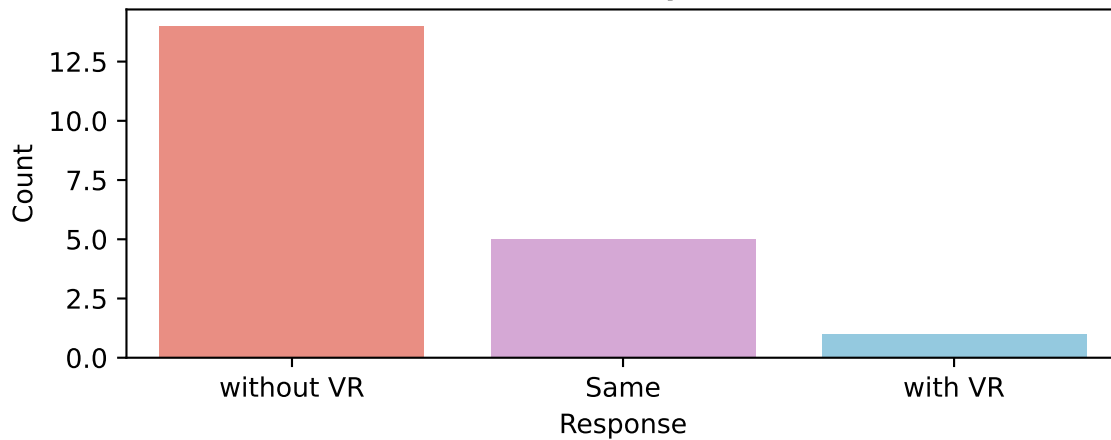
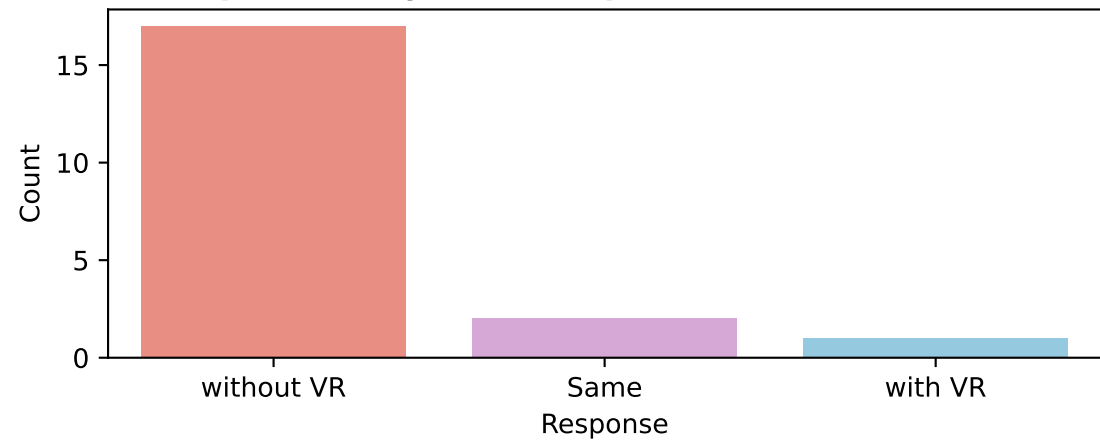


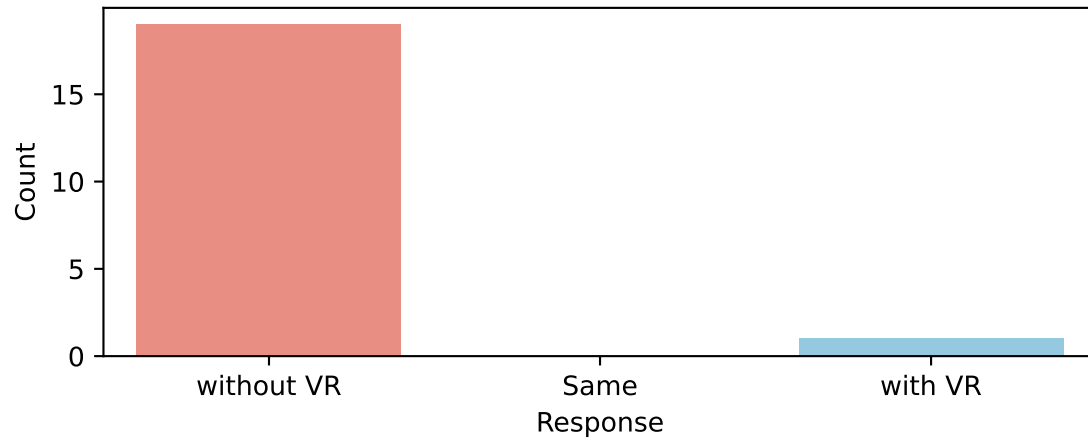
Overall, which one did you like the most?



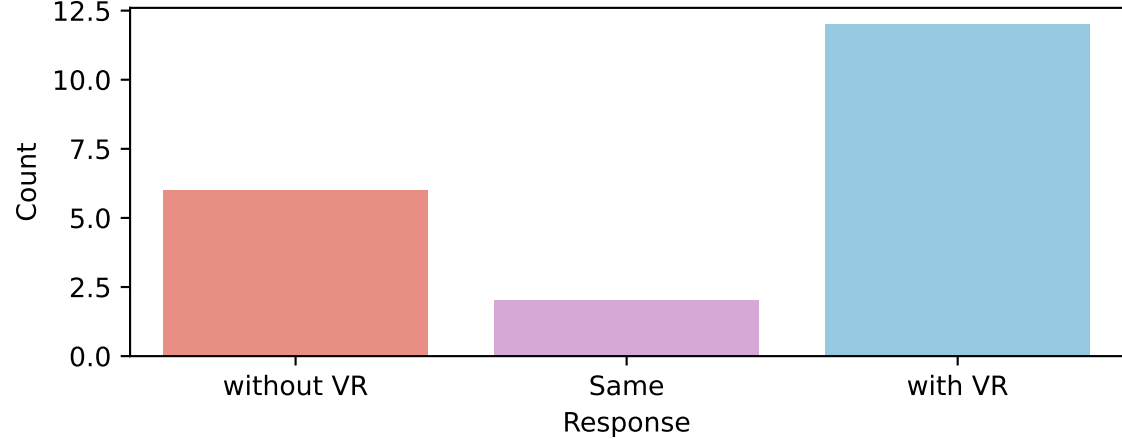
Which setup allowed you to complete the tasks more efficient



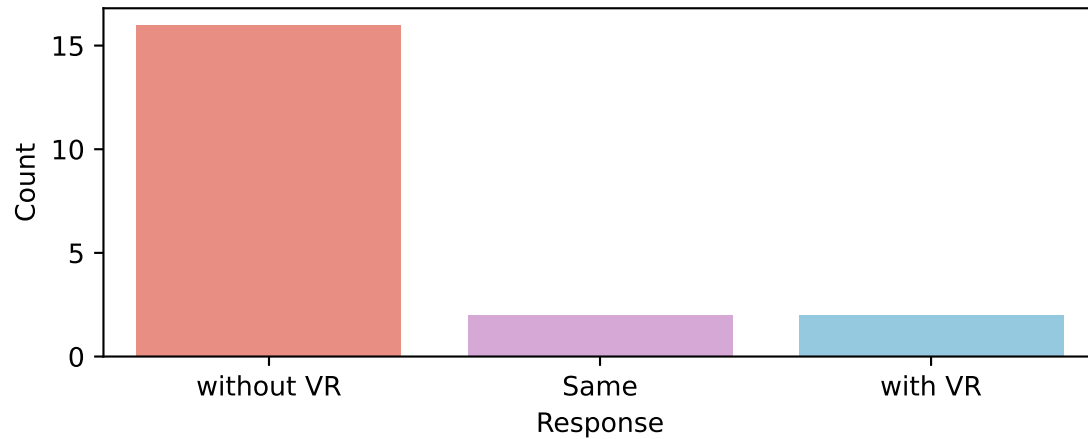
Which setup did you find more comfortable?



Which setup felt more immersive?



Which setup made it easier to operate the robot accurately?



Which setup would you be willing to use many times again

