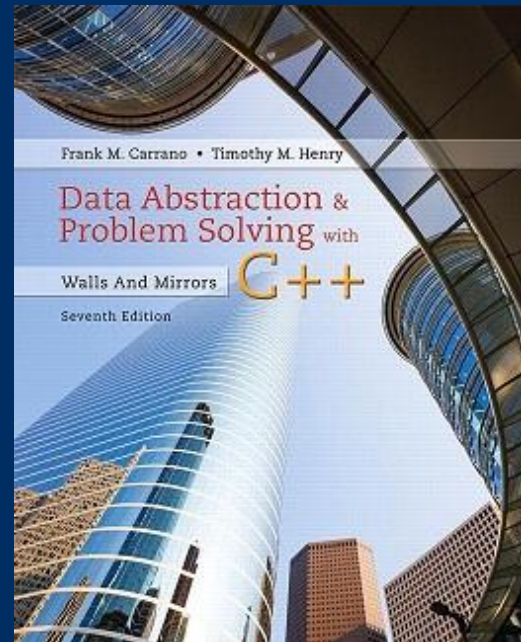


Dictionaries and Their Implementations

CS 302 - Data Structures

M. Abdullah Canbaz



- What are the names of to TAs?
- Where do they held their office hours?
- Where is the office of the instructor?





Reminders

- Assignment 5 is available
 - Due April 11th at 2pm
- TA
 - Athanasia Katsila,
Email: akatsila [at] nevada {dot} unr {dot} edu,
Office Hours: Tuesday, 10:30 am - 12:30 pm at SEM 211
- Quiz 9 is available
 - Today between 4pm to 11:59pm



Contents

- The ADT Dictionary
- Possible Implementations
- Selecting an Implementation
- Hashing



The ADT Dictionary

| <u>City</u> | <u>Country</u> | <u>Population</u> |
|---------------|----------------|-------------------|
| Buenos Aires | Argentina | 13,639,000 |
| Cairo | Egypt | 17,816,000 |
| Johannesburg | South Africa | 7,618,000 |
| London | England | 8,586,000 |
| Madrid | Spain | 5,427,000 |
| Mexico City | Mexico | 19,463,000 |
| Mumbai | India | 16,910,000 |
| New York City | U.S.A. | 20,464,000 |
| Paris | France | 10,755,000 |
| Sydney | Australia | 3,785,000 |
| Tokyo | Japan | 37,126,000 |
| Toronto | Canada | 6,139,000 |

- A collection of data about certain cities



The ADT Dictionary

- Consider need to search such a collection for
 - Name
 - Address
- Criterion chosen for search is *search key*
- The ADT dictionary uses a search key to identify its entries



Examples

- Telephone directory
- Library catalogue
- Books in print: key ISBN
- FAT (File Allocation Table)



Main Issues

- Size
- Operations: search, insert, delete,
 - < Create reports, Lists>
- What will be stored in the dictionary?
- How will be items identified?

Dictionary

```
+isEmpty(): boolean  
+getNumberOfEntries(): integer  
+add(searchKey: KeyType, newValue: ValueType): boolean  
+remove(targetKey: KeyType): boolean  
+clear(): void  
+getValue(targetKey: KeyType): ValueType  
+contains(targetKey: KeyType): boolean  
+traverse(visit(value: ValueType): void): void
```

- UML diagram for a class of dictionaries

- Categories of linear implementations
 - Sorted by search key array-based
 - Sorted by search key link-based
 - Unsorted array-based
 - Unsorted link-based

| | |
|------------|------------|
| Search key | Data Value |
|------------|------------|

A dictionary entry

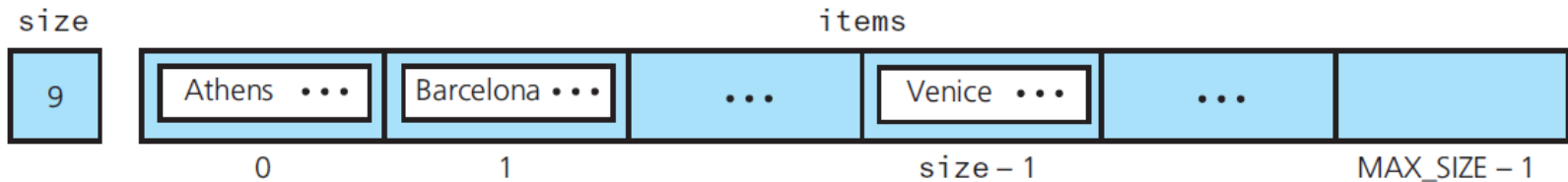
```
1  /** A class of entries to add to an array-based implementation of the
2      ADT dictionary.
3      @file Entry.h */
4
5  #ifndef ENTRY_
6  #define ENTRY_
7
8  template <class KeyType, class ValueType>
9  class Entry
10 {
11     private:
12         KeyType key;
13         ValueType value;
14
15     protected:
16         void setKey(const KeyType& searchKey);
17
```

- A header file for a class of dictionary entries

```
16     void setKey(const KeyType& searchKey);
17
18 public:
19     Entry();
20     Entry(const KeyType& searchKey, const ValueType& newValue);
21     ValueType getValue() const;
22     KeyType getKey() const;
23     void setValue(const ValueType& newValue);
24
25     bool operator==(const Entry<KeyType, ValueType>& rightHandValue) const;
26     bool operator>(const Entry<KeyType, ValueType>& rightHandValue) const;
27 }; // end Entry
28 #include "Entry.cpp"
29 #endif
```

- A header file for a class of dictionary entries

(a) Array based



(b) Link based



- Data members for two sorted linear implementations of the ADT dictionary

```
1  /** An interface for the ADT dictionary.
2   * @file DictionaryInterface.h */
3
4  #ifndef DICTIONARY_INTERFACE_
5  #define DICTIONARY_INTERFACE_
6
7  #include "NotFoundException.h"
8
9  template<class KeyType, class ValueType>
10 class DictionaryInterface
11 {
12 public:
13     /** Sees whether this dictionary is empty.
14      * @return True if the dictionary is empty;
15      *         otherwise returns false. */
16     virtual bool isEmpty() const = 0;
17
18     /** Gets the number of entries in this dictionary.
19      * @return The number of entries in the dictionary. */
20     virtual int getNumberOfEntries() const = 0;
```

- A header file for a class of dictionary interface

```
21
22  /** Adds a new search key and associated value to this dictionary.
23   * @pre The new search key differs from all search keys presently
24   * in the dictionary.
25   * @post If the addition is successful, the new key-value pair is in its
26   * proper position within the dictionary.
27   * @param searchKey The search key associated with the value to be added.
28   * @param newValue The value to be added.
29   * @return True if the entry was successfully added, or false if not. */
30  virtual bool add(const KeyType& searchKey, const ValueType& newValue) = 0;
31
32  /** Removes a key-value pair from this dictionary.
33   * @post If the entry whose search key equals searchKey existed in the
34   * dictionary, the entry was removed.
35   * @param searchKey The search key of the entry to be removed.
36   * @return True if the entry was successfully removed, or false if not. */
37  virtual bool remove(const KeyType& searchKey) = 0;
38
39  /** Removes all entries from this dictionary. */
40  virtual void clear() = 0;
```

- A header file for a class of dictionary interface

```
40 virtual void clear() = 0;
41
42 /** Retrieves the value in this dictionary whose search key is given
43     @post  If the retrieval is successful, the value is returned.
44     @param searchKey  The search key of the value to be retrieved.
45     @return  The value associated with the search key.
46     @throw  NotFoundException if the key-value pair does not exist. */
47 virtual ValueType getValue(const KeyType& searchKey) const
48         throw (NotFoundException) = 0;
49
50 /** Sees whether this dictionary contains an entry with a given search key.
51     @post  The dictionary is unchanged.
52     @param searchKey  The given search key.
53     @return  True if an entry with the given search key exists in the
54             dictionary. */
55 virtual bool contains(const KeyType& searchKey) const = 0;
56
```

- A header file for a class of dictionary interface

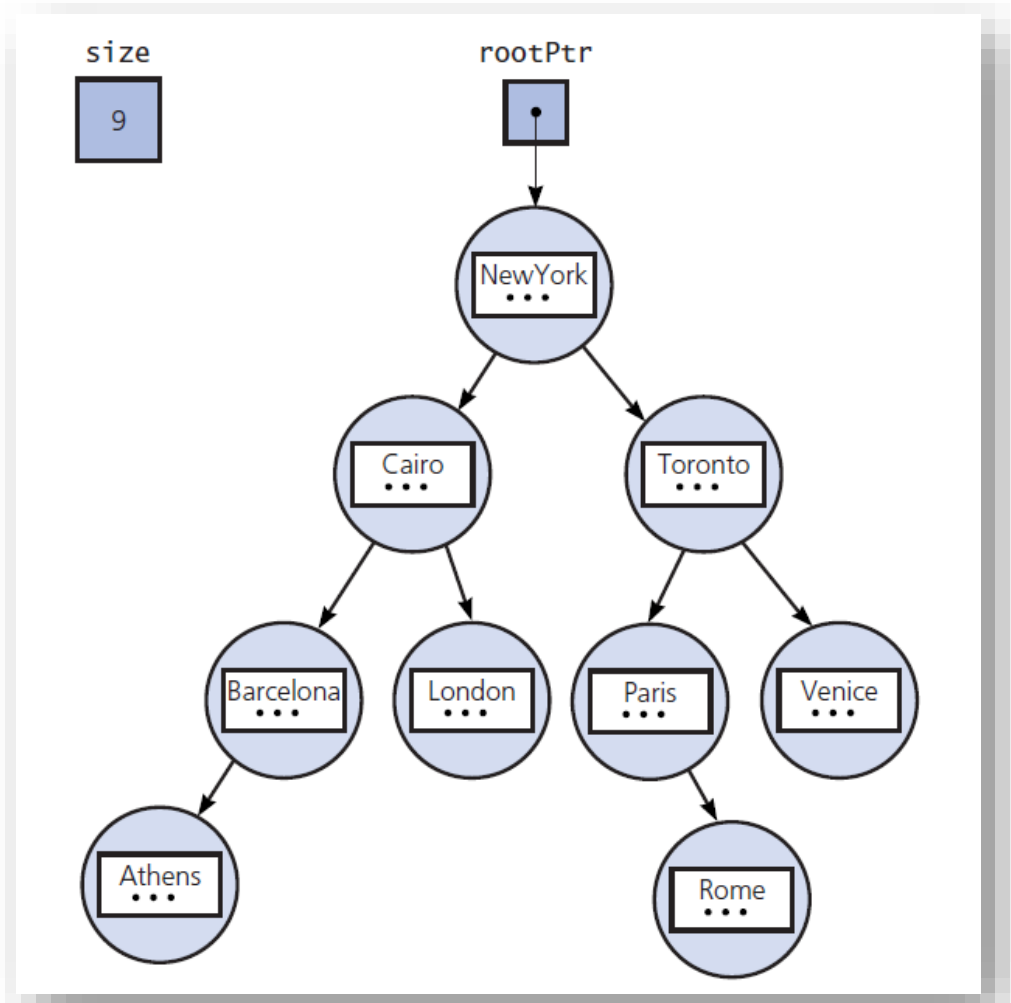

```
55 virtual bool contains(const key_typed searchKey) const = 0;
56
57 /** Traverses this dictionary and calls a given client function once
58     for each entry.
59     @post The given function's action occurs once for each entry in the
60         dictionary and possibly alters the entry.
61     @param visit A client function. */
62 virtual void traverse(void visit(ValueType&)) const = 0;
63 /** Destroys this dictionary and frees its assigned memory. */
64
65 virtual ~DictionaryInterface(){ }
66 }; // end DictionaryInterface
67 #endif
```

- A header file for a class of dictionary interface

```
25
26 public:
27     ArrayDictionary();
28     ArrayDictionary(int maxNumberOfEntries);
29     ArrayDictionary(const ArrayDictionary<KeyType, ValueType>& dictionary);
30
31     virtual ~ArrayDictionary();
32
33     bool isEmpty() const;
34     int getNumberOfEntries() const;
35     bool add(const KeyType& searchKey, const ValueType& newValue) throw(PrecondViolatedExcept);
36     bool remove(const KeyType& searchKey);
37     void clear();
38     ValueType getValue(const KeyType& searchKey) const throw(NotFoundException);
39     bool contains(const KeyType& searchKey) const;
40
41     /** Traverses the entries in this dictionary in sorted search-key order
42         and calls a given client function once for the value in each entry. */
43     void traverse(void visit(ValueType&)) const;
44 }; // end ArrayDictionary
45 #include "ArrayDictionary.cpp"
46 #endif
```

- A header file for the class `ArrayDictionary`

- The data members for a binary search tree implementation of the ADT dictionary



```
1  /** A binary search tree implementation of the ADT dictionary
2     that organizes its data in sorted search-key order.
3     Search keys in the dictionary are unique.
4     @file TreeDictionary.h */
5
6  #ifndef TREE_DICTIONARY_
7  #define TREE_DICTIONARY_
8
9  #include "DictionaryInterface.h"
10 #include "BinarySearchTree.h"
11 #include "Entry.h"
12 #include "NotFoundException.h"
13 #include "PrecondViolatedExcept.h"
14
15 template <class KeyType, class ValueType>
16 class TreeDictionary : public DictionaryInterface<KeyType, ValueType>
17 {
18 private:
```

- A header file for the class **TreeDictionary**

```
17  
18 private:  
19     // Binary search tree of dictionary entries  
20     BinarySearchTree<Entry<KeyType, ValueType> > entryTree;  
21  
22 public:  
23     TreeDictionary();  
24     TreeDictionary(const TreeDictionary<KeyType, ValueType>& dictionary);  
25  
26     virtual ~TreeDictionary();  
27  
28     // The declarations of the public methods appear here and are the  
29     // same as given in Listing 18-3 for the class ArrayDictionary.  
30     ...  
31 }; // end TreeDictionary  
32 #include "TreeDictionary.cpp"  
33 #endif
```

- A header file for the class **TreeDictionary**

```
template < class KeyType, class ValueType>
bool TreeDictionary<KeyType, ValueType>::add(const KeyType& searchKey,
                                             const ValueType& newValue)
                                             throw(PrecondViolatedExcept)
{
    Entry<KeyType, ValueType> newEntry(searchKey, newValue);

    // Enforce precondition: Ensure distinct search keys
    if (!itemTree.contains(newEntry))
    {
        // Add new entry and return boolean result
        return itemTree.add(Entry<KeyType, ValueType>(searchKey, newValue));
    }
    else
    {
        auto message = "Attempt to add an entry whose search key exists in dictionary.";
        throw(PrecondViolatedExcept(message)); // Exit the method
    } // end if
} // end add
```

- Method **add** which prevents duplicate keys.

- Linear implementations
 - Perspective
 - Efficiency
 - Motivation
- Consider
 - What operations are needed
 - How often each operation is required



Three Scenarios

A. Addition and traversal in no particular order

- Unsorted order is efficient
- Array-based versus pointer-based

B. Retrieval

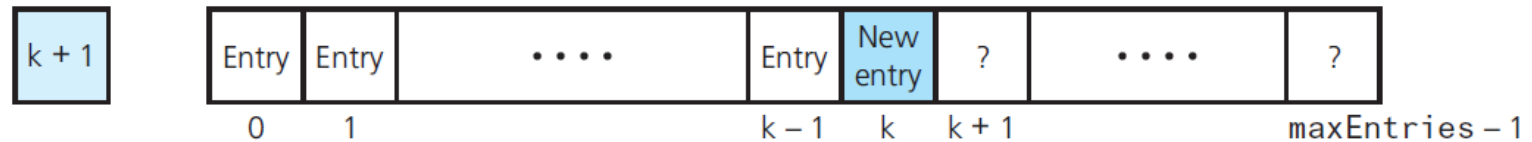
- Sorted array-based can use binary search
- Binary search impractical for link-based
- Max size of dictionary affects choice

C. Addition, removal, retrieval, traversal in sorted order

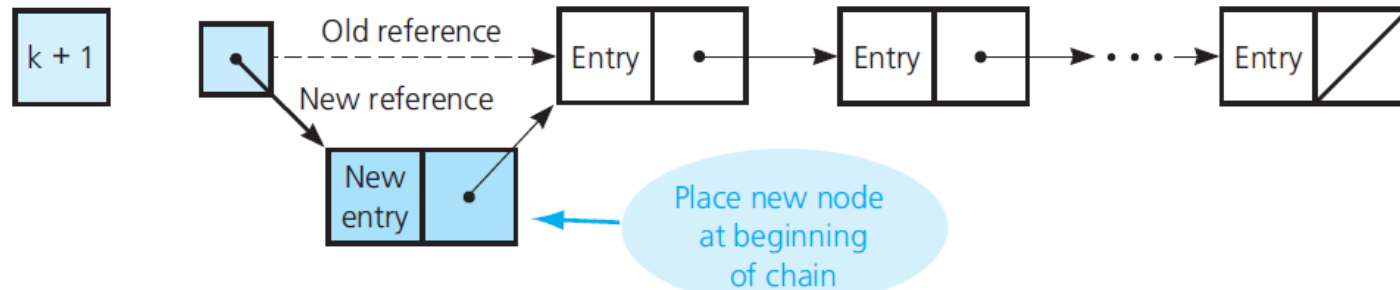
- Add and remove need to find position, then add or remove from that position
- Array-based best for find, link-based best for addition/removal

Three Scenarios

(a) Array based
entryCount



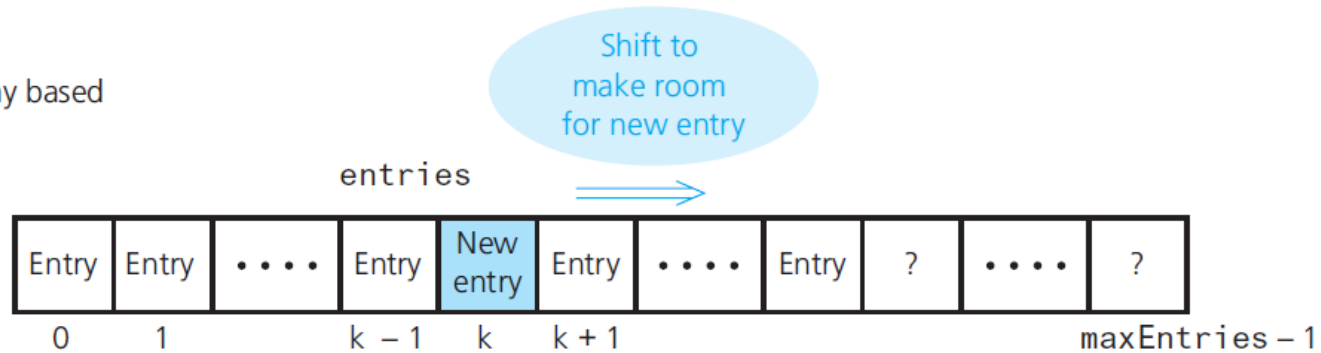
(b) Link based
entryCount headPtr



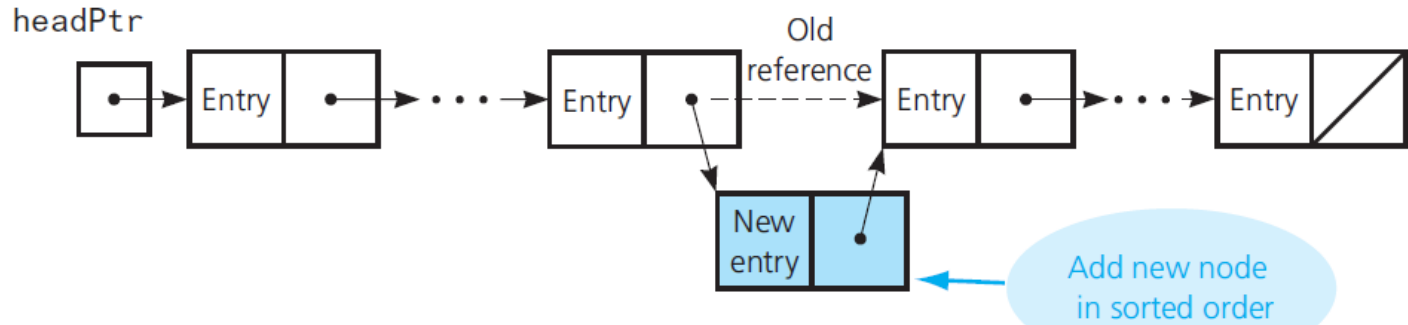
- Addition for unsorted linear implementations

Three Scenarios

(a) Array based



(b) Link based



- Addition for sorted linear implementations

| | <u>Addition</u> | <u>Removal</u> | <u>Retrieval</u> | <u>Traversal</u> |
|----------------------|-----------------|----------------|------------------|------------------|
| Unsorted array-based | $O(1)$ | $O(n)$ | $O(n)$ | $O(n)$ |
| Unsorted link-based | $O(1)$ | $O(n)$ | $O(n)$ | $O(n)$ |
| Sorted array-based | $O(n)$ | $O(n)$ | $O(\log n)$ | $O(n)$ |
| Sorted link-based | $O(n)$ | $O(n)$ | $O(n)$ | $O(n)$ |
| Binary search tree | $O(\log n)$ | $O(\log n)$ | $O(\log n)$ | $O(n)$ |

- The average-case order of the ADT dictionary operations for various implementations

Direct Addressing





The Search Problem

- Unsorted list
 - $O(N)$
- Sorted list
 - $O(\log N)$ using arrays (i.e., binary search)
 - $O(N)$ using linked lists
- Binary Search tree
 - $O(\log N)$ (i.e., balanced tree)
 - $O(N)$ (i.e., unbalanced tree)
- Can we do better than this?
 - Direct Addressing
 - Hashing

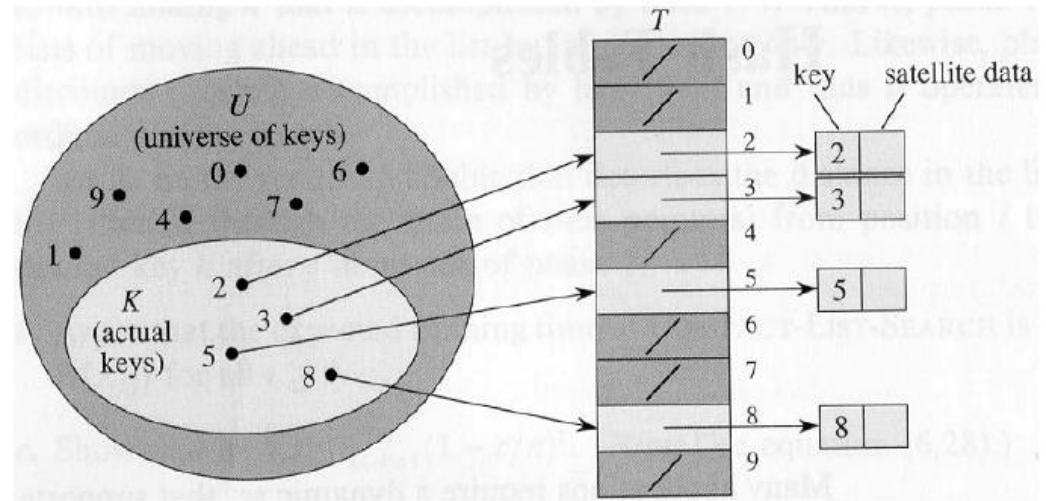


Direct Addressing

- Assumptions:
 - Key values are **distinct**
 - Each key is drawn from a universe $U = \{0, 1, \dots, n - 1\}$
- Idea:
 - Store the items in an array, indexed by keys

- **Direct-address table representation:**

- An array $T[0 \dots n - 1]$
- Each **slot**, or position, in T corresponds to a key in U
- For an element x with key k , a pointer to x will be placed in location $T[k]$
- If there are no elements with key k in the set, $T[k]$ is empty, represented by NIL



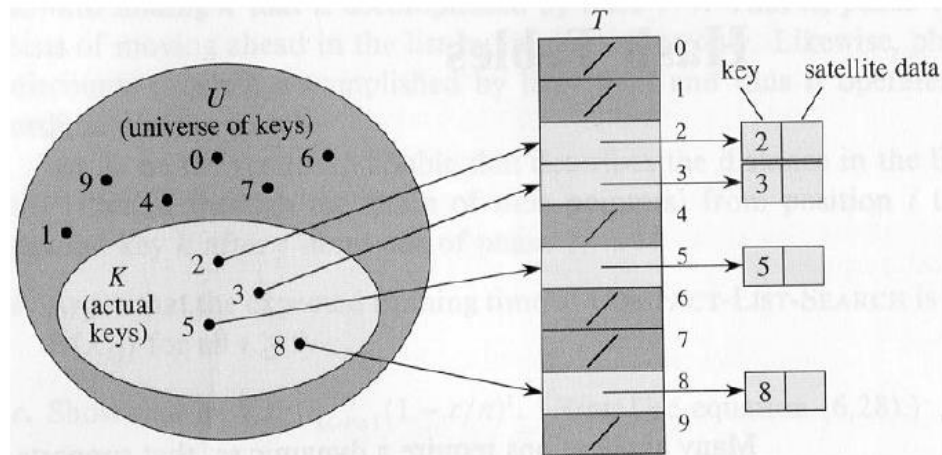
Search, insert, delete in $O(1)$ time!

Example 1: Suppose that there are integers from 1 to 100 and that there are about 100 records.

Create an array A of 100 items and stored the record whose key is equal to i in $A[i]$.

$$|K| = |U|$$

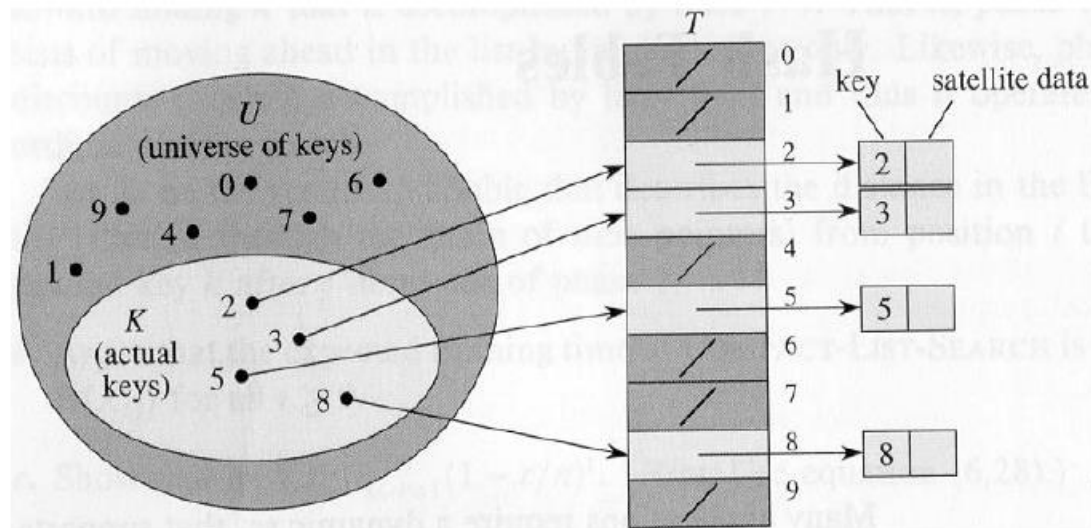
$|K|$: # elements in K
 $|U|$: # elements in U



Example 2: Suppose that the keys are 9-digit social security numbers (SSN)

Although we could use the same idea, it would be very inefficient (i.e., use an array of 1 billion size to store 100 records)

$$|K| \ll |U|$$



```

/*
 * number Declaration
 */
struct number
{
    int key;
    string english_text;

    // Constructors
    number(){}
    number( int k, string e )
    {
        english_text=e;
        key = k;
    }
};

```

```

/*
 * Main Contains Menu
 */
int main()
{
    int i, key, ch;
    string str;
    number x;

    number T[65536];

    for(i = 0; i < 65536;i++)
        T[i] = number(0,"");
}

```

```

/*
 * Insertion of element at a key
 */
void INSERT( number T[], number x )
{
    T[ x.key ] = x;
}

```

```

/*
 * Deletion of element at a key
 */
void DELETE( number T[], number x )
{
    T[ x.key ] = number(0, "");
}

```

```

/*
 * Searching of element at a key
 */
number SEARCH( number T[], int k )
{
    return T[ k ];
}

```



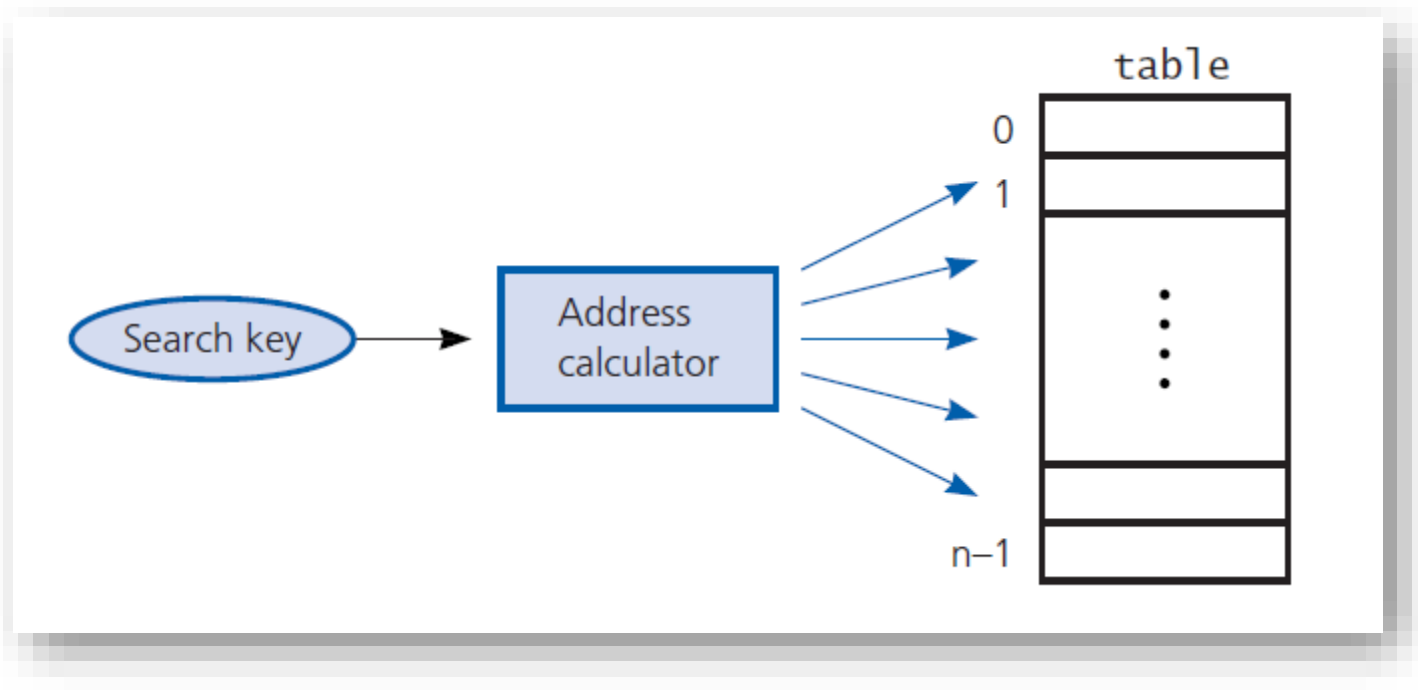
```
while (1)
{
    cout<<"\n-----"<<endl;
    cout<<"\nOperations on Direct Addressing number"<<endl;
    cout<<"\n-----"<<endl;
    cout<<"1.Insert element into the key"<<endl;
    cout<<"2.Delete element from the number"<<endl;
    cout<<"3.Search element into the number"<<endl;
    cout<<"4.Exit"<<endl;
    cout<<"Enter your Choice: ";
    cin>>ch;
    switch(ch)
    {
    case 1:
    {
```

```
switch(ch)
{
    case 1:
    {
        string str1 = "";
        cout<<"Enter the key value: ";
        cin>>key;
        cout<<"Enter the string to be inserted: ";
        cin.ignore();
        getline(cin, str);
        INSERT(T, number(key, str));
        break;
    }
    case 2:
        cout<<"Enter the key of element to be deleted: ";
        cin>>key;
        x = SEARCH(T, key);
        DELETE(T, x);
        break;
    case 3:
        cout<<"Enter the key of element to be searched: ";
        cin>>key;
        x = SEARCH(T, key);
        if (x.key == 0)
        {
            cout<<"No element inserted at the key"<<endl;
            continue;
        }
        cout<<"Element at key "<<key<<" is-> ";
        cout<<"\n"<<x.english_text<<"\n"<<endl;
        break;
    case 4:
        exit(1);
}
```

Hashing



- Situations occur for which search-tree implementations are not adequate.
- Consider a method which acts as an “address calculator” which determines an array index
 - Used for `add`, `getValue`, `remove` operations
- Called a hash function
 - Tells where to place item in a hash table



- Address calculator

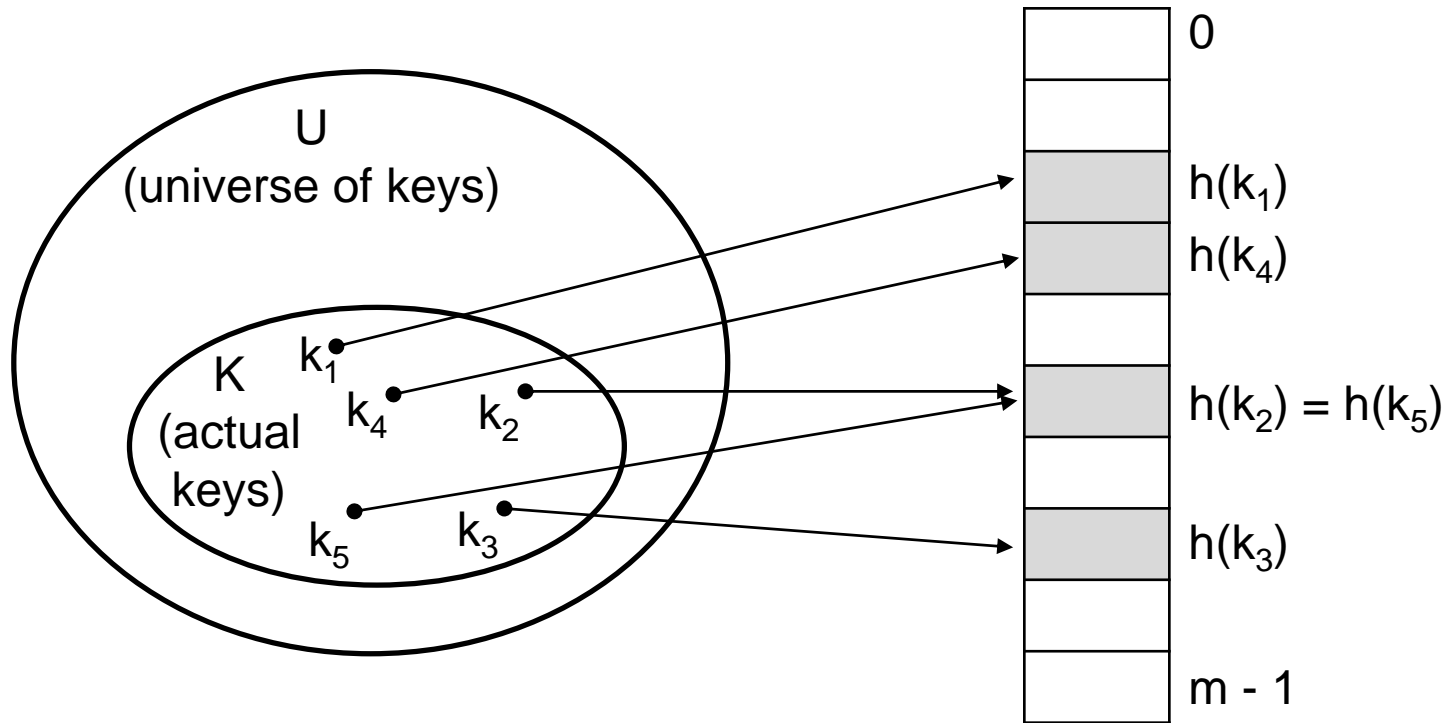
- is a means used to order and access elements in a list quickly by using a function of the key value to identify its location in the list.
 - the goal is $O(1)$ time
- The function of the key value is called a hash function

Idea:

- Use a function **h** to compute the slot for each key
- Store the element in slot **$h(k)$**
- A **hash function h** transforms a key into an index in a hash table $T[0 \dots m-1]$:

$$h : U \rightarrow \{0, 1, \dots, m - 1\}$$
- We say that **k hashes** to slot **$h(k)$**

Hashing (cont'd)



$$h : U \rightarrow \{0, 1, \dots, m-1\}$$

hash table size: **m**

Example 2: Suppose that the keys are 9-digit social security numbers (SSN)

Possible hash function

$$h(ssn) = ssn \bmod 100 \text{ (last 2 digits of ssn)}$$

e.g., if $ssn = 10123411$ then $h(10123411) = 11$)

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Advantages of Hashing

- Reduce the range of array indices handled:

m instead of $|U|$

where m is the hash table size: $T[0, \dots, m-1]$

- Storage is reduced.
- $O(1)$ search time (i.e., under assumptions).

- **Good hash function properties**

- (1) Easy to compute

- (2) Approximates a random function

- i.e., for every input, every output is equally likely.

- (3) Minimizes the chance that similar keys hash to the same slot

- i.e., strings such as **pt** and **pts** should hash to different slot.

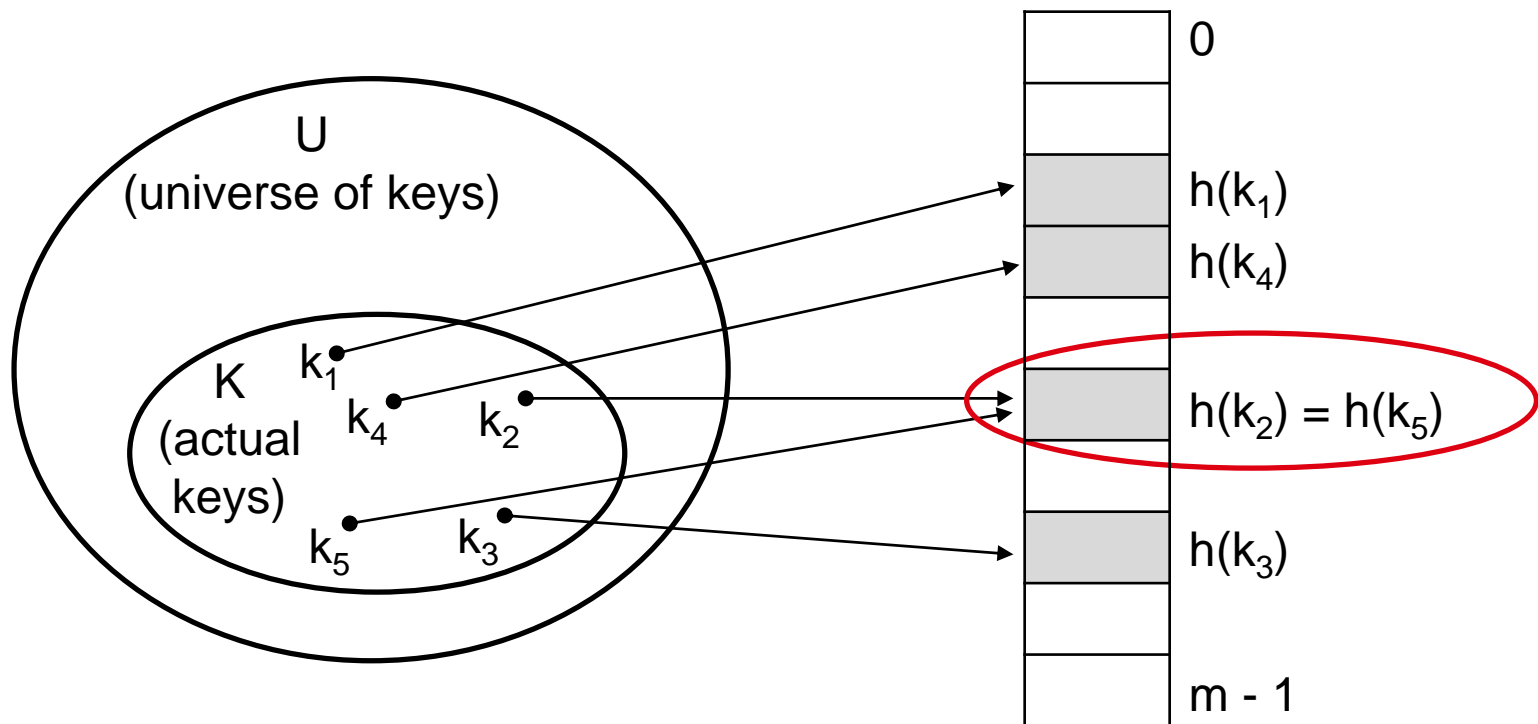
- Perfect hash function
 - Maps each search key into a unique location of the hash table
 - Possible if you know all the search keys
- Collision occurs when hash function maps more than one entry into same array location
- Hash function should
 - Be easy, fast to compute
 - Place entries evenly throughout hash table



Hash Functions

- Sufficient for hash functions to operate on integers – examples:
 - Select digits from an ID number
 - Folding – add digits, sum is the table location
 - Modulo arithmetic $h(x) = x \bmod \textit{tableSize}$
 - Convert character string to an integer – use ASCII values

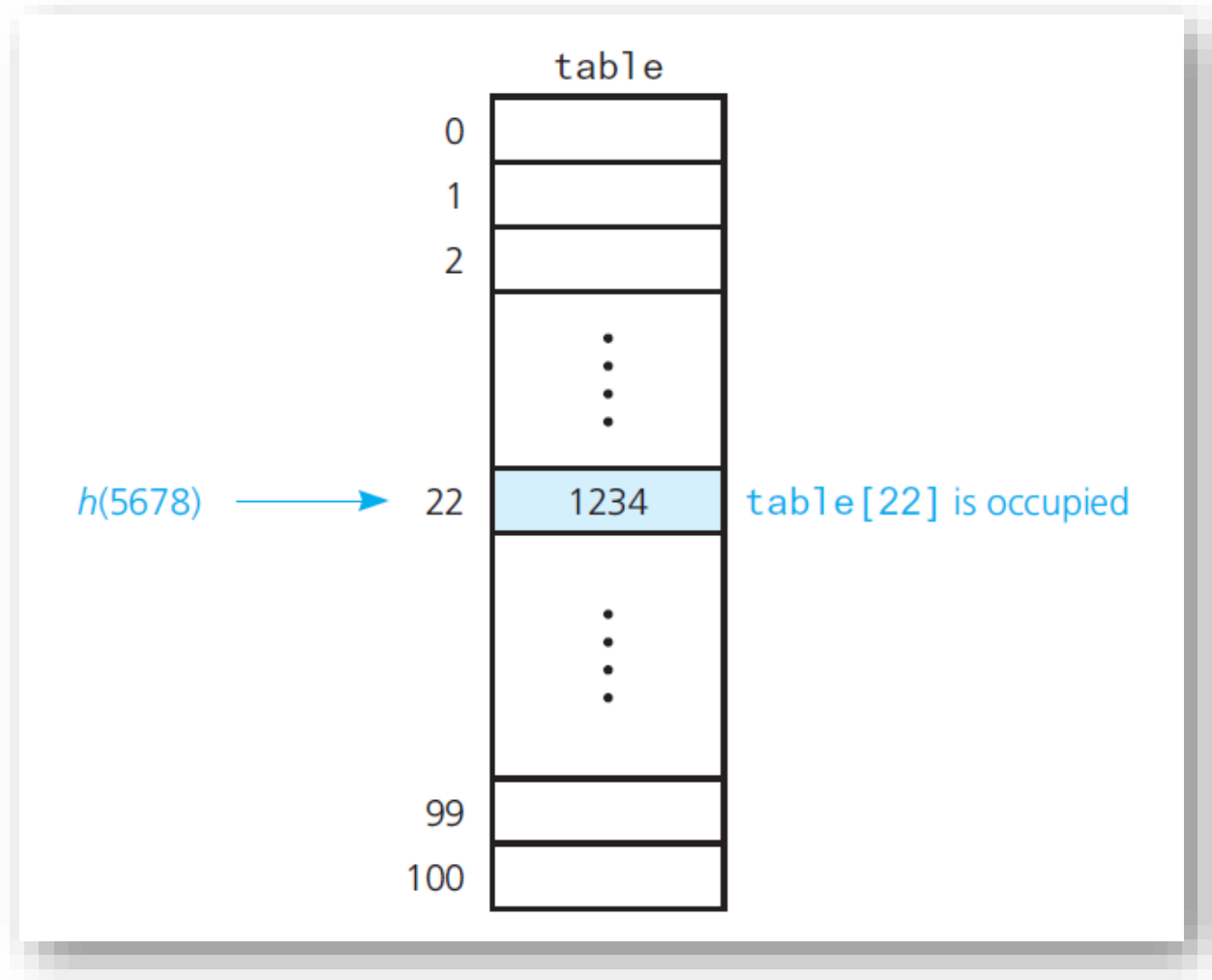
Collisions occur when $h(k_i) = h(k_j)$, $i \neq j$



- For a given set K of keys:
 - If $|K| \leq m$, collisions may or may not happen, depending on the hash function!
 - If $|K| > m$, collisions will definitely happen
 - i.e., there must be at least two keys that have the same hash value
- Avoiding collisions completely might not be easy.



Resolving Collisions with Open Addressing



- A collision

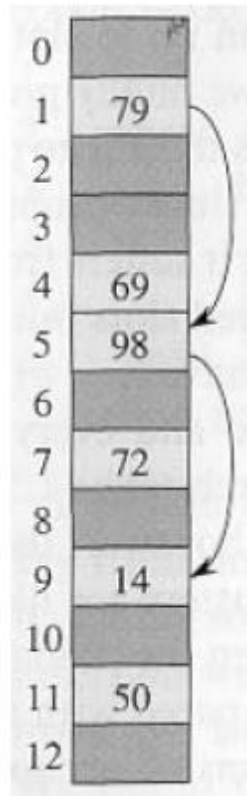
- Approach 1: Open addressing
 - Linear probing
 - Quadratic probing
 - Double hashing
 - Increase size of hash table

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Open Addressing

- Idea: store the keys in the table itself
- No need to use linked lists anymore
- Basic idea:
 - Insertion: if a slot is full, try another one, until you find an empty one.
 - Search: follow the same **probe sequence**.
 - Deletion: need to be careful!
- Search time depends on the length of probe sequences!

e.g., insert 14



probe sequence: $\langle 1, 5, 9 \rangle$

Generalize hash function notation:

- A hash function contains two arguments now:
(i) key value, and (ii) probe number e.g., insert 14

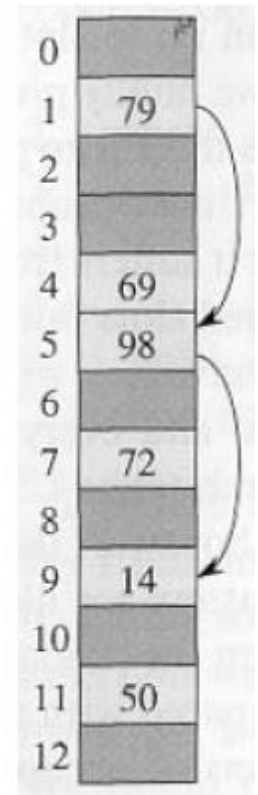
$$h(k,p), \quad p=0,1,\dots,m-1$$

- Probe sequence:

$$\langle h(k,0), h(k,1), h(k,2), \dots \rangle$$

- Example:

Probe sequence: $\langle h(14,0), h(14,1), h(14,2) \rangle = \langle 1, 5, 9 \rangle$



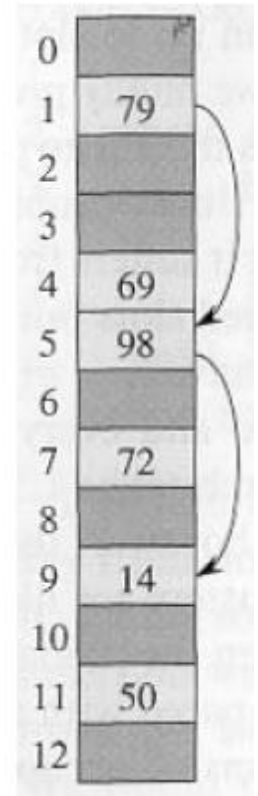
Generalize hash function notation:

- Probe sequence must be a permutation of

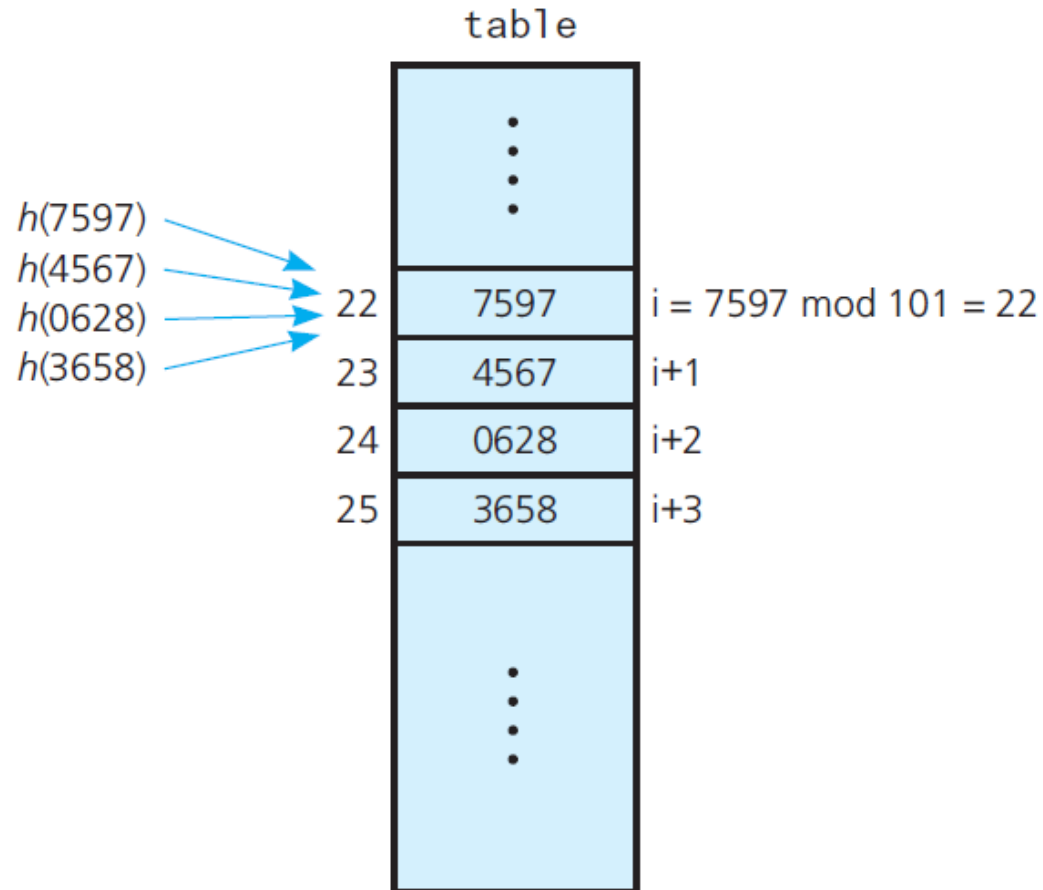
$\langle 0, 1, \dots, m-1 \rangle$

e.g., insert 14

- There are $m!$ possible permutations



Probe sequence: $\langle h(14,0), h(14,1), h(14,2) \rangle = \langle 1, 5, 9 \rangle$



- Linear probing with $h(x) = x \bmod 101$

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Linear probing: Inserting a key

- **Idea:** when there is a collision, check the next available position in the table:

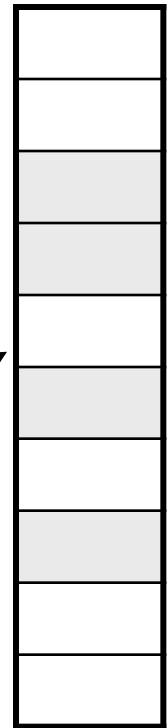
$$h(k,i) = (h_1(k) + i) \bmod m$$
$$i=0,1,2,\dots$$

- $i=0$: first slot probed: $h_1(k)$
- $i=1$: second slot probed: $h_1(k) + 1$
- $i=2$: third slot probed: $h_1(k)+2$, and so on

probe sequence: $\langle h_1(k), h_1(k)+1, h_1(k)+2, \dots \rangle$

- How many probe sequences can linear probing generate?

m probe sequences maximum

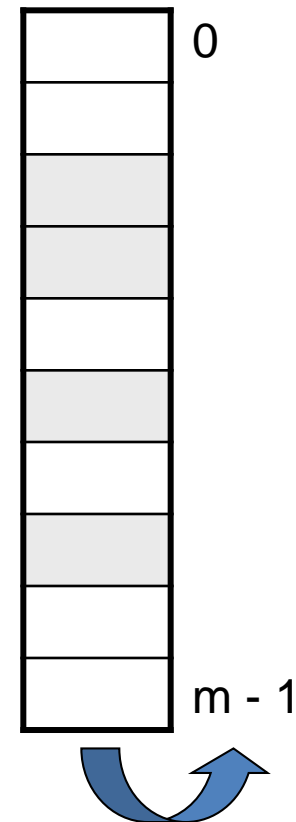


wrap around

N

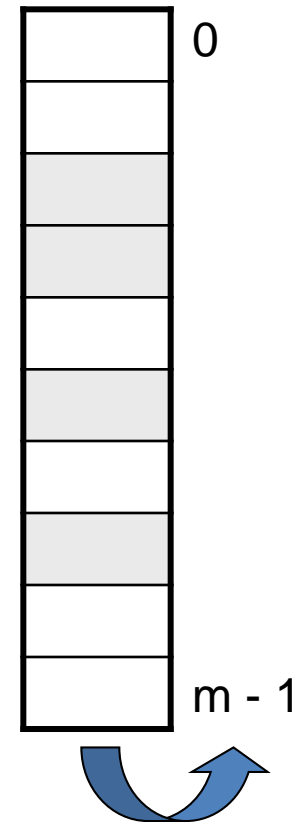
Linear probing: Searching for a key

- Given a key, generate a probe sequence using the same procedure.
- Three cases:
 - (1) Position in table is occupied with an element of equal key → **FOUND**
 - (2) Position in table occupied with a different element → **KEEP SEARCHING**
 - (3) Position in table is empty → **NOT FOUND**



wrap around

- Running time depends on the length of the probe sequences.
- Need to keep probe sequences short to ensure fast search.



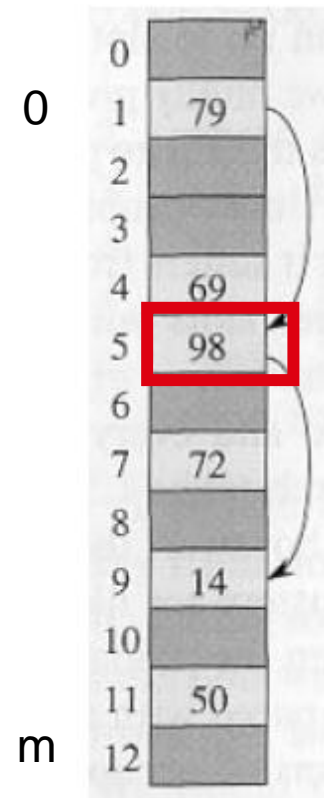
wrap around

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Linear probing: Deleting a key

- First, find the slot containing the key to be deleted.
- Can we just mark the slot as empty?
 - It would be impossible to retrieve keys inserted after that slot was occupied!
- Solution
 - “Mark” the slot with a sentinel value DELETED
- The deleted slot can later be used for insertion.

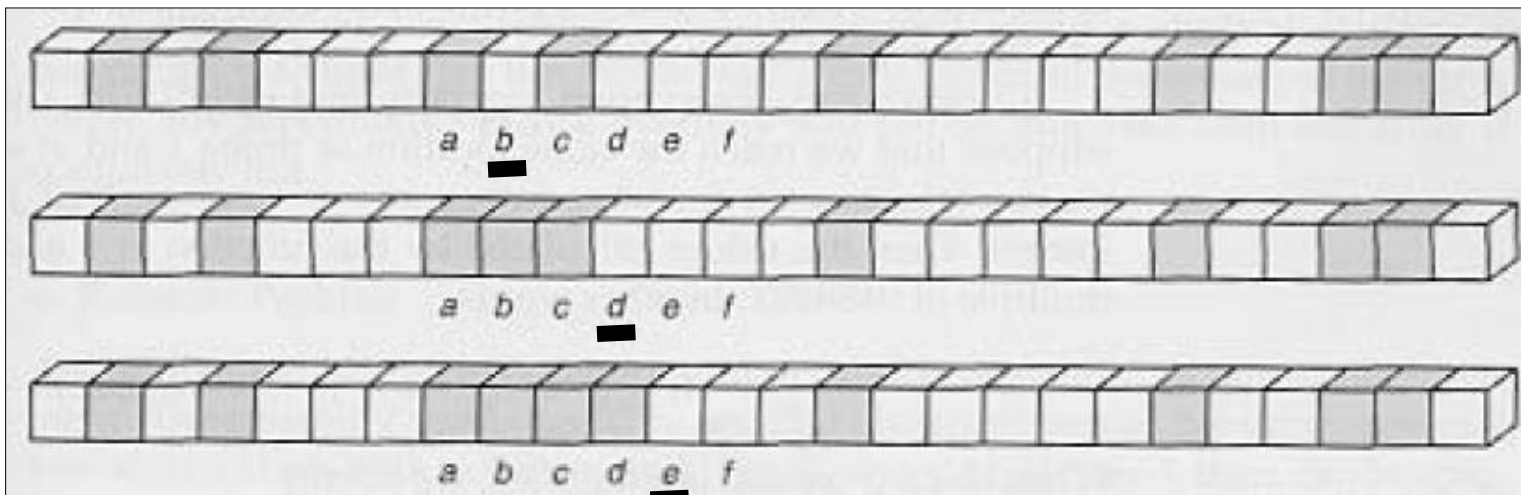
e.g., delete 98



Primary Clustering Problem

- Long chunks of occupied slots are created.
- As a result, some slots become more likely than others.
- Probe sequences increase in length. \Rightarrow search time increases!!

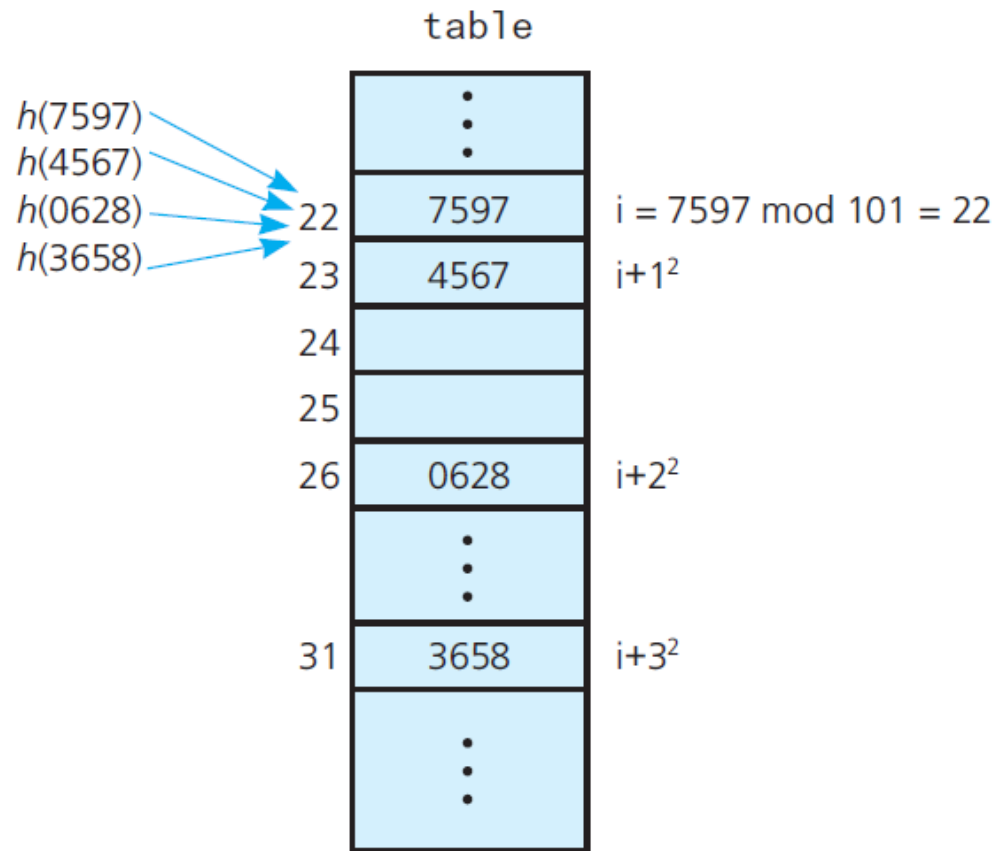
initially, all slots have probability $1/m$



Slot b:
 $2/m$

Slot d:
 $4/m$

Slot e:
 $5/m$



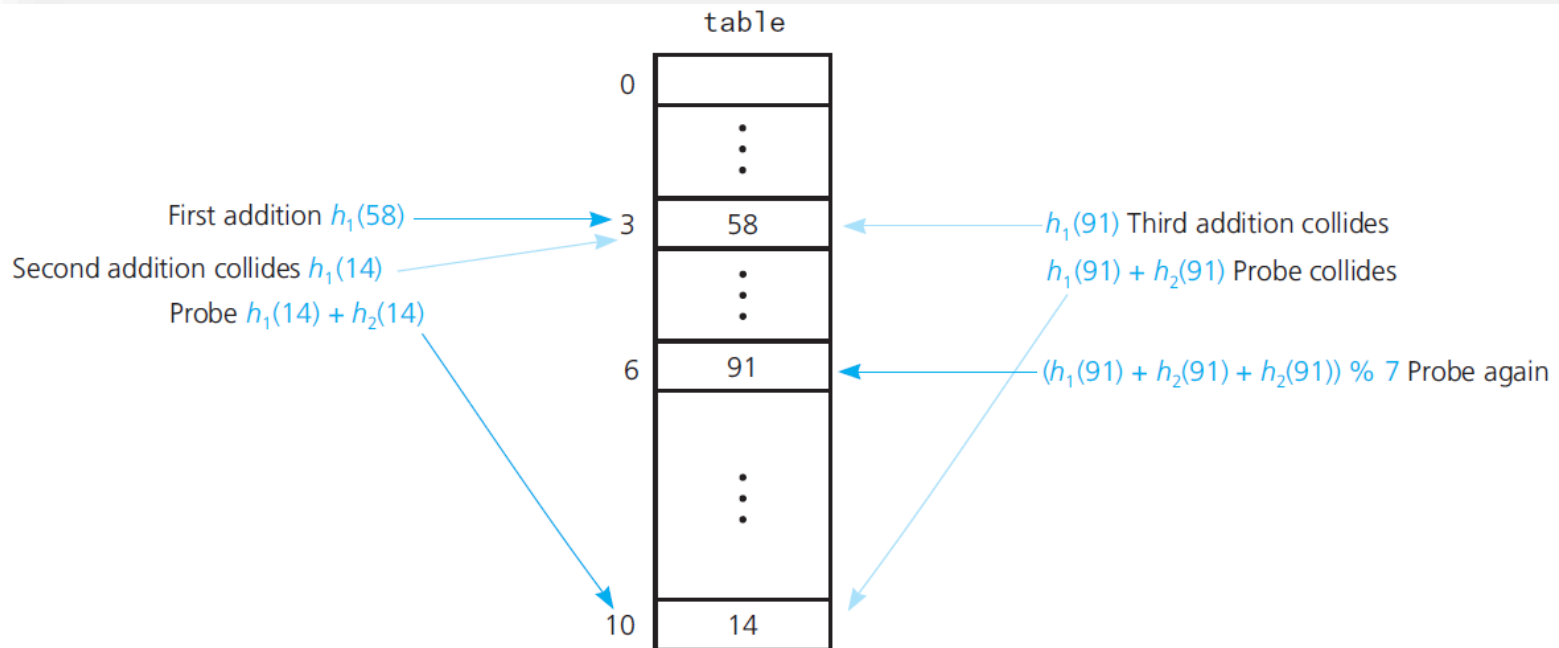
- Quadratic probing with $h(x) = x \bmod 101$

$$h(k, i) = (h'(k) + c_1 i + c_2 i^2) \bmod m, \text{ where } h': U \rightarrow (0, 1, \dots, m-1)$$

$i=0,1,2,\dots$

- Clustering is less serious but still a problem
 - *secondary clustering*
- How many probe sequences can quadratic probing generate?

m -- the initial position determines probe sequence



- Double hashing during the addition of 58, 14, and 91

- (1) Use one hash function to determine the first slot.
- (2) Use a second hash function to determine the increment for the probe sequence:

$$h(k,i) = (h_1(k) + i h_2(k)) \bmod m, \quad i=0,1,\dots$$

- Initial probe: $h_1(k)$
- Second probe is offset by $h_2(k) \bmod m$, so on ...
- **Advantage:** handles clustering better
- **Disadvantage:** more time consuming
- How many probe sequences can double hashing generate?

$$m^2$$

N

Double Hashing: Example

$$h_1(k) = k \bmod 13$$

$$h_2(k) = 1 + (k \bmod 11)$$

$$h(k,i) = (h_1(k) + i h_2(k)) \bmod 13$$

- Insert key 14:

$$i=0: h(14,0) = h_1(14) = 14 \bmod 13 = 1$$

$$\begin{aligned} i=1: h(14,1) &= (h_1(14) + h_2(14)) \bmod 13 \\ &= (1 + 4) \bmod 13 = 5 \end{aligned}$$

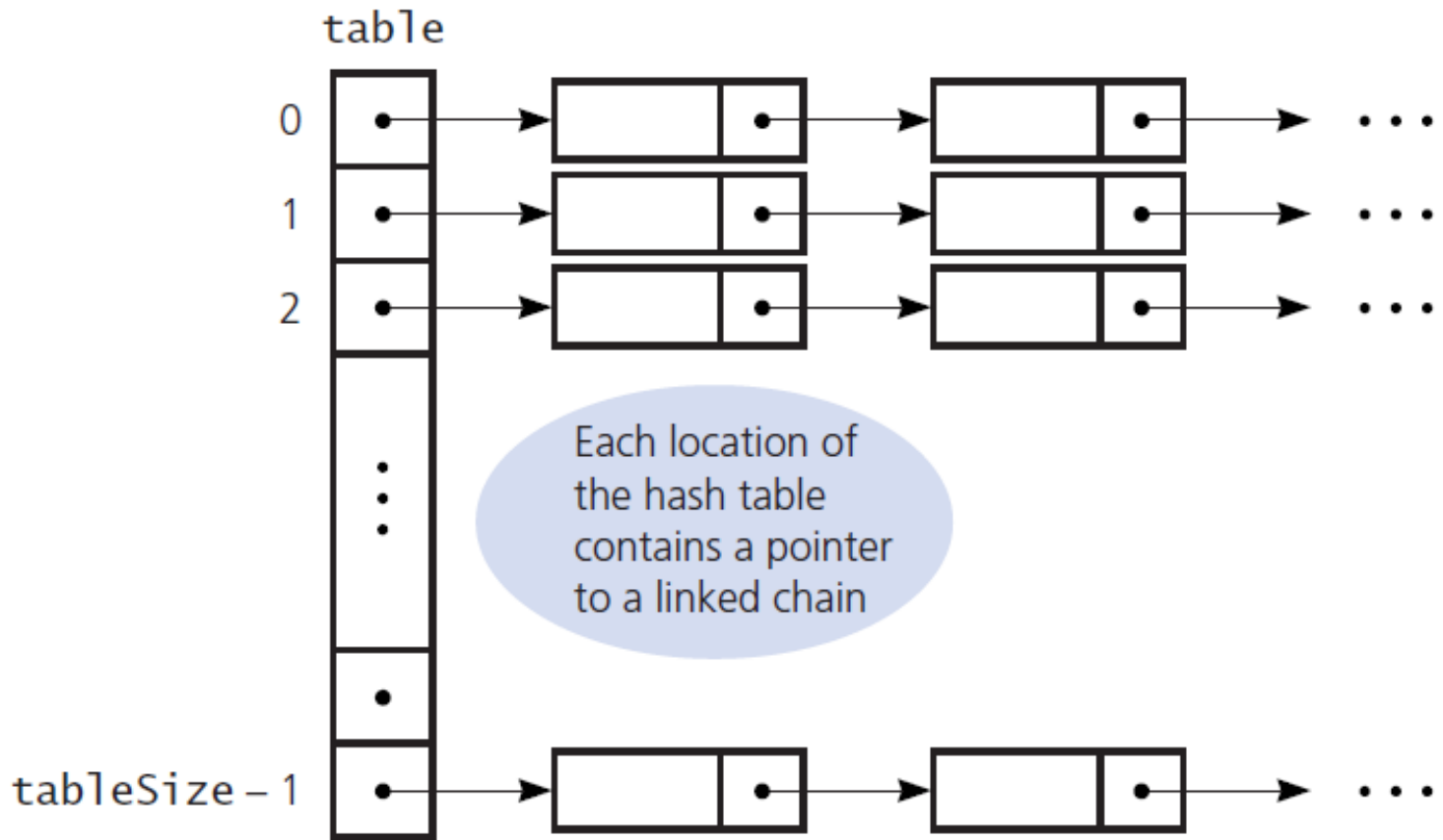
$$\begin{aligned} i=2: h(14,2) &= (h_1(14) + 2 h_2(14)) \bmod 13 \\ &= (1 + 8) \bmod 13 = 9 \end{aligned}$$

| | |
|----|----|
| 0 | |
| 1 | 79 |
| 2 | |
| 3 | |
| 4 | 69 |
| 5 | 98 |
| 6 | |
| 7 | 72 |
| 8 | |
| 9 | 14 |
| 10 | |
| 11 | 50 |
| 12 | |



Resolving Collisions with Open Addressing

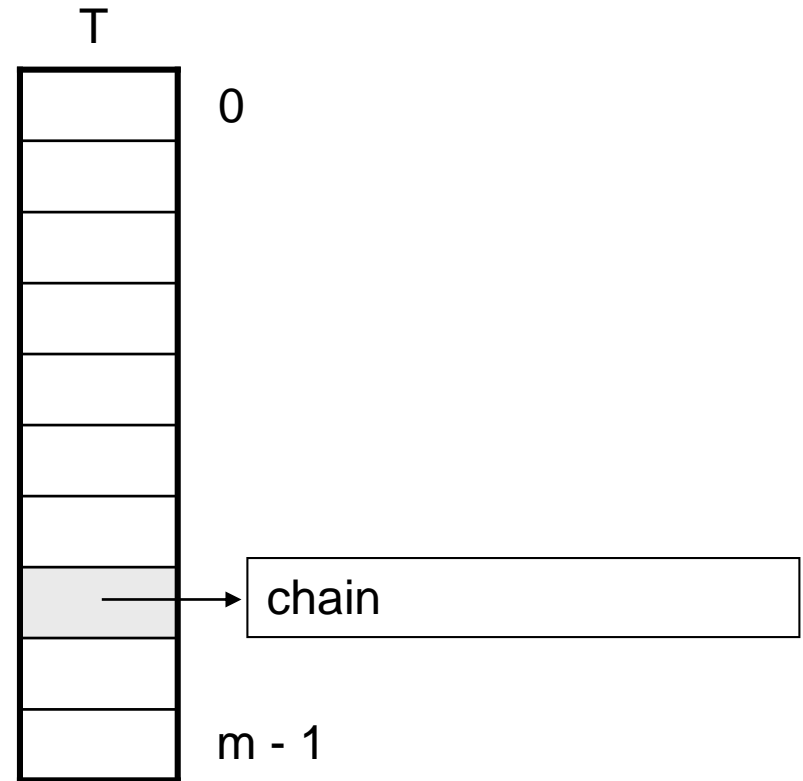
- Approach 2: Resolving collisions by restructuring the hash table
 - Buckets
 - Separate chaining



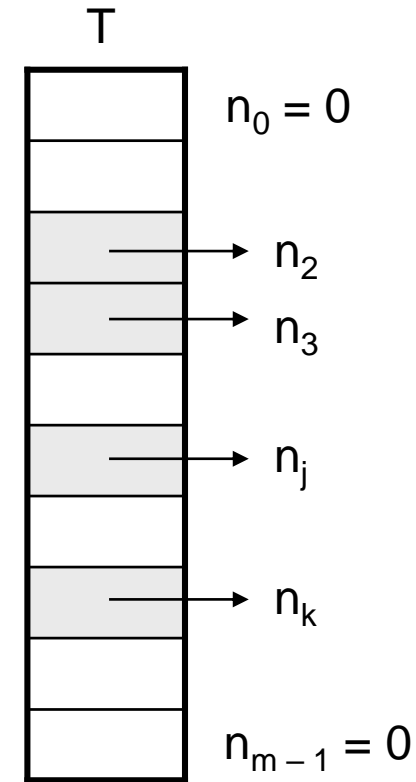
- Separate chaining

- How to choose the size of the hash table **m**?
 - Small enough to avoid wasting space
 - Large enough to avoid many collisions and keep linked-lists short
 - Typically 1/5 or 1/10 of the total number of elements
- Should we use sorted or unsorted linked lists?
 - Unsorted
 - Insert is fast
 - Can easily remove the most recently inserted elements

- How long does it take to search for an element with a given key?
 - Worst case:
 - All n keys hash to the same slot
- then $O(n)$ plus time to compute the hash function



- It depends on how well the hash function distributes the n keys among the m slots
 - Under the following assumptions:
 - (1) $n = O(m)$
 - (2) any given element is **equally likely** to hash into any of the m slotsi.e., simple uniform hashing property
- then $\rightarrow O(1)$ time plus time to compute the hash function



N

The Efficiency of Hashing

- Load factor measures how full a hash table is

$$\alpha = \frac{\text{Current number of table entries}}{\text{tableSize}}$$

- Unsuccessful searches
 - Generally require more time than successful
- Do not let the hash table get too full

- Linear probing – average number of comparisons

$$\frac{1}{2} \left[1 + \frac{1}{1 - \alpha} \right] \quad \text{for a successful search, and}$$

$$\frac{1}{2} \left[1 + \frac{1}{(1 - \alpha)^2} \right] \quad \text{for an unsuccessful search}$$

- Quadratic probing and double hashing – average number of comparisons

$$\frac{-\log_e(1 - \alpha)}{\alpha}$$

for a successful search,

$$\frac{1}{1 - \alpha}$$

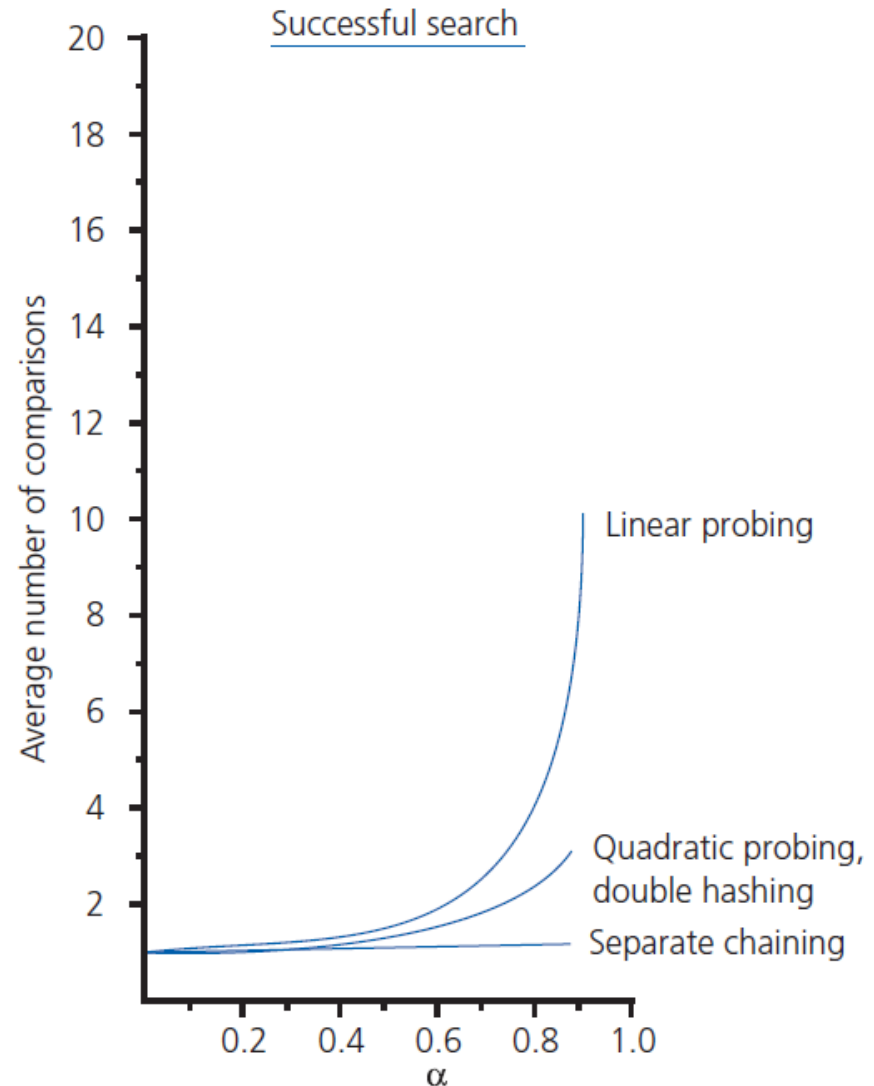
for an unsuccessful search

- Efficiency of the retrieval and removal operations under the separate-chaining approach

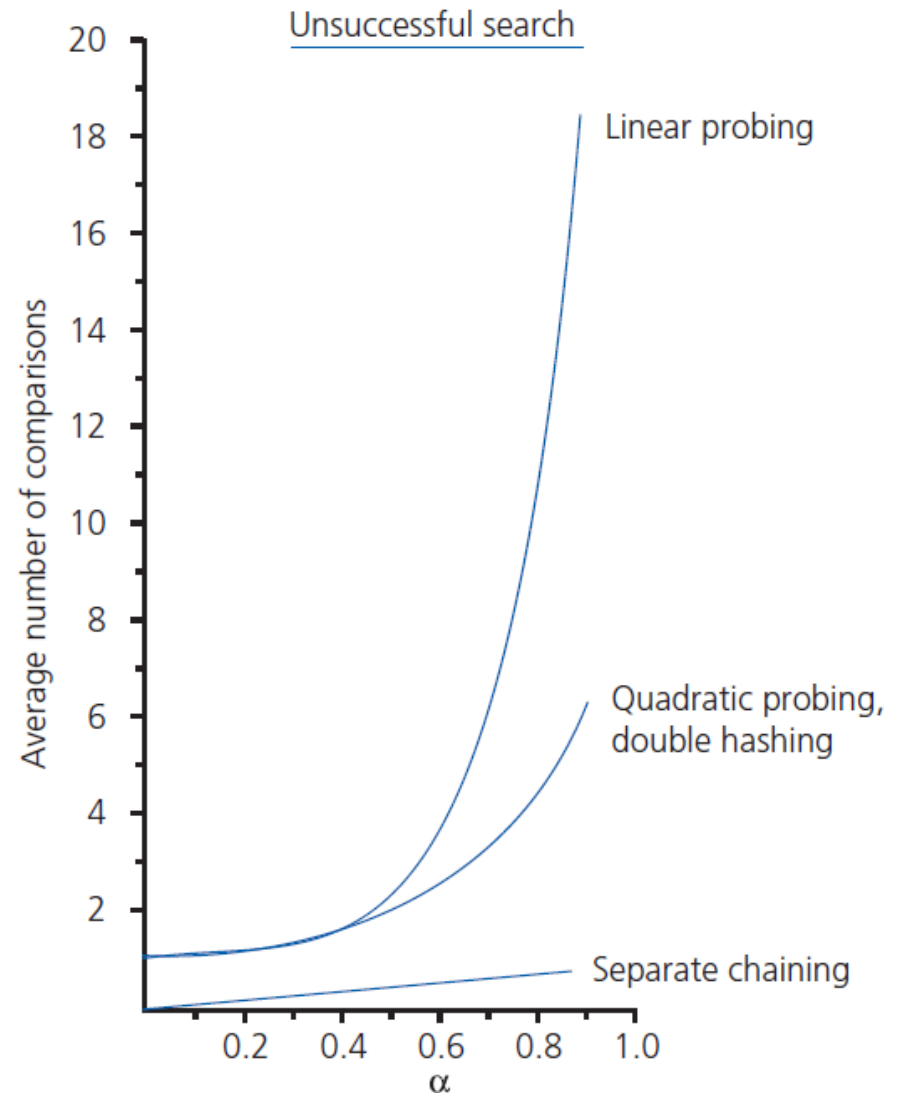
$$1 + \frac{\alpha}{2} \quad \text{for a successful search,}$$

$$\alpha \quad \text{for an unsuccessful search}$$

- The relative efficiency of four collision-resolution methods



- The relative efficiency of four collision-resolution methods





What Constitutes a Good Hash Function?

- Is hash function easy and fast to compute?
- Does hash function scatter data evenly throughout hash table?
- How well does hash function scatter random data?
- How well does hash function scatter *non-random* data?

- Entries hashed into `table[i]` and `table[i+1]` have no ordering relationship
- Hashing does not support well traversing a dictionary in sorted order
 - Generally better to use a search tree
- In external storage possible to see
 - Hashing implementation of `getValue`
 - And search-tree for ordered operations simultaneously



Using Hashing, Separate Chaining to Implement ADT Dictionary



- A dictionary entry when separate chaining is used

```
1  /** A class of entry objects for a hashing implementation of the
2      ADT dictionary.
3      @file HashedEntry.h */
4
5  #ifndef HASHED_ENTRY_
6  #define HASHED_ENTRY_
7
8  #include "Entry.h"
9
10 template<class KeyType, class ValueType>
11 class HashedEntry : public Entry<KeyType, ValueType>
12 {
13 private:
14     std::shared_ptr<HashedEntry<KeyType, ValueType>> nextPtr;
15 public:
```

- The class **HashedEntry**


```
14     std::shared_ptr<HashedEntry<KeyType, ValueType>> nextPtr;  
15 public:  
16     HashedEntry();  
17     HashedEntry(KeyType searchKey, ValueType newValue);  
18     HashedEntry(KeyType searchKey, ValueType newValue,  
19                 std::shared_ptr<HashedEntry<KeyType, ValueType>> nextEntryPtr);  
20  
21     void setNext(std::shared_ptr<HashedEntry<KeyType, ValueType>>  
22                 nextEntryPtr nextEntryPtr);  
23     auto getNext() const;  
24 }; // end HashedEntry  
25  
26 #include "HashedEntry.cpp"  
27 #endif
```

- The class **HashedEntry**