# Posterior predictive checks

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Here we simulate 100 observations from a quadratic regression  $Y_i = \mu_i + \epsilon_i, i = 1, \dots, 100$ . Here,  $\mu_i = \beta_0 + \beta_1 X_i + \beta_2 X_i^2$  and  $\epsilon_i \sim \text{Normal}(0, \sigma^2)$ .

## 1. Simulate data

```
rm(list = ls())

n <- 100

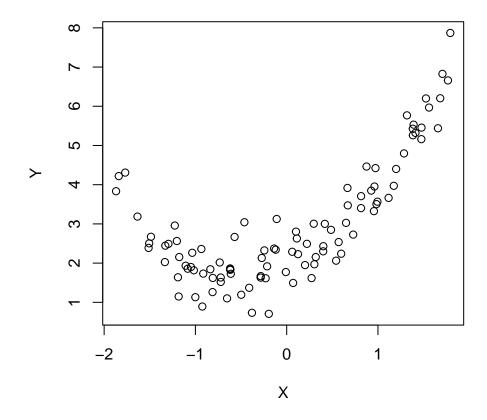
set.seed(100)

X <- runif(n)
X <- as.vector(scale(X))

beta <- c(2, 1, 1) # (beta0, beta1, beta2)
sigmaSq <- 0.25

Y <- beta[1] + beta[2] * X + beta[3] * X^2 + rnorm(n, mean = 0, sd = sqrt(sigmaSq))

plot(X, Y)</pre>
```



Now, we want to compare the models  $\mathcal{M}_1: \mu_i = \beta_0 + \beta_1 X_i$  versus  $\mathcal{M}_2: \mu_i = \beta_0 + \beta_1 X_i + \beta_2 X_i^2$ . Posterior predictive checks are performed for the following test statistics:

$$D_1(Y) = \min(Y_1, \dots, Y_n) \ D_2(Y) = mean(Y_1, \dots, Y_n) \ D_3(Y) = \max(Y_1, \dots, Y_n)$$

# 2. Specify two competing models:

Model 1 has non-informative Gaussian priors  $\beta_0, \beta_1 \sim \text{Normal}(0, 100^2)$ .

Model 2 has non-informative Gaussian priors  $\beta_0, \beta_1, \beta_2 \sim \text{Normal}(0, 100^2)$ .

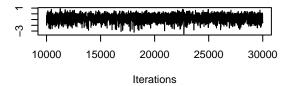
#### library(rjags)

- ## Loading required package: coda
- ## Linked to JAGS 4.3.0
- ## Loaded modules: basemod, bugs

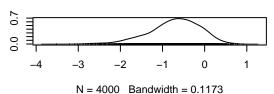
```
# M1
model_string1 <- "model{</pre>
 # Likelihood
 for(i in 1:n){
   Y[i] ~ dnorm(mu[i], inv.var)
   mu[i] <- beta0 + beta1 * X[i]</pre>
 #Priors
 beta0 ~ dnorm(0, 0.00001)
 beta1 ~ dnorm(0, 0.00001)
 inv.var ~ dgamma(0.01, 0.01)
 # Posterior preditive checks
 for(i in 1:n){
   Y1[i] ~ dnorm(mu[i], inv.var)
 D[1] <- min(Y1[])</pre>
 D[2] <- mean(Y1[])</pre>
 D[3] \leftarrow max(Y1[])
}"
 # M2
model_string2 <- "model{</pre>
 # Likelihood
 for(i in 1:n){
   Y[i] ~ dnorm(mu[i], inv.var)
   mu[i] <- beta0 + beta1 * X[i] + beta2 * X[i]^2</pre>
 #Priors
 beta0 ~ dnorm(0, 0.00001)
 beta1 ~ dnorm(0, 0.00001)
 beta2 ~ dnorm(0, 0.00001)
 inv.var ~ dgamma(0.01, 0.01)
 # Posterior preditive checks
 for(i in 1:n){
   Y2[i] ~ dnorm(mu[i], inv.var)
 D[1] \leftarrow min(Y2[])
 D[2] \leftarrow mean(Y2[])
 D[3] <- max(Y2[])
}"
```

#### 3. Fit the two models

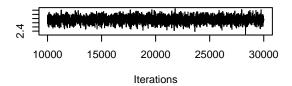
#### Trace of D[1]



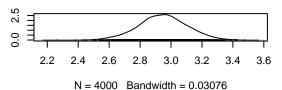
#### Density of D[1]



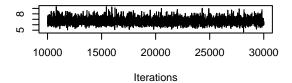
#### Trace of D[2]



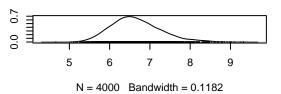
#### Density of D[2]

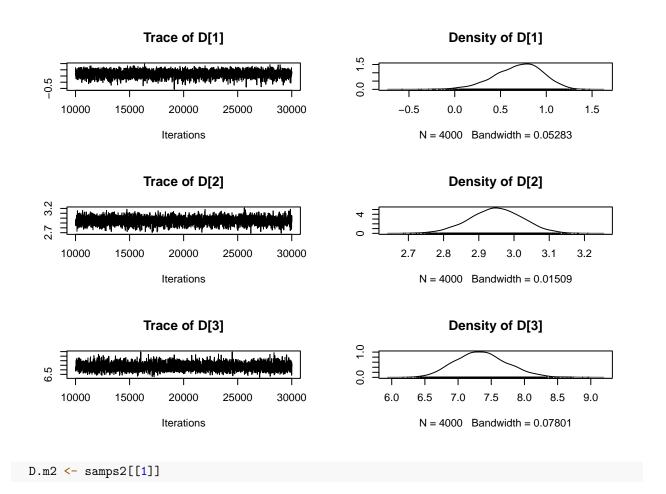


#### Trace of D[3]



### Density of D[3]

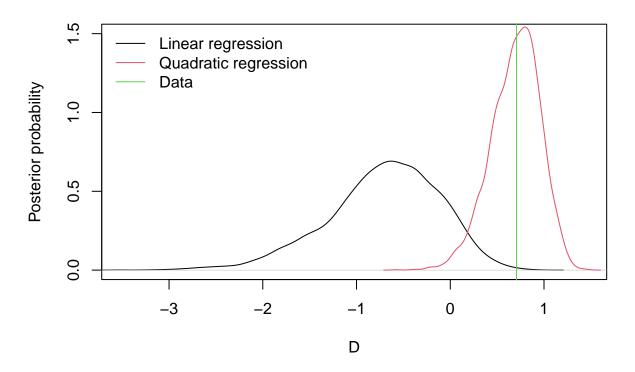




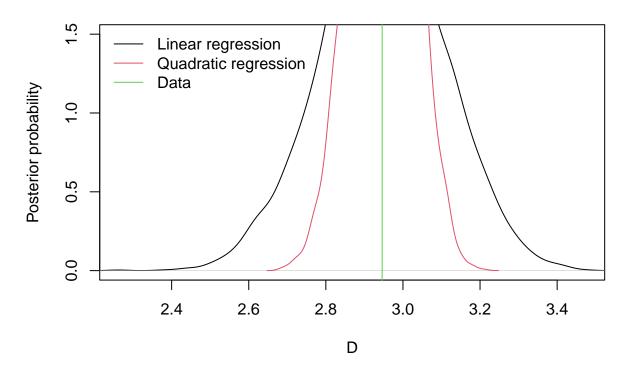
## 4. Compute the Bayesian p-values

```
pval2[j] \leftarrow mean(D.m2[ , j] > D0[j])}
```

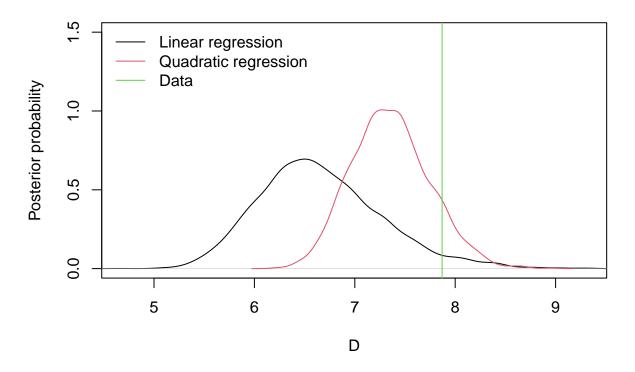
# Min Y



# Mean Y



## Max Y



## 5. Results

```
pval1
```

## Min Y Mean Y Max Y ## 0.00125 0.50500 0.03975

### pval2

## Min Y Mean Y Max Y ## 0.51375 0.51450 0.10300