Algorithm 1 SeedSubTrees(Γ)

1: **for** $rootC \in compSet$ **do**
2: **if** (Empty(Γ_{rootC})) **then**
3: continue;
4: **end if**
5: $level$ = [ ]; {dynamic array of failed components at subTree's current level}
6: $nFailed = (0, 0, \ldots, 0)$; {counts failed components of each type}
7: $BFHist = (( ), ( ), \ldots, ( ))$; {an array of linked lists that keeps a breadth-first history of subTrees, array is indexed by component type, linked list for each component type stores parents in breadth-first order}
8: add $rootC$ to $level$;
9: $nFailed[rootC] = 1$;
10: add @ to $BFHist[rootC]$; {signifies one component of type rootC has failed}
11: AddSubTreeLevel($level$, $nFailed$, $BFHist$, 1, $rootC$);
12: **end for**

Algorithm 2 AddSubTreeLevel(*level*, *nFailed*, *BFHist*, *subTreeRate*, *rootC*)

1: $nextLevelPossibilities = \bigtimes_{i=1}^{|level|} \mathcal{P}(\Gamma_{level[i]})$;
{Builds set of all possible nodes in next level as Cartesian product of powersets of Γ's}
2: **for** *oneNextLevelPossibility* ∈ *nextLevelPossibilities* **do**
3: *addedChildFlag* = False;
4: **for** *parentC* ∈ *level* **do**
5: **for** *childC* ∈ $\Gamma_{parentC}$ **do**
6: **if** *childC* ∈ *oneNextLevelPossibility* **then**
7: **if** *nFailed*[*childC*] == Redundancy(*childC*) **then**
8: goto line 3; {invalid subtree, requires more comps than available in system}
9: **end if**
10: *addedChildFlag* = True;
11: *nFailed*[*childC*] = *nFailed*[*childC*] + 1;
12: add @ to *BFHist*[*childC*]; {signifies one component of type childC has failed}
13: *subTreeRate* = *subTreeRate* ∗ $\phi_{parentC,\ childC}$;
{update rate with ϕ}
14: **else**
15: add *parentC* to *BFHist*[*childC*]; {signifies one component of type childC has not failed, but was present in $\Gamma_{parentC}$}
16: **end if**
17: **end for**
18: **end for**
19:
20: **if** *addedChildFlag* **then**
21: AddSubTreeLevel(*oneNextLevelPossibility*, *nFailed*, *BFHist*, *subTreeRate*, *rootC*);
{subTree can be grown further}
22: **else**
23: ComputeTreeRates(*nFailed*, *BFHist*, *subTreeRate*, *rootC*);
{current subTree is completed because it cannot be grown further}
24: **end if**
25: **end for**

Algorithm 3 ComputeTreeRates(*nFailed*, *BFHist*, *subTreeRate*, *rootC*)

1: **for** $x \in Q$ **do**
2: e = Environment(x);
3: Initialize y as a state with no components failed and environment e;
4: **for** *comp* $\in$ *compSet* **do**
5: $y[comp] = x[comp] + nFailed[comp]$;
6: **end for**
7: **if** y is not a valid state **then**
8: continue;
9: **end if**
10: $rootFailureRate =$ (Redundancy($rootC$) $- x[rootC]$) $* \lambda_{rootC,\, e}$;
11: $prodNotFailedProb = 1$; {cumulative probability of comps that could have failed but did not}
12: **for** *comp* $\in$ {*compSet*} **do**
13: $compsAvailable =$ Redundancy($comp$) $- x[comp]$;
14: **for** *parentC* $\in$ *BFHist*[*comp*] **do**
15: **if** *parentC* == @ **then**
16: $compsAvailable = compsAvailable - 1$;
17: **else if** $compsAvailable > 0$ **then**
18: $prodNotFailedProb = prodNotFailedProb * (1 - \phi_{parentC,\, comp})$;
19: **end if**
20: **end for**
21: **end for**
22: $Q(x, y) = Q(x, y) + rootFailureRate * subTreeRate * prodNotFailedProb$;
23: **end for**