

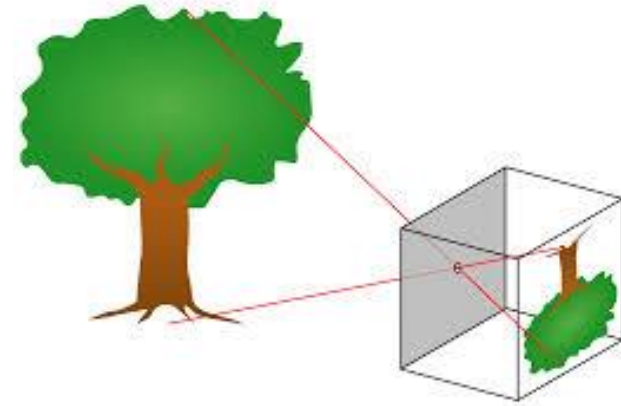
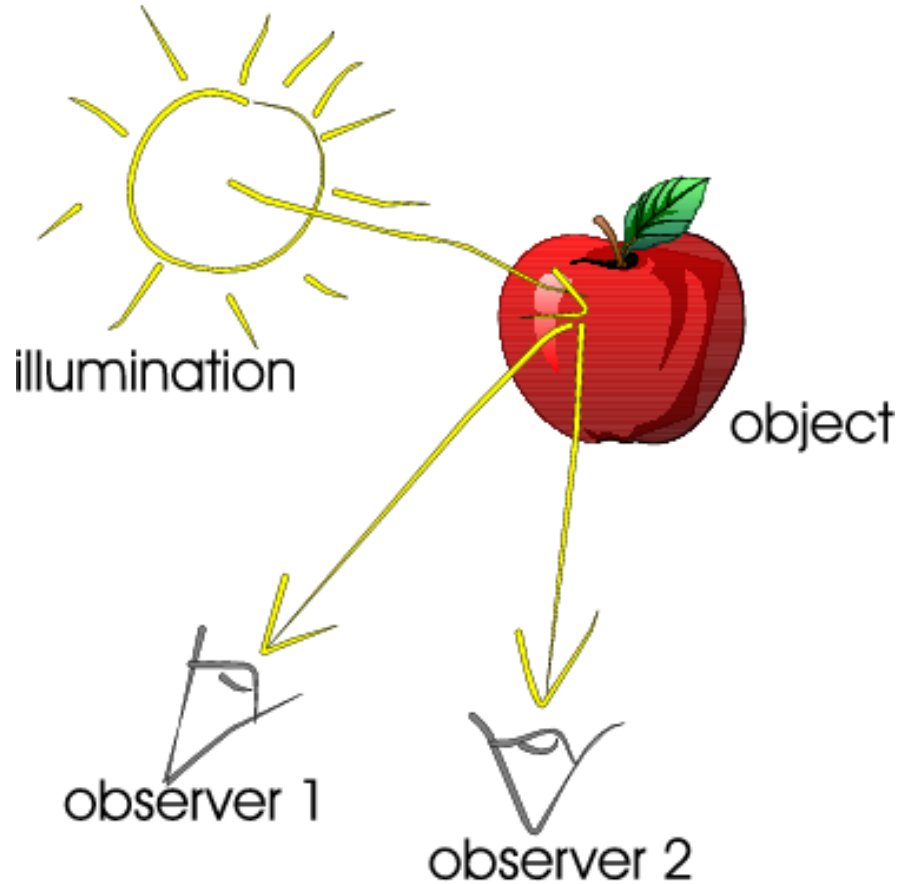
Image Formation and Representation

DUANGPEN JETPIPATTANAPONG

A solid orange horizontal bar spanning the width of the slide, located at the bottom.

Digital Image Formation

Components of Image Formation

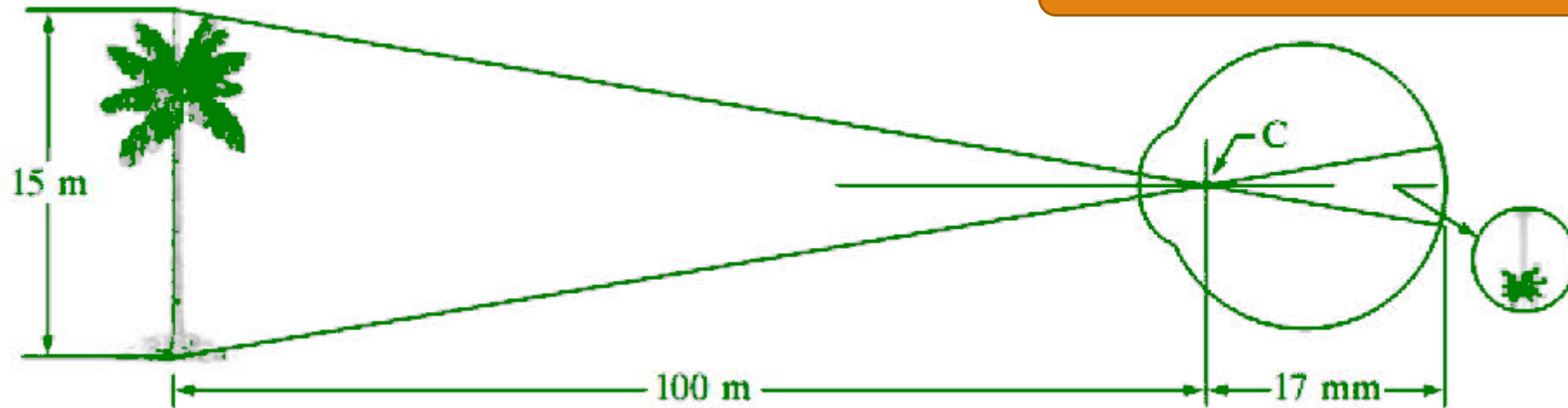


Illumination

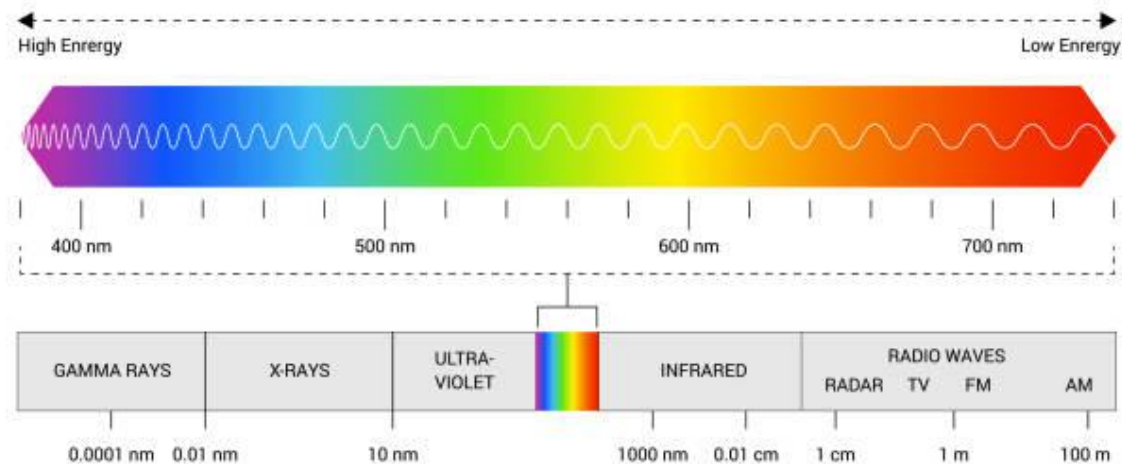
Reflectance of surface

Image Receiver : Sensor, Retina

Human Sensitivity

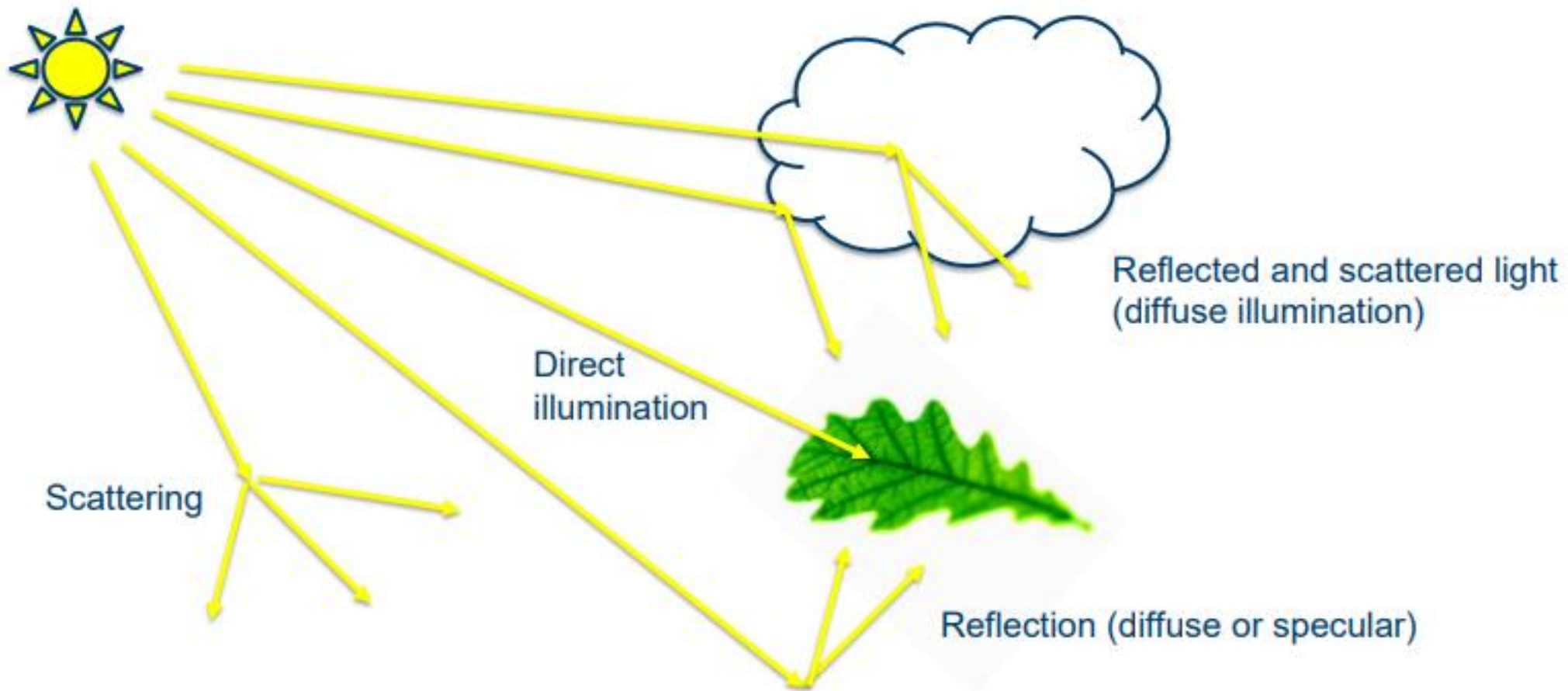


VISIBLE SPECTRUM



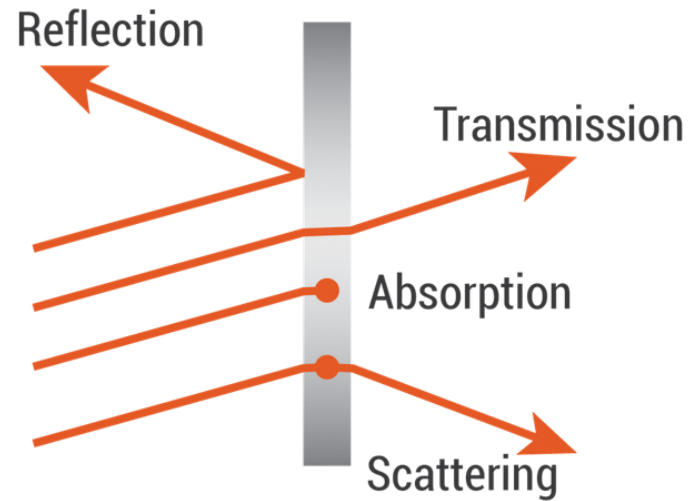
- **Light** produces the psychological sensation when it impinges on our eyes and **excites our visual sense**.
- The peak spectral sensitivity of a human observer happens at 555 *nm wavelength*.
- Visible light waves measure anywhere from around **380 nm** to about **740 nm**

Illumination



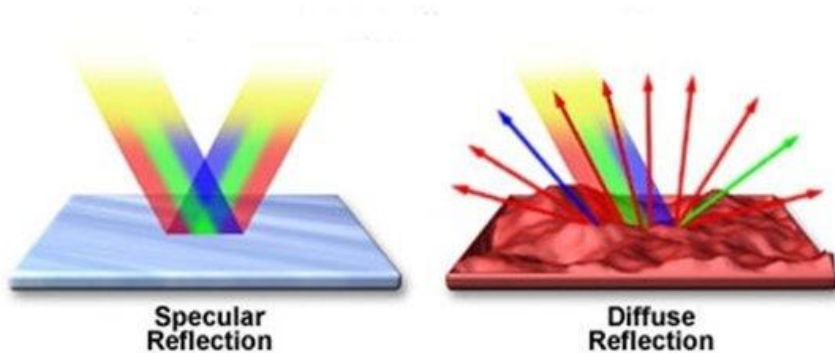
Direct Illumination and Indirect Illumination

Reflectance of surface

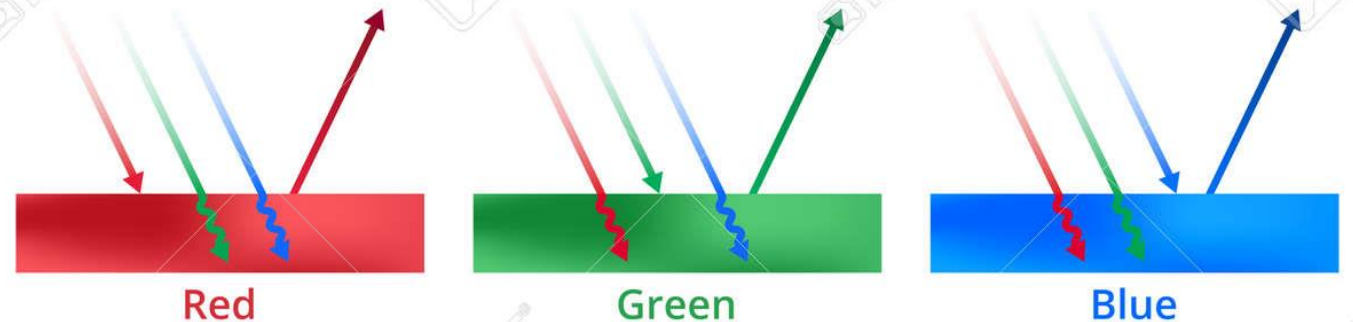


Some surfaces may be **perfectly absorbing** (e.g., black absorbing surfaces), which absorb the entire incident luminous flux and do not reflect any light.

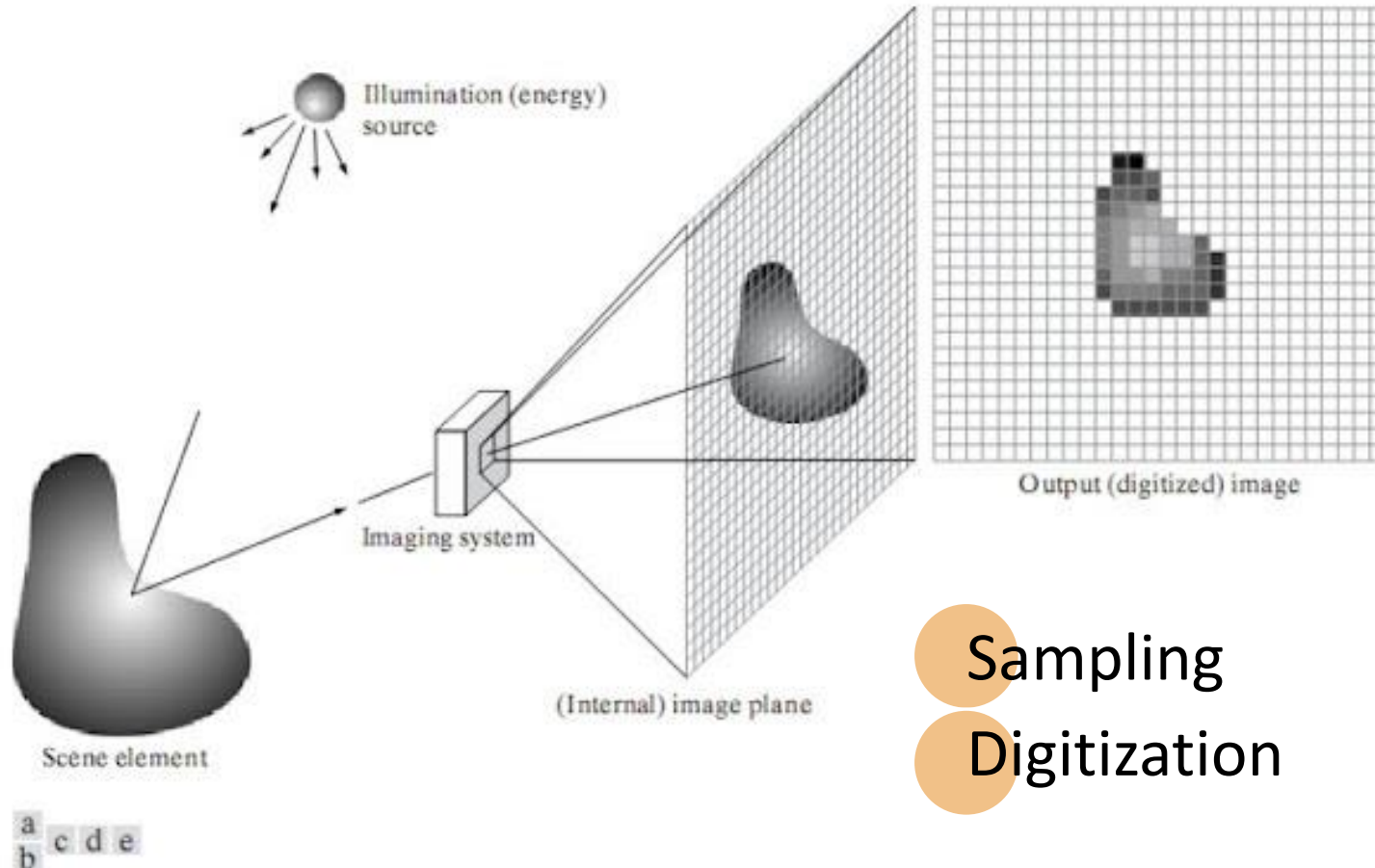
TWO KIND OF REFLECTIONS



RGB COLORS - ABSORPTION AND REFLECTION

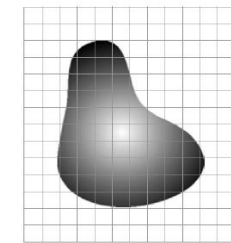


Digital Image Formation

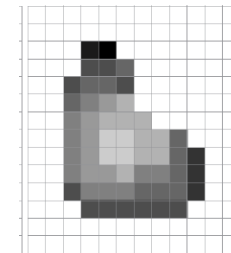


Sampling
Digitization

Sensor



Analog Image



Digital Image

SAMPLING AND QUANTIZATION

Sampling

Partitioning the image
at a finite number of
point

Quantization

Representation each
sample within the finite
work size of he
computer

Figure 2.13 from [Müller, FMP, Springer 2015]

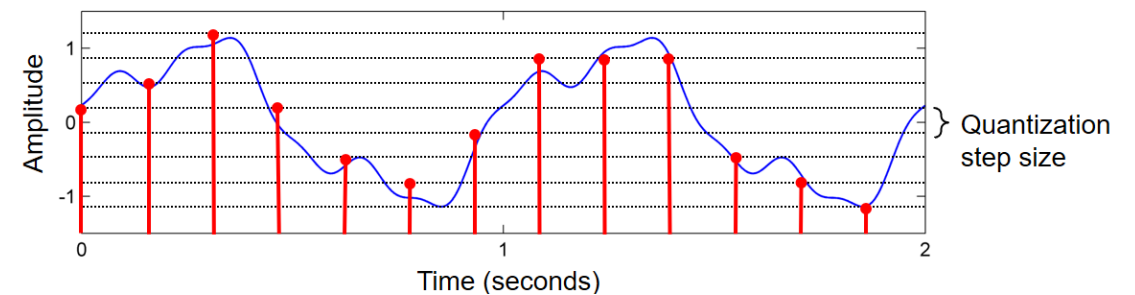
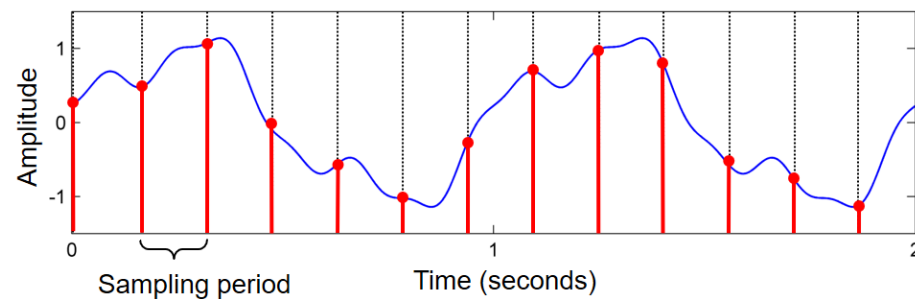


Image Sampling

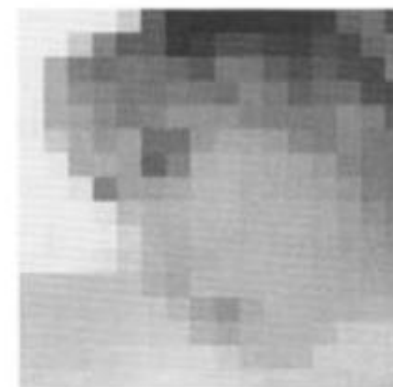
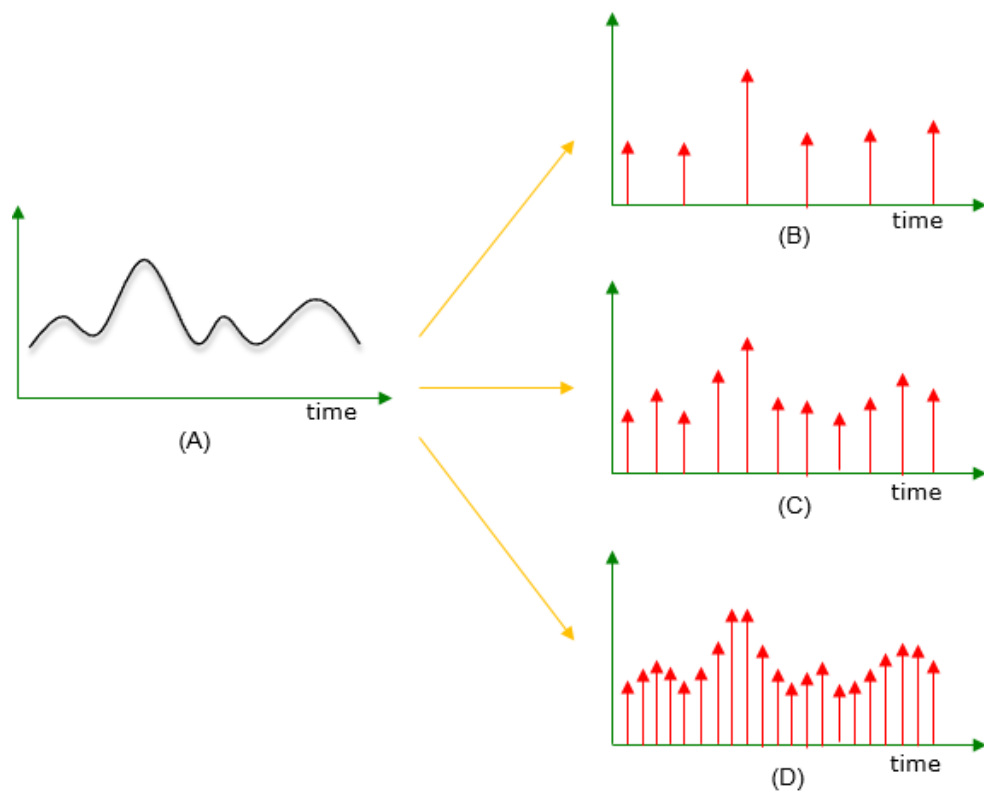


Image Sampling

The sampling period, according to Nyquist criterion, should be **smaller than or at the most equal to half of the period of the finest detail present** within an image.

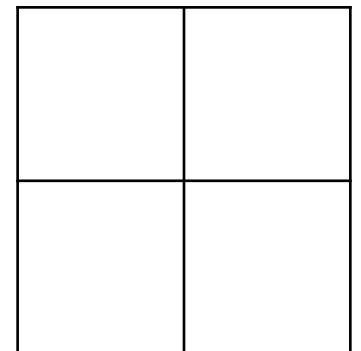
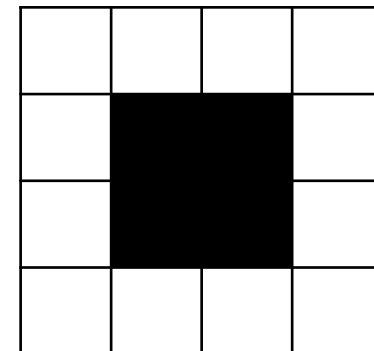
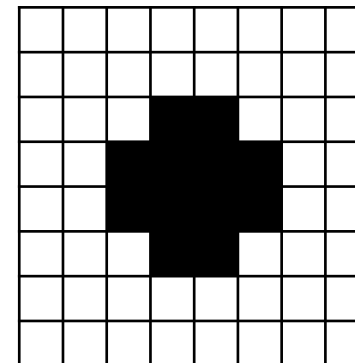
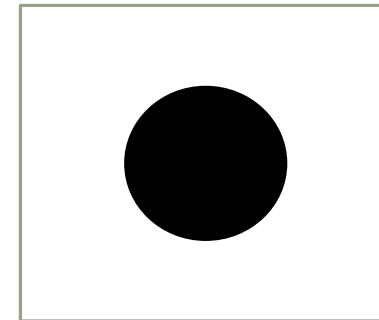
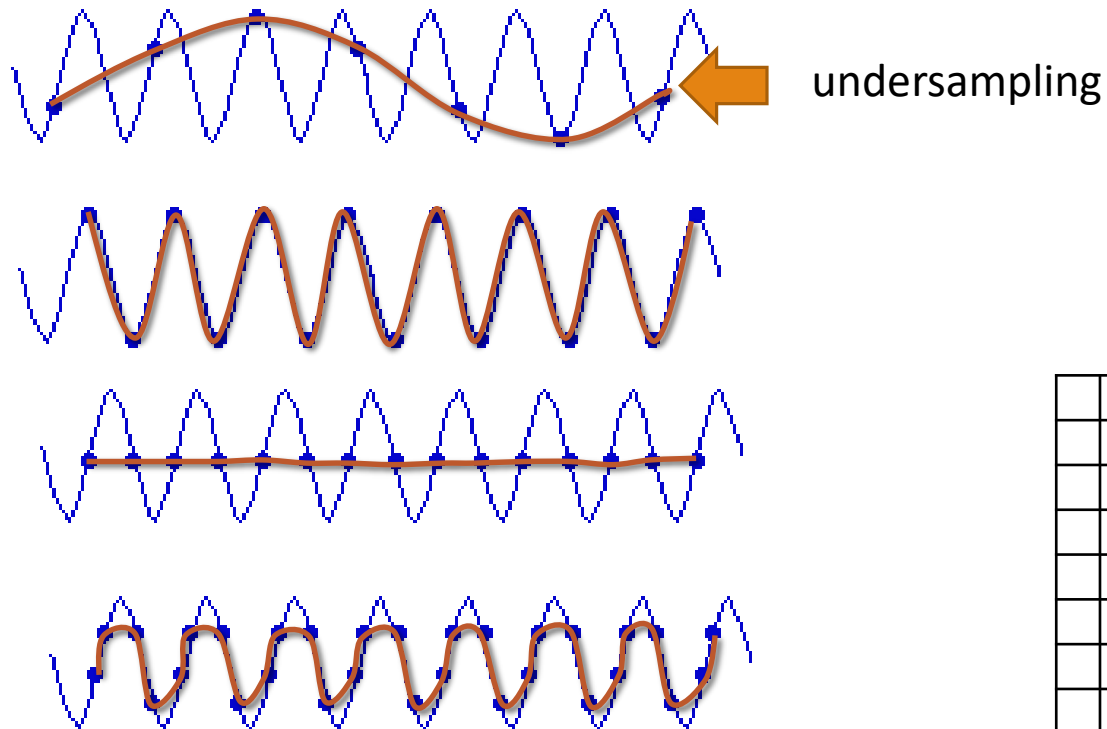
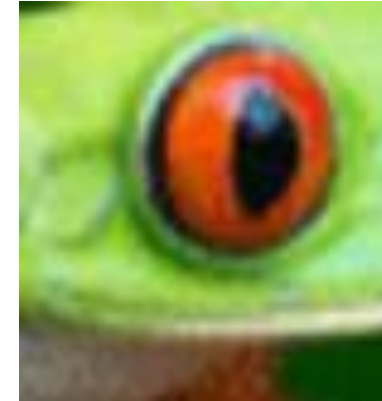
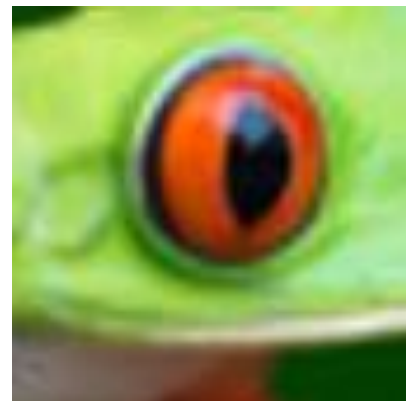
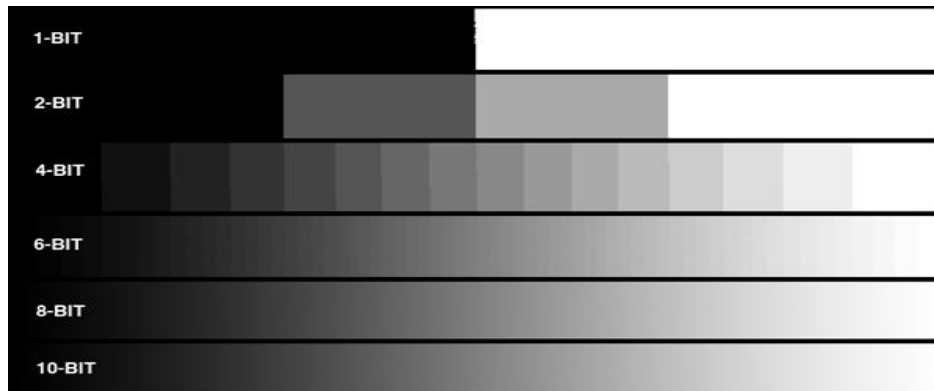
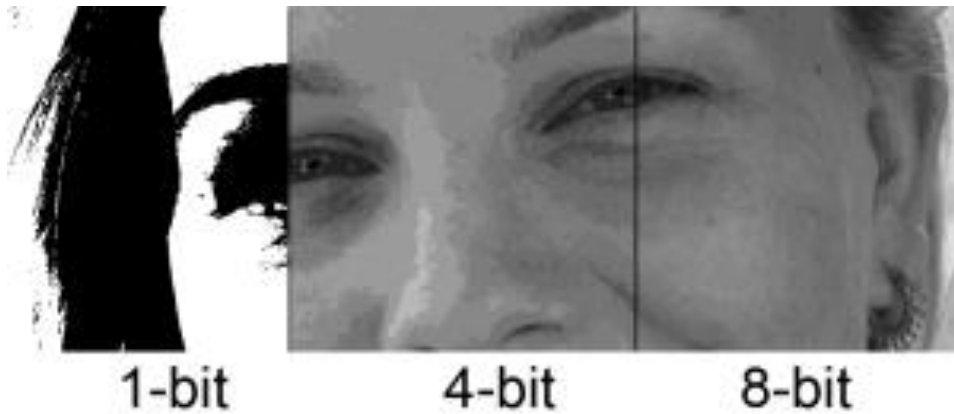
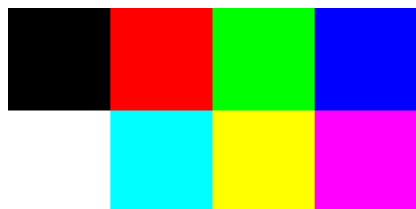


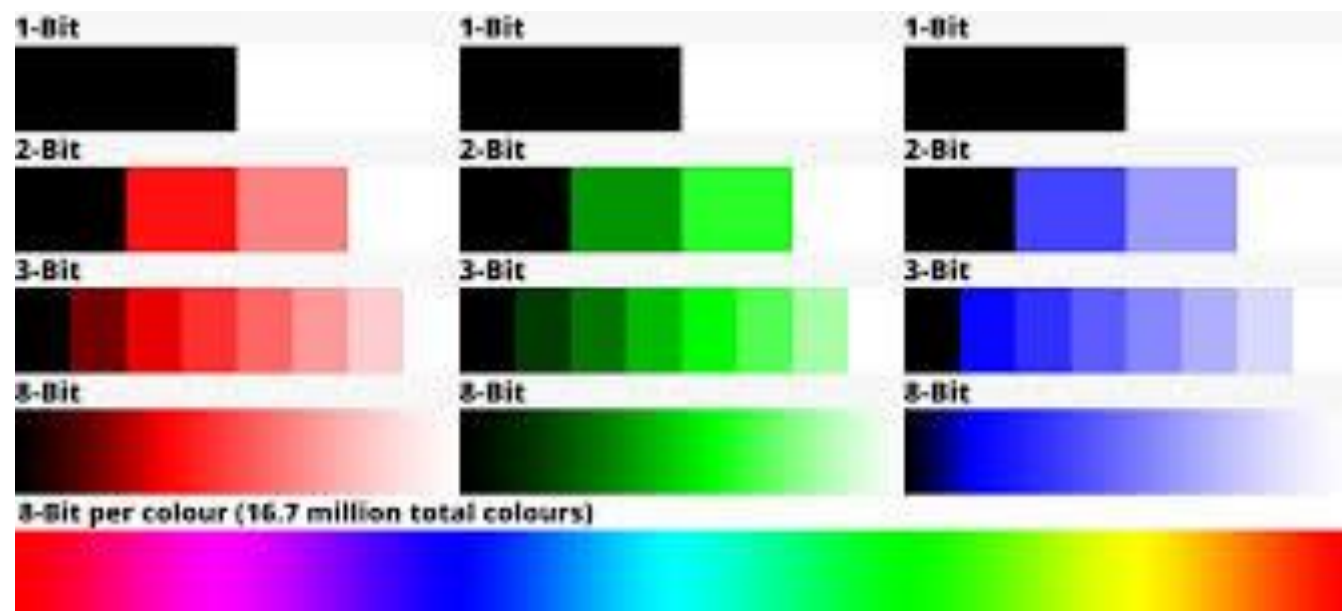
Image Quantization

Conversion of the sampled analog pixel intensities to **discrete valued integer numbers**





3 bit color



Color Depth (<i>bpp total</i>)	R,G,B (<i>bpp</i>)	No. of Colors	Note
8-bit	(3,3,2)	256	VGA
15/16-bit	(5,5,5) or (5,6,5)	32.7k or 65.5k	High color
18-bit	(6,6,6)	262k	
24-bit	(8,8,8)	16.7M	True Color

Color Mode	Color Depth	Number of Colors
HiColor	15 Bit	32.768
	16 Bit	65.536
Direct Color	18 Bit	262.144
	21 Bit	2.097.152
True Color	24 Bit	16.777.217
Deep Color	30 bit	1,07x10exp9
	36 Bit	68,7x10exp9
	48 Bit	281x10exp12

Untitled.png

PNG (*.png)

Monochrome Bitmap (*.bmp;*.dib)

16 Color Bitmap (*.bmp;*.dib)

256 Color Bitmap (*.bmp;*.dib)

24-bit Bitmap (*.bmp;*.dib)

JPEG (*.jpg;*.jpeg;*.jpe;*.jfif)

GIF (*.gif)

TIFF (*.tif;*.tiff)

PNG (*.png)

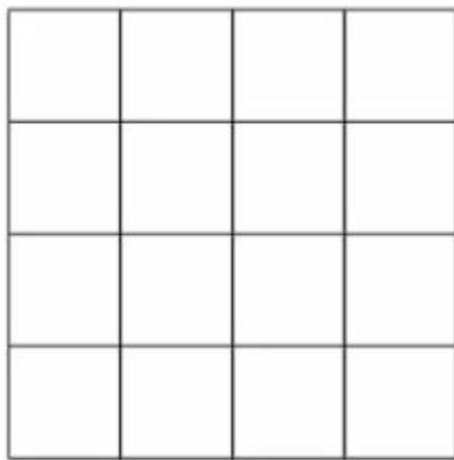
HEIC (*.heic)

Problem in Digital image

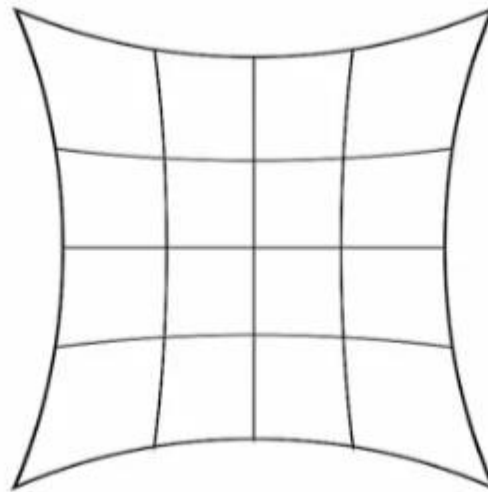
Geometric Distortion

Geometric distortion is an unwanted “warping” of the image that distorts the spatial relationship among objects in the image.

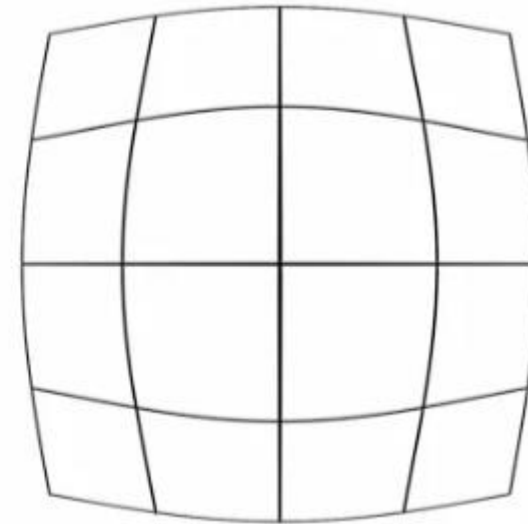
It can change the apparent size and shape of objects and the spacing between them.



Original image



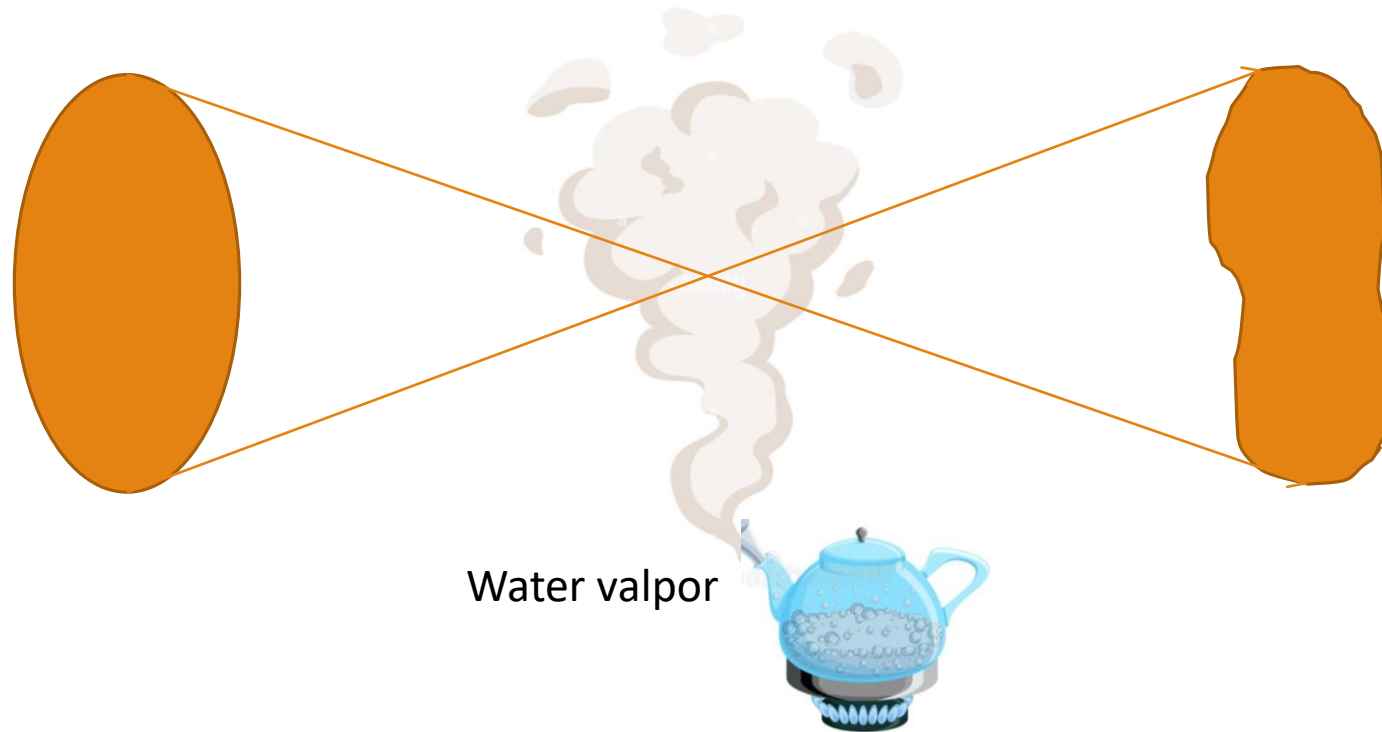
pincushion distortion



barrel distortion

Scattering

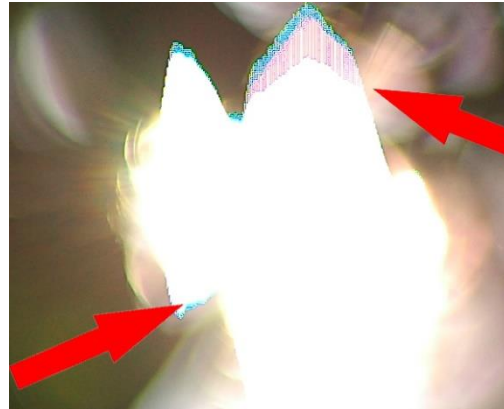
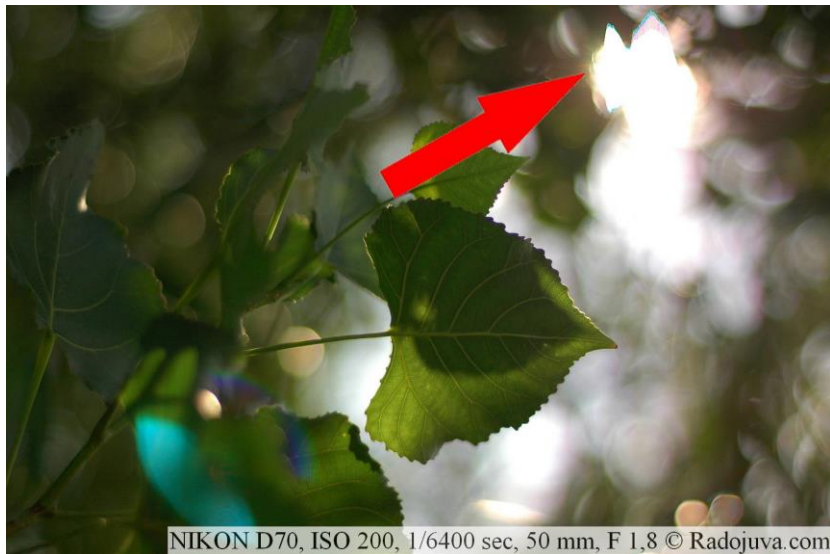
Beam of radiation bent by the medium through which they pass.



Blooming

Blooming occurs when shooting bright light sources, or when shooting at slow shutter speeds.

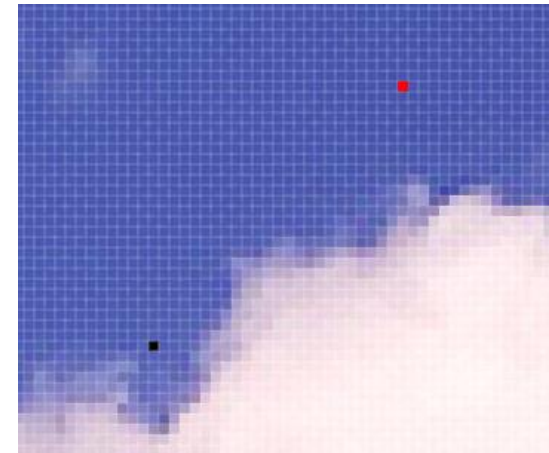
In such cases, the cells of the CCD matrix overflow with charges (light up), the charges 'spread' over neighboring cells, illuminating them as well



CCD Variation

Difference cells maybe variations response to identical light intensity,

- hot pixel - a pixel "**hot**" when it is bright instead of being dark
- dead pixel - a pixel "**dead**" when they are abnormally dark in a bright scene



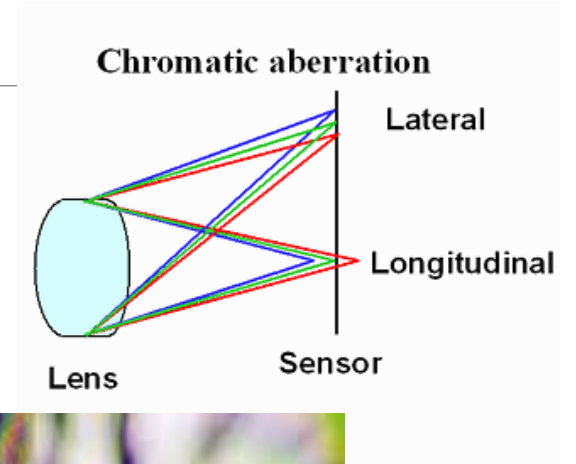
Clipping

A **very high intensity** may be clipping off to a **maximum value**



Chromatic distortion

chromatic distortion is a **failure of a lens to focus all colors** to the same point



Sampling and Quantization effect



THREE-DIMENSIONAL IMAGING

Stereo Images

The human eye use **two images of the same object** captured by both our eyes and combine them to get a three-dimensional perception

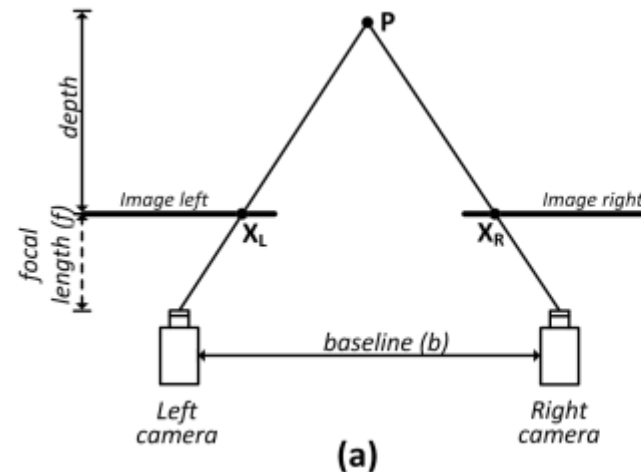
we can use two images of the object using two cameras and combine them to get the depth perception as in case of human vision



Left image



Right image



(a)



(b)



Coordinate system

Pixel Coordinate System

A digital image is essentially a Matrix, consisting of a certain number of rows and a certain number of columns

The first row is always at the top, and named row number 0. The first column is at the left most, and is call column number 0

