

# Jacqueline Song

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EDUCATION	<p><b>The Cooper Union for the Advancement of Science and Art</b>, New York, NY</p> <ul style="list-style-type: none"><li>• <i>Bachelor of Engineering</i>, Mechanical Engineering, expected May 2015</li><li>• Full-tuition scholarship</li><li>• <i>Cumulative GPA: 3.7/4.0</i></li></ul> <p style="text-align: right;">2011-2015</p>
EXPERIENCE	<p><b>Hardware Engineer</b> at Matterport, Mountain View, CA <span style="float: right;">Summer 2014</span></p> <ul style="list-style-type: none"><li>• Relieved camera production bottleneck by implementing electromechanical system to automate labor-intensive calibration movements.</li><li>• Specified imaging hardware and developed evaluation procedures for candidate components.</li><li>• Supported engineering activities including hardware troubleshooting, reverse engineering, and process documentation.</li></ul> <p><b>Mechanical Design Engineer</b> at Social Bicycles, New York, NY <span style="float: right;">Spring 2014</span></p> <ul style="list-style-type: none"><li>• Supported design team in redesign of bicycle locking mechanism for improved manufacturability and ease of use.</li><li>• Prepared electronics housing components for injection molding using SolidWorks.</li></ul> <p><b>Teaching Assistant</b> for Design and Prototyping, Prof. Eric Lima, The Cooper Union <span style="float: right;">2013-2014</span></p> <ul style="list-style-type: none"><li>• Developed machine design project that gave students hands-on experience in designing, building, and troubleshooting electromechanical systems.</li><li>• Guided students through prototyping tasks in laser cutting, machining, and injection molding.</li></ul> <p><b>Electromechanical Engineer</b> at Carson Optical, Hauppauge, NY <span style="float: right;">Summer 2013</span></p> <ul style="list-style-type: none"><li>• Designed and prototyped novel optical and electromechanical systems, working independently and in teams; developed one consumer product from concept to manufacture.</li><li>• Optimized injection-molded parts in SolidWorks for manufacture and assembly.</li></ul> <p><b>Consultant</b> for “LURE,” MaDora Frey, New York, NY <span style="float: right;">2012–2013</span></p> <ul style="list-style-type: none"><li>• Advised client from concept to manufacturing of kinetic sculptures for gallery exhibition.</li><li>• Prototyped sculpture systems, including aesthetic mechanisms and microcontroller electronics.</li></ul>
PROJECTS	<p><b>Curved Layer Carbon Fiber Reinforced Polymer FDM</b> <span style="float: right;">Senior Design, 2014–2015</span></p> <ul style="list-style-type: none"><li>• Develop manufacturing process and Fused Deposition Modeling (FDM) printing method for continuous carbon fiber reinforced thermoplastic filament.</li><li>• Optimize carbon fiber orientation in printed parts using finite element analysis.</li><li>• Modify existing 3D printing toolchains to print curved-layer parts using a 6-DOF robot arm.</li></ul> <p><b>Notchmatic</b> <span style="float: right;">Design Elements, Fall 2014</span></p> <ul style="list-style-type: none"><li>• Lead the design and build effort on workpiece fixturing subassembly for an industrial tube notching machine; collaborate with teammates on cost, scheduling, and systems integration.</li><li>• Develop safety, usage, and installation manuals for future shop use.</li></ul> <p><b>3D-printed injection molds</b> <span style="float: right;">Independent, 2013</span></p> <ul style="list-style-type: none"><li>• Demonstrated the viability of 3D-printed injection molds as a prototyping tool.</li><li>• Explored effect on molded part quality of different mold print systems, settings, and materials.</li></ul> <p><b>Arduino Robot Pac-Man</b> <span style="float: right;">Microcontroller Projects, 2012</span></p> <ul style="list-style-type: none"><li>• Designed and implemented Arduino controlled autonomous and remote-controlled robots and a robot-sensing dot matrix maze based on the classic arcade game.</li></ul> <p><b>Gumball Machine</b> <span style="float: right;">Principles of Design, 2011</span></p> <ul style="list-style-type: none"><li>• Designed and built an Arduino controlled electromechanical gumball dispenser game featuring interactive mechanical paths, including a 3-axis crane arm and binary logic puzzle.</li></ul>
SKILLS	<p><b>Computer:</b> proficient in SolidWorks, C++, ANSYS, MATLAB, AutoCAD, LabView, Python, Linux, Microsoft Office, LaTeX, CSS, HTML, Javascript, Arduino, Adobe CS.</p> <p><b>Manufacturing processes:</b> design for injection molding, machining, welding, casting, sewing.</p> <p><b>Mechatronics:</b> motor and actuator control; digital logic design; PCB design; sensor integration; microcontroller-based control systems.</p> <p><b>Machine shop:</b> comfortable with TIG welding, mill, lathe, drill press, rotary tools, hand tools.</p>