

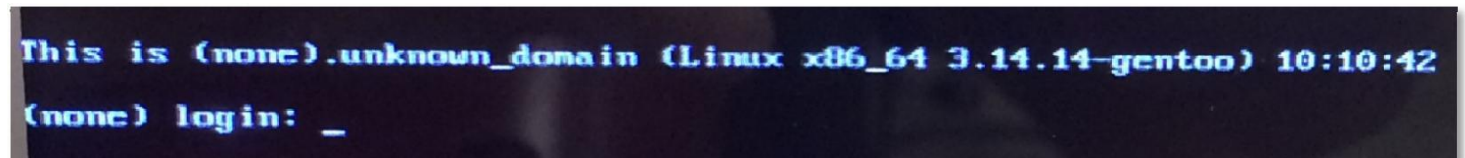
Software Procedure

Classification:	Software
Related Product(s):	ALL
Affected Software Version	3.3
Affected Serial Numbers	N/A
Affected Area	N/A

Overview

The procedure below describes how to perform a software factory reset on Intera versions 3.3 and newer. If the robot replaces the hard drive, you need to reset the system to match the communication.

The image below is an example of corrupt Intera software.



Requirements

Required Equipment and Materials

- ☐ USB keyboard

Prerequisites

- ☐ Intera 3.3 or newer

Procedure

Performing the Factory Reset

1. Press the power button to power down the robot. On Sawyer the power button is located on the Control Box.



Baxter



Sawyer

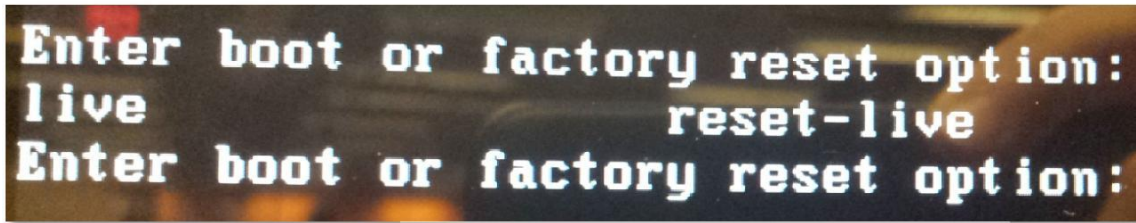
2. Plug a USB keyboard into the robot. Baxter's USB port is located on the back, next to the power button. On Sawyer the USB ports are located in the front panel of the Control Box.



3. While the robot is booting up, press Shift + R on the keyboard to enter the Factory Reset Menu. If there is extra text after the colon, press the Backspace key to remove it.
Note: On Baxter the display will be upside down.

Enter boot or factory reset option:

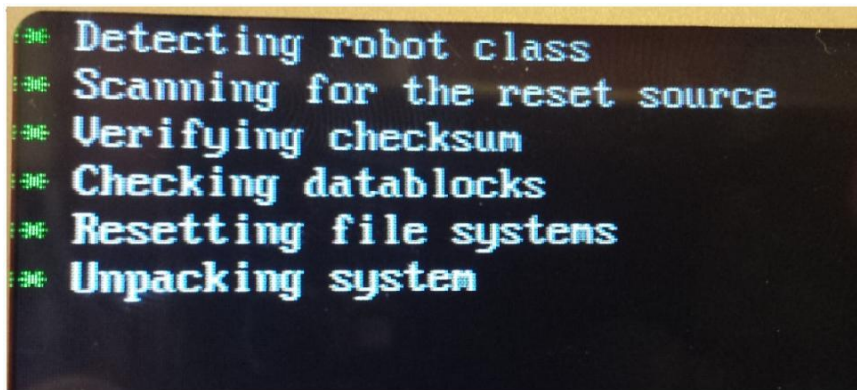
4. Press the Tab key to display the recovery options



A terminal window with a dark background and white text. It displays the prompt "Enter boot or factory reset option:" twice. The first time, the user has entered "live", and the second time, the user has entered "reset-live".

```
Enter boot or factory reset option:  
live  
Enter boot or factory reset option:  
reset-live
```

5. Enter the reset-live option and press the Enter key. The robot will start the recovery process.



A terminal window with a dark background and green text. It displays a list of recovery steps, each preceded by a green double hash symbol (##).

```
## Detecting robot class  
## Scanning for the reset source  
## Verifying checksum  
## Checking datablocks  
## Resetting file systems  
## Unpacking system
```

6. Once the recovery process is complete, the robot will reboot on its own.
7. Unplug the USB keyboard from the robot.