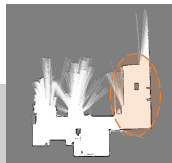


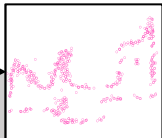
Local
Maps



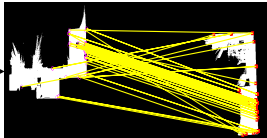
Map
Images



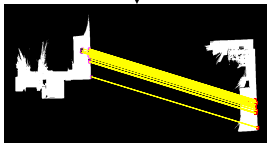
Feature
Detection



Feature
Matching

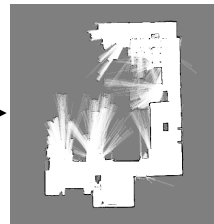


Outlier
Elimination



Decision

Global
Grid Fusion



*No merge;
Wait... for new maps*