FEI-FEI(SOPHIA) ZHENG

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WHO AM I

I am super passionate about solving problems by science and technology. I am strong self-motivated quick learner and I love to keep things organized. I have my own way of organizing and digesting knowledge and apply it across disciplines. My excellent communication and critical thinking skills help me getting things done collaboratively with others.

Currently I live in Toronto and working in IBM Supply Chain team. My interests in computer science area are in software design and computer vision. I'm a frequent visitor to Udacity, Coursera, Lynda, InfoQ to keep my knowledge to up to date. But I am not entirely geeky, since I also build hand crafts and play Chinese classical music instruments in spare time.

WHAT I KNOW

- Motivated Software Engineer with strong analytical, programming and problem-solving experience
- In-depth understanding of Data Structure, Algorithms and OOP principles
- In-depth understanding of Web, Mobile, Database and other software design best practices
- Love using Git version control, especially when working with other geeks
- Excellent communication skills and great team player
- Quick learner and ability to work under pressure with time management skills
- Good motivator, enthusiastic and passionate about new tools and technology

WHAT I AM GOOD AT

Programming: NodeJS, Python, Java, PostgreSQL

Framework & Tools: React JS, Express JS, Angular, D3.js, RESTful API, OAuth2

DevOps: Git, Docker, AWS EC2AI & Mathematics: OpenCV, NumPy, MATLAB

Platforms: Linux (Alpine, CentOS), MacOS, Windows

WHAT I LEARNED

2016.1 – 2021.4 B.Sc. Honored Major, Computer Science

Lassonde School of Engineering, York University

2017.6 – 2017.8 Machine Learning Certificate

Stanford University (via Coursera)

2014 – 2016 Advanced Diploma, Graphic Design

Seneca College

2021.5 - present **Software Developer, IBM**

- Developed new features with IBM Carbon Design System for IBM Sterling Business Transaction Intelligence Tool.
- Improved existing features for UX enhancement.
- Collaborated with team members for large defect fixes.
- Produced the front-end for web application with various technologies, but not limited to: **HTML**, **CSS**, **Angular**, **TypeScript**, **Git**, **NodeJS**.

2019.9 – 2021.4 Frontend Developer Intern, IBM

- Worked in an Agile, collaborative environment to understand requirements, design, code, and test applications.
- Produced the front-end for web application with various technologies, but not limited to: HTML, CSS, ReactJS, Angular, TypeScript, Git, NodeJS.
- Implemented new features for Carbon Charts and Carbon Design System, provide unit tests and solve issues with **D3.js** and **Vanilla JavaScript**.
- Employed Design Thinking to create features that provide a great user experience.

2018.5 – 2019.4 Computer Vision Research Assistant, York University CVR

- Participated in Intelligent Systems for Sustainable Urban Mobility (ISSUM) project
- Evaluated and compared state of art algorithms for specified datasets via Python and MATLAB
- Assist postdoctoral fellows in research process with programming and Mathematical knowledge and skills
- Analyzed and tested Auto Camera Calibration with Manhattan Frame Estimation and Unsupervised Crowd Counting
- Took the initiative to learn the knowledge about computer vision algorithms (Geo Camera Calibration, SIFT, PCA, etc.)

WHAT I HAVE DONE FOR FUN

RSME web application (https://github.com/sophiiae/rsme)

- Built a web application that auto generates resume in PDF
- It gets user profile information with given binding permission from LinkedIn via LinkedIn, RESTful API and OAuth2 and gets code contribution chart from GitHub with given username
- The project is written in **Node.js** and **Express.js** with various of Node.js libraries, including **request**, **PDFKit**, **xpath**, **xmldom**, **mustache-express**, etc.
- Deployed to AWS using Docker container (https://cloud.docker.com/u/sophiiae/repository/docker/sophiiae/rsme)

Lane Detection (https://github.com/sophiiae/AdvancedLaneDetection)

- Designed an algorithm to recognize lane marks from image and video without camera calibration
- It includes image color analysis, filtering, perspective transform and sliding windows
- The dataset is chosen randomly without camera specification
- The project uses Python libraries include Matplotlib, OpenCV and NumPy