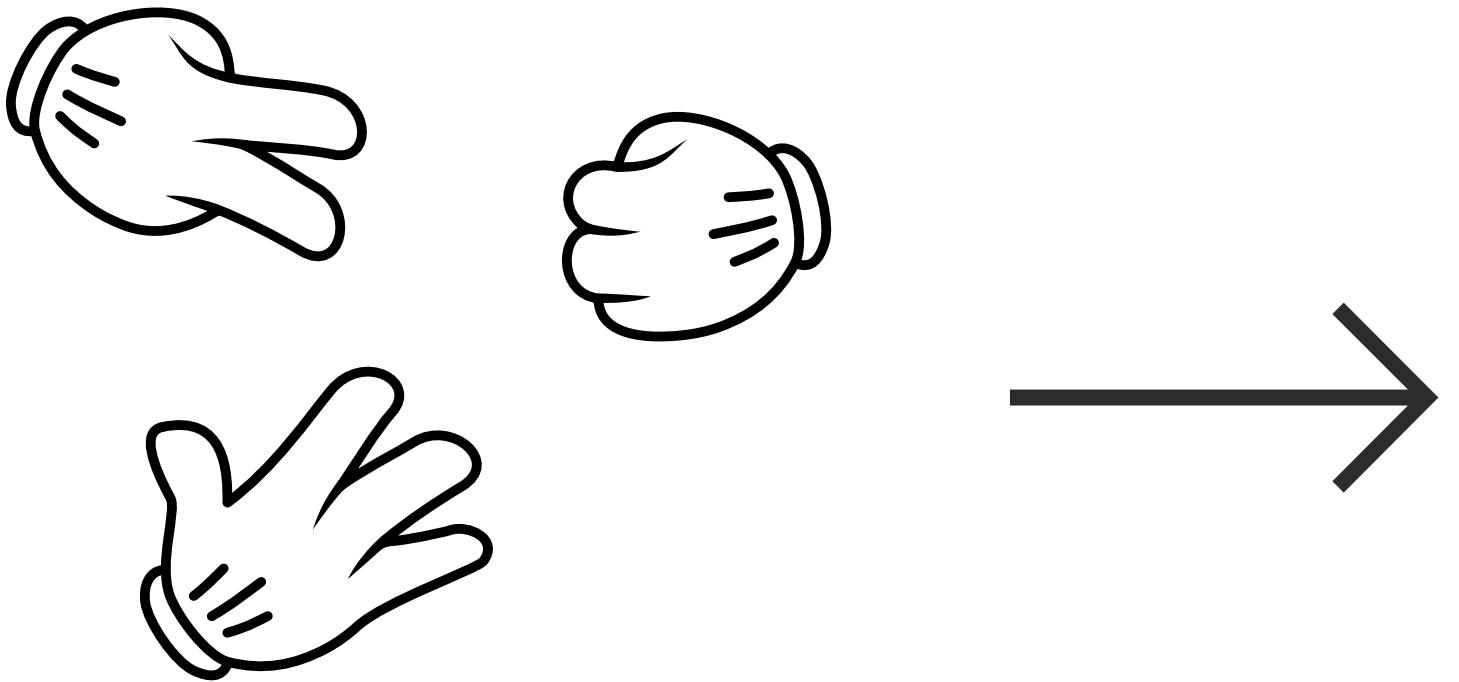


# Rock Paper Scissors with Computer!



# Agenda →

1. Introduction

2. Workframe

2.1 Data collection

2.2 Model building

2.3 Model training and testing

2.4 Model deployment

2.5 Model parameter tuning

2.6 Final optimal model

2.7 Program building

3. Limitations and Challenges

4. Demo of the program

# Introduction



## Project Idea

- Create an program on Arduino IDE to complete:
- Detect which gesture the user gives
  - Randomly generate a choice
  - Use built-in LED as an output signal

## Inspiration

- Image classification and object detection lectures
- 'How to win paper rock and scissors in Dr. Kawashima's Brain Training' game on Switch

## Aim

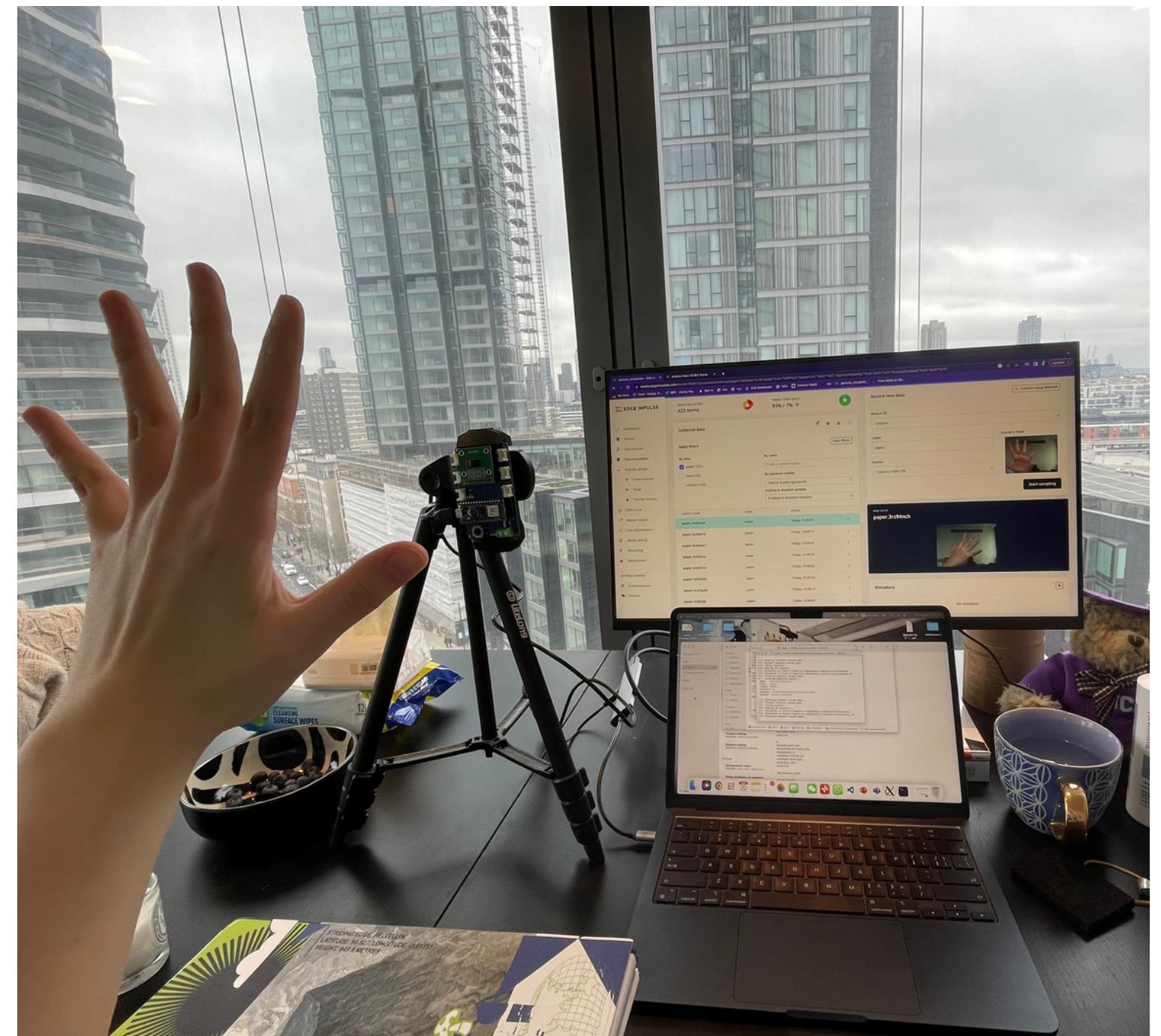
Reach an accuracy up to 80%

# 2.1 Data Collection



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- Collected, labeled, split by Edge Impulse
- Dataset size 423 training/74 testing (85%/15%)
  - Paper 121 training/21 testing
  - Rock 152 training/27 testing
  - Scissors 150 training/26 testing
- Considered control variables in images:
  - Background
  - Left and right hands
  - Gestures by different people



# 2.1 Data Collection



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- Collected, labeled, split by Edge Impulse
- Dataset size 423 training/74 testing (85%/15%)
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- Considered control variables in images:
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  - Left and right hands
  - Gestures by different people



# 2.2 Model building



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**Image data**

**Input axes**  
image

**Image width** 96

**Image height** 96

**Resize mode** Squash

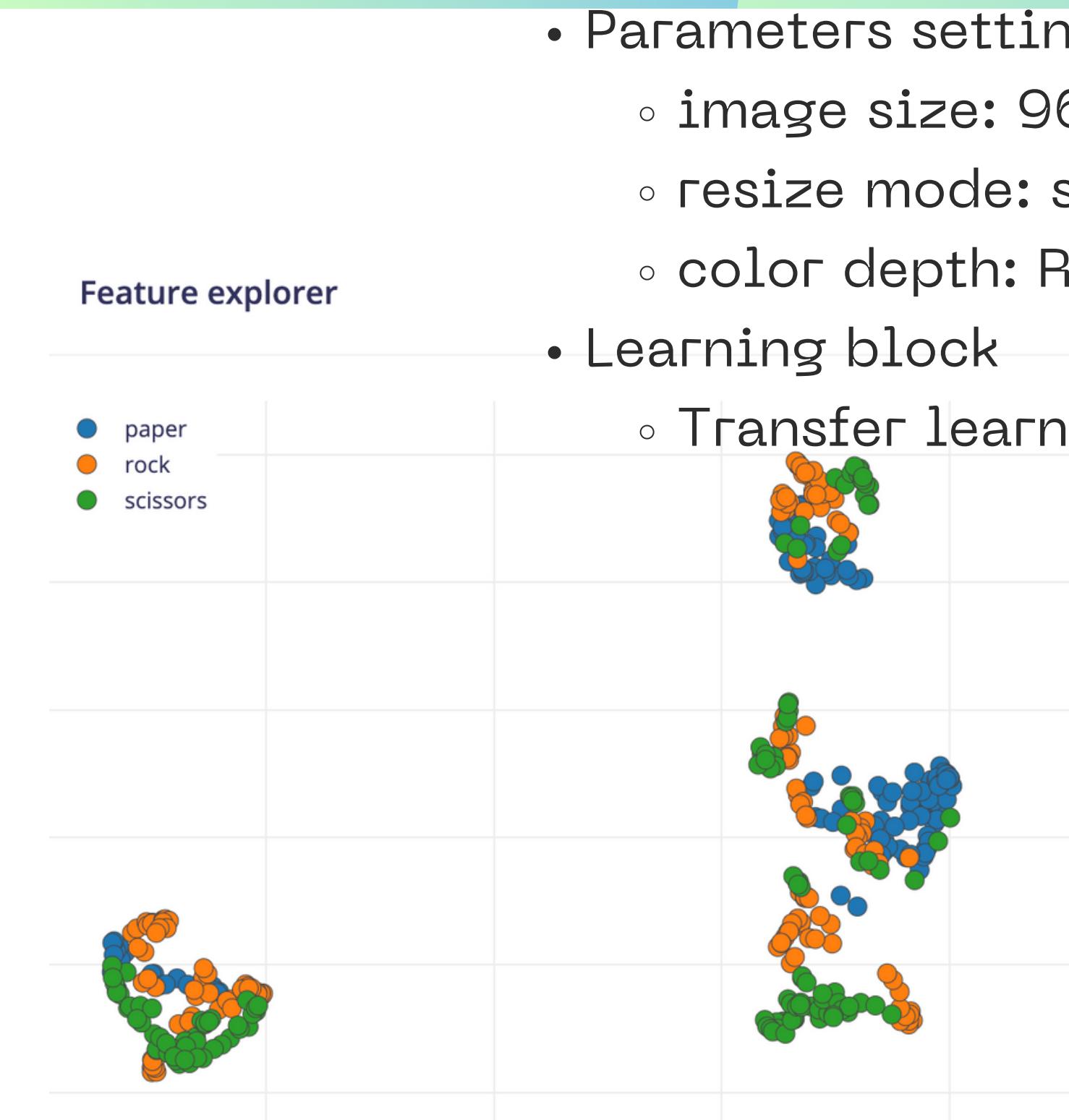
For optimal accuracy with transfer learning blocks, use a 96x96 or 160x160 image size.

**Transfer Learning (Images)**

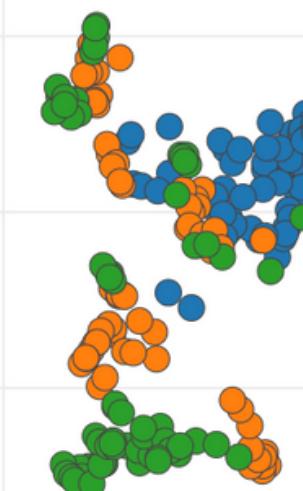
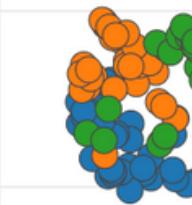
**Name** Transfer learning

**Input features**  Image

**Output features** 3 (paper, rock, scissors)



- Parameters setting
  - image size: 96 x 96
  - resize mode: squash
  - color depth: RGB
- Learning block
  - Transfer learning



# 2.3 Model training and testing



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## Neural Network settings

### Training settings

Number of training cycles ②

20

Learning rate ②

0.005

Validation set size ②

20 %

Auto-balance dataset ②

Data augmentation ②

### Neural network architecture

Input layer (27,648 features)



MobileNetV2 96x96 0.35 (final layer: 8 neurons, 0.1 dropout)

Choose a different model

Output layer (3 classes)

## Last training performance (validation set)

%  
**ACCURACY  
91.8%**

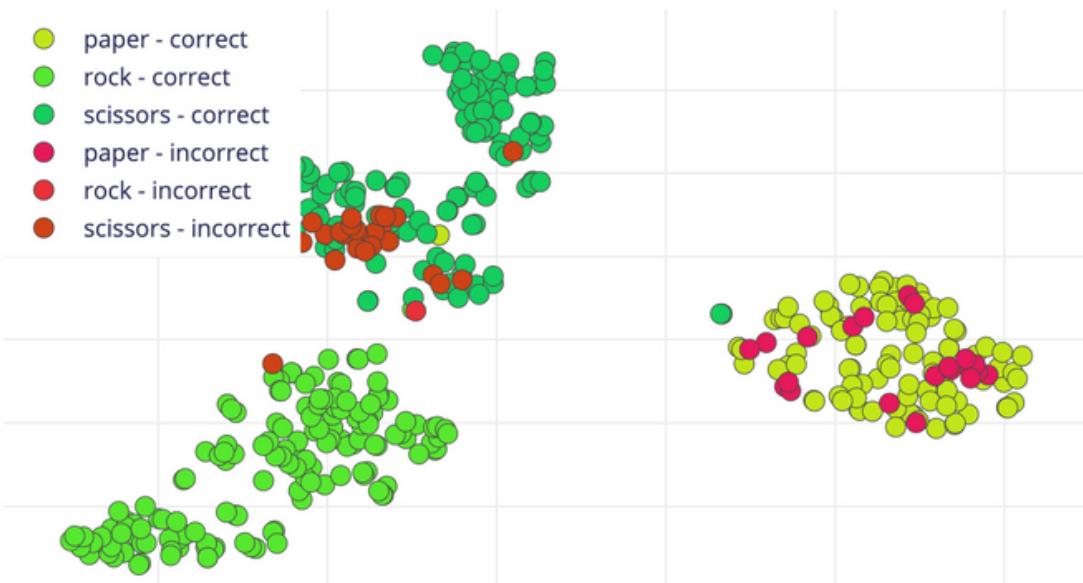
LOSS  
**0.23**

## Confusion matrix (validation set)

	PAPER	ROCK	SCISSORS
PAPER	92.3%	0%	7.7%
ROCK	0%	100%	0%
SCISSORS	0%	15.2%	84.8%
F1 SCORE	0.96	0.91	0.89

## Data explorer (full training set) ②

- paper - correct
- rock - correct
- scissors - correct
- paper - incorrect
- rock - incorrect
- scissors - incorrect



## On-device performance ②

INFERENCING...  
**1,974 ms.**

PEAK RAM US...  
**346.9K**

FLASH USAGE  
**570.5K**

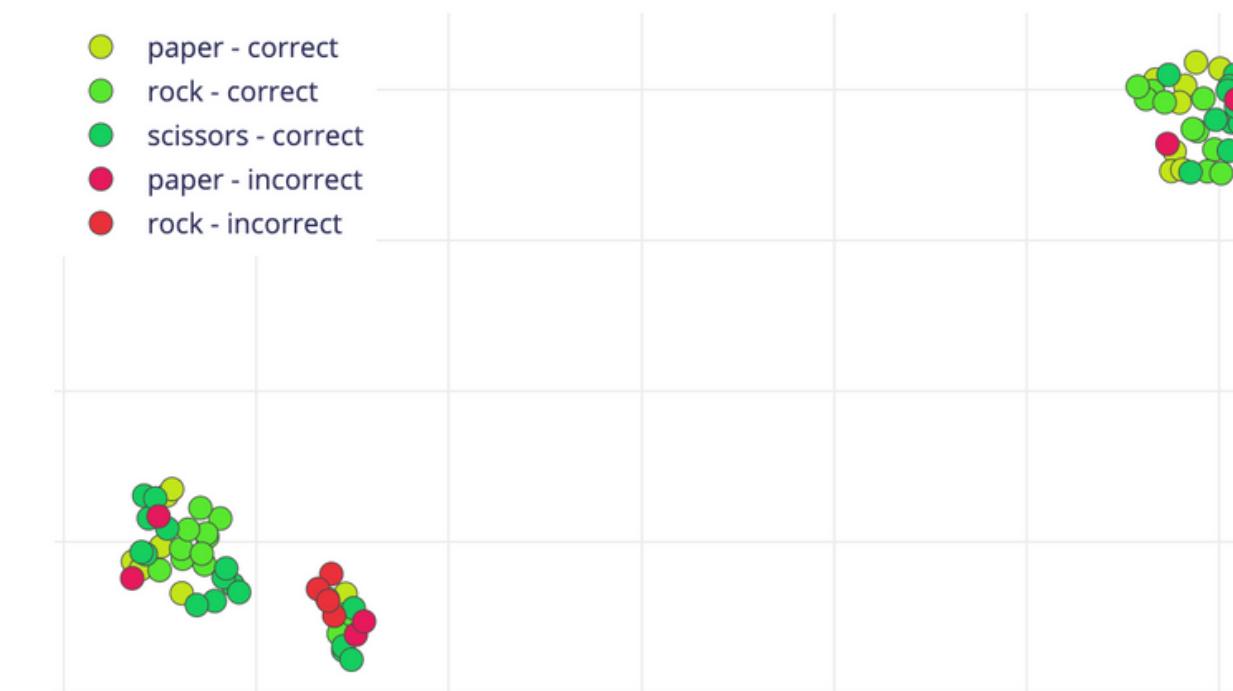
## Model testing results

%  
**ACCURACY  
86.49%**

	PAPER	ROCK	SCISSORS	UNCERTAIN
PAPER	71.4%	0%	23.8%	4.8%
ROCK	11.1%	85.2%	0%	3.7%
SCISSORS	0%	0%	100%	0%
F1 SCORE	0.77	0.92	0.91	

## Feature explorer ②

- paper - correct
- rock - correct
- scissors - correct
- paper - incorrect
- rock - incorrect



# 2.4 Model Deployment →

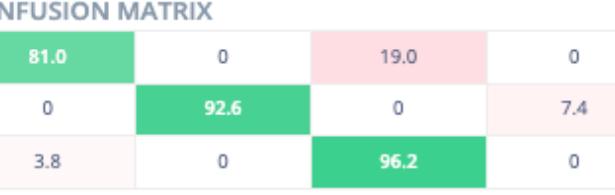
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## Select optimizations (optional)

Model optimizations can increase on-device performance but may reduce accuracy. Click below to analyze optimizations and see the recommended choices for your target. Or, just click Build to use the currently selected options.

 **Enable EON™ Compiler**  
Same accuracy, up to 50% less memory. Open source.

**Available optimizations for Transfer learning**

<b>Quantized (int8)</b> ★	<b>RAM USAGE</b> <b>346.9K</b>	<b>LATENCY</b> <b>1,951 ms</b>	<b>FLASH USAGE</b> <b>580.7K</b>	<b>ACCURACY</b> -
<b>Currently selected</b>				
This optimization is recommended for best performance.				
<b>Unoptimized (float32)</b>	<b>RAM USAGE</b> <b>960.9K</b>	<b>LATENCY</b> <b>13,362 ms</b>	<b>CONFUSION MATRIX</b>	
	<b>Click to select</b>			
Estimate for Arduino Nano 33 BLE Sense (Cortex-M4F 64MHz).				

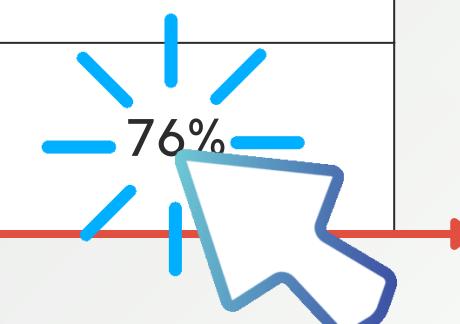
**Build**

- Exceeds the model's maximum size: 256KB

# 2.5 Model parameters tuning

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- With the help of EON tuner, different models with different parameters were experimented

	Learning type	Image input	color depth	learning rate	epochs	Accuracy (validation)	Accuracy (test)
1	Classification	32 x 32	grayscale	0.001	50	89%	55%
2	Classification	32 x 32	RGB	0.001	50	87%	45%
3	Transfer Learning	96 x 96	RGB	0.0005	50	84%	62%
4	Transfer Learning	96 x 96	grayscale	0.005	50	75%	62%
5	Transfer Learning	96 x 96	RGB	0.005	50	73%	 76%

# 2.6 Final optimal model

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**Neural Network settings**

**Training settings**

Number of training cycles ② 50

Learning rate ② 0.005

Validation set size ② 20 %

Auto-balance dataset ②

Data augmentation ②

**Neural network architecture**

Input layer (27,648 features)

MobileNetV1 96x96 0.1 (final layer: 32 neurons, 0.2 dropout)

Choose a different model

Output layer (3 classes)

**Neural Network settings**

**Training settings**

Validation set size ② 20 %

**Neural network architecture**

```
34 base_model = tf.keras.applications.MobileNet(
35     input_shape = INPUT_SHAPE,
36     weights = WEIGHTS_PATH,
37     alpha = 0.1
38 )
39
40 base_model.trainable = True
41
42 model = Sequential()
43 model.add(InputLayer(input_shape=INPUT_SHAPE, name='x_input'))
44 # Don't include the base model's top layers
45 last_layer_index = -5
46 model.add(Model(inputs=base_model.inputs, outputs=base_model
47     .layers[last_layer_index].output))
48 model.add(Reshape((-1, model.layers[-1].output.shape[3])))
49 model.add(Dense(32, activation='relu'))
50 model.add(Dropout(0.2))
51 model.add(Flatten())
52 model.add(Dense(classes, activation='softmax'))
53
54
55 BATCH_SIZE = 32
56 EPOCHS = args.epochs or 50
57 LEARNING_RATE = args.learning_rate or 0.005
58 train_dataset = train_dataset.batch(BATCH_SIZE, drop_remainder
59     =False)
60 validation_dataset = validation_dataset.batch(BATCH_SIZE,
61     drop_remainder=False)
62 callbacks.append(BatchLoggerCallback(BATCH_SIZE,
63     train_sample_count, epochs=EPOCHS))
```

**Last training performance (validation set)**

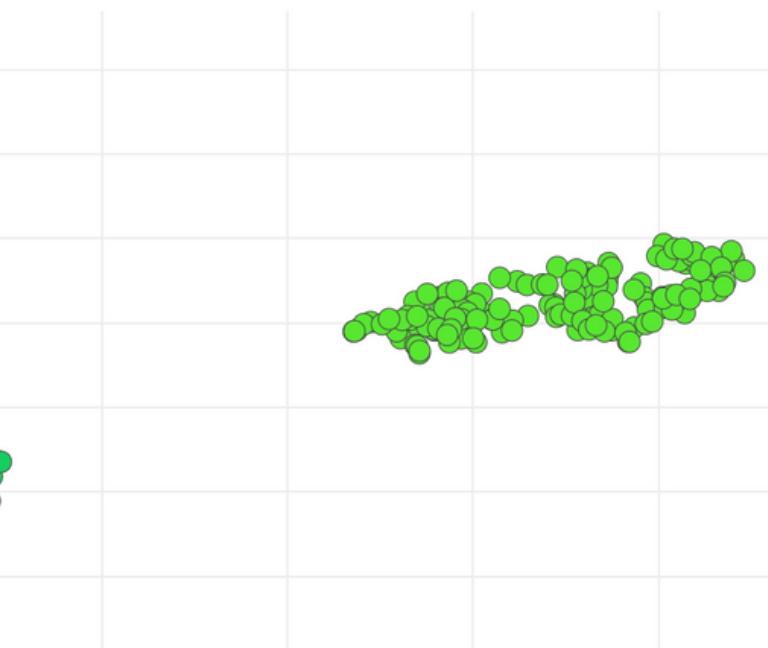
**ACCURACY** 100.0% **LOSS** 0.00

**Confusion matrix (validation set)**

	PAPER	ROCK	SCISSORS
PAPER	100%	0%	0%
ROCK	0%	100%	0%
SCISSORS	0%	0%	100%
F1 SCORE	1.00	1.00	1.00

**Data explorer (full training set) ②**

paper - correct  
rock - correct  
scissors - correct



**On-device performance ②**

**INFERRING...** 344 ms. **PEAK RAM US...** 66.9K **FLASH USAGE** 111.2K

# 2.6 Final optimal model

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Neural Network settings

Training settings

Number of training cycles ② 50

Learning rate ② 0.005

Validation set size ② 20 %

Auto-balance dataset ②

Data augmentation ②

Neural network architecture

Input layer (27,648 features)

MobileNetV1 96x96 0.1 (final layer: 32 neurons, 0.2 dropout)

Choose a different model

Output layer (3 classes)

Neural Network settir Model testing results

Training settings

Validation set size ② % ACCURACY 83.78%

Neural network architecture

```
34 base_model = tf.l
35   input_shape =
36   weights = WE
37   alpha = 0.1
38 )
39
40 base_model.trainin
41
42 model = Sequential(
43   model.add(InputL
44   # Don't include t
45   last_layer_index
46   model.add(ModelC
47     .layers[last_
48   model.add(Reshape(
49   model.add(Dense(3
50   model.add(Dropout(
51   model.add(Flatten(
52   model.add(Dense(3
53
54
55 BATCH_SIZE = 32
56 EPOCHS = args.epe
57 LEARNING_RATE = 0.
58 train_dataset = tra
59 validation_datalo
60 drop_remainder=
```

Feature explorer ②

- paper - correct
- rock - correct
- scissors - correct
- paper - incorrect
- rock - incorrect
- scissors - incorrect

LOSS 0.00

	PAPER	ROCK	SCISSORS	UNCERTAIN
PAPER	90.5%	0%	9.5%	0%
ROCK	18.5%	81.5%	0%	0%
SCISSORS	7.7%	11.5%	80.8%	0%
F1 SCORE	0.81	0.85	0.86	

ROCK SCISSORS

0%	0%
100%	0%
0%	100%
1.00	1.00

AK RAM US... 5.9K FLASH USAGE 111.2K

# 2.7 Program building

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```
// find the label with the highest probability
float max_prob = 0;
const char* max_label = "";
for (size_t ix = 0; ix < EI_CLASSIFIER_LABEL_COUNT; ix++) {
    if (result.classification[ix].value > max_prob) {
        max_prob = result.classification[ix].value;
        max_label = result.classification[ix].label;
    }
}
// turn the LED off by making the voltage LOW

ei_printf("Your choice: %s (%.5f)\n", max_label, max_prob);
```

- Print the label with highest probability
- Compare it with computer generated choice
- Output LED signal

```
// generate a random choice and compare it with the max_label
const char* options[] = {"rock", "paper", "scissor"};
const char* random_choice = random_string(options, 3);
ei_printf("Randomly generated choice: %s\n", random_choice);
if (strcmp(max_label, random_choice) == 0) {
    ei_printf("It's a tie!\n");
    digitalWrite(GREEN, HIGH);
    delay(1000);
    digitalWrite(BLUE, LOW);
    digitalWrite(RED, LOW);
    digitalWrite(GREEN, LOW);

} else if (strcmp(max_label, "rock") == 0 && strcmp(random_choice, "scissor") == 0 ||
           strcmp(max_label, "paper") == 0 && strcmp(random_choice, "rock") == 0 ||
           strcmp(max_label, "scissor") == 0 && strcmp(random_choice, "paper") == 0) {
    ei_printf("You win!\n");
    digitalWrite(RED, HIGH);
    delay(1000);
    digitalWrite(GREEN, LOW);
    digitalWrite(RED, LOW);
    digitalWrite(BLUE, LOW);

} else {
    ei_printf("You lose!\n");
    digitalWrite(BLUE, HIGH); // turn the LED on (HIGH is the voltage level)
    delay(1000);
    digitalWrite(RED, LOW);
    digitalWrite(GREEN, LOW);
    digitalWrite(BLUE, LOW);
}
```

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# 3. Demostration



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# 4. Limitations and future works



- Other gesture
- Detailed parameters modification
- Trade off between size and performances of the model