



Tutorial: Advances in Human Event Modeling: From Graph Neural Networks to Language Models

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Sunday, August 25 2024
10:00 AM – 1:00 PM (CEST)



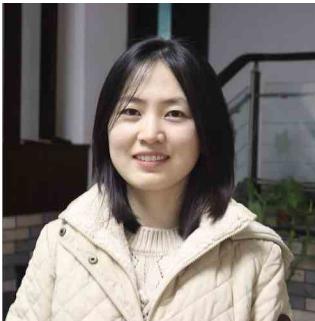
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Acknowledgements

Tutorial based in part on materials in the Tutorial at AAAI 2021: *Explainable AI for Societal Event Predictions: Foundations, Methods, and Applications* and a number of published papers.

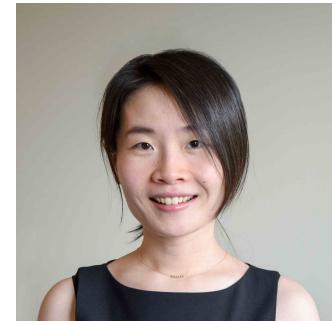
Organizers



Songgaojun Deng
Postdoc Researcher
University of Amsterdam
(Presenter)
ML and data mining in social science,
health and e-commerce



Maarten de Rijke
Distinguished Professor
University of Amsterdam
(Contributor)
Information retrieval and machine
learning



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Assistant Professor
Stevens Institute of Technology
(Presenter)
Socially Responsible AI

Objectives

- Gain a solid understanding of human event modeling and its significance.
- Learn about the latest advancements in graph neural networks (GNNs) and large language models (LLMs).
- Recognize open challenges and opportunities for further exploration.
- Engage in discussions to exchange ideas with peers.

Roadmap

- Introduction and motivation
- Methodology
 - Part 1: Graph Neural Network (GNN)-based methods
 - Part 2: Large Language Model (LLM)-based methods
- Conclusion and future directions

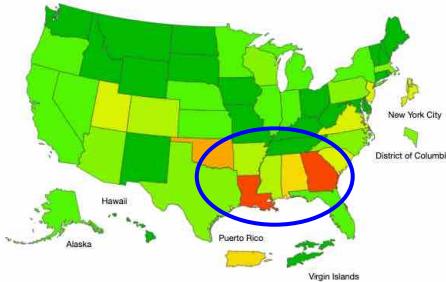
Introduction and motivation

Human events

Epidemic outbreak during 2018-2019 in southern region



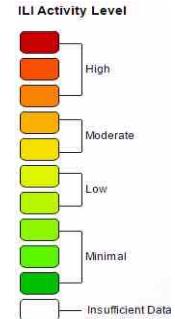
Week 44



Week 47

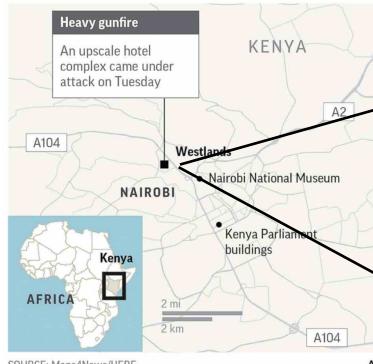


Week 52



influenza

Terrorism events



Human events



Protests

Civil unrest events on Mar 17, 2013 in Brazil



Economic crisis

Human events

civil-unrest riots treaties
elections crisis market-crashes
strikes protests congestion
terrorism pandemics
economic-events epidemics
crimes traffic boycotts

Event forecasting

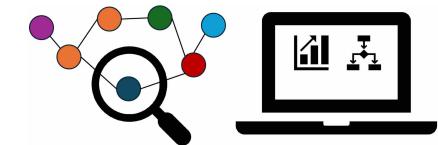
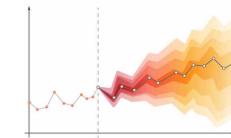
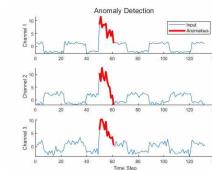
- The task is to predict the occurrence of events in the future using historical data.
- Underlying mechanism of societal events
 - Complex, dynamic, sparse
 - Hard to comprehensively model with limited data
 - Largely unknown



Build the forecaster driven by large historical data

Comparison of event modeling tasks

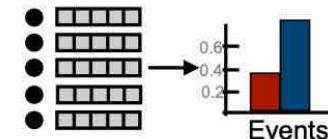
- Extraction
 - Given a piece of text, extract key elements such as location and entities.
 - Supervised/Semi-supervised learning
 - **Techniques:** natural language processing
- Detection
 - Given historical or ongoing events, detect anomaly
 - Unsupervised learning
 - **Techniques:** anomaly detection, outlier detection, change detection, motif discovery
- **Forecasting** (or prediction/projection)
 - Given historical data, predict event occurrences in the future
 - Supervised/self-supervised/semi-supervised learning
 - **Techniques:** autoregressive, Markov chain, sequential models, neural networks
- Interpretation
 - Given a prediction, provide explanation or evidence
 - **Techniques:** gradient-based methods, multi-instance learning, attention, knowledge distillation, causal inference



Problem formulation

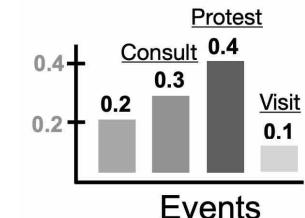
Binary event prediction

- Given static and dynamic input features, learn a classifier that maps the input to a **binary event variable** (e.g., protest or not) at a future time for a target location .



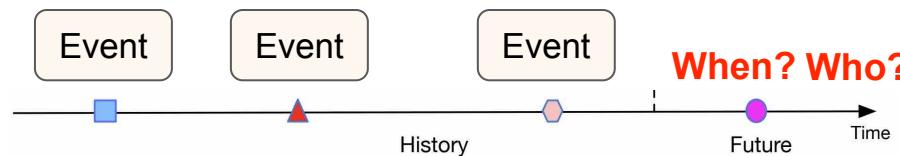
Multi/Concurrent event prediction

- Events can occur concurrently (e.g., Appeal for judicial cooperation, accuse of crime).
- Learn a classifier that maps the input to a **multi-hot vector denoting the occurrences of different event types**.



More

- Time** prediction
- Actor** prediction



Lead time

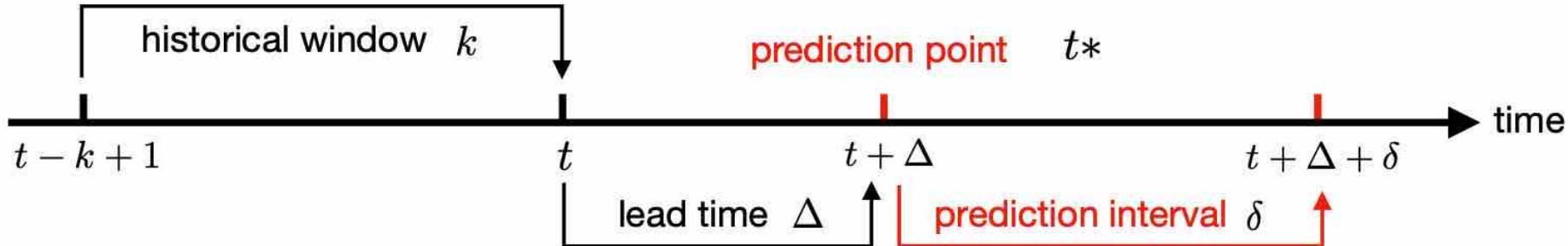
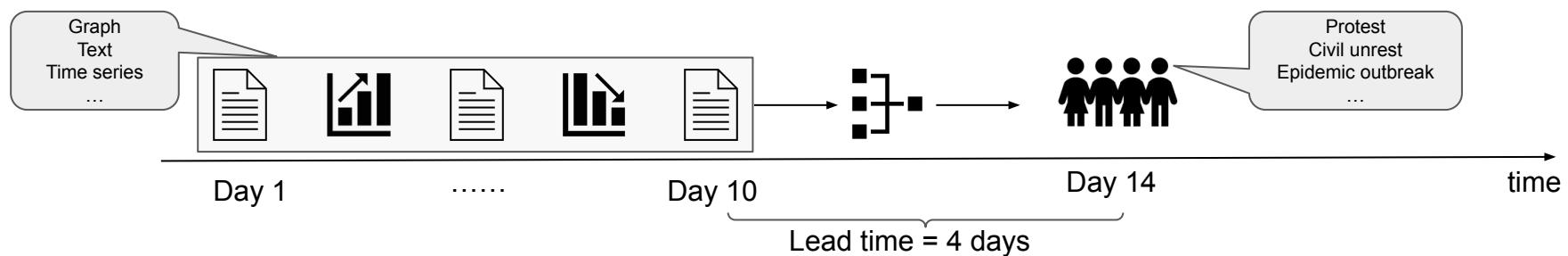
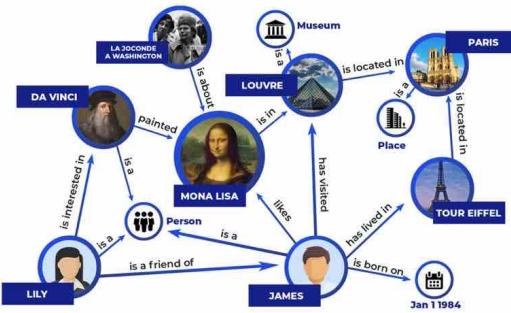


Figure: Example of lead time and prediction time



Human event data

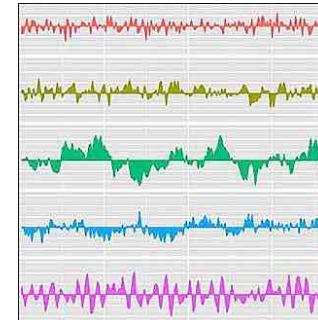
Graph



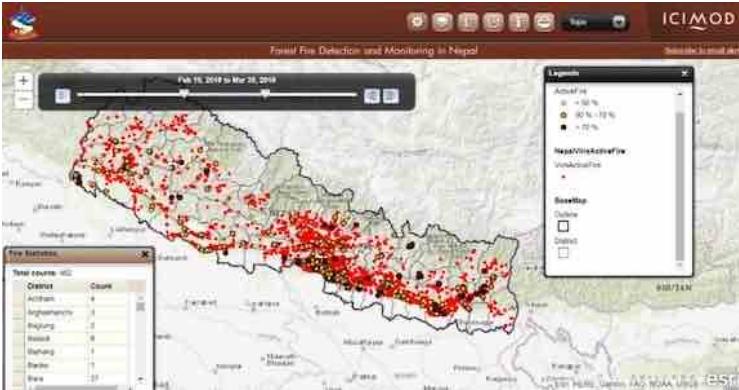
Text



Time Series



Examples of event data



Forest Fire Detection and monitoring in Nepal



Global event encoding system

Social Media Landscape 2023



@FredCavazza

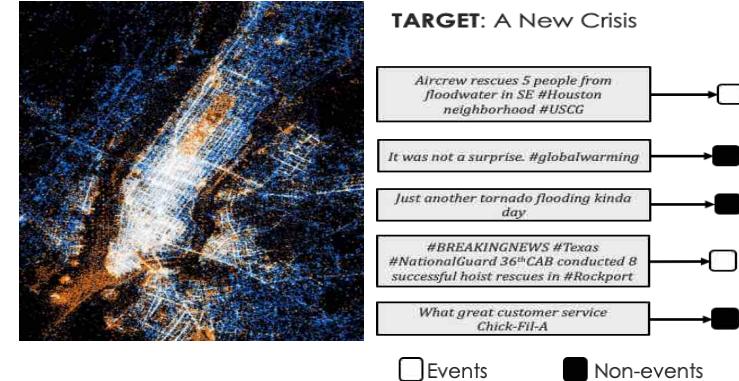
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Characteristics of social indicators

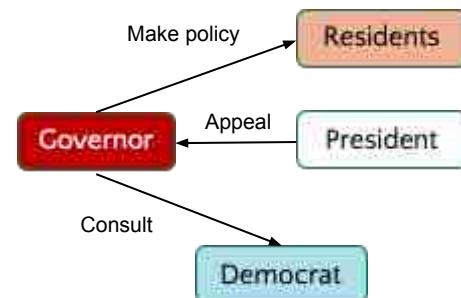
- Social Media

- Ubiquitous
 - Every user/agent of social media/web/forum is a social sensor (citizen sensor)
 - They are everywhere observing the world all the time.
- Timeliness
 - 6,000 tweets every second.
 - 500 million tweets per day.
 - Usually beats the earliest official reports.



- Event encoding systems

- Annotations
 - Each event is labeled with subject, object, type, and time, formulating a graph
- Comprehensive coverage
- Less prompt

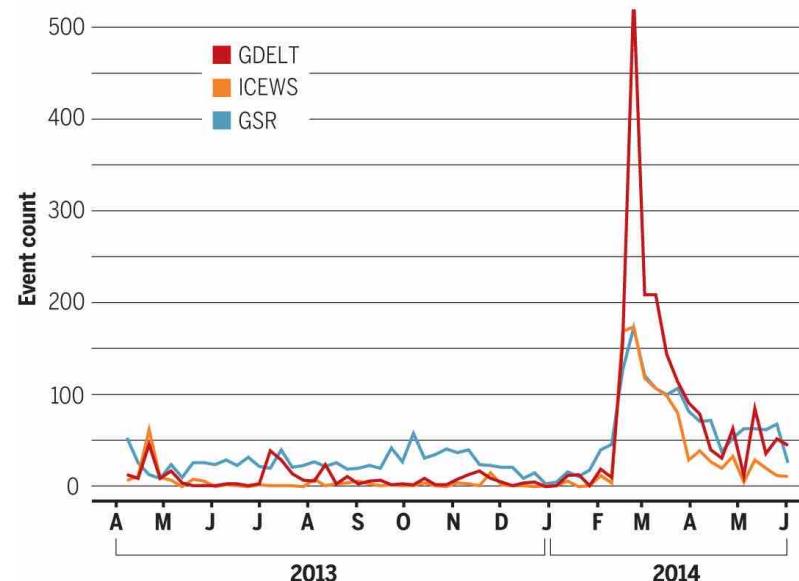


Challenges in human event prediction

Multi-source unstructured data

Weekly count of protest events in Venezuela

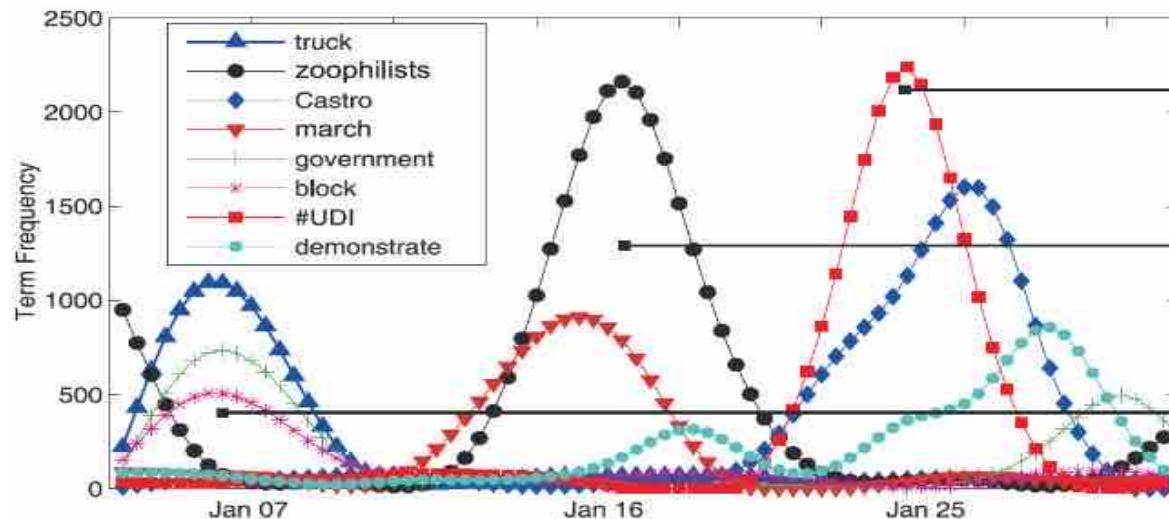
Event data from GDELT, Global Data on Events Language and Tone; ICEWS, International Crisis Early Warning System; and GSR, Gold Standard Report (see suppl. materials).



Challenges in human event prediction

Dynamic and rapid changes over time

New words, entities, relations and shift of topics



Source: Spatio-Temporal Event Forecasting and Precursor Identification. Tutorial in 25th ACM SIGKDD Conference on Knowledge Discovery and Data Mining (KDD 2019)

Challenges in human event prediction

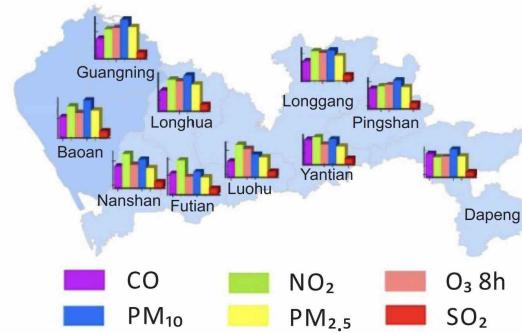
Heterogeneous data

Need to align data samples with different time granularity

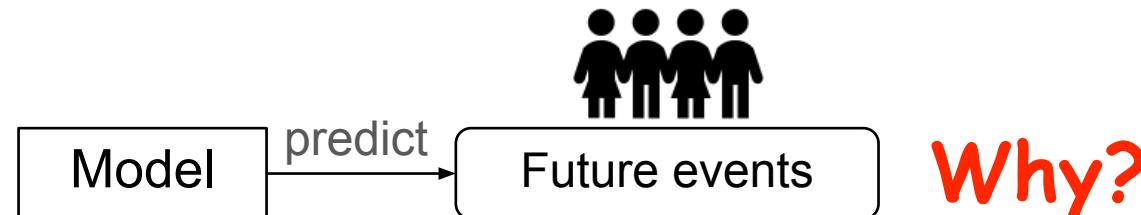


Other challenges

Dependencies among events, e.g., spatial dependencies



Lack of interpretability – benefit for decision making



Explainable event prediction

- **Social indicators** can be general signals, features, and even distributions in open source data sets.
- **Precursor discovery** refers to identifying specific examples or instances in the historical data given a prediction.
- **Explainable predictive models** uncover significant features, graphs, documents for explaining prediction results.

An example event

2014 Venezuelan National Students Protest



major protests began with student marches led by opposition leaders in 38 cities.

Feb. 12

2014 Venezuelan National Students Protest



Opposition Leader, López, called upon students to peacefully protest.

major protests began with student marches led by opposition leaders in 38 cities.



Feb. 1

Feb. 12

2014 Venezuelan National Students Protest



López, alongside María Corina Machado launched a campaign to remove Maduro from office.



Opposition Leader, López, called upon students to peacefully protest.



major protests began with student marches led by opposition leaders in 38 cities.

Jan. 23

Feb. 1

Feb. 12

2014 Venezuelan National Students Protest



Murder of former Miss Venezuela, Monica Spear.



Former presidential candidate Henrique Capriles shook the hand of President Maduro



Attempted rape of a young student on a university campus in San Cristóbal



The harsh police response to their initial protest



López, alongside María Corina Machado launched a campaign to remove Maduro from office.



Opposition Leader, López, called upon students to peacefully protest.



major protests began with student marches led by opposition leaders in 38 cities.

January

Jan. 23

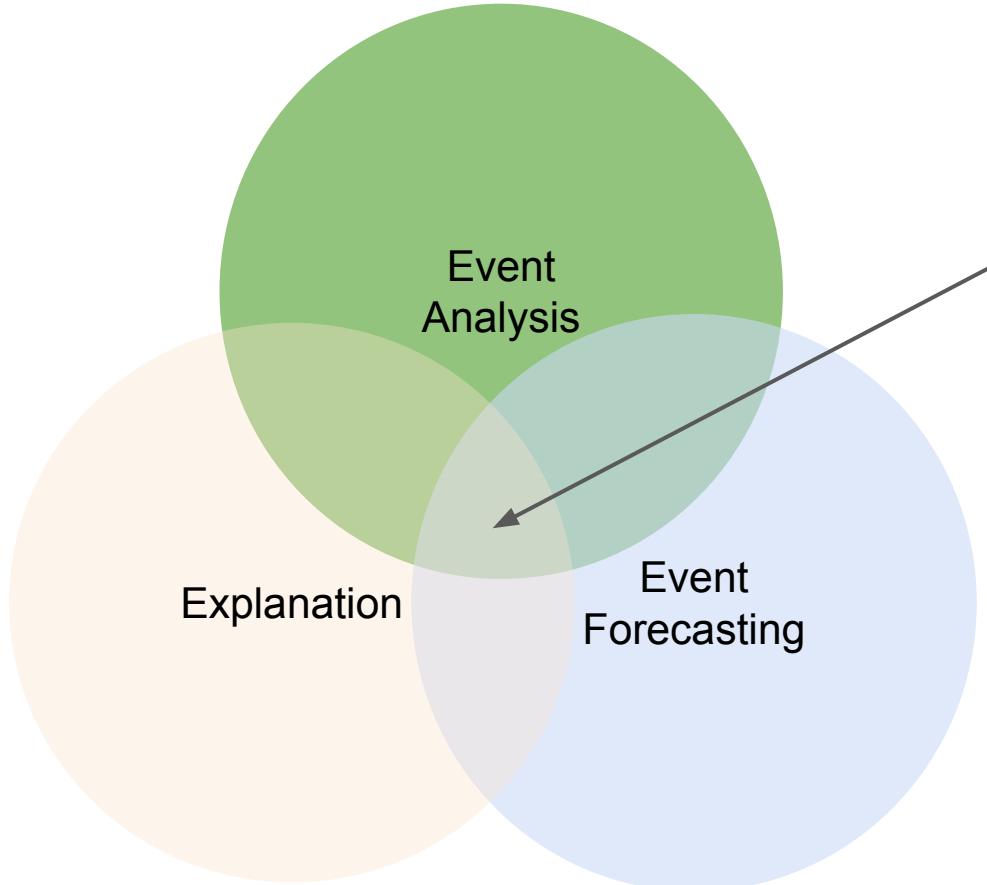
Feb. 1

Feb. 12

If social scientists need to do this a lot



Overview



Early approaches

Statistical methods

- A probabilistic model [Radinsky et al. 2013]
 - Assume that events in the real-world are generated by a probabilistic model that also generates news reports corresponding to these events.
- A threshold-based approach [Manrique et al. 2013]
 - The model forecasts civil unrest relying on a search in volume of event-related terms and their momenta.
- Hidden markov model [Qiao et al. 2017]
 - A HMMs-based social unrest (SU) event prediction framework: two HMMs are trained, with one for SU-prone sequences and one for SU-free sequences.

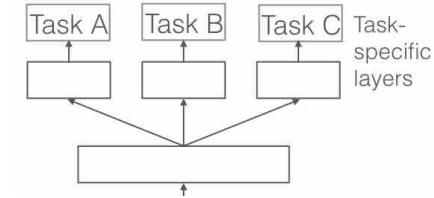
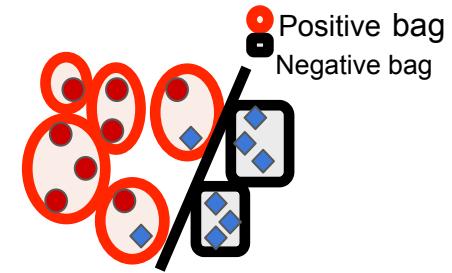
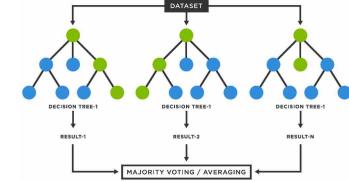
Radinsky, Kira, and Eric Horvitz. **Mining the web to predict future events**. *WSDM*. 2013.

Manrique, Pedro, et al. **Context matters: Improving the uses of big data for forecasting civil unrest: Emerging phenomena and big data**. *IEEE International Conference on Intelligence and Security Informatics*. 2013.

Qiao, Fengcai, et al. **Predicting social unrest events with hidden Markov models using GDELT**. *Discrete Dynamics in Nature and Society* 2017.1.

Machine learning methods

- Random Forest [Kallus 2014]
 - Quantify the predictive signals/features
- Multi-Instance Learning [Ning et al. 2016]
 - Incomplete knowledge about labels in training data;
Propagate bag level supervision to individual document
- Multi-task learning [Ning et al. 2018]
 - Explicitly enforces pairs of cities with similar event patterns in the past to learn similar vectors.



Kallus, Nathan. **Predicting crowd behavior with big public data**. World Wide Web. 2014.

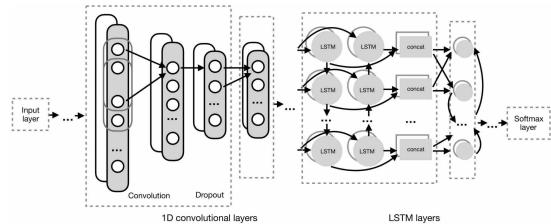
Ning, Yue, et al. **Modeling precursors for event forecasting via nested multi-instance learning**. KDD 2016.

Ning, Yue, et al. **STAPLE: Spatio-temporal precursor learning for event forecasting**. SDM 2018.

Early deep learning methods

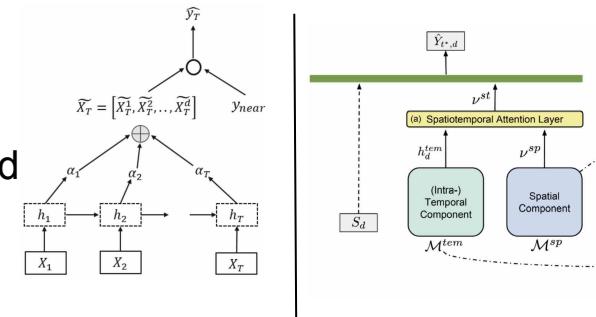
- Recurrent neural networks (RNNs) [Meng et al. 2019]

- Use recurrent neural networks (RNN, LSTM) to capture temporal information of event signals to predict the civil unrest events.



- Attention models [Wang et al. 2018, Ertugrul et al. 2019]

- Use attention methods to study different contributions of data points in the time series for predicting civil unrest and explaining feature importance.



Meng, Lu, et al **Leveraging heterogeneous data sources for civil unrest prediction**. *Social, Cultural, and Behavioral Modeling* (2019).

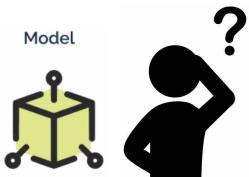
Wang, Xiuling, et al. **Unrest news amount prediction with context-aware attention Istm**. *PRICAI 2018*

Ertugrul, Ali Mert, et al. **Activism via attention: interpretable spatiotemporal learning to forecast protest activities**. *EPJ Data Science* 8.1 (2019).

Limitations of these works

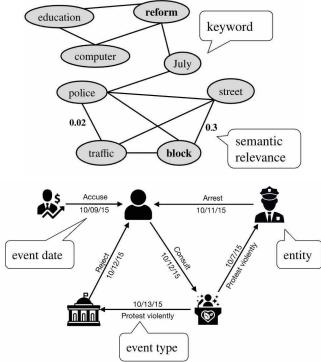


Reliance on feature selection and engineering



Limited model ability to understand predicted events

Limitations of using grid-like or homogeneous data



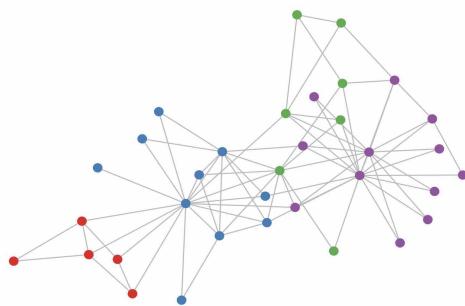
Limited causal analysis in event prediction



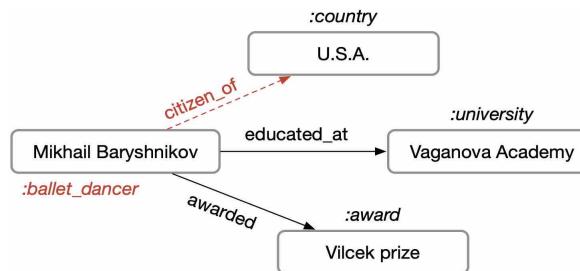
Part 1: Graph Neural Network (GNN)-based methods

Graph Neural Networks (GNNs)

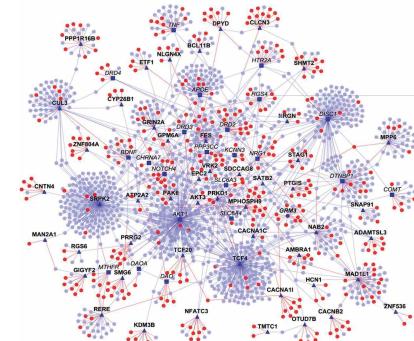
GNNs are a class of neural networks that operate on graph-structured data. GNNs are powerful for graph representation learning in diverse domains.



Social Networks



Knowledge Graphs



Protein Interaction Networks

Standard CNN and RNN architectures cannot work effectively on graph-structured data.

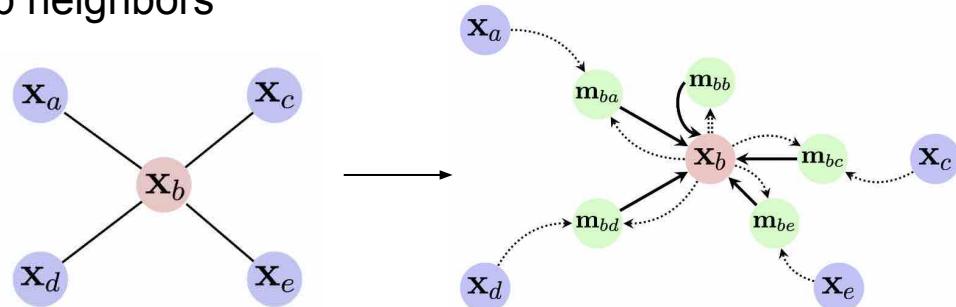
How do GNNs work?

A message-passing-framework perspective

- Node representation updates by aggregating messages sent from its neighbors
- K-layer GNNs take into account K-hop neighbors

Representative GNN models

- Graph Convolutional Network (GCN)
- Graph Attention Network (GAT)
- Relational Graph Convolutional Networks (R-GCNs)

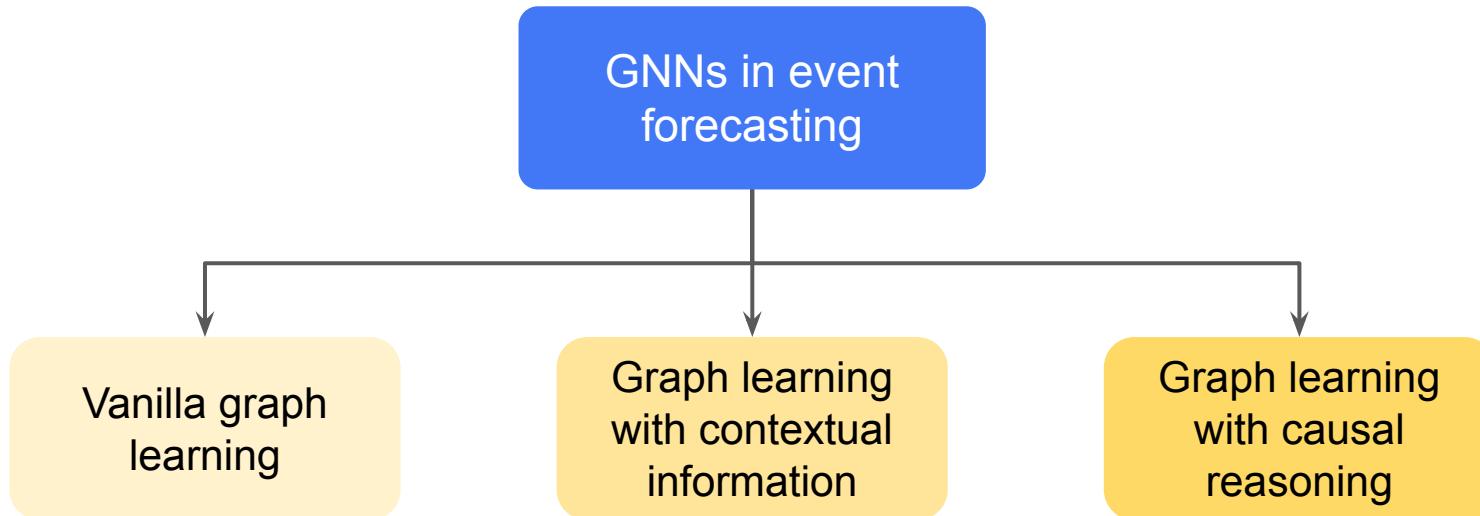


Kipf, Thomas N., and Max Welling. **Semi-supervised classification with graph convolutional networks**. arXiv:1609.02907 (2016).

Veličković, Petar, et al. **Graph attention networks**. arXiv preprint arXiv:1710.10903 (2017).

Schlichtkrull, Michael, et al. **Modeling relational data with graph convolutional networks**. "ESWC 2018.

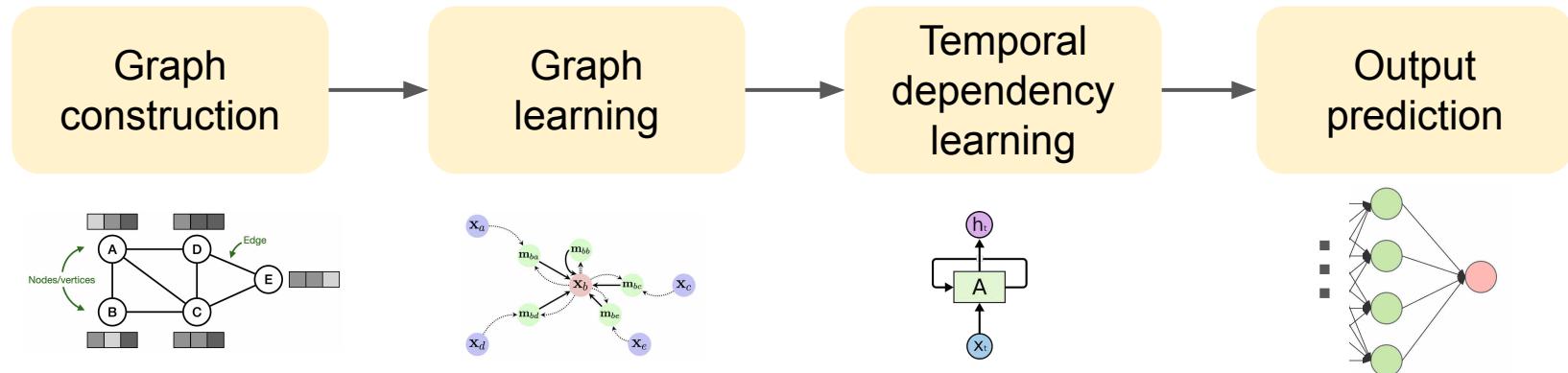
GNNs in event forecasting



Vanilla graph learning

Vanilla graph learning

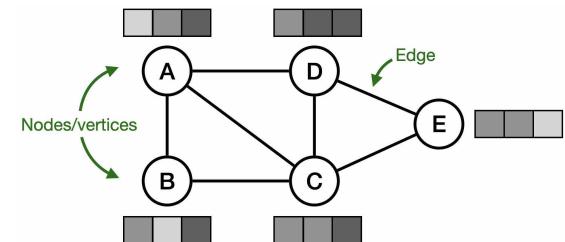
Concentrate on graph operations, which leverage node and/or edge embeddings techniques.



Graph construction

Define graph structure

- Historical event data (G_{t-k+1}, \dots, G_t) where k is the sequence length.
- $G_t = (V_t, E_t)$ is the graph at time t with the node set V and edge set E.



Define features for graph elements

- Word embeddings for node features at time t denoted as $X_t^{N \times d}$, where N is the number of words and d is the feature dimension.

Graph learning

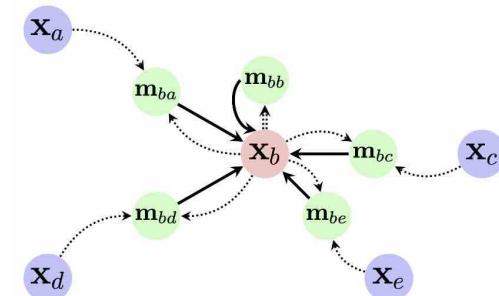
Update node and/or edge representations based on information from neighboring nodes.

Updated representation of node i

Neighbor information extractor

$$\mathbf{H}_t^{(l)}[i] \leftarrow \text{AGG}_{\forall j \in N_t(i), \forall e \in E_t(j,i))} \left(\text{EX} \left(\mathbf{H}_t^{(l-1)}[i]; \mathbf{H}_t^{(l-1)}[j], e \right) \right)$$

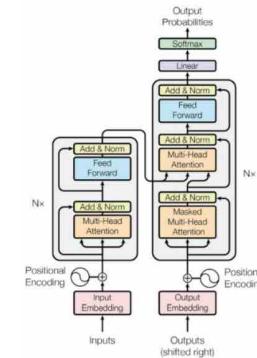
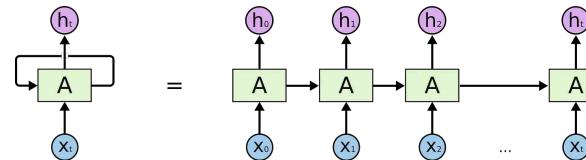
Gathers the neighborhood information of source nodes, e.g., mean, max.



Temporal dependency learning

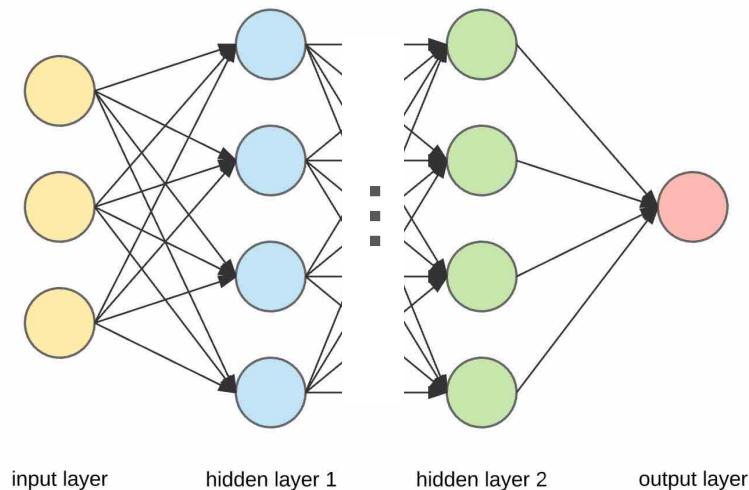
This step involves capturing **temporal dependencies** from past events to effectively forecast future events.

Techniques commonly employed include time series analysis methods, recurrent neural networks, attention mechanisms, or customized temporal methods.



Output prediction

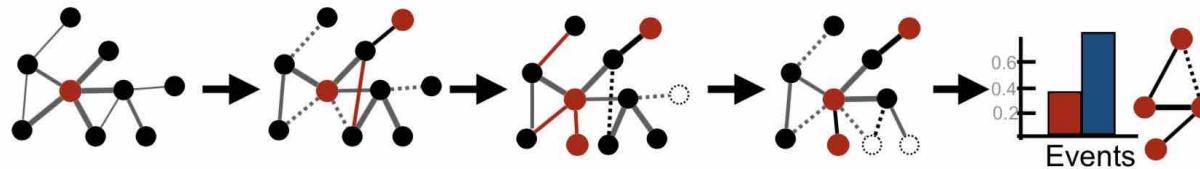
Use the learned node or graph representations for downstream tasks, such as predicting **binary events** or **concurrent** events, by applying an appropriate output layer.



E.g., applying sigmoid to predict the binary occurrence of events.

Learning Dynamic Context Graphs for Predicting Social Events [Deng et al. KDD19]

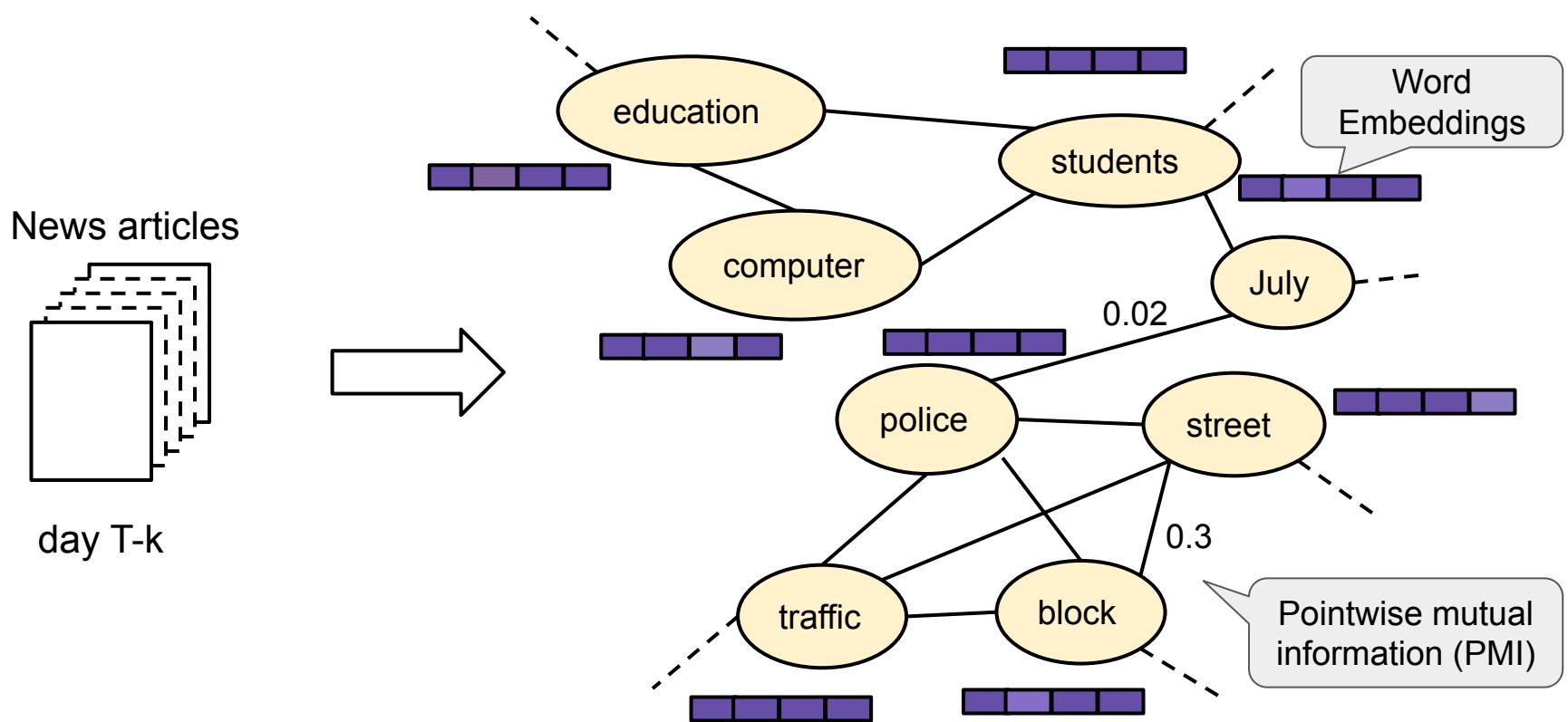
Propose a novel **graph-based model** for predicting events and identifying relevant event subgraphs.



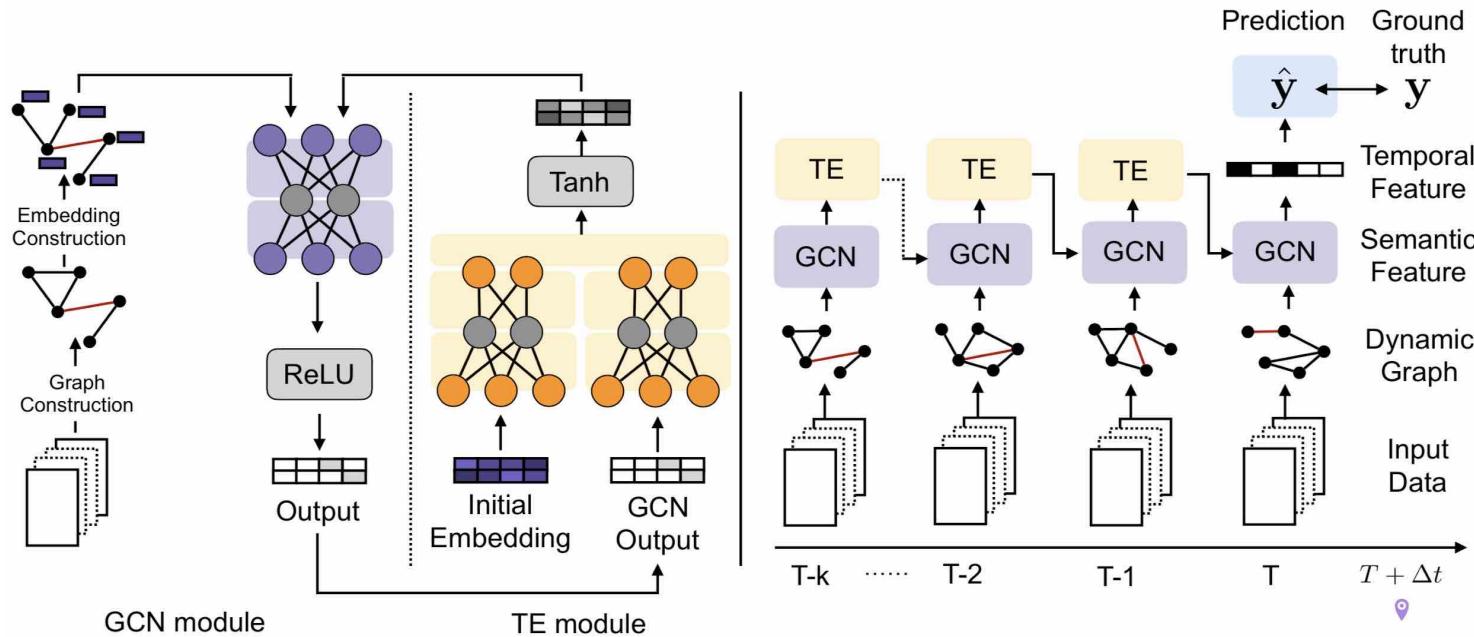
Motivation

- Improve the interpretability of event forecasting algorithms by **providing supporting evidence/clue**, e.g., subgraphs.
- Graph structured data encode rich information and easy to understand.

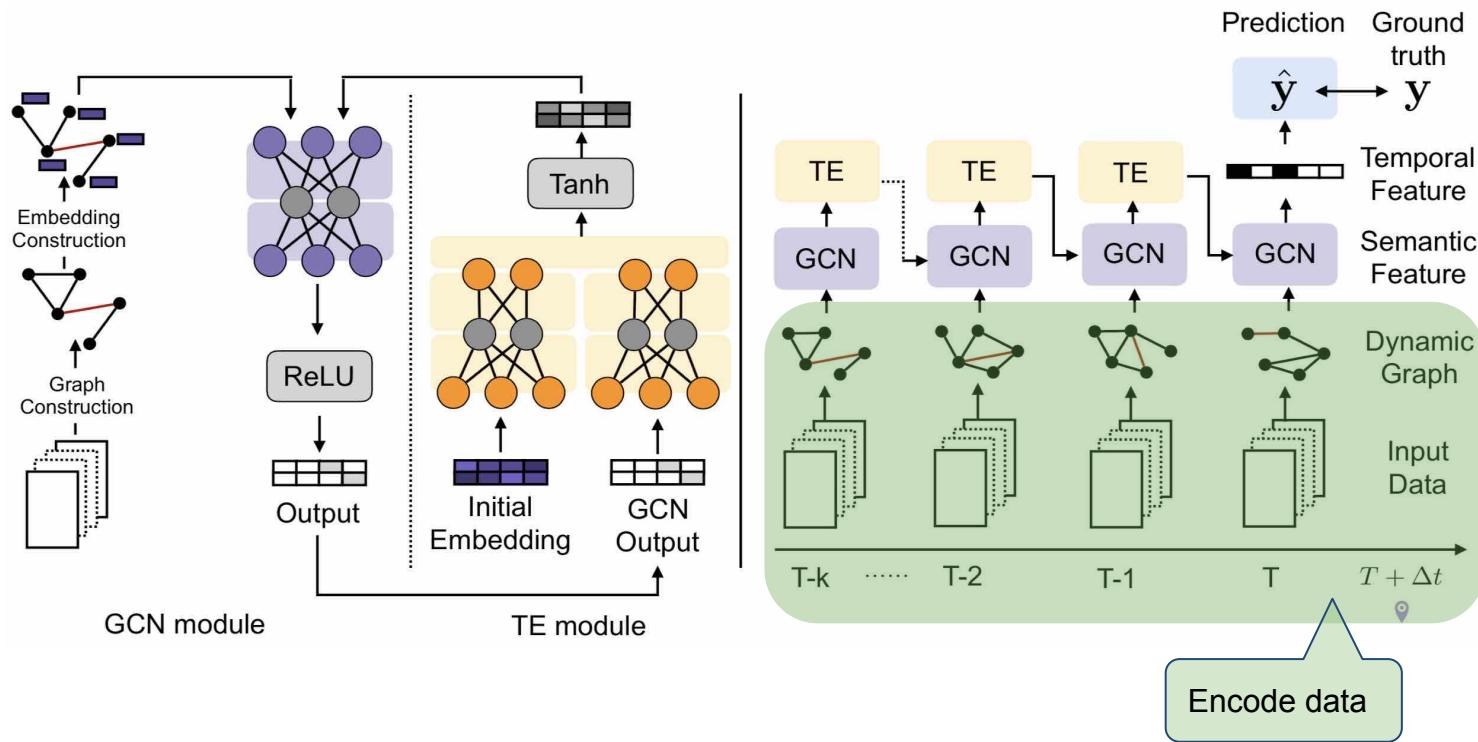
Encoding documents into graphs



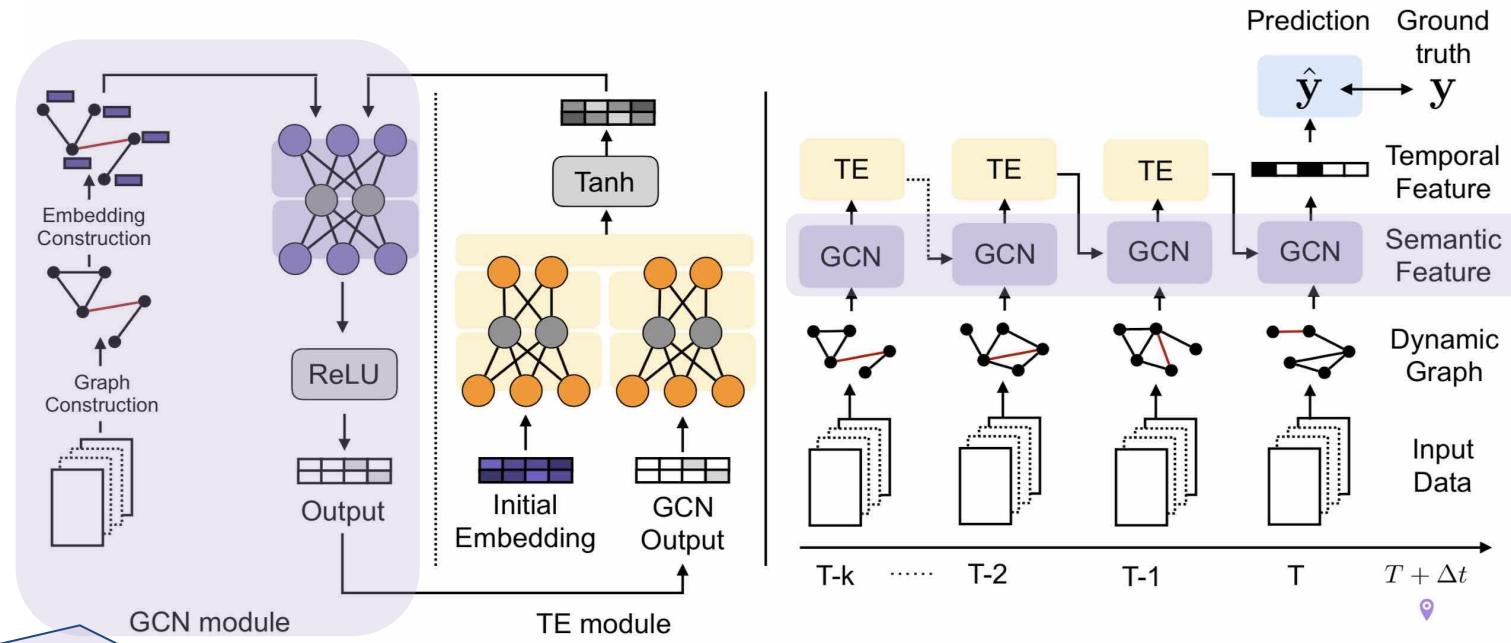
Model framework: DynamicGCN



Model framework: DynamicGCN

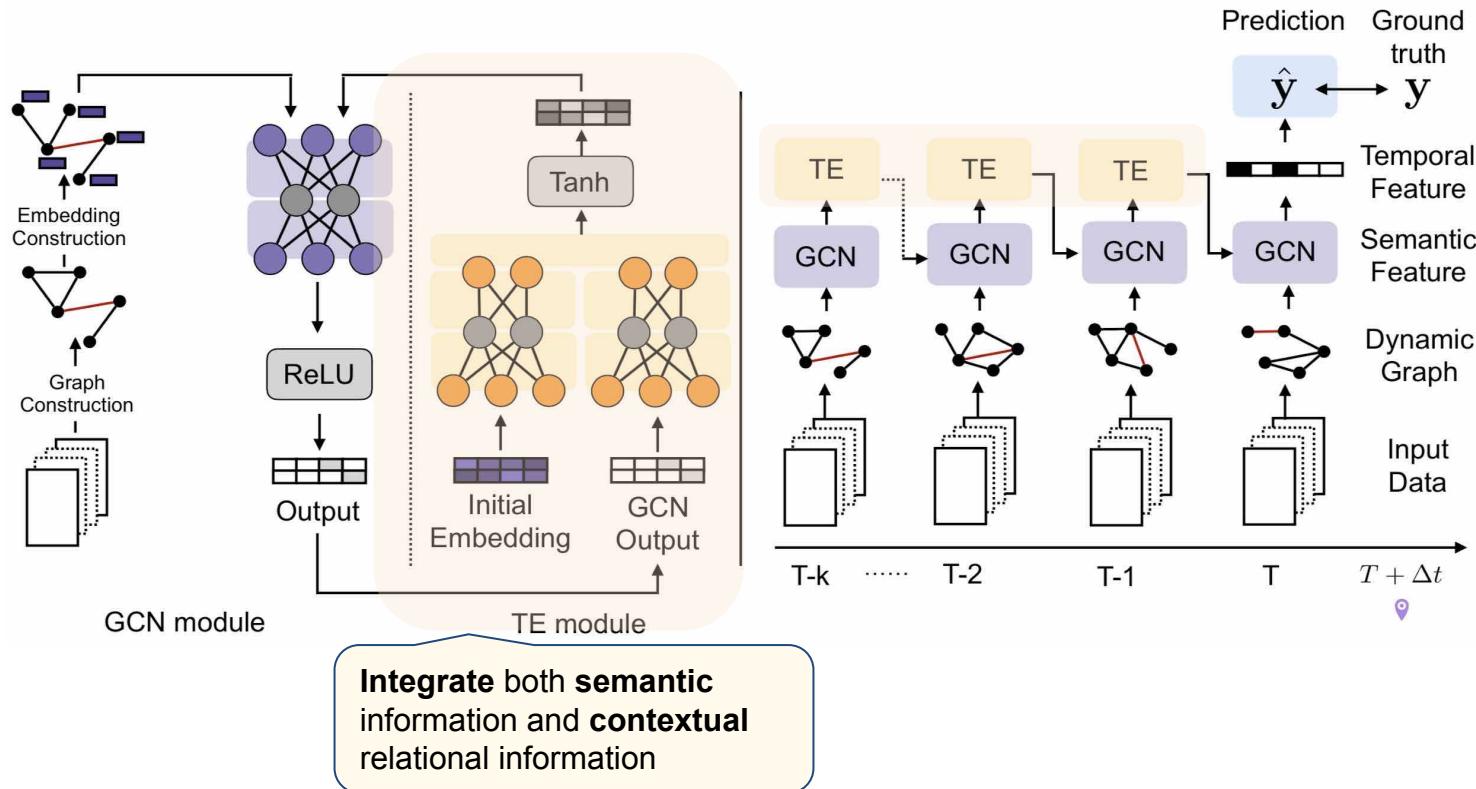


Model framework: DynamicGCN

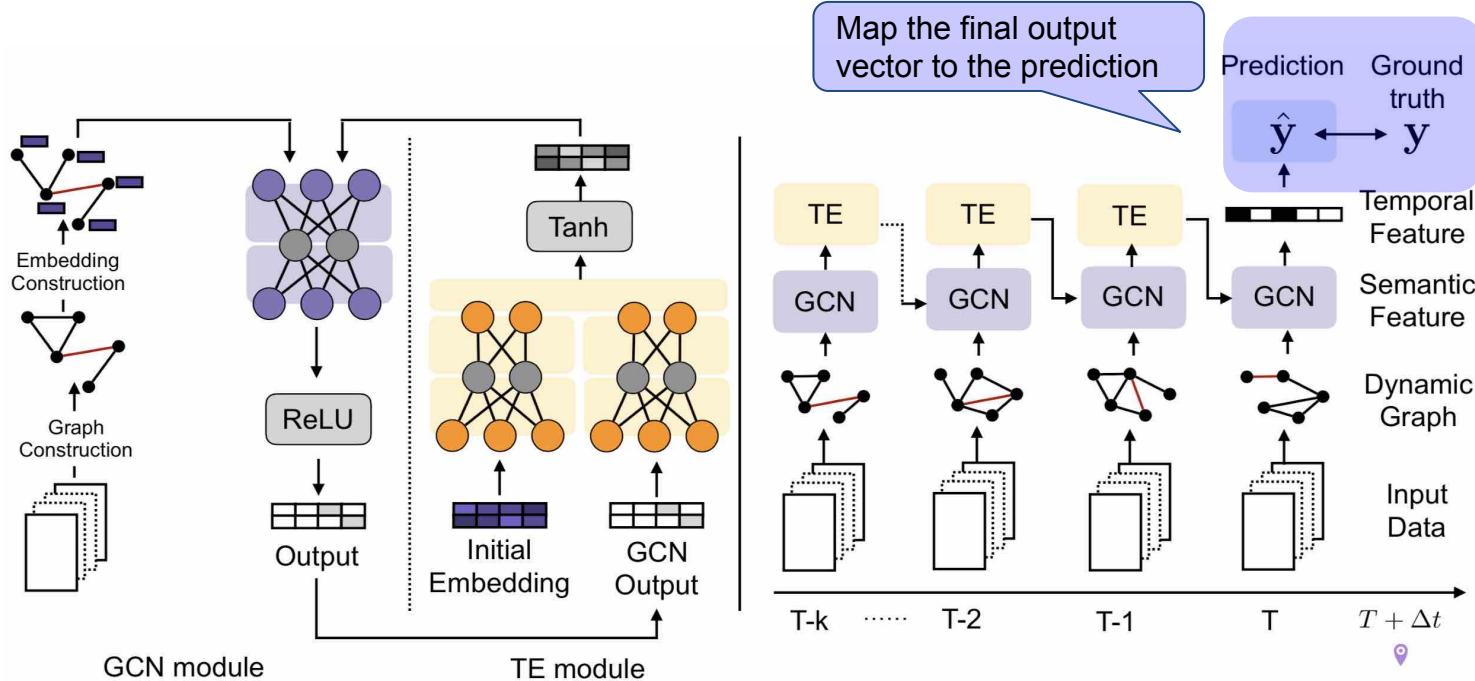


Learn the node representation
by involving the semantic
information from neighbors

Model framework: DynamicGCN



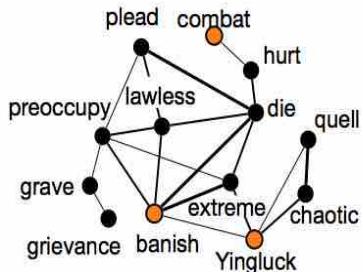
Model framework: DynamicGCN



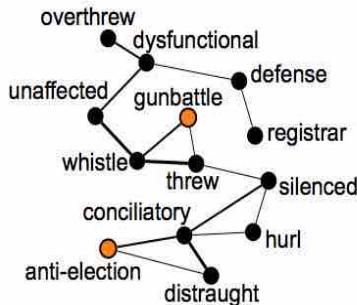
A case study

Context subgraphs generated from the trained model.

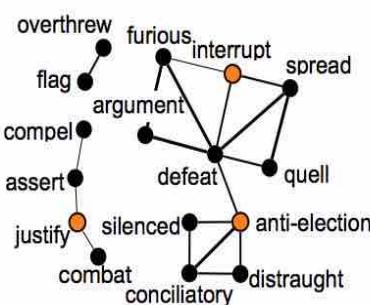
02/01/2014



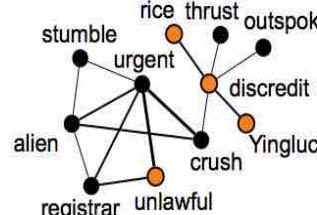
02/02/2014



02/03/2014



02/05/2014



02/07/2014



Violence grips Thai capital on eve of vote called by Yingluck.

Thailand started voting. Voters blocked by anti-election groups squared off with scuffles and hurled objects.

Election Commission asked the national police chief to maintain law and order. Thai Protests Disrupt Vote.

Yingluck's former commerce ministers were suspected of being involved in improper rice deals.

The election related to **Yingluck** was ever **interrupted**

A possible fraud involving **rice** traders and some **politicians**.



Coffee Break

(15 minutes)

Next: Part 1: Graph Neural Network (GNN)-based methods

- Graph learning with contextual information

Graph learning with contextual information

- Context in graph construction
- Context in graph learning

Graph learning with contextual information

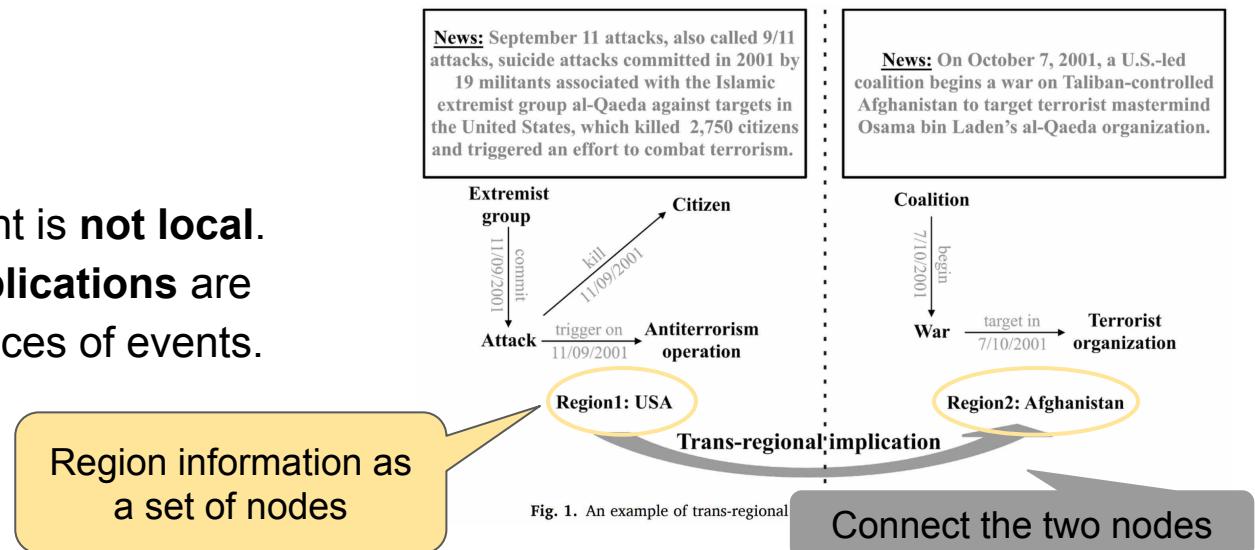
- **Context in graph construction**
- Context in graph learning

Spatial-temporal knowledge graph network for event prediction [Huai et al. 2023]

Introduced **additional spatial and textual information** in graph construction, and proposed a spatial and temporal knowledge graph neural network (STKGN)

Motivation

- Cause of the incident is **not local**.
- **Trans-regional implications** are behind the occurrences of events.



Context-aware event forecasting via graph disentanglement [Ma et al. KDD2023]

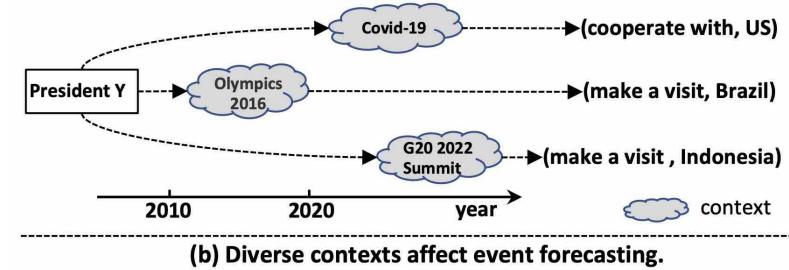
Introduce **specific categorical context** in graph construction, assuming the availability of external prior knowledge.

Motivation

- Most events fall into general types in the event ontology, and tend to be **coarse-grained**.
- Events defined by a fixed ontology **fail to retain out-of-ontology** contextual information.

hierarchical event ontology	% of event types in each level	#events per event type of each level	exemplar event types
1 st level	7%	20,063	02: appeal
2 nd level	43%	4,574	021: appeal for cooperation
3 rd level	50%	407	0211: appeal for economic cooperation

(a) Most events fall into coarse-grained and higher-level types.



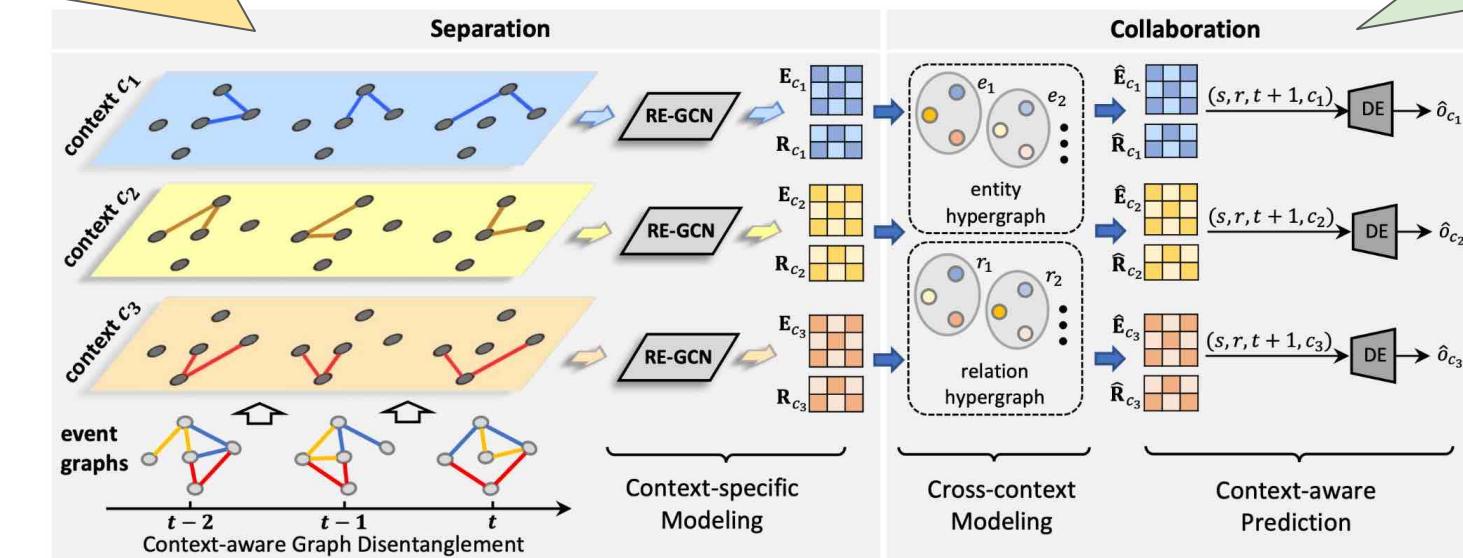
(b) Diverse contexts affect event forecasting.

Leverage contextual information

Define **context** as a **categorical value** and assign it to each event.

1. Use the **context** as a prior guidance to separate the event graphs.
2. Capture the context-specific patterns.

1. Construct **hypergraphs**.
2. GNN learns the collaborative associations among contexts.



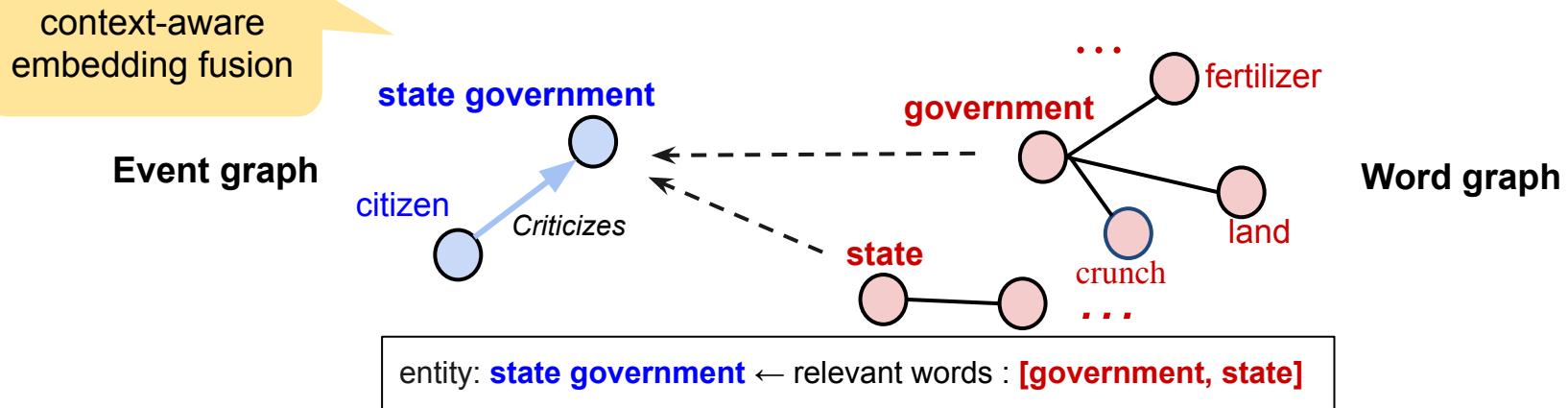
Graph learning with contextual information

- Context in graph construction
- **Context in graph learning**

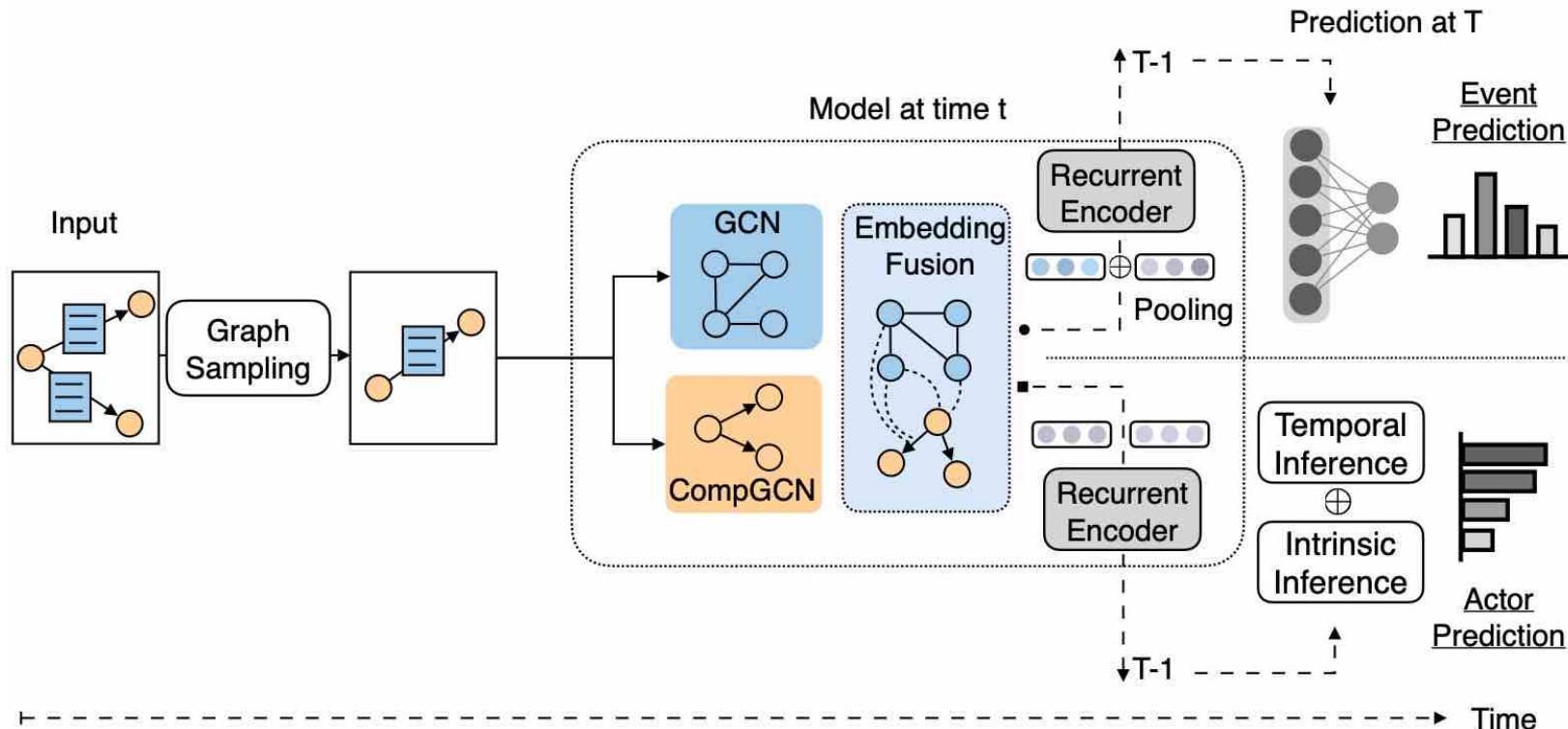
Dynamic knowledge graph based multi-event forecasting

[Deng et al. KDD2020]

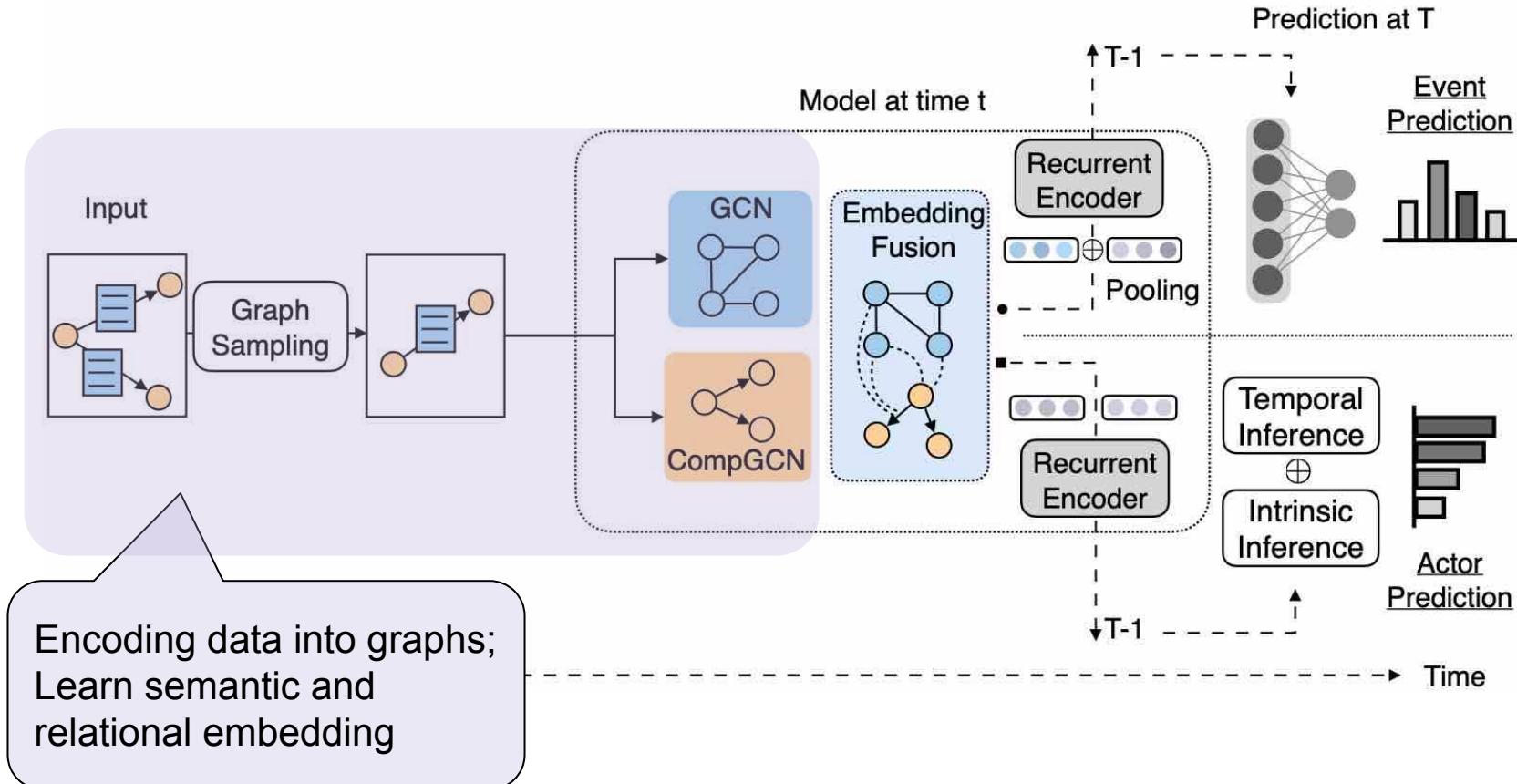
An event: (**Citizen**, *Criticizes*, **State government**, 02/26/2015) “A Politician attacked the government on various fronts such as *fertilizer crunch* and *land acquisition act*.”



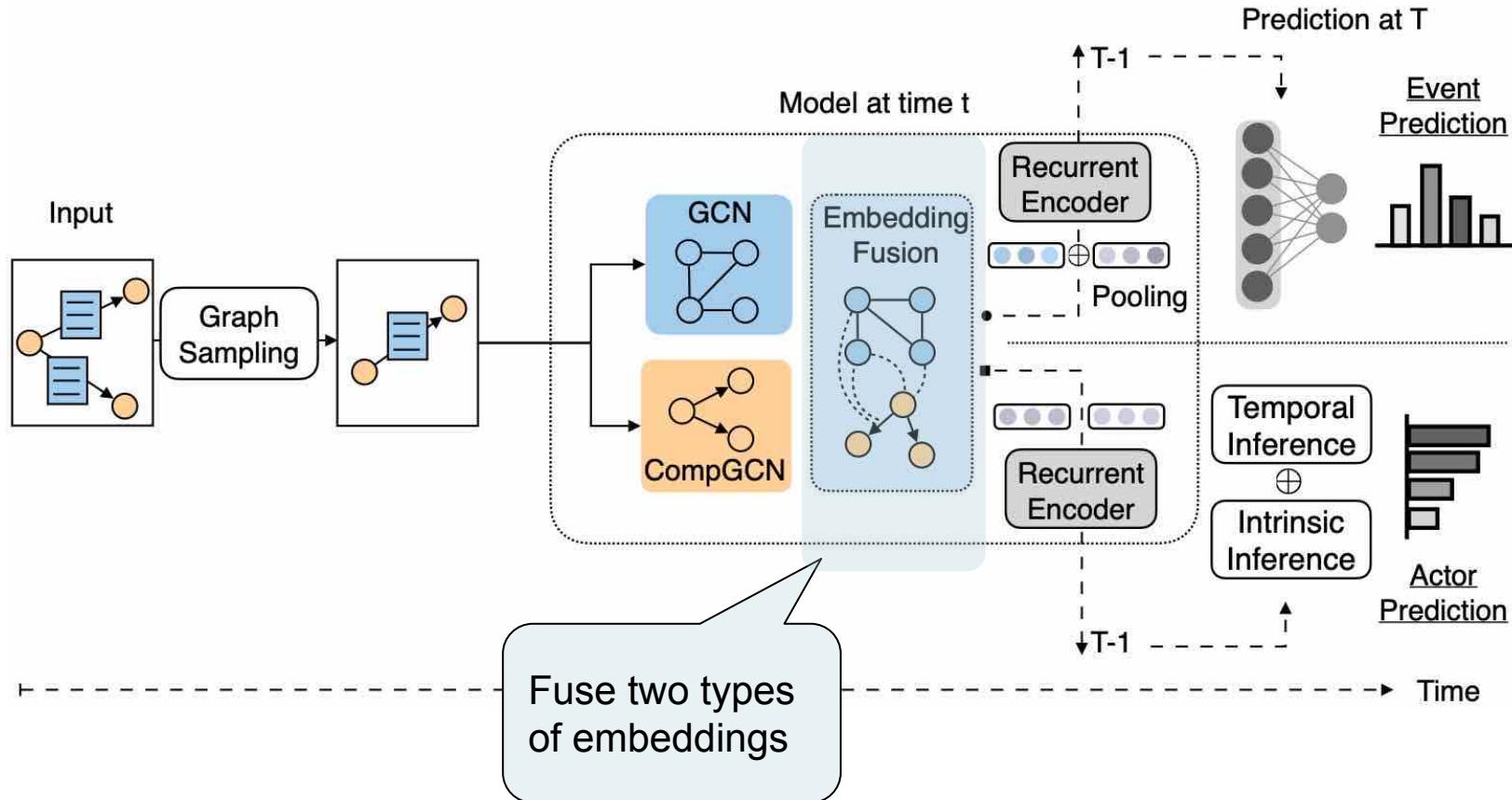
Model framework: Glean



Model framework: Glean



Model framework: Glean



Context-aware embedding fusion

An event: (**Citizen**, Criticizes, **State government**, 02/26/2015) “A Politician attacked the **government** on various fronts such as *fertilizer crunch* and *land acquisition act*.”

Relational embedding learned from event graphs.

(State government)

(state/government)

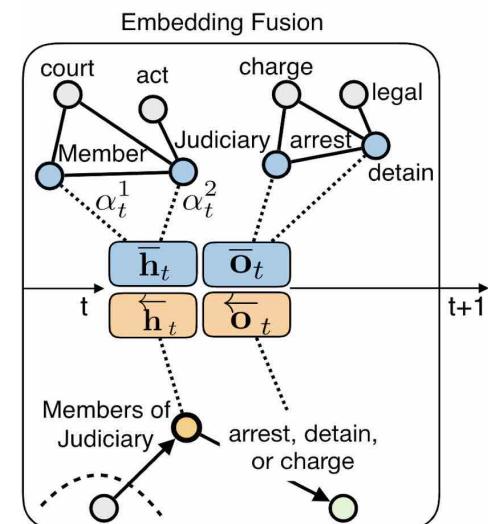
Semantic embedding learned from word graphs.

$$\alpha_{t,(i,\omega)} = \frac{\exp\left(\text{Attn}\left(\overleftarrow{\mathbf{h}}_{t,(i)}, \overline{\mathbf{h}}_\omega\right)\right)}{\sum_{\varphi \in \mathcal{W}_i} \exp\left(\text{Attn}\left(\overleftarrow{\mathbf{h}}_{t,(i)}, \overline{\mathbf{h}}_\varphi\right)\right)} \in \mathbb{R}, \quad (7)$$

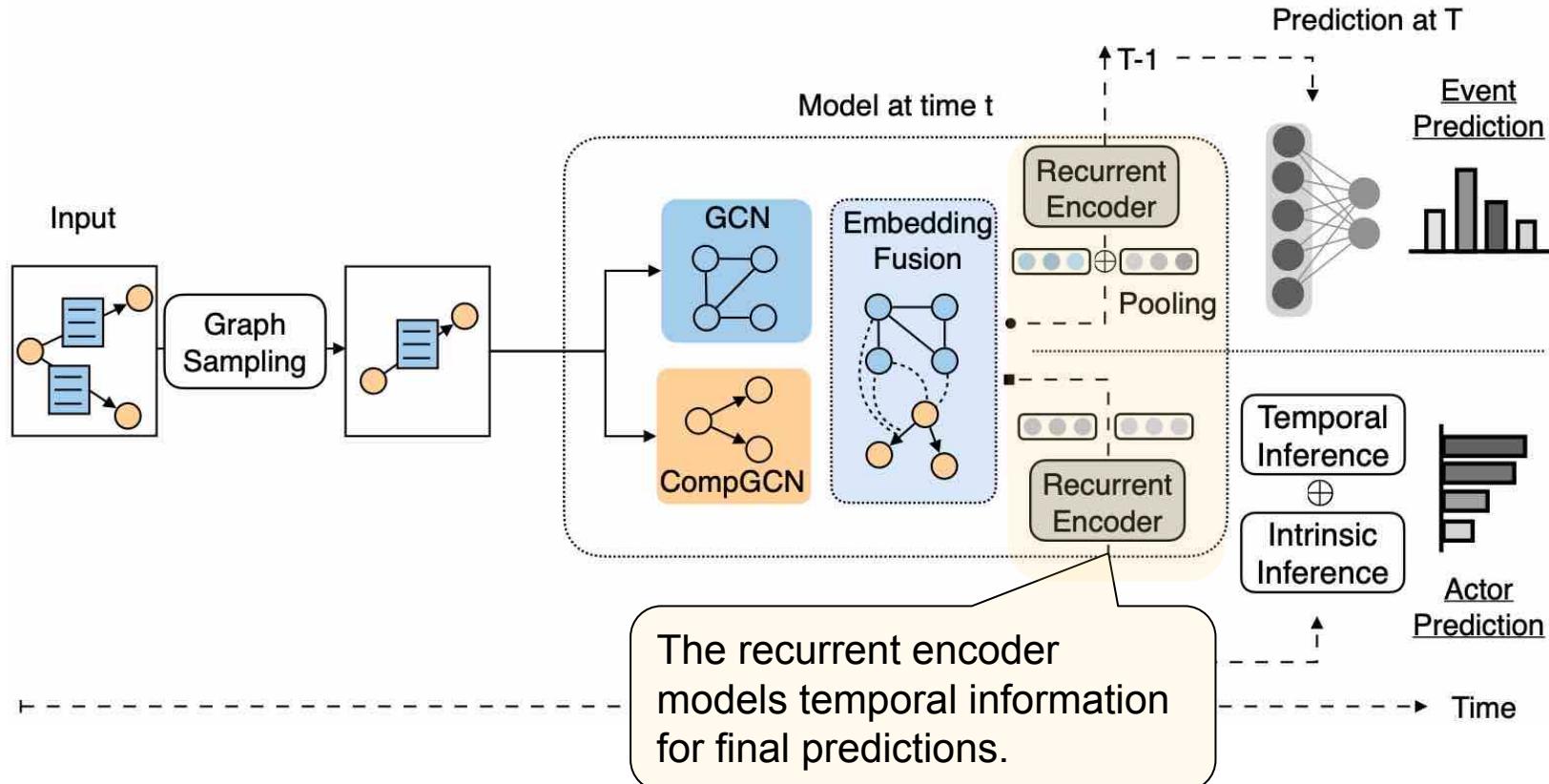
$$\mathbf{h}_{t,(i)}^\star = \tanh\left(\mathbf{W}_\alpha^\top \cdot \left[\underbrace{\overleftarrow{\mathbf{h}}_{t,(i)}}_{\text{rel.}}, \underbrace{\sum_{\omega \in \mathcal{W}_i} \alpha_{t,(i,\omega)} \overline{\mathbf{h}}_\omega}_{\text{semantic}} \right] \right) \in \mathbb{R}^d, \quad (8)$$

Fused embedding that enhances the information of entities (or event types) from words.

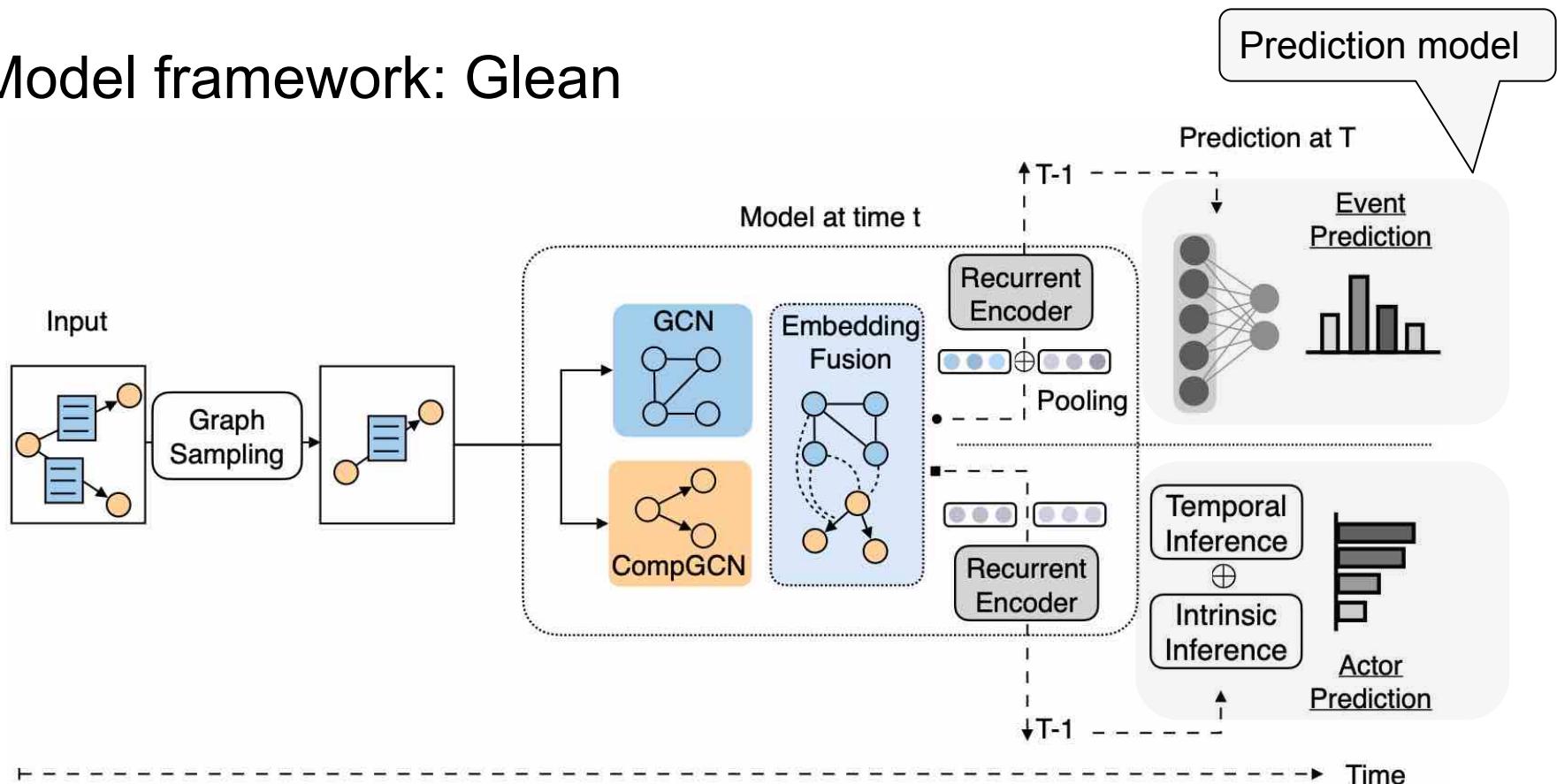
$|\mathcal{W}_i| \geq 1$: the set of words related to entity i



Model framework: Glean



Model framework: Glean



Experimental results

Glean is the best and
“fusion” is helpful.

Multi-event prediction

Method	India			Russia		
	F1	F2	Recall	F1	F2	Recall
DNN	52.49	54.65	56.38	53.81	58.44	62.61
MLkNN	52.33	54.27	55.77	51.38	55.29	58.62
BRkNN	50.36	53.05	56.00	47.46	51.53	56.64
MLARAM	33.68	33.93	34.10	25.67	26.27	26.71
DynGCN	41.80	42.57	43.19	52.81	56.77	60.14
T-GCN	60.73	64.14	67.20	56.36	61.86	67.66
RENET ¹	55.10	57.26	58.99	54.47	58.98	63.02
RENET ²	58.44	61.46	64.18	55.85	60.86	65.66
Glean_fusion	65.91	70.87	75.80	58.92	65.60	73.47
Glean	66.69	71.95	77.31	58.92	65.64	73.57
% relative gain	9.8%	10.9%	15.0%	4.5%	6.1%	8.7%

Multi-actor prediction

Method	India			Russia		
	H @ 1	3	10	1	3	10
DNN	2.09	11.01	33.87	1.46	9.72	36.40
RENET ³	8.87	21.57	39.85	16.52	22.31	40.21
tRGCN	9.74	22.74	41.04	18.83	30.79	44.62
tCompGCN	9.62	21.91	40.53	18.27	30.20	44.79
Glean_temp	13.39	24.50	43.68	18.24	31.15	43.27
Glean_fusion	13.95	27.03	45.73	20.25	34.64	48.10
Glean	14.01	27.17	45.73	20.49	34.36	48.10
% relative gain	4.6%	10.9%	4.7%	8.8%	11.2%	7.4%

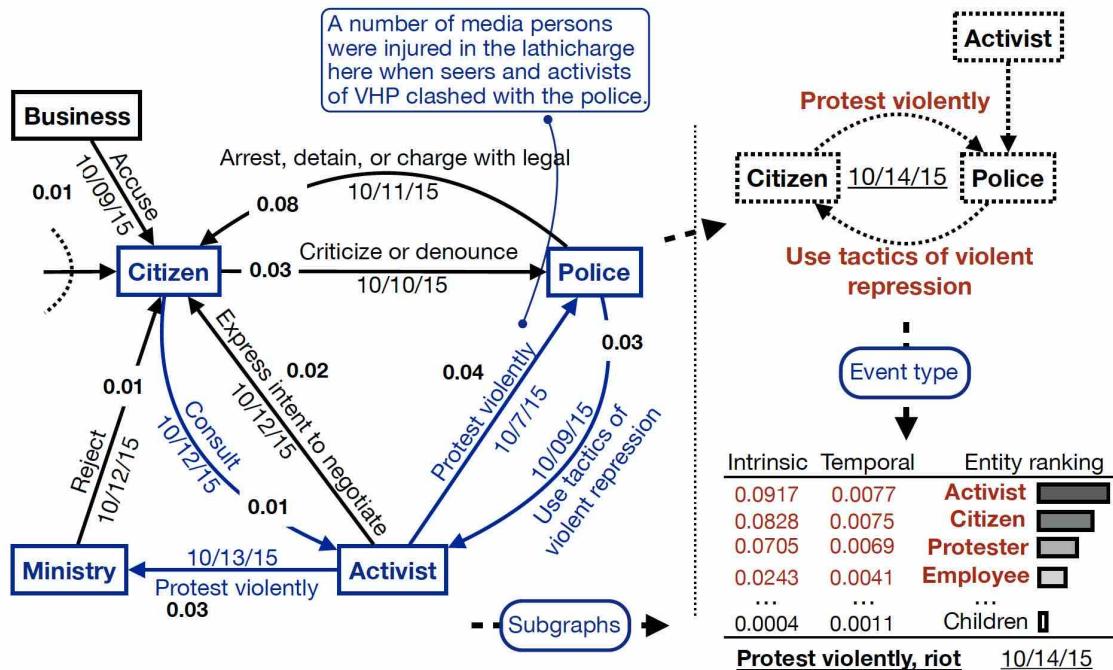
Case study

Identifying important historical events.

The blue part represents the subgraph sampled for actor prediction.

- Select entities that partially retain their feature variables after a max pooling layer.

The red font indicates the model prediction.

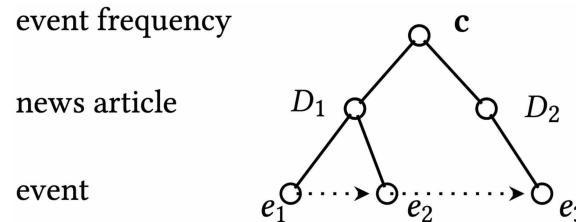


Understanding event predictions via contextualized multilevel feature learning [Deng et al. CIKM2021]

Introduce **contextualized multilevel feature learning** for interpretable event forecasting, i.e., providing example-level explanations.

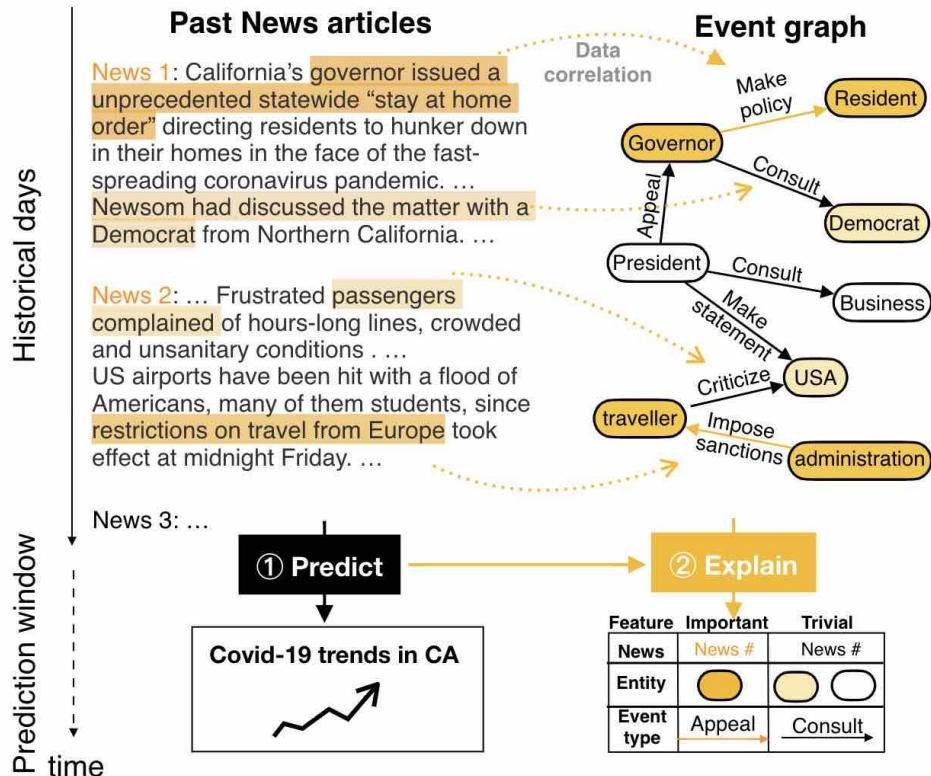
Motivation

- Event data (i.e., ICEWS) can be organized in **multiple levels**.
- Combining multilevel features can provide **rich explanations**.



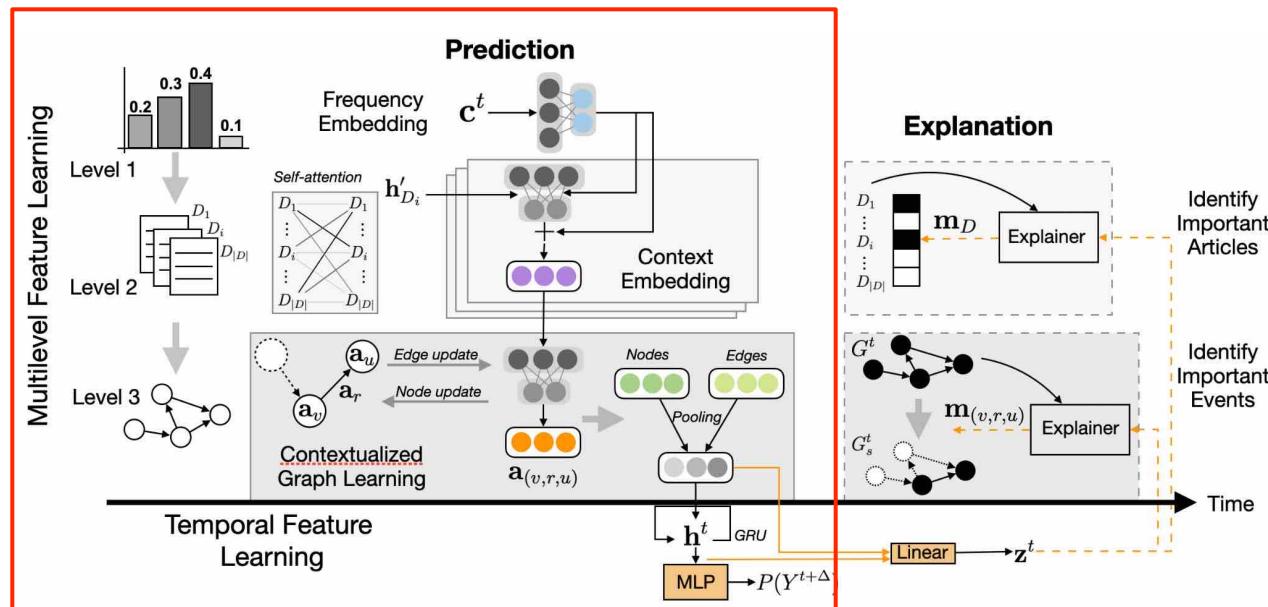
A motivating example

Predicting and explaining Covid-19 trends in CA.



Model framework: CMF (Contextualized Multilevel Feature learning)

- A **predictor** fuses hierarchical and heterogeneous data, and learns sequential features.

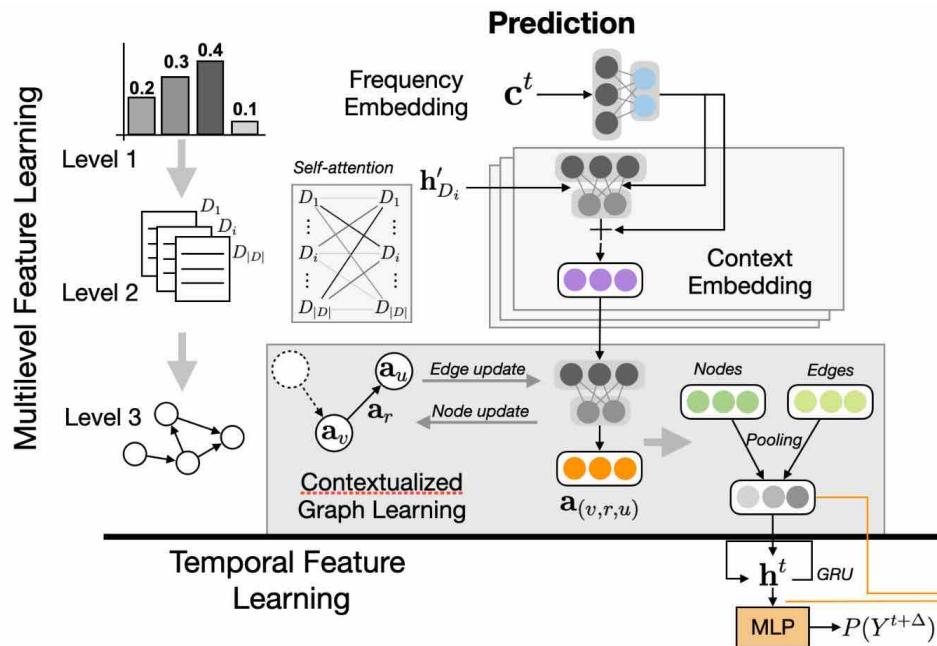


Prediction

1. **Multilevel feature learning** that hierarchically models heterogeneous data.

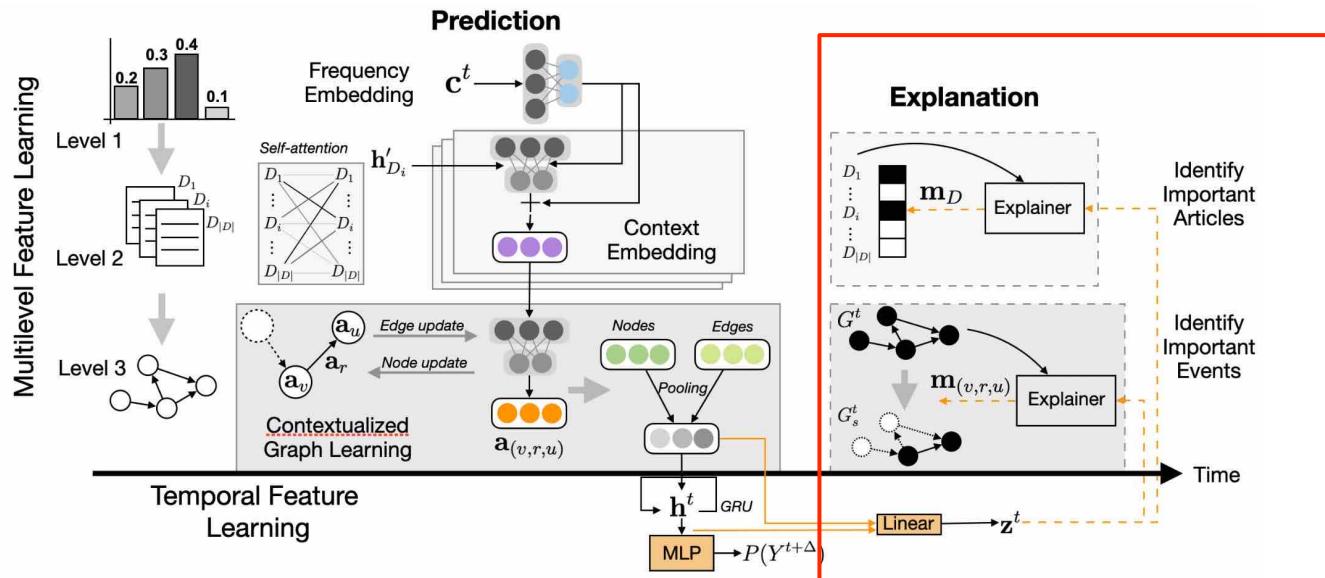
- *Level 1 Frequency Embedding*
- *Level 2 Context Embedding*
- *Level 3 Contextualized Graph Learning*

2. GRU learns sequential information across different historical time steps.



Model framework: CMF (Contextualized Multilevel Feature learning)

- An **explainer** provides temporal and multilevel explanations.



Multilevel explanation

The learning objective:

- Identify a subset of **key news articles** and a **subgraph of key events** over the historical time window.

Formalize the **feature importance** using Mutual Information (MI):

$$\begin{aligned} & \underset{\{\mathcal{D}_s\}^{t-w+1:t}}{\text{Max}} MI(\hat{y}^{t+\Delta}, \{\mathcal{D}_s\}^{t-w+1:t}) \\ &= H(\hat{y}^{t+\Delta}) - H(\hat{y}^{t+\Delta} \mid \{\mathcal{D}_s\}^{t-w+1:t}) \end{aligned}$$

Since direct approximation is intractable, we relax the objective using parameterized neural networks to obtain $\{\mathcal{D}_s\}^{t-w+1:t}$, i.e., learn important scores for articles and events.

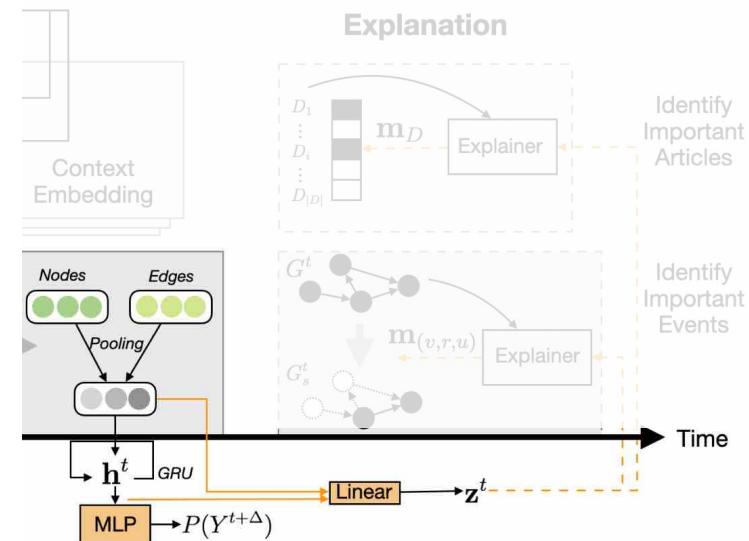
Multilevel explanation

1. Reference embedding, a guideline for selecting important features at each historical time step.

Averaged node and edge embeddings

$$\mathbf{z}^\tau = f_{z_1}(\mathbf{h}^t \oplus \bar{\mathbf{u}}^\tau \oplus \bar{\mathbf{r}}^\tau), \quad t - w + 1 \leq \tau \leq t$$

Final feature vector (GRU)



Multilevel explanation

1. Reference embedding, a guideline for selecting important features at each historical time step.

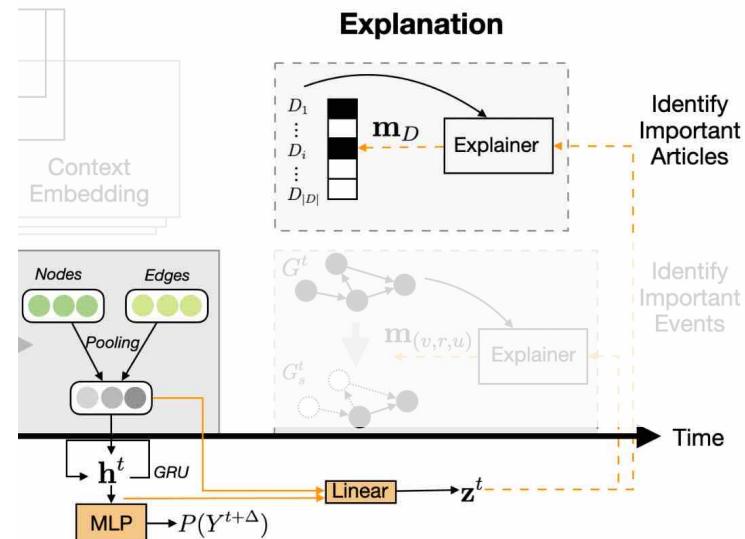
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Final feature vector (GRU)

2. Semantic explanations which identify **key documents** at each historical time step.

$$\alpha_{D_i} = \mathbf{v}^\top \text{Tanh}(\mathbf{W}_a(\mathbf{h}_{D_i} \oplus \mathbf{z}^t))$$



Multilevel explanation

1. Reference embedding, a guideline for selecting important features at each historical time step.

Averaged node and edge embeddings

$$\mathbf{z}^\tau = f_{z_1}(\mathbf{h}^t \oplus \bar{\mathbf{u}}^\tau \oplus \bar{\mathbf{r}}^\tau), \quad t - w + 1 \leq \tau \leq t$$

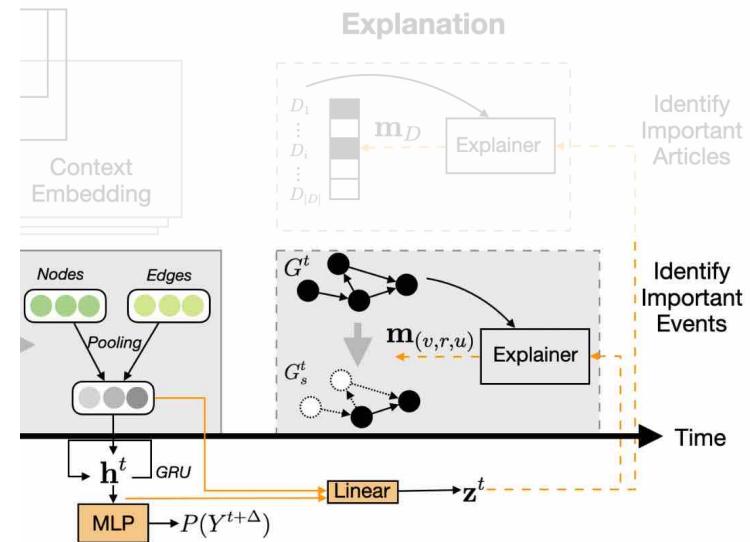
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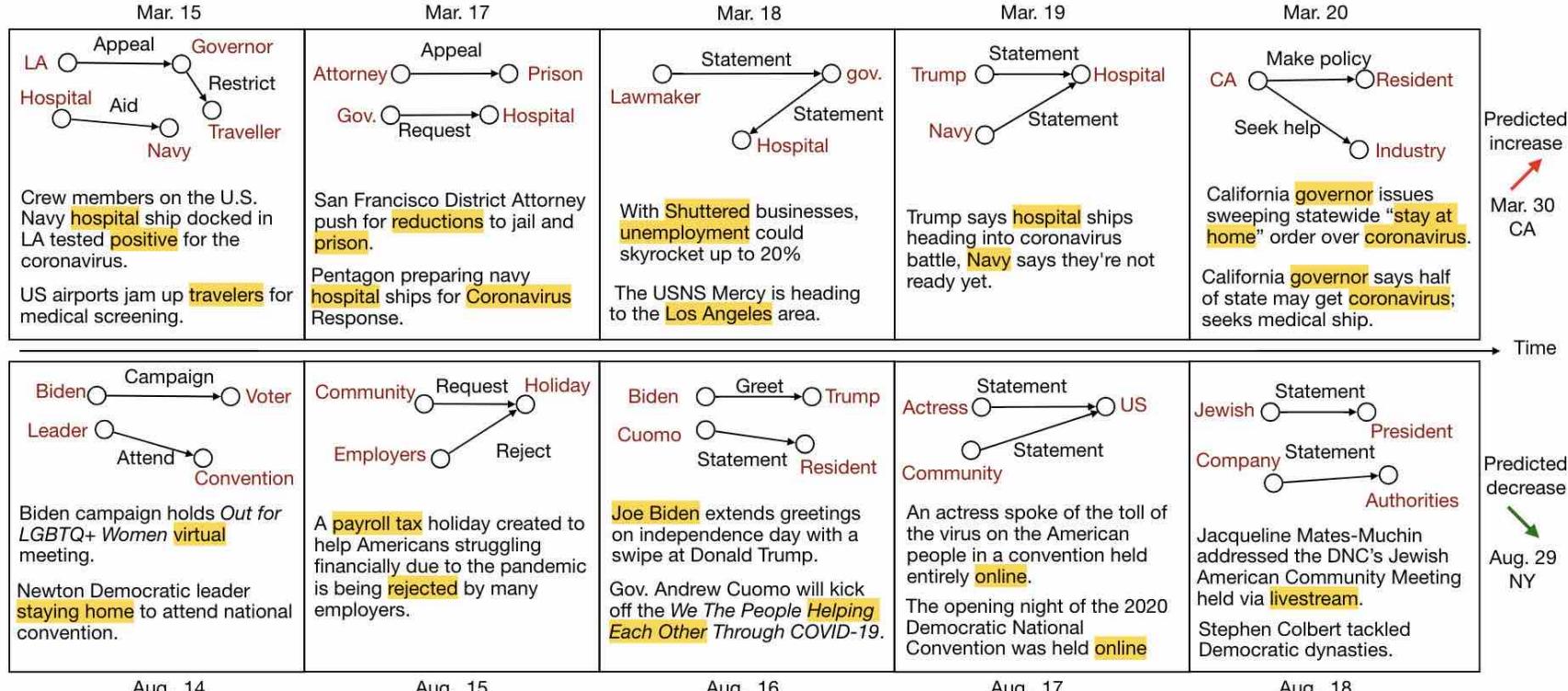
$$\alpha_{D_i} = \mathbf{v}^\top \text{Tanh}(\mathbf{W}_a(\mathbf{h}_{D_i} \oplus \mathbf{z}^t))$$

3. Relational explanations which detect **key events** by applying edge masks.

$$\alpha_{(v,r,u)} = \text{Tanh}\left(f_{z_2}(\mathbf{z}^t \oplus f_{ex}(\mathbf{a}_v \oplus \mathbf{a}_r \oplus \mathbf{a}_u))\right) \quad \text{Event tuple info.}$$



Two explanation examples on the Covid-19 dataset



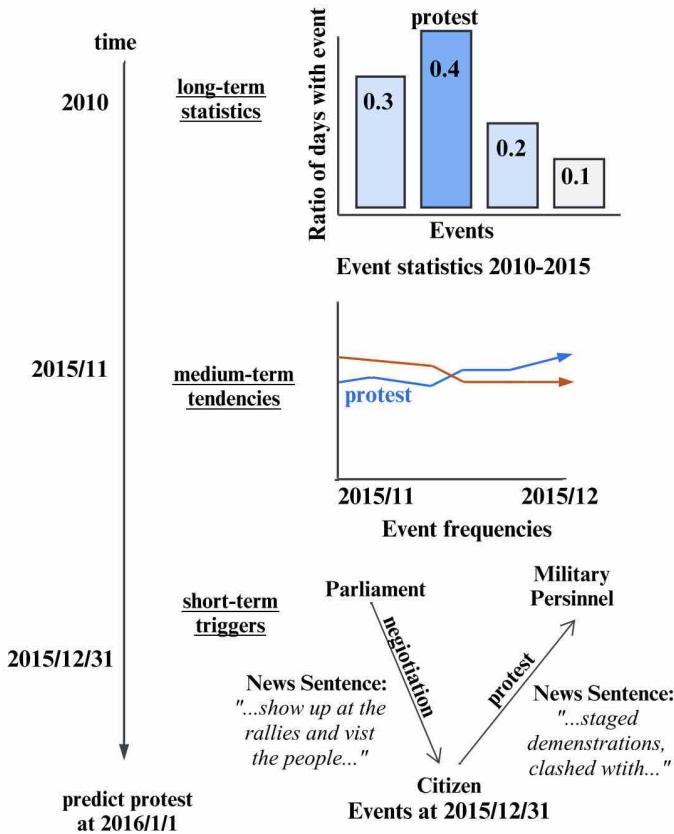
Text-enhanced multi-granularity temporal graph learning for event prediction [Han et al. ICDM2022]

Develop a graph-based model that learns entities and event types embeddings through **different historical hierarchies**.

Motivation

- Existing methods rely on **Markov assumption** that event's probability only depends on **very recent history** – a condition not always true in real life.

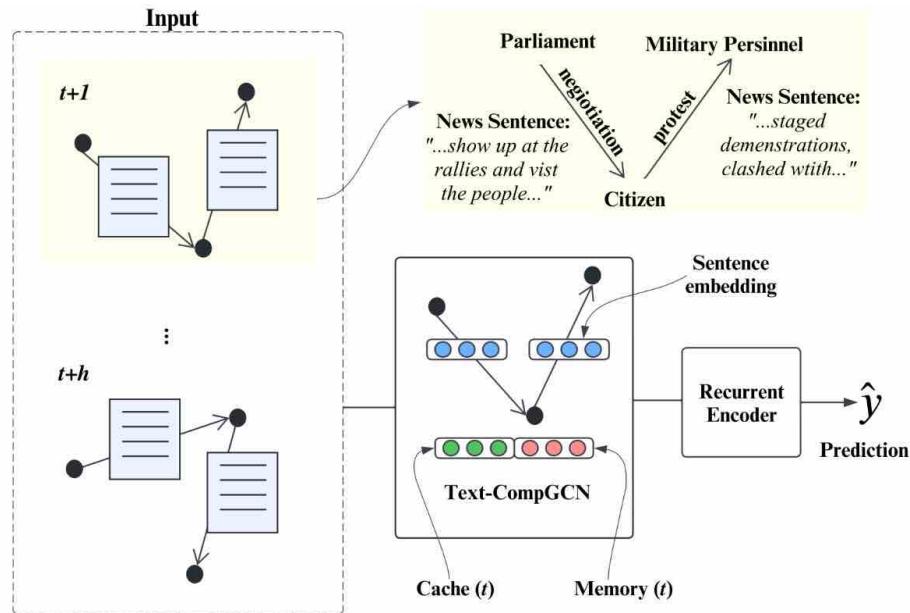
An intuitive example



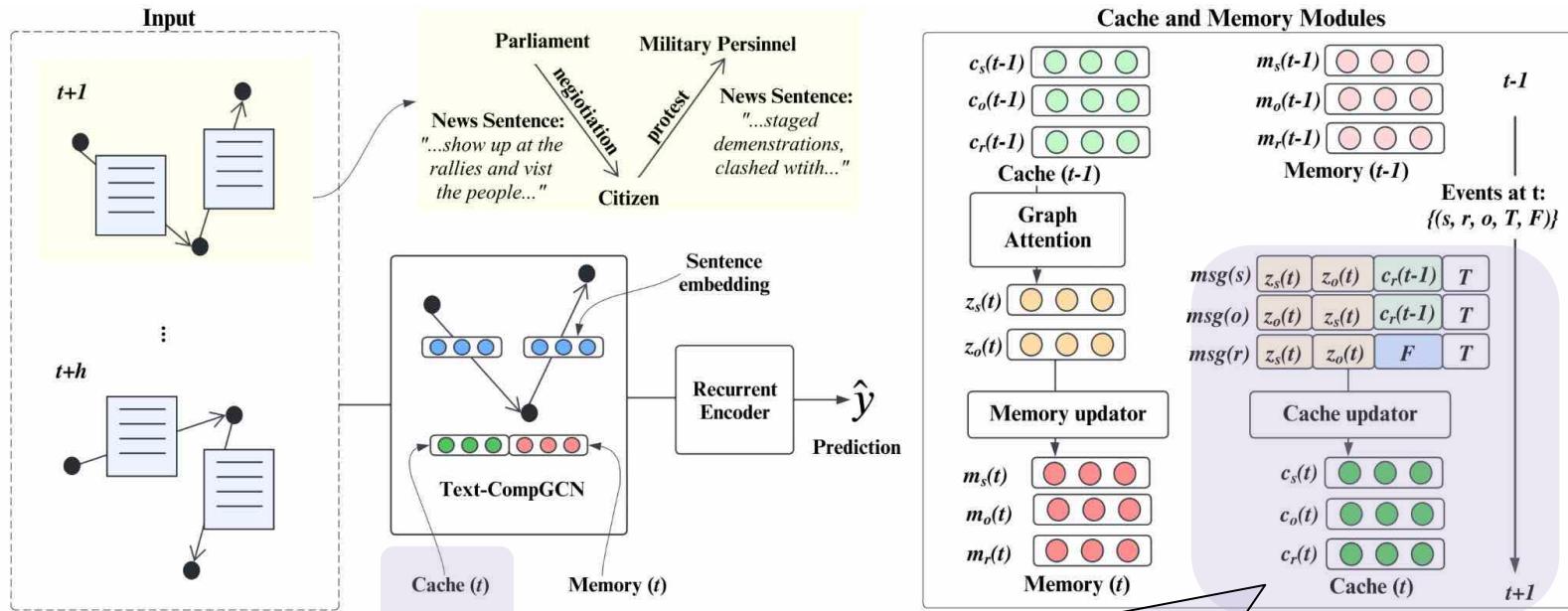
To predict if protests would happen tomorrow in a city, three potential questions:

- **Long-term statistics**: Is this society in a stable status? *Annual statistics can act as prior knowledge for the prediction.*
- **Mid-term tendencies**: Do people tend to protest these days? *Factors can be current economy and unemployment rates, and a look-back period like few months.*
- **Short-term triggers**: Any recent events that may trigger a protest?

Model framework: MTG (Multiple Temporal Granularities)

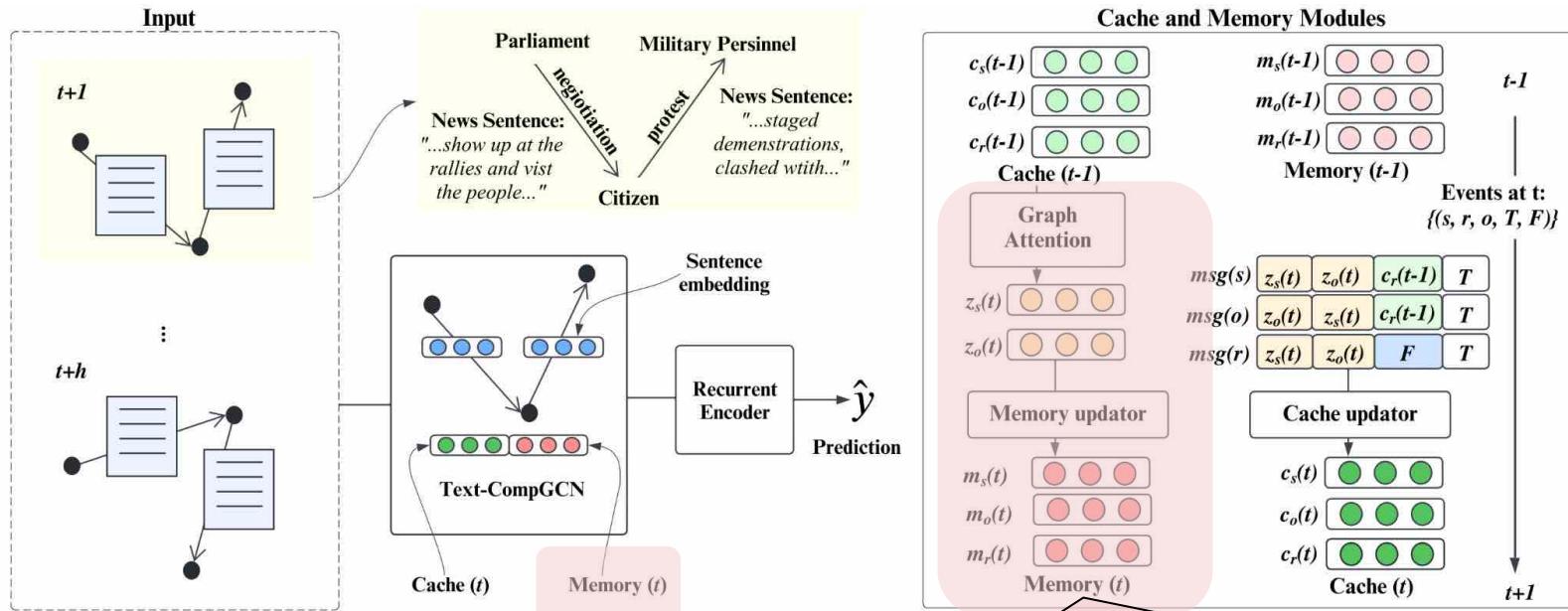


Model framework: MTG (Multiple Temporal Granularities)



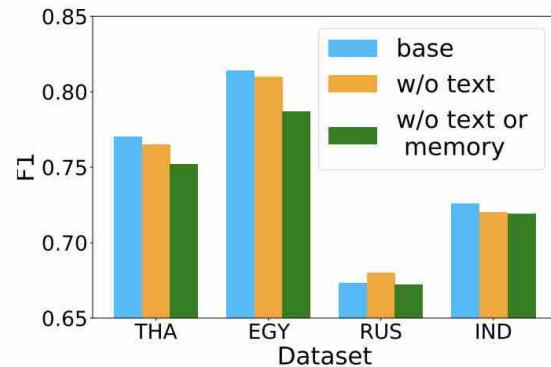
A RNN-based **cache** module models the mid-term tendencies, similar to RNN.

Model framework: MTG (Multiple Temporal Granularities)

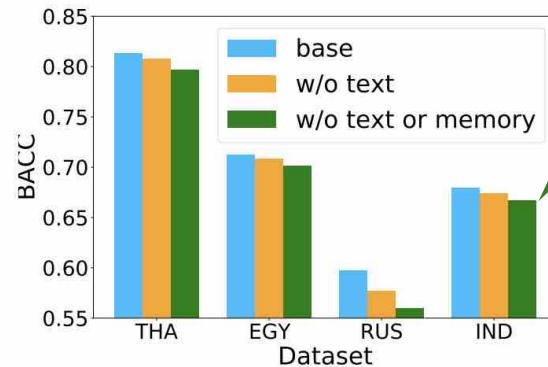


Memory module models the long-term statistics, using a memory matrix.

Impact of the text feature and the memory module



(a) F1



(b) BACC

Long-term
information is
helpful!

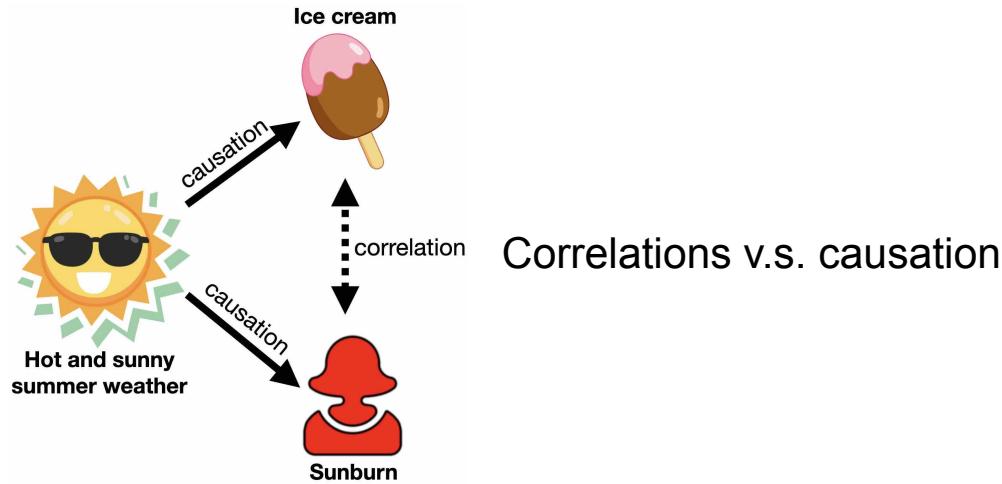
Graph learning with causal reasoning

Two-stage approaches:

- Discover causal information
- Use them to assist in forecasting

Causality

Causality is an influence by which one event contributes to the occurrence of another event.



Causal reasoning is a promising direction for improving prediction accuracy and interpretability in event forecasting.

Robust Event Forecasting with Spatiotemporal Confounder Learning [Deng et al. KDD22]

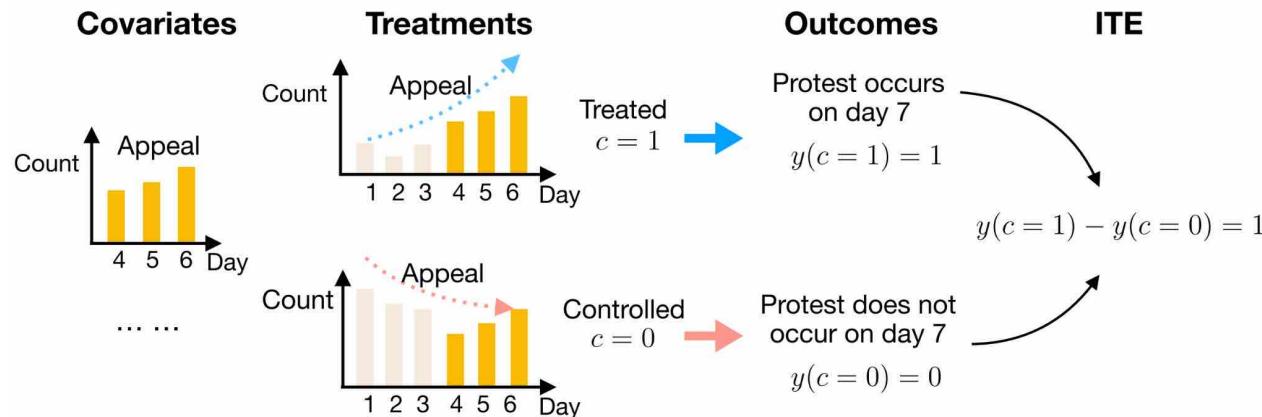
Leverage **estimated event-related causal effects as prior knowledge** for event prediction

Motivation

- Existing event studies focus on correlation analysis.
- **Causal effect learning** has shown advantages in improving predictions in recommender systems, disease diagnosis, and computer vision.
- Studying causal effects of events might contribute to more robust predictions of events (e.g., less susceptible to noise in data).

Problem formulation

- Estimate **individual treatment effects (ITE)** of multiple pre-defined treatment events (e.g., appeal, demand, etc.) on a target event (i.e., protest).

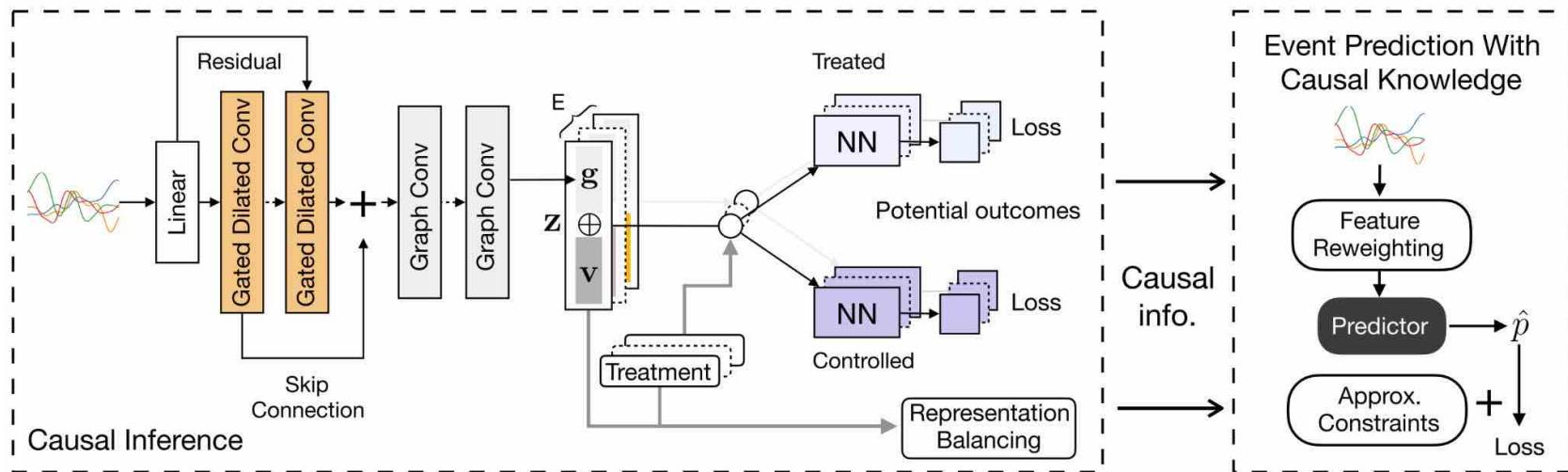


How does increased “Appeal” causally impact “Protest” at a time and location?

- Predict future events with the estimated causal information.

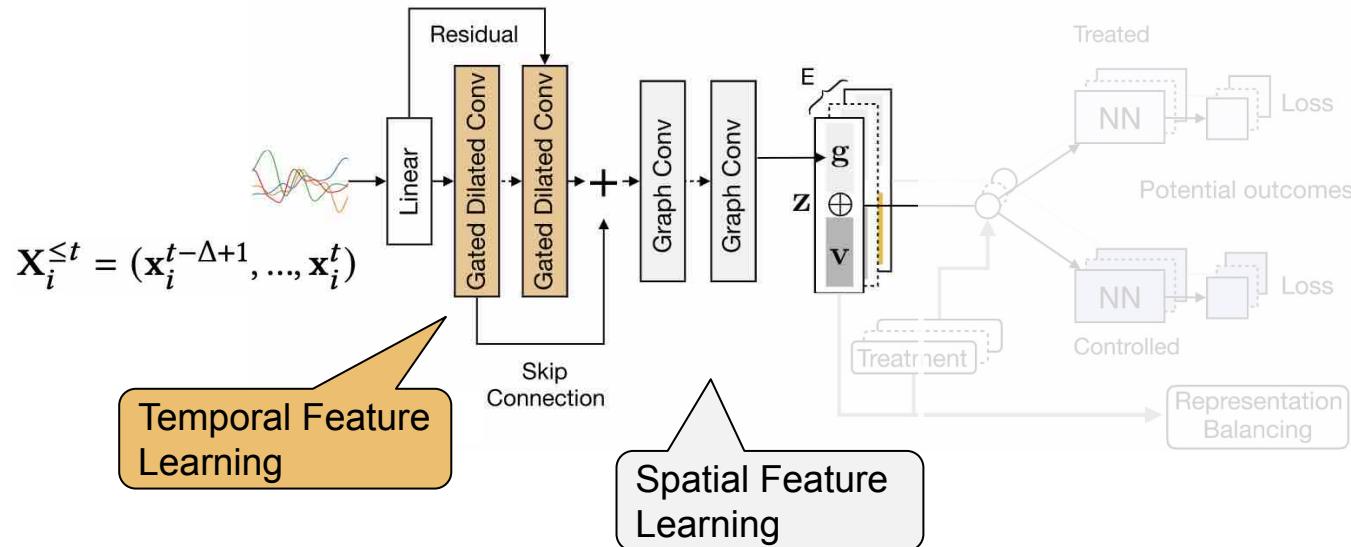
Proposed method

CAPE, which **incorporates causal inference into the prediction of future event occurrences in a spatiotemporal environment.**



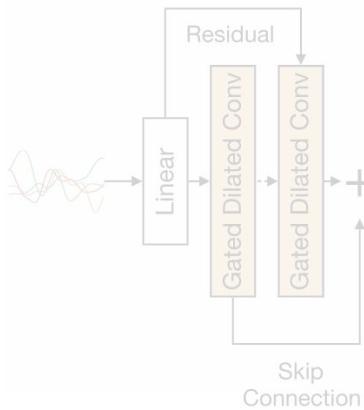
Causal Inference

1. A **spatiotemporal** model learns hidden confounder representations using covariates.



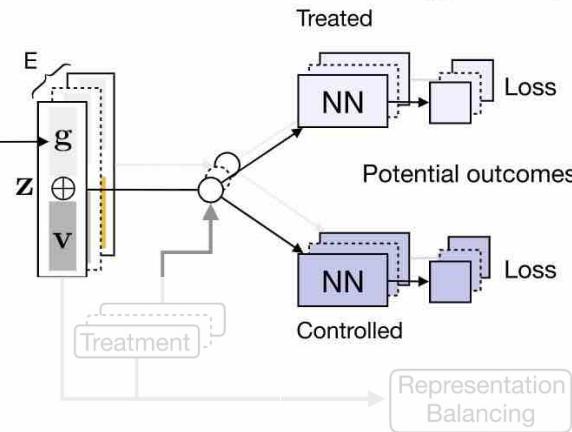
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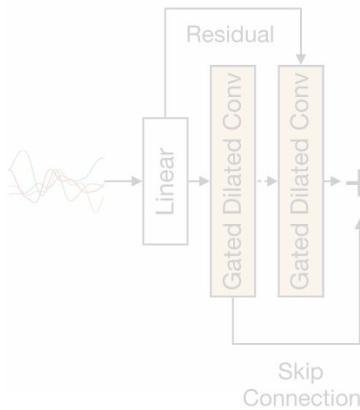
2. A multi-task framework estimates two potential outcomes for each treatment event (j).

$$\hat{y}_{(j)}^{t+\delta}(1) \quad \hat{y}_{(j)}^{t+\delta}(0)$$



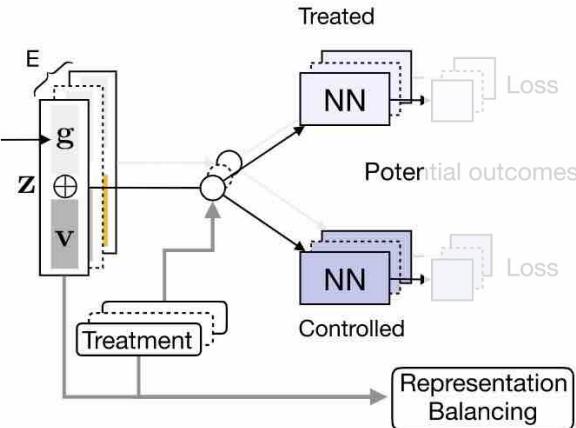
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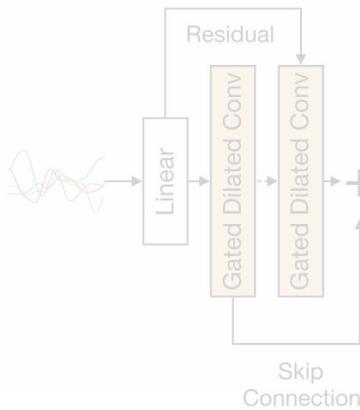
$$\hat{y}_{(j)}^{t+\delta}(1) \quad \hat{y}_{(j)}^{t+\delta}(0)$$



3. Representation balancing **forces** hidden confounders of **treated** and **controlled groups** to be similar. [Johansson, et al. 2016]

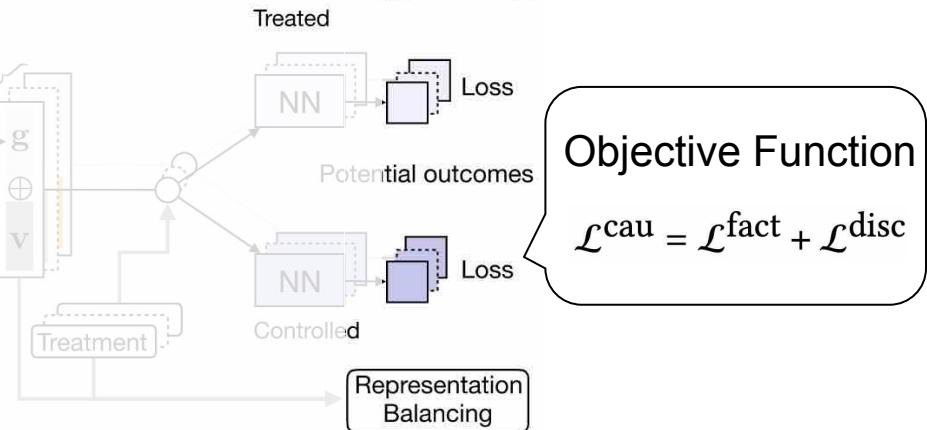
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$$\hat{y}_{(j)}^{t+\delta}(1) \quad \hat{y}_{(j)}^{t+\delta}(0)$$



3. Representation balancing forces hidden confounders of treated and controlled groups to be similar. [Johansson, et al. 2016]

Event Prediction with Causal Knowledge

Feature Reweighting

- Reweighting input features \mathbf{x} using gating variables $\beta^{t+\delta}$ obtained from estimated ITEs which **quantify causal effects**.

$$\tilde{\mathbf{x}}^t = \text{FFN}(\mathbf{x}^t) \odot \beta^{t+\delta} + \mathbf{x}^t$$

Approximation constraints

- A penalty is applied if a prediction exceeds the boundaries defined by estimated causal information

$$\mathcal{L}^{\text{cstr}} = \sum_{t \in T} \sum_{i \in M} \text{ReLU}(l_i^{t+\delta} - \hat{p}_i^{t+\delta}) + \text{ReLU}(\hat{p}_i^{t+\delta} - u_i^{t+\delta})$$

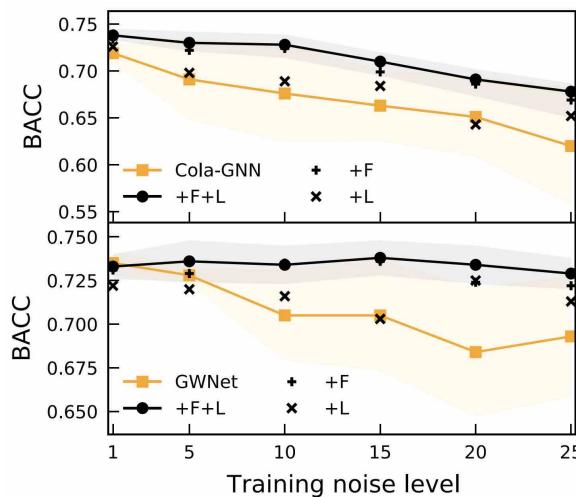
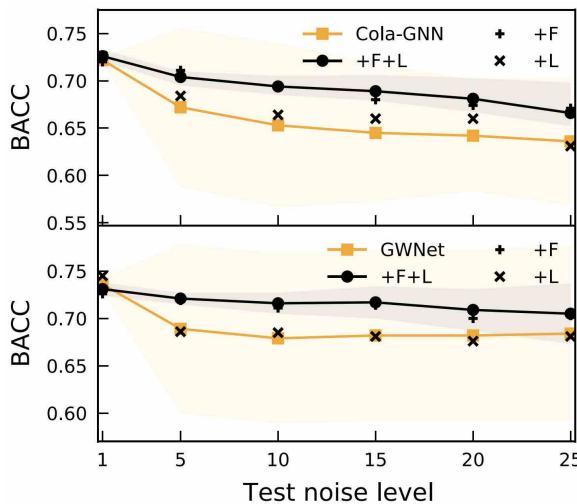
Event prediction

Min of predicted potential outcomes
for all treatment events.

Max of predicted potential
outcomes for all treatment events.

Robustness test in event prediction

Poisson noise is added into the test (left) and training sets (right) while keeping the others noise-free on the India dataset.



Adding both modules (+F+L) leads to a higher average BACC and lower variance.

Causality Enhanced Societal Event Forecasting With Heterogeneous Graph Learning [Deng et al. ICDM22]

Study the **causal factors of societal event** in the form of **topics**, and leverages those topics in dynamic heterogeneous contexts for predicting events.

Motivation

- Knowing the causes of past events can help humans reason about future events.
- Incorporating **causal information into graph learning** can enhance the representation learning of graph nodes by broadcasting causal information.

Preliminaries

Heterogeneous graph

- A directed graph $G \subseteq (\mathcal{V}, \mathcal{E}, \mathcal{A}, \mathcal{R})$ with **multiple types of nodes and edges**.

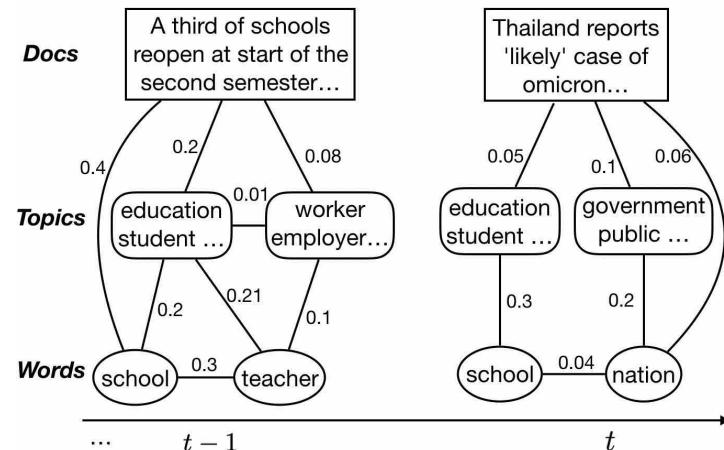
Dynamic Heterogeneous Context Graph

- A type of heterogeneous graph where **edges have timestamps** $G[t] \subseteq (\mathcal{V}, \mathcal{E}, \mathcal{A}, \mathcal{R}, \mathcal{T})$

E.g., a timestamped edge $(e, t) = ((u, v), t)$ denotes the connection of two nodes u and v at time t .

Edge definition:

- word-word: PMI
- word-doc: TF-IDF
- topic-topic: Similarity
- topic-doc: Probability
- topic-word: Probability



An example of the dynamic heterogeneous context graph with three types of nodes: **word**, **topic**, and **docs**.

Preliminaries

Average Treatment Effect (ATE)

- The difference in the mean outcome between the treatment and control groups

Propensity Score Matching (PSM) [Caliendo, et al. 2008]

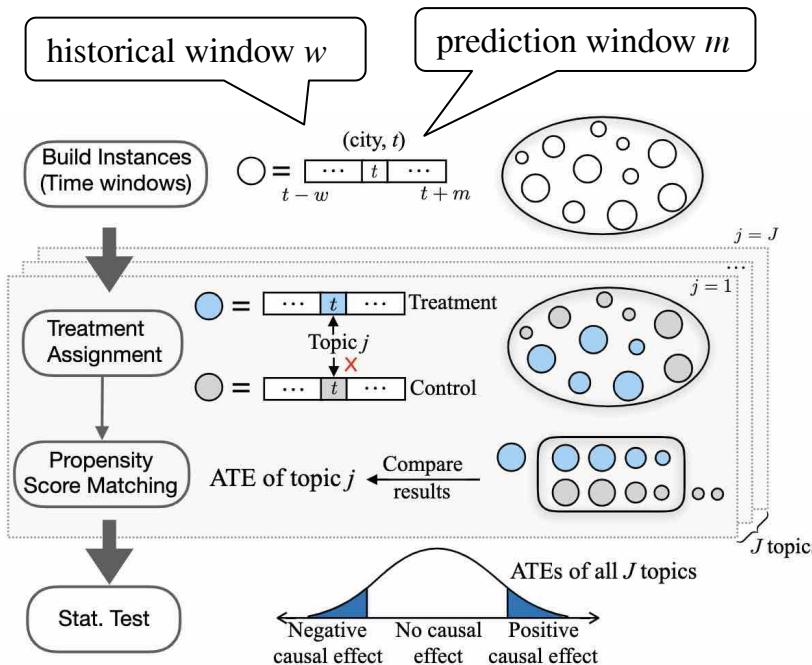
- A statistical matching technique that estimates the ATE.
- Reduce the bias due to confounding variables that could be found in treatment effect estimation.

Problem Statement

- Predict the event by taking a dynamic heterogeneous context graph as input. **Topics** that might cause events (e.g., protest) are discovered and identified in the input graph.

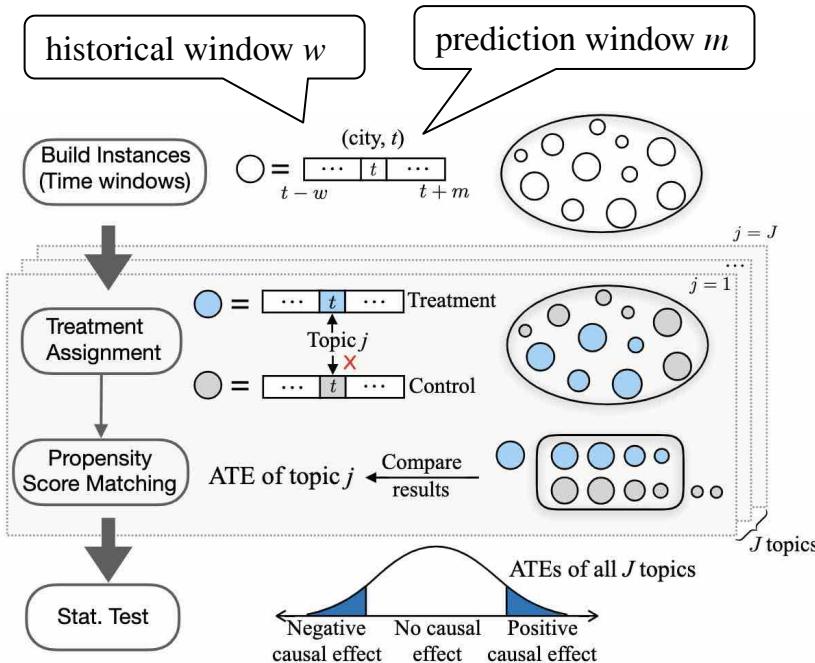
Methodology - Causal analysis

Discovering causal topics

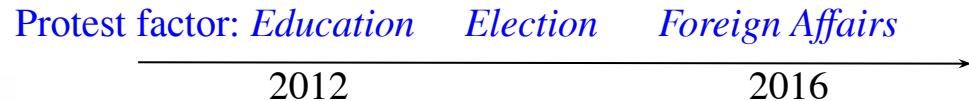


Methodology - Causal analysis

Discovering causal topics

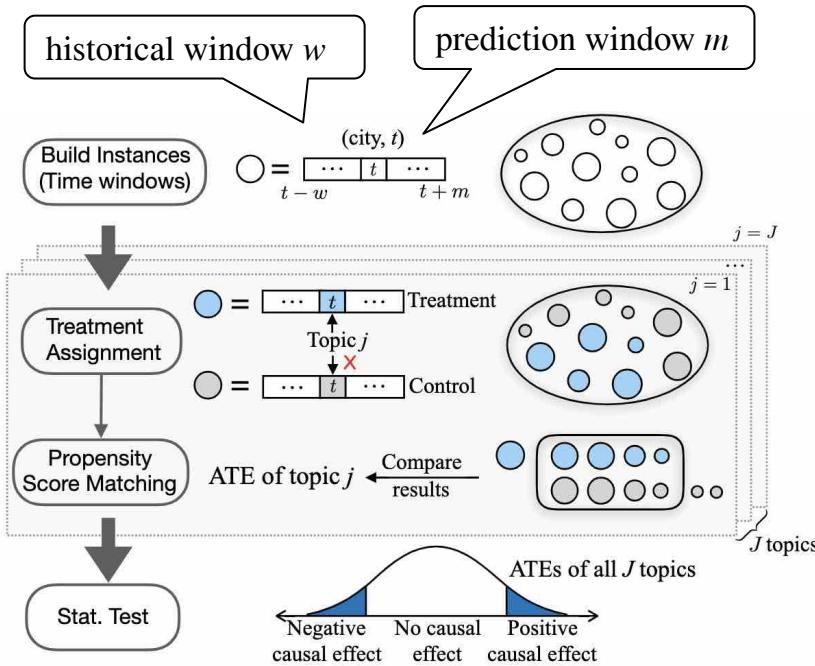


Social environments are changing!
Event factors may change!

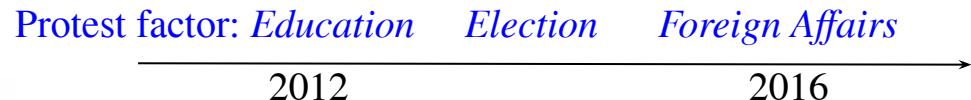


Methodology - Causal analysis

Discovering causal topics



Social environments are changing!
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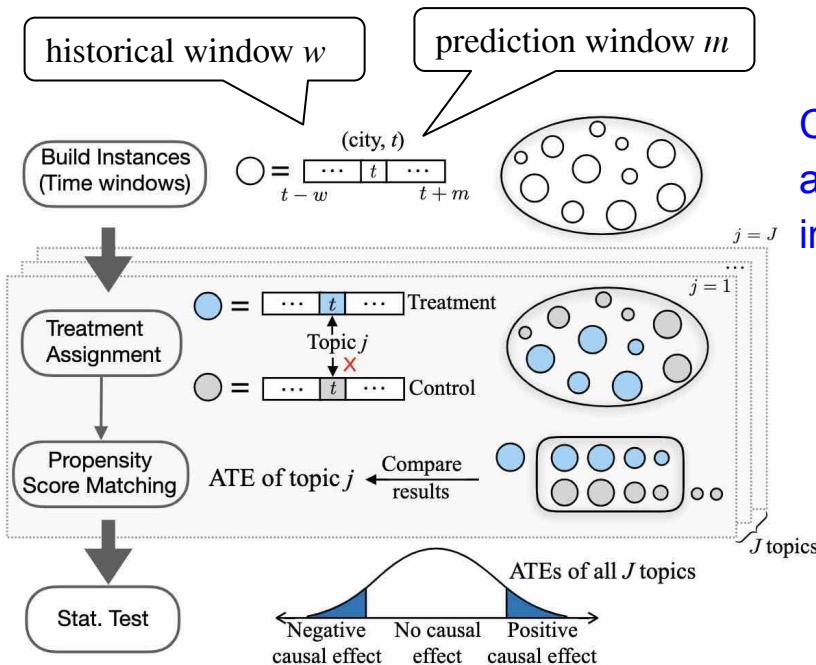


Discovering **evolving and multi-view** causal topics

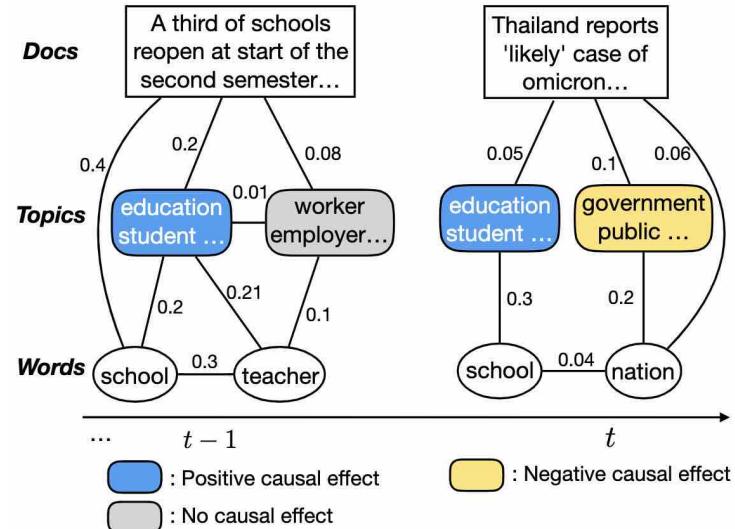
- Obtain **time-sensitive causal topics** for each season (i.e., 3 months) by using time windows in the past.
- Vary the prediction window size m (e.g., 3, 7, and 14) to obtain topics that have **long-term and short-term effects**.

Methodology - Causal analysis

Discovering causal topics

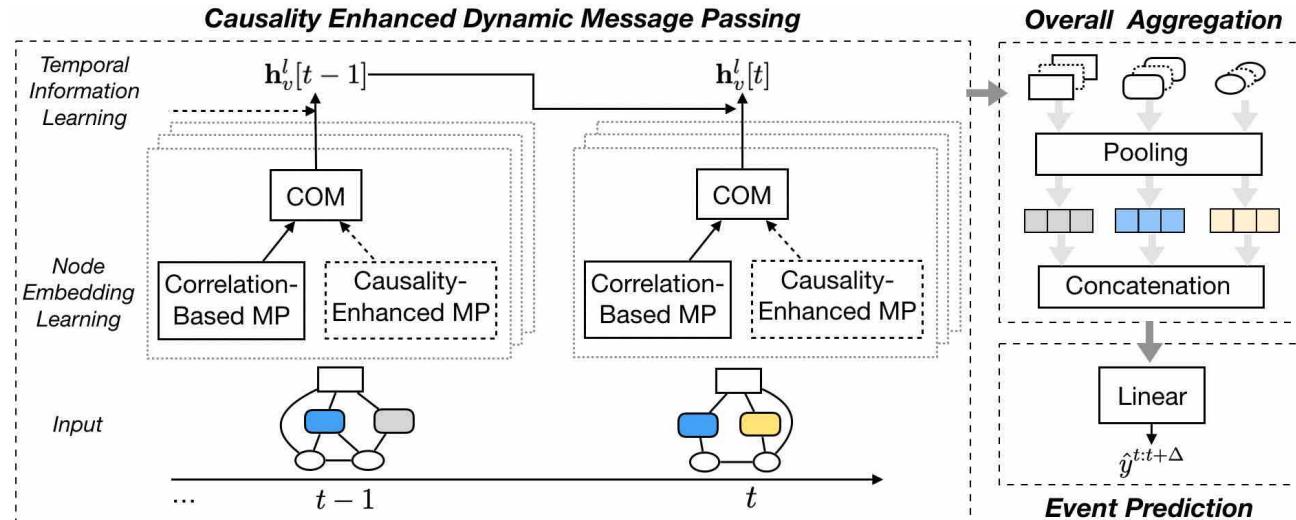


Causal topics
are identified in
input graphs



Methodology - Event prediction

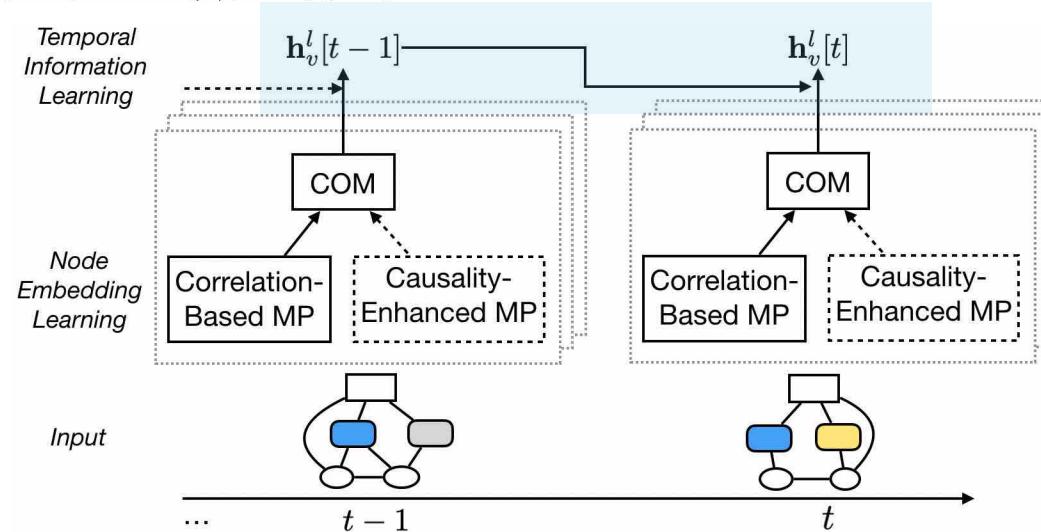
Dynamic heterogeneous graph model with causality enhanced node representations (HGC)



Causality Enhanced Dynamic Message Passing

1. A temporal information learning module (TEM) incorporates node embedding learned in the past graph.

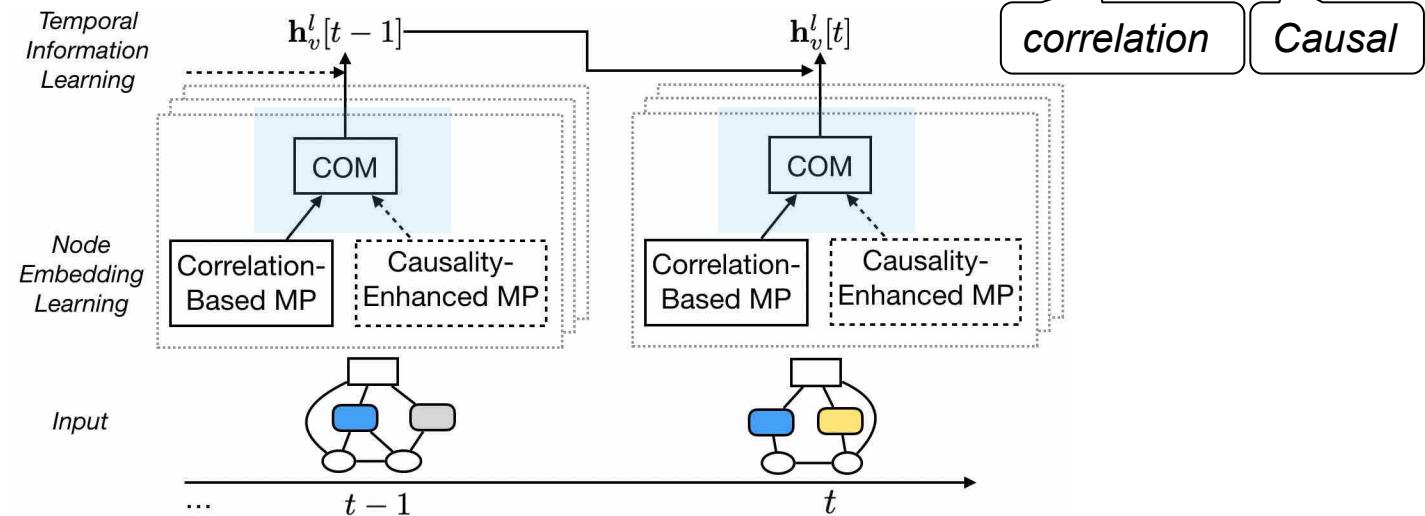
$$\mathbf{h}_v^l[t] = \alpha_{\tau(v)} \cdot \tilde{\mathbf{h}}_v^l[t] + (1 - \alpha_{\tau(v)}) \cdot \mathbf{h}_v^l[< t]$$



Causality Enhanced Dynamic Message Passing

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$$\mathbf{h}_v^l[t] = \alpha_{\tau(v)} \cdot \tilde{\mathbf{h}}_v^l[t] + (1 - \alpha_{\tau(v)}) \cdot \mathbf{h}_v^l[< t]$$



2. A combination module (COM) incorporates causal information.

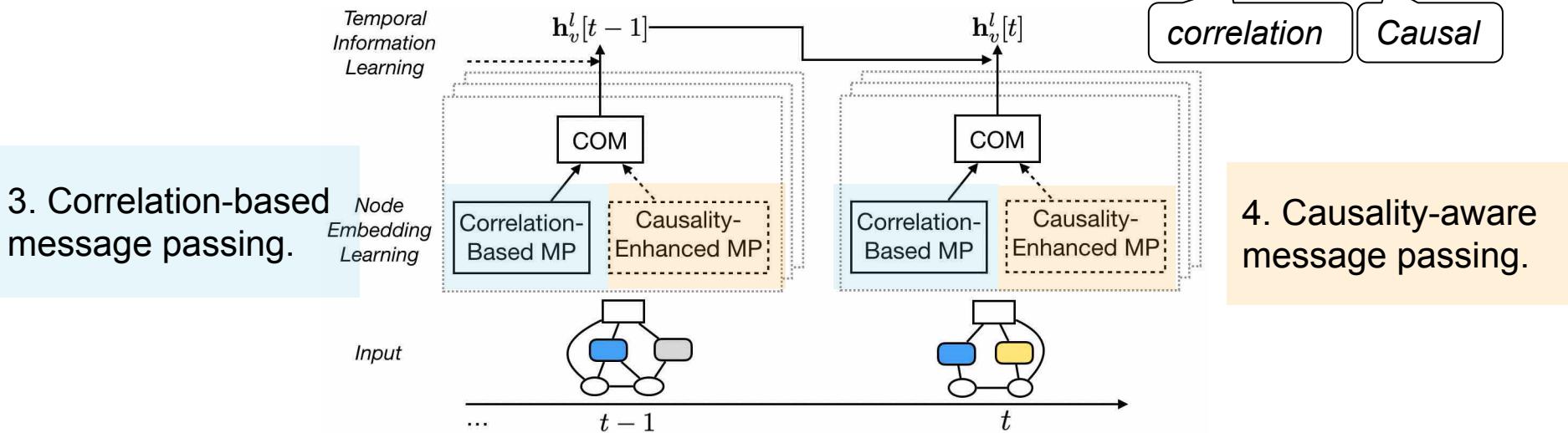
$$\mathbf{h}_v^l[t] = \text{ReLU}(\mathbf{o}_v^l[t] + \mathbf{c}_v^l[t])$$

correlation *Causal*

Causality Enhanced Dynamic Message Passing

1. A temporal information learning module (TEM) incorporates node embedding learned in the past graph.

$$\mathbf{h}_v^l[t] = \alpha_{\tau(v)} \cdot \tilde{\mathbf{h}}_v^l[t] + (1 - \alpha_{\tau(v)}) \cdot \mathbf{h}_v^l[< t]$$



2. A combination module (COM) incorporates causal information.

$$\mathbf{h}_v^l[t] = \text{ReLU}(\mathbf{o}_v^l[t] + \mathbf{c}_v^l[t])$$

correlation **Causal**

4. Causality-aware message passing.

Experimental results of event prediction

	Train ratio	Metric	GAT	EvolveGCN	RGCN	HGT	HGC
THA	60%	F1	0.713±0.038	0.717±0.019	0.754±0.014	0.803±0.03	0.839±0.023
		BACC	0.767±0.029	0.765±0.015	0.795±0.012	0.838±0.024	0.867±0.019
	40%	F1	0.662±0.028	0.628±0.060	0.719±0.013	0.765±0.025	0.796±0.019
		BACC	0.711±0.019	0.698±0.033	0.759±0.007	0.800±0.021	0.826±0.015
AFG	60%	F1	0.512±0.056	0.576±0.043	0.599±0.008	0.650±0.029	0.700±0.013
		BACC	0.641±0.015	0.673±0.025	0.684±0.011	0.721±0.021	0.758±0.010
	40%	F1	0.544±0.071	0.541±0.029	0.610±0.023	0.629±0.028	0.683±0.011
		BACC	0.657±0.036	0.635±0.012	0.686±0.023	0.711±0.019	0.751±0.009

Graph types the
model handles:

Static
homo

Dynamic
homo

Static
homo

Static
hetero

Dynamic
hetero

Causal topic analysis

Qualities of causal topics

	Sig. level	#Pos	#Neg	F1	BACC
THA	99%	2	1	0.839±0.037	0.868±0.031
	95%	4	2	0.847±0.022	0.875±0.020
	90%	5	3	0.829±0.023	0.859±0.020
	80%	8	7	0.834±0.009	0.863±0.007
AFG	99%	3	1	0.700±0.013	0.758±0.010
	95%	4	1	0.688±0.035	0.750±0.027
	90%	5	2	0.694±0.021	0.754±0.017
	80%	7	7	0.660±0.053	0.734±0.034

The average # of topics per sample that has a positive/negative causal effect on future protests.

There is a trade-off between

- involving fewer causal topics with high confidence or
- involving more causal topics that may sacrifice confidence.

Challenges and considerations

GNN-based models can capture intricate interactions and dependencies in complex event data, thereby enhancing prediction accuracy.

Limitations

- The **computational demands** for training GNNs on massive graphs pose scalability challenges, when considering the vast volume of event data.
- **Generalizing to unseen** graphs. Low ability to capture relevant patterns or dependencies in unfamiliar event contexts, such as underrepresented regions with limited training data.

Large language models!



Coffee Break

(15 minutes)

Next: Part 2: Large Language Model (LLM)-based methods

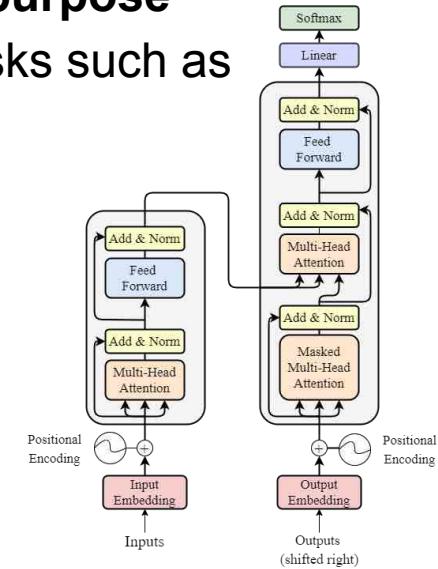
Part 2: Large Language Model (LLM)-based methods

Large language models

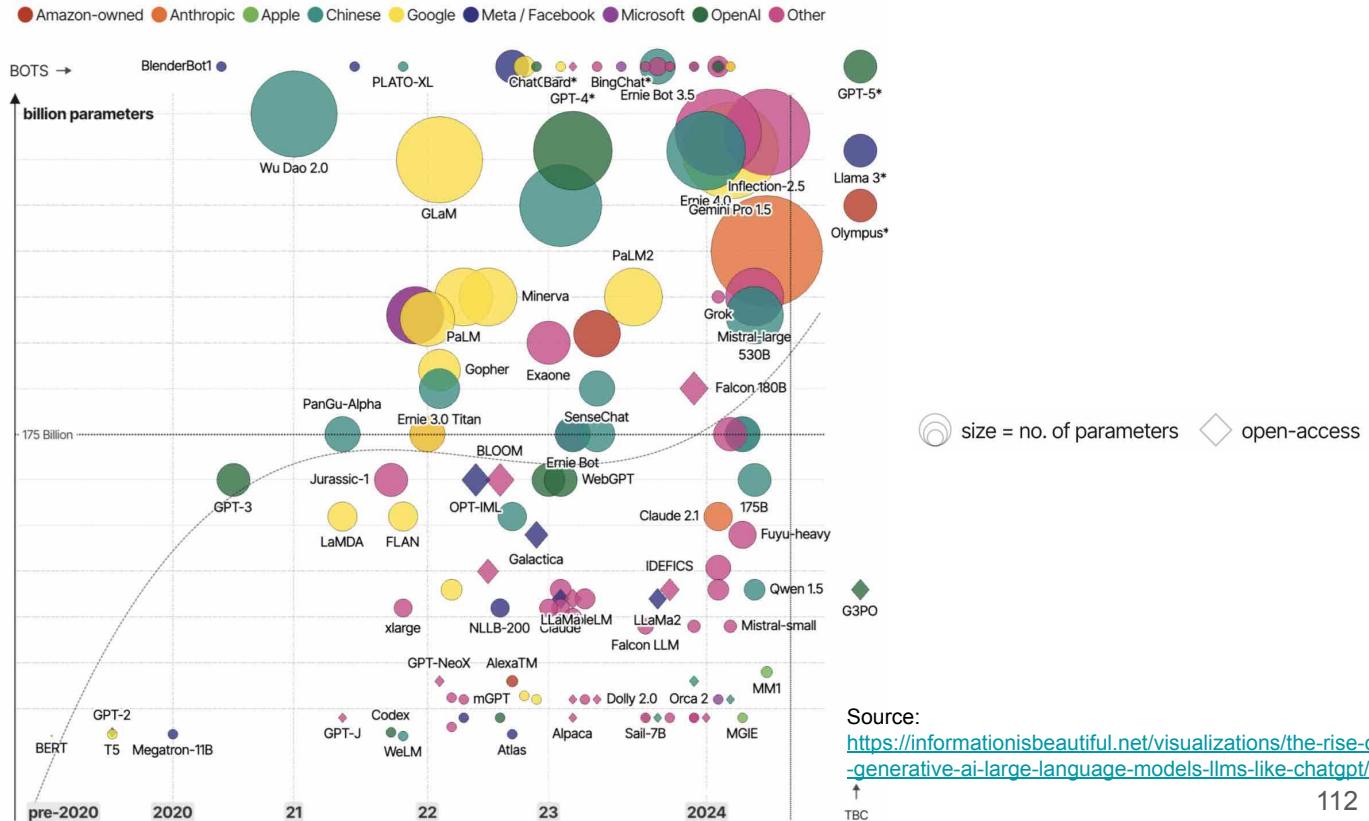
A computational model notable for its ability to achieve **general-purpose language generation** and other natural language processing tasks such as classification.

A brief history

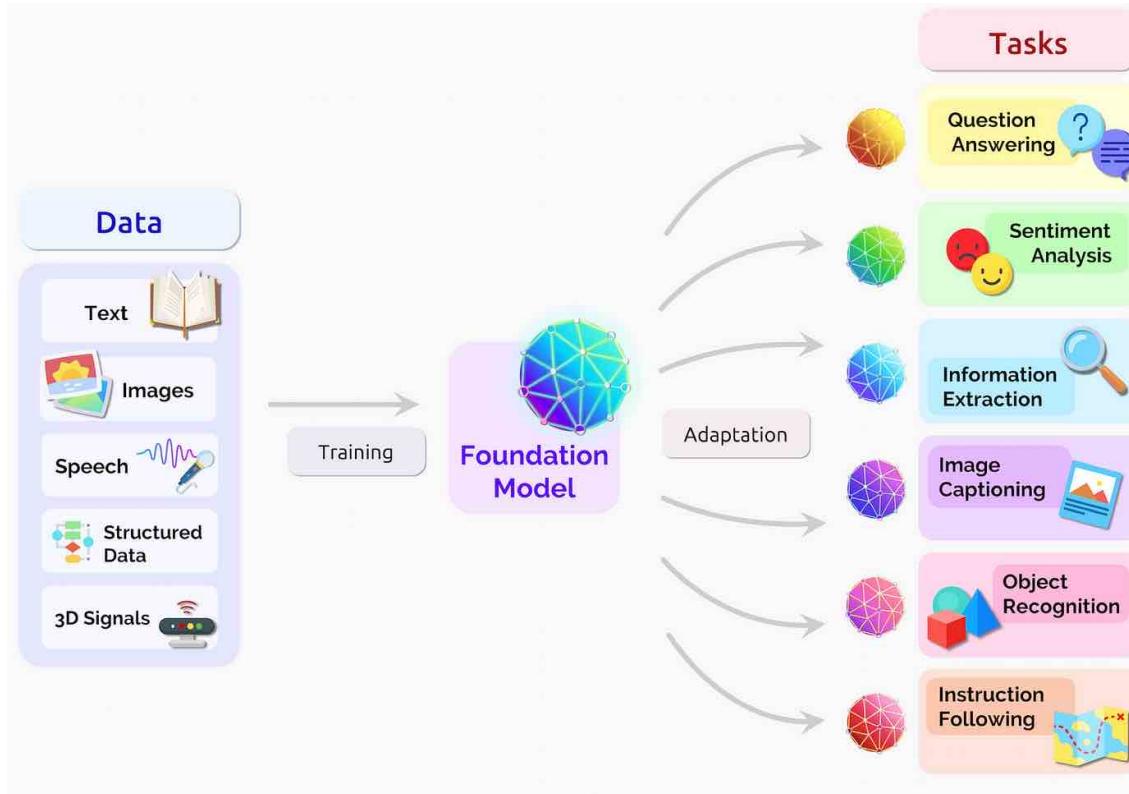
- 2017 Attention Is All You Need
- 2018 BERT was introduced and quickly became "ubiquitous"
- 2018 OpenAI introduced Decoder only GPT-1
- 2019-2022 OpenAI released GPT-2, GPT-3
- Since 2022, source-available models gain popularity, e.g., LLaMA
- 2023, GPT-4 was praised for its increased accuracy and multimodal capabilities
- ...



The rise of large language models (LLMs)



Overview of LLM applications



LLMs for event prediction

Language Models Can Improve Event Prediction by Few-shot Abductive Reasoning [Shi et al. NeurIPS 2024]

Propose the first work that **integrates LLMs into event prediction**.

Motivation

- **Event** data usually comes with **texts**, how to effectively use textual information for event prediction?
- LLMs have shown astonishing performance on various reasoning tasks.
- **Can LLMs reason about real-world events** and help improve the prediction performance of event sequence models.

Event sequence modeling

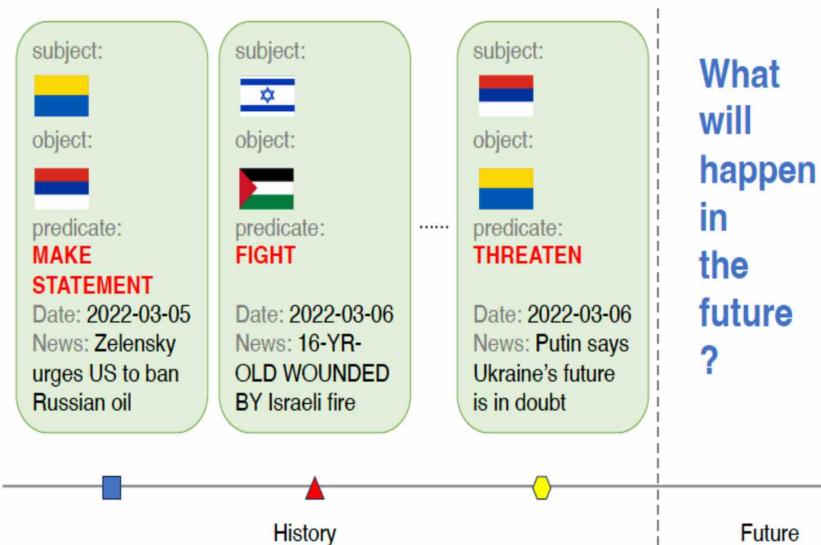
Suppose given an event sequence $(t_1, k_1), (t_2, k_2), \dots$, where $0 < t_1 < t_2 < \dots$ are **times** of occurrence and each $k_i \in \mathcal{K}$ is a discrete **event type**.

Goal: Predict the **next event** for a given history of events.

$$\mathcal{H}_i = (t_1, k_1), \dots, (t_{i-1}, k_{i-1})$$

It consists of two subtasks:

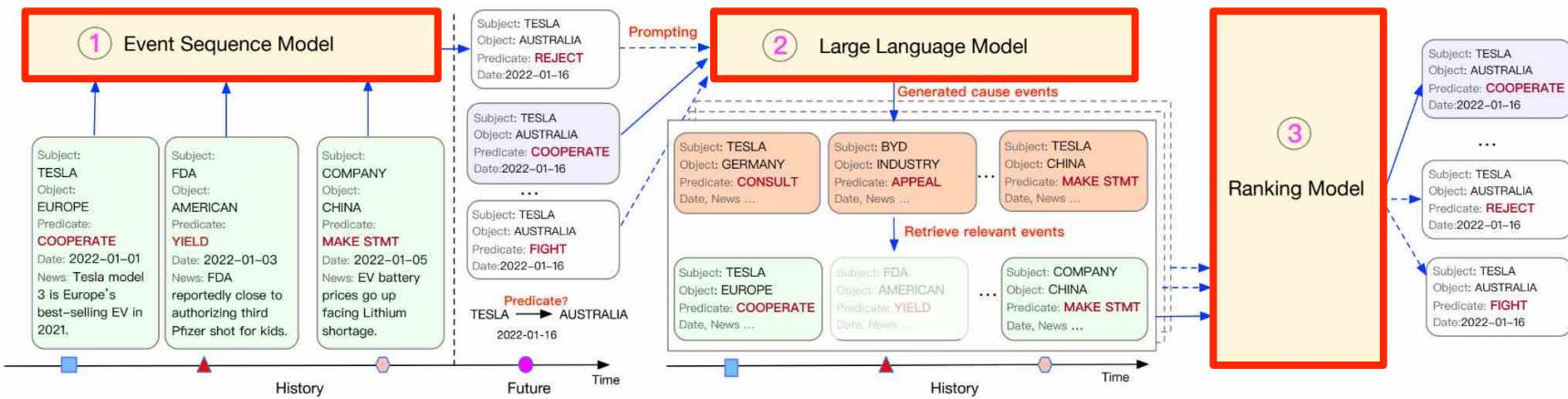
- Predict **time t** of the next event
- Then predict **type k** of the next event



LAMP: Large Language Model in Event Prediction

LAMP has three key components

1. A base event sequence model **proposes candidate predictions**.
2. A large language model **performs abductive reasoning**.
3. A ranking model **learns to scores predictions**.



Phase-I: Proposing Predictions

Propose candidate predictions based on history $\mathcal{H}_i = (t_1, k_1), \dots, (t_{i-1}, k_{i-1})$

Transformer based model
ANHP [Yang et al 2022]

- **Time** prediction
 - Draw L i.i.d. samples from the base model $\hat{t}_i^{(1)}, \dots, \hat{t}_i^{(L)}$
 - Usually, we use the **average** of the samples $\hat{t}_i = \frac{1}{L} \sum_{\ell=1}^L \hat{t}_i^{(\ell)}$
- **Type** prediction given the ground-truth time t_i
 - Find M event types $\hat{k}_i^{(1)}, \dots, \hat{k}_i^{(M)}$ ordered by their **intensity** at the time from the base model.
 - Usually, we select the type with the **highest** intensity.

Base model is imperfect and and we want more informed predictions.

Phase-I: Proposing Predictions

Propose candidate predictions based on history $\mathcal{H}_i = (t_1, k_1), \dots, (t_{i-1}, k_{i-1})$

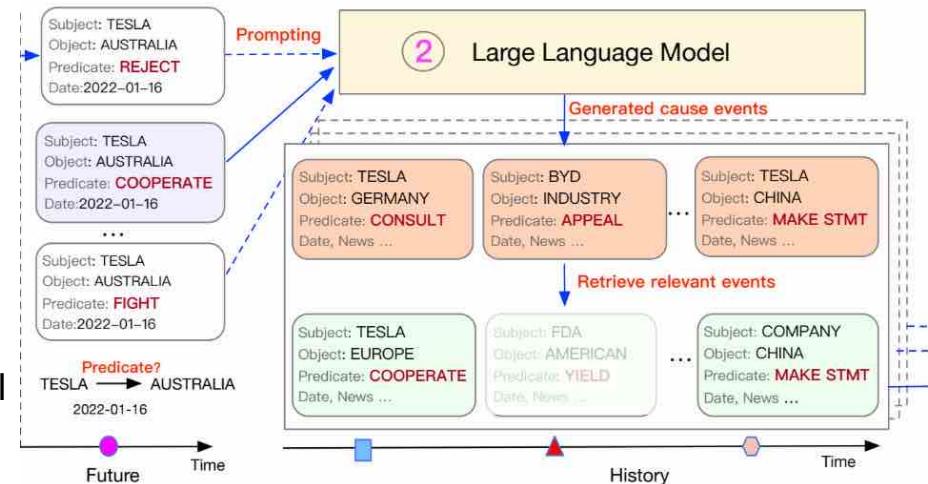
- **Time** prediction
 - Draw L i.i.d. samples from the base model $\hat{t}_i^{(1)}, \dots, \hat{t}_i^{(L)}$
 - Treat all the $L+1$ samples as **candidates**, including the average $\hat{t}_i = \frac{1}{L} \sum_{\ell=1}^L \hat{t}_i^{(\ell)}$
- **Type** prediction given the ground-truth time t_i
 - Find M event types $\hat{k}_i^{(1)}, \dots, \hat{k}_i^{(M)}$ ordered by their **intensity** at the time from the base model.
 - Keep most probable M full events $\{(\hat{t}_i^{(\ell)}, \hat{k}_i^{(\ell, m)})\}_{m=1}^M$ for each time proposal $\hat{t}_i^{(\ell)}$

How to deal with all the (t, k) event candidates?

Phase-II: Prompting LLM to Perform Abductive Reasoning

For each proposed event (t, k) , the framework **selects a set of previous events** from its full history as its supporting evidence $e(t, k)$, using an **LLM** (e.g., GPT-3.5)

- Prompt the LLM to imagine some **possible cause events** that could explain the occurrence of this proposal.
- Search for the most similar ones if not exactly match.
 - Cosine similarity of embeddings of actual and cause events.
(subject-predicate-object, time, text)



Prompt formats

Explain the task,
concepts, examples
and post the query.

I want you to do the reasoning over social events. I give you an effect event and you give me four or five cause events. An effect event is an event that happens. A cause event is believed to be one of the causes that have triggered the effect event to happen. Each event consists of a time, a type (that includes subject, predicate, object), and a news headline describing the event.

The predicates are restricted to the 20 options below.

1. MAKE STATEMENT

: // Full list are in Appendix E.4.

20. ENGAGE IN MASS VIOLENCE

Now I give you 10 examples. In each example, the first event is the effect and the next several events are the causes that happened earlier.

: // Examples are in Listing 2.

Now please generate possible causes for

effect

predicate: CONSULT

time: 2022-07-05

subject: CHINA PM

object: YELLEN

Listing 1: Format of our LLM prompt.

Prompt formats

Here, each example includes 1 **effect** and 5 **cause events**.

I want you to do the reasoning over social events. I give you an effect event and you give me four or five cause events. An effect event is an event that happens. A cause event is believed to be one of the causes that have triggered the effect event to happen. Each event consists of a time, a type (that includes subject, predicate, object), and a news headline describing the event.

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predicate: CONSULT

time: 2022-07-05

subject: CHINA PM

object: YELLEN

Listing 1: Format of our LLM prompt.

Example 1

effect
predicate: APPEAL
time: 2022-04-23
subject: GERMANY
object: GREEN PROJECT

reasoning:

cause event 1
predicate: REDUCE RELATIONS
time: 2022-04-21
subject: EUROPE
object: RUSSIA
headline: Europe determined to ban Russian energy exports.

cause event 2

predicate: DISAPPROVE
time: 2022-03-16
subject: EUROPE
object: RUSSIAN
headline: Europe can endure painful transition to live without Russian oil.

: // Other causes are in Appendix E.4.

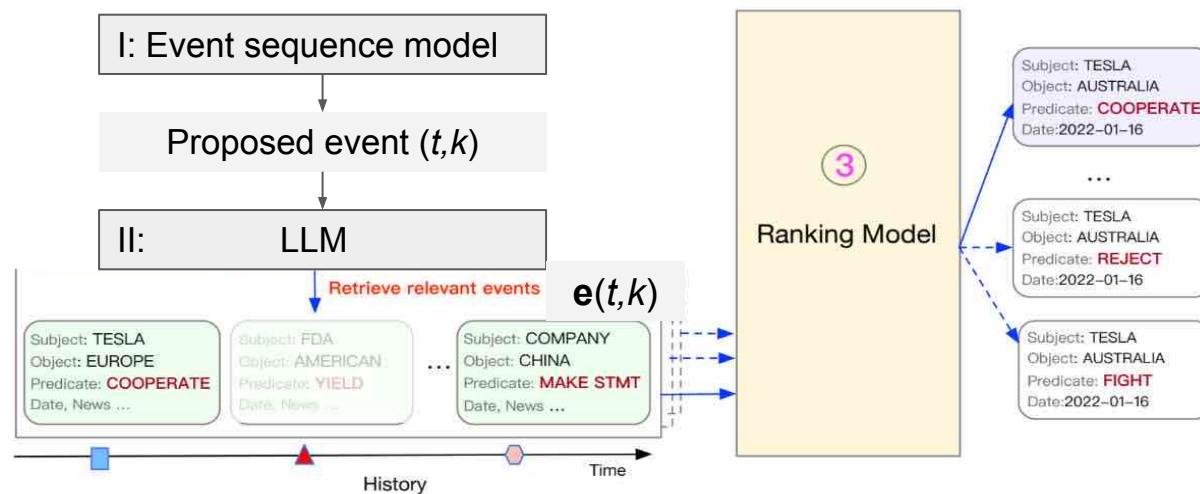
Example 2

: // Other examples in Appendix E.4.

Listing 2: Few-shot examples in our prompt. 122

Phase-III: Ranking Proposals

Score each proposed event (t, k) based on the compatibility with its retrieved evidence $e(t, k)$.



Phase-III: Ranking Proposals

Score each proposed event (t, k) based on the compatibility with its retrieved evidence $\mathbf{e}(t, k)$.

- Calculate the score of each proposed event (t, k)

$$s_{\text{event}}(t, k) \stackrel{\text{def}}{=} \exp(c((t, k), \mathbf{e}(t, k)))$$

A **high** score means the proposal is **strongly supported** by its retrieved evidence; more likely to happen at time t .

- Measure the overall belief for candidate time t , given the most probable M events at time t $\{(t, k^{(m)})\}_{m=1}^M$

$$s_{\text{time}}(t) \stackrel{\text{def}}{=} \sum_{m=1}^M s_{\text{event}}(t, k^{(m)})$$

Time prediction: time with highest $s_{\text{time}}(\hat{t}^{(\ell)})$

Type prediction: type with highest $s_{\text{event}}(t, \hat{k}^{(m)})$

Model architecture and training

Model architecture

- Function c has a continuous-time Transformer architecture [Yang et al. ICLR 2022].
 - Its attention mechanism learns to disregard irrelevant retrieved events.
 - its sophisticated handling of time may be helpful (e.g., recent evidence events matters more than ancient events)

Training

- Train the ranking model by maximizing the objective

$$J \stackrel{\text{def}}{=} J_{\text{actual}} + \beta J_{\text{no}}$$

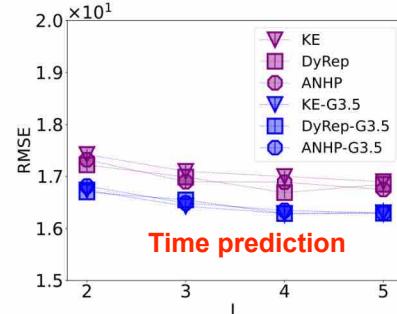
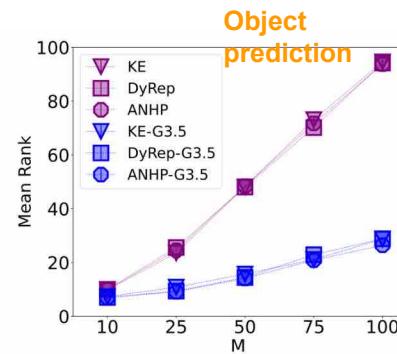
Scores of the events that have actually happened.

Negative scores of the non-events at sampled times.

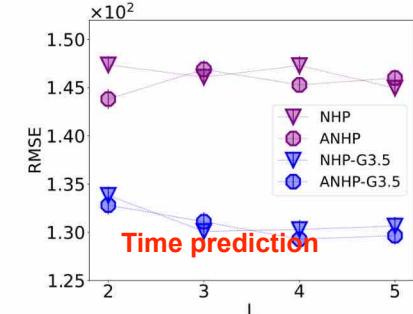
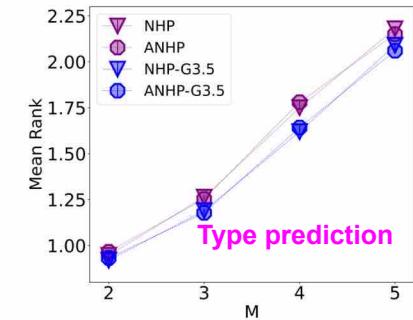
Experiments on real-world datasets

Mean Rank (MR) ↓: average rank of the ground-truth type/object in the list.

RMSE ↓: how close top-ranked time prediction is to the ground-truth time.



(b) ICEWS.

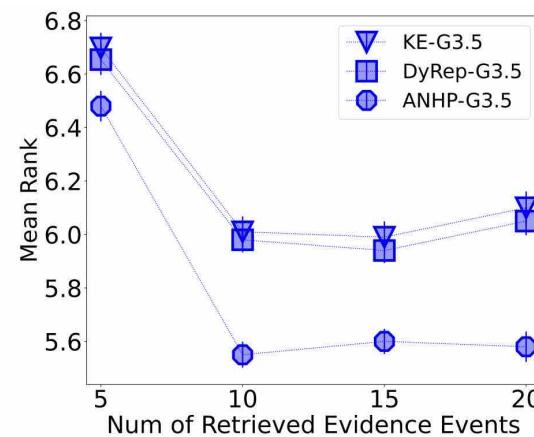
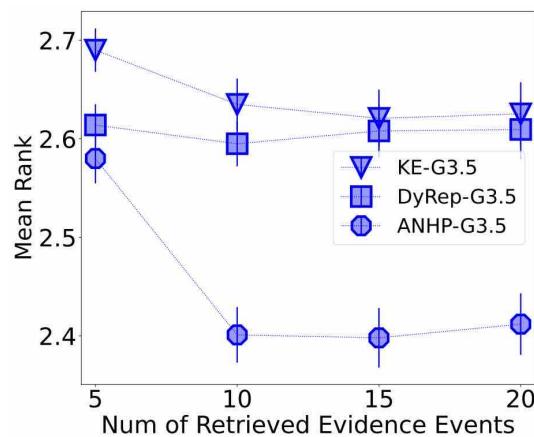


(c) Amazon Review.

How many evidence events do we need?

Evidence events are generated by LLM at Phase II.

Effect of the number of evidence events on predicate (left) and object (right) prediction on GDELT.

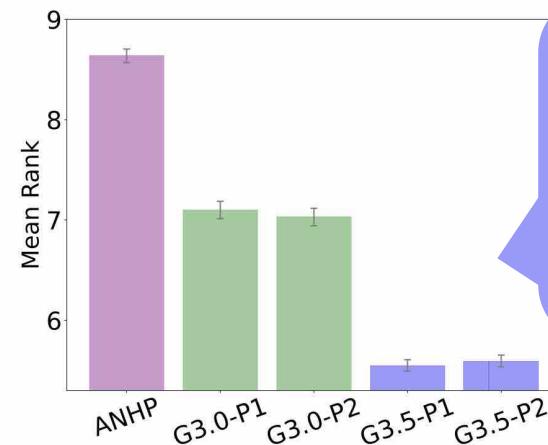
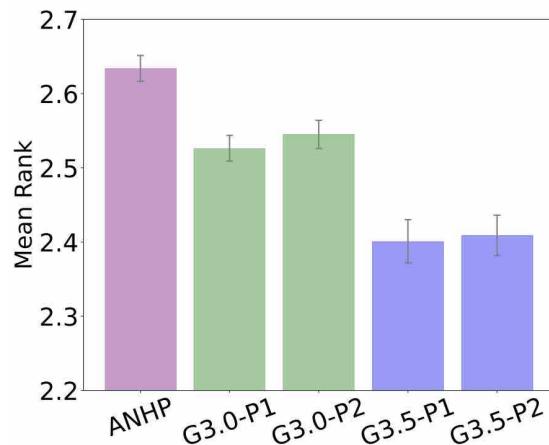


Retrieve too
many
“evidences”
event might not
be helpful.

Prompt design – choice of demonstrations

P1: the set of demonstrations used throughout the main experiments.

P2: randomly replace half of the demonstrations in P1.



Different demonstrations only have a slight effect on performance.
(Results are on GDELT)

Does the GPT already have the ability to do reasoning?

About data leakage

GPT models are trained on online text data up to 2021.

For GDELT or ICEWS, the data used in experiments are from 2022.

For Amazon review, the data are from 2014 to 2016. To verify data leakage, a conversation was made with GPT-3.5

input: We are using Amazon Review Data, published by Jianmo Ni, et al., 2018, which is firstly used in the paper "Justifying recommendations using distantly-labeled reviews and fined-grained aspects", EMNLP 2019.

The dataset includes millions of reviews (ratings, text, helpfulness votes), product metadata (descriptions, category information, price, brand, and image features) in the range May 1996 – Oct 2018. Do you remember any of the review information if I give you a review id?

GPT-3.5 output: As an AI language model, I am not capable of remembering any review information given a review ID.
I can search ...

input: can you recall any information with reviewer ID A28GK1G2KDXHRP on date 04/17, 2014.

GPT-3.5 output: I apologize, but the Amazon Review dataset does not include information about the specific date when a review was posted. It only includes the year and month when the review was posted. Therefore, I cannot provide you with any information about reviews ...

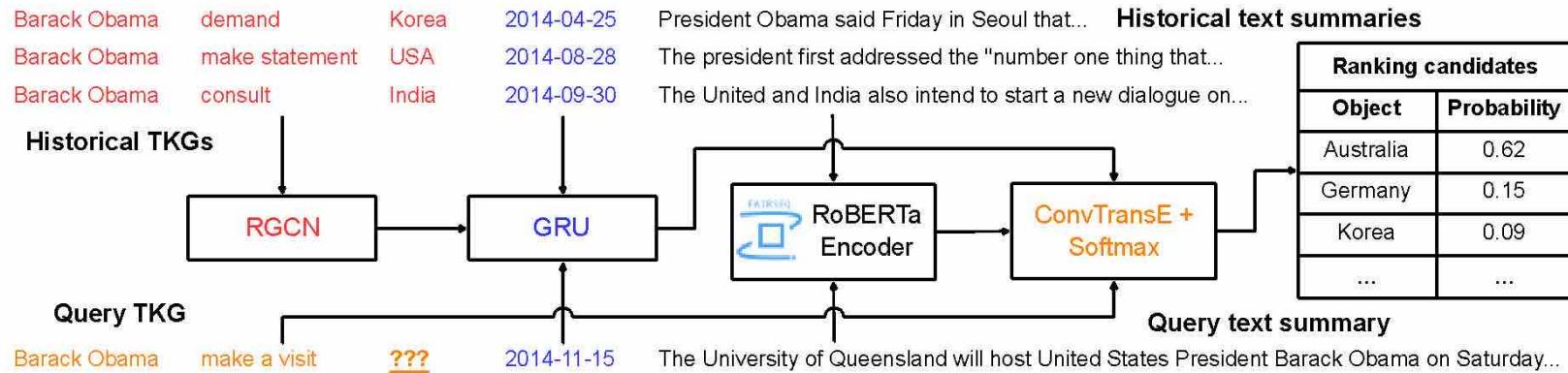
Large Language Models as Event Forecasters [Zhang et al. 2024]

- Existing challenges and motivations for leveraging LLMs
 - Large language models as event forecasters (LEAF)
- LEAF: LLMs for object prediction
 - Object prediction as a ranking task
 - Object prediction as a generative task
- LEAF: LLMs for multi-event forecasting
 - Quintuple-level prompt encoding and multi-label binary classification

Challenges and motivations

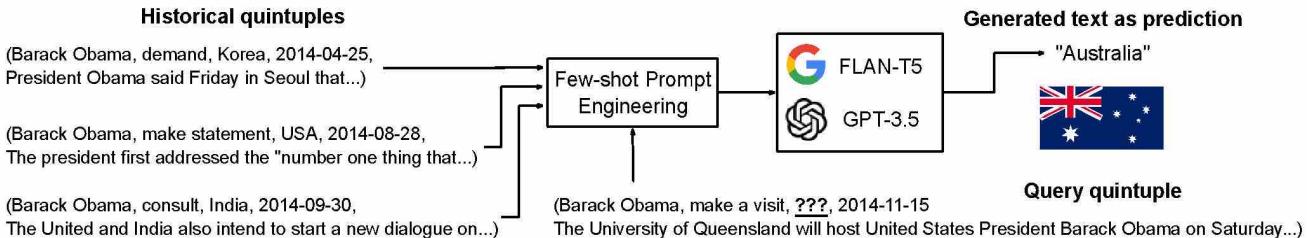
- Underestimation of individual TKG quintuple contextualization
 - Contextual meaning of each short phrase
- Unfamiliar domain-specific knowledge for closed-source LLMs
 - Trade-off between detailed prompt engineering and token-related pricing
- Limited maximum input context length for open-source LLMs
 - Misaligned goals between prediction accuracy and instruction fine-tuning

Object prediction as a ranking task



- Encoder-only LLM: RoBERTa
- The RoBERTa encoder is separately fine-tuned with masked language modeling loss by simply concatenating text summaries from all TKG quintuples
- Only RGCN, GRU, and ConvTransE are involved during ranking optimization

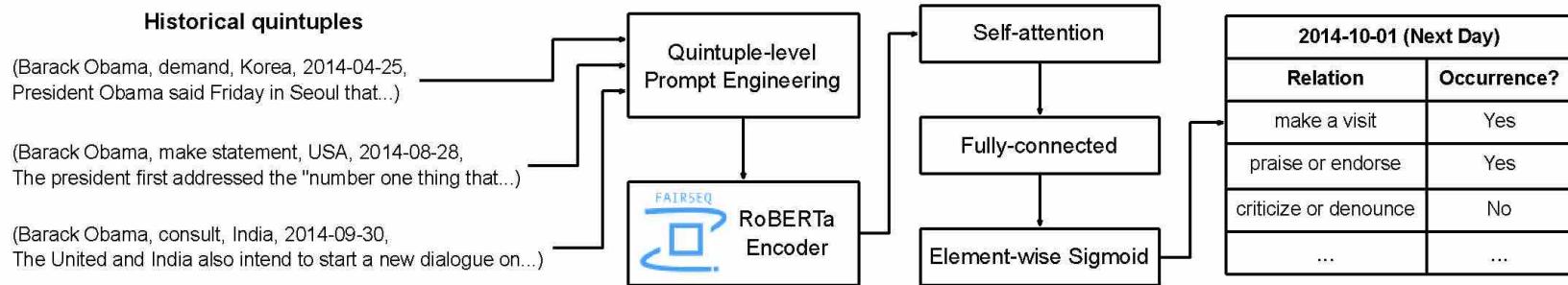
Object prediction as a generative task



- Encoder-decoder LLM: FLAN-T5, or
- Decoder-only generative LLM: GPT-3.5
- A standard question-answering task
- The question is formulated as a prompt, with in-context learning examples and the query to be completed
- The answer is the ground-truth object
- Feed text in, and get text out

Name	Prompt Template
Original	I ask you to perform an object prediction task after I provide you with five examples. Each example is a knowledge quintuple containing two entities, a relation, a timestamp, and a brief text summary. Each knowledge quintuple is strictly formatted as (subject entity, relation, object entity, timestamp, text summary). For the object prediction task, you should predict the missing object entity based on the other four available elements. Now I give you five examples. ## Example 1 (<code>SUBJECT 1</code> , <code>RELATION 1</code> , <code>MISSING OBJECT ENTITY</code> , <code>TIMESTAMP 1</code> , <code>TEXT SUMMARY 1</code>) \nThe <code>MISSING OBJECT ENTITY</code> is: <code>OBJECT 1</code> \n : ## Example 5 (<code>SUBJECT 5</code> , <code>RELATION 5</code> , <code>MISSING OBJECT ENTITY</code> , <code>TIMESTAMP 5</code> , <code>TEXT SUMMARY 5</code>) \nThe <code>MISSING OBJECT ENTITY</code> is: <code>OBJECT 5</code> \n Now I give you a query: (<code>SUBJECT 6</code> , <code>RELATION 6</code> , <code>MISSING OBJECT ENTITY</code> , <code>TIMESTAMP 6</code> , <code>TEXT SUMMARY 6</code>) \nPlease predict the missing object entity. You are allowed to predict new object entity which you have never seen in examples. The correct object entity is:
Zero-shot	Remove all five in-context learning examples in the original prompt.
No-text	Remove all text summaries of five in-context learning examples and the query in the original prompt.

LLMs for multi-event forecasting



- Encoder-only LLM: RoBERTa
- Each historical quintuple is formulated as a prompt for RoBERTa encoding
- Self-attention mechanism is applied to weigh the significance differences among different quintuples within one historical day
- The dimension tracing back to multiple days is collapsed through aggregation
- Each relation's occurrence potential is evaluated through element-wise Sigmoid activation

Experiments: object prediction, ranking

Table 2: Model architectures for object prediction

Model	GNN	RNN	Decoder	How to handle text?
ConvTransE (Shang et al. 2019)	N/A	N/A	ConvTransE × 1	N/A
SeCoGD, LDA, 5 (Ma et al. 2023)	RGCN × 5	GRU × 5	ConvTransE × 5	Context clusters
Baseline w/o LLM	RGCN × 1	GRU × 1	ConvTransE × 1	N/A
LEAF-OP (ours)	RGCN × 1	GRU × 1	ConvTransE × 1	Query embeddings

Table 3: Object prediction results as a ranking task on the ICEWS dataset

Model	Afghanistan			India			Russia		
	1	3	10	1	3	10	1	3	10
Historical sequence length = 3 (back to 3 days), fine-tuned RoBERTa-base as an encoder-only LLM									
Baseline w/o LLM	0.1538	0.3137	0.5408	0.1704	0.3125	0.4952	0.1332	0.2345	0.3767
SeCoGD, LDA, 5	0.1878	0.3570	0.5740	0.2064	0.3554	0.5357	0.1768	0.2909	0.4351
ConvTransE	0.1235	0.2704	0.4916	0.1521	0.2821	0.4600	0.1009	0.1791	0.3078
LEAF-OP (ours)	<u>0.3691</u>	<u>0.5630</u>	<u>0.7317</u>	<u>0.3675</u>	<u>0.5507</u>	<u>0.7233</u>	<u>0.3751</u>	<u>0.5390</u>	<u>0.6831</u>
Historical sequence length = 7 (back to 7 days), fine-tuned RoBERTa-base as an encoder-only LLM									
Baseline w/o LLM	0.1551	0.3298	0.5544	0.1724	0.3175	0.5004	0.1335	0.2349	0.3781
SeCoGD, LDA, 5	0.1833	0.3652	0.5862	0.2056	0.3516	0.5352	0.1661	0.2823	0.4433
ConvTransE	0.1243	0.2759	0.4909	0.1544	0.2911	0.4740	0.0973	0.1804	0.2971
LEAF-OP (ours)	0.3861	0.5884	0.7664	0.3935	0.5831	0.7454	0.3861	0.5590	0.7077

- Evaluation metrics: Hits @ 1, 3, and 10
- Incorporating more historical knowledge enhances the prediction performance, but is inefficient in terms of memory and time

Experiments: object prediction, generative

Table 6: Object prediction results as a generative task (for the first 5000 test samples)

ICEWS dataset	Afghanistan			India			Russia		
	1	2	L	1	2	L	1	2	L
Metric: ROUGE—									
Historical sequence length = 3 (back to 3 days), fine-tuned RoBERTa-base as an encoder-only LLM									
SeCoGD, LDA, 5	0.4137	0.1676	0.4134	0.4916	0.2957	0.4918	0.3326	0.1189	0.3331
LEAF-OP (ours)	0.5320	0.2848	0.5322	0.5709	0.3888	0.5709	0.4671	0.2455	0.4674
Historical sequence length = 7 (back to 7 days), fine-tuned RoBERTa-base as an encoder-only LLM									
SeCoGD, LDA, 5	0.4222	0.1770	0.4221	0.5016	0.2977	0.5022	0.3385	0.1175	0.3385
LEAF-OP (ours)	0.5732	0.3502	0.5728	0.6167	0.4251	0.6168	0.5024	0.2554	0.5015
Prompt engineering: back to 5 samples or no sample, fine-tuned FLAN-T5-base as a generative LLM									
Original prompt (ours)	0.8789	0.5887	0.8786	0.8666	0.7191	0.8670	0.8154	0.4942	0.8150
Zero-shot prompt (ours)	0.8742	0.5805	0.8741	0.8622	0.7128	0.8624	0.8053	0.4874	0.8047
No-text prompt (ours)	0.3940	0.1307	0.3941	0.4810	0.2572	0.4817	0.3522	0.1151	0.3525
Prompt engineering: back to 5 samples, closed-source GPT-3.5-Turbo-Instruct as a generative LLM									
Original prompt	0.4097	0.1302	0.4092	0.3644	0.1601	0.3640	0.3480	0.1255	0.3485

- Evaluation metrics: ROUGE scores
- Fine-tuned FLAN-T5 under the question-answering format has the best performance
- Text summaries are important for LLMs to make correct predictions

Experiments: multi-event forecasting

Table 9: Model architectures for multi-event forecasting

Model	GNN	RNN	How to handle text?
DNN	N/A	N/A	N/A
DynGCN	DynGCN	N/A	Word graph only
T-GCN	GCN	GRU	Word graph only
RENET	RGCN	RNN	Event graph only
Glean	CompGCN	GRU	Word graph + event graph
LEAF-MEF (ours)	N/A	N/A	TKG quintuple prompt encoding

Table 10: Multi-event forecasting results, historical sequence length = 7 (back to 7 days)

ICEWS dataset	Afghanistan			India			Russia		
	Metric	F1	Recall	Precision	F1	Recall	Precision	F1	Recall
DNN	55.77	68.14	47.20	52.49	56.38	49.10	53.81	62.61	47.18
Dynamic GCN	50.05	57.75	44.16	41.80	43.19	40.50	52.81	60.14	47.07
Temporal GCN	60.04	76.93	49.23	60.73	67.20	55.40	56.36	67.66	48.29
RENET	60.58	77.75	49.62	58.44	64.18	53.64	55.85	65.66	48.59
Glean	62.48	82.84	50.15	66.69	77.31	58.64	58.92	73.57	49.14
LEAF-MEF w/o SA (ours)	60.93	78.32	49.86	59.21	64.76	54.54	56.67	68.38	48.38
LEAF-MEF w/ SA (ours)	63.63	88.69	49.61	70.99	87.31	59.81	62.80	86.81	49.19

- Evaluation metrics: F1 score, recall, and precision
- The self-attention mechanism before historical aggregation is important for enhancing the forecasting performance

Limitations and potential future work

- An appropriate alignment between the pre-trained LLMs and the dynamic evolution of knowledge graphs as time goes remains to be explored.
- The LLM fine-tuning in LEAF is conducted separately, therefore, to better utilize LLM's contextualized potential, better customization for combining LLMs with downstream tasks is expected.
- When retrieving historical knowledge, LEAF considers each quintuple wholly, whereas a closer look at the versatile relationships among different subjects, relations, and objects could lead to finer granularity.

Challenges and considerations

LLMs provide powerful tools for human event forecasting by extracting insights and performing reasoning from textual data.

Limitations

- The answers from LLMs may **lack factuality and causality**, as they generate responses based on statistical patterns rather than explicit knowledge.

How to ensure the accuracy and reliability of their outputs?

- Develop methods to enhance reliability
- Critically evaluate LLM outputs in event forecasting applications

LLMs for event data construction

Event encoding systems

Event data can be categorized into:

- **Human-encoded** events depend on human research teams with specific knowledge of the local context.
 - Armed Conflict Location & Event Data (ACLED)
- **Machine-encoded** events rely entirely on automated event encoding systems.
 - Integrated Crisis Early Warning System (ICEWS)
 - Global Database of Events, Language, and Tone (GDELT)



LLMs for event data construction

Compared to rule-based machine coding methods, LLMs have **better language comprehension** and can effectively **save labor** compared to manual coding.

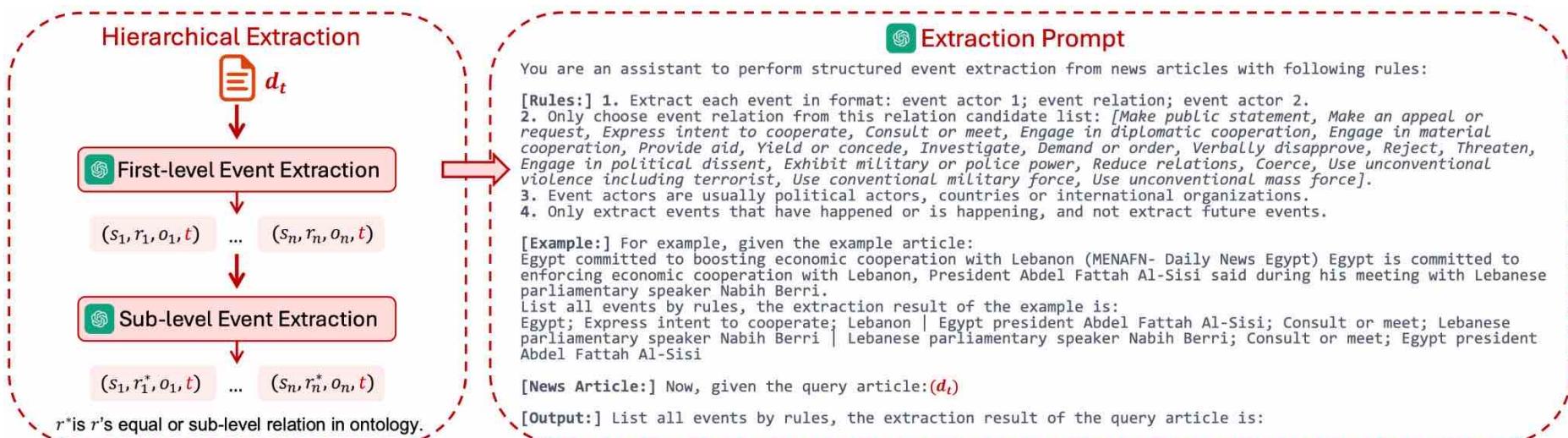
A recent work introduces a fully automated pipeline and a new event dataset MidEast-TE [Ma et al. 2024]

- utilizes the pre-trained large language models (LLMs) for event extraction from news articles.



Hierarchically extracts structured events with LLMs

- Hierarchically extraction due to **input length limitation** of LLMs.
- Follow the **three-level relation hierarchy in CAMEO** (event encoding scheme) from coarse-grain to fine-grain.



Entity linking with LLMs

No predefined entity set during LLM based event extraction, thus multiple entities may correspond to the same one, e.g., U.S.A and United States.

Linking method

- Apply a K-means clustering to group original entities into multiple groups.
- Ask the GPT-4 to perform entity linking for each cluster.
 - Entity cluster size is relatively small, thus the cost of using GPT-4 is marginal.

Accuracy might not be guaranteed

Dataset evaluation

The events in MidEast-TE are **more fine-grained**, because of

- A larger entity set.
- The distribution of events in different levels (less low level events and more high level events)

Table 4: Event extraction results comparison.

Dataset	\mathcal{R}	\mathcal{E}	#atomic events	% of different levels		
				1st	2nd	3rd
GDELT-TE	239	1,555	1,201,881	38.93	57.19	3.88
MidEast-TE	234	2,794	455,877	21.24	64.82	13.94

Evaluating LLMs for event forecasting

A benchmark for evaluating LLMs for event forecasting

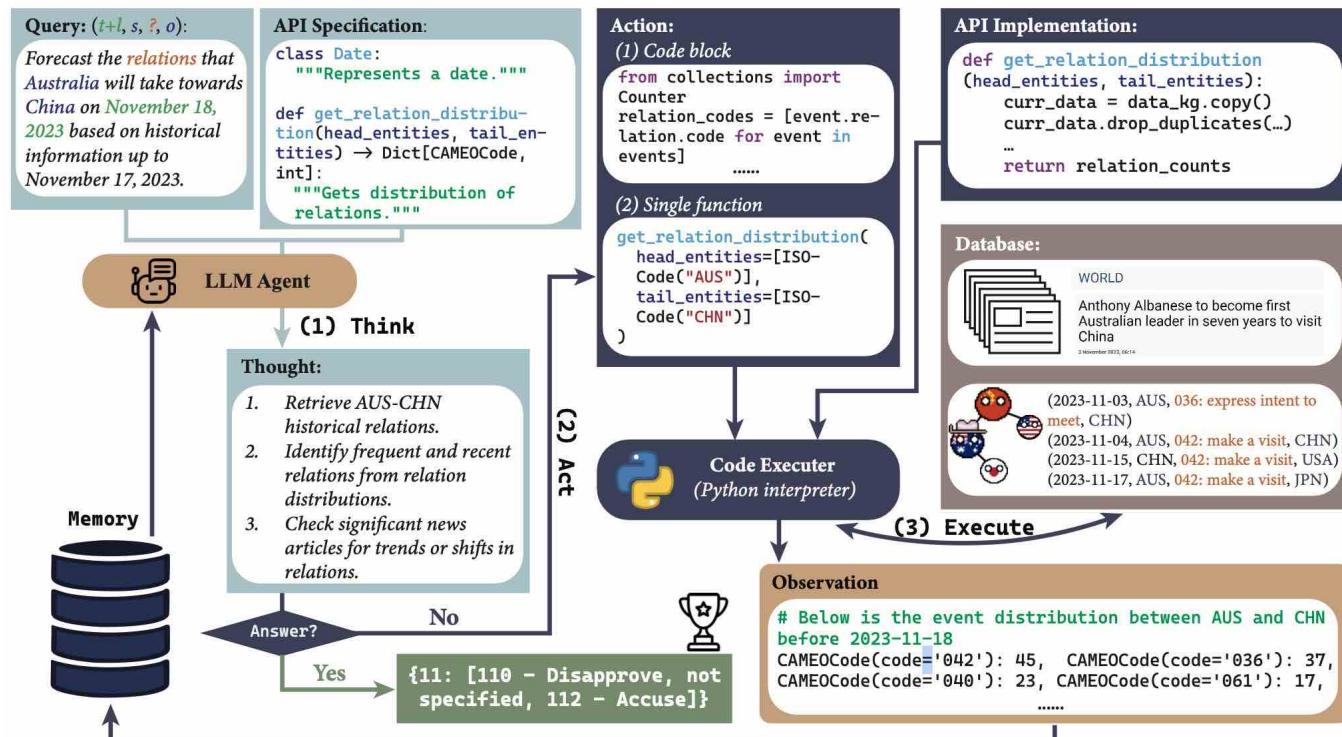
MIRAI, a novel benchmark designed to systematically **evaluate LLM agents as temporal forecasters** in the context of international events.

Motivation:

- Increasing interests have been put into employing LLM agents for event prediction.
- A lack of a rigorous benchmark of LLM agents' forecasting capability and reliability.

The pipeline

Overview of the LLM agent's interaction with the multi-source environment using the **ReAct** [Yao et al 2022] strategy for forecasting a query event.



Different agent tools and the tool-use strategies

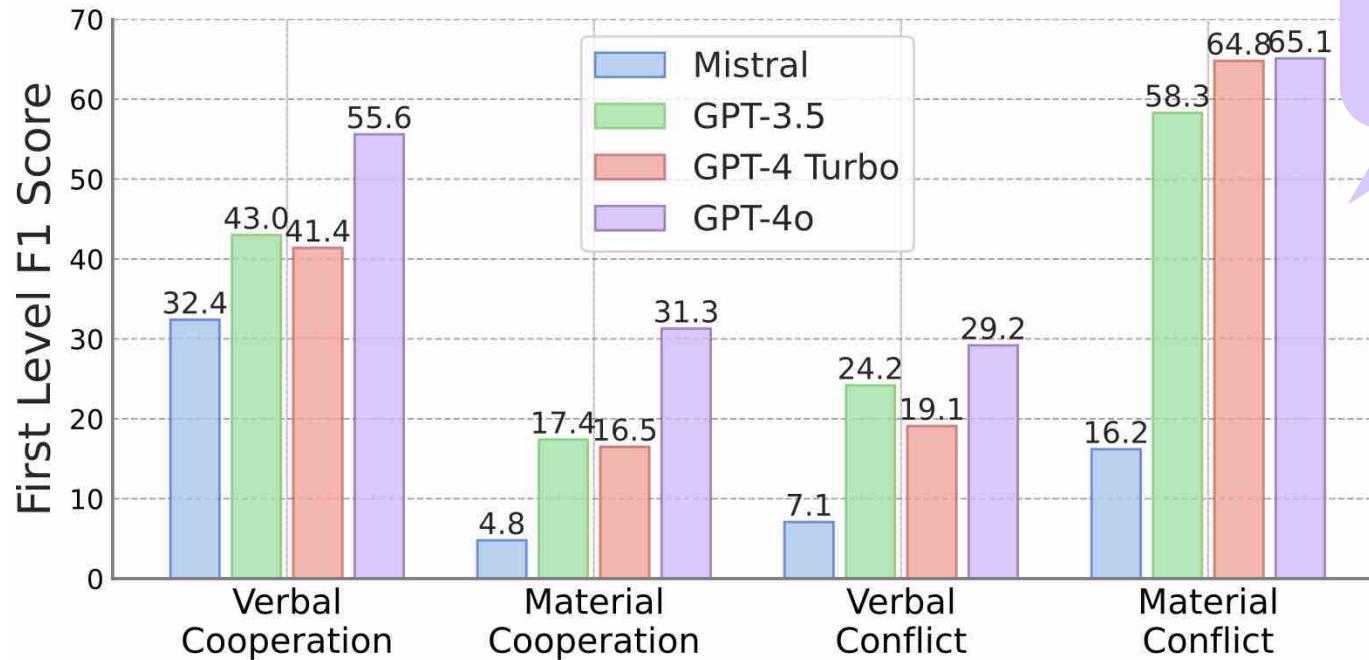
Direct IO: standard LLM chatbot approach

Zero-Shot Chain-of-Thought (ZS-CoT): prompt to the LLM to encourage explicit step-by-step thinking before making the final prediction.

ReAct: follow **ReAct** to interact with the provided environments through an iterative process of thinking, acting, and observing.

Agent	Tool-Use		Binary KL (↓)	Quad KL (↓)	First-level Relation (%)			Second-level Relation (%)		
	Action Type	API			Pre. (↑)	Rec. (↑)	F1 (↑)	Pre. (↑)	Rec. (↑)	F1 (↑)
Direct IO	—	—	6.5 \pm 1.7	15.9 \pm 1.5	27.6 \pm 8.1	19.7 \pm 5.9	18.8 \pm 6.9	6.6 \pm 1.5	5.1 \pm 0.4	3.5 \pm 0.8
ZS-COT	—	—	6.9 \pm 0.8	10.1 \pm 0.8	27.6 \pm 4.0	36.0 \pm 4.5	26.7 \pm 4.1	10.2 \pm 1.4	17.4 \pm 1.1	10.5 \pm 0.7
ReAct	Single Function	<i>Event-Only</i>	33.5 \pm 0.7	6.7 \pm 0.7	44.3 \pm 3.9	54.2 \pm 3.9	41.4 \pm 1.7	25.3 \pm 2.6	47.4 \pm 2.4	26.9 \pm 1.9
	Single Function	<i>News-Only</i>	6.1 \pm 1.0	12.8 \pm 0.6	27.8 \pm 3.1	25.9 \pm 2.9	21.8 \pm 2.3	6.3 \pm 2.2	9.0 \pm 2.0	5.4 \pm 1.3
ReAct	Single Function	All	3.1 \pm 0.5	5.9 \pm 1.0	47.6 \pm 5.8	58.3 \pm 2.6	44.2 \pm 4.0	28.7 \pm 3.9	51.0 \pm 4.0	29.6 \pm 3.7
	Code Block	All	5.1 \pm 0.9	8.9 \pm 0.5	27.1 \pm 4.0	38.6 \pm 2.5	25.9 \pm 2.2	11.6 \pm 2.4	26.3 \pm 2.0	12.6 \pm 1.7

Different LLM agents on event type prediction



GPT-4o consistently outperforms other models.

Summary and future work

Summary

- Introduction and motivation for event predictions
 - Definitions and challenges
 - A brief summary of early approaches
- Graph neural networks (GNNs)-based methods
 - Valina graph learning, graph learning with contextual information, and with causal reasoning
- Large language models (LLMs)-based methods
 - LLMs for event prediction, data construction and a benchmark

Future directions

- Combining the strengths of GNNs and LLMs
 - Utilize the structural understanding of GNNs with the contextual and linguistic capabilities of LLMs.
 - Leveraging LLMs for event prediction with causality
 - Incorporate causal relationships into LLM-based predictions.
 - Addressing biases and ensuring fairness
 - Identify and mitigate biases in both data and models.
- ...

Tutorial: Advances in Human Event Modeling: From Graph Neural Networks to Language Models

Thank you

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Tutorial website
(Slides uploaded)