# Time Series Analysis and Forecasting of Beer Prices in Australia: $1960\mbox{-}2010$

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#### 1 Abstract

This project aims to analyze quarterly data on beer prices in Australia spanning from 1960 to 2010, employing time series analysis techniques to understand the underlying patterns and dynamics. The primary objective is to identify and fit appropriate time series models to the dataset, thereby enabling the forecasting of future beer prices. The analysis involves exploring the temporal dependencies, trends, and seasonality present in the data to select the most suitable model. Various time series models, including autoregressive integrated moving average (ARIMA), seasonal ARIMA (SARIMA), and possibly more sophisticated models such as exponential smoothing methods, will be considered and evaluated based on their ability to capture the historical price variations accurately. Additionally, diagnostics tests will be employed to assess the adequacy of the selected model and ensure its robustness. Ultimately, leveraging the chosen model, this study aims to provide reliable forecasts of beer prices in Australia, offering valuable insights for stakeholders in the brewing industry, policymakers, and consumers.

#### 2 Theory

#### 2.1 Autocorrelation Function (ACF) and Partial Autocorrelation Function (PACF)

The Autocorrelation Function (ACF) and Partial Autocorrelation Function (PACF) are essential tools in time series analysis for understanding the correlation structure within a time series dataset.

**ACF**: The ACF measures the correlation between a time series and its lagged values. Mathematically, it is defined as:

$$\rho_k = \frac{\text{Cov}(y_t, y_{t-k})}{\sqrt{\text{Var}(y_t) \cdot \text{Var}(y_{t-k})}}$$

where  $\rho_k$  represents the autocorrelation at lag k,  $y_t$  is the time series at time t, and Cov and Var represent the covariance and variance, respectively.

**PACF**: The PACF measures the correlation between a time series and its lagged values while controlling for the intermediate lags. It helps identify the direct effect of a lag on the current value of the series. Mathematically, it can be calculated using the Durbin-Levinson recursion formula.

#### 2.2 Model Selection based on ACF and PACF

The ACF and PACF plots provide insights into the potential structure of the time series data, aiding in model selection. For instance:

- A rapidly decaying ACF and a significant cutoff in the PACF suggest an AR(p) model.
- A rapidly decaying PACF and a significant cutoff in the ACF suggest an MA(q) model.
- Both slowly decaying ACF and PACF suggest a possible integrated component, leading to an ARIMA model.

# 2.3 ARIMA (AutoRegressive Integrated Moving Average) and SARIMA (Seasonal ARIMA)

**ARIMA**: ARIMA models are a class of models that capture autocorrelation in a time series. They consist of three main components: Autoregression (AR), Differencing (I), and Moving Average (MA). The general form of an ARIMA model of order (p, d, q) is:

$$Y_{t} = c + \phi_{1}Y_{t-1} + \phi_{2}Y_{t-2} + \dots + \phi_{p}Y_{t-p} + \theta_{1}\epsilon_{t-1} + \theta_{2}\epsilon_{t-2} + \dots + \theta_{q}\epsilon_{t-q} + \epsilon_{t}$$

where  $Y_t$  is the observed value at time t, c is a constant,  $\phi_1, \phi_2, \ldots, \phi_p$  are the autoregressive parameters,  $\theta_1, \theta_2, \ldots, \theta_q$  are the moving average parameters,  $\epsilon_t$  is white noise, and d is the degree of differencing.

**SARIMA**: SARIMA extends the ARIMA model to incorporate seasonal components. It includes additional seasonal autoregressive (SAR) and seasonal moving average (SMA) terms. A SARIMA model is denoted as  $(p, d, q) \times (P, D, Q)_s$ , where (p, d, q) are the non-seasonal components and  $(P, D, Q)_s$  are the seasonal components with period s.

#### 2.4 Ljung-Box Test and Portmanteau Test

The Ljung-Box test and Portmanteau test are statistical tests used to evaluate whether the residuals of a time series model exhibit autocorrelation at various lags.

**Ljung-Box Test**: The Ljung-Box test is based on the sum of squares of autocorrelations of the residuals up to a certain lag. The test statistic is:

$$Q = n(n+2) \sum_{k=1}^{h} \frac{\hat{\rho}_k^2}{n-k}$$

where  $\hat{\rho}_k$  are the sample autocorrelations of the residuals at lag k, n is the sample size, and h is the number of lags being tested.

**Portmanteau Test**: The Portmanteau test is similar to the Ljung-Box test but uses a different formulation to test for autocorrelation in residuals. It provides a single test statistic, which is compared to the Chi-squared distribution with degrees of freedom equal to the number of lags being tested.

Both tests are used to assess whether the residuals are independently and identically distributed (iid), which is a key assumption of many time series models. A significant result suggests the presence of autocorrelation in the residuals, indicating that the model might be misspecified.

#### 2.5 Metrics for accuracy checking

#### Mean Squared Error (MSE):

The Mean Squared Error (MSE) is a measure of the average squared difference between the actual and predicted values in a dataset. It is calculated as the average of the squared residuals.

Mathematically, the MSE is defined as:

$$MSE = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2$$

where:

- $\bullet$  *n* is the number of observations,
- $y_i$  represents the actual value of the target variable for observation i,
- $\hat{y}_i$  represents the predicted value of the target variable for observation i.

#### Mean Absolute Percentage Error (MAPE):

The Mean Absolute Percentage Error (MAPE) is a measure of the average percentage difference between the actual and predicted values in a dataset. It is calculated as the average of the absolute percentage errors. Mathematically, the MAPE is defined as:

$$MAPE = \frac{1}{n} \sum_{i=1}^{n} \left| \frac{y_i - \hat{y}_i}{y_i} \right| \times 100\%$$

where:

- $\bullet$  *n* is the number of observations,
- $y_i$  represents the actual value of the target variable for observation i,
- $\hat{y}_i$  represents the predicted value of the target variable for observation i.

## 3 Data Description

The data is collected from CRAN Library. The data contains quarterly data on beer price in Australia from 1960 to 2010.

	Quarter	Beer
0	1956 Q1	284
1	1956 Q2	213
2	1956 Q3	227
3	1956 Q4	308
4	1957 Q1	262

Figure 1: First 5 rows of the dataset

The plot of the data is like this:

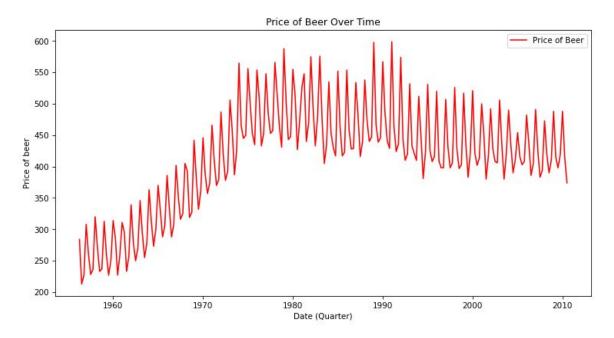


Figure 2: Plot of the dataset

# 4 Analysis Methodologies

#### 4.1 Data Splitting

The dataset was divided into training and testing sets, with the first 80% of the data allocated for training and the remaining 20% for testing.

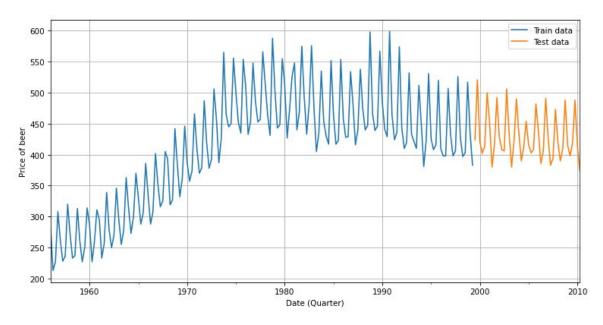


Figure 3: Train-test split of the dataset

#### 4.2 Trend Analysis

To assess the presence of trend in the dataset, a decomposition technique was employed to separate the time series into trend, seasonality, and error components.

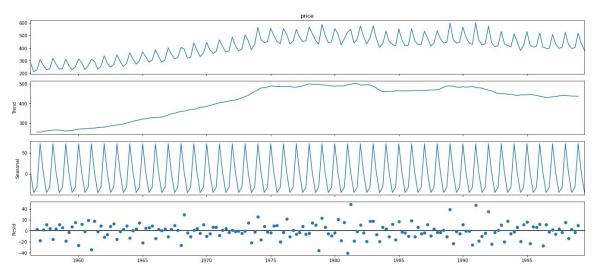


Figure 4: Decomposition of Time series

#### 4.3 Autocorrelation and Partial Autocorrelation Analysis

Autocorrelation Function (ACF) and Partial Autocorrelation Function (PACF) plots were generated to examine the autocorrelation structure of the time series data. Significant periodic spike patterns were observed in the ACF plot.

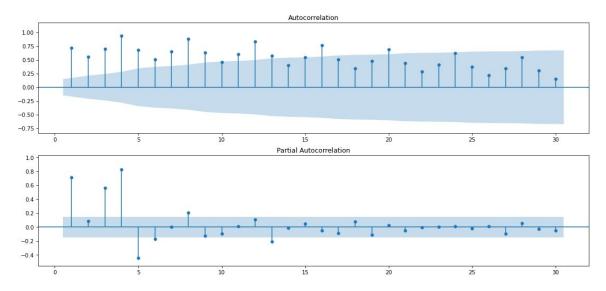


Figure 5: ACF & PACF of the whole dataset

#### 4.4 Differencing

First-order differencing was applied to the dataset to remove the trend component and reduce the non-seasonal lags in autocorrelation. Subsequently, ACF and PACF plots were re-examined to assess the effectiveness of differencing.

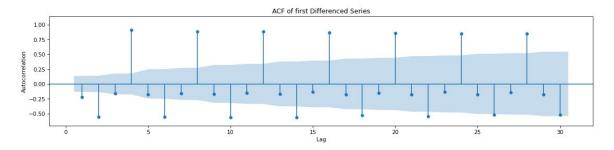


Figure 6: ACF of First order differenced data

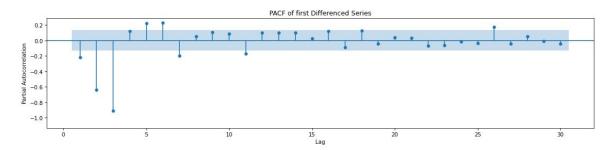


Figure 7: PACF of First order differenced data

#### 4.5 Seasonal Differencing

To address the seasonality observed in the dataset, seasonal differencing of period 4 was performed. This process aimed to eliminate the seasonal component from the time series.

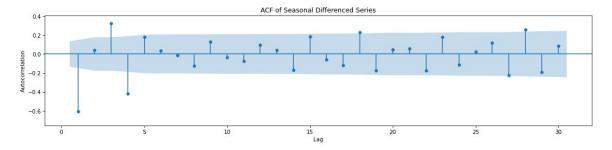


Figure 8: ACF of seasonality removed data

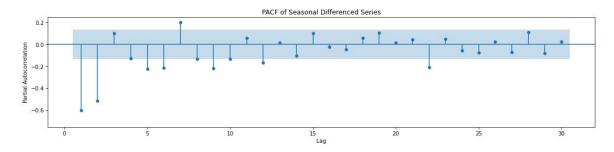


Figure 9: PACF of seasonality differenced data

#### 4.6 Model Selection

Based on the ACF and PACF plots post-differencing, two candidate ARIMA models were identified: ARIMA(3,1,3) and ARIMA(3,1,2). These models were selected considering their ability to capture the autocorrelation structure and seasonal patterns observed in the data.

#### 5 Result

SARIMAX Results								
Dep. Variab Model: Date: Time: Sample:	SA Th		174 -726.260 1466.521 1488.471 1475.428					
========	coef	std err	z	P> z	[0.025	0.975]		
intercept ar.L1 ar.L2 ar.L3 ma.L1 ma.L2 sigma2	3.1816 -0.9009 -1.0036 -0.8985 -0.1166 0.6947 297.7777	0.007 0.039 0.052	-23.461	0.142 0.000 0.000 0.000 0.025 0.000 0.000	-1.069 -0.976 -1.017 -0.974 -0.218 0.591 238.633	-0.990 -0.823 -0.015		
Ljung-Box (L1) (Q): Prob(Q): Heteroskedasticity (H): Prob(H) (two-sided):			0.17 0.68 2.03 0.01	Jarque-Bera Prob(JB): Skew: Kurtosis:	(JB):	0 -0	.03 .22 .14 .59	

Figure 10: Summary of ARIMA(3,1,2)

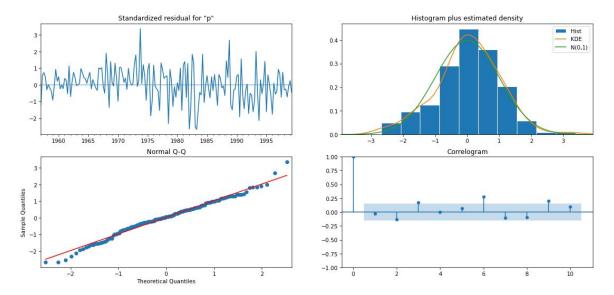


Figure 11: Model Adequacy Checking of ARIMA(3,1,2)

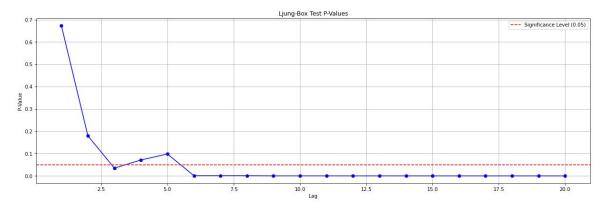


Figure 12: Ljung box test for ARIMA(3,1,2)

#### SARIMAX Results

Dep. Variab Model: Date: Time: Sample:	SAI Thi	RIMAX(3, 1 u, 02 May :	, 3) Log 2024 AIC 5:34 BIC 1956 HQIC	Observations Likelihood		174 -720.591 1457.182 1482.221 1467.343	
Covariance	Type:		opg 				
	coef	std err	z	P> z	[0.025	0.975]	
intercept	3.4867	1.932	1.805	0.071	-0.300	7.273	
ar.L1	-0.8563	0.048	-17.996	0.000	-0.950	-0.763	
ar.L2	-1.0047	0.005	-222.365	0.000	-1.014	-0.996	
ar.L3	-0.8555	0.048	-17.959	0.000	-0.949	-0.762	
ma.L1	-0.2350	0.083	-2.840	0.005	-0.397	-0.073	
ma.L2	0.8158	0.051	15.845	0.000	0.715	0.917	
ma.L3	-0.1616	0.083	-1.952	0.051	-0.324	0.001	
sigma2	292.0594	28.430	10.273	0.000	236.338	347.780	
Ljung-Box ( Prob(Q): Heteroskeda Prob(H) (tw	sticity (H):		0.09 0.77 2.16 0.00	Jarque-Bera Prob(JB): Skew: Kurtosis:	(JB):	_	8.09 0.02 -0.19 4.00

Figure 13: ARIMA(3,1,3)

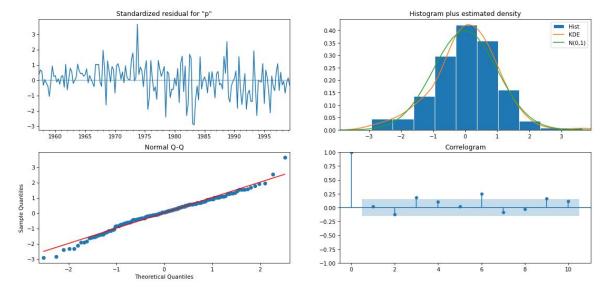


Figure 14: Model Adequacy checking for ARIMA (3,1,3)

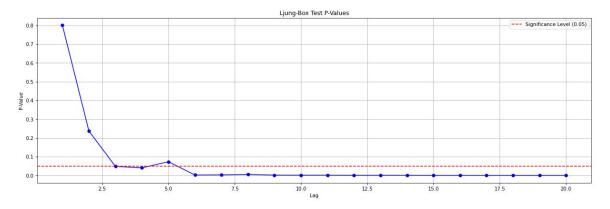


Figure 15: Ljung Box test for ARIMA(3,1,3

#### 5.1 Forecasting using ARIMA(3,1,3)

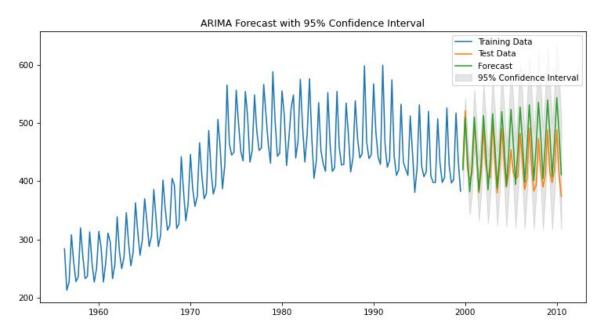


Figure 16: Forecasting using ARIMA(3,1,3)

Mean Squared Error (MSE): 1405.3869321572079 Mean Absolute Percentage Error (MAPE): 7.31 %

Figure 17: MSE of ARIMA model

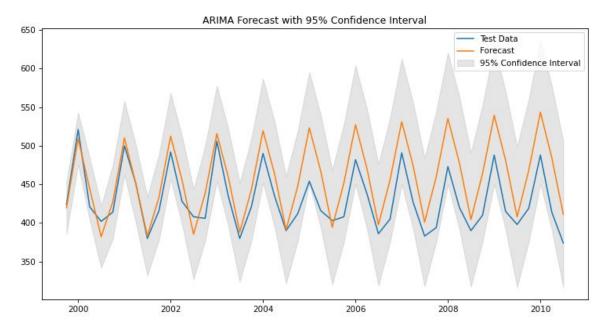


Figure 18: Magnified view

#### SARIMAX Results

Dep. Variate Model: Date: Time: Sample: Covariance	SARI	MAX(3, 1,		1], 4) Log y 2024 AIC :50:21 BIC 1-1956 HQI		5:	174 -669.488 1358.976 1389.790 1371.487
=======	coef	std err	======= Z	P> z	[0.025	0.975]	
intercept ar.L1 ar.L2 ar.L3 ma.L1 ma.L2 ma.L3 ar.S.L4 ma.S.L4 sigma2	-0.2568 -1.3423 -1.3185 -0.3719 0.3906 0.4109 -0.4260 0.1955 -0.7975 234.7199	0.398 0.191 0.165 0.144 0.208 0.094 0.127 0.130 0.070 22.374	-0.645 -7.017 -8.003 -2.588 1.875 4.393 -3.364 1.502 -11.416 10.491		-1.038 -1.717 -1.641 -0.653 -0.018 0.228 -0.674 -0.060 -0.934 190.867	-0.090 0.799 0.594 -0.178 0.451	
Ljung-Box ( Prob(Q): Heteroskeda Prob(H) (tw	asticity (H):		0.01 0.92 2.40 0.00	Jarque-Bera Prob(JB): Skew: Kurtosis:	(JB):	0	

Figure 19: Summary of Sarima(3,1,3)(1,1,1)4

#### SARIMAX Results

Dep. Variab Model: Date: Time: Sample: Covariance	SARI	MAX(3, 1, 3	Thu, 02		No. Observat Log Likeliho AIC BIC HQIC		174 -652.363 1324.726 1355.288 1337.138
	coef	std err	z	P> z	[0.025	0.975]	
intercept	-0.3049	 0.467	-0.654	0.513	 -1 <b>.</b> 219	0.610	
ar.L1	-1.2835	0.206	-6.232	0.000	-1.687	-0.880	
ar.L2	-1.2649	0.194	-6.520	0.000	-1.645	-0.885	
ar.L3	-0.3250	0.159	-2.042	0.041	-0.637	-0.013	
ma.L1	0.3263	0.220	1.480	0.139	-0.106	0.758	
ma.L2	0.4075	0.093	4.393	0.000	0.226	0.589	
ma.L3	-0.4505	0.122	-3.697	0.000	-0.689	-0.212	
ma.S.L4	-0.5413	0.098	-5.549	0.000	-0.732	-0.350	
ma.S.L8	-0.2086	0.100	-2.086	0.037	-0.405	-0.013	
sigma2	235.6173	22.795	10.336	0.000	190.940	280.295	
Ljung-Box (	 L1) (0):		 0.00	======== Jarque-Bera	======== a (JB):	9.16	
Prob(Q):			0.97	Prob(JB):		0.01	
	sticity (H):		2.19	Skew:		0.08	
Prob(H) (tw			0.01	Kurtosis:		4.17	

Figure 20: Summary of Sarima(3,1,3)(0,1,2)4

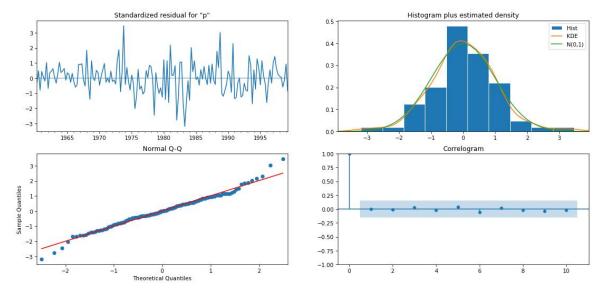


Figure 21: Model Adequacy for Sarima

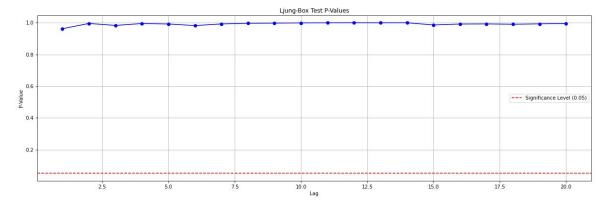


Figure 22: Ljung Box test for Sarima model

#### 5.2 Forecasting using Sarima model

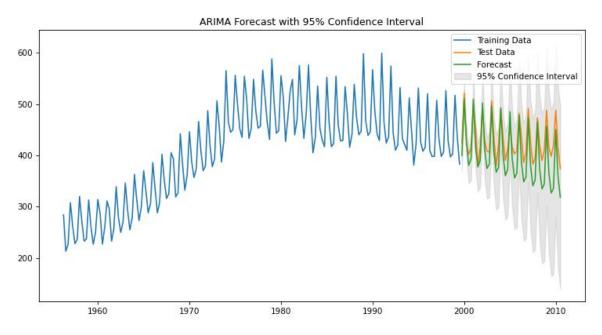


Figure 23: Forecasting using Sarima Model

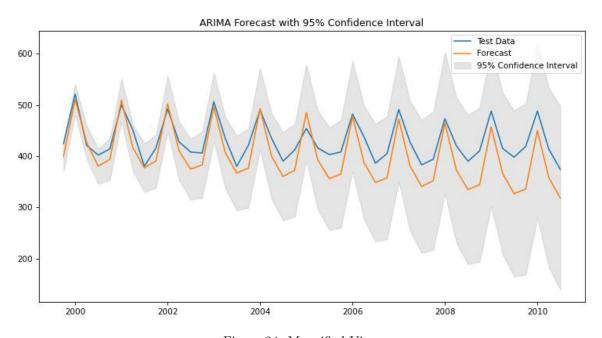


Figure 24: Magnified View

Mean Squared Error (MSE): 1427.8832585608397 Mean Absolute Percentage Error (MAPE): 7.82 %

Figure 25: MSE of forecasted values using Sarima Model

### 6 Conclusion

Utilized visualizations of the Autocorrelation Function (ACF) and Partial Autocorrelation Function (PACF) plots on the first difference of the time series data to identify potential ARIMA models. Two promising ARIMA models, (3, 1, 2) and (3, 1, 3), were obtained through this process. Further analysis involved visualizing the ACF and PACF plots on the seasonal difference of the differenced time series data. This led to the identification of two seasonal ARIMA models, namely (3, 1, 3) with seasonal order (1, 1, 1, 4) and (3, 1, 3) with seasonal order (10, 1, 2, 4). The data was decomposed into trend-cycle, seasonal, and remainder error terms to better understand its underlying components. Assessment of model accuracy was performed using Ljung-Box p-value, Mean Squared Error (MSE), and Mean Absolute Percentage Error (MAPE) metrics. These evaluations provided insights into the predictive performance of both ARIMA and seasonal ARIMA models.