# Derivations of Equations for The Elements of Statistical Learning

by

Soong Lee

August, 2024

This document is a collection of derivations of non-trivial equations and statements from ESL (Second Edition). I did not include the equations that were assigned as exercises, since the solutions of them are available from the resources in the internet.

- 1. ESL Solutions by Yuhang Zhou (github/YuhangZhou88)
- 2. A Solution Manual and Notes for ESL by J. L. Weatherwax and D. Epstein
- 3. A Guide and Solution Manual to ESL by J. C. Ma

I used the same mathematical notation as in ESL. However, on a few occasions I used boldface lower characters for vector notation, like when referring Wikipedia or Matrix Cookbook.

#### References:

- 1. The Matrix Cookbook (Nov 2012) by K. B. Peterson and M. S. Pederson (https://www2.imm.dtu.dk/pubdb/pubs/3274-full.html)
- A Solution Manual and Notes for ESL (October 2021) by J. L. Weatherwax and D. Epstein
- 3. Pattern Recognition and Machine Learning (February 2006) by C. M. Bishop

# Chapter 2. Overview of Supervised Learning

**Eq 2.16:** (ESL p.19)

$$\beta = [\mathrm{E}(XX^T)]^{-1}\mathrm{E}(XY)$$

Proof:

Utilizing Matrix Cookbook Eq (78):

$$\frac{\partial (\mathbf{B}\mathbf{x} + \mathbf{b})^T \mathbf{C} (\mathbf{D}\mathbf{x} + \mathbf{d})}{\partial \mathbf{x}} = \mathbf{B}^T \mathbf{C} (\mathbf{D}x + \mathbf{d}) + \mathbf{D}^T \mathbf{C}^T (\mathbf{B}\mathbf{x} + \mathbf{b})$$

$$EPE(f) = E(Y - f(X))^{2}$$
$$= E[(Y - X^{T}\beta)^{T}(Y - X^{T}\beta)]$$

$$\frac{\partial}{\partial \beta}[(Y - X^T \beta)^T (Y - X^T \beta)] = (-X^T)^T (-X^T \beta + Y) + (-X^T)^T (Y - X^T \beta)$$

$$= -2X(Y - X^T \beta) = 0$$

$$\Rightarrow \quad \mathbf{E}(XY) = \mathbf{E}(XX^T)\beta$$

$$\therefore \quad \beta = [\mathbf{E}(XX^T)]^{-1}\mathbf{E}(XY)$$

**Eq 2.22:** (ESL p.21)

$$\hat{G}(x) = \operatorname{argmin}_{g \in \mathcal{G}}[1 - \Pr(g|X = x)]$$

Proof:

$$\hat{G}(x) = \operatorname{argmin}_{g \in \mathcal{G}} \sum_{k=1}^{K} L(\mathcal{G}_k, g) \Pr(\mathcal{G}_k | X = x)$$
(2.21)

0-1 loss function means that

$$L(\mathcal{G}_k, g) = \begin{cases} 1 & \text{when } \mathcal{G}_k \neq g \\ 0 & \text{else} \end{cases}$$

$$\sum_{k=1}^{K} L(\mathcal{G}_k, g) \Pr(\mathcal{G}_k | X = x) = \Pr(\mathcal{G}_1 | X = x) + \Pr(\mathcal{G}_2 | X = x) + \dots + 0 \cdot \Pr(g | X = x)$$
$$+ \Pr(\mathcal{G}_{g+1} | X = x) + \dots + \Pr(\mathcal{G}_k | X = x)$$

Since

$$\sum_{k=1}^{K} \Pr(\mathcal{G}_k | X = x) = 1$$

$$\therefore \sum_{k=1}^{K} L(\mathcal{G}_k, g) \Pr(\mathcal{G}_k | X = x) = 1 - \Pr(g | X = x)$$

Eq 2.25: (ESL p.24)

$$MSE(x_0) = E_{\mathcal{T}}[f(x_0) - \hat{y}_0]^2$$
  
=  $E_{\mathcal{T}}[\hat{y}_0 - E_{\mathcal{T}}(\hat{y}_0)]^2 + [E_{\mathcal{T}}(\hat{y}_0) - f(x_0)]^2$ 

Proof:

$$\begin{split} \mathbf{E}_{\mathcal{T}}[f(x_0) - \hat{y}_0]^2 &= \mathbf{E}_{\mathcal{T}}[f(x_0) - \hat{y}_0 + \mathbf{E}_{\mathcal{T}}(\hat{y}_0) - \mathbf{E}_{\mathcal{T}}(\hat{y}_0)]^2 \\ &= \mathbf{E}_{\mathcal{T}}[(\mathbf{E}_{\mathcal{T}}(\hat{y}_0) - \hat{y}_0) + (f(x_0) - \mathbf{E}_{\mathcal{T}}(\hat{y}_0))]^2 \\ &= \mathbf{E}_{\mathcal{T}}[\hat{y}_0 - \mathbf{E}_{\mathcal{T}}(\hat{y}_0)]^2 + \mathbf{E}_{\mathcal{T}}[\mathbf{E}_{\mathcal{T}}(\hat{y}_0) - f(x_0)]^2 \\ &+ 2\mathbf{E}_{\mathcal{T}}[\mathbf{E}_{\mathcal{T}}(\hat{y}_0) - \hat{y}_0] \cdot \mathbf{E}_{\mathcal{T}}[f(x_0) - \mathbf{E}_{\mathcal{T}}(\hat{y}_0)] \\ &(\text{Since } \mathbf{E}_{\mathcal{T}}[\mathbf{E}_{\mathcal{T}}(\hat{y}_0) - \hat{y}_0] = \mathbf{E}_{\mathcal{T}}(\hat{y}_0) - \mathbf{E}_{\mathcal{T}}(\hat{y}_0) = 0) \\ &= \mathbf{E}_{\mathcal{T}}[\hat{y}_0 - \mathbf{E}_{\mathcal{T}}(\hat{y}_0)]^2 + \mathbf{E}_{\mathcal{T}}[\mathbf{E}_{\mathcal{T}}(\hat{y}_0) - f(x_0)]^2 \end{split}$$

## **ESL** p.24

"For an arbitray test point  $x_0$ , we have  $\hat{y}_0 = x_0^T \hat{\beta}$ , which can be written as  $\hat{y}_0 = x_0^T \beta + \sum_{i=1}^N l_i(x_0) \epsilon_i$ , where  $l_i(x_0)$  is the i-th element of  $\mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} x_0$ ."

Proof:

$$\hat{y}_0 = x_0^T \beta$$

$$\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \leftarrow \text{from the method of least squares}$$
 (2.6)

$$Y = X\beta + \epsilon \tag{2.26}$$

Since  $X^T = [X_1 X_2, \cdots, X_p]$  ( $\leftarrow$  see ESL p.10.)

$$[X_1, X_2, \cdots, X_p]\beta = X^T \beta \quad \Rightarrow \quad Y = X^T \beta$$

$$\mathbf{X} = \begin{bmatrix} X_{11} & X_{12} & \cdots & X_{1p} \\ X_{21} & X_{22} & \cdots & X_{2p} \\ \vdots & & & & \\ X_{N1} & X_{N2} & \cdots & X_{Np} \end{bmatrix} \quad \Rightarrow \quad \mathbf{y} = \mathbf{X}\boldsymbol{\beta}$$

 $\beta$  becomes,

$$\beta = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T (\mathbf{X}\beta + \epsilon) = \beta + (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \epsilon$$
$$\hat{y}_0 = x_0^T \hat{\beta} = x_0^T \beta + x_0^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \epsilon$$

To match the dimension compared to the sum notation, the second term is transposed,

$$[x_0^T(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T]^T = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}x_0$$

# Chapter 3. Linear Methods for Regression

**Eq 3.12:** (ESL p.48)

$$z_j = \frac{\hat{\beta}_j}{\hat{\sigma}\sqrt{v_j}}$$

Proof:

$$z_{j} = \frac{\hat{\beta}_{j} - 0}{\sqrt{\operatorname{Var}(\hat{\beta}_{j})}} \quad (\leftarrow z = \frac{\overline{x} - m}{\sigma / \sqrt{n}})$$

$$\operatorname{Var}(\hat{\beta}) = (\mathbf{X}^{T} \mathbf{X})^{-1} \sigma^{2}$$
(3.8)

where  $\sigma^2$  is the variance of the observations  $y_i$ 's.

$$\Rightarrow z_j = \frac{\hat{\beta}_j}{\sqrt{(\mathbf{X}^T \mathbf{X})_{jj}^{-1} \hat{\sigma}^2}} = \frac{\hat{\beta}_j}{\hat{\sigma} \sqrt{(\mathbf{X}^T \mathbf{X})_{jj}^{-1}}}$$

where

$$\hat{\sigma} = \frac{1}{N - P - 1} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2 \quad \leftarrow \text{ estimate of } \sigma^2$$

 $v_j = \text{j-th diagonal element of } (\mathbf{X}^T \mathbf{X})^{-1}$ 

$$\therefore z_j = \frac{\hat{\beta}_j}{\hat{\sigma}\sqrt{v_j}}$$

## ESL p.53:

"Then it is easy to check that the multiple least squares estimates  $\hat{\beta}_j$  are equal to  $\langle \mathbf{x}_j, \mathbf{y} \rangle / \langle \mathbf{x}_j, \mathbf{x}_j \rangle$  - the univariate estimates."

#### Proof:

 $X: N \times p \text{ matrix}$ 

$$\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \tag{3.6}$$

Since  $\mathbf{X}^T\mathbf{X}$  is  $\mathbf{p} \times \mathbf{p}$  dimension, and  $\mathbf{X}^T\mathbf{y}$  is  $\mathbf{p} \times 1$ , so  $\hat{\beta}$  is  $\mathbf{p} \times 1$ .

$$\mathbf{x}_1 = \begin{bmatrix} x_{11} \\ x_{21} \\ \vdots \\ x_{N1} \end{bmatrix} \qquad : \quad \text{N data collection of first component of } \mathbf{x}$$

$$\mathbf{X} = \begin{bmatrix} x_{11} & x_{12} & \cdots & x_{1p} \\ x_{21} & x_{22} & \cdots & x_{2p} \\ \vdots & & & & \\ x_{N1} & x_{N2} & \cdots & x_{Np} \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_1 & \cdots & \mathbf{x}_p \end{bmatrix} \quad : \quad \mathbf{N} \times \mathbf{p}$$

$$\mathbf{X}^T = \begin{bmatrix} \mathbf{x}_1^T \\ \mathbf{x}_1^T \\ \vdots \\ \mathbf{x}_p^T \end{bmatrix} : \mathbf{p} \times \mathbf{N}$$

$$\mathbf{X}^T\mathbf{X} = \begin{bmatrix} \mathbf{x}_1^T \\ \mathbf{x}_1^T \\ \vdots \\ \mathbf{x}_p^T \end{bmatrix} \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_1 & \cdots & \mathbf{x}_p \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1^T\mathbf{x}_1 & \mathbf{x}_1^T\mathbf{x}_2 & \cdots & \mathbf{x}_1^T\mathbf{x}_p \\ \mathbf{x}_2^T\mathbf{x}_1 & \mathbf{x}_2^T\mathbf{x}_2 & \cdots & \mathbf{x}_2^T\mathbf{x}_p \\ \vdots & & & \\ \mathbf{x}_p^T\mathbf{x}_1 & \mathbf{x}_p^T\mathbf{x}_2 & \cdots & \mathbf{x}_p^T\mathbf{x}_p \end{bmatrix}$$

$$\mathbf{X}^T\mathbf{y} = egin{bmatrix} \mathbf{x}_1^T \ \mathbf{x}_1^T \ dots \ \mathbf{x}_p^T \end{bmatrix} \mathbf{y} \ = egin{bmatrix} \mathbf{x}_1^T \mathbf{y} \ \mathbf{x}_2^T \mathbf{y} \ dots \ \mathbf{x}_p^T \mathbf{y} \end{bmatrix}$$

If  $\langle \mathbf{x}_j, \mathbf{x}_k \rangle = 0$  for  $j \neq k$ ,

$$\mathbf{X}^T\mathbf{X} = egin{bmatrix} \mathbf{x}_1^T\mathbf{x}_1 & & & & \\ & \mathbf{x}_2^T\mathbf{x}_2 & & & & \\ & & \ddots & & & \\ & & & \mathbf{x}_p^T\mathbf{x}_p \end{bmatrix}$$

$$(\mathbf{X}^T \mathbf{X})^{-1} = \begin{bmatrix} (\mathbf{x}_1^T \mathbf{x}_1)^{-1} & & & \\ & (\mathbf{x}_2^T \mathbf{x}_2)^{-1} & & & \\ & & \ddots & & \\ & & & (\mathbf{x}_p^T \mathbf{x}_p)^{-1} \end{bmatrix}$$

Now  $\hat{\beta}$  can be calculated using the above equations,

$$\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

$$= \begin{bmatrix} \frac{\mathbf{x}_1^T \mathbf{y}}{\mathbf{x}_1^T \mathbf{x}_1} & & \\ & \frac{\mathbf{x}_2^T \mathbf{y}}{\mathbf{x}_2^T \mathbf{x}_2} & & \\ & & \ddots & \\ & & \frac{\mathbf{x}_p^T \mathbf{y}}{\mathbf{x}_p^T \mathbf{x}_p} \end{bmatrix}$$

$$\therefore \hat{\beta}_j = \frac{\langle \mathbf{x}_j, \mathbf{y} \rangle}{\langle \mathbf{x}_j, \mathbf{x}_j \rangle}$$

**Eq 3.27:** (ESL p.53)

$$\hat{\beta}_1 = \frac{\langle \mathbf{x} - \overline{x} \mathbf{1}, \mathbf{y} \rangle}{\langle \mathbf{x} - \overline{x} \mathbf{1}, \mathbf{x} - \overline{x} \mathbf{1} \rangle}$$

Proof:

$$RSS(\beta) = (\mathbf{y} - \mathbf{X}\beta)^{T}(\mathbf{y} - \mathbf{X}\beta)$$
(3.3)

When there is an intercept,

$$Y = X\beta + \beta_0 + \epsilon$$

For univariate case

$$y = \mathbf{x}_1 \beta_1 + \mathbf{x}_0 \beta_0 + \epsilon$$

where

$$\mathbf{x}_0 = 1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} \qquad \leftarrow N \times 1$$

$$RSS(\beta) = (y - \mathbf{x}_0 \beta_0 - \mathbf{x}_1 \beta_1)^T (\mathbf{y} - \mathbf{x}_0 \beta - \mathbf{x}_1 \beta_1)$$

To find minimum RSS w.r.t.  $\beta_0$  and  $\beta_1$ ,

$$\frac{\partial \text{RSS}(\beta)}{\partial \beta_0} = -2\mathbf{x}_0^T (\mathbf{y} - \mathbf{x}_0 \beta_0 - \mathbf{x}_1 \beta_1) = 0$$

$$\Rightarrow -\sum_{i=1}^N y_i + N\beta_0 + \sum_{i=1}^N x_{1i} \beta_1 = 0$$

$$\frac{\partial \text{RSS}(\beta)}{\partial \beta_1} = -2\mathbf{x}_1^T (\mathbf{y} - \mathbf{x}_0 \beta_0 - \mathbf{x}_1 \beta_1) = 0$$

$$\Rightarrow -\mathbf{x}_1^T \mathbf{y} + \sum_{i=1}^N x_{1i} \beta_0 + \sum_{i=1}^N x_{1i}^2 \beta_1 = 0$$
(2)

Defining 
$$\overline{x} = \frac{1}{N} \sum_{1}^{N} x_{1i}$$

Eq (1) becomes 
$$-\sum_{1}^{N} y_i + N\beta_0 + N\overline{x}\beta_1 = 0$$
 (3)

Eq (2) becomes 
$$-\mathbf{x}_1^T \mathbf{y} + N \overline{x} \beta_0 + \sum_{1}^{N} x_{1i}^2 \beta_1 = 0$$
 (4)

To eliminate  $\beta_0$  from Eqs (3) and (4),

Eq (3)  $\times \overline{x}$  – Eq (4):

$$\Rightarrow -\mathbf{x}_{1}^{T}\mathbf{y} + \sum_{1}^{N} \overline{x}y_{i} + \sum_{1}^{N} x_{1i}^{2}\beta_{1} - N\overline{x}^{2}\beta_{1} = 0$$

$$\Rightarrow \beta_{1} = \frac{x_{1}^{T}\mathbf{y} - \sum_{1}^{N} \overline{x}y_{i}}{\sum_{1}^{N} x_{1i}^{2} - N\overline{x}^{2}}$$

$$= \frac{\sum_{1}^{N} x_{1i}y_{i} - \sum_{1}^{N} \overline{x}y_{i}}{\sum_{1}^{N} x_{1i}^{2} - \sum_{1}^{N} \overline{x}^{2}}$$

$$= \frac{\sum_{1}^{N} (x_{1i} - \overline{x})y_{i}}{\sum_{1}^{N} (x_{1i}^{2} - \overline{x}^{2})}$$

To show 
$$< \mathbf{x}_1 - \overline{x} \mathbf{1}, \mathbf{x}_1 - \overline{x} \mathbf{1} > = \sum_{1}^{N} (x_{1i}^2 - \overline{x}^2),$$

$$<\mathbf{x}_1-\overline{x}\,\mathbf{1},\mathbf{x}_1-\overline{x}\,\mathbf{1}>=(\mathbf{x}_1-\overline{x}\,\mathbf{1})^T\cdot(\mathbf{x}_1-\overline{x}\,\mathbf{1})$$

$$= (x_{11} - \overline{x}, x_{12} - \overline{x}, \dots, x_{1N} - \overline{x}) \begin{pmatrix} x_{11} - \overline{x} \\ x_{12} - \overline{x} \\ \vdots \\ x_{1N} - \overline{x} \end{pmatrix}$$

$$= (x_{11} - \overline{x})^2 + (x_{12} - \overline{x})^2 + \dots + (x_{1N} - \overline{x})^2$$

$$= (x_{11}^2 + x_{12}^2 + \dots + x_{1N}^2) - 2\overline{x}(x_{11} + x_{12} + \dots + x_{1N}) + \overline{x}^2 N$$

$$= \sum_{1}^{N} x_{1i}^2 - N\overline{x}^2$$

$$= \sum_{1}^{N} (x_{1i}^2 - \overline{x}^2)$$

$$\therefore \hat{\beta}_1 = \frac{\langle \mathbf{x} - \overline{x} \mathbf{1}, \mathbf{y} \rangle}{\langle \mathbf{x} - \overline{x} \mathbf{1}, \mathbf{x} - \overline{x} \mathbf{1} \rangle}$$
(Here  $\mathbf{x}$  is  $\mathbf{x}_1$  above.)

**Eq 3.31:** (ESL p.55)

$$\mathbf{X} = \mathbf{Z}\mathbf{D}^{-1}\mathbf{D}\boldsymbol{\Gamma} = \mathbf{Q}\mathbf{R}$$
 where  $\mathbf{Q} = \mathbf{Z}\mathbf{D}^{-1},\,\mathbf{R} = \mathbf{D}\boldsymbol{\Gamma}$ 

**Proof**:

$$\mathbf{X} = \mathbf{Z}\,\mathbf{\Gamma} \tag{3.30}$$

 $\Gamma$ : upper triangular matrix

$$D_{jj} = \|\mathbf{z}_j\|$$

 $\mathbf{R} = \mathbf{D}\mathbf{\Gamma}$  an upper triangular matrix, since  $\mathbf{\Gamma}$  is an upper triangular matrix and  $\mathbf{D}$  is a diagonal matrix.

We need to show  $\mathbf{Q} = \mathbf{Z}\mathbf{D}^{-1}$  is an orthonormal matrix.

$$\mathbf{Q}^T\mathbf{Q} = (\mathbf{Z}\mathbf{D}^{-1})^T(\mathbf{Z}\mathbf{D}^{-1}) = \mathbf{D}^{-1}\mathbf{Z}^T\mathbf{Z}\mathbf{D}^{-1}$$

$$\mathbf{Z} = (\mathbf{z}_0, \mathbf{z}_1, \cdots, \mathbf{z}_p) \qquad (\leftarrow N \times (p+1))$$

where 
$$\mathbf{z}_i = egin{bmatrix} z_{1i} \\ z_{2i} \\ \vdots \\ z_{Ni} \end{bmatrix}$$

$$\mathbf{D}^{-1} = \begin{bmatrix} |\mathbf{z}_0|^{-1} & & & & \\ & |\mathbf{z}_1|^{-1} & & & \\ & & \ddots & & \\ & & |\mathbf{z}_p|^{-1} \end{bmatrix} \leftarrow (p+1) \times (p+1)$$

Using the above two equations for  $\mathbf{D}^{-1}$  and  $\mathbf{Z}^{T}\mathbf{Z}$ ,

$$\mathbf{D}^{-1}(\mathbf{Z}^T\mathbf{Z}) = \begin{bmatrix} |\mathbf{z}_0|^{-1} & & & & \\ & |\mathbf{z}_1|^{-1} & & \\ & & |\mathbf{z}_p|^{-1} \end{bmatrix} \begin{bmatrix} \mathbf{z}_0^T\mathbf{z}_0 & \mathbf{z}_0^T\mathbf{z}_1 & \cdots & \mathbf{z}_0^T\mathbf{z}_p \\ \mathbf{z}_1^T\mathbf{z}_0 & \mathbf{z}_1^T\mathbf{z}_1 & \cdots & \mathbf{z}_1^T\mathbf{z}_p \\ \vdots & & & \\ \mathbf{z}_p^T\mathbf{z}_0 & \mathbf{z}_p^T\mathbf{z}_1 & \cdots & \mathbf{z}_p^T\mathbf{z}_p \end{bmatrix}$$

$$= \begin{bmatrix} \mathbf{z}_0^T\mathbf{z}_0 & & & & \\ |\mathbf{z}_0| & & & & \\ & |\mathbf{z}_1| & & & \\ & |\mathbf{z}_p| \end{bmatrix}$$

Finally,

$$(\mathbf{D}^{-1}\mathbf{Z}^T\mathbf{Z})\mathbf{D}^{-1} = \begin{bmatrix} |\mathbf{z}_0| & & & \\ & |\mathbf{z}_1| & & \\ & & \ddots & \\ & & & |\mathbf{z}_p| \end{bmatrix} \begin{bmatrix} |\mathbf{z}_0|^{-1} & & & \\ & |\mathbf{z}_1|^{-1} & & \\ & & \ddots & \\ & & & |\mathbf{z}_p|^{-1} \end{bmatrix}$$

$$= \mathbf{I}$$

Eq 3.32 & 3.33: (ESL p.55)

$$\hat{\beta} = \mathbf{R}^{-1} \mathbf{Q}^T \mathbf{y}$$
$$\hat{\mathbf{y}} = \mathbf{Q} \mathbf{Q}^T \mathbf{y}$$

 $\mathbf{Proof}:$ 

$$\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \tag{3.6}$$

$$\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\beta}} \tag{3.7}$$

$$\mathbf{X} = \mathbf{QR} \tag{3.31}$$

$$\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

$$= [(\mathbf{Q} \mathbf{R})^T \mathbf{Q} \mathbf{R}]^{-1} (\mathbf{Q} \mathbf{R})^T \mathbf{y}$$

$$= (\mathbf{R}^T \mathbf{Q}^T \mathbf{Q} \mathbf{R})^{-1} \mathbf{R}^T \mathbf{Q}^T \mathbf{y}$$

$$(\text{since } \mathbf{Q}^T \mathbf{Q} = \mathbf{I})$$

$$= (\mathbf{R}^T \mathbf{R})^{-1} \mathbf{R}^T \mathbf{Q}^T \mathbf{y}$$

$$= \mathbf{R}^{-1} (\mathbf{R}^T)^{-1} \mathbf{R}^T \mathbf{Q}^T \mathbf{y}$$

$$(\text{since } (\mathbf{R}^T)^{-1} \mathbf{R}^T = \mathbf{I})$$

$$= \mathbf{R}^{-1} \mathbf{Q}^T \mathbf{y}$$

$$\therefore \hat{\mathbf{y}} = \mathbf{X} \hat{\beta} = (\mathbf{Q} \mathbf{R}) \mathbf{R}^{-1} \mathbf{Q}^T \mathbf{y} = \mathbf{Q} \mathbf{Q}^T \mathbf{y}$$

Eq 3.46: (ESL p.66)

$$\mathbf{X}\hat{\beta}^{\text{ls}} = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y}$$
$$= \mathbf{U}\mathbf{U}^T\mathbf{y}$$

**Proof**:

$$\mathbf{X} = \mathbf{U}\mathbf{D}\mathbf{V}^T$$

$$\mathbf{U}: N \times p \text{ orthonormal } \rightarrow \mathbf{U}^T \mathbf{U} = \mathbf{I}$$

 $\mathbf{D}: p \times p$  diagonal

$$\mathbf{V}: p \times p \text{ orthonormal } \rightarrow \mathbf{V}^T \mathbf{V} = \mathbf{I}$$

$$\mathbf{X}^{T}\mathbf{X} = (\mathbf{U}\mathbf{D}\mathbf{V}^{T})^{T}\mathbf{U}\mathbf{D}\mathbf{V}^{T}$$

$$= \mathbf{V}\mathbf{D}^{T}\mathbf{U}^{T}\mathbf{U}\mathbf{D}\mathbf{V}^{T}$$

$$(\text{since } \mathbf{U}^{T}\mathbf{U} = \mathbf{I})$$

$$= \mathbf{V}\mathbf{D}^{T}\mathbf{D}\mathbf{V}^{T}$$

If **A** and **B** are square matrices,  $(\mathbf{AB})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$ .

Since  $\mathbf{V}\mathbf{D}^T$  and  $\mathbf{D}\mathbf{V}^T$  are square matrices,

$$(\mathbf{X}^T\mathbf{X})^{-1} = (\mathbf{V}\mathbf{D}^T\mathbf{D}\mathbf{V}^T)^{-1} = (\mathbf{D}\mathbf{V}^T)^{-1}(\mathbf{V}\mathbf{D}^T)^{-1}$$

**Eq 3.47:** (ESL p.66)

$$\mathbf{X}\hat{\beta}^{\text{ridge}} = \mathbf{X}(\mathbf{X}^T\mathbf{X} + \lambda \mathbf{I})^{-1}\mathbf{X}^T\mathbf{y}$$
$$= \mathbf{U}\mathbf{D}(\mathbf{D}^2 + \lambda \mathbf{I})^{-1}\mathbf{D}\mathbf{U}^T\mathbf{y}$$

Proof:

Using  $\mathbf{X}^T \mathbf{X} = \mathbf{V} \mathbf{D}^T \mathbf{D} \mathbf{V}^T$  from the derivation of Eq (3.46),

$$\mathbf{X}^{T}\mathbf{X} + \lambda \mathbf{I} = \mathbf{V}\mathbf{D}^{T}\mathbf{D}\mathbf{V}^{T} + \lambda \mathbf{I}\mathbf{V}\mathbf{V}^{T}$$
$$= \mathbf{V}(\mathbf{D}^{T}\mathbf{D} + \lambda \mathbf{I})\mathbf{V}^{T}$$

Since all three matrices have  $p \times p$  dimension;  $\mathbf{V}$ ,  $(\mathbf{D}^T \mathbf{D} + \lambda \mathbf{I})$ ,  $\mathbf{V}^T$ .

$$\Rightarrow$$
  $(\mathbf{X}^T\mathbf{X} + \lambda \mathbf{I})^{-1} = (\mathbf{V}^T)^{-1}(\mathbf{D}^T\mathbf{D} + \lambda \mathbf{I})^{-1}\mathbf{V}^{-1}$ 

$$\therefore \mathbf{X}(\mathbf{X}^T\mathbf{X} + \lambda \mathbf{I})^{-1}\mathbf{X}^T\mathbf{y} = (\mathbf{U}\mathbf{D}\mathbf{V}^T)[(\mathbf{V}^T)^{-1}(\mathbf{D}^T\mathbf{D} + \lambda \mathbf{I})^{-1}\mathbf{V}^{-1}](\mathbf{V}\mathbf{D}^T\mathbf{U}^T)\mathbf{y}$$

$$= \mathbf{U}\mathbf{D}(\mathbf{D}^2 + \lambda \mathbf{I})^{-1}\mathbf{D}\mathbf{U}^T\mathbf{y}$$

**Eq 3.49:** (ESL p.66)

$$\operatorname{Var}(\mathbf{z}_1) = \operatorname{Var}(\mathbf{X}v_1) = \frac{d_1^2}{N}$$

#### Proof:

We know that

$$Covar(X) = \frac{\mathbf{X}^T \mathbf{X}}{N} = \frac{\mathbf{V} \mathbf{D}^2 \mathbf{V}^T}{N}$$

Let's calculate  $Var(v_1^T \mathbf{X})$  instead of  $Var(\mathbf{X}v_1)$ , since they are the same.

$$\operatorname{Var}(v_{1}\mathbf{X}) = \operatorname{E}[(v_{1}^{T}\mathbf{X} - v_{1}^{T}\mathbf{X})(v_{1}^{T}\mathbf{X} - v_{1}^{T}\mathbf{X})^{T}]$$

$$= v_{1}^{T}\operatorname{E}[(\mathbf{X} - \mathbf{X})(\mathbf{X} - \mathbf{X})^{T}]v_{1}$$

$$= v_{1}^{T}\operatorname{Covar}(\mathbf{X})v_{1}$$

$$= v_{1}^{T}\frac{\mathbf{V}\mathbf{D}^{2}\mathbf{V}^{T}}{N}v_{1}$$

$$= (v_{1}^{T}\mathbf{V})\frac{\mathbf{D}^{2}}{N}(\mathbf{V}^{T}v_{1})$$

$$= \frac{1}{N}\begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \end{bmatrix} \begin{bmatrix} d_{1}^{2} & & & \\ & d_{2}^{2} & & \\ & & \ddots & \\ & & & d_{p}^{2} \end{bmatrix} \begin{bmatrix} 1 & & \\ 0 & & \\ \vdots & & \\ 0 & & \\ \vdots & & \\ 0 & & \end{bmatrix}$$

$$= \frac{1}{N}\begin{bmatrix} d_{1}^{2} & 0 & 0 & \cdots & 0 \end{bmatrix} \begin{bmatrix} 1 & & \\ 0 & & \\ \vdots & & \\ 0 & & \\ \vdots & & \\ 0 & & \\ \vdots & & \\ 0 & & \\ \end{bmatrix}$$

# Chapter 5. Basis Expansions and Regularization

**Eq 5.18:** (ESL p.154)

$$RSS = (\mathbf{y} - \mathbf{f})^T (\mathbf{y} - \mathbf{f}) + \lambda \mathbf{f}^T \mathbf{K} \mathbf{f}$$

Proof:

From Exercise 5.9,

$$\mathbf{K} = \mathbf{N}^{-1} \mathbf{\Omega}_N \mathbf{N}^{-1}$$
  
 $\Rightarrow \mathbf{\Omega}_N = \mathbf{N}^T \mathbf{K} \mathbf{N}$ 

$$RSS = (\mathbf{y} - \mathbf{N}\theta)^T (\mathbf{y} - \mathbf{N}\theta) + \lambda \theta^T \mathbf{\Omega}_N \theta$$
 (5.11)

Since  $\mathbf{f} = \mathbf{N}\theta$  (Eq 5.13),

RSS = 
$$(\mathbf{y} - \mathbf{f})^T (\mathbf{y} - \mathbf{f}) + \lambda \theta^T (\mathbf{N}^T \mathbf{K} \mathbf{N}) \theta$$
  
=  $(\mathbf{y} - \mathbf{f})^T (\mathbf{y} - \mathbf{f}) + \lambda (\mathbf{N} \theta)^T \mathbf{K} (\mathbf{N} \theta)$   
 $\therefore \text{RSS} = (\mathbf{y} - \mathbf{f})^T (\mathbf{y} - \mathbf{f}) + \lambda \mathbf{f}^T \mathbf{K} \mathbf{f}$ 

Eq 5.31 & 5.32: (ESL p.162)

$$\begin{split} \frac{\partial l(\theta)}{\partial \theta} &= \mathbf{N}^T (\mathbf{y} - \mathbf{p}) - \lambda \mathbf{\Omega} \theta \\ \frac{\partial^2 l(\theta)}{\partial \theta \ \partial \theta^T} &= - \mathbf{N}^T \mathbf{W} \mathbf{N} - \lambda \mathbf{\Omega} \end{split}$$

Proof:

$$l(f;\lambda) = \sum_{i=1}^{N} [y_i f(x_i) - \log(1 + e^{f(x_i)})] - \frac{1}{2} \lambda \int \{f''(t)\}^2 dt$$

$$\Rightarrow l(\theta) = \mathbf{y} \mathbf{N} \theta - \log(1 + e^{\mathbf{N} \theta}) - \frac{1}{2} \lambda \int \theta^T \mathbf{N}''^T \mathbf{N} \theta dt$$

$$\frac{\partial l(\theta)}{\partial \theta} = \mathbf{y} \mathbf{N} - \frac{N e^{N \theta}}{1 + e^{\mathbf{N} \theta}} - \lambda \int \theta^T \mathbf{N}''^T \mathbf{N}'' dt$$
(5.30)

Since 
$$\mathbf{p} = \frac{e^{\mathbf{N}\theta}}{1 + e^{\mathbf{N}\theta}}$$
,

$$\frac{\partial l(\theta)}{\partial \theta} = \mathbf{y}^{T} \mathbf{N} - \mathbf{N} \mathbf{p} - \lambda \mathbf{\Omega} \theta$$

$$= \mathbf{N}^{T} (\mathbf{y} - \mathbf{p}) - \lambda \mathbf{\Omega} \theta$$
where  $\mathbf{\Omega} = \int \mathbf{N}''^{T} \mathbf{N}'' dt$  (see Eq 5.11)
$$\frac{\partial^{2} l(\theta)}{\partial \theta \partial \theta^{T}} = -\mathbf{N} \frac{\mathbf{N} \theta e^{\mathbf{N} \theta}}{1 + e^{\mathbf{N} \theta}} + \frac{\mathbf{N} e^{\mathbf{N} \theta} \mathbf{N} e^{\mathbf{N} \theta}}{(1 + e^{\mathbf{N} \theta})^{2}} - \lambda \mathbf{\Omega}$$

$$= -\mathbf{N}^{2} \mathbf{p} + \mathbf{N}^{2} \mathbf{p} \mathbf{p}^{T} - \lambda \mathbf{\Omega}$$

$$= -\mathbf{N}^{T} \mathbf{p} (1 - \mathbf{p})^{T} \mathbf{N} - \lambda \mathbf{\Omega}$$

$$= -\mathbf{N}^{T} \mathbf{W} \mathbf{N} - \lambda \mathbf{\Omega}$$
where  $\mathbf{W} = \mathbf{p} (1 - \mathbf{p})^{T}$ 

## **Eq 5.33:** (ESL p.162)

$$\theta^{new} = (\mathbf{N}^T \mathbf{W} \mathbf{N} + \lambda \mathbf{\Omega})^{-1} \mathbf{N}^T \mathbf{W} (\mathbf{N} \theta^{old} + \mathbf{W}^{-1} (\mathbf{y} - \mathbf{p}))$$

#### Proof:

We want to find  $\theta$  for  $\frac{\partial l(\theta)}{\partial \theta} = 0$  (Eq 5.31).

The Newton-Raphson method is to find f(x) = 0, so in our case  $f(x) = \frac{\partial l(\theta)}{\partial \theta}$ .

The Newton-Raphson method for f(x) says,

$$\mathbf{w}_1 = \mathbf{w}_0 - \frac{f(\mathbf{w}_0)}{f'(\mathbf{w}_0)}$$

So in our case it will be

$$\begin{split} \theta^{new} &= \theta^{old} - \frac{\left(\frac{\partial l(\theta)}{\partial \theta}\right)}{\left(\frac{\partial^2 l(\theta)}{\partial \theta \partial \theta^T}\right)} \\ &= \theta^{old} + \frac{\mathbf{N}^T(\mathbf{y} - \mathbf{p}) - \lambda \mathbf{\Omega} \theta^{old}}{\mathbf{N}^T \mathbf{W} \mathbf{N} - \lambda \mathbf{\Omega}} \\ &= \frac{\theta^{old}(\mathbf{N}^T \mathbf{W} \mathbf{N} - \lambda \mathbf{\Omega}) + \mathbf{N}^T(\mathbf{y} - \mathbf{p}) - \lambda \mathbf{\Omega} \theta^{old}}{\mathbf{N}^T \mathbf{W} \mathbf{N} - \lambda \mathbf{\Omega}} \end{split}$$

Numerator = 
$$\mathbf{N}^T \mathbf{W} [\theta^{old} (\mathbf{N} - (\mathbf{N}^T \mathbf{W})^{-1} \lambda \mathbf{\Omega}) + (\mathbf{N}^T \mathbf{W})^{-1} \mathbf{N}^T (\mathbf{y} - \mathbf{p}) - (\mathbf{N}^T \mathbf{W})^{-1} \lambda \mathbf{\Omega} \theta^{old}]$$
  
=  $\mathbf{N}^T \mathbf{W} [\theta^{old} (\mathbf{N} - \mathbf{W}^{-1} (\mathbf{N}^T)^{-1} \lambda \mathbf{\Omega}) + \mathbf{W}^{-1} (\mathbf{N}^T)^{-1} \mathbf{N}^T (\mathbf{y} - \mathbf{p})$   
 $- \mathbf{W}^{-1} (\mathbf{N}^T)^{-1} \lambda \mathbf{\Omega} \theta^{old}]$   
=  $\mathbf{N}^T \mathbf{W} (\mathbf{N} \theta^{old} + \mathbf{W}^{-1} (\mathbf{y} - \mathbf{p}))$   
 $\therefore \theta^{new} = (\mathbf{N}^T \mathbf{W} \mathbf{N} + \lambda \mathbf{\Omega})^{-1} \mathbf{N}^T \mathbf{W} (\mathbf{N} \theta^{old} + \mathbf{W}^{-1} (\mathbf{y} - \mathbf{p}))$ 

## ESL p.187:

"If we adopt the convention that  $B_{i,1}=0$  if  $\tau_i=\tau_{i+1}$ , then by induction  $B_{i,m}=0$  if  $\tau_i=\tau_{i+1}=\cdots=\tau_{i+m}$ ."

**Proof**: (Ref: Wikipedia/B-Spline)

$$B_{i,m}(x) = \frac{x - \tau_i}{\tau_{i+m-1} - \tau_i} B_{i,m-1}(x) + \frac{\tau_{i+m} - x}{\tau_{i+m} - \tau_{i+1}} B_{i+1,m-1}(x)$$
(5.78)

To prove this, the notation at the Wiki is more convenient.

$$B_{i,k+1}(x) = w_{i,k}B_{i,k}(x) + [1 - w_{i+1,k}(x)]B_{i+1,k}(x)$$
where  $w_{i,k}(x) = \begin{cases} \frac{x - \tau_i}{\tau_{i+k} - \tau_i} & \text{if } \tau_{i+k} \neq \tau_i \\ 0 & \text{otherwise} \end{cases}$  (1)

Let's show Eq (5.78) and Eq (1) are equivalent.

If we use m = k + 1 in Eq (5.78), it becomes

$$B_{i,k+1} = \frac{x - \tau_i}{\tau_{i+k} - \tau_i} B_{i,k} + \frac{\tau_{i+k+1} - x}{\tau_{i+k+1} - \tau_{i+1}} B_{i+1,k}$$
 (2)

If we define 
$$\frac{x - \tau_i}{\tau_{i+k} - \tau_i} \equiv w_{i,k}$$
, then

$$1 - w_{i+1,k} = 1 - \frac{x - \tau_{i+1}}{\tau_{i+k+1} - \tau_{i+1}} = \frac{\tau_{i+k+1} - x}{\tau_{i+k+1} - \tau_{i+1}}$$

This is the same as the second term in Eq (2). Therefore Eq (5.78) and Eq (1) are equivalent. Now let's prove  $B_{i,m}=0$  if  $\tau_i=\tau_{i+1}=\cdots=\tau_{i+m}$ . We already have  $B_{i,1}=0$  if  $\tau_i=\tau_{i+1}$  from convention.

Let's show  $B_{i,2} = 0$  if  $\tau_i = \tau_{i+1} = \tau_{i+2}$ .

From Eq (1), when k = 1,

$$B_{i,2} = w_{i,1}B_{i,1} + [1 - w_{i+1,1}]B_{i+1,1} = 0$$

 $B_{i+1,1} = 0$  if  $\tau_i = \tau_{i+1}$ . This is simply from  $B_{i,1} = 0$  if  $\tau_i = \tau_{i+1}$ . (Since i is any number.) We keep doing this until k = m - 1.

$$B_{i,m} = w_{i,m-1}B_{i,m-1} + [1 - w_{i+1,m-1}]B_{i+1,m-1}$$

where we know  $B_{i,m-1} = 0$ .

We have to show  $B_{i+1,m-1}=0$  if  $\tau_i=\tau_{i+1}=\cdots=\tau_{i+m}$ . So far we have  $B_{i,m-1}=0$  if  $\tau_i=\tau_{i+1}=\cdots=\tau_{i+m-1}$ . If we simply use  $i\to i+1$ , then  $B_{i+1,m-1}=0$  if  $\tau_i=\tau_{i+1}=\cdots=\tau_{(i+1)+m-1}$ .

$$\therefore B_{i,m} = 0 \text{ if } \tau_i = \tau_{i+1} = \dots = \tau_{i+m}$$

# Chapter 7. Model Assessment and Selection

**Eq 7.10:** (ESL p.223)

$$\operatorname{Err}(x_0) = \operatorname{E}[(Y - \hat{f}_k(x_0))^2 | X = x_0]$$

$$= \sigma_{\epsilon}^2 + \left[ f(x_0) - \frac{1}{k} \sum_{l=1}^k f(x_{(l)}) \right]^2 + \frac{\sigma_{\epsilon}^2}{k}$$

#### Proof:

This is a K-Nearest Neighbor problem. The important thing to understand about this problem is that the inputs  $x_i$  are fixed for simplicity. When  $x_i$ 's are fixed in KNN, there will be only  $y_i$  differences due to the intrinsic noise  $\epsilon$ .

$$Y = f(X) + \epsilon, \qquad \epsilon \sim \mathcal{N}(0, \sigma_{\epsilon}^2)$$

$$\Rightarrow y_i = f(x_i) + \epsilon$$

where Y is a random variable and  $x_i$  is an input.

The prediction per a sample will be

$$\hat{f}(x_i) = \frac{1}{k} \sum_{l=1}^{k} y_{(l)}$$
 (*l* is NN for  $x_i$ )
$$= \frac{1}{k} \sum_{l=1}^{k} [f(x_{(l)}) + \epsilon_{(l)}]$$

Expected prediction over the samples  $(\mathcal{T})$  will be,

$$\mathbf{E}_{\mathcal{T}}\hat{f}(x_i) = \frac{1}{k} \sum_{l=1}^{k} f(x_{(l)})$$

This solves the second term in Eq (7.10).

As for the third term  $\sigma_{\epsilon}^2/k$ ,

$$\operatorname{Var}_{\mathcal{T}}(\hat{f}(x_{i})) = \operatorname{Var}_{\mathcal{T}} \left[ \frac{1}{k} \sum_{l=1}^{k} f(x_{(l)}) + \frac{1}{k} \sum_{l=1}^{k} \epsilon_{(l)} \right]$$

$$= \operatorname{Var}_{\mathcal{T}} \left( \frac{1}{k} \sum_{l=1}^{k} \epsilon_{(l)} \right)$$

$$= \frac{1}{k^{2}} \operatorname{Var}_{\mathcal{T}}(\epsilon_{(1)} + \epsilon_{(2)} + \dots + \epsilon_{(k)})$$

$$= \frac{1}{k^{2}} (k \sigma_{\epsilon}^{2}) \qquad (\leftarrow \operatorname{Var}_{\mathcal{T}}(\epsilon_{(l)}) = \sigma_{\epsilon}^{2})$$

$$= \frac{1}{k} \sigma_{\epsilon}^{2}$$

## **Eq 7.11:** (ESL p.224)

$$\operatorname{Err}(x_0) = \operatorname{E}[(Y - \hat{f}_p(x_0))^2 | X = x_0]$$

$$= \sigma_{\epsilon}^2 + [f(x_0) - \operatorname{E}\hat{f}_p(x_0)]^2 + \|\mathbf{h}(x_0)\|^2 \sigma_{\epsilon}^2$$
where  $\mathbf{h}(x_0) = \mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} x_0$ 

Proof:

For a linear model, we have  $y = X\beta + \epsilon$ .

$$\hat{f}_p(x) = x^T \hat{\beta}$$

$$\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T y \qquad \text{(from least squares)}$$

$$\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T (\mathbf{X} \beta + \epsilon)$$

$$= \beta + (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \epsilon$$
(3.6)

We have  $E_{\mathcal{T}}(\epsilon) = 0$  and  $E(\epsilon \epsilon^T) = \sigma^2 \mathbf{I}$ .

$$\Rightarrow \quad \mathrm{E}_{\mathcal{T}}(\hat{\beta}) = \beta$$

$$\operatorname{Var}_{\mathcal{T}}(\hat{\beta}) = \operatorname{E}_{\mathcal{T}}(\hat{\beta}\hat{\beta}^{T}) - \operatorname{E}_{\mathcal{T}}(\hat{\beta})\operatorname{E}_{\mathcal{T}}(\hat{\beta}^{T})$$

$$= (\mathbf{X}^{T}\mathbf{X})^{-1}\sigma^{2} \qquad (\text{See Weatherwax p.9})$$

$$\operatorname{Var}_{\mathcal{T}}(\hat{y_{0}}) = \operatorname{Var}_{\mathcal{T}}(x_{0}^{T}\hat{\beta})$$

$$= x_{0}^{T}\operatorname{Var}_{\mathcal{T}}(\hat{\beta})x_{0}$$

$$= x_{0}^{T}(\mathbf{X}^{T}\mathbf{X})^{-1}\sigma^{2}x_{0}$$

Let's calculate  $\mathbf{h}(x_0)^T \cdot \mathbf{h}(x_0)$ ,

$$[\mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}x_0]^T [\mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}x_0] = x_0^T [(\mathbf{X}^T\mathbf{X})^{-1}]^T \mathbf{X}^T \mathbf{X} (\mathbf{X}^T\mathbf{X})^{-1}x_0$$
(Since  $[(\mathbf{X}^T\mathbf{X})^{-1}]^T = [(\mathbf{X}^T\mathbf{X})^T]^{-1} = (\mathbf{X}^T\mathbf{X})^{-1}$ )
$$= x_0^T (\mathbf{X}^T\mathbf{X})^{-1}x_0$$

$$\therefore \operatorname{Var}_{\mathcal{T}}(\hat{y_0}) = \operatorname{Var}_{\mathcal{T}}(\hat{f_p}(x_0)) = \|\mathbf{h}(x_0)\|^2 \sigma_{\epsilon}^2$$

**Eq 7.41:** (ESL p.235)

$$p(\mathcal{M}_m|\mathbf{Z}) \approx \frac{e^{-\frac{1}{2}\mathrm{BIC}_m}}{\sum_{l=1}^{M} e^{-\frac{1}{2}\mathrm{BIC}_l}}$$

Proof:

$$\log p(\mathbf{Z}|\mathcal{M}_m) = \log p(\mathbf{Z}|\hat{\theta}_m, \mathcal{M}_m) - \frac{d_m}{2}\log N + O(1)$$
(7.40)

$$BIC = -2 \log lik + (\log N)d \tag{7.35}$$

If we define our loss function to be  $-2 \log p(\mathbf{Z}|\hat{\theta}_m, \mathcal{M}_m)$ , Eq (7.40) becomes after dropping O(1), (multiply by -2)

$$-2\log p(\mathbf{Z}|\mathcal{M}_m) = -2\log p(\mathbf{Z}|\hat{\theta}_m, \mathcal{M}_m) + d_m \log N$$

where  $\log p(\mathbf{Z}|\mathcal{M}_m) = \text{BIC}$ , and  $\log p(\mathbf{Z}|\hat{\theta}_m, \mathcal{M}_m) = \text{loglik}$ .

$$\Rightarrow$$
 BIC<sub>m</sub> =  $-2 \log \text{lik} + d_m \log N$ 

This is same as Eq (7.35).

Since  $BIC_m = -2\log p(\mathbf{Z}|\mathcal{M}_m)$ ,

$$p(\mathbf{Z}|\mathcal{M}_m) = \exp\left(-\frac{1}{2}\mathrm{BIC}_m\right)$$
Posterior = 
$$\frac{p(\mathcal{M}_m) \cdot \exp\left(-\frac{1}{2}\mathrm{BIC}_m\right)}{p(\mathbf{Z})}$$

$$p(\mathcal{M}_m) \cdot \exp\left(-\frac{1}{2}\mathrm{BIC}_m\right)$$

$$= \frac{p(\mathcal{M}_m) \cdot \exp\left(-\frac{1}{2}BIC_m\right)}{\sum_{l=1}^{M} p(\mathbf{Z}|\mathcal{M}_l)}$$
$$= \frac{p(\mathcal{M}_m) \cdot \exp\left(-\frac{1}{2}BIC_m\right)}{\sum_{l=1}^{M} \exp\left(-\frac{1}{2}BIC_l\right)}$$

**Eq 7.59:** (ESL p.252)

$$\hat{\gamma} = \hat{p}_1(1 - \hat{q}_1) + (1 - \hat{p}_1)\hat{q}_1$$

Proof:

$$\hat{\gamma} = \frac{1}{N^2} \sum_{i=1}^{N} \sum_{i'=1}^{N} L(y_i, \hat{f}(x_{i'}))$$

$$= \frac{1}{N^2} \left[ \sum_{i \in p_1} \sum_{i' \in q_0} L(y_i, \hat{f}(x_{i'})) + \sum_{i \in p_0} \sum_{i' \in q_1} L(y_i, \hat{f}(x_{i'})) \right]$$

In the above equation, L=0 for the cases of i and i' other than the values defined in the equation. Since L=1 in the above equation,

$$\hat{\gamma} = \frac{1}{N^2} \left[ \sum_{i \in p_1} \sum_{i' \in q_0} 1 + \sum_{i \in p_0} \sum_{i' \in q_1} 1 \right]$$

$$= \frac{1}{N} \sum_{i \in p_1} \left( \sum_{i' \in q_0} \frac{1}{N} \right) + \frac{1}{N} \sum_{i \in p_0} \left( \sum_{i' \in q_1} \frac{1}{N} \right)$$

Since 
$$\sum_{i' \in q_0} \frac{1}{N} = 1 - \hat{q}_1$$
, and  $\sum_{i' \in q_1} \frac{1}{N} = \hat{q}_1$ ,

$$\hat{\gamma} = \frac{1}{N} \sum_{i \in p_1} (1 - \hat{q}_1) + \frac{1}{N} \sum_{i \in p_0} (\hat{q}_1)$$

Since 
$$\frac{1}{N} \sum_{i \in p_1} = \hat{p}_1$$
, and  $\frac{1}{N} \sum_{i \in p_0} = 1 - \hat{p}_1$ ,

$$\hat{y} = \hat{p}_1(1 - \hat{q}_1) + (1 - \hat{p}_1)(\hat{q}_1)$$

# Chapter 8. Model Inference and Averaging

**Eq 8.30:** (ESL p.271)

$$p(\theta|z) \sim \mathcal{N}\left(\frac{z}{1+1/\tau}, \frac{1}{1+1/\tau}\right)$$

**Proof**:

$$p(z) \sim \mathcal{N}(\theta, 1)$$
 (8.29)

Since Eq (8.29) is equivalent to  $p(z|\theta)$ ,

$$\Rightarrow \quad p(z|\theta) = \frac{1}{(2\pi)^{1/2}} \cdot \exp\left\{-\frac{1}{2}(z-\theta)^2\right\} \qquad \text{likelihood}$$
 Posterior  $p(\theta|z) = \frac{p(z|\theta) \cdot p(\theta)}{p(z)}$ 

$$\begin{split} p(\theta|z) &\sim p(z|\theta) \cdot p(\theta) \\ &= \frac{1}{(2\pi)^{1/2}} \cdot \exp\left\{-\frac{1}{2}(z-\theta)^2\right\} \frac{1}{(2\pi)^{1/2}\tau^{1/2}} \exp\left(-\frac{1}{2\tau}\theta^2\right) \\ &= \frac{1}{2\pi\,\tau^{1/2}} \cdot \exp\left\{-\frac{1}{2}(z-\theta)^2 - \frac{\theta^2}{2\tau}\right\} \\ &= \frac{1}{2\pi\,\tau^{1/2}} \cdot \exp\left\{-\frac{1}{2}\left[(z-\theta)^2 + \frac{\theta^2}{2\tau}\right]\right\} \end{split}$$

$$(z-\theta)^2 + \frac{\theta^2}{2\tau} = z^2 - 2z\theta + \theta^2 + \frac{\theta^2}{\tau}$$

$$= \left(1 + \frac{1}{\tau}\right)\theta^2 - 2z\theta + z^2$$

$$= \left(1 + \frac{1}{\tau}\right)\left[\left(\theta - \frac{z}{1+1/\tau}\right)^2 + \frac{z^2}{(1+1/\tau)} - \frac{z^2}{(1+1/\tau)^2}\right]$$

$$\therefore p(\theta|z) \sim \mathcal{N}\left(\frac{z}{1+1/\tau}, \frac{1}{1+1/\tau}\right)$$

**Eq 8.54:** (ESL p.289)

$$E(\zeta|\mathbf{Z}) = \sum_{m=1}^{M} E(\zeta|\mathcal{M}_m, \mathbf{Z}) p(\mathcal{M}_m|\mathbf{Z})$$

Proof:

$$E(\zeta|\mathbf{Z}) = \int \zeta p(\zeta|\mathbf{Z}) d\zeta$$

$$= \int \zeta \sum_{m} p(\zeta|\mathcal{M}_{m}, \mathbf{Z}) \cdot p(\mathcal{M}_{m}|\mathbf{Z}) d\zeta$$

$$= \sum_{m} \int \zeta p(\zeta|\mathcal{M}_{m}, \mathbf{Z}) d\zeta \cdot p(\mathcal{M}_{m}|\mathbf{Z})$$
(Since 
$$\int \zeta p(\zeta|\mathcal{M}_{m}, \mathbf{Z}) d\zeta = E(\zeta|\mathcal{M}_{m}, \mathbf{Z})$$

$$= \sum_{m} E(\zeta|\mathcal{M}_{m}, \mathbf{Z}) \cdot p(\mathcal{M}_{m}|\mathbf{Z})$$

# Chapter 9. Additive Models, Trees

**Eq 9.11:** (ESL p.307)

$$\hat{c}_m = \operatorname{ave}(y_i | x_i \in R_m)$$

Proof:

$$L = \sum_{i} (y_i - f(x_i))^2$$

$$\frac{\partial L}{\partial c_m} = \sum_{i} 2(y_i - f(x_i)) \cdot \left(-\frac{\partial f(x_i)}{\partial c_m}\right)$$

$$f(x_i) = \sum_{m=1}^{M} c_m I(x_i \in R_m)$$

$$\frac{\partial f(x_i)}{\partial c_m} = I(x_i \in R_m)$$

$$\frac{\partial L}{\partial c_m} = \sum_{i} 2(y_i - f(x_i)) \cdot (-I(x_i \in R_m)) = 0$$

$$(9.10)$$

 $\Rightarrow$  Two conditions:

1. 
$$I(x_i \in R_m) = 1$$

2. 
$$\sum_{i} (y_i - f(x_i)) = \sum_{i} \left[ y_i - \sum_{m=1}^{M} c_m I(x_i \in R_m) \right] = 0$$

$$\Rightarrow \sum_{i} [y_i | x_i \in R_m - C_m I(x_i \in R_m)] = 0$$

$$\Rightarrow \sum_{i} [y_i | x_i \in R_m] = C_m \sum_{i} I(x_i \in R_m)$$

where  $\sum_{i} I(x_i \in R_m) = \#$  of  $x_i$ 's belonging to  $R_m$ .

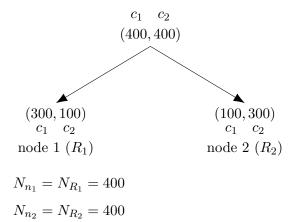
$$\therefore c_m = \frac{\sum_i [y_i | x_i \in R_m]}{\text{# of } x_i \text{'s belonging to } R_m}$$
$$= \text{ave}(y_i | x_i \in R_m)$$

## ESL p. 309:

"For example, in a two-class problem with 400 observations in each class (denote this by (400, 400)), suppose one split created nodes (300, 100) and (100, 300), while the other created nodes (200, 400) and (200, 0). Both splits produce a mis-classification rate of 0.25."

#### Proof:

1. First case



Misclassification error:

$$\frac{1}{N_m} \sum_{i \in R_m} I(y_i \neq k(m)) = 1 - \hat{p}_{mk(m)}$$

Let's calculate  $\hat{p}_{mk}$ 's,

$$\hat{p}_{mk} = \frac{1}{N_m} \sum_{i \in R_m} I(y_i = k)$$

 $n_1$ : node 1, and  $n_2$ : node 2

$$\hat{p}_{n_1c_1} = \frac{1}{400} \sum_{x_i \in R_1} I(y_i = c_1) = \frac{1}{400} \cdot 300 = \frac{3}{4}$$

$$\hat{p}_{n_1c_2} = \frac{1}{400} \sum_{x_i \in R_1} I(y_i = c_2) = \frac{1}{400} \cdot 100 = \frac{1}{4}$$

$$\hat{p}_{n_2c_1} = \frac{1}{400} \sum_{x_i \in R_2} I(y_i = c_1) = \frac{100}{400} = \frac{1}{4}$$

$$\hat{p}_{n_2c_2} = 1 - \hat{p}_{n_2c_1} = \frac{3}{4}$$

ME:

For node 1:  $k(n_1) = c_1$ 

$$\frac{1}{N_{n_1}} \sum_{x_i \in R_1} I(y_i \neq k(n_1)) = \frac{1}{400} \sum_{x_i \in R_1} I(y_i \neq c_1) = \frac{1}{4}$$

For node 2:  $k(n_2) = c_2$ 

$$\frac{1}{N_{n_2}} \sum_{x_i \in R_1} I(y_i \neq c_2) = \frac{1}{400} \cdot 100 = \frac{1}{4}$$

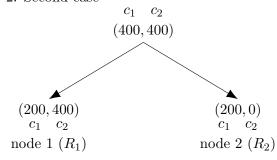
We can calculate this from  $1 - \hat{p}_{mk(m)}$ .

For node 1, 
$$ME_1 = 1 - \hat{p}_{n_1 k(n_1)} = 1 - \frac{3}{4} = \frac{1}{4}$$
  
For node 2,  $ME_2 = 1 - \hat{p}_{n_2 k(n_2)} = 1 - \frac{3}{4} = \frac{1}{4}$ 

Now to calculate the combined ME, we use the suggestion given in p.309, saying that we need to weight the node impurity measures by the number  $N_{m_L}$  and  $N_{m_R}$  of observations in the two child nodes.

$$\begin{aligned} \text{ME}_{combined} &= \frac{N_{n_1}}{N_{n_1} + N_{n_2}} \cdot \text{ME}_1 + \frac{N_{n_2}}{N_{n_1} + N_{n_2}} \cdot \text{ME}_2 \\ &= \frac{400}{800} \cdot \frac{1}{4} + \frac{400}{800} \cdot \frac{1}{4} = \frac{1}{4} \end{aligned}$$

## 2. Second case



$$N_{n_1} = 600$$

$$N_{n_2} = 200$$

$$\hat{p}_{n_1c_1} = \frac{1}{600} \sum_{x_i \in R_1} I(y_i = c_1) = \frac{1}{600} \cdot 200 = \frac{1}{3}$$

$$\hat{p}_{n_1c_2} = \frac{2}{3}$$

$$\hat{p}_{n_2c_1} = \frac{1}{200} \sum_{x_i \in R_2} I(y_i = c_1) = \frac{1}{200} \cdot 200 = 1$$

$$\hat{p}_{n_2c_2} = 0$$

For node 1:  $k(n_1) = c_2$ 

$$ME_1 = 1 - \frac{2}{3} = \frac{1}{3}$$

For node 2:  $k(n_2) = c_1$ 

$$ME_2 = 1 - 1 = 0$$

$$ME_{combined} = \frac{600}{800} \cdot \frac{1}{3} + \frac{200}{800} \times 0 = \frac{1}{4}$$

where  $\frac{600}{800}$  is from weight  $=\frac{N_{n_1}}{N_{n_1} + N_{n_2}}$ .

# Chapter 10. Boosting and Additive Trees

**Eq 10.11:** (ESL p.344)

$$\sum_{i=1}^{N} w_i^{(m)} \exp\left(-\beta y_i G(x_i)\right) = \left(e^{\beta} - e^{-\beta}\right) \cdot \sum_{i=1}^{N} w_i^{(m)} I(y_i \neq G(x_i)) + e^{-\beta} \sum_{i=1}^{N} w_i^{(m)}$$

Proof:

$$\begin{split} \sum_{i=1}^{N} w_{i}^{(m)} \exp\left(-\beta y_{i} G(x_{i})\right) &= e^{-\beta} \sum_{y_{i} = G(x_{i})} w_{i}^{(m)} + e^{\beta} \sum_{y_{i} \neq G(x_{i})} w_{i}^{(m)} \\ &= e^{-\beta} \sum_{i=1}^{N} w_{i}^{(m)} I(y_{i} = G(x_{i})) + e^{\beta} \sum_{i=1}^{N} w_{i}^{(m)} I(y_{i} \neq G(x_{i})) \\ &= e^{-\beta} \sum_{i=1}^{N} w_{i}^{(m)} I(y_{i} = G(x_{i})) + \left\{ e^{-\beta} \sum_{i=1}^{N} w_{i}^{(m)} I(y_{i} \neq G(x_{i})) - e^{-\beta} \sum_{i=1}^{N} w_{i}^{(m)} I(y_{i} \neq G(x_{i})) \right\} + e^{\beta} \sum_{i=1}^{N} w_{i}^{(m)} I(y_{i} \neq G(x_{i})) \\ &= e^{-\beta} \sum_{i=1}^{N} w_{i}^{(m)} [I(y_{i} = G(x_{i})) + I(y_{i} \neq G(x_{i}))] \\ &+ (e^{\beta} - e^{-\beta}) \sum_{i=1}^{N} w_{i}^{(m)} I(y_{i} \neq G(x_{i})) \end{split}$$

Since  $I(y_i = G(x_i)) + I(y_i \neq G(x_i)) = 1$ ,

$$\therefore \sum_{i=1}^{N} w_i^{(m)} \exp\left(-\beta y_i G(x_i)\right) = e^{-\beta} \sum_{i=1}^{N} w_i^{(m)} + (e^{\beta} - e^{-\beta}) \sum_{i=1}^{N} w_i^{(m)} I(y_i \neq G(x_i))$$

**Eq 10.12:** (ESL p.344)

$$\beta_m = \frac{1}{2} \log \frac{1 - \operatorname{err}_m}{\operatorname{err}_m}$$
where  $\operatorname{err}_m = \frac{\sum_{i=1}^N w_i^{(m)} I(y_i \neq G_m(x_i))}{\sum_{i=1}^N w_i^{(m)}}$ 

Proof:

$$f(\beta) = (e^{\beta} - e^{-\beta}) \sum_{i=1}^{N} w_i^{(m)} I(y_i \neq G_m(x_i)) + e^{-\beta} \sum_{i=1}^{N} w_i^{(m)}$$

$$\frac{\partial f(\beta)}{\partial \beta} = \beta (e^{\beta} + e^{-\beta}) \sum_{i=1}^{N} w_i^{(m)} I(y_i \neq G_m(x_i)) - \beta e^{-\beta} \sum_{i=1}^{N} w_i^{(m)}$$

$$= 0$$

$$(e^{2\beta} + 1) \sum_{i=1}^{N} w_i^{(m)} I(y_i \neq G_m(x_i)) - \sum_{i=1}^{N} w_i^{(m)} = 0$$

$$(e^{2\beta} + 1) = \frac{1}{\text{err}_m}$$

$$\therefore \beta_m = \frac{1}{2} \log \frac{1 - \text{err}_m}{\text{err}_m}$$

**Eq 10.18:** (ESL p.346)

$$-l(Y, f(x)) = \log(1 + e^{-2Yf(x)})$$

Proof:

$$l(Y, f(x)) = Y' \log p(x) + (1 - Y') \log(1 - p(x))$$
  
where  $Y' \in \{0, 1\}$  and  $Y \in \{1, -1\}$ 

$$p(x) = p(Y = 1|x) = \frac{1}{1 + e^{-2f(x)}} = \sigma(2f(x))$$
(10.17)

And we know

$$1 - p(x) = 1 - \frac{1}{1 + e^{-2f(x)}} = \frac{1}{1 + e^{2f(x)}} = \sigma(-2f(x))$$

$$l(Y, f(x)) = \begin{cases} \log(p(x)) & \text{if } Y' = 1\\ \log(1 - p(x)) & \text{if } Y' = 0 \end{cases}$$

$$\log p(x) = -\log(1 + e^{-2f(x)}) \qquad \leftarrow \mathbf{Y} = 1 \text{ case}$$
$$\log (1 - p(x)) = -\log(1 + e^{2f(x)}) \qquad \leftarrow \mathbf{Y} = -1 \text{ case}$$

If we write both cases in one equation with  $Y \in \{1, -1\}$ ,

$$-l(Y, f(x)) = \log(1 + e^{-2Yf(x)})$$

## **Eq 10.19:** (ESL p.348)

$$E(Y|x) = 2p(Y = 1|x) - 1$$

## Proof:

From PRML Eq (1.89),

$$\begin{split} E(Y|x) &= \sum_{Y \in \{1,-1\}} Y p(Y|x) \\ &= 1 \cdot p(Y=1|x) + (-1) \cdot p(Y=-1|x) \\ &= p(Y=1|x) - [1 - p(Y=1|x)] \\ &= 2p(Y=1|x) - 1 \end{split}$$

**Eq 10.52:** (ESL p.370)

$$f_k(X) = \ln p_k(X) - \frac{1}{K} \sum_{l=1}^K \ln p_l(X)$$

 $\mathbf{Proof}:$ 

$$p_k(x) = \frac{e^{f_k(x)}}{1 + \sum_{l=1}^K e^{f_l(x)}}$$
 with constraint  $\sum_{k=1}^K f_k(x) = 0$ . (10.21)

Using Eq (10.21), let's prove the RHS of Eq (10.52) becomes  $f_k(X)$ .

$$\ln p_k(X) - \frac{1}{K} \sum_{l=1}^K \ln p_l(X)$$

$$= f_k(X) - \ln \left( 1 + \sum_{l=1}^K e^{f_l(x)} \right) - \frac{1}{K} \sum_{l=1}^K \left\{ f_k(X) - \ln \left( 1 + \sum_{k=1}^K e^{f_k(x)} \right) \right\}$$

$$= f_k(X) - \ln \left( 1 + \sum_{l=1}^K e^{f_l(x)} \right) - \frac{1}{K} \sum_{l=1}^K f_k(X) + \frac{1}{K} \sum_{l=1}^K \ln \left( 1 + \sum_{k=1}^K e^{f_k(x)} \right)$$

In the above equation, the third term = 0 since from the constraint ,  $\sum_{l=1}^{K} f_k(X) = 0$ .

The fourth term's sum over l does not affect inside the bracket.

$$\Rightarrow \ln p_k(X) - \frac{1}{K} \sum_{l=1}^K \ln p_l(X) = f_k(X) - \ln \left( 1 + \sum_{l=1}^K e^{f_l(x)} \right) + \frac{K}{K} \ln \left( 1 + \sum_{l=1}^K e^{f_l(x)} \right)$$
$$= f_k(X)$$

**Eq 10.54:** (ESL p.376)

$$E(Y|X) = E(Y|Y > 0, X) \cdot p(Y > 0|X)$$

Proof:

$$p(Y|X) = \frac{p(Y,X)}{p(X)}$$

$$p(Y,X) = p(Y,X|Y>0) \cdot p(>0) + p(Y,X|Y=0) \cdot P(Y=0) \quad \leftarrow \text{sum rule}$$

$$\Rightarrow \quad p(Y|X) = \frac{p(Y,X|Y>0) \cdot p(Y>0)}{p(X)} + \frac{p(Y,X|Y=0) \cdot p(Y=0)}{p(X)}$$

$$= p(Y|Y>0,X) \cdot p(Y>0) + p(Y|Y=0,X) \cdot p(Y=0)$$

$$\begin{split} \mathbf{E}(Y|X) &= \int Y p(Y)X)dY \\ &= \int p(Y|Y>0,X) \cdot p(Y>0)dY + \int p(Y|Y=0,X) \cdot p(Y=0)dY \\ &\text{(second term = 0, since Y = 0)} \\ &= \int p(Y|Y>0,X) \cdot p(Y>0)dY \\ &\text{(since p(Y>0) is a constant,)} \\ &= \int p(Y|Y>0,X)dY \cdot p(Y>0) \\ &= \mathbf{E}(Y|Y>0,X) \cdot p(Y>0) \end{split}$$

# Chapter 12. Support Vector Machines

**Eq 12.33:** (ESL p.433)

$$\beta_{\lambda} = \frac{1}{\lambda} \sum_{i=1}^{N} \alpha_i y_i x_i$$

Proof:

$$\min_{\beta,\beta_0} \frac{1}{2} \|\beta\|^2 + C \sum_{i=1}^{N} \xi_i$$
 (12.8)

subject to  $\xi_i \geq 0$ ,  $y_i(x_i^T \beta + \beta_0) \geq 1 - \xi_i \quad \forall_i$ 

$$\min_{\beta,\beta_0} \sum_{i=1}^{N} [1 - y_i f_i(x_i)]_+ + \frac{\lambda}{2} \|\beta\|^2$$
 (12.25)

Since the solutions of  $\beta$  are identical for both Eqs (12.8) and (12.25), we can write Eq (12.25) in the form of (12.8) with  $\lambda$  instead of C.  $(\frac{1}{\lambda} \leftrightarrow c)$ 

$$\min_{\beta,\beta_0} \frac{\lambda}{2} \|\beta\|^2 + \sum_{i=1}^{N} \xi_i$$
 (12.8a)

Then the new Lagrange function is

$$L'_{p} = \frac{\lambda}{2} \|\beta\|^{2} + \sum_{i=1}^{N} \xi_{i} - \sum_{i=1}^{N} \alpha_{i} [y_{i}(x_{i}^{T}\beta + \beta_{0}) - (1 - \xi_{i})] - \sum_{i=1}^{N} \mu_{i} \xi_{i}$$

$$\frac{\partial L'_{p}}{\partial \beta_{0}} = 0 \quad \rightarrow \quad \beta = \frac{1}{\lambda} \sum_{i=1}^{N} \alpha_{i} y_{i} x_{i}$$
(This proves Eq (12.33))
$$\frac{\partial L'_{p}}{\partial \beta_{0}} = 0 \quad \rightarrow \quad 0 = \sum_{i=1}^{N} \alpha_{i} y_{i}$$

$$\frac{\partial L'_{p}}{\partial \xi_{i}} = 0 \quad \rightarrow \quad \alpha_{i} = 1 - \mu_{i} \quad \forall_{i}$$
and  $\alpha_{i}, \mu_{i}, \xi_{i} \geq 0 \quad \forall_{i}$ 

From  $\alpha_i = 1 - \mu_i$ ,  $\alpha_i \leq 1$ ,

$$\Rightarrow 0 \le \alpha_i \le 1.$$

# Chapter 14. Unsupervised Learning

**Eq 14.58:** (ESL p.540)

$$\min_{\beta, \mathbf{R}} \| \mathbf{X}_2 - \beta \mathbf{X}_1 \mathbf{R} \|_F$$
  
Solutions:  $\hat{\mathbf{R}} = \mathbf{U} \mathbf{V}^T$ ,  $\hat{\beta} = \frac{\text{Tr}(\mathbf{D})}{\| \mathbf{X}_1 \|_F^2}$ 

## **Proof:**

 $\beta$  is a positive scalar.

Based on Eq (14.58), Lagrangian will be

$$L(\beta, \mathbf{R}, \mathbf{A}) = \text{Tr}[(\mathbf{X}_2 - \beta \mathbf{X}_1 \mathbf{R})^T (\mathbf{X}_2 - \beta \mathbf{X}_1 \mathbf{R})] + \text{Tr}[\mathbf{A}(\mathbf{R}^T \mathbf{R} - \mathbf{I})]$$

First term:

$$(\mathbf{X}_2 - \beta \mathbf{X}_1 \mathbf{R})^T (\mathbf{X}_2 - \beta \mathbf{X}_1 \mathbf{R}) = (\mathbf{X}_2^T - \beta \mathbf{R}^T \mathbf{X}_1^T) (\mathbf{X}_2 - \beta \mathbf{X}_1 \mathbf{R})$$
$$= \mathbf{X}_2^T \mathbf{X}_2 - \mathbf{X}_2^T \beta \mathbf{X}_1 \mathbf{R} - \beta \mathbf{R}^T \mathbf{X}_1^T \mathbf{X}_2 + \beta^2 \mathbf{R}^T \mathbf{X}_1^T \mathbf{X}_1 \mathbf{R}$$

$$\frac{\partial}{\partial \beta} \operatorname{Tr}(\beta \mathbf{X}_{2}^{T} \mathbf{X}_{1} \mathbf{R}) = \operatorname{Tr}(\mathbf{X}_{2}^{T} X_{1} \mathbf{R})$$

$$\frac{\partial}{\partial \beta} \operatorname{Tr}(\beta \mathbf{R}^{T} \mathbf{X}_{1}^{T} \mathbf{X}_{2}) = \operatorname{Tr}(\mathbf{R}^{T} \mathbf{X}_{1}^{T} \mathbf{X}_{2})$$

$$\frac{\partial}{\partial \beta} \operatorname{Tr}(\beta^{2} \mathbf{R}^{T} \mathbf{X}_{1}^{T} \mathbf{X}_{1} \mathbf{R}) = 2\beta \operatorname{Tr}(\mathbf{R}^{T} \mathbf{X}_{1}^{T} \mathbf{X}_{1} \mathbf{R})$$

Using the trace relations;  $\operatorname{Tr}(\mathbf{A}^T\mathbf{B}) = \operatorname{Tr}(\mathbf{B}^T\mathbf{A}) = \operatorname{Tr}(\mathbf{A}\mathbf{B}^T) = \operatorname{Tr}(\mathbf{B}\mathbf{A}^T),$ 

$$Tr(\mathbf{X}_2^T \mathbf{X}_1 \mathbf{R}) = Tr(\mathbf{X}_2 \mathbf{R}^T \mathbf{X}_1^T) \tag{1}$$

$$\operatorname{Tr}(\mathbf{R}^T \mathbf{X}_1^T \mathbf{X}_2) = \operatorname{Tr}(\mathbf{X}_2^T \mathbf{X}_1 \mathbf{R}) = \operatorname{Tr}(\mathbf{X}_2 \mathbf{R}^T \mathbf{X}_1^T)$$
 (2)

To maximize L w.r.t.  $\beta$ ,

$$\Rightarrow \frac{\partial L(\beta, \mathbf{R}, A)}{\partial \beta} = -\text{Tr}(\mathbf{X}_2^T \mathbf{X}_1 \mathbf{R}) - \text{Tr}(R^T \mathbf{X}_1^T \mathbf{X}_2) + 2\beta \text{Tr}(\mathbf{R}^T \mathbf{X}_1^T \mathbf{X}_1 \mathbf{R}) = 0$$

Utilizing Eqs (1) and (2),

$$\begin{split} \frac{\partial L(\beta, \mathbf{R}, A)}{\partial \beta} &= -2 \text{Tr}(\mathbf{X}_2 \mathbf{R}^T \mathbf{X}_1^T) + 2\beta \text{Tr}(\mathbf{R}^T \mathbf{X}_1^T \mathbf{X}_2 \mathbf{R}) \\ &= -2 \text{Tr}(\mathbf{X}_2 \mathbf{R}^T \mathbf{X}_1^T) + 2\beta \text{Tr}(\mathbf{X}_1^T \mathbf{X}_2) \\ &= 0 \end{split}$$

Therefore we have

$$\hat{\beta} = \frac{\text{Tr}(\mathbf{R}^T \mathbf{X}_1^T \mathbf{X}_2)}{\|\mathbf{X}_1\|_F}$$
 (3)

 $\frac{\partial L}{\partial \mathbf{R}} = 0$  will produce the same solution for  $\mathbf{R}$  as in Eq (14.57), since the only change is  $\hat{\beta} \tilde{\mathbf{X}}_1$  instead of  $\tilde{\mathbf{X}}_1$ . So  $\hat{\mathbf{R}} = \mathbf{U} \mathbf{V}^T$ .

Plugging this into Eq (3), (and  $\mathbf{X}_1^T \mathbf{X}_2 = \mathbf{U} \mathbf{D} \mathbf{V}^T$ )

$$\hat{\beta} = \frac{\text{Tr}[\mathbf{V}\mathbf{U}^T \cdot \mathbf{U}\mathbf{D}\mathbf{V}^T]}{\|\mathbf{X}_1\|_F} = \frac{\text{Tr}[\mathbf{V}\mathbf{D}\mathbf{V}^T]}{\|\mathbf{X}_1\|_F}$$
$$= \frac{\text{Tr}[\mathbf{V}^T\mathbf{V}\mathbf{D}]}{\|\mathbf{X}_1\|_F} = \frac{\text{Tr}[\mathbf{D}]}{\|\mathbf{X}_1\|_F}$$

where  $\mathbf{V}^T\mathbf{V} = \mathbf{I}$  is used.

# Chapter 17. Undirected Graphical Models

**Eq 17.6:** (ESL p.630)

$$p(Y|Z=z) \sim \mathcal{N}(\mu_Y + (z - \mu_Z)^T \Sigma_{ZZ}^{-1} \sigma_{ZY}, \sigma_{YY} - \sigma_{ZY}^T \Sigma_{ZZ}^{-1} \sigma_{ZY})$$
where  $\mathbf{\Sigma} = \begin{pmatrix} \Sigma_{ZZ} & \sigma_{ZY} \\ \sigma_{ZY}^T & \sigma_{YY} \end{pmatrix}$ 

### Proof:

Let's use the method described in §2.3.1 Conditional Gaussian Distributions in PRML. In the book, the derivations are based on the condition on  $x_b$ .

$$egin{aligned} x &= egin{pmatrix} x_a \ x_b \end{pmatrix}, & \Sigma &= egin{pmatrix} oldsymbol{\Sigma}_{aa} & oldsymbol{\Sigma}_{ab} \ oldsymbol{\Sigma}_{ba} & oldsymbol{\Sigma}_{bb} \end{pmatrix} \ oldsymbol{\Lambda} &= egin{pmatrix} oldsymbol{\Lambda}_{aa} & oldsymbol{\Lambda}_{ab} \ oldsymbol{\Lambda}_{ba} & oldsymbol{\Lambda}_{bb} \end{pmatrix} \end{aligned}$$

where  $\mathbf{\Lambda} = \mathbf{\Sigma}^{-1}$ .

But here, the order is reversed; conditioned on  $x_a$ . So if we rearrange  $\Sigma$  to match PRML's, we can use the same equations.

$$oldsymbol{\Sigma} = egin{pmatrix} oldsymbol{\Sigma}_{zz} & \sigma_{zy} \ \sigma_{zy}^T & \sigma_{yy} \end{pmatrix} & \longrightarrow & oldsymbol{\Sigma}' = egin{pmatrix} \sigma_{yy} & \sigma_{zy}^T \ \sigma_{zy} & oldsymbol{\Sigma}_{zz} \end{pmatrix} \ oldsymbol{\Lambda}' = egin{pmatrix} oldsymbol{\Lambda}_{yy} & oldsymbol{\Lambda}_{yz} \ oldsymbol{\Lambda}_{zy} & oldsymbol{\Lambda}_{zz} \end{pmatrix}$$

We know that

$$(\mathbf{\Sigma}')^{-1} = egin{pmatrix} \sigma_{yy} & \sigma_{zy}^T \ \sigma_{zy} & \mathbf{\Sigma}_{zz} \end{pmatrix}^{-1} = egin{pmatrix} \mathbf{\Lambda}_{yy} & \mathbf{\Lambda}_{yz} \ \mathbf{\Lambda}_{zy} & \mathbf{\Lambda}_{zz} \end{pmatrix}$$

From PRML Eq (2.76),

$$\begin{pmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{pmatrix}^{-1} = \begin{pmatrix} \mathbf{M} & -\mathbf{M}\mathbf{B}\mathbf{D}^{-1} \\ -\mathbf{D}^{-1}\mathbf{C}\mathbf{M} & \mathbf{D}^{-1} + \mathbf{D}^{-1}\mathbf{C}\mathbf{M}\mathbf{B}\mathbf{D}^{-1} \end{pmatrix}$$

where  $\mathbf{M} = (\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C})^{-1}$ .

Using PRML Eq (2.96),

$$p(x_a|x_b) = \mathcal{N}(x_a|\mu_{a|b}, \mathbf{\Lambda}_{aa}^{-1})$$
 (PRML Eq 2.96)  
$$p(Y|Z) = \mathcal{N}(\mu_{y|z}, \mathbf{\Lambda}_{yy}^{-1})$$

Using PRML Eq (2.97),

$$\mu_{a|b} = \mu_{a} - \mathbf{\Lambda}_{aa}^{-1} \mathbf{\Lambda}_{ab}(x_{b} - \mu_{b}) \qquad (PRML Eq 2.97)$$

$$\mu_{y|z} = \mu_{y} - \mathbf{\Lambda}_{yy}^{-1} \mathbf{\Lambda}_{yz}(z - \mu_{z})$$

$$\mathbf{\Lambda}_{yy}^{-1} = \mathbf{M}^{-1} = (\sigma_{yy} - \sigma_{zy}^{T} \mathbf{\Sigma}_{zz}^{-1} \sigma_{zy})$$

$$\mathbf{\Lambda}_{yz} = -\mathbf{M}\mathbf{B}\mathbf{D}^{-1} = -\mathbf{M}\sigma_{zy}^{T} \mathbf{\Sigma}_{zz}^{-1}$$

$$\Rightarrow \mu_{y|z} = \mu_{y} + \mathbf{M}^{-1} \cdot \mathbf{M}\sigma_{zy}^{T} \mathbf{\Sigma}_{zz}^{-1}(z - \mu_{z})$$

$$= \mu_{y} + \sigma_{zy}^{T} \mathbf{\Sigma}_{zz}^{-1}(z - \mu_{z})$$

By taking transpose on the second term,

$$\mu_{y|z} = \mu_y + (z - \mu_z)^T \mathbf{\Sigma}_{zz}^{-1} \sigma_{zy}$$
 (2)

Eqs (1) and (2) prove Eq (17.6).

## **Eq 17.8:** (ESL p.631)

$$\begin{aligned} \theta_{zy} &= -\theta_{yy} \cdot \boldsymbol{\Sigma}_{zz}^{-1} \sigma_{zy} \\ \text{where } \frac{1}{\theta_{yy}} &= \sigma_{yy} - \sigma_{zy}^T \boldsymbol{\Sigma}_{zz}^{-1} \sigma_{zy} \end{aligned}$$

## Proof:

Referring to §2.3.1 Conditional Gaussian Distributions in PRML,  $\Theta$  here corresponds to  $\Lambda$  in PRML.

Using

$$oldsymbol{\Sigma}' = egin{pmatrix} \sigma_{yy} & \sigma_{zy}^T \ \sigma_{zy} & oldsymbol{\Sigma}_{zz} \end{pmatrix}^{-1} \quad ext{and} \quad oldsymbol{\Theta}' = egin{pmatrix} heta_{yy} & heta_{yz} \ heta_{zy} & heta_{zz} \end{pmatrix}$$

$$\theta_{zy} = -\mathbf{D}^{-1}\mathbf{CM}$$

$$= -\mathbf{\Sigma}_{zz}^{-1}\sigma_{zy}\theta_{yy}$$
where  $\theta_{yy}^{-1} = \mathbf{M}^{-1} = \sigma_{yy} - \sigma_{zy}^T\mathbf{\Sigma}_{zz}^{-1}\sigma_{zy}$ 

Eq 17.33: (ESL p.639)

$$\frac{\partial \Phi(\mathbf{\Theta})}{\partial \theta_{jk}} = \sum_{x \in \mathcal{X}} x_j x_k \cdot p(x, \mathbf{\Theta})$$

Proof:

$$\Phi(\Theta) = \log \sum_{x \in \chi} \left[ \exp \left( \sum_{(j,k) \in E} \theta_{jk} x_j x_k \right) \right]$$
 (17.29)

$$\frac{\partial \Phi(\Theta)}{\partial \theta_{jk}} = \frac{\sum_{x \in \chi} \exp\left(\sum_{(j,k) \in E} \theta_{jk} x_j x_k\right) \cdot x_j x_k}{\sum_{x \in \chi} \left[\exp\left(\sum_{(j,k) \in E} \theta_{jk} x_j x_k\right)\right]}$$

$$= \sum_{x \in \chi} x_j x_k \cdot \frac{\exp\left(\sum_{(j,k) \in E} \theta_{jk} x_j x_k\right)}{\sum_{x \in \chi} \left[\exp\left(\sum_{(j,k) \in E} \theta_{jk} x_j x_k\right)\right]} \tag{1}$$

$$p(X, \mathbf{\Theta}) = \exp\left[\sum_{(j,k)\in E} \theta_{jk} x_j x_k - \mathbf{\Phi}(\mathbf{\Theta})\right]$$

$$= \frac{\exp\left[\sum_{(j,k)\in E} \theta_{jk} x_j x_k\right]}{\exp\left[\mathbf{\Phi}(\mathbf{\Theta})\right]}$$

$$= \frac{\exp\left[\sum_{(j,k)\in E} \theta_{jk} x_j x_k\right]}{\exp\left\{\log\sum_{x\in\chi} \left[\exp\left(\sum_{(j,k)\in E} \theta_{jk} x_j x_k\right)\right]\right\}}$$

$$= \frac{\exp\left[\sum_{(j,k)\in E} \theta_{jk} x_j x_k\right]}{\sum_{x\in\chi} \left[\exp\left(\sum_{(j,k)\in E} \theta_{jk} x_j x_k\right)\right]}$$
(2)

Eq (2) is equal to the fraction part of Eq (1).

$$\therefore \frac{\partial \Phi(\Theta)}{\partial \theta_{jk}} = \sum_{x \in \chi} x_j x_k \cdot p(x, \Theta)$$

# Chapter 18. High-Dimensional Problems

Eq 18.52: (ESL p.692)

$$p(t_i) \sim \pi_0 \cdot F_0 + (1 - \pi_0)F_1$$

 $\mathbf{Proof}:$ 

$$p(t_{j}, z_{j}) = p(z_{j}) \cdot [(t_{j}|z_{j})]$$

$$p(t_{j}) = \int p(t_{j}, z_{j}) dz_{j}$$

$$= \int p(z_{j}) \cdot p(t_{j}|z_{j}) dz_{j}$$

$$= \pi_{0}p(t_{j}|z_{j} = 0) + (1 - \pi_{0})p(t_{j}|z_{j} = 1)$$

Since  $F_0 = p(t_j|z_j = 0)$  and  $F_1 = p(t_j|z_j = 1)$ ,

$$p(t_i) \sim \pi_0 \cdot F_0 + (1 - \pi_0) F_1$$