1. Solve the follwing set of equations Ax = b.

lineq1.dat, lineq2.dat, lineq3.dat에 대해 1) Guass-Jordan elimination, 2) LU decomposition, 3) SVD 적용하여 solve한 결과,

- lineq1.dat & Guass-Jordan elimination:

- lineq1.dat & LU decomposition:

```
• (base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq1.dat ludcmp
File 'lineq_dat/lineq1.dat' read complete. =======
Using LU Decomposition: x = [ 1.00000 -3.00000 2.00000 0.00000 ]^t
```

- lineq1.dat & SVD:

```
• (base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq1.dat svdcmp
File 'lineq_dat/lineq1.dat' read complete. ========
Using SVD: x = [ 1.73333 -1.53333 -0.20000 -0.73333 ]^t
```

- lineg2.dat & Guass-Jordan elimination:

```
(base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq2.dat gaussj
File 'lineq_dat/lineq2.dat' read complete. =======
Using Gauss-Jordan Elimination: x = [ -2.87357 -0.61236  0.97628  0.63582 -0.55344 ]^t
-lineq2.dat & LU decomposition:
(base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq2.dat ludcmp
File 'lineq_dat/lineq2.dat' read complete. =======
Using LU Decomposition: x = [ -2.87357 -0.61236  0.97628  0.63582 -0.55344 ]^t
```

```
- lineq2.dat & SVD:
  (base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq2.dat svdcmp
  File 'lineq_dat/lineq2.dat' read complete. =======
```

-0.61236

- lineg3.dat & Guass-Jordan elimination:

비슷한 solution을 얻을 수 있었다.

Using SVD: x = [-2.87357]

```
    (base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq3.dat gaussj
    File 'lineq_dat/lineq3.dat' read complete. =======
    Using Gauss-Jordan Elimination: x = [ -0.32661 1.53229 -1.04483 -1.58745 2.92848 -2.21893 ]^t
    -lineq3.dat & LU decomposition:
        (base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq3.dat ludcmp
```

0.97628

0.63582

-0.55344]^t

```
(base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq3.dat ludcmp
File 'lineq_dat/lineq3.dat' read complete. ========
Using LU Decomposition: x = [ -0.32661 1.53229 -1.04483 -1.58745 2.92848 -2.21893 ]^t
```

- lineq3.dat & SVD:

2. Apply the method of iterative improvement (mprove()) to the above problem and discuss the results.

```
(base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq2.dat mprove
File 'lineq_dat/lineq2.dat' read complete. ======
Using LU Decomposition: x = [ -2.87357 -0.61236 0.97628 0.65]
Solution x, noise added: x = [ -2.87356 -0.48082 1.73188 1.0]
After improvement: x = [ -2.87357 -0.61236 0.97628 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582 0.63582
                                                                                                                                                                                                                                                                                                                                                                                                                               -0.55344 ]^t
-0.02067 ]^t
                                                                                                                                                                                                                                                                                                                                                                           0.63582
                                                                                                                                                                                                                                                                                                                                                                                1.09447
 After improvement: x = [ -2.87357 -0.61236 0.97628 0.63582 (base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq3.dat mprove File 'lineq_dat/lineq3.dat' read complete. =======
                                                                                                                                                                                                                                                                                                                                                                                                    -0.55344 ]^t
 Using LU Decomposition: x = [
                                                                                                                                                                             -0.32661
                                                                                                                                                                                                                                                   1.53229
                                                                                                                                                                                                                                                                                                           -1.04483
                                                                                                                                                                                                                                                                                                                                                                     -1.58745
                                                                                                                                                                                                                                                                                                                                                                                                                                        2.92848
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              -2.21893 ]^t
 Solution x, noise added: x = [
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 -1.99997 ]^t
                                                                                                                                                                                    -0.32660
                                                                                                                                                                                                                                                         1.66383
                                                                                                                                                                                                                                                                                                                  -0.28922
                                                                                                                                                                                                                                                                                                                                                                              -1.12880
                                                                                                                                                                                                                                                                                                                                                                                                                                             3.46125
                                                                                                                                                                                                                      1.53229
                                                                                                                                                                                                                                                                           -1.04483
                                                                                                                                                                                                                                                                                                                                   -1.58745
 After improvement: x = [
                                                                                                                                              -0.32661
```

non-singular matrix (lineq2.dat, lineq3.dat)에 대해 LU decomposition하여 solution을 구한 뒤, solution vector element 각각에 [0, 1] 구간의 random noise를 추가하였다. 이후 mprove()를 한번 호출한 결과, 마지막 결과 (After improvement: ...)와 같이, 다시 원래 solution과 비슷해짐을 확인할 수 있었다. Numerical Analysis in C에서 'Unless you are starting quite far from the true solution, one call is generally enough.'라고 언급한 대로, noise가 크지 않아 한번의 improvement call로도 noise 추가 전 solution과

3. Find the inverse and the determinant of the matrix A in the above problem.

non-singular matrix (lineg2.dat, lineg3.dat)에 대해 matrix A의 inverse matrix를 구한 결과,

```
(base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq2.dat inverse
File 'lineq_dat/lineq2.dat' read complete. ======
Using LU Decomposition: inverse of matrix is
                                0.20777
0.19578
   0.35454
                 0.76694
                                             -0.59541
                                                             0.25313
                0.12669
-0.09854
                                                            0.05031
0.01642
   0.03545
                                             -0.15954
  -0.13869
                               -0.09672
                                              0.12409
  -0.05214
                -0.30396
                               -0.02320
                                              0.23462
                                                           -0.04458
   0.14911
                 0.45933
                                0.05136
                                              -0.17101
                                                            0.04249
```

```
(base) lee@lee 03-LinearEquation % ./linEq lineq_dat/lineq3.dat inverse
File 'lineq_dat/lineq3.dat' read complete. ======
Using LU Decomposition: inverse of matrix is
  -0.16221
                0.12280
                             0.02407
                                         -0.01643
                                                      -0.02284
                                                                    0.04613
   0.16941
               -0.04112
                             0.22831
                                         -0.08762
                                                       0.18031
                                                                   -0.39565
                            -0.11741
  -0.01164
                0.12274
                                         -0.18098
                                                       0.01591
                                                                    0.18677
   0.10567
               -0.05173
                            -0.10892
                                          0.29977
                                                       0.00086
                                                                    -0.19054
   -0.05303
               -0.04236
                             0.16051
                                          0.22403
                                                       0.16181
                                                                    0.01502
   -0.06234
               -0.06469
                             -0.23422
                                          0.35113
                                                       -0.36483
                                                                     0.43463
```

lineq1.dat, lineq2.dat, lineq3.dat 각각에 대해 matrix A의 determinant를 구한 결과,