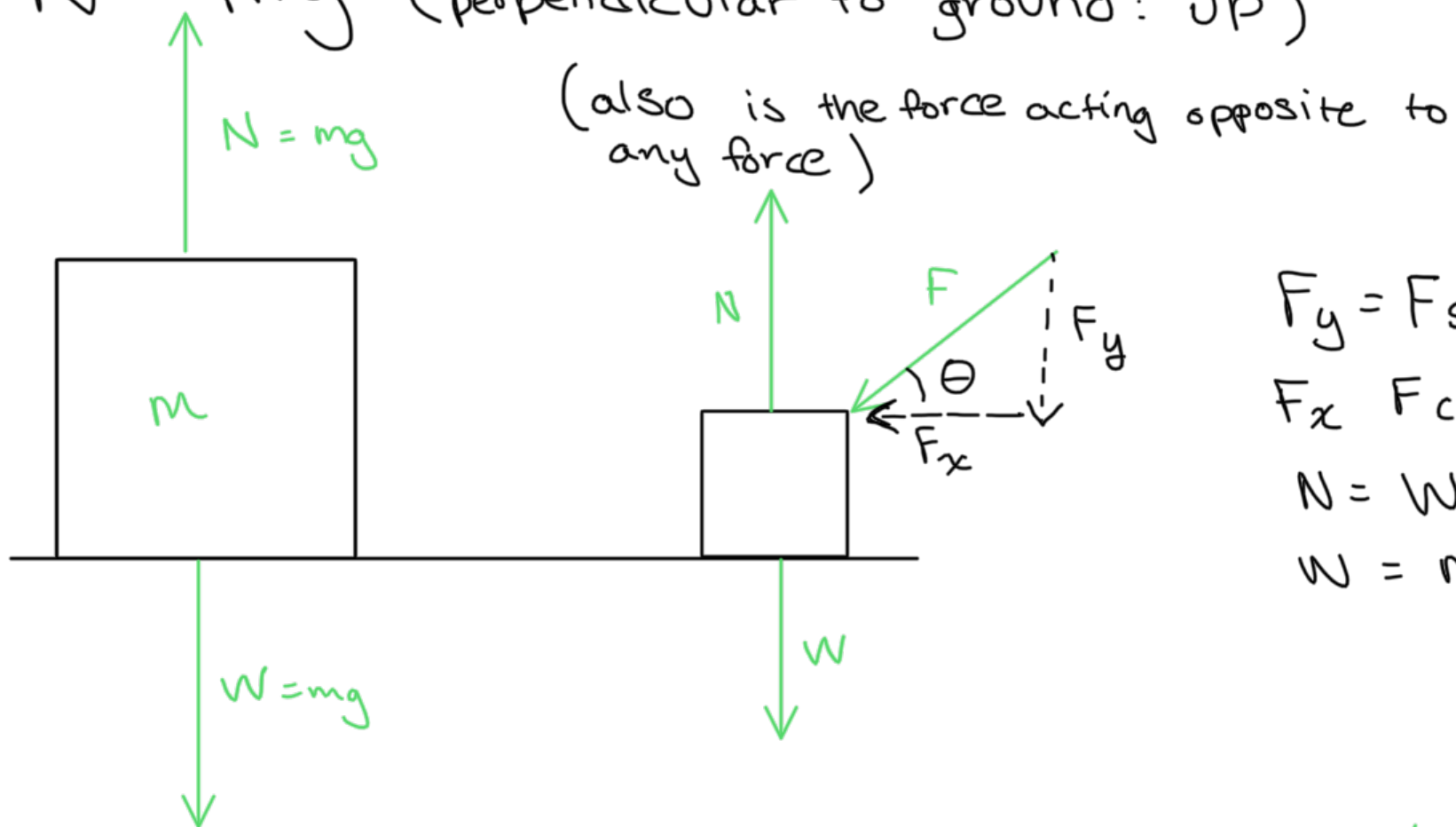


FORCES (DYNAMICS)

$$F = ma$$

$$W = mg \quad (\text{towards center of earth})$$

$$N = mg \quad (\text{perpendicular to ground: up})$$



$$F_y = F \sin \theta$$

$$F_x = F \cos \theta$$

$$N = W + F_y$$

$$W = mg$$

Friction

$$F_{\text{friction}} = \mu N$$

μ = friction constant

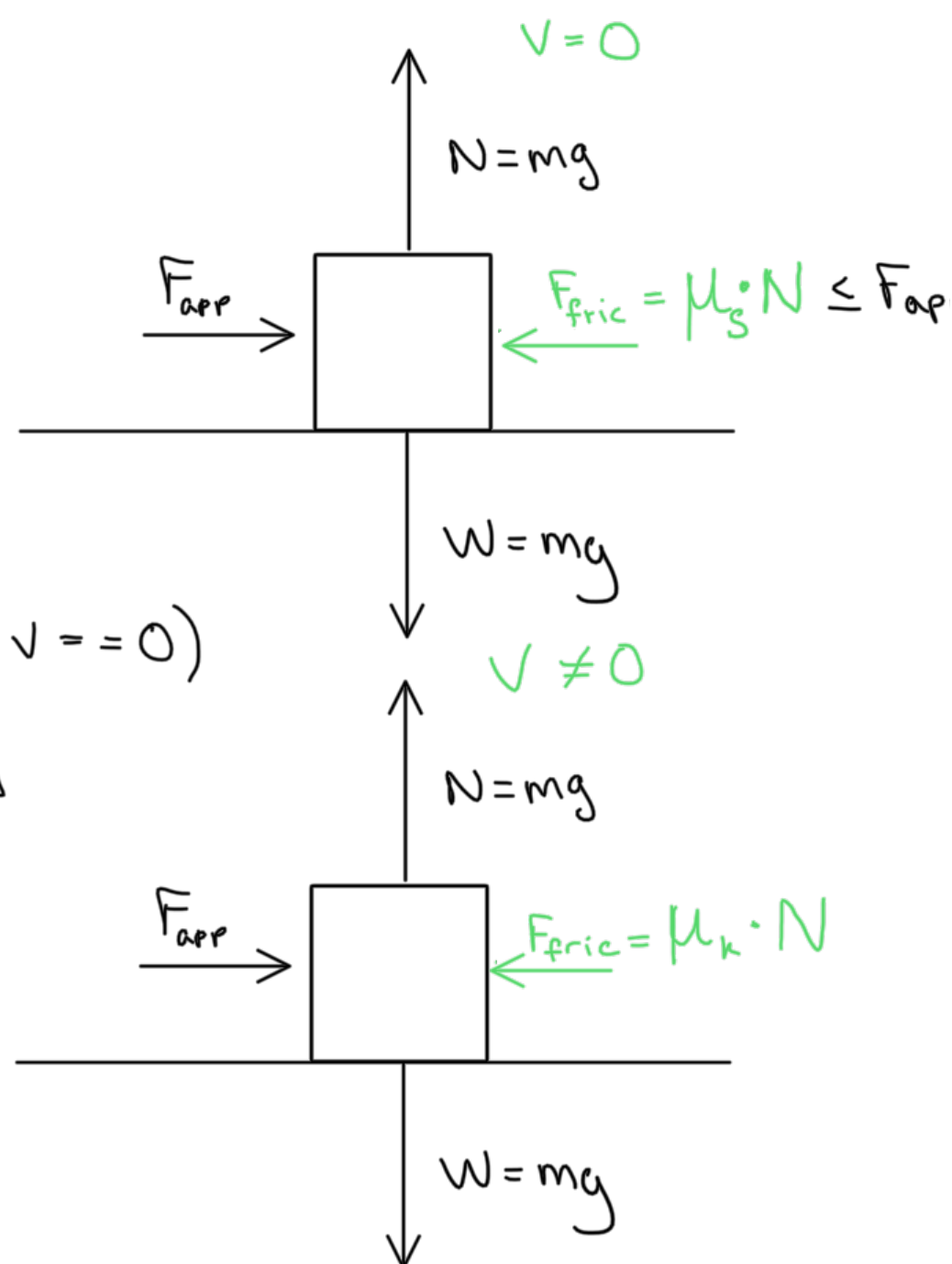
$$F_{\text{static}} = \mu_s N \leq \text{Applied Force}$$

if (Applied Force $> F_{\text{static max}}$ & $v = 0$)

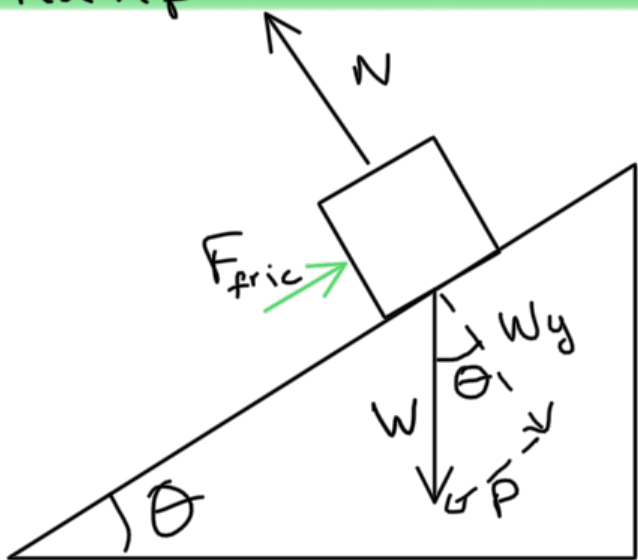
{

$$F_{\text{friction}} = F_{\text{friction kinetic}} = \mu_k N$$

}



Ramp



$$P = W \cdot \sin \theta$$

$$N = W_y = W \cos \theta$$

$$F_{\text{fric}} = \mu N$$

$$F_{\text{net}} = P + F_{\text{fric}}$$

$$a = \frac{(P + F_{\text{fric}})}{m}$$

Circular Motion

$$F_c = a_c \cdot m$$

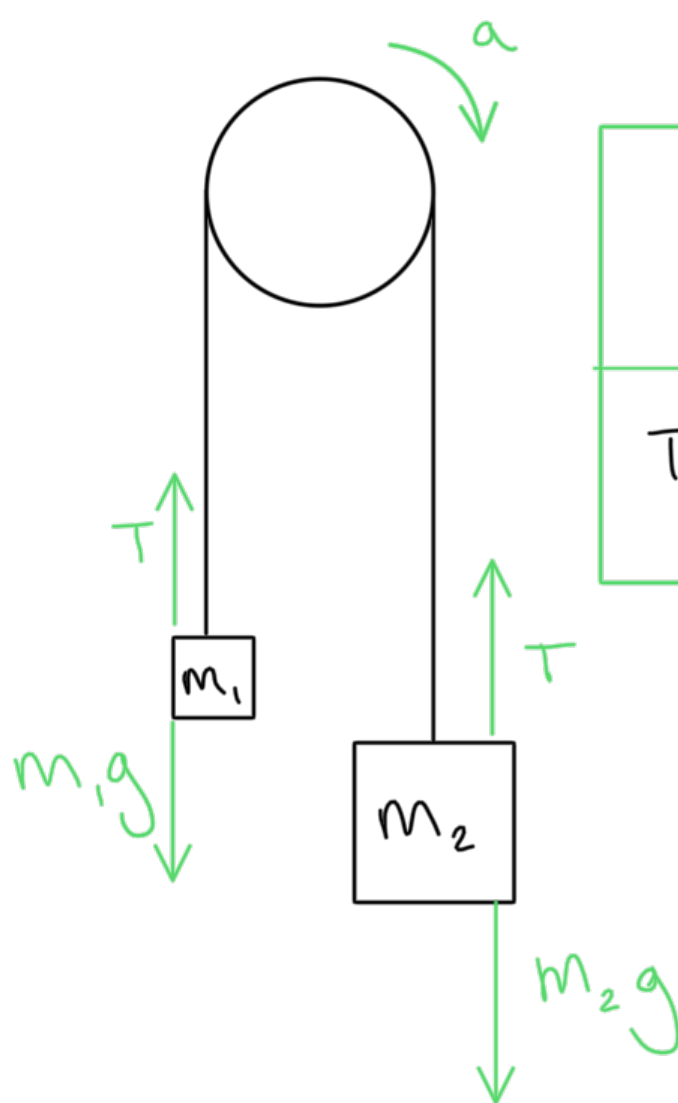
$$= \frac{mv^2}{r}$$

$$= m r \omega^2$$

$$v = \frac{2\pi r}{T}$$

Common Test Problems

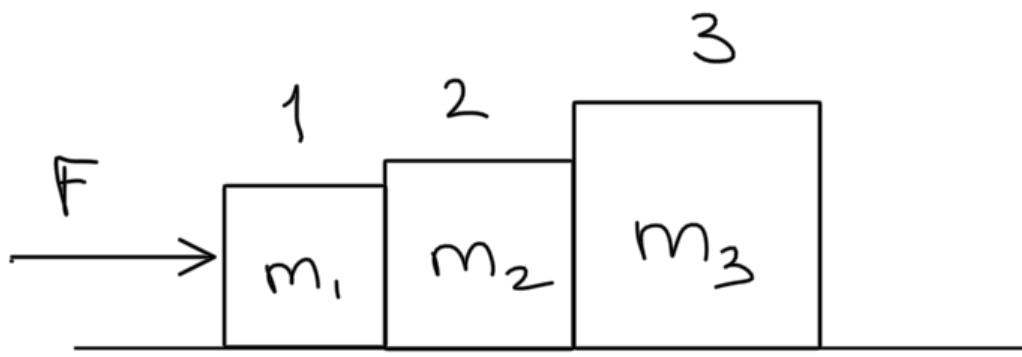
Pulley



$$a = \frac{F_{\text{net}}}{m_t} = \frac{m_2 g - m_1 g}{m_2 + m_1}$$

$$T = m_2 g - m_2 a = m_1 g + m_1 a$$

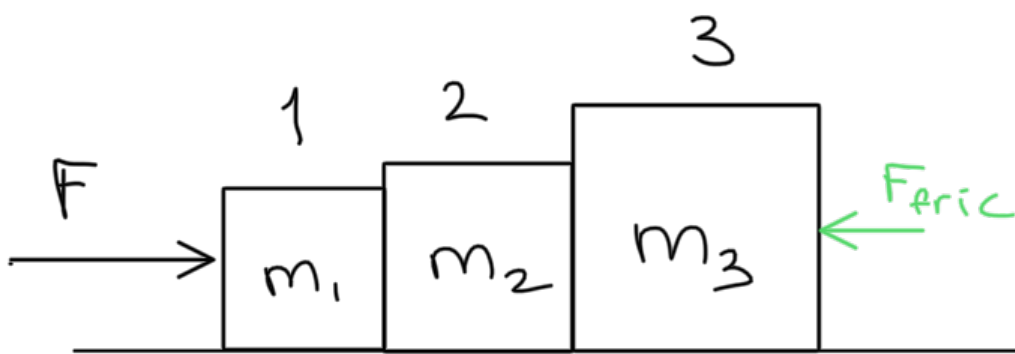
Frictionless Blocks



$$F_{1 \text{ on } 2} = \frac{m_2 + m_3}{m_T} \cdot F$$

$$F_{2 \text{ on } 3} = \frac{m_3}{m_T} \cdot F$$

Friction Blocks



$$\vec{F}_{\text{net on } 1} \quad \vec{F}_{\text{net on } 2} \quad \vec{F}_{\text{net on } 3}$$

$$\vec{F}_{f_1} = a_f \cdot m_1$$

$$\vec{F}_{f_2} = a_f \cdot m_2$$

$$\vec{F}_{f_3} = a_f \cdot m_3$$

$$F_{\text{fric}} = \mu \cdot N$$

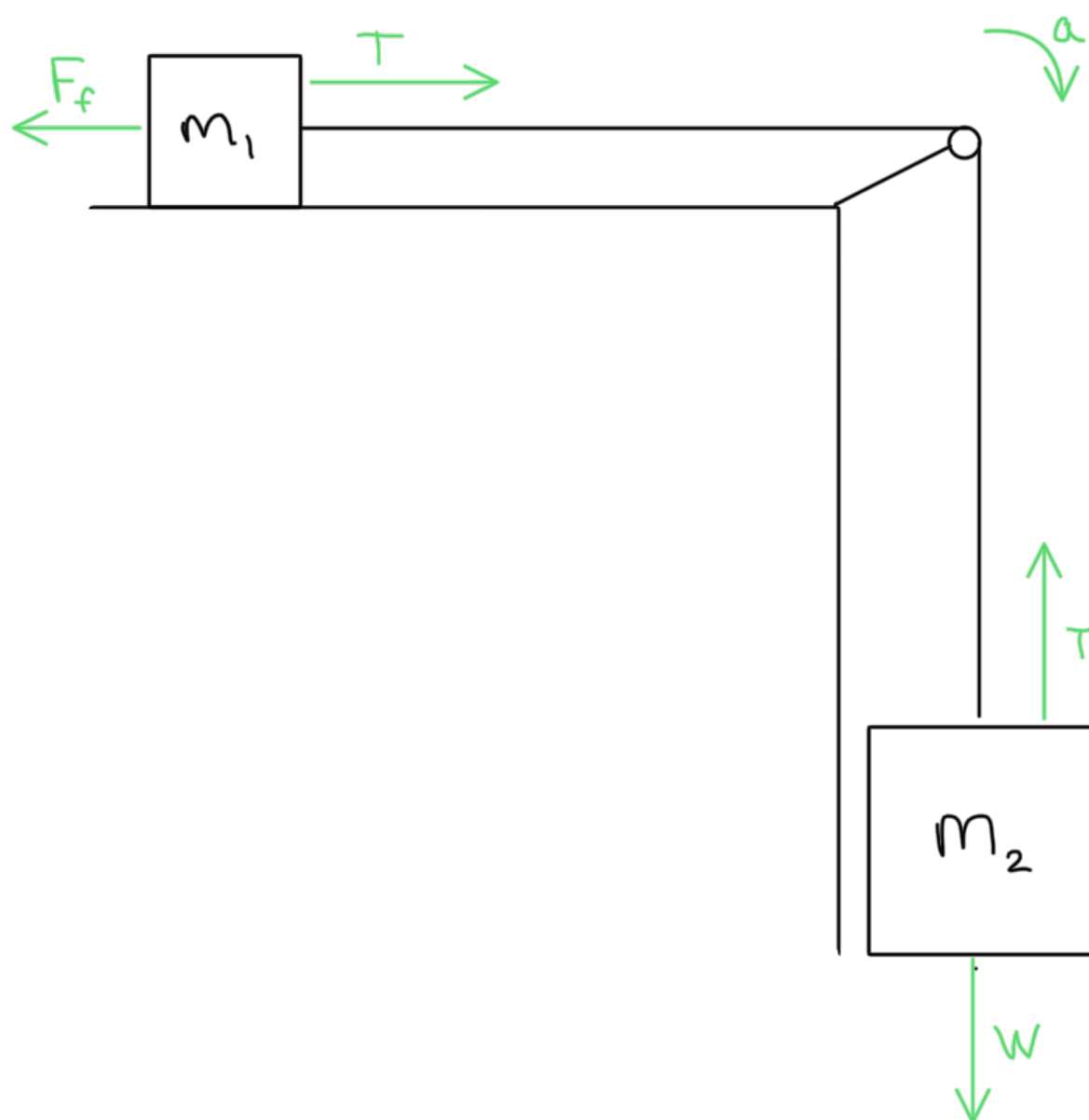
$$a_{\text{net}} = \frac{F - F_{fk}}{m_T}$$

$$a_{\text{fric}} = \frac{F_{fk}}{m_T}$$

$$F_{\text{net on } 2} = F - F_{\text{net on } 1} - F_{fk_1}$$

$$F_{\text{net on } 3} = F - F_{\text{net on } 2} - F_{fk_2}$$

Pulley 2

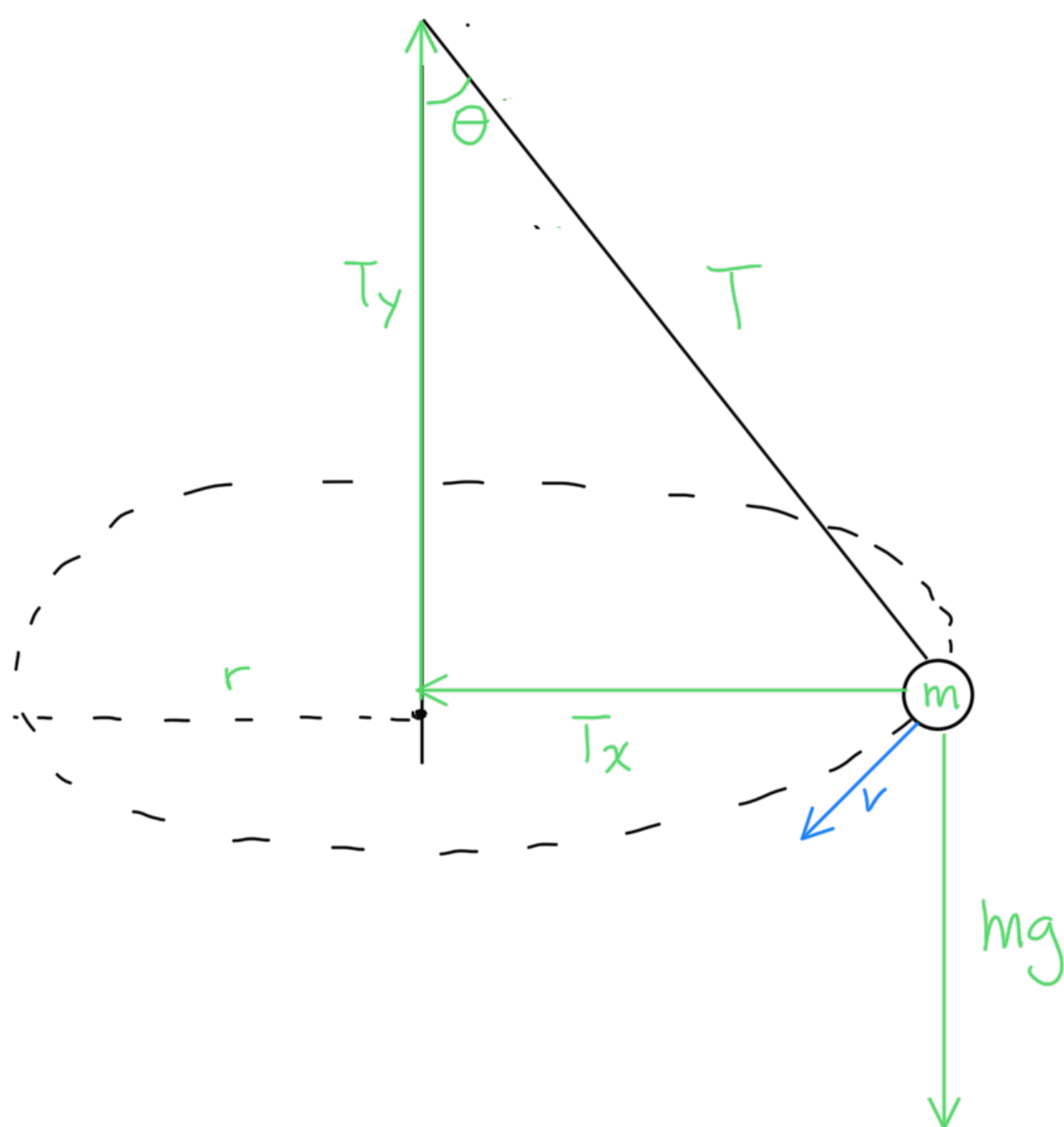


$$a = \frac{F_{\text{net}}}{m} = \frac{m_2 g - F_f}{m_1 + m_2}$$

$$F_{\text{net}x} = T - F_f$$

$$T = m_1 a + F_f = m_2 a + m_2 g$$

Tetherball



$$T_x = F_c = \frac{mv^2}{r} = mr\omega$$

$$T_y = mg$$

$$\theta = \tan^{-1} \left(\frac{T_x}{T_y} \right)$$

$$T = \sqrt{T_x^2 + T_y^2}$$