#### Quick Reference

### NEMA size 17 1.8° 2-phase stepper motor









#### **Notes and Warnings**

Installation, configuration and maintenance must be carried out by qualified technicians only. You must have detailed information to be able to carry out this work.

- Unexpected dangers may be encountered when working with this product!
   Incorrect use may destroy this product and connected components!

For more information, go to www.imshome.com

#### **Specifications**

1.5 Amp motors		Single length	Double length	Triple length			
Part number		M-1713-1.5 ● (1)	M-1715-1.5 • (1)	M-1719-1.5 ● (1)			
Holding torque	oz-in	32	60	75			
	N-cm	23	42	53			
Detent torque	oz-in	1.7	2.1	3.5			
	N-cm	1.2	1.5	2.5			
Rotor inertia	oz-in-sec <sup>2</sup>	0.000538	0.0008037	0.0011562			
	kg-cm <sup>2</sup>	0.038	0.057	0.082			
Weight	OZ	7.4	8.1	12.7			
	grams	210	230	360			
Phase current	amps	1.5	1.5	1.5			
Phase resistance	ohms	1.3	2.1	2.0			
Phase inductance	mH	2.1	5.0	3.85			

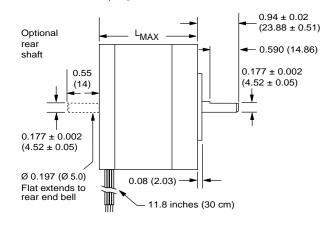
(1) Indicate S for single-shaft or D for double-shaft. Example M-1713-1.5S

#### Wiring and Connections

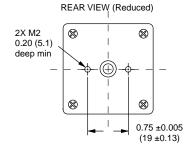
Signals and wire colors	
Phase A	Red
Phase /A	Blue
Phase B	Green
Phase /B	Black

#### **Mechanical Specifications**

Dimensions in inches (mm)



## FRONT VIEW 4X Ø M3xP0.5 0.177 (4.5) deep min Ø 0.197 +0/-0.001 (Ø 4.99 +0/-0.012) Ø 0.866 +0/-0.002 (Ø 22.0 +0/-0.052) $- \oplus$ □1.22 (□30.99) □1 67 (□42.3)



Motor stack length inches (mm)	Single	Double	Triple		
LMAX	1.34 (34.0)	1.57 (40)	1.89 (48)		

#### **Part Numbers**

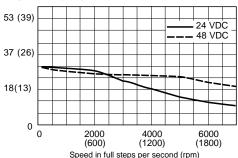
Example:	IVI	-	1	1	1	3 -	1.	5 ;	5		
Stepper motor frame size M-17 = NEMA 17 (1.7"/42 mm)	M	-	1	7	1	3 -	1 .	5 \$	S		
Motor length 13- = single stack 15- = double stack 19- = triple stack	М	-	1	7	1	3	1 . :	5 \$	S		
Phase current 1.5 = 1.5 Amps	М	-	1	7	1	3 -	1 . :	5 \$	S		
Shaft S = single, front shaft only D = double, front and rear shafts	М	-	1	7	1	3 -	1 . :	5 \$	S		
Optional optical encoder (1) ES = Single-end ED = Differential	М	-	1	7	1	3 -	1 .	5 <b>I</b>	E S	1	0 0
<b>Line count</b> 100, 200, 250, 400, 500 or 1000 <i>(2)</i>											

- (1) An encoder replaces the shaft designator in the part number.
- (2) All encoders have an index mark, except the 1000 line count version.

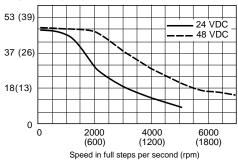
# **Torque-speed performance** Measured at 1.5 Amps RMS

#### M-1713-1.5

Torque in oz-in (N-cm)

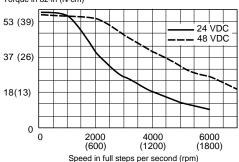


# **M-1715-1.5** Torque in oz-in (N-cm)



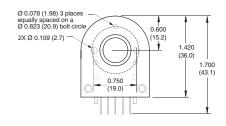
#### M-1719-1.5

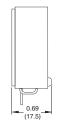
Torque in oz-in (N-cm)



#### **Optical Encoder Option**

Dimensions in inches (mm)





differential encoder

Connectivity

single-end encoder

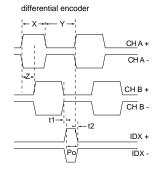


function Brown Ground
Violet Index
Blue Channel A
Orange +5 VDC input
Yellow Channel B pin function
1 no conne
2 +5 VDC i
3 Ground
4 no conne
5 Channel pin function
6 Channel A+
7 Channel B 8 Channel B+
9 Index 10 Index + no connect +5 VDC input Ground no connect Channel A –

optional interface cable available: ES-CABLE-2

interface cable included

Timing single-end encoder - X → - Y -<u>Сн</u>в -t2 IDX



Parameter	Symbol	Min	Тур	Max	Units
Cycle error			3	5.5	°e
Symmetry		130	180	230	°e
Quadrature		40	90	140	°e
Index pulse width	Po	60	90	120	°e
Index rise (after Ch A or B rise)	t1	-300	100	250	ns
Index fall (after Ch A or B fall)	t2	70	150	1000	ns

One cycle: 360 electrical degrees (°e).

Symmetry: the measure of the relationship between X and Y, nominally 180°e.

Quadrature: the phase lead or lag between channels A and B, nominally 90°e.

Index pulse width, nominally 90 °e.

NOTE: Rotation is as viewed from the cover side of the encoder.