

$\sigma : V_B \cup F_B \cup Z_B \longrightarrow \mathcal{I} = \{0, 1, \dots, r-2\}$; let $v, f, z, v_1, v_2, f_1, f_2, z_1, z_2 \in \text{Im}(\sigma) = \mathcal{I}$.

