

HW5 ECE542

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Q1

HW5

$$Q1. \text{ let } \vec{x}_2 = (x_{2,1}, x_{2,2}, x_{2,3})^T$$

$$\vec{x}_3 = (x_{3,1}, x_{3,2}, x_{3,3})^T$$

$$\text{We have } \vec{x}_1^T A \vec{x}_2 = 0$$

$$(1, 0, 0) \begin{pmatrix} 1.0 & 0.5 & 0.1 \\ 0.5 & 1.0 & 0.5 \\ 0.1 & 0.5 & 1.0 \end{pmatrix} \begin{pmatrix} x_{2,1} \\ x_{2,2} \\ x_{2,3} \end{pmatrix} = 0$$

$$\therefore x_{2,1} + 0.5 x_{2,2} + 0.1 x_{2,3} = 0$$

Therefore, one possible value for \vec{x}_2 is

$$\vec{x}_2 = (-1, 2, 0)^T$$

For \vec{x}_3 , we have

$$\begin{cases} \vec{x}_1^T A \vec{x}_3 = 0 \\ \vec{x}_2^T A \vec{x}_3 = 0 \end{cases}$$

$$\therefore \begin{cases} x_{3,1} + 0.5 x_{3,2} + 0.1 x_{3,3} = 0 \\ 1.5 x_{3,2} + 0.9 x_{3,3} = 0 \end{cases}$$

$$\therefore \vec{x}_3 = (1, -3, 5)^T$$

\therefore One solution for A-conjugate given $\vec{x}_1 = (1, 0, 0)^T$

is

$$\begin{cases} \vec{x}_2 = (-1, 2, 0)^T \\ \vec{x}_3 = (1, -3, 5)^T \end{cases}$$

Figure 1: Q1

Q2

data set setting:

dist = 5.0, width = 6, radius = 10

train samples = 2000, test samples = 2000

experiments

- training method
 - gradient descent
 - conjugate descent
 - Levenverg-Marquart
- hidden neuron numbers
 - 5
 - 20

Result

- testing error
- training time (both epochs and real clock time)
- Repeat measure time = 5
- convergence criterion

MSE	Epochs	training time	convergence reason
parameters	hidden numbers = 5	trainFcn = trainlm	
4.152e-07	10	0.484s	performance goal reached
3.214e-07	6	0.141s	performance goal reached
3.196e-07	11	0.188s	performance goal reached
8.428e-08	11	0.188s	performance goal reached
4.041e-07	9	0.141s	performance goal reached
parameters	hidden numbers = 5	trainFcn = traingd	
1.069e-03	10000	16.328s	maximum epoch reached
1.194e-03	10000	15.484s	maximum epoch reached
9.472e-04	10000	15.922s	maximum epoch reached
1.074e-03	10000	16.266s	maximum epoch reached
1.337e-03	10000	16.172s	maximum epoch reached
parameters	hidden numbers = 5	trainFcn = traincgf	
7.757e-05	110	0.563s	minimum step size reached
1.113e-04	109	0.531s	minimum step size reached
1.515e-04	89	0.531s	minimum step size reached
2.348e-05	232	1.094s	minimum step size reached
5.258e-05	85	0.500s	minimum step size reached

Table 1: hidden number =5

MSE	Epochs	training time	convergence reason
parameters	hidden numbers = 20	trainFcn = trainlm	
6.104e-07	33	0.500s	performance goal reached
4.686e-07	16	0.313s	performance goal reached
4.248e-07	6	0.188s	performance goal reached
5.168e-07	6	0.172s	performance goal reached
6.978e-08	8	0.188s	performance goal reached
parameters	hidden numbers = 20	trainFcn = traingd	
3.254e-04	10000	19.953s	maximum epoch reached
3.179e-04	10000	20.719s	maximum epoch reached
3.429e-04	10000	20.438s	maximum epoch reached
4.101e-04	10000	20.656s	maximum epoch reached
4.013e-04	10000	19.984s	maximum epoch reached
parameters	hidden numbers = 20	trainFcn = traincgf	
4.070e-05	487	2.766s	minimum step size reached
3.727e-05	568	3.156s	minimum step size reached
5.127e-05	490	2.641s	minimum step size reached
5.668e-05	487	2.719s	minimum step size reached
1.226e-05	465	2.656s	minimum step size reached

Table 2: hidden number =20

Q3

Repeat measure number = 5

(a)

hidden number = 5

plot:

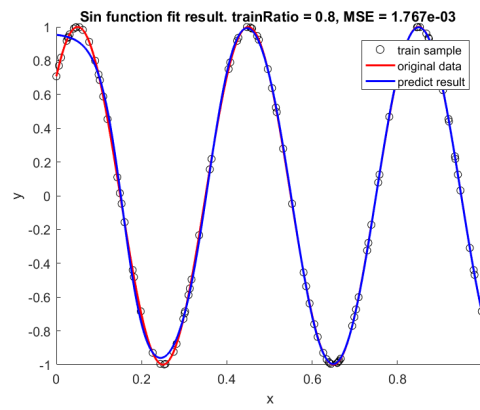


Figure 2: hidden number = 5, trainFcn = trainlm

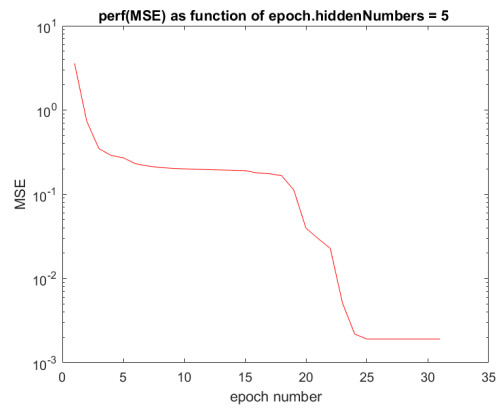


Figure 3: hidden number = 5, trainFcn = trainlm

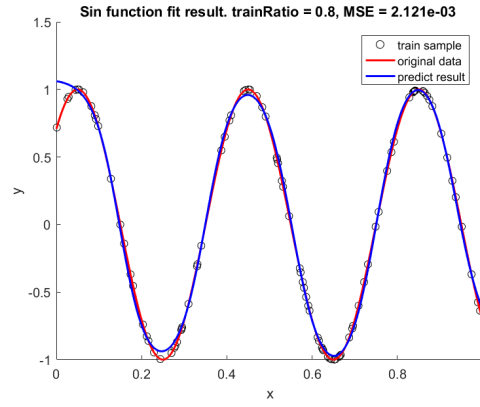


Figure 4: hidden number =5, trainFcn = traingd

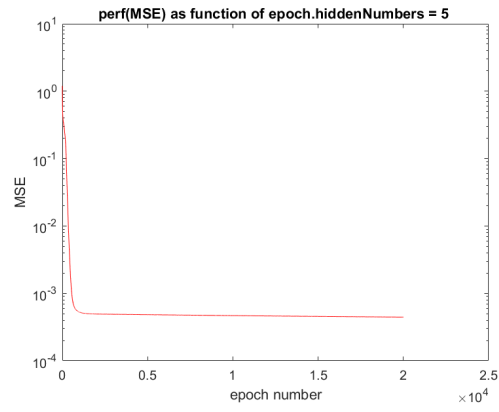


Figure 5: hidden number =5, trainFcn = traingd

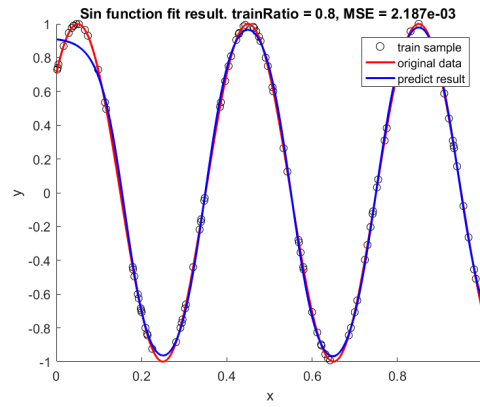


Figure 6: hidden number =5, trainFcn = traingcf

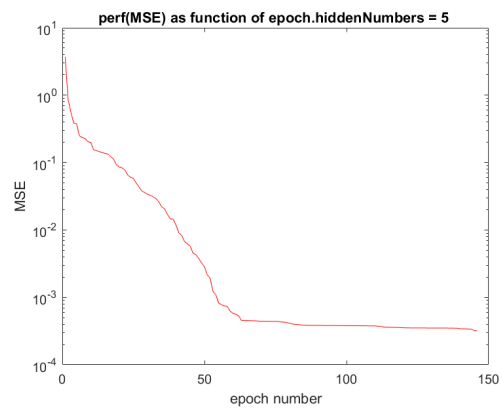


Figure 7: hidden number =5, trainFcn = traingcf

MSE(5 runs)	Epochs	reason of termination
Levenberg-Marquardt(trainlm)		
1.767e-03	39	minimum gradient
6.390e-04	23	minimum gradient
1.383e-03	100	maximum epoch(100)
1.640e-03	33	minimum gradient
3.169e-04	12	minimum gradient
gradient descent(traingd)		
2.121e-03	20000	maximum epoch(20000)
9.884e-04	20000	maximum epoch(20000)
2.050e-03	20000	maximum epoch(20000)
1.082e-03	20000	maximum epoch(20000)
1.592e-03	20000	maximum epoch(20000)
conjugate gradient(traincgf)		
7.272e-04	257	minimum step size
1.142e-03	390	minimum step size
3.231e-03	561	minimum step size
5.618e-04	577	minimum step size
3.382e-03	513	minimum step size

Table 3: hidden number =5

(b)

hidden number =20

plot:

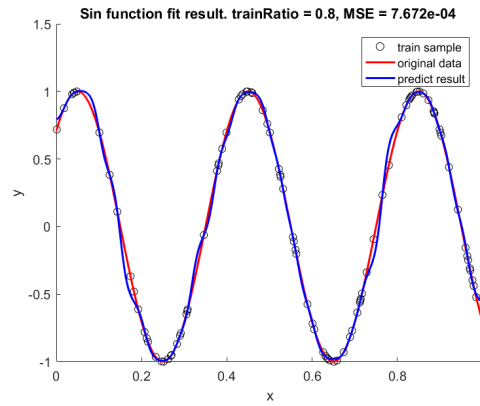


Figure 8: hidden number =20, trainFcn = trainlm

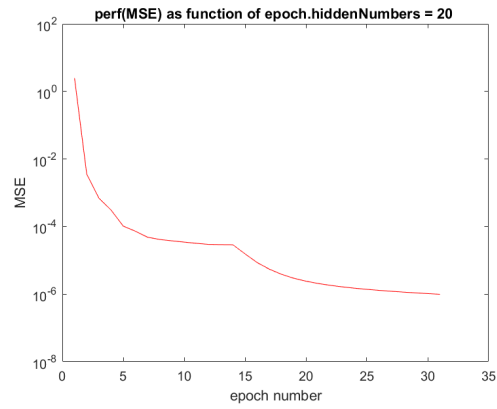


Figure 9: hidden number =20, trainFcn = trainlm

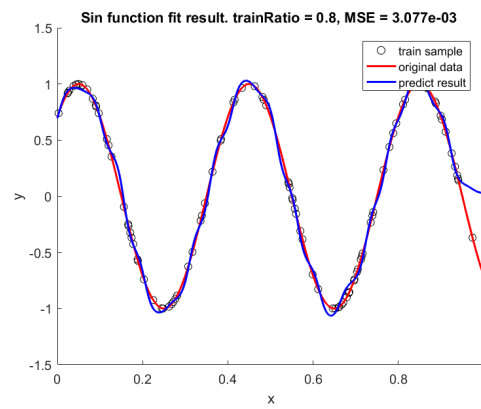


Figure 10: hidden number =20, trainFcn = traingd

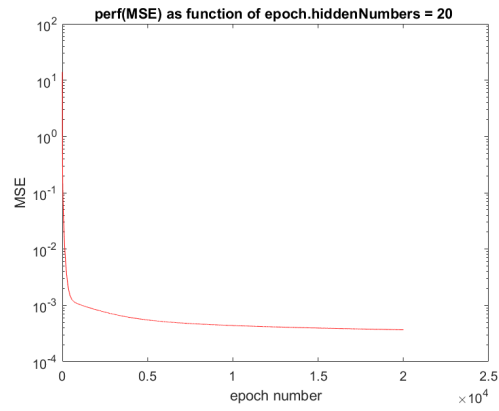


Figure 11: hidden number =20, trainFcn = traingd

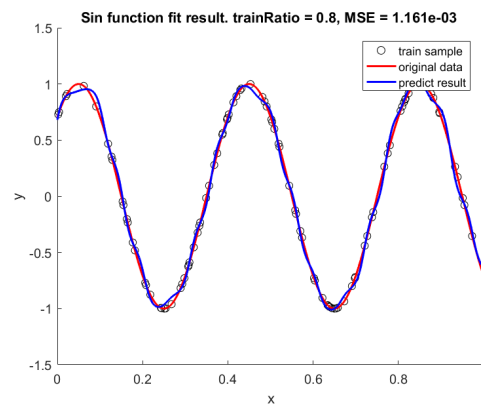


Figure 12: hidden number =20, trainFcn = traingcf

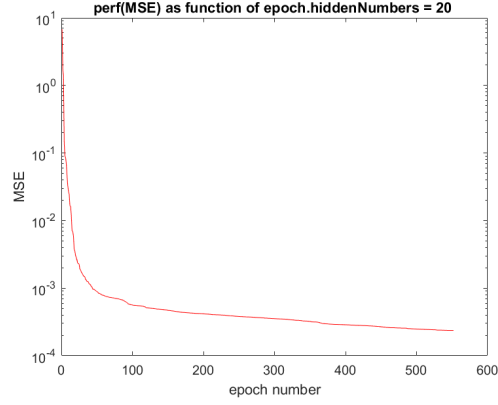


Figure 13: hidden number =20, trainFcn = traingcf

MSE	Epochs	reason of termination
Levenberg-Marquardt(trainlm)		
7.672e-04	30	Performance goal met
1.061e-04	35	Performance goal met
9.617e-04	47	Performance goal met
3.427e-04	44	Performance goal met
4.245e-03	26	Performance goal met
gradient descent(traingd)		
1.042e-03	20000	maximum epoch(20000)
3.077e-03	20000	maximum epoch(20000)
1.891e-03	20000	maximum epoch(20000)
1.686e-02	20000	maximum epoch(20000)
1.323e-03	20000	maximum epoch(20000)
conjugate gradient(traincgf)		
7.388e-04	916	minimum step size
1.161e-03	551	minimum step size
8.459e-04	675	minimum step size
7.019e-04	428	minimum step size
9.575e-04	611	minimum step size

Table 4: hidden number =20

(c) Comment

Apparently, with more hidden neurons, the fitting of the sin function is better. And with more training samples, the training error will be smaller, but the testing error may be larger due to the overfitting effect.

So when the training sample is not enough, increase the complexity of model can not always give us a better result.

Q4

(a)

Clearly, here the minimum value of K should be no greater than 4, since 4 is the sample number. And K should also be larger than 1 if we transform the data using radial function. So try $K = 2$. And one possible solution is

$$\phi_1 = \exp(-x^2), \phi_2 = \exp(-(x-2)^2)$$

$x = [0, 2, 1, 3]^T$ will be transformed into:

$$\begin{bmatrix} 1 & 0.0183 \\ 0.0183 & 1 \\ 0.368 & 0.368 \\ 1.234e-4 & 0.368 \end{bmatrix}$$

The transformed data points and boundary is as follows:

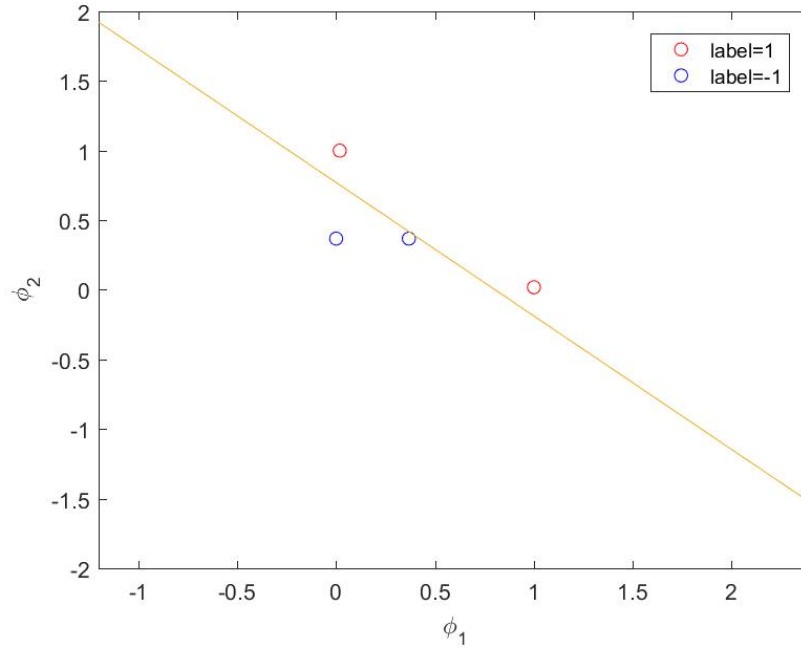


Figure 14: $K=2$

As the figure shows, now the data can be separate by line.

And the boundary point in the original 1D space is 0.727, 1.273, 2.515. This was searched by matlab.

(b)

Here, I can find when $K=3$, the boundary has no bias term in the transformed space. Chosen radical functions:

$$\phi_1 = \exp(-x^2), \phi_2 = \exp(-(x-2)^2), \phi_3 = \exp(-(x-1)^2/100),$$

$x = [0, 2, 1, 3]^T$ will be transformed into:

$$x2 = \begin{bmatrix} 1.0000 & 0.0183 & 0.9900 \\ 0.0183 & 1.0000 & 0.9900 \\ 0.3679 & 0.3679 & 1.0000 \\ 0.0001 & 0.3679 & 0.9608 \end{bmatrix}$$

We can choose $w = [1, 1, -1]^T$, without bias term,

$$x2 * w = \begin{bmatrix} 0.0283 \\ 0.0283 \\ -0.2642 \\ -0.5928 \end{bmatrix}$$

And

$$\text{sign}(x2 * w) = \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}$$

Here the boundary point is 0.242, 1.788, 2.182, which were also searched by matlab.

Q5

HW5

Q5 (a)

Using Non-linear transform as follows.

$$x_1 \rightarrow (1, 0, 0, \dots, 0)^T$$

$$x_2 \rightarrow (0, 1, 0, \dots, 0)^T$$

$$x_n \rightarrow (0, 0, \dots, 1)^T$$

So \vec{x}_i will be transformed into

$$\vec{\phi}_i = (0, 0, 0, \dots, 1, 0, \dots, 0)^T, \text{ Only } i_{th} \text{ element is } 1.$$

$$(b) C_1: (0, 5, 15, 20), \text{ label } 1$$

$$C_2: (1, 2, 3, 4, 6, 7, 8, 9, 11, 12, 13, 14, 16, 17, 18, 19), \text{ label } -1.$$

Using the mapping defined in (a)

We can have W , as

$$W = (1, -1, -1, -1, -1, 1, -1, -1, -1, -1, 1, -1, -1, -1, -1, 1, -1, -1, -1, 1)^T$$

$$\text{such that } W^T \vec{\phi}_i = \begin{cases} 1 > 0, \text{ if Sample } i \in C_1 \\ -1 < 0, \text{ if Sample } i \in C_2 \end{cases}$$

For example, 1st sample 0 is mapped to $\vec{\phi}_0 = (1, 0, \dots, 0)^T$

$$\therefore W^T \vec{\phi}_0 = 1 > 0$$

Similar for other data points

Figure 15: Q5

Q6

During the training, I disabled the validation and test dataset since here the number of training sample is so small (only 4).

two hidden nuerons

two typical plots

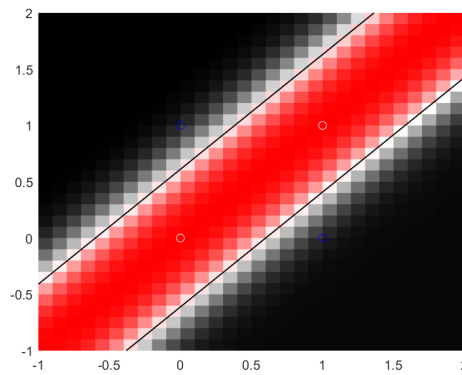


Figure 16: hidden number =2,trainFcn = trainlm

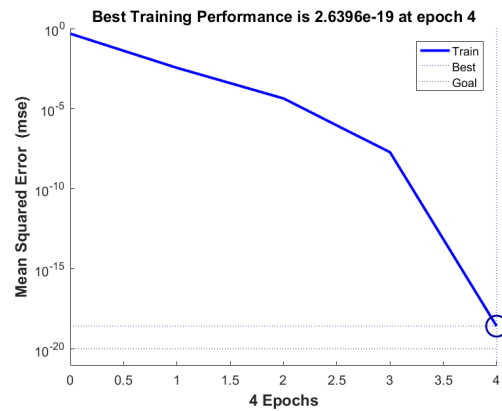


Figure 17: hidden number =2,trainFcn = trainlm

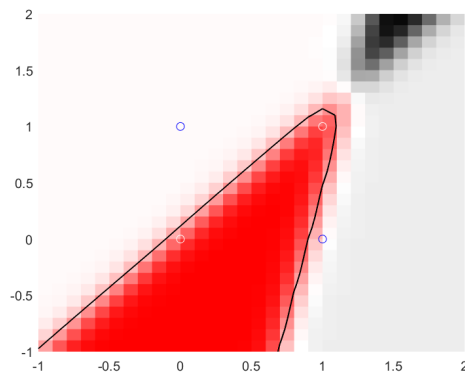


Figure 18: hidden number =2,trainFcn = trainlm

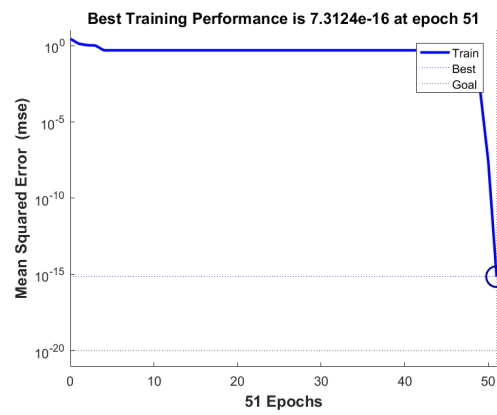


Figure 19: hidden number =2,trainFcn = trainlm

four hidden nuerons

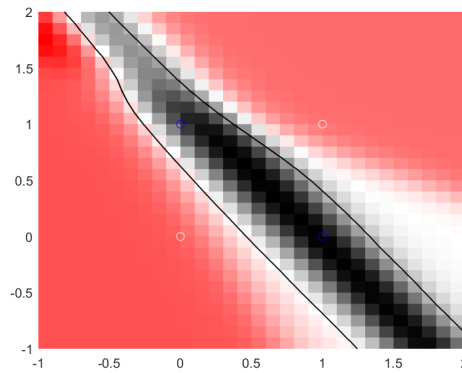


Figure 20: hidden number =4,trainFcn = trainlm

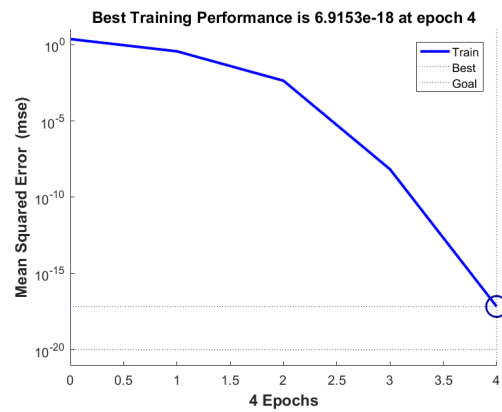


Figure 21: hidden number =4,trainFcn = trainlm

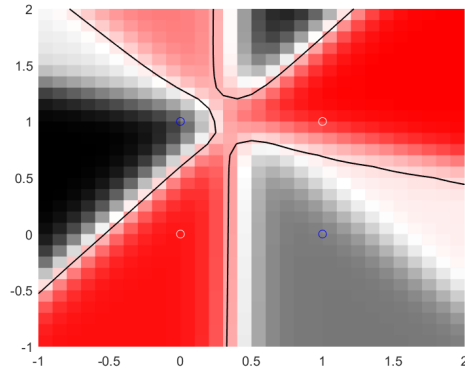


Figure 22: hidden number =4,trainFcn = trainlm

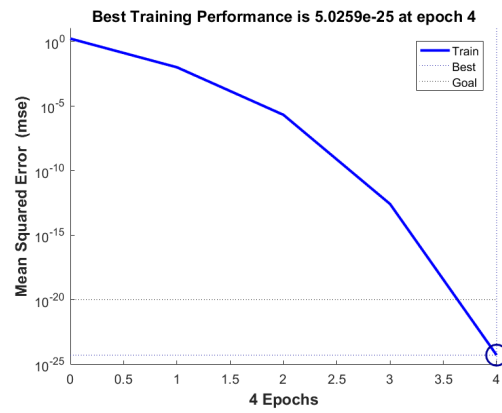


Figure 23: hidden number =4,trainFcn = trainlm

Comment

Similar with MLP in the hw4, although 2 hidden neurons is enough, and the boundary of 4 hidden neurons may be similar to the one of 2 hidden neurons, we can not delete some of the weights of the 4 hidden neurons.

Q7

HW5

7.

According to Cover's Theorem

$$\begin{aligned}\text{we have } P(4, z) &= \left(\frac{1}{2}\right)^3 \left[\binom{3}{1} + \binom{3}{0} \right] \\ &= \frac{1}{8} [3+1] \\ &= \frac{1}{2}\end{aligned}$$

So the probability is $\frac{1}{2}$

Figure 24: Q7