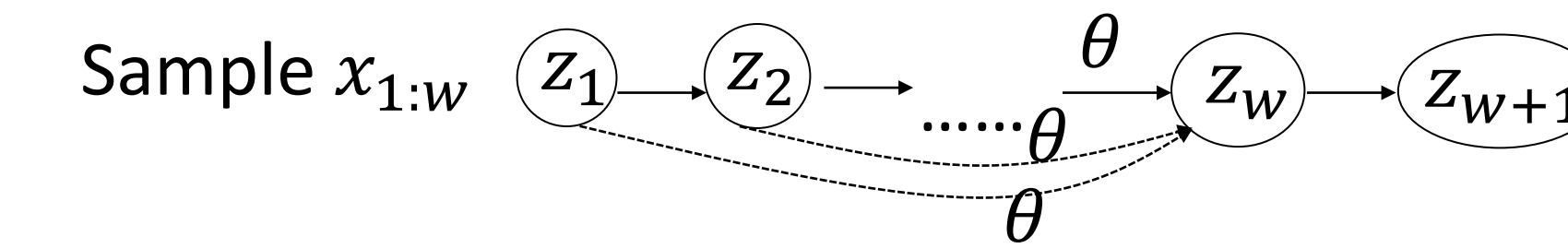


- Multi-dimensional correlation:

$$\hat{x}_{t^*}^i = \left[\sum_{j=1}^d \rho_{ij} \lambda(t^*, \mathbf{m}^i; \alpha_j) \bar{x}_{t^*}^j \right] / \sum_{j=1}^d \lambda(t^*, \mathbf{m}^i; \alpha_j)$$

Forecasting component

Transition Process



$$p(z_{t+1}|z_{1:t}) = f_{\theta}(z_{1:t})$$

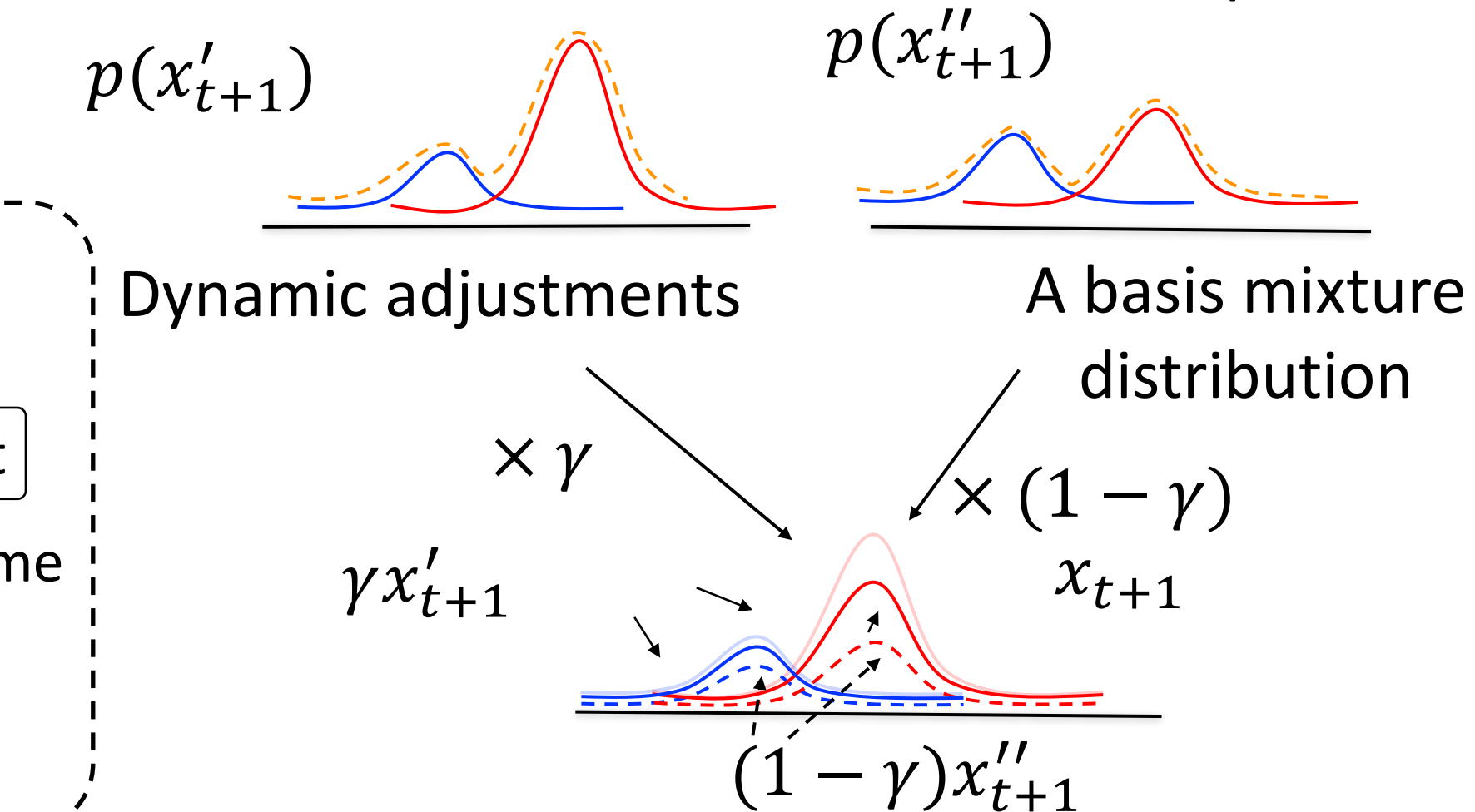
Emission Process

Emission of a new observation from a Dynamic Gaussian mixture

- Draw a latent cluster variable z_{t+1} from $Categorical(p(\psi_{t+1}))$
- Draw x_{t+1} from $N(\mu_{z_{t+1}}, \sigma^{-1}I)$

$$\psi_{t+1} = \underbrace{(1 - \gamma)p(z_{t+1}|z_{1:t})}_{\text{dynamic adjustment}} + \underbrace{\gamma p(\mu)}_{\text{basis mixture}}$$

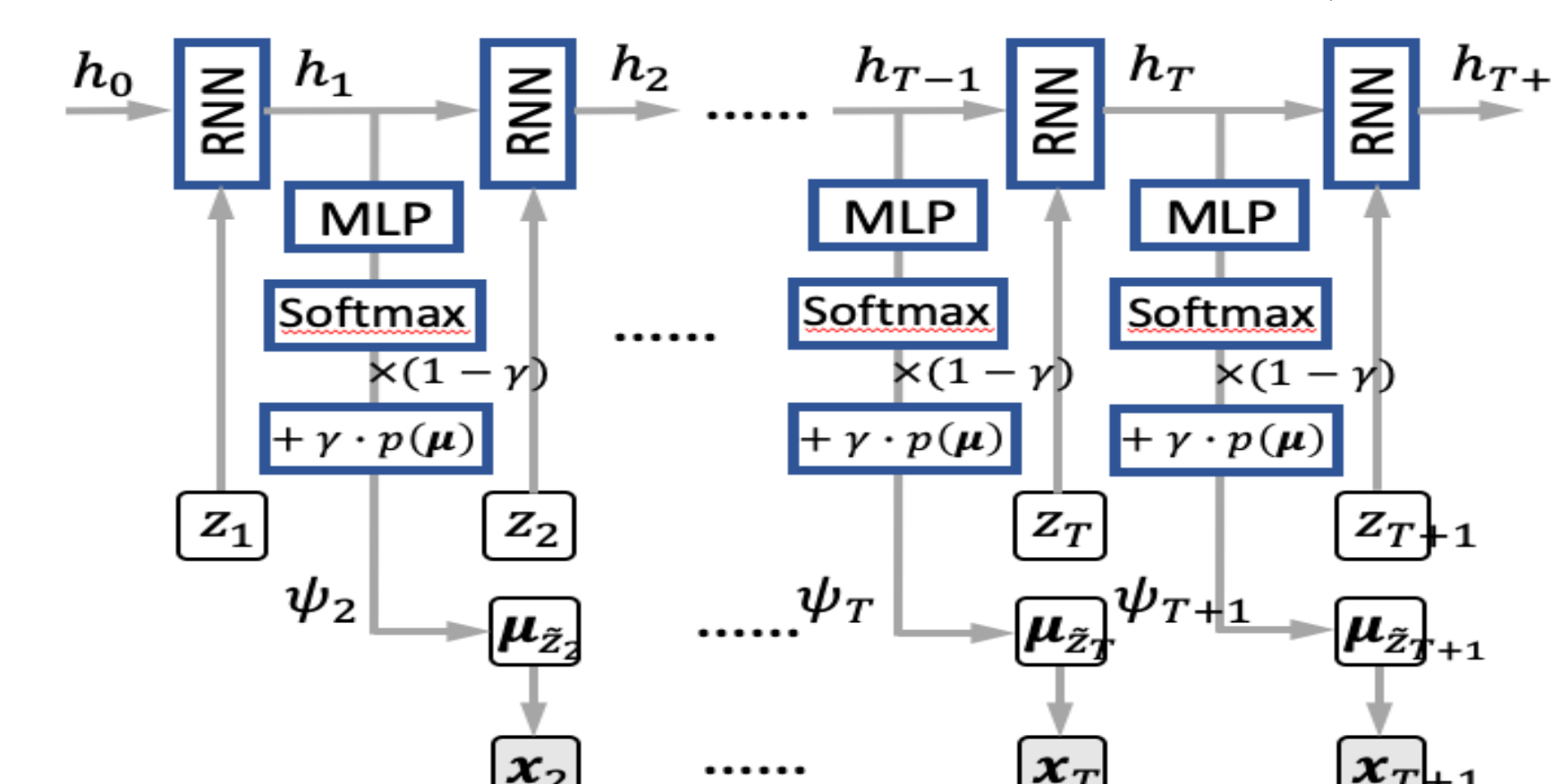
Gaussian Mixture with two mixture components:



Parameterization

Generative network

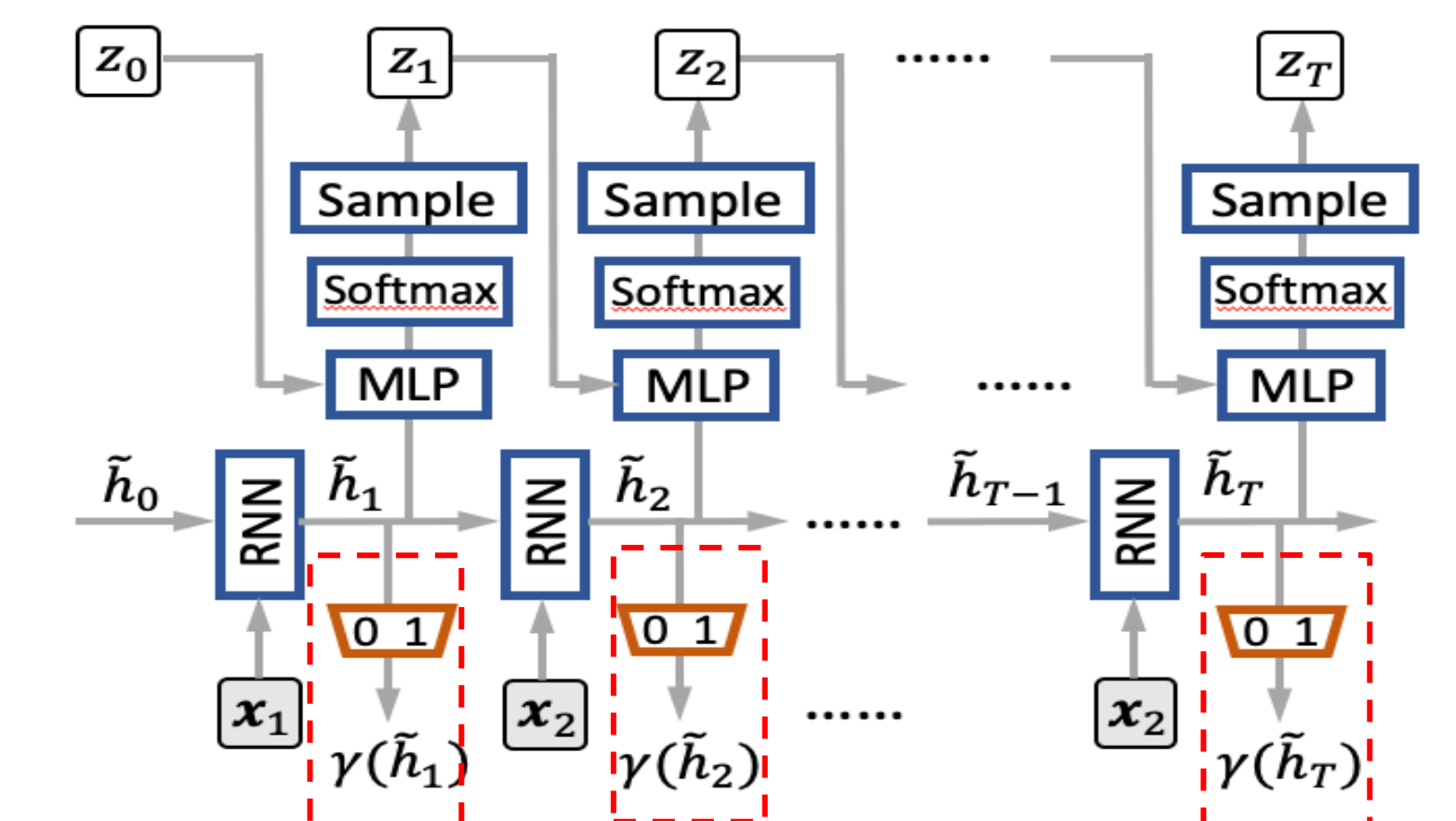
$$p(z_{t+1}|z_{1:t}) = f_{\theta}(z_{1:t}) \quad p(z_{t+1}|z_{1:t}) = \text{softmax}(\text{MLP}(\mathbf{h}_t)), \text{ where } \mathbf{h}_t = \text{RNN}(z_t, \mathbf{h}_{t-1})$$



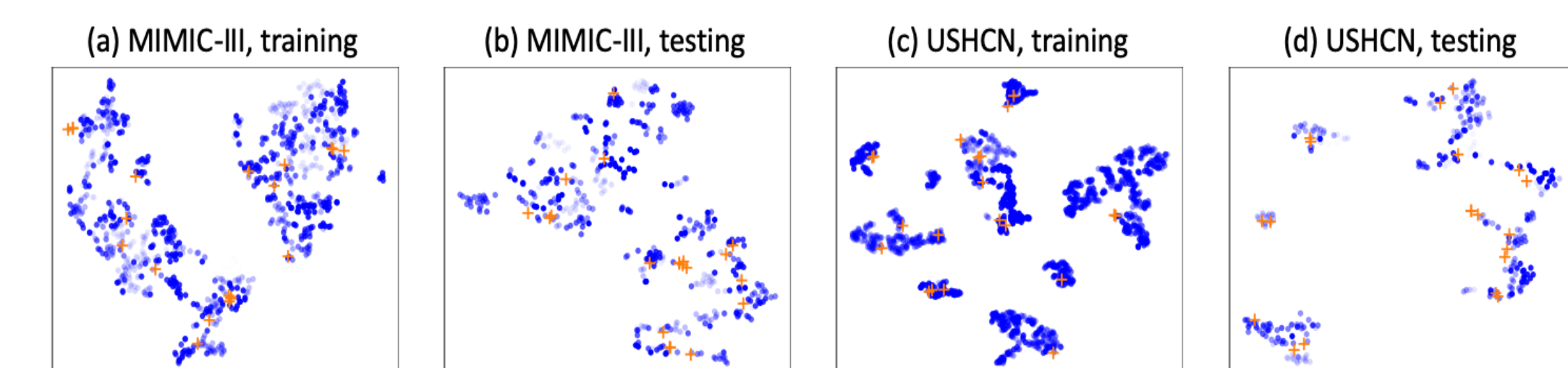
Inference network

Variational inference:

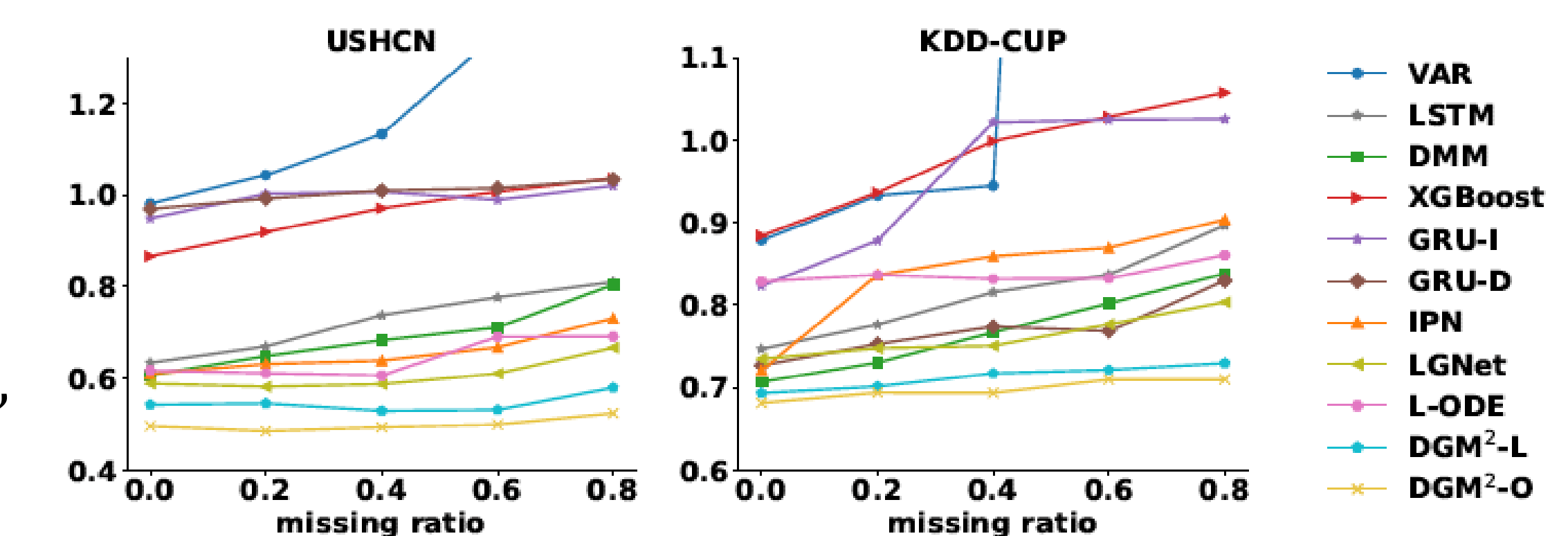
- introduce approximate posterior $q_{\phi}(z_{1:T}|x_{1:T}) = q_{\phi}(z_1|x_1) \prod_{t=1}^{T-1} q_{\phi}(z_{t+1}|x_{1:t+1}, z_t)$



Experiments



DGM² is able to fit the underlying clustering structures



DGM² can generate time series that are close to the true values