

(Hansen 1959): “potential of opportunities for interaction”

$$S_i = \sum_j O_j \cdot f(c_{ij})$$

A Family of Accessibility Measures:

Bringing the units back

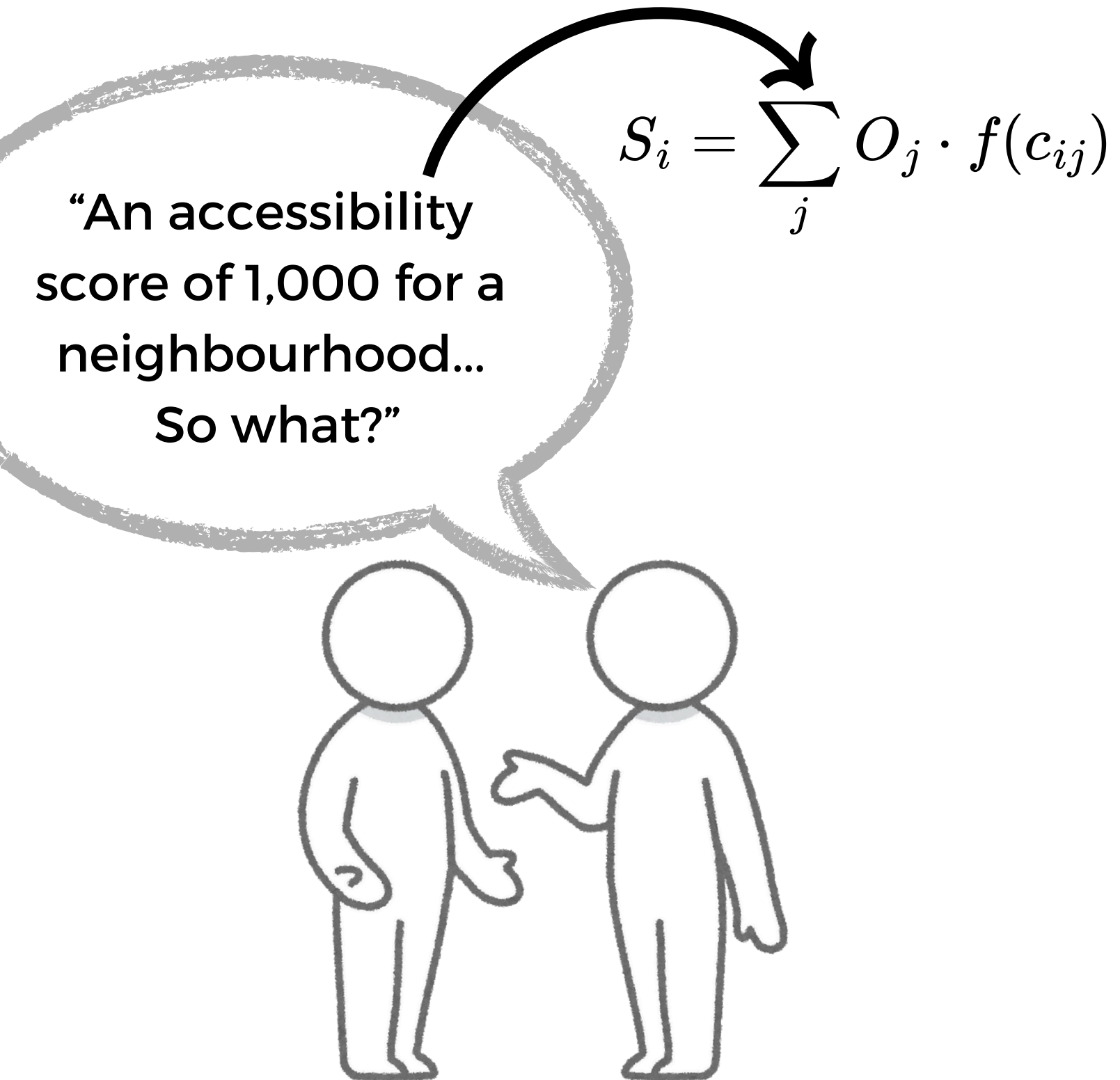
Anastasia Soukhov B.Eng. MASc.

(Supervisor: Antonio Páez)

PhD Candidate in Transport Geography

McMaster University, Canada

Deciphering accessibility scores:



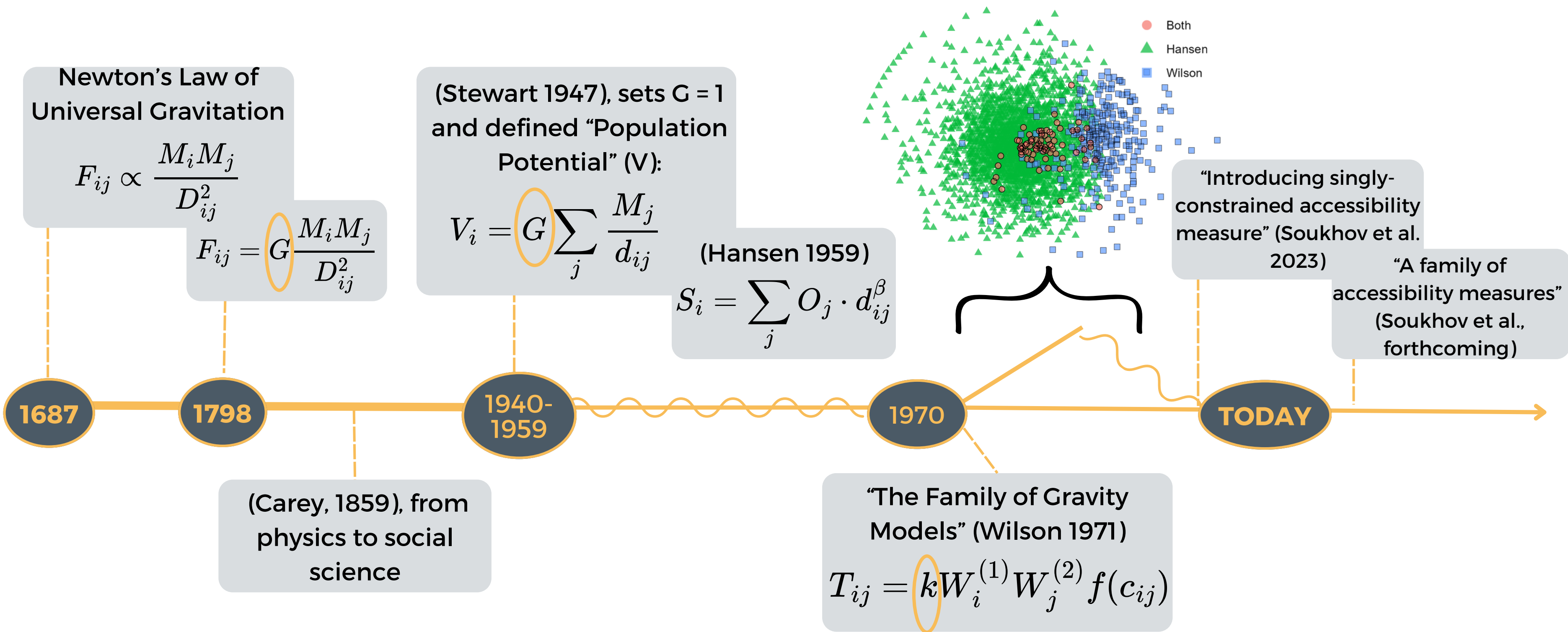
The problem:

- What does the accessibility score mean? The units are uninterpretable!

A solution:

- (Re)introducing proportionality constants to bring units back to accessibility

Evolution of gravity-based accessibility: what about G?



A “family” of accessibility measures

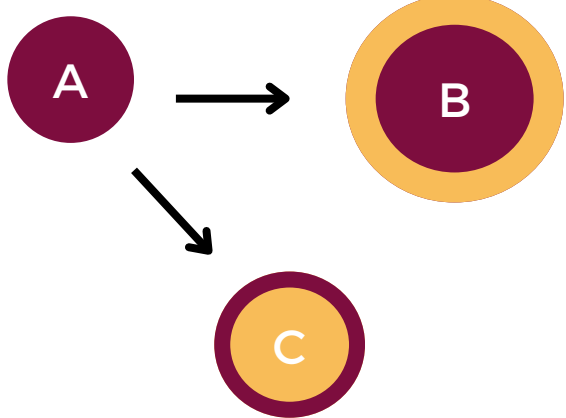
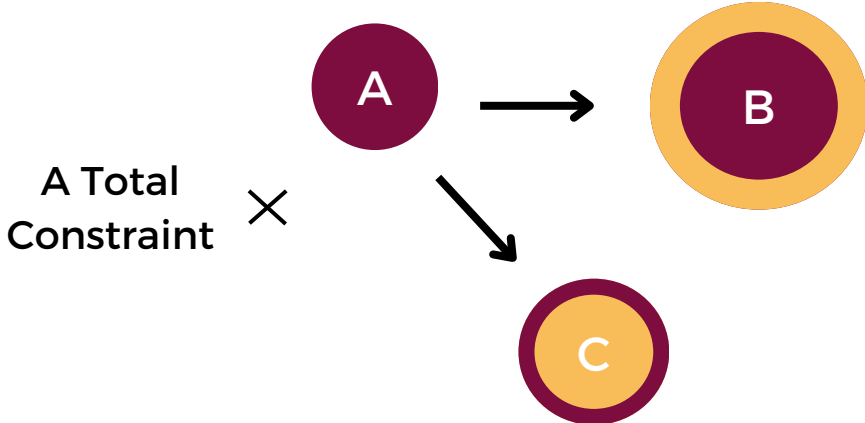
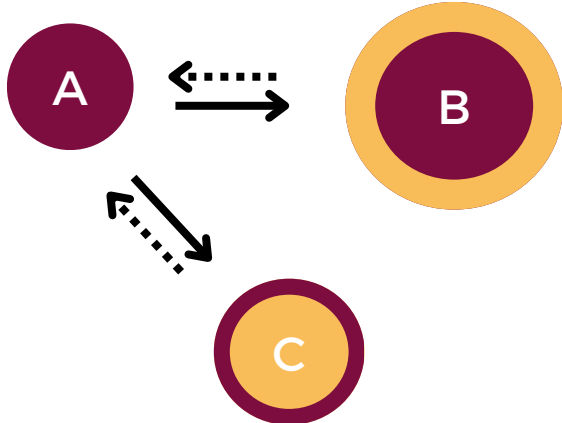
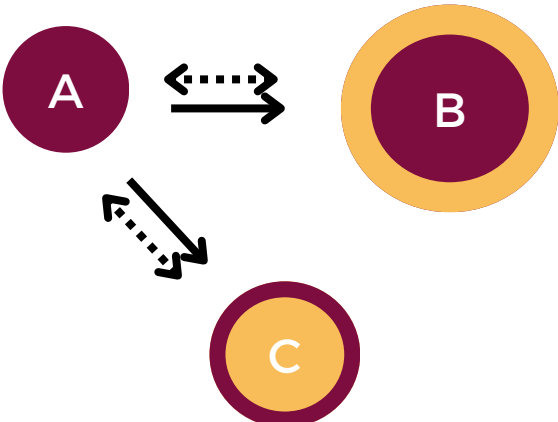
Gravity model's formulation:

$$T_{ij} = kW_i^{(1)}W_j^{(2)}f(c_{ij}) \longrightarrow V_{ij} = kO_jf(c_{ij})$$
$$V_i = k \sum_j O_j f(c_{ij})$$

$W_i^{(1)} \longrightarrow P_i$
 $W_j^{(2)} \longrightarrow O_j$

k is a set of balancing factors defined by zonal/region constraints.

Proportionality constraints in accessibility matter:

Unconstrained (all people to all jobs)	Total Constrained (all people to all jobs ; balanced)	Singly-constrained (all people to jobs at each zone)	Doubly-constrained (people at each zone to jobs at each zone)
			
1,000 'accessible' jobs at A	100 accessible jobs at A (out of 500)	200 accessible jobs at A (out of 500)	250 accessible jobs at A (out of 500)

By balancing the units, an accessibility “family” framework can add:

- 1. Enhanced interpretation,
- 2. Comparability across spatial and temporal cases
- 3. Robustness to spatial analysis (e.g., V_i adds up to 100%)

$$V_i = k \sum_j O_j f(c_{ij})$$

A “family” of accessibility measures

$$V_{ij} = k O_j f(c_{ij})$$

$$V_i = k \sum_j O_j f(c_{ij})$$

k is a set of balancing factors defined by zonal/region constraints.

$$\sum_i \sum_j V_{ij} = V \rightarrow 1) \text{ Total constraint}$$

$$\sum_i V_{ij} = O_j \rightarrow 2) \text{ Opportunity constraint}$$

$$\sum_j V_{ij} = P_i \rightarrow 3) \text{ Population constraint}$$

Unconstrained case (neither constraint 1, 2, or 3)

- Current practice

Total constrained case (constraint 1)

Singly-constrained case (constraint 1 and 2)

- e.g., spatial availability measure (Soukhov et al., 2023, 2024, 2024)

$$k = B_{ij} = \frac{P_i}{\sum_i P_i f(c_{ij})}$$

Doubly-constrained case (constraint 1,2, and 3)