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CG & MI

Center of Gravity \rightarrow CG is that point through which the whole body weight acts.

The CG of a body doesn't change for any position of the body.

Centroid of a plane lamina is the point through which the total area must be considered to be concentrated.

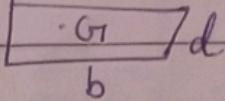
$$\bar{x} = \frac{a_1x_1 + a_2x_2 + a_3x_3 + \dots}{a_1 + a_2 + a_3 + \dots} = \frac{\sum a_i x_i}{\sum a_i} = \frac{\sum a_i x_i}{\sum a_i}$$

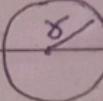
$$\bar{y} = \frac{a_1y_1 + a_2y_2 + a_3y_3 + \dots}{a_1 + a_2 + a_3 + \dots} = \frac{\sum a_i y_i}{\sum a_i} = (\bar{x}, \bar{y})$$

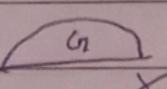
most ask

figure

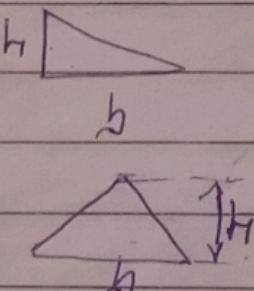
Symbol

Imp. \rightarrow ① Rectangle  $G(\frac{b}{2}, \frac{d}{2})$

② Circle  $G(r, r)$

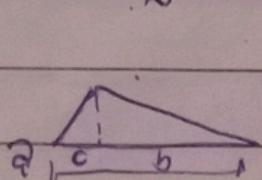
③ Semicircle  $G(\frac{4r}{3\pi}, \frac{4r}{3\pi})$

④ Quarter Circle  $G(\frac{4r}{3\pi}, \frac{4r}{3\pi})$

⑤ Triangle 

$$G(\frac{b}{3}, \frac{h}{3})$$

$$G(\frac{b}{2}, \frac{h}{3})$$



$$G(\frac{c+b}{3}, \frac{h}{3})$$

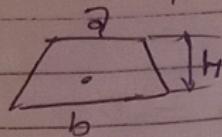
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$$I = f d^2$$

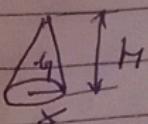
$$(I = \frac{1}{12} \pi r^4)$$

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(6)
Trapezium

Symbol



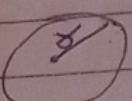
$$G_I \left(\frac{b}{2}, \frac{h}{2} \right) \left(\frac{b+2a}{b+a} \right)$$

(7)Right Circular
Solid Cone

$$G_I \left(\frac{r}{4}, \frac{h}{4} \right)$$

(8)

Sphere



$$G_I (r, r)$$

(9)

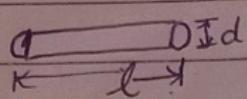
Hemisphere



$$\left(r, \frac{3r}{8} \right)$$

(10)

Uniform rod



$$G_I \left(\frac{l}{2}, \frac{d}{2} \right)$$

Moment of Inertia :-

MI is the second moment of a plane lamina or mass to the desired reference access axis

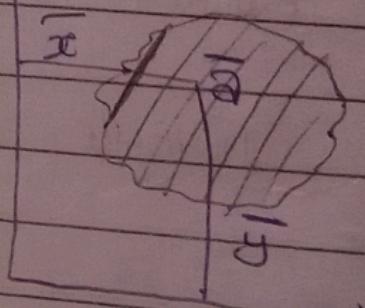
$$M = f x d x d$$

$$I = f x d^2$$

$$I = f x^2$$

$$\leftarrow x = a y^2$$

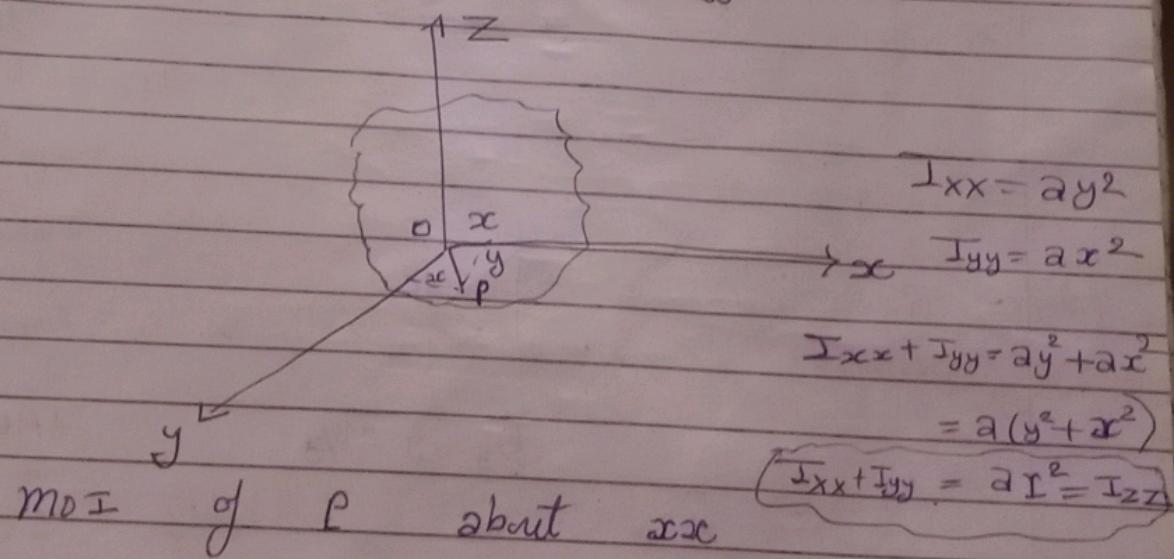
$$I_{yy} = a \bar{x}^2$$



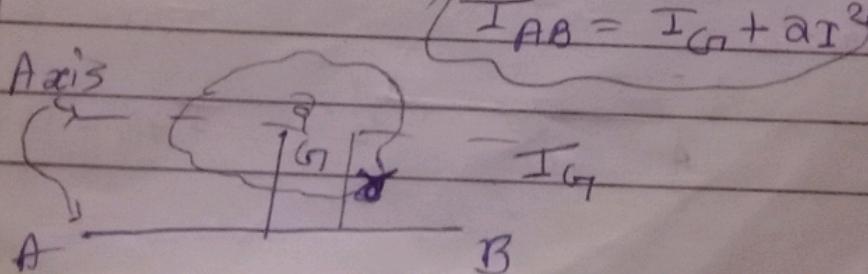
$$I_{xx} = a \bar{y}^2$$

$$I_{yy} = a \bar{x}^2$$

① Theorem
 Perpendicular axis theorem states if I_{xx} and I_{yy} be the moment of inertia of a plane section about two perpendicular axes meeting at O, then the MoI about an axis \perp to the plane and passing through the intersection of I_{xx} and I_{yy} is equal to the sum of I_{xx} and I_{yy} mathematically
 $I_{zz} = I_{xx} + I_{yy}$



② Parallel axis theorem It states if the MoI of a plane area about an axis passing through center of gravity is denoted by I_G and the MoI of the area about a parallel axis AB given by



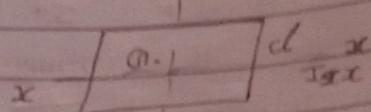
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formula

Lamina

Diagram



$$I_{\text{axx}} = \frac{bd^3}{12}$$

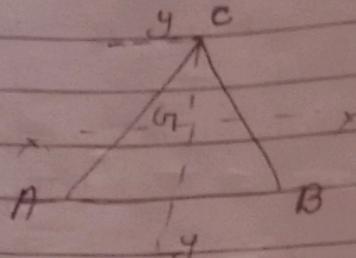
① Rectangle

$$I_{\text{ayy}} = \frac{db^3}{12}$$

$$I_{\text{yy}}$$

$$I_{\text{Gxx}} = \frac{bh^3}{36}$$

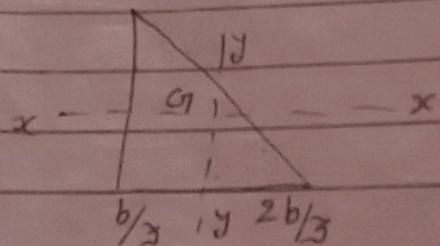
② Triangle



$$I_{\text{Gyy}} = \frac{hb^3}{36}$$

$$I_{\text{AB}} = \frac{bh^3}{12}$$

$$I_C = \frac{bh^3}{4}$$

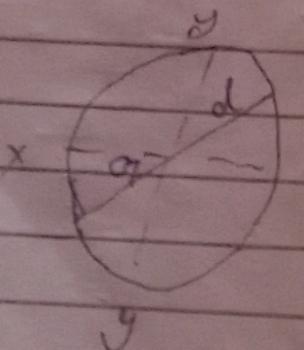
③ Right angle
triangle

$$I_{\text{Gxx}} = \frac{bh^3}{36}$$

$$I_{\text{Gyy}} = \frac{hb^3}{36}$$

$$I_{\text{AB}} = \frac{hb^3}{12}$$

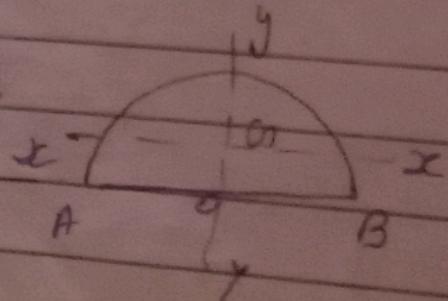
$$I_C = \frac{bh^3}{4}$$



Circle

$$I_{\text{axx}} = \frac{\pi d^4}{64} = I_{\text{ayy}}$$

Semi circle



$$I_{\text{Gxx}} = 0.11 \pi r^4$$

$$I_{\text{Gyy}} = 0.393 \pi r^4$$

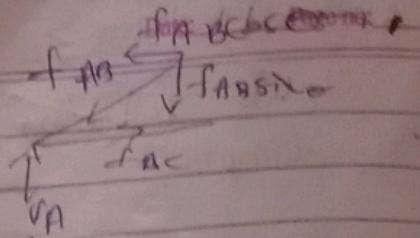
$$I_{\text{AB}} = 0.393 \pi r^4$$

$$N_A + V_f = 80 \quad (1)$$

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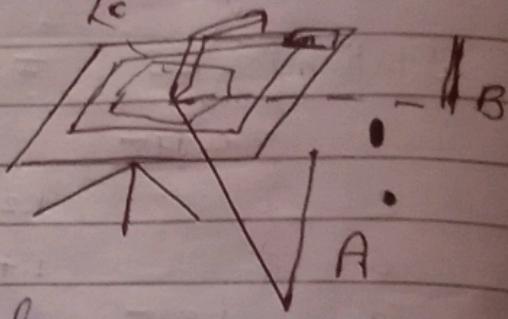
$$5ux9 + 3ox8 - V_{rx}11 = 0$$

$$\sqrt{3} = ?$$



Planetable Surveying

It is the type of Surveying in which both observation & recording is done simultaneously. It can be adopted only when survey is to be carried out in small and scattered areas.



Instrument Use

- ① Plane table, ② Adgeate
 - ③ plumping fork, ④ compass, ⑤ Ranging rod
 - ⑥ Plane sheet, ⑦ staf, ⑧ Reveal tube
 - ⑨ tricode

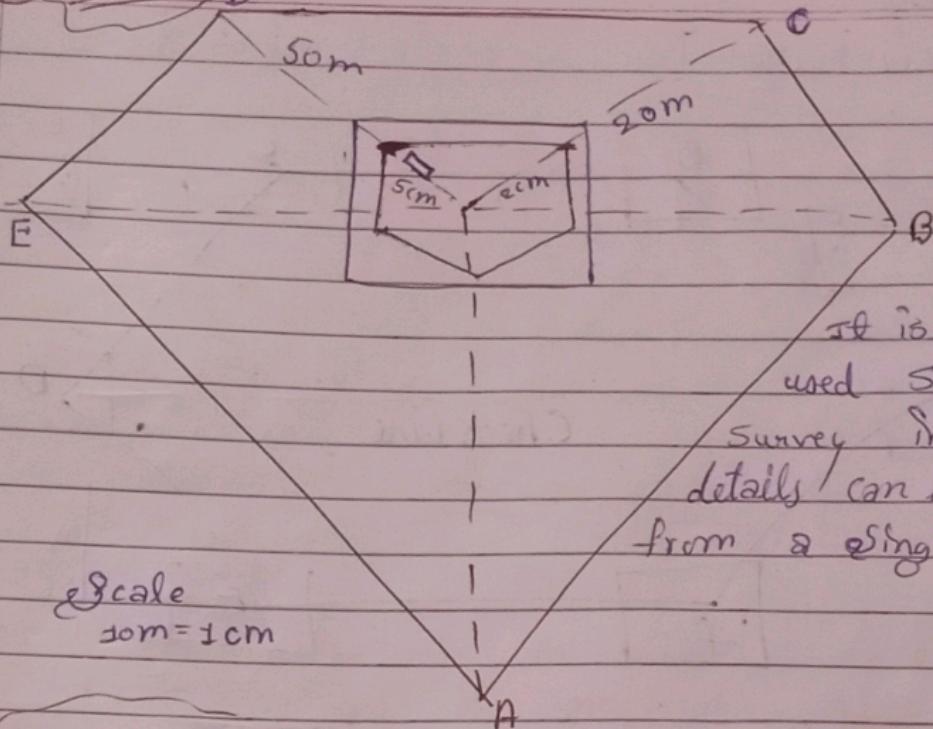
Method involve in plane table Survey

- ① Radiation, ② Intersektion, ③ trahier sing
 - ④ Resepson

First two mtd are used to collect the details of the object & later to mtd's are used to locating the position of the plane table station over the drawing sheet.

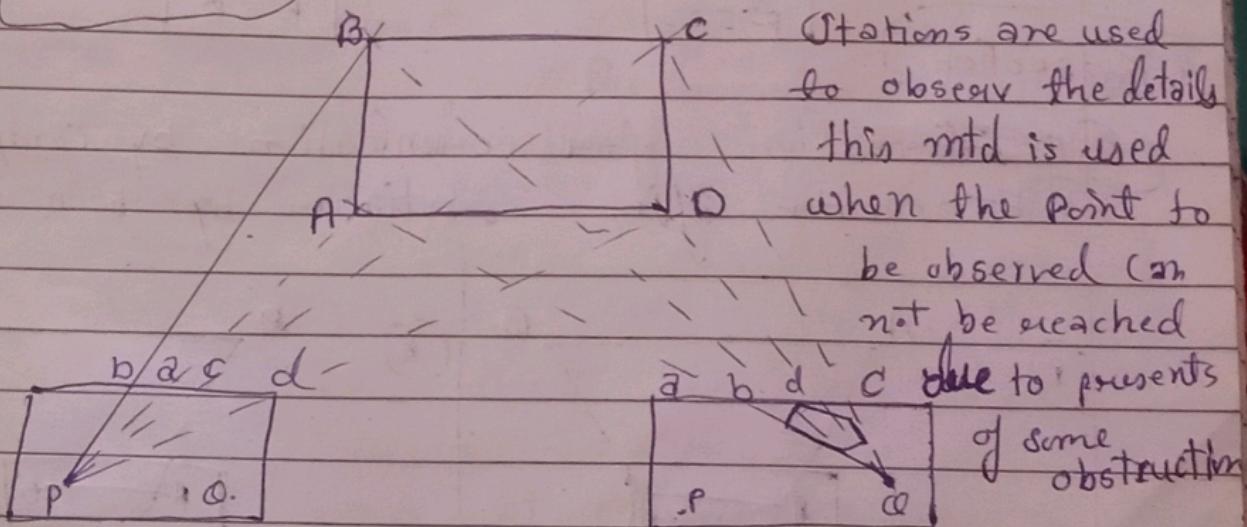
① Radiation

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It is generally used Small area Survey in which details can be collected from a single station

② Intersection



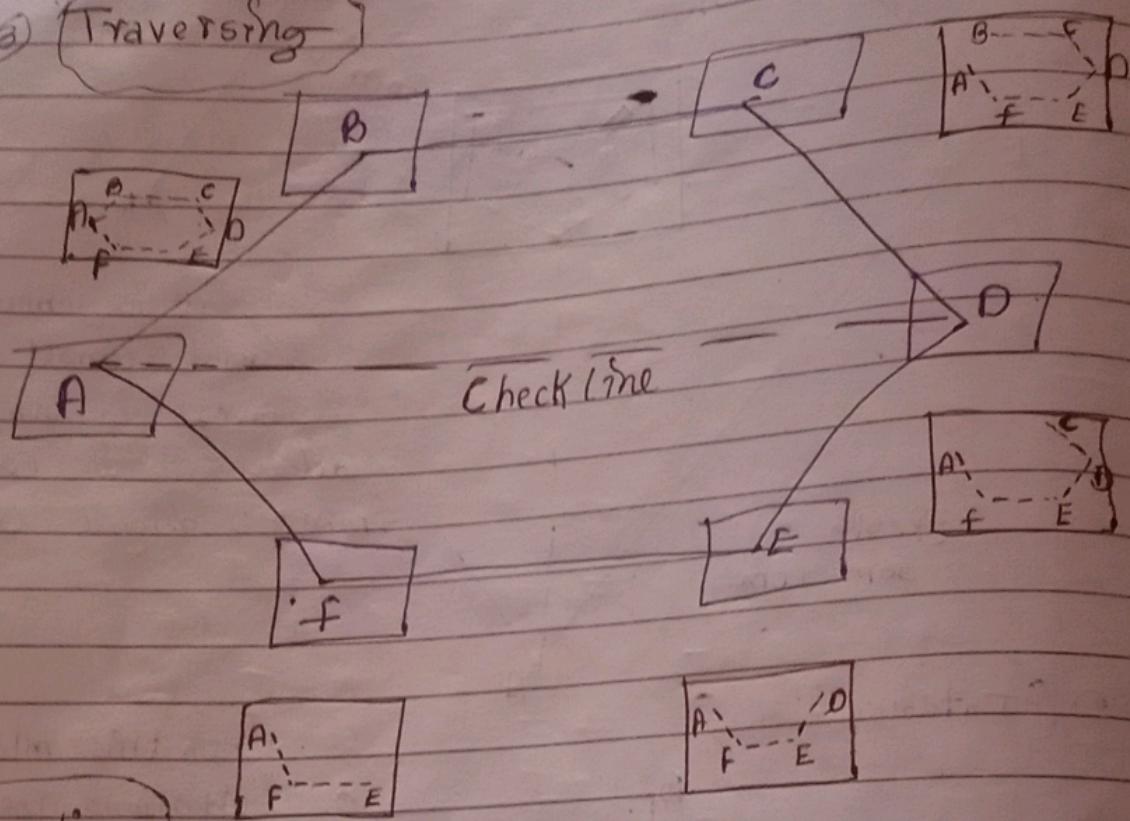
In this mtd two stations are used to observe the details this mtd is used when the point to be observed can not be reached

due to presence of some obstruction

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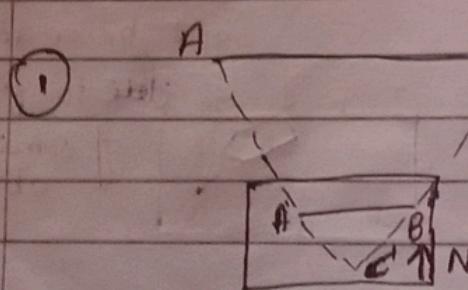
(3) Traversing



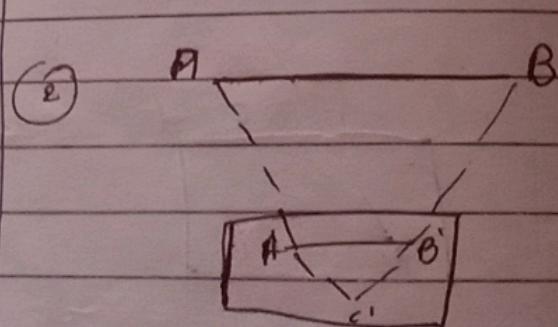
(Resection)

① Resection after orientation by compass

② Resection after orientation by back sighting

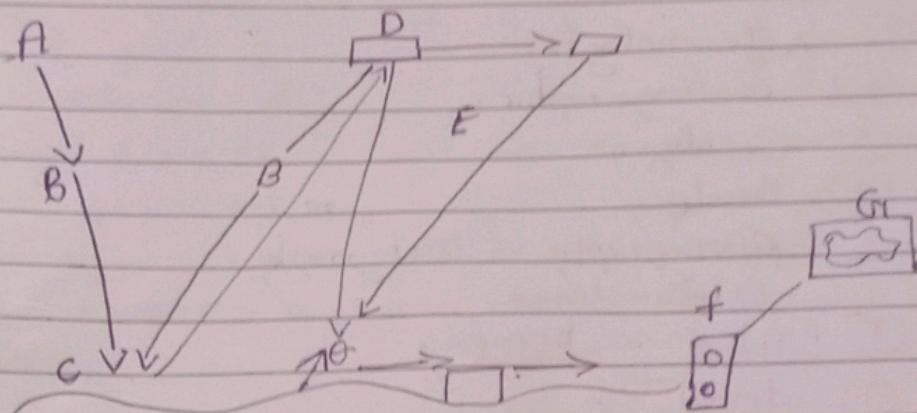


→ orientation is done by
Compass and Resection
is done after orientation
of Plane table.



→ Assume any point of the
table 'c'' and orient
the table after
the draw the sectors
from 'P'

d= Remote Sensing:



Remote Sensing is to collect data on dangerous or inaccessible area its application includes monitoring deforestation, effect of climate change, damped sounding of Pastal & portion desk. Collection of data for military purpose It is also replaces costly & slow data collection on the ground and to insuring the areas that area or object are not distrib.

A → Energy or radiation

B → Radiation at the atmosphere

C → Interaction with the target

D → Recording of Energy by the sensor

E → transmission, reception & processing

F → Interpretation and analysis

G → Application

Application of Remote Sensing

- ① Meteorological for
- ② Cartography
- ③ Geology
- ④ Biology (map)
- ⑤ Photography & Cartography
(Localized area)
- ⑥ Agriculture boundary
- ⑦ Forest
- ⑧ Botany
- ⑨ Hydrology
- ⑩ Disaster management
- ⑪ Planning Application
- ⑫ Oil & gas rental Expansion
- ⑬ Mining
- ⑭ Urban
- ⑮ Climate
- ⑯ Space programming