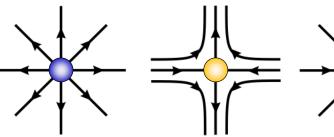


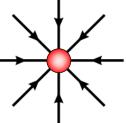
#### critical points as defined by the gradient

$$\mathbf{v}(\mathbf{x}_0) = \mathbf{0}$$
 with  $\mathbf{v}(\mathbf{x}_0 \pm \boldsymbol{\epsilon}) \neq \mathbf{0}$ 

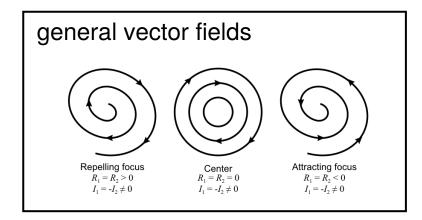


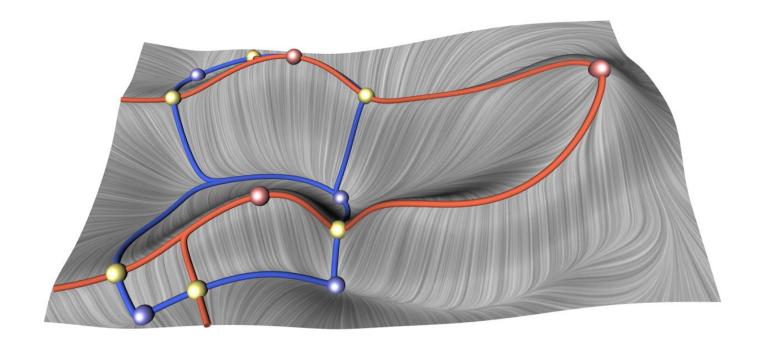
Repelling node  $R_1$ ,  $R_2 > 0$  $I_1 = I_2 = 0$ 

Saddle point  $R_1 < 0, R_2 > 0$   $I_1 = I_2 = 0$ 

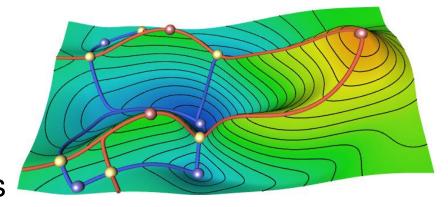


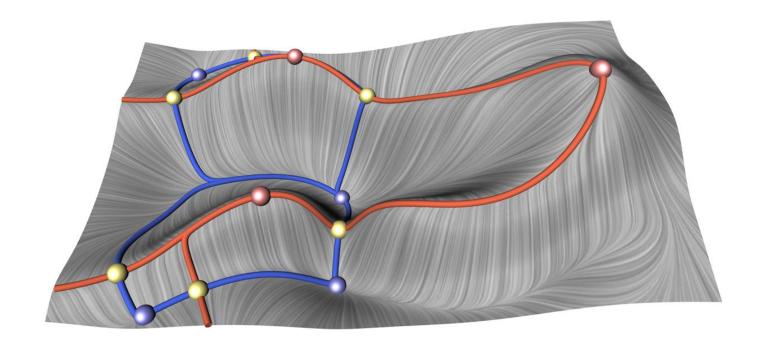
Attracting node  $R_1$ ,  $R_2 < 0$   $I_1 = I_2 = 0$ 





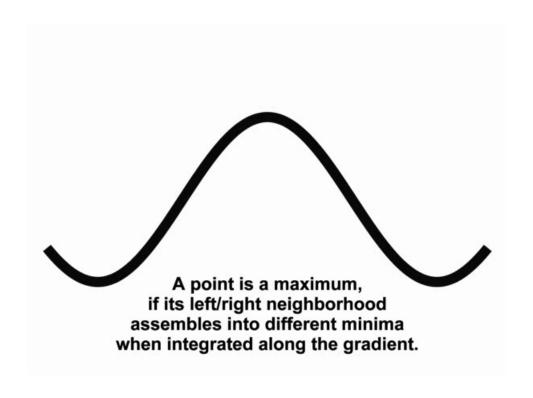
- integral lines of the gradient
- → follow the steepest ascend
- → perpendicular to isocontours





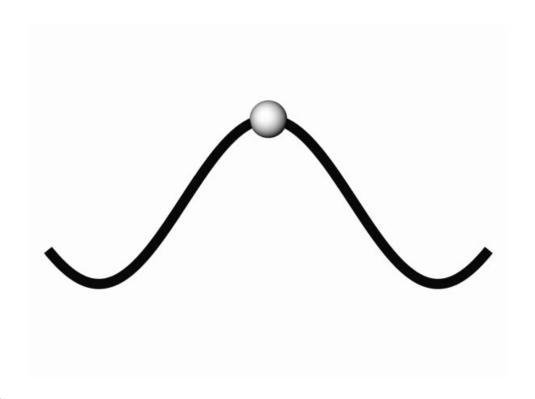
- integral lines of the gradient
- → follow the steepest ascend
- perpendicular to isocontours

- started at saddle points
- extremal structures

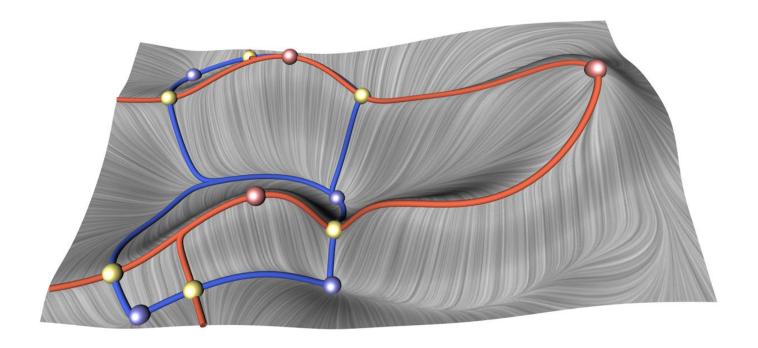


- integral lines of the gradient started at saddle points
- → follow the steepest ascend
- perpendicular to isocontours

- extremal structures



- integral lines of the gradient started at saddle points
- → follow the steepest ascend
  extremal structures
- perpendicular to isocontours



- integral lines of the gradient
- started at saddle points
- extremal structures

- global structures
   we cannot decide locally, whether a
   point is on a separatrix or not.
- parallel computation limited