

Homework Set 3, CPSC 8420, Spring 2022

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Problem 1

Data points were centered when they were dealt with PCA and LDA. The projection lines crossed the center of the points. If centered data points were scatter-plotted, the projection lines should have crossed the origin.

```
# -*- coding: utf-8 -*-
"""
Created on Mon Mar 21 15:12:32 2022

@author: Henry Song
"""

import numpy as np
import matplotlib.pyplot as plt
from numpy.linalg import svd
from numpy.linalg import inv
data_raw = np.array([[1,3],[2,5],[3,4],[4,3],[5,2],[5,1]])
data = data_raw - np.mean(data_raw,axis=0)
center = np.mean(data_raw,axis=0)
u,s,_ = svd(data.T.dot(data))
phi11 = u[0,0];phi21 = u[1,0]
line_x = np.linspace(np.min(data_raw[:,0]),np.max(data_raw[:,0]),10)#+center[0]
line_y = (line_x-center[0])*phi21/phi11+center[1]
plt.scatter(data_raw[:,0],data_raw[:,1])

cluster = {0:data_raw[:4],1:data_raw[4:]}
centroids = [np.mean(cluster[i],axis=0)[...,None] for i in range(2)]
Sb = (centroids[0]-centroids[1]).dot((centroids[0]-centroids[1]).T)
Sw = 0
for i in range(2):
    for j in range(len(cluster[i])):
        diff = cluster[i][j][...,None]-centroids[i]
        Sw = Sw + diff.dot(diff.T)
u2,s2,v2 = svd(inv(Sw).dot(Sb))
w = u2[:,0]
line_y1 = (line_x-center[0])*w[1]/w[0]+center[1]
plt.plot(line_x,line_y,label='PCA')
plt.plot(line_x,line_y1,label='LDA')
plt.xlabel('X coordinate')
```

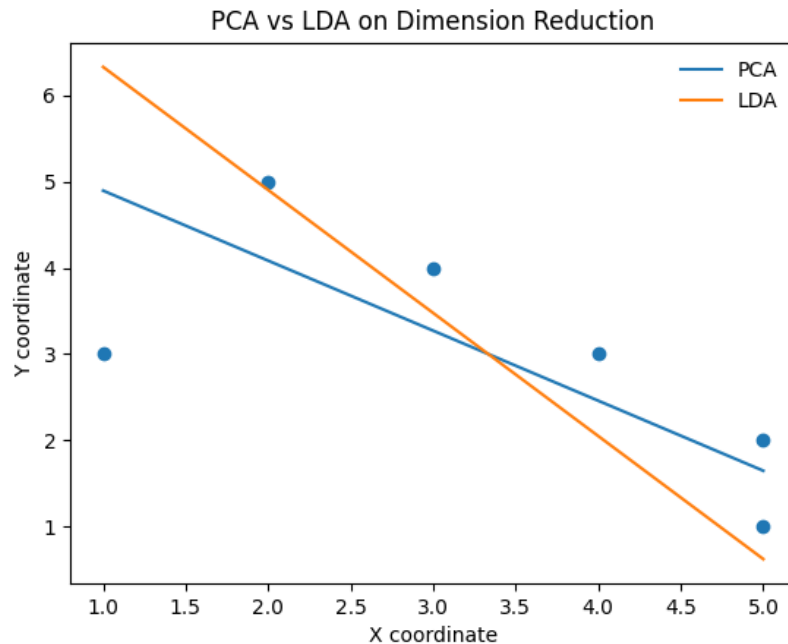


Figure 1: Dimension Reduction using PCA and LDA

```
plt.ylabel('Y coordinate')
plt.legend(frameon=False)
plt.title('PCA vs LDA on Dimension Reduction')
plt.savefig('prob1.png')
```

Problem 2

Given positive data-set $\{\{1, 1\}, \{2, 2\}, \{2, 3\}\}$, as well as negative data-set $\{\{3, 2\}, \{3, 3\}, \{4, 4\}\}$, please determine the decision boundary when leveraging k -NN where $k = 1$ and $k = 3$ respectively. Boundaries were determined using different k .

```
# -*- coding: utf-8 -*-
"""
```

Created on Sat Mar 26 18:05:06 2022

```
@author: Henry Song
"""
```

```
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.colors import ListedColormap
from sklearn import neighbors
cmap_light = ListedColormap(['#FFAAAA', '#AAAAFF'])
data_set = np.array([[1, 1], [2, 2], [2, 3], [3, 2], [3, 3], [4, 4]])
y = np.array([0, 0, 0, 1, 1, 1])
```

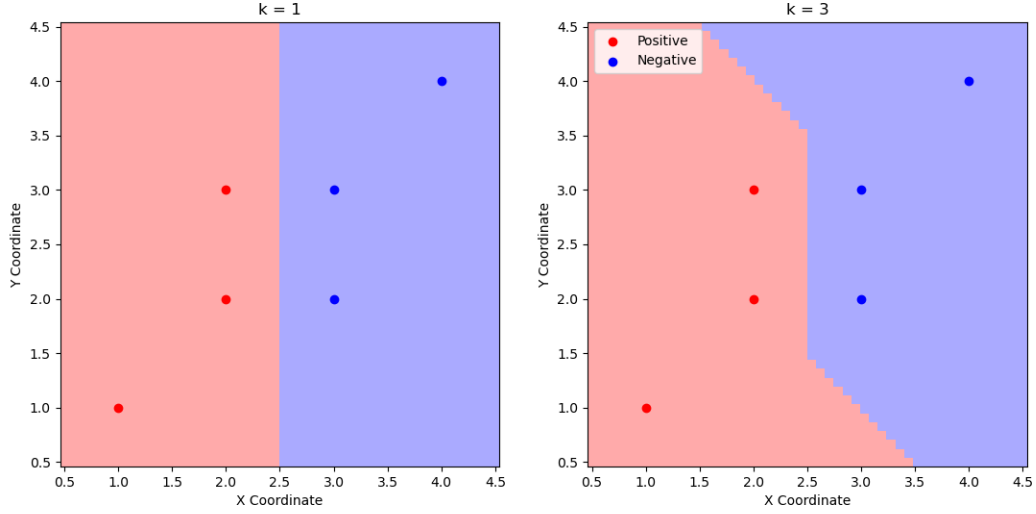


Figure 2: $K - NN$ Boundary Determination with Different k

```

num = 50
x_range = np.linspace(np.min(data_set[:,0])-0.5, np.max(data_set[:,0])+0.5,num)
y_range = np.linspace(np.min(data_set[:,1])-0.5, np.max(data_set[:,1])+0.5,num)
X,Y = np.meshgrid(x_range,y_range)
K = [1,3]
labels = ['Positive','Negative']
fig, axes = plt.subplots(figsize=(13,6),nrows=1,ncols=2)
for k,ax in zip(K,axes):
    knn = neighbors.KNeighborsClassifier(k)
    knn.fit(data_set,y)
    Z = knn.predict(np.c_[X.ravel(),Y.ravel()])
    Z = Z.reshape(X.shape)
    ax.pcolormesh(X,Y,Z,cmap=cmap_light)
    ax.scatter(data_set[:,0],data_set[:,1],c='#FF0000',label='Positive')
    ax.scatter(data_set[:,0],data_set[:,1],c='#0000FF',label='Negative')
    ax.set_xlabel('X Coordinate')
    ax.set_ylabel('Y Coordinate')
    ax.set_title('k = '+str(k))
axes[1].legend(loc='upper left')
plt.savefig('prob2.png')

```

Problem 3

Given SPD matrices X, Y, Z , now please follow the idea/method used in LDA/PCA to find the best solution to:

$$\begin{aligned}
 & \underbrace{\arg \max}_{a,b} a^T Z b \\
 & s.t. \quad a^T X a = 1, \quad b^T Y b = 1
 \end{aligned} \tag{1}$$

Applying Lagrange multiplier to this optimization problem, Eq.1 is equivalent to

$$\min_{a,b,\lambda,\beta} -a^T Z b + \frac{1}{2} \lambda (a^T X a - 1) + \frac{1}{2} \beta (b^T Y b - 1) \quad (2)$$

Let $f = -a^T Z b + \lambda (a^T X a - 1) + \beta (b^T Y b - 1)$, we can get condition-constrained equations by taking partial derivative and make differential equations equal to zero, respected to a, b, λ, β , respectively.

$$\frac{\partial f}{\partial a} = -Z b + \lambda S_X a = -Z b + \lambda X a = 0 \quad (3)$$

$$\frac{\partial f}{\partial b} = -Z^T a + \beta S_Y b = -Z^T a + \beta Y b = 0 \quad (4)$$

Where S_X and S_Y are the symetric part of the X and Y , respectively. In general, $S_A = \frac{1}{2} (A + A^T)$. In the case of a SPD matrix $A, S_A = A$. Besides, other two derivatives will lead to constrains, as shown below.

$$\begin{aligned} \frac{\partial f}{\partial \lambda} &= a^T X a - 1 = 0 \\ \frac{\partial f}{\partial \beta} &= b^T Y b - 1 = 0 \end{aligned}$$

If we manipulate Eq.3 with left multiply a^T , we will get $a^T Z b = \lambda a^T X a = \lambda$. Similarly, we can also obtain $b^T Z a = \beta$ from Eq.4. Therefore, λ and β are equivalent. In order to get $\max a^T Z b$, we need to maximize either λ or β (λ used in the later context). We can obtain the expression of b in terms of a using Eq.3, $b = \lambda Z^{-1} X a$, and plug it into Eq.4. Consequently, we can get

$$\begin{aligned} Z a &= \lambda \beta Y Z^{-1} X a \\ X^{-1} Z Y^{-1} Z a &= \lambda^2 a \end{aligned} \quad (5)$$

Similarly, we can express a in terms of b from Eq.4 and plug it into Eq.4 to get the equation for b .

$$Y^{-1} Z X^{-1} Z b = \lambda^2 b \quad (6)$$

Eq.5 and 6 are nothing but eigenvalue problems for matrices $\mathbf{A} = X^{-1} Z Y^{-1} Z$ and $\mathbf{B} = Y^{-1} Z X^{-1} Z$, respectively.

Besides, we can notice that matrices \mathbf{A} and \mathbf{B} can be expressed as

$$\begin{aligned} \mathbf{A} &= \mathbf{U} \mathbf{M} \\ \mathbf{B} &= \mathbf{M} \mathbf{U} \end{aligned}$$

where $\mathbf{U} = X^{-1} Z$ and $\mathbf{M} = Y^{-1} Z$. In the eigenvalue decomposition on A and B , we know that $U \mathbf{M}$ and $\mathbf{M} \mathbf{U}$ have the same eigenvalues. Therefore, Eq.5 and Eq.6 can result in the same eigenvalues for λ^2 from $[W_A, V_A] = \text{eig}(A)$ and $[W_B, V_B] = \text{eig}(B)$. Meanwhile, matrices X , Y and Z are all SPD, leading to the eigenvalues for either A or B are non-negative real numbers. We can simply sort the eigenvalues and select the eigenvectors corresponding to largest eigenvalue for a and b from W_A and W_B , respectively. As a result, $a^T Z b$ can be maximized with the constrains $a^T X a = 1$ and $b^T Y b = 1$.