

SONGYANG HAN

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EDUCATION

University of Connecticut (UConn) **Storrs, USA**
PhD in *Computer Science and Engineering* Supervisor: Prof. [Fei Miao](#) *Aug. 2018-May 2023(expected)*

- GPA: **4.0/4.0**
- Core courses: *Algorithms, Formal Methods, Machine Learning, Advanced Computer Network, Optimal & Model Predictive Control, Deep Reinforcement Learning, Cryptography*

Shanghai Jiao Tong University (SJTU) **Shanghai, China**
([University of Michigan-SJTU Joint Institute](#)) *Sep. 2015-Mar. 2018*

M.S. in *Electrical and Computer Engineering* Supervisor: Prof. [Chengbin Ma](#)

- GPA: **3.96/4.0** **Ranking: 1/20**
- Core courses: *Game Theory, Data Mining, Engineering Optimization, Methods of Applied Mathematics I, Probability and Random Process, Mechatronic Systems Design, New Energy System*

Nanjing University (NJU) **Nanjing, China**
B.Eng. in *Automation* *Sep. 2011-Jun. 2015*

- GPA: **4.44/5.0** **Ranking: 1/34**
- Core courses: *Principles of Automatic Control, Modern Cybernetics, Operations Research, C++, Data Structure, Database, Computer Vision, Computer Network, Signals and Systems, Digital Signal Processing, Circuit Analysis, Analog Circuit, Digital Circuit, Principles of Microcomputer*

RESEARCH EXPERIENCE

University of Connecticut
Research Assistant, supervised by Prof. Fei Miao *Aug. 2018-Present*

- **Key words:** multi-agent reinforcement learning (MARL), safe MARL, robust MARL, game theory
- Designed an algorithm to exploit the advantages raised by the extended sensing capability of connected autonomous vehicles (CAVs) through beneficial information sharing.
- Analyzed quantum key distribution protocols through a game theoretic framework to show improved noise tolerance and secure communication rate assuming adversaries are “rational”.
- Designed an integrated information sharing and multi-agent reinforcement learning framework for the behavior planning of connected autonomous vehicles to improve traffic efficiency and safety.
- Studied the fundamental properties of the robust multi-agent RL problem under adversarial state perturbations. We define the concept of a robust agent policy and prove its existence.
- Designed a stable and efficient reward reallocation algorithm to motivate cooperation for multi-agent reinforcement learning assuming all agents are self-interested.

Reinforcement Learning for Autonomous Driving

Research Internship, Baidu USA Apollo team *May 2020-Dec. 2020*

- Summarized existing reinforcement learning methods and the state-of-art deep learning methods used in autonomous driving.
- Wrote a design document for single and multi-agent RL, distributed learning, algorithm architecture and interface, and a prototype design.
- Built a prototype platform to train and test RL algorithms for autonomous vehicles in the Apollo platform and Amazon Web Services (AWS).

Energy Management of Battery/Super Capacitor Hybrid System

Team Leader, collaborating with [Nippon Chemi-Con Corporation](#), Japan

Dec. 2016-Apr. 2017

- Improved the energy management approach of a hybrid energy storage system in a novel topology.
- Improved the system efficiency without the help from special alternator like MAZDA i-ELoop.

[Dynamic Systems Control Laboratory](#), UM-SJTU Joint Institute

Research Assistant, supervised by Prof. Chengbin Ma

Sep. 2015-Mar. 2018

- **Key words:** game theory, optimization, microgrid, energy management, electric vehicle
- Designed a flexible energy management approach to handle the uncertainties of weather and sizing in an isolated microgrid, which would not be influenced dramatically by different weather conditions.
- Designed and fabricated high efficient bidirectional DC/DC converters to conduct and validate energy management approaches in a downsized system.
- Built a hardware testbed to study reconfigurable energy systems.

3D Laser Processing Based on Computer Vision

May 2013-Dec. 2014

Team Leader, sponsored by National Undergraduate Training Programs for Innovation and Entrepreneurship

- Combined a camera and structured light to model a feather in 3D, which rebuilt the feather's shape.
- Successfully extracted the feather stroke with image processing methods, including Hough transform.

PUBLICATIONS

- **Songyang Han**, Shanglin Zhou, Jiangwei Wang, Lynn Pepin, Caiwen Ding, Jie Fu, Fei Miao. *A Multi-Agent Reinforcement Learning Approach For Safe and Efficient Behavior Planning Of Connected Autonomous Vehicles*. In IEEE Transactions on Intelligent Transportation Systems. (Under review, available on arXiv:2003.04371)
- **Songyang Han**, Sanbao Su, Sihong He, Shuo Han, Haizhao Wang, Fei Miao. *What is the Solution for State-Adversarial Multi-Agent Reinforcement*. Available on arXiv:2212.02705. (Under review)
- Sanbao Su, Yiming Li, Sihong He, **Songyang Han**, Chen Feng, Caiwen Ding, Fei Miao. *Uncertainty Quantification of Collaborative Detection for Self-Driving*. In 2023 IEEE International Conference on Robotics and Automation (ICRA). (Under review, available on arXiv:2209.08162)
- Zhili Zhang, **Songyang Han**, Jiangwei Wang, Fei Miao. *Spatial-Temporal-Aware Safe Multi-Agent Reinforcement Learning of Connected Autonomous Vehicles in Challenging Scenarios*. In 2023 IEEE International Conference on Robotics and Automation (ICRA). (Under review, available on arXiv:2210.02300)
- Jiangwei Wang, Lili Su, **Songyang Han**, Dongjin Song, Fei Miao. *Towards Safe Autonomy in Hybrid Traffic: The Power of Information Sharing in Detecting Abnormal Human Drivers Behaviors*. In the AI4TS workshop at the 31st International Joint Conference On Artificial Intelligence (IJCAI), Messe Wien, Vienna, Austria, 2022.
- Yukun Yuan, Meiyi Ma, **Songyang Han**, Desheng Zhang, Fei Miao, John Stankovic, Shan Lin. *DeResolver: A Decentralized Negotiation and Conflict Resolution Framework for Smart City Services*. In ACM Transactions on Cyber-Physical Systems, 2022.
- **Songyang Han**, He Wang, Sanbao Su, Yuanyuan Shi, Fei Miao. *Stable and Efficient Shapley Value-Based Reward Reallocation for Multi-Agent Reinforcement Learning of Autonomous Vehicles*. In 2022 IEEE International Conference on Robotics and Automation (ICRA), Philadelphia, USA, May 2022.
- Yukun Yuan, Meiyi Ma, **Songyang Han**, Desheng Zhang, Fei Miao, John Stankovic, Shan Lin. *DeResolver: A Decentralized Negotiation and Conflict Resolution Framework for Smart City Services*. In 12th ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS),

Nashville, USA, May 2021. (**Best paper award**)

- **Songyang Han**, Walter O. Krawec, Fei Miao. *A Game Theoretic Security Framework for Quantum Cryptography: Performance Analysis and Application*. Quantum Information Processing 19.10 (2020): 1-24.
- **Songyang Han**, Jie Fu, Fei Miao. *Exploiting Beneficial Information Sharing Among Autonomous Vehicles*. In 2019 IEEE 58th Conference on Decision and Control (CDC), Nice, France, Dec. 2019.
- Amro Alsabbagh, Dongxiang Yan, **Songyang Han**, Yandong Wang, Chengbin Ma. *Behaviour-based distributed energy management for charging EVs in photovoltaic charging station*. In 2018 IEEE International Conference on Industrial Electronics for Sustainable Energy Systems (IESES), Hamilton, New Zealand, Jan. 2018.
- Shuangke Liu, Ming Liu, **Songyang Han**, Xinen Zhu, Chengbin Ma. *Tunable Class-E2 DC-DC Converter with High Efficiency and Stable Output Power for 6.78 MHz Wireless Power Transfer*. IEEE Transactions on Power Electronics 33.8 (2018): 6877-6886.
- Amro Alsabbagh, He Yin, **Songyang Han**, Chengbin Ma. *Two-stage distributed energy management for islanded DC microgrid with EV parking lot*. In 2017 43rd Annual Conference of the IEEE Industrial Electronics Society (IECON), Beijing, China, Oct. 2017.
- **Songyang Han**, He Yin, Amro Alsabbagh, Chengbin Ma. *A Flexible Distributed Approach to Energy Management of an Isolated Microgrid*. In 2017 IEEE 26th International Symposium on Industrial Electronics (ISIE), Edinburgh, Scotland, June 2017.
- Yandong Wang, He Yin, **Songyang Han**, Amro Alsabbagh, Chengbin Ma. *A novel switched capacitor circuit for battery cell balancing speed improvement*. In 2017 IEEE 26th International Symposium on Industrial Electronics (ISIE), Edinburgh, Scotland, June 2017.
- **Songyang Han**, Xianzhong Zhou, Chunlin Chen. *Path Planning for Multi-robot Systems Using PSO and Critical Path Schedule Method*. In 2016 IEEE 13th International Conference on Networking, Sensing, and Control (ICNSC), Mexico City, Mexico, April 2016.

SKILLS

Standardized Tests: TOEFL iBT: 107, GRE: V152 + Q170 + AW3.5

Programming: Python, C/C++, MATLAB, LabVIEW, SQL

Tools: Deep reinforcement learning, LaTeX, Linux, Git, CARLA, NI myRIO, NI CompactRIO, Arduino, PIC, Altium Designer, Multisim, AutoCAD

HONOR & AWARDS

- GE Fellowship of Excellence, University of Connecticut **Aug. 2022**
- Predoctoral Research Fellowship, University of Connecticut **May 2022**
- First Place Award, 8th Annual Graduate Poster Competition, University of Connecticut **Mar. 2022**
- Predoctoral Research Fellowship, University of Connecticut **May 2021**
- Best Paper Award, 12th ACM/IEEE International Conference on Cyber-Physical Systems **May 2021**
- Cigna Graduate Fellowship, University of Connecticut **Aug. 2020**
- Predoctoral Research Fellowship, University of Connecticut **May 2020**
- Postgraduate Academic Excellence Scholarship, Shanghai Jiao Tong University **Oct. 2016**
- Guanghua Scholarship, Shanghai Jiao Tong University **Dec. 2015**
- Outstanding Graduates of Nanjing University **May 2015**
- National Endeavor Fellowship, 3 times, Nanjing University **Dec. 2012-Dec. 2014**
- Outstanding Winner of Educational Robot Competition in China, Chinese Association for Artificial Intelligence **Nov. 2014**
- Meritorious Winner of 2014 MCM, the Consortium for Mathematics and Its Applications **May 2014**

- Outstanding Students of Nanjing University, 2 times, Nanjing University *Nov. 2012-Nov. 2013*

SERVICE EXPERIENCE

Reviewer,

- IEEE Transactions on Industrial Informatics
- IEEE Transactions on Neural Networks and Learning Systems
- The 43rd Annual Conference of the IEEE Industrial Electronics Society (IECON 2017)
- The 58th Conference on Decision and Control (CDC 2019)
- The 2020 American Control Conference (ACC 2020)
- The 59th Conference on Decision and Control (CDC 2020)
- The 2021 American Control Conference (ACC 2021)
- 2020 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2020)
- 2021 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2021)
- 2022 IEEE International Conference on Robotics and Automation (ICRA 2022)
- 2023 IEEE International Conference on Robotics and Automation (ICRA 2023)