

Advanced algorithms and data structures

Lecture 6: van Emde Boas Trees

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December 7th 2022

Today's Lecture

van Emde Boas Trees

- Predecessor search/ordered sets

- Naive

- Twolevel

- Recursive

- vEB: worst case $\mathcal{O}(\log \log |U|)$ time

- RS-vEB: expected $\mathcal{O}(\log \log |U|)$ time, $\mathcal{O}(n \log \log |U|)$ space

- R²S-vEB: expected $\mathcal{O}(\log \log |U|)$ time, $\mathcal{O}(n)$ space

- Bonus: vEB is optimal for $w = \Theta(\log n)$

- Bonus: Integer sorting in expected $\mathcal{O}(n \log \log |U|)$ time.

Predecessor search/ordered sets

Problem:

Given a universe $U = [u]$ where $u = 2^w$,
maintain subset $S \subseteq U$, $|S| = n$ under:

member(x, S): Return $[x \in S]$.

insert(x, S): Add x to S (assumes $x \notin S$).

delete(x, S): Remove x from S (assumes $x \in S$).

empty(S): Return $[S = \emptyset]$.

min(S): Return $\min S$ (assumes $S \neq \emptyset$).

max(S): Return $\max S$ (assumes $S \neq \emptyset$).

predecessor(x, S): Return $\max\{y \in S \mid y < x\}$
(assumes $\{y \in S \mid y < x\}$ is nonempty,
i.e. $S \neq \emptyset$ and $x > \min(S)$).

successor(x, S): Return $\min\{y \in S \mid y > x\}$
(assumes $\{y \in S \mid y > x\}$ is nonempty,
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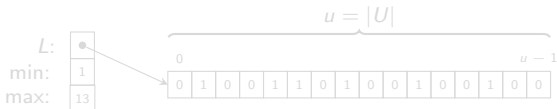
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Naive

Idea: If we are willing to spend $\mathcal{O}(|U|)$ space...

Store S as a bit-array L of length $|U|$ such that $L[x] = [x \in S]$, and keep track of the min and max values explicitly.



$\{1, 4, 5, 7, 10, 13\}$

How fast is:

$\text{empty}(S)$, $\text{min}(S)$, and $\text{max}(S)$?

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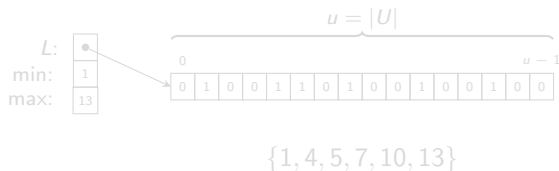
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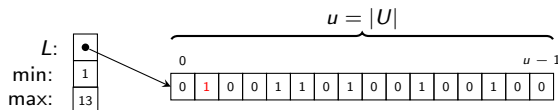
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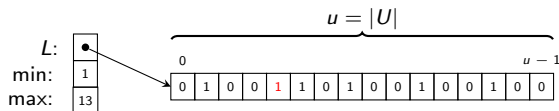
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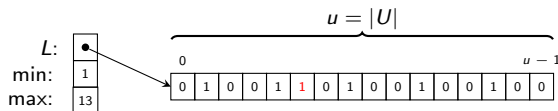
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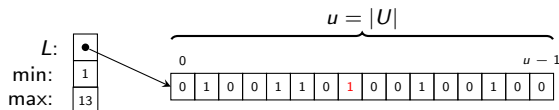
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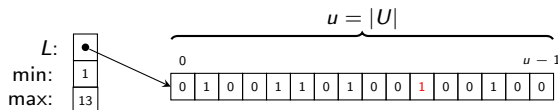
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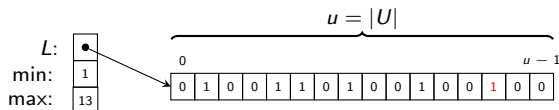
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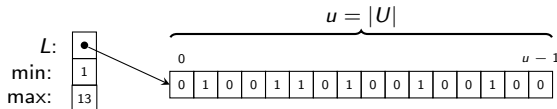
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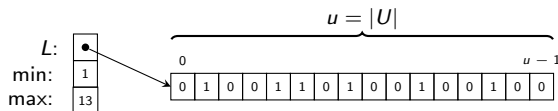
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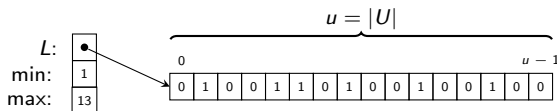
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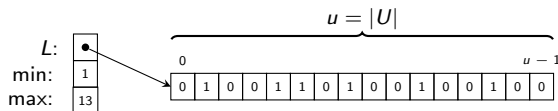
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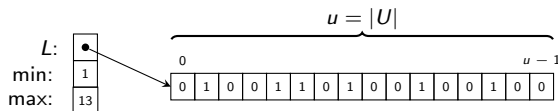
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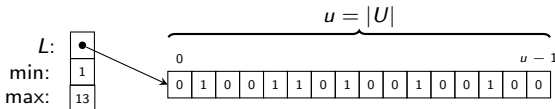
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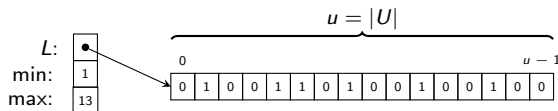
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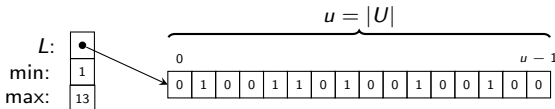
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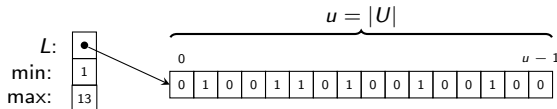
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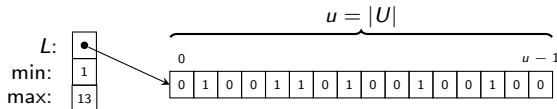
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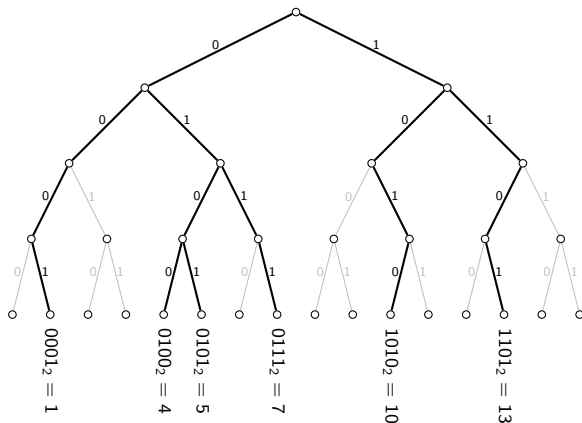
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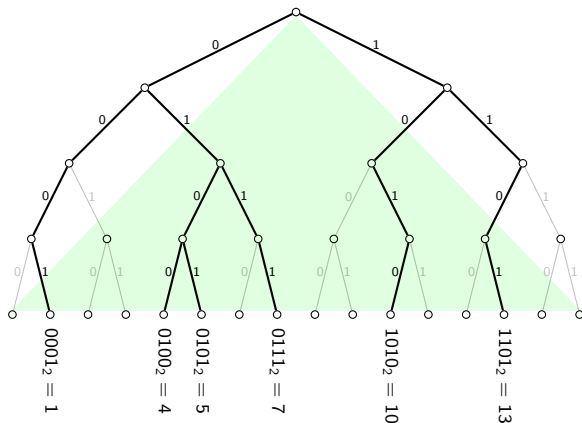
Bit-Trie

Idea: Think of each key as a w -bit string describing a path in a binary *trie* (= a special kind of tree). The naive structure ignores all intermediate branches and jump directly to the leaves. What if we split each key into a high and a low part?



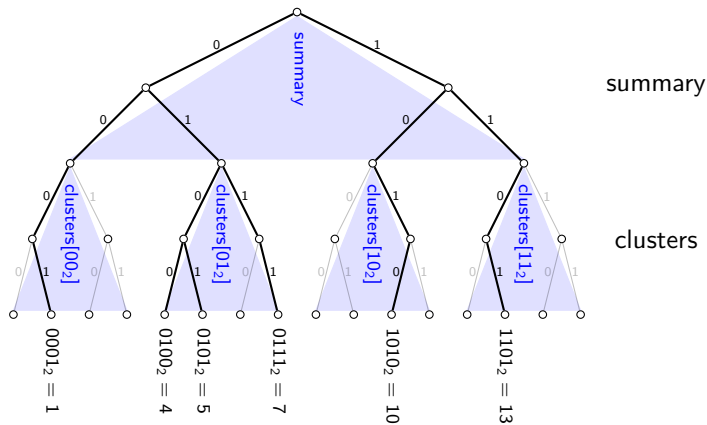
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Twolevel

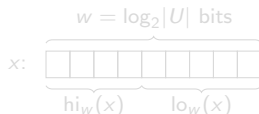
Idea: Split each key into *high* and *low* parts. Use naive for each.

Recall that $U = [2^w]$, and define:

$$\text{hi}_w(x) := \left\lfloor \frac{x}{2^{\lceil w/2 \rceil}} \right\rfloor$$

$$\text{lo}_w(x) := x \bmod 2^{\lceil w/2 \rceil}$$

$$\text{index}_w(h, \ell) := h \cdot 2^{\lceil w/2 \rceil} + \ell$$



note that $x = \text{index}_w(\text{hi}_w(x), \text{lo}_w(x))$.

Now let the structure directly store the values:

$$\text{min} := \min(S) \text{ if } S \neq \emptyset, \text{ else } 1$$

$$\text{max} := \max(S) \text{ if } S \neq \emptyset, \text{ else } 0$$

and use the naive structure to store

$$\text{summary} := \{\text{hi}_w(x) \mid w \in S\}$$

$$\text{clusters}[h] := \{\ell \in [2^{\lceil w/2 \rceil}] \mid \text{index}_w(h, \ell) \in S\} \quad \forall h \in [2^{\lfloor w/2 \rfloor}]$$

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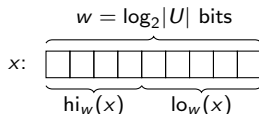
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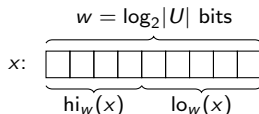
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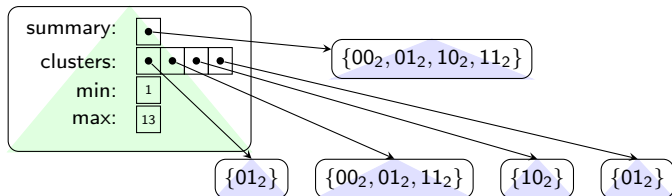
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Twolevel

We can draw the structure for the set $S = \{1, 4, 5, 7, 10, 13\} = \{0001_2, 0100_2, 0101_2, 0111_2, 1010_2, 1101_2\} \subseteq [2^4]$ as:



How fast (worst case) is:

$\text{empty}(S)$, $\text{min}(S)$, $\text{max}(S)$?

$\text{member}(x, S)$?

$\text{predecessor}(x, S)$, $\text{successor}(x, S)$?

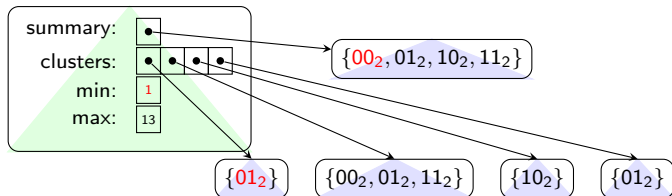
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How can we improve the time further?

Twolevel

We can draw the structure for the set $S = \{1, 4, 5, 7, 10, 13\} = \{0001_2, 0100_2, 0101_2, 0111_2, 1010_2, 1101_2\} \subseteq [2^4]$ as:



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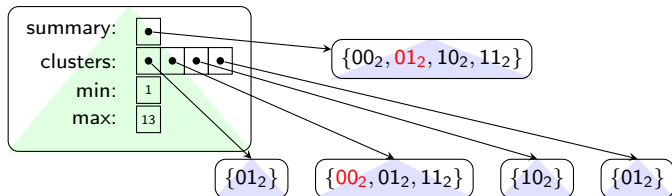
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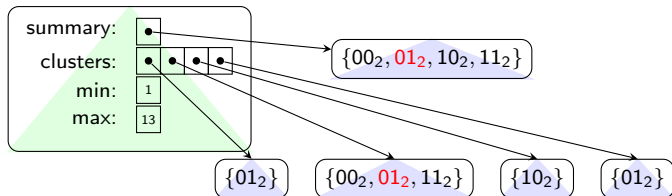
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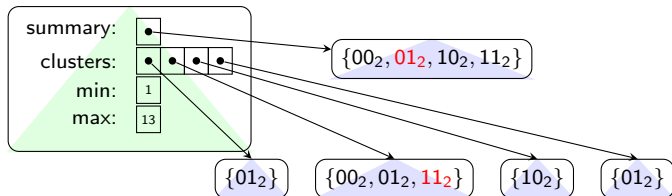
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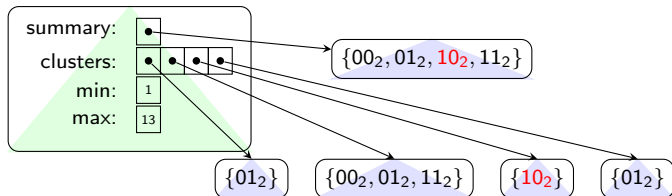
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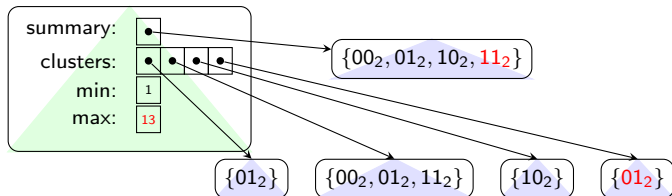
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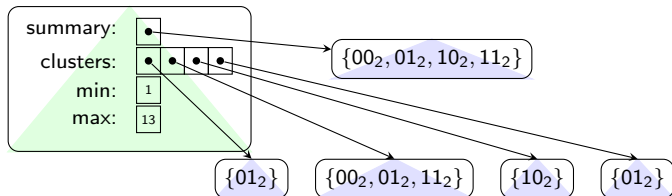
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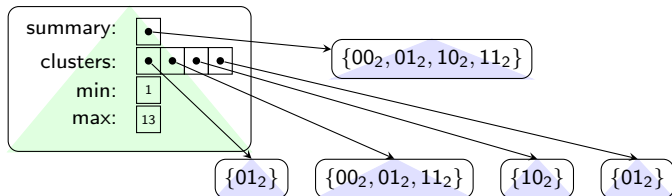
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```
function EMPTY(S)  
    return S.min > S.max
```

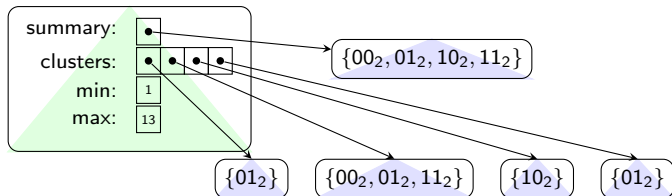
```
function MIN(S)  
    ▷ Assumes  $S \neq \emptyset$   
    return S.min
```

```
function MAX(S)  
    ▷ Assumes  $S \neq \emptyset$   
    return S.max
```

How can we improve the time further?

Twolevel

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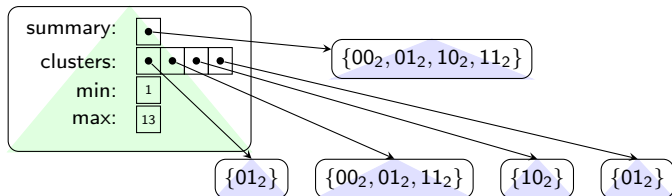
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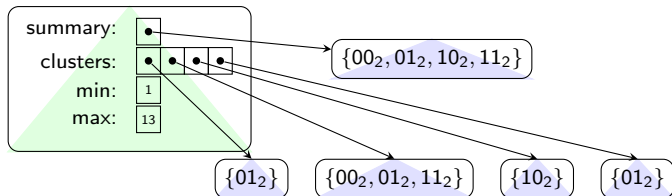
$\text{insert}(x, S)$?

```
function MEMBERw( $x, S$ )  
  return MEMBER $\lceil w/2 \rceil$ ( $\text{lo}_w(x), S.\text{clusters}[\text{hi}_w(x)]$ )
```

How can we improve the time further?

Twolevel

We can draw the structure for the set $S = \{1, 4, 5, 7, 10, 13\} = \{0001_2, 0100_2, 0101_2, 0111_2, 1010_2, 1101_2\} \subseteq [2^4]$ as:



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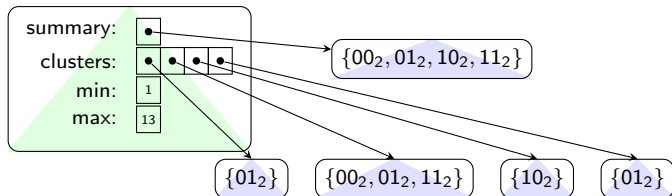
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$= \Theta(2^{\lceil w/2 \rceil}) = \Theta(\sqrt{|U|})$

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function $\text{PREDECESSOR}_w(x, S)$

▷ Assumes $S \neq \emptyset$ and $\text{min}(S) < x$

if $x > S.\text{max}$ **then**

return $S.\text{max}$

$p \leftarrow \text{hi}_w(x)$, $s \leftarrow \text{low}_w(x)$, $C \leftarrow S.\text{clusters}[p]$

if not $\text{EMPTY}(C)$ **and** $C.\text{min} < s$ **then**

return $\text{index}_w(p, \text{PREDECESSOR}_{\lceil w/2 \rceil}(s, C))$

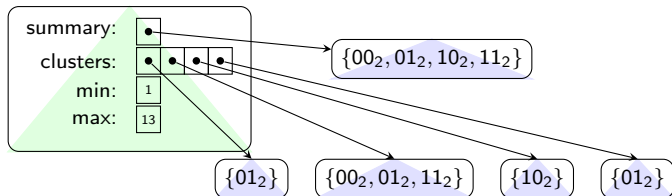
$p \leftarrow \text{PREDECESSOR}_{\lfloor w/2 \rfloor}(p, S.\text{summary})$

return $\text{index}_w(p, S.\text{clusters}[p].\text{max})$

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Twolevel

We can draw the structure for the set $S = \{1, 4, 5, 7, 10, 13\} = \{0001_2, 0100_2, 0101_2, 0111_2, 1010_2, 1101_2\} \subseteq [2^4]$ as:



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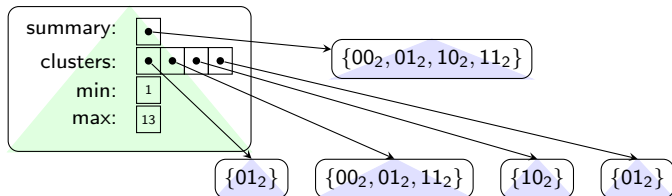
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$\text{insert}(x, S)$?

function $\text{DELETE}_w(x, S)$

▷ Assumes $x \in S$

$p \leftarrow \text{hi}_w(x)$, $s \leftarrow \text{lo}_w(x)$, $C \leftarrow S.\text{clusters}[p]$

DELETE $_{\lceil w/2 \rceil}(s, C)$

if $\text{EMPTY}(C)$ **then**

DELETE $_{\lfloor w/2 \rfloor}(p, S.\text{summary})$

if $S.\text{min} = S.\text{max}$ **then**

$S.\text{min} \leftarrow 1$, $S.\text{max} \leftarrow 0$

else if $x = S.\text{min}$ **then**

$p \leftarrow S.\text{summary}.\text{min}$, $S.\text{min} \leftarrow \text{index}_w(p, S.\text{clusters}[p].\text{min})$

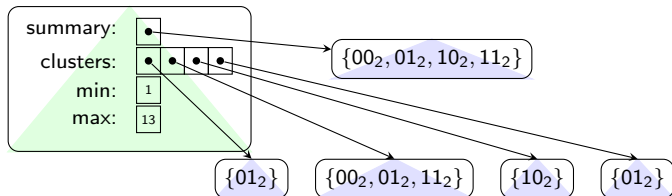
else if $x = S.\text{max}$ **then**

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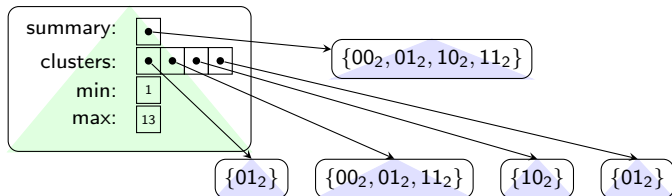
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function $\text{INSERT}_w(x, S)$

▷ Assumes $x \notin S$

if $\text{EMPTY}(S)$ **then**

$S.\text{min} \leftarrow x$, $S.\text{max} \leftarrow x$

if $x < S.\text{min}$ **then** $S.\text{min} \leftarrow x$

if $x > S.\text{max}$ **then** $S.\text{max} \leftarrow x$

$p \leftarrow \text{hi}_w(x)$, $s \leftarrow \text{lo}_w(x)$

if $\text{EMPTY}(S.\text{clusters}[p])$ **then**

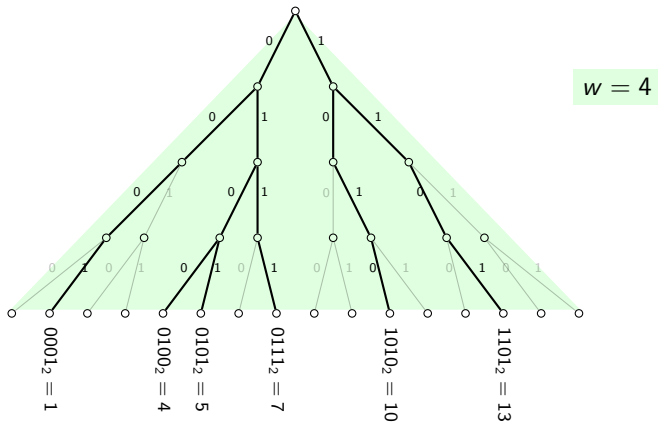
$\text{INSERT}_{\lfloor w/2 \rfloor}(p, S.\text{summary})$

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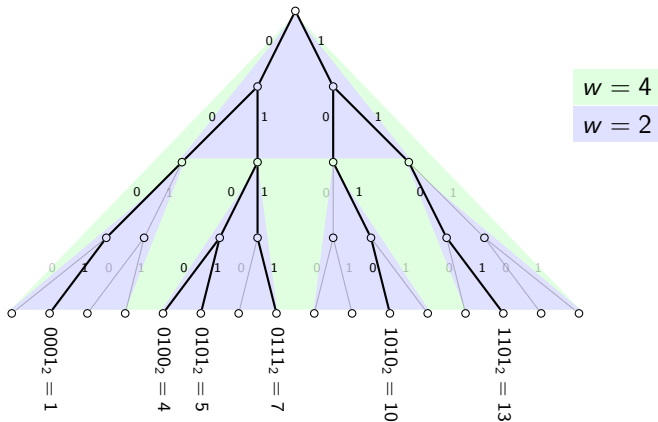
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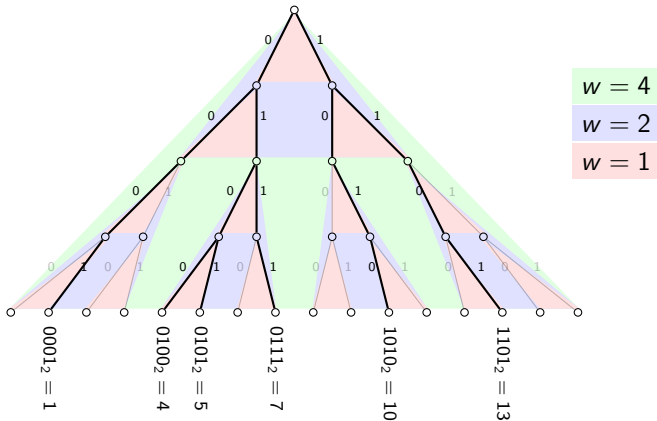
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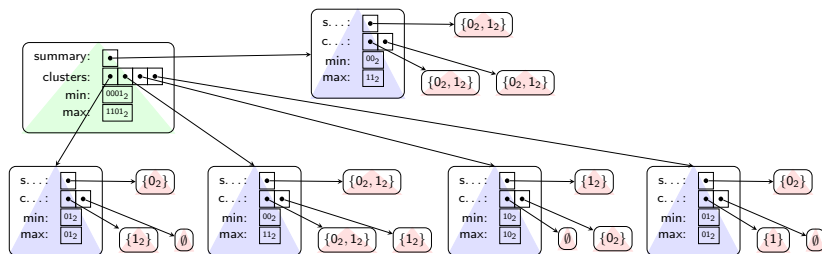
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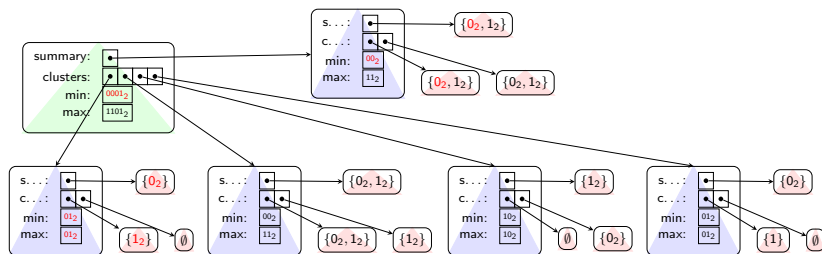


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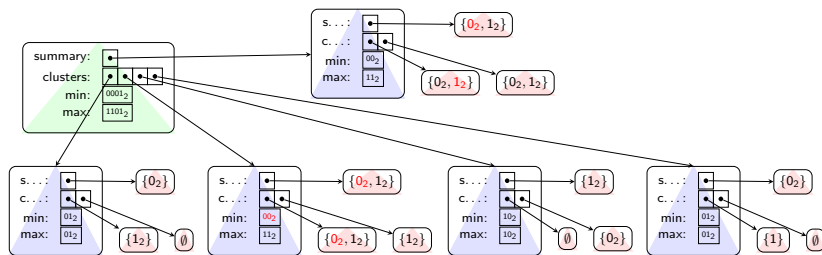


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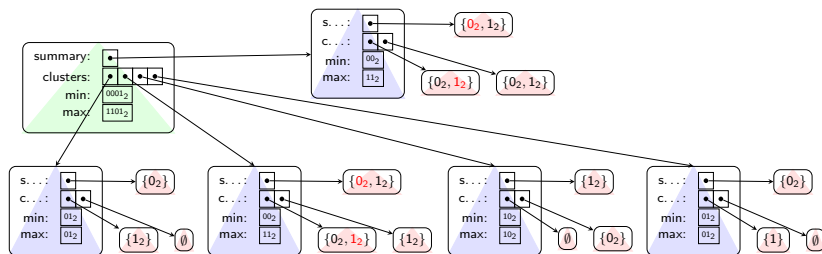


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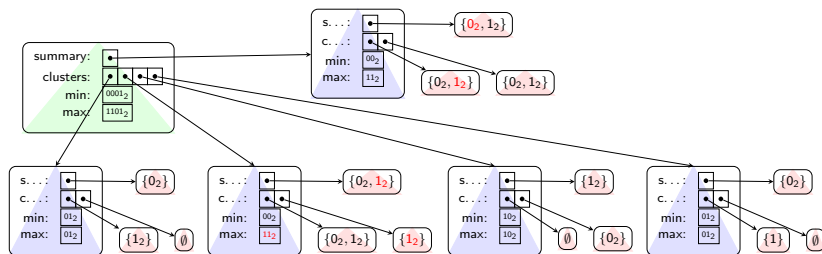


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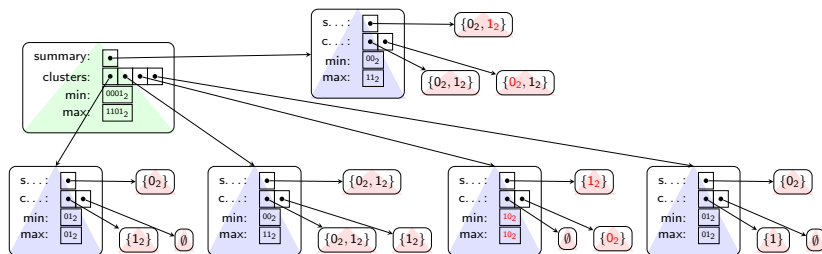


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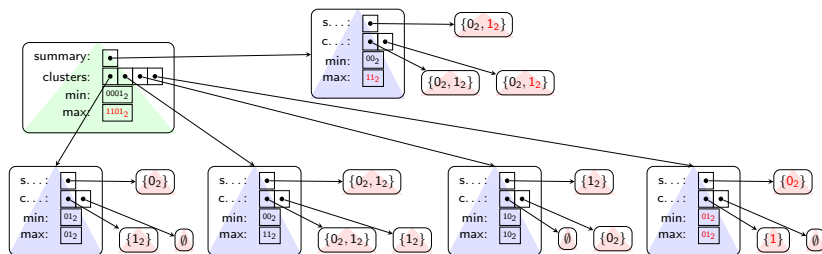


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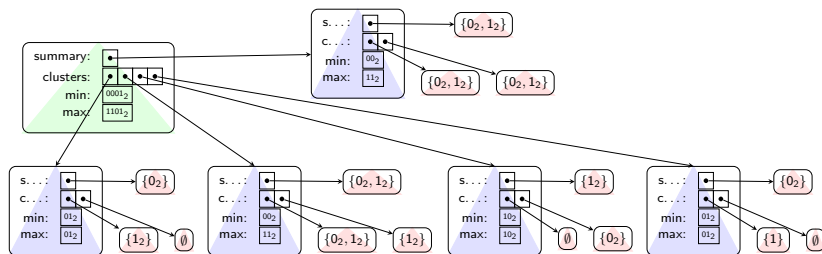


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Recursive

Theorem

The recursion depth of this structure, when used on the universe $U = [2^w]$ is $\lceil \log_2 w \rceil = \mathcal{O}(\log \log |U|)$.

Proof.

Let $d(w)$ be the recursion depth when working with a universe of size 2^w . We will prove by induction that $d(w) = \lceil \log_2 w \rceil$.

The base case is $w = 1$ where there is no recursion, so $d(1) = 0 = \lceil \log_2(1) \rceil$.

For the induction case, suppose $w > 1$ and that $d(w') = \lceil \log_2(w') \rceil$ for all $w' \in [w]_+$. Now let $w' = \lceil w/2 \rceil \in [w]_+$, then the largest universe size used in the recursion is $2^{w'}$, and

$$d(w) = 1 + d(w') = 1 + \lceil \log_2(w') \rceil = \lceil \log_2(2w') \rceil.$$

If w is even, $2w' = w$ and we are done.

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Using the recursive structure, how fast is:
 $\text{empty}(S)$, $\text{min}(S)$, and $\text{max}(S)$?

$\text{member}(x, S)$?

$\text{predecessor}(x, S)$ and $\text{successor}(x, S)$?

$\text{insert}(x, S)$ and $\text{delete}(x, S)$?

How can we improve the update time?

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Using the recursive structure, how fast is:

$\text{empty}(S)$, $\text{min}(S)$, and $\text{max}(S)$? worst case $\mathcal{O}(1)$.

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 $= \Theta(2^{d(w)}) = \Theta(w) = \Theta(\log |U|)$.

How can we improve the update time? Somehow make insert and delete recurse in only one substructure.

vEB: worst case $\mathcal{O}(\log \log |U|)$ time

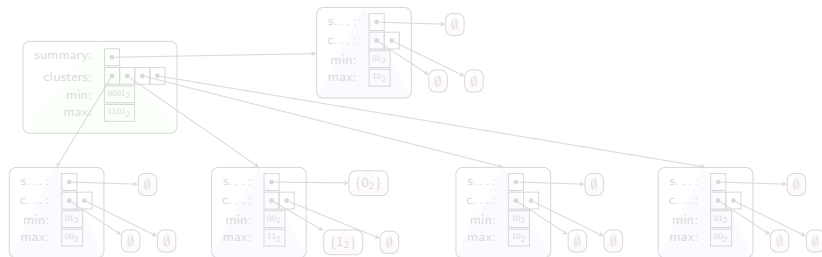
Idea: Exclude $\min(S)$ and/or $\max(S)$ from the set of keys stored in summary and clusters. (CLRS excludes only $\min(S)$, I exclude both).

Specifically, redefine summary and clusters to recursively store the sets:

$$\text{summary} := \{hi_w(x) \mid w \in S \setminus \{\min, \max\}\}$$

$$\text{clusters}[h] := \{\ell \in [2^{\lceil w/2 \rceil}] \mid \text{index}_w(h, \ell) \in S \setminus \{\min, \max\}\} \quad \forall h \in [2^{\lfloor w/2 \rfloor}]$$

We can draw the van Emde Boas tree for the set $S = \{1, 4, 5, 7, 10, 13\} = \{0001_2, 0100_2, 0101_2, 0111_2, 1010_2, 1101_2\} \subseteq [2^4]$ as:



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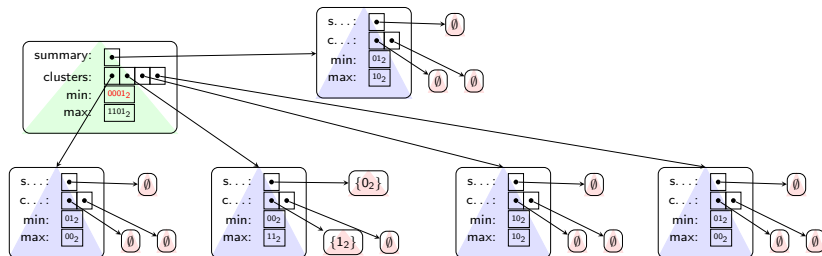
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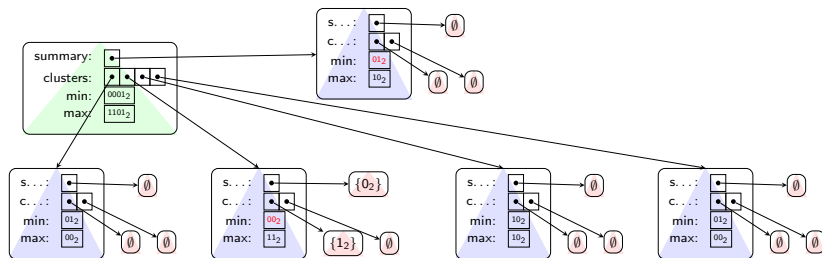
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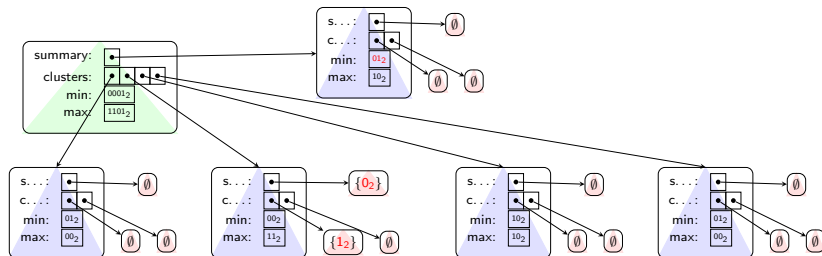
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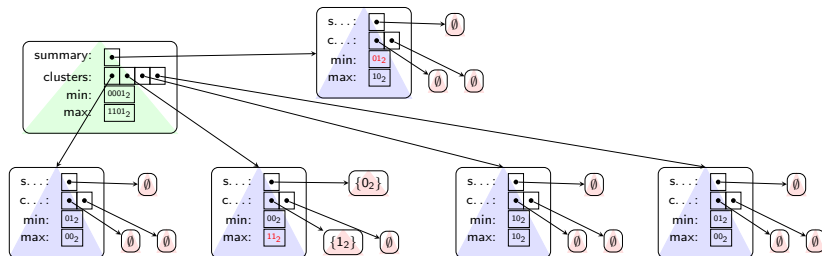
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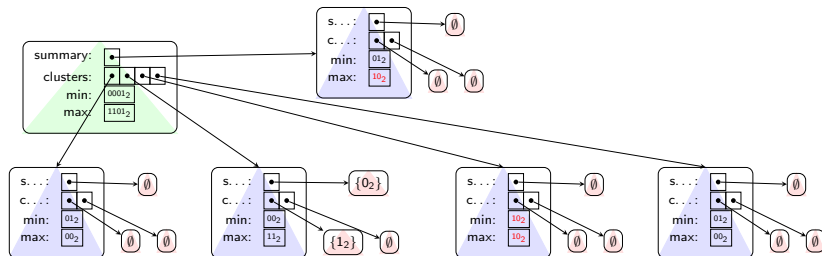
Specifically, redefine summary and clusters to recursively store the sets:

$$\text{summary} := \{hi_w(x) \mid w \in S \setminus \{\min, \max\}\}$$

$$\text{clusters}[h] := \{\ell \in [2^{\lceil w/2 \rceil}] \mid \text{index}_w(h, \ell) \in S \setminus \{\min, \max\}\} \quad \forall h \in [2^{\lfloor w/2 \rfloor}]$$

We can draw the van Emde Boas tree for the set $S =$

$$\{1, 4, 5, 7, 10, 13\} = \{0001_2, 0100_2, 0101_2, 0111_2, 1010_2, 1101_2\} \subseteq [2^4] \text{ as:}$$



vEB: worst case $\mathcal{O}(\log \log |U|)$ time

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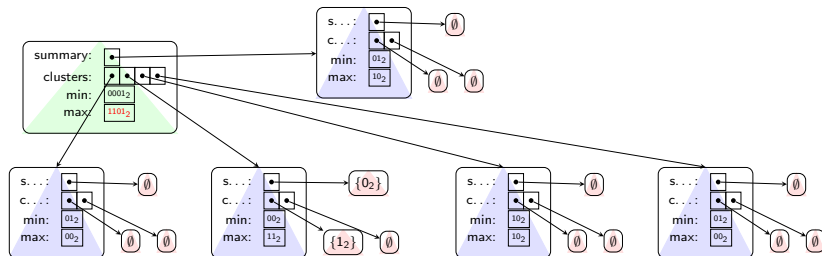
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vEB: worst case $\mathcal{O}(\log \log |U|)$ time, $\mathcal{O}(|U|)$ space

```
1: function PREDECESSORw(x, S)    ▷ Assumes  $S \neq \emptyset$  and  $x > S.\text{min}$ 
2:   if  $x > S.\text{max}$  then
3:     return  $S.\text{max}$ 
4:   if  $w = 1$  then
5:     return  $S.\text{min}$ 
6:    $p \leftarrow \text{hi}_w(x)$ ,  $s \leftarrow \text{lo}_w(x)$ ,  $C \leftarrow S.\text{clusters}[p]$ 
7:   if not EMPTY( $C$ ) and  $C.\text{min} < s$  then
8:     return  $\text{index}_w(p, \text{PREDECESSOR}_{\lceil w/2 \rceil}(s, C))$ 
9:   if EMPTY( $S.\text{summary}$ ) or  $p \leq S.\text{summary}.\text{min}$  then
10:    return  $S.\text{min}$ 
11:    $p \leftarrow \text{PREDECESSOR}_{\lfloor w/2 \rfloor}(p, S.\text{summary})$ 
12:   return  $\text{index}_w(p, S.\text{clusters}[p].\text{max})$ 
```

Theorem

$\text{PREDECESSOR}_w(x, S)$ takes worst case $\mathcal{O}(d(w)) = \mathcal{O}(\log \log |U|)$ time.

Proof.

It makes at most one recursive call.



vEB: worst case $\mathcal{O}(\log \log |U|)$ time, $\mathcal{O}(|U|)$ space

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1: function PREDECESSORw(x, S)    ▷ Assumes  $S \neq \emptyset$  and  $x > S.min$ 
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vEB: worst case $\mathcal{O}(\log \log |U|)$ time, $\mathcal{O}(|U|)$ space

```
1: function INSERTw( $x, S$ ) ▷ Assumes  $x \notin S$ 
2:   if EMPTY( $S$ ) then
3:      $S.\text{min} \leftarrow x, S.\text{max} \leftarrow x$ , return
4:   if  $S.\text{min} = S.\text{max}$  then
5:     if  $x < S.\text{min}$  then  $S.\text{min} \leftarrow x$ 
6:     if  $x > S.\text{max}$  then  $S.\text{max} \leftarrow x$ 
7:     return
8:   if  $x < S.\text{min}$  then  $S.\text{min} \leftrightarrow x$ 
9:   if  $x > S.\text{max}$  then  $S.\text{max} \leftrightarrow x$ 
10:   $p \leftarrow \text{hi}_w(x), s \leftarrow \text{lo}_w(x)$ 
11:  if EMPTY( $S.\text{clusters}[p]$ ) then
12:    INSERT $\lfloor w/2 \rfloor$ ( $p, S.\text{summary}$ )
13:  INSERT $\lceil w/2 \rceil$ ( $s, S.\text{clusters}[p]$ )
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Theorem

INSERT_w(x, S) takes worst case $\mathcal{O}(d(w)) = \mathcal{O}(\log \log |U|)$ time.

Proof.

It makes at most one recursive call on a non-empty substructure, and inserting in an empty substructure takes constant time. □

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▷ Assumes $x \notin S$

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It makes at most one recursive call on a non-empty substructure, and inserting in an empty substructure takes constant time.



RS-vEB: expected $\mathcal{O}(\log \log |U|)$ time, $\mathcal{O}(n \log \log |U|)$ space

Idea: Use a hash table instead of an array to store clusters[·], and don't store empty substructures.

Why does this change updates from worst case $\mathcal{O}(\log \log |U|)$ to expected $\mathcal{O}(\log \log |U|)$ time?

Why does this only use $\mathcal{O}(n \cdot d(w)) = \mathcal{O}(n \log \log |U|)$ space?

RS-vEB: expected $\mathcal{O}(\log \log |U|)$ time, $\mathcal{O}(n \log \log |U|)$ space

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Why does this change updates from worst case $\mathcal{O}(\log \log |U|)$ to expected $\mathcal{O}(\log \log |U|)$ time? Because updates to a hash table take expected $\mathcal{O}(1)$ time rather than worst case.

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Why does this only use $\mathcal{O}(n \cdot d(w)) = \mathcal{O}(n \log \log |U|)$ space? Because the empty structure uses $\mathcal{O}(1)$ space and INSERT_w only creates or updates $\mathcal{O}(d(w))$ substructures in the worst case. Each of these costs at most an additional $\mathcal{O}(1)$ space

R²S-vEB: expected $\mathcal{O}(\log \log |U|)$ time, $\mathcal{O}(n)$ space

Idea: Partition S into “chunks” of size $\Theta(\min\{n, \log \log |U|\})$, and store only one element representing each chunk in the RS-vEB structure. I.e. RS-vEB stores only $\mathcal{O}(\max\{1, n/\log \log |U|\})$ elements, using $\mathcal{O}(n)$ space.

We can store each chunk as a sorted linked list, and keep a hash table mapping each representative to its chunk. This also takes $\mathcal{O}(n)$ space.

PREDECESSOR and SUCCESSOR uses the RS-vEB structure to find the nearest two representatives in $\mathcal{O}(\log \log |U|)$ time, and can then spend linear time in the size of the two chunks to find the result.

INSERT may have to split a chunk that becomes too large and insert a new representative in the RS-vEB structure. Splitting the chunk can take linear time in the size of the chunk, and together with inserting the new representative into the RS-vEB structure, this still only takes expected $\mathcal{O}(\log \log |U|)$ time.

Similarly, DELETE may have to join two chunks and delete a representative, but again this only takes expected $\mathcal{O}(\log \log |U|)$ time.

R^2S -vEB: expected $\mathcal{O}(\log \log |U|)$ time, $\mathcal{O}(n)$ space

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Bonus: vEB is optimal for $w = \Theta(\log n)$

In fact, $\mathcal{O}(\log w)$ is the optimal query time when $w \in \Theta(\log n)$, or equivalently when $n \in 2^{\Theta(w)}$. This was shown in:

Time-space trade-offs for predecessor search,

Mihai Pătraşcu and Mikkel Thorup,

STOC'06: Proceedings of the thirty-eighth annual ACM symposium on Theory of Computing, pages 232–240.

<https://doi.org/10.1145/1132516.1132551>

Bonus: Integer sorting in expected $\mathcal{O}(n \log \log |U|)$ time.

Idea: Insert all elements in R^2S -vEB structure, use $\text{MIN}(S)$ then repeatedly $\text{SUCCESSOR}(x, S)$.

This takes expected $\mathcal{O}(n \log \log |U|) = \mathcal{O}(n \log w)$ time.

Compare this to other famous sorting methods:

QUICKSORT Takes expected $\mathcal{O}(n \log n)$ time.

COUNTINGSORT Takes $\mathcal{O}(n + |U|)$ time.

RADIXSORT Takes $\mathcal{O}((n + r) \log_r |U|) = \mathcal{O}((n + r) \frac{w}{\log r})$ time for radix r , e.g. $\mathcal{O}(\frac{n}{\log n} \log |U|) = \mathcal{O}(\frac{nw}{\log n})$ for $r = n$.

We observe that for $\log n \in \Omega(\log w) \cap \mathcal{O}(\frac{w}{\log w})$, or equivalently $n \in w^{\Omega(1)} \cap 2^{\mathcal{O}(\frac{w}{\log w})}$, sorting using vEB should be better than these alternatives.

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Today's topic was van Emde Boas Trees, which is a data structure for sets of bounded integers. We have covered

- ▶ A naive implementation of ordered sets.
- ▶ A slightly less naive two-level implementation.
- ▶ A recursive implementation with good query time (proto-vEB).
- ▶ The actual van Emde Boas Tree (vEB).
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