Introduction To Searching

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Linear Search

```
Algorithm sequentialsearch(int list[] , int end , int target )
i= 0
while(i < end && list[i] != target)
i++
if(i == end)
return -1
else
return i
```

Best Case	Average Case	Worst Case
T(n) = c	T(n) = n/2	T(n) = n
= O(1)	= O(n)	= O(n)

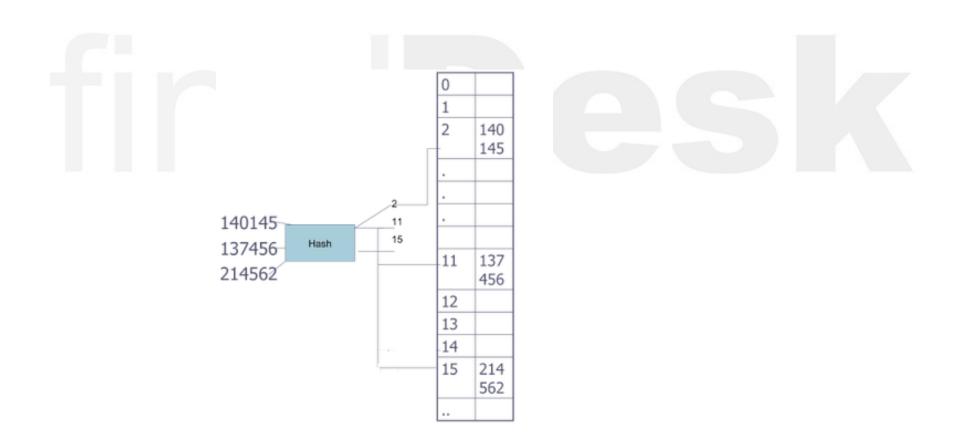
Binary Search

```
Algorithm binarysearch(int list[], int left, int right, int target)
  while ( left <= right )
     mid = (left + right) / 2
     if( list[ mid ] == target )
       return mid
   else if( list[mid] < target )</pre>
        left = mid + 1
     else
       right = mid - 1
  return -1
```

Best Case	Average Case	Worst Case
T(n) = c	T(n) = log n	T(n) = log n
= O(1)	= O(log n)	= O(n)

Hashed Search

Hashing is a key-to-address mapping process.



Hashing Methods

- Direct
- Subtraction
- Modulo-division: address = key % listsize
 (listsize must be chosen a prime no)
- Digit-Extraction
- Mid-square
- Folding: Fold Shift and Fold Boundary
- Rotation
- PseudoRandom

Collision

- Keys collide to same home address
- Solution
 - Allocate new address in Prime Area
 - Allocate new address in Overflow Area

Collision Resolution

- Open Addressing
 - Linear Probe
 - Quadratic Probe
- Link List
- Bucket

Linear Probe

Address = (Key + Probe) % Size

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Add key 10

Key = 10 % 8

__

= 2

Add key 5

Key = 5 % 8

= 5

Quadratic Probe

• Address = (Key + Probe²) % Size

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Add key 18

1

Probe 0:

2

= (18+0) % 10

3

= 8

4

Add Key 89

5

= 9

6

8

9

Add key 21

= (89 + 0) % 10

= 1

21

18

Add key 58

Probe 0:

= (58+0) % 10

= 8

Probe 1:

= (58 + 1) % 10

= 9

Probe 2:

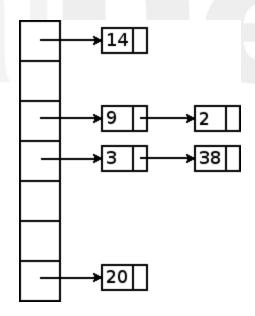
= (58 + 4) % 10

= 2

Best Case	Average Case	Worst Case
T(n) = c	T(n) = c	T(n) = n
= O(1)	= O(1)	= O(n)

Link List

- Chain the keys that collide at same location
- The collided Keys occupy overflow area instead of prime area



Best Case	Average Case	Worst Case
T(n) = c	T(n) = c	T(n) = c
= O(1)	= O(1)	= O(1)

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